






# Meeting Notes 07.04.2022

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## Attendance :

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| Name   | abbr     | attendance                                                                         |
|--------|----------|------------------------------------------------------------------------------------|
| Marco  | forstma1 |  |
| Dan    | hochsdan |  |
| Luis   | miranlui |  |
| Monika | reif     |  |
| Stefan | brtt     |  |

## Notes

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### What we have done:

- Chapter 2 Algorithms (wrote about RRT and Triangulation)
- Chapter 2 Formula Student (from Monika's Input)
- Optimized the triangulation algorithm with less cones
- Created an "Input Transformer" in ROS (prepares cones and reference line for global racetrajectory)

### What we want to accomplish by next week:

- Integrate global trajectory into ROS project
- Work on chapter 2

### Problems:

- Finding a way to get the middle point with less cones on one side (not perfect yet à Demo)