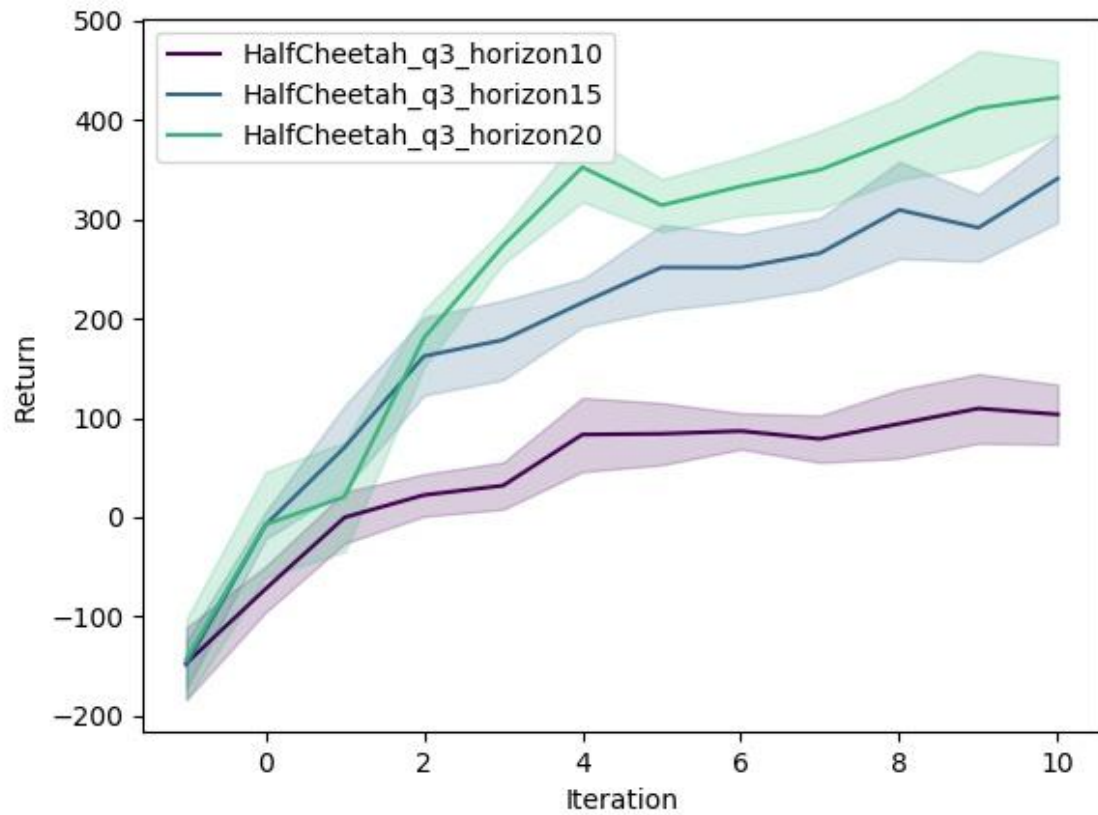
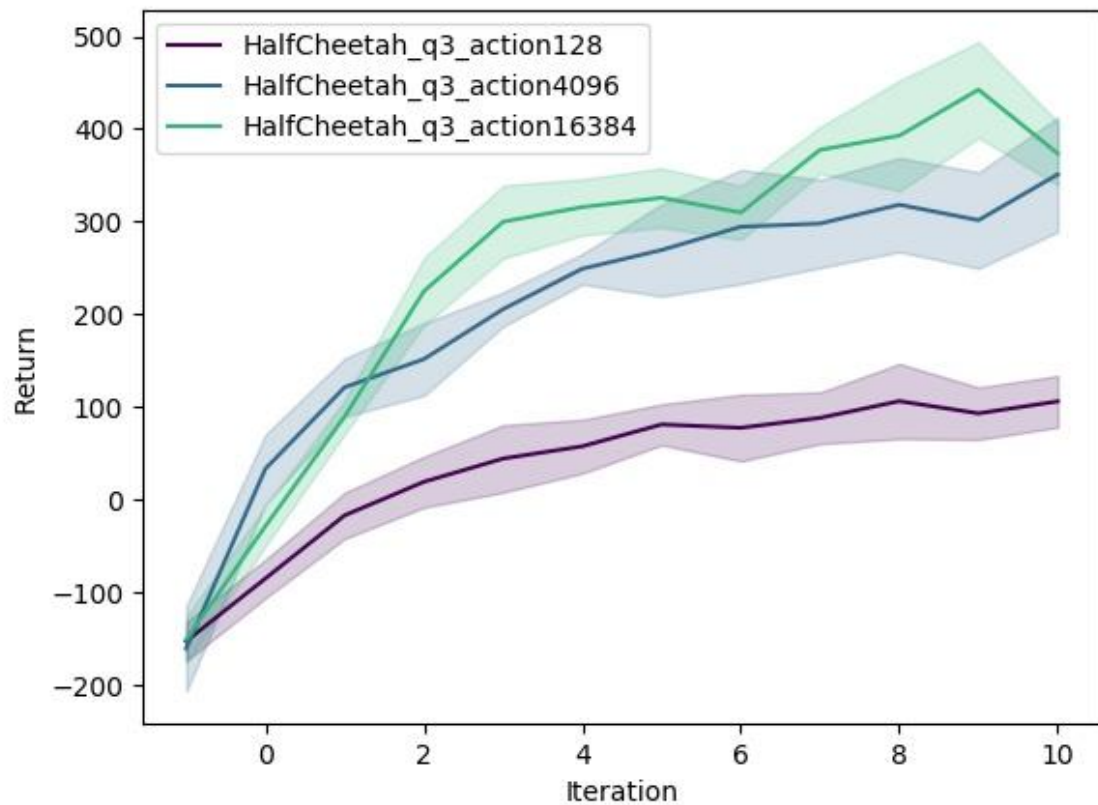


## Problem 3b

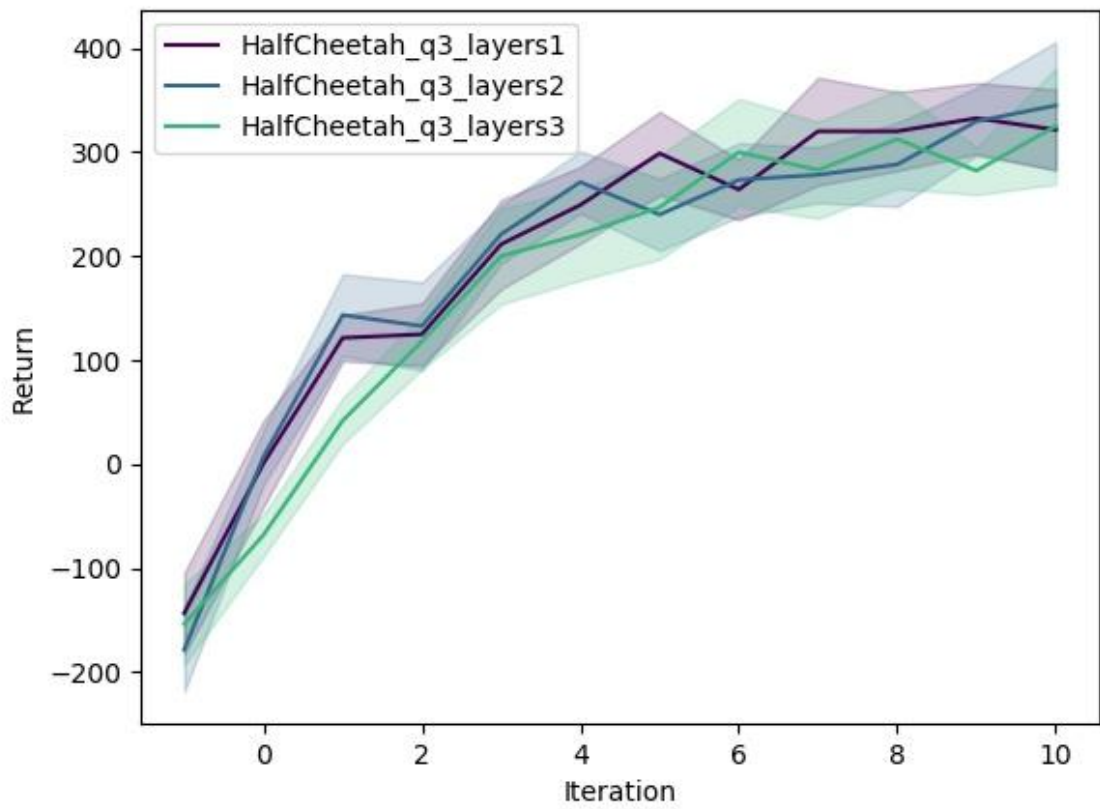
a) Plot comparing performance when varying the MPC horizon.



b) Plot comparing performance when varying the number of randomly sampled action sequences used for planning.



**c) Plot comparing performance when varying the number of neural network layers for the learned dynamics model.**



In [ ]: