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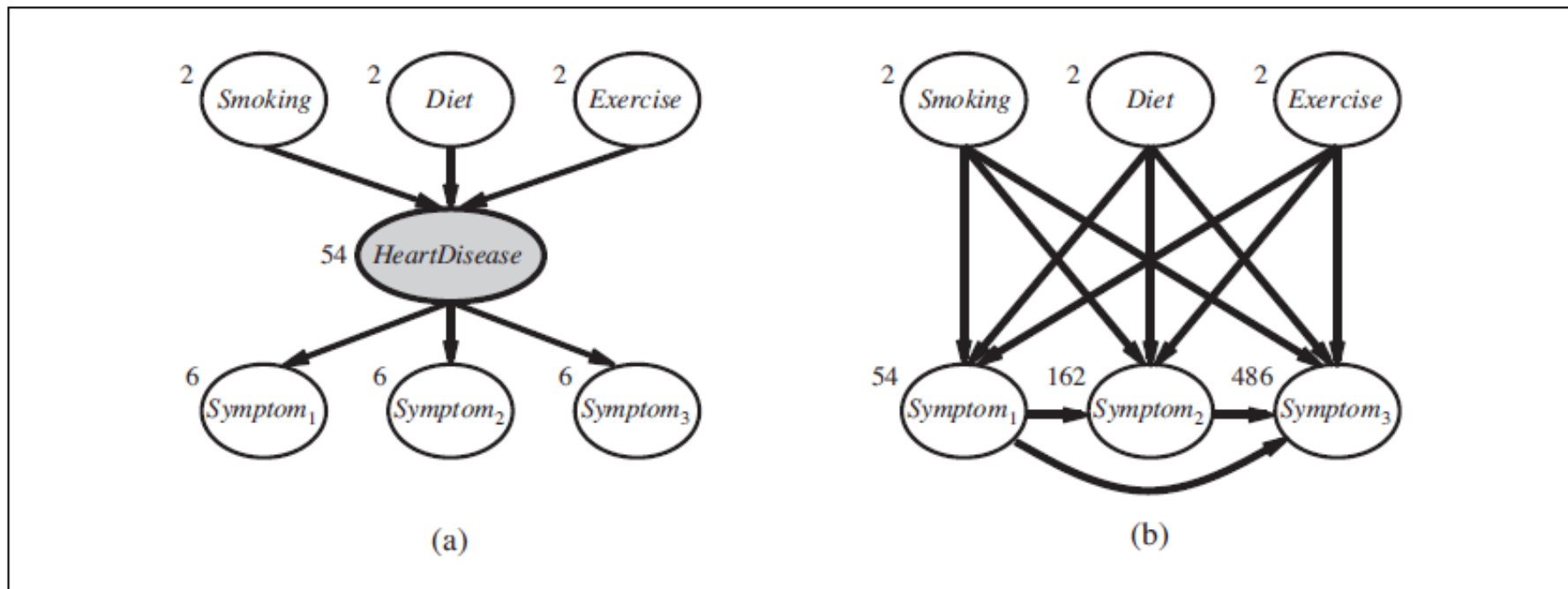
# **Introduction to Intelligent Systems**

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# **LEARNING WITH HIDDEN VARIABLES: THE EM ALGORITHM**

# Latent (or Hidden) Variables

- Latent variables can dramatically reduce the number of parameters required to specify a Bayesian network.

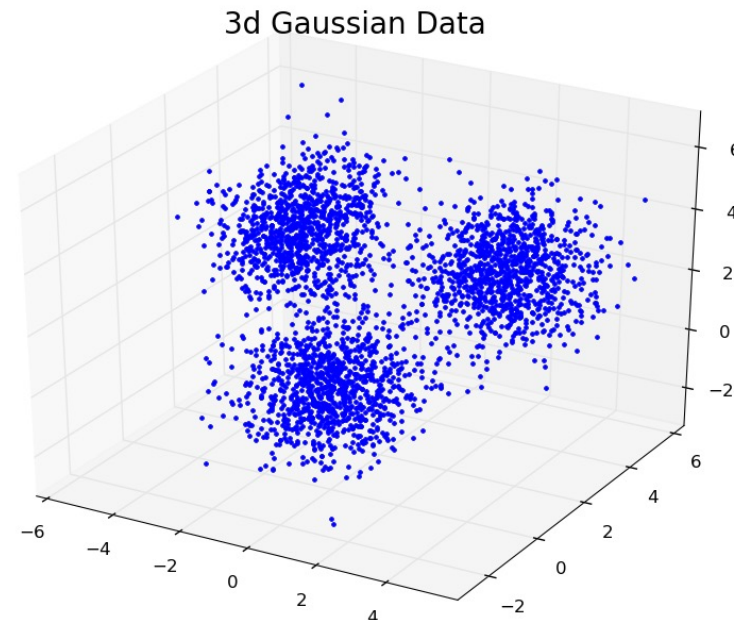


**Figure 20.10** (a) A simple diagnostic network for heart disease, which is assumed to be a hidden variable. Each variable has three possible values and is labeled with the number of independent parameters in its conditional distribution; the total number is 78. (b) The equivalent network with *HeartDisease* removed. Note that the symptom variables are no longer conditionally independent given their parents. This network requires 708 parameters.

# Unsupervised Clustering

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- The problem of discerning multiple categories in a collection of objects.
- The problem is unsupervised because the category labels are not given.
- **Chicken-and-egg problem:** We do not know the assignments nor the parameters



# k-means Algorithm

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- $k = 2$  (number of clusters)
- Means:  $\mu_1, \mu_2$
- Indicator variables  $c_n^i \in \{0, 1\}$ :  $c_n^i = 1$  if  $x_n$  is assigned to the  $i$ th cluster.
- Iterate the following two steps until convergence.

1. Find assignments

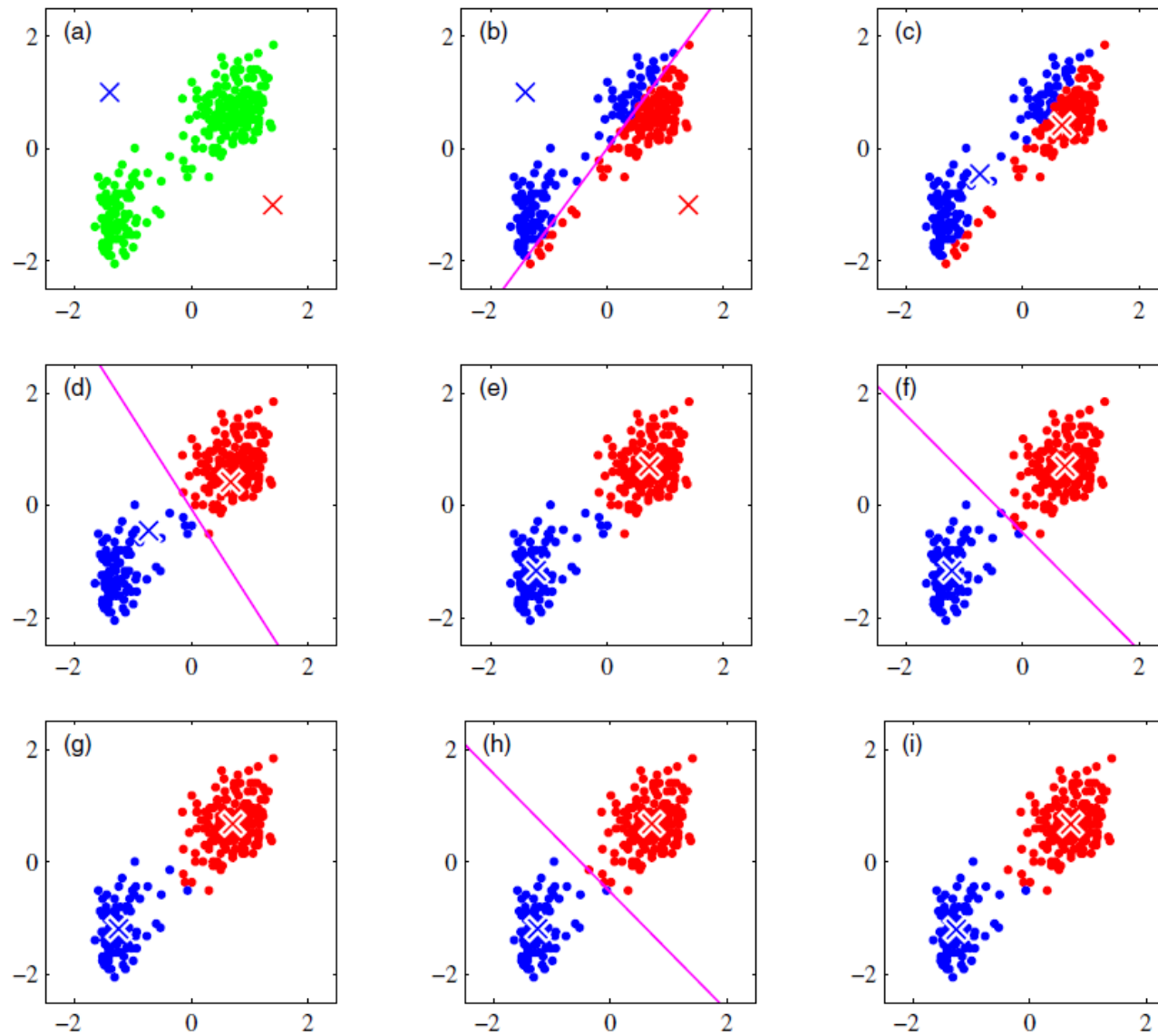
$$c_n^i = \begin{cases} 1 & \text{if } i = \arg \min_j \|x_n - \mu_j\|^2 \\ 0 & \text{otherwise.} \end{cases}$$

2. Update means

$$\mu_i = \frac{\sum_n c_n^i x_n}{\sum_n c_n^i}$$

- k-means algorithm finds a solution which minimizes the following cost function (distortion measure).

$$J = \sum_{n=1}^N \sum_{i=1}^k c_n^i \|x_n - \mu_i\|^2.$$



# Mixture Models

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- Mixture distribution with  $k$  components:

$$P(\mathbf{x}) = \sum_{i=1}^k P(C = i)P(\mathbf{x}|C = i)$$

mixture weight



- Mixture of Gaussians (or a Gaussian Mixture Model (GMM))

$$P(\mathbf{x}) = \sum_{i=1}^k P(C = i)\mathcal{N}(\mathbf{x}|\mu_i, \Sigma_i)$$

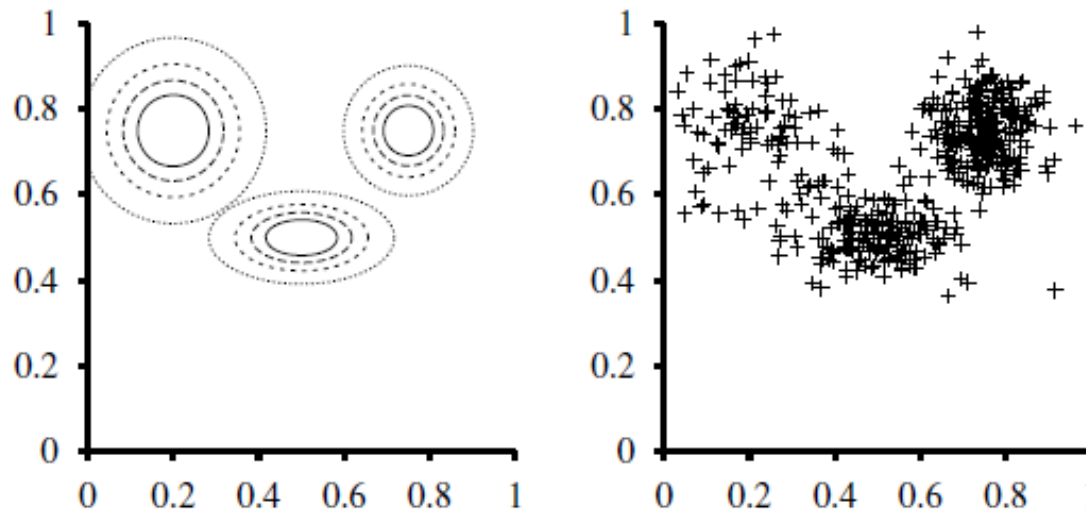
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- Mixture of Gaussians

$$P(\mathbf{x}) = \sum_{i=1}^k P(C = i) \mathcal{N}(\mathbf{x} | \mu_i, \Sigma_i)$$

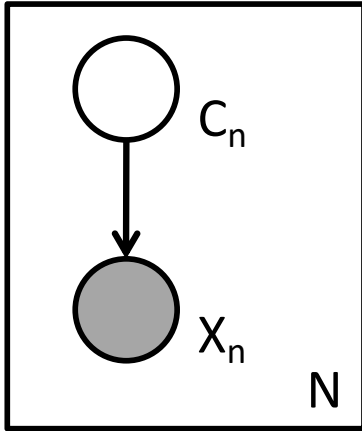
Generative model

1. Choose the component with probability  $P(C=i)$
2. Generate a sample using the distribution of the chosen component





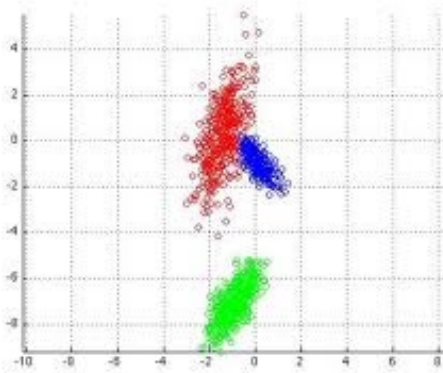
# Mixture Models



$$C_n = \text{multinomial}(K; \pi)$$

$$P(X_n | \theta) = \sum_{i=1}^K P(C_n^i = 1 | \pi) P(X_n | C_n^i = 1, \theta_i)$$

Mixture of Gaussians



$$P(x_n | c_n^i = 1, \theta_i) = \mathcal{N}(x_n | \mu_i, \Sigma_i)$$

Likelihood

$$P(x_1, \dots, x_N | \theta) = \prod_{n=1}^N \left( \sum_{i=1}^K P(C_n^i = 1 | \pi) P(x_n | C_n^i = 1, \theta_i) \right)$$

Log-likelihood

$$\mathcal{L}(\theta | x_1, \dots, x_N) = \sum_{n=1}^N \log \left\{ \sum_{i=1}^K P(C_n^i = 1 | \pi) P(x_n | C_n^i = 1, \theta_i) \right\}$$

No closed-form ML solution

# Expectation-Maximization (EM) Algorithm

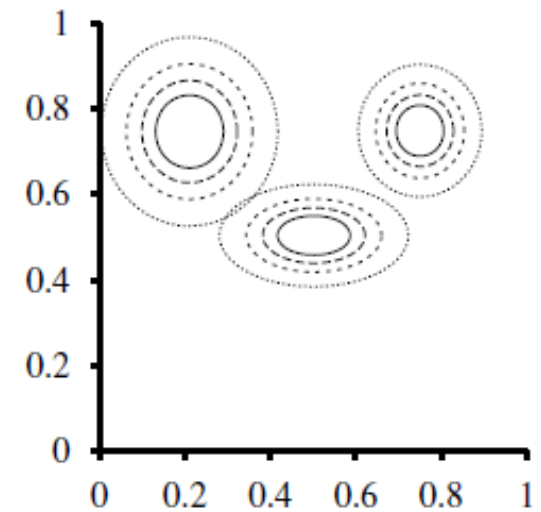
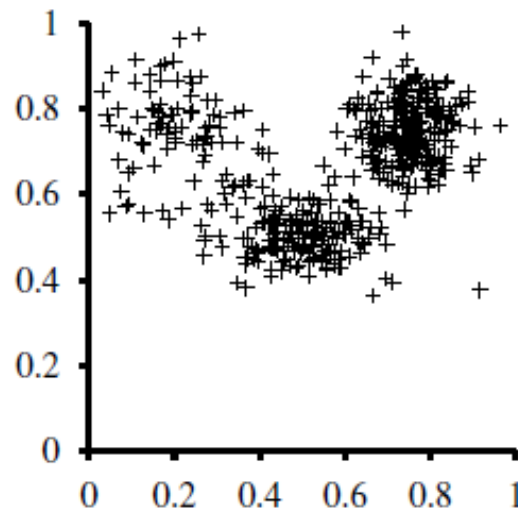
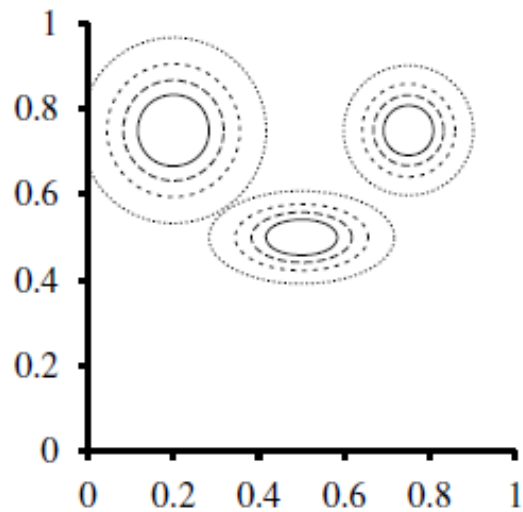
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For the mixture of Gaussians, we initialize the mixture-model parameters arbitrarily and then iterate the following two steps:

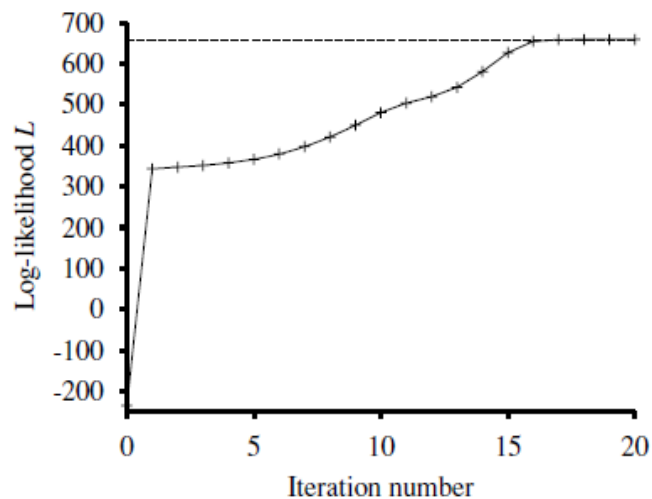
1. **E-step:** Compute the probabilities  $p_{ij} = P(C = i | \mathbf{x}_j)$ , the probability that datum  $\mathbf{x}_j$  was generated by component  $i$ . By Bayes' rule, we have  $p_{ij} = \alpha P(\mathbf{x}_j | C = i) P(C = i)$ . The term  $P(\mathbf{x}_j | C = i)$  is just the probability at  $\mathbf{x}_j$  of the  $i$ th Gaussian, and the term  $P(C = i)$  is just the weight parameter for the  $i$ th Gaussian. Define  $n_i = \sum_j p_{ij}$ , the effective number of data points currently assigned to component  $i$ .
2. **M-step:** Compute the new mean, covariance, and component weights using the following steps in sequence:

$$\begin{aligned}\mu_i &\leftarrow \sum_j p_{ij} \mathbf{x}_j / n_i \\ \Sigma_i &\leftarrow \sum_j p_{ij} (\mathbf{x}_j - \mu_i)(\mathbf{x}_j - \mu_i)^\top / n_i \\ w_i &\leftarrow n_i / N\end{aligned}$$

E-step (expectation step) computes the expected values  $p_{ij}$  of the hidden indicator variables  $Z_{ij}$ , where  $Z_{ij} = 1$  if  $x_j$  was generated by the  $i$ th component and 0 otherwise. M-step (maximization step) finds the ML estimates, given the expected values of the hidden indicator variables.

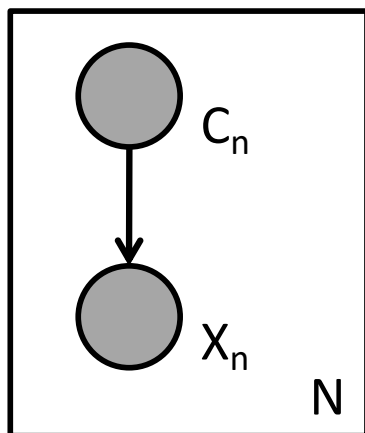


The model learned by the EM algorithm



- The EM algorithm increases the log likelihood at every iteration
- The EM algorithm converges to a local maximum in likelihood.

# EM Algorithm



Pretend all nodes are observed

$$\mathcal{D}_c = \{(x_n, c_n) : n = 1, \dots, N\}$$

Complete likelihood

$$\prod_{n=1}^N \prod_{i=1}^K \left( P(c_n^i = 1 | \pi) P(x_n | c_n^i = 1, \theta_i) \right)^{c_n^i}$$

Complete log-likelihood

$$\mathcal{L}_c(\theta | \mathcal{D}_c) = \sum_{n=1}^N \sum_{i=1}^K c_n^i \log \left( P(c_n^i = 1 | \pi) P(x_n | c_n^i = 1, \theta_i) \right)$$

Expected complete log-likelihood

$$\begin{aligned} \mathbb{E}_{\tilde{\theta}} (\mathcal{L}_c(\theta | \mathcal{D}_c)) &= \mathbb{E}_{\tilde{\theta}} \left( \sum_{n=1}^N \sum_{i=1}^K c_n^i \log \left( P(c_n^i = 1 | \pi) P(x_n | c_n^i = 1, \theta_i) \right) \right) \\ &= \sum_{n=1}^N \sum_{i=1}^K \mathbb{E}_{\tilde{\theta}} (c_n^i) \log \left( P(c_n^i = 1 | \pi) P(x_n | c_n^i = 1, \theta_i) \right) \end{aligned}$$

# EM Algorithm

1. E-step: Compute  $\mathbb{E}_{\theta^{(t)}} (c_n^i) = P(c_n^i = 1 | x_1, \dots, x_N, \theta^{(t)})$
2. M-step: Maximize  $\mathbb{E}_{\theta^{(t)}} (\mathcal{L}_c(\theta | \mathcal{D}_c))$  with respect to  $\theta$ ; the solution becomes  $\theta^{(t+1)}$ .
3. Iterate until it converges

