BPG Documentation

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CHAPTER

ONE

BPG

1.1 BPG package

1.1.1 Submodules

1.1.2 BPG.dataprep_gdspy module

BPG.dataprep_gdspy.cleanup_loop(coords_list_ori, eps_grid=0.0001)

Parameters

- coords_list_ori (List[Tuple[float, float]]) The list of x-y coordinates composing a polygon shape
- **eps_grid** grid resolution below which points are considered to be the same

Returns output_dict - Dictionary of 'coords_list_out' and 'fully_cleaned'

Return type Dict[str]

BPG.dataprep_gdspy.coord_to_shapely(pos_neg_list_list)

Converts list of coordinate lists into shapely polygon objects

Parameters pos_neg_list_list - The tuple of positive and negative lists of coordinate lists

Returns polygon_out – The Shapely representation of the polygon

Return type Union[Polygon, Multipolygon]

BPG.dataprep_gdspy.coords_apprx_in_line (coord1, coord2, coord3, eps_grid=0.0001)

Determines if three coordinates are in the same line

Parameters

- coord1 (Tuple[float, float]) First coordinate
- coord2 (Tuple[float, float]) Second coordinate
- coord3 (Tuple[float, float]) Third coordinate
- eps_grid (float) grid resolution below which points are considered to be the same

Returns True if coordinates are in a line, False if not in a line

Return type bool

BPG. dataprep_gdspy.coords_cleanup (coords_list_ori, eps_grid=0.0001, debug=False) clean up coordinates in the list that are redundant or harmful for following Shapely functions

Parameters

- coords_list_ori (List[Tuple[float, float]]) list of coordinates that enclose a polygon
- **eps_grid** (*float*) a size smaller than the resolution grid size, if the difference of x/y coordinates of two points is smaller than it, these two points should actually share the same x/y coordinate
- debug (bool) -

Returns coords list out – The cleaned coordinate list

Return type List[Tuple[float, float]]

BPG.dataprep_gdspy.dataprep_cleanup_gdspy (polygon, do_cleanup=True)
Clean up a gdspy Polygon/PolygonSet by performing offset with size = 0

First offsets by size 0 with precision higher than the global grid size. Then calls an explicit rounding function to the grid size. This is done because it is unclear how the clipper/gdspy library handles precision

Parameters

- polygon (Union[gdspy.Polygon, gdspy.PolygonSet]) The polygon to clean
- **do_cleanup** (bool) True to perform the cleanup. False will return input polygon unchanged

Returns clean_polygon - The cleaned up polygon

Return type Union[gdspy.Polygon, gdspy.PolygonSet]

BPG. dataprep_gdspy.dataprep_coord_to_gdspy (pos_neg_list_list, manh_grid_size, do_manh)
Converts list of polygon coordinate lists into GDSPY polygon objects The expected input list will be a list of all polygons on a given layer

Parameters

- **pos_neg_list_list** (*Tuple[List, List]*) A tuple containing two lists: the list of positive polygon shapes and the list of negative polygon shapes. Each polygon shape is a list of point tuples
- manh_grid_size (float) The Manhattanization grid size
- do_manh (bool) True to perform Manhattanization

Returns polygon_out – The gdpsy.Polygon formatted polygons

Return type Union[gdspy.Polygon, gdspy.PolygonSet]

BPG.dataprep_gdspy.dataprep_oversize_gdspy(polygon, offset)

Grow a polygon by an offset. Perform cleanup to ensure proper polygon shape.

Parameters

- polygon (Union[gdspy.Polygon, gdspy.PolygonSet, None]) The polygon to size, in gdspy representation
- **offset** (float) The amount to grow the polygon

Returns polygon_oversized – The oversized polygon

Return type Union[gdspy.Polygon, gdspy.PolygonSet, None]

BPG. dataprep_gdspy.dataprep_roughsize_gdspy (polygon, size_amount, do_manh)

Add a new polygon that is rough sized by 'size amount' from the provided polygon. Rough sizing entails:

• oversize by 2x the global rough grid size

- undersize by 2x the global rough grid size
- oversize by the global rough grid size
- Manhattanize to the global rough grid
- undersize by the fine global fine grid size
- oversize by the fine global fine grid size
- oversize by 'size amount' less the 2x global grid size already used

Parameters

- **polygon** (*Union*[gdspy.Polygon, gdspy.PolygonSet]) **polygon** to be used as the base shape for the rough add, in gdspy representation
- **size_amount** (float) amount to oversize (undersize is not supported, will be set to 0 if negative) the rough added shape
- do_manh (bool) True to perform Manhattanization of after the oouuo shape

Returns polygon_roughsized - the rough added polygon shapes, in gdspy representation

Return type Union[gdspy.Polygon, gdspy.PolygonSet]

BPG.dataprep_gdspy.dataprep_undersize_gdspy (polygon, offset)
Shrink a polygon by an offset. Perform cleanup to ensure proper polygon shape.

Parameters

- polygon (Union[gdspy.Polygon, gdspy.PolygonSet, None]) The polygon to size, in gdspy representation
- **offset** (float) The amount to shrink the polygon

Returns polygon_undersized - The undersized polygon

Return type Union[gdspy.Polygon, gdspy.PolygonSet, None]

 ${\tt BPG.dataprep_gdspy.gdspy_manh} \ (polygon_gdspy, manh_grid_size, do_manh)$

Performs Manhattanization on a gdspy representation of a polygon, and returns a gdspy representation of the Manhattanized polygon

Parameters

- polygon_gdspy (Union[gdspy.Polygon, gdspy.PolygonSet, None]) The gdspy representation of the polygons to be Manhattanized
- manh_grid_size (float) grid size for Manhattanization, edge length after Manhattanization should be larger than it
- do_manh (bool) True to perform Manhattanization

Returns polygon_out – The Manhattanized polygon, in gdspy representation

Return type Union[gdspy.Polygon, gdspy.PolygonSet]

BPG.dataprep_gdspy.manh_skill (poly_coords, manh_grid_size, manh_type)

Convert a polygon into a polygon with orthogonal edges (ie, performs Manhattanization)

Parameters

• poly_coords (List[Tuple[float, float]]) - list of coordinates that enclose a polygon

- manh_grid_size (float) grid size for Manhattanization, edge length after Manhattanization should be larger than it
- manh_type (str) 'inc': the Manhattanized polygon is larger compared to the one on the manh grid 'dec': the Manhattanized polygon is smaller compared to the one on the manh grid 'non': additional feature, only map the coords to the manh grid but do no Manhattanization

Returns poly_coords_cleanup – The Manhattanized list of coordinates describing the polygon **Return type** List[Tuple[float, float]]

BPG.dataprep_gdspy.not_manh(coord_list, eps_grid=1e-06, print_failing_points=False) Checks whether the passed coordinate list is Manhattanized

Parameters

- coord_list (List[Tuple[float, float]]) The coordinate list to check
- eps_grid (float) The grid tolerance below which points are considered the same
- print_failing_points (bool) True to print the coordinates of the points that do not have Manhattanized edges

Returns non_manh_edge – The count of number of edges that are non-Manhattan in this shape **Return type** int

BPG.dataprep_gdspy.poly_operation(polygon1, polygon2, operation, size_amount, do manh=False)

Parameters

- polygon1 (Union[gdspy.Polygon, gdspy.PolygonSet, None]) The shapes currently on the output layer
- polygon2 (Union[gdspy.Polygon, gdspy.PolygonSet, None]) The shapes on the input layer that will be added/subtracted to/from the output layer
- operation (str) The operation to perform: 'rad', 'add', 'sub', 'ext', 'ouo', 'del'
- size_amount (float) The amount to over/undersize the shapes to be added/subtracted
- do_manh (bool) True to perform Manhattanization during the 'rad' operation

Returns polygons_out – The new polygons present on the output layer

Return type Union[gdspy.Polygon, gdspy.PolygonSet, None]

```
BPG.dataprep_gdspy.polyop_gdspy_to_point_list(polygon_gdspy_in, fracture=True, do_manh=True, manh_grid_size=0.001, debug=False)
```

Converts the gdspy representation of the polygon into a list of fractured polygon point lists

Parameters

- **polygon_gdspy_in** (*Union[gdspy.Polygon, gdspy.PolygonSet]*) The gdspy polygons to be converted to lists of coordinates
- **fracture** (bool) True to fracture shapes
- **do_manh** (bool) True to perform Manhattanization
- manh_grid_size (float) The Manhattanization grid size
- **debug** (bool) True to print debug information

Returns output_list_of_coord_lists – A list containing the polygon point lists that compose the input gdspy polygon

Return type List[List[Tuple[float, float]]]

BPG.dataprep_gdspy.shapely_to_gdspy(geom_shapely)

Convert the shapely representation of a polygon/multipolygon into the gdspy representation of the polygon/polygonset

Parameters geom_shapely (*Union*[*Polygon*, *MultiPolygon*]) – The shapely representation of the polygon

Returns polygon_gdspy – The gdspy representation of the polygon

Return type Union[gdspy.Polygon, gdspy.PolygonSet]

BPG.dataprep_gdspy.shapely_to_gdspy_polygon(polygon_shapely)

Converts the shapely representation of a polygon to a gdspy representation

Parameters polygon_shapely (*shapely.geometry.Polygon*) – The shapely representation of the polygon

Returns polygon_gdspy – The gdspy representation of the polygon

Return type gdspy.Polygon

BPG.dataprep_gdspy.simplify_coord_to_gdspy(pos_neg_list_list, tolerance=0.0005)

Simplifies a polygon coordinate-list representation of a complex polygon (multiple shapes, with holes, etc) and converts the simplified polygon into gdspy representation. Simplification involves reducing the number of points in the shape based on a tolerance of how far the points are from being collinear.

Parameters

- pos_neg_list_list (Tuple[List[List[Tuple[float, float]]], List[List[Tuple[float, float]]]]) Tuple containing the positive and negative list of polygon point-lists
- **tolerance** (float) The tolerance within which a set of points are deemed collinear

Returns poly_gdspy_simplified - The simplified polygon in gdspy representation

Return type Union[gdspy.PolygonSet, gdspy.Polygon]

1.1.3 BPG.dataprep_shapely module

1.1.4 BPG.lumerical generator module

Module containing various classes used to systematically generate clean Lumerical script code

```
class BPG.lumerical_generator.LumericalCodeGenerator
    Bases: object
```

This class enables the generation of lumerical .lsf code

```
add\_code(code: str) \rightarrow None
```

Adds provided statement of code to the script file, and formats it accordingly Adds a semicolon and a newline character to each line to match standard LSF syntax

Parameters code (str) – Single string containing lumerical script

```
add_code_block (code: List[str])
```

Adds a preformatted list of lines of code to the script file

```
Parameters code (List[str]) - Single string containing lumerical script
     add line (code: str) \rightarrow None
          Adds provided line of code to the script file Does not add a semicolon, but does add a newline character
               Parameters code (str) – Single string containing lumerical script
     get file header()
          Returns a list of strings that form the header of the script file
               Returns header – Contains comments for the header of the file
              Return type List[str]
     set (key: str, value) \rightarrow None
          Conveniently adds a set statement to the LSF file
              Parameters
                   • key (str) – parameter to be changed with the set statement
                   • value (any) – value that the parameter will be assigned
class BPG.lumerical_generator.LumericalDesignGenerator(filepath)
     Bases: BPG.lumerical generator.LumericalCodeGenerator
     export_to_lsf()
          Take all code in the database and export it to a lumerical script file
class BPG.lumerical generator.LumericalSweepGenerator(filepath)
     Bases: BPG.lumerical_generator.LumericalCodeGenerator
     This class enables the creation of .lsf files for swept variables
     add_sweep_point (script_name)
          Adds a given script name to the be run in the main sweep loop. Scripts are executed in the order in which
          they are added
              Parameters script_name (str) - Name of script to be executed
     create_sweep_loop()
     export_to_lsf()
          Take all code in the database and export it to a lumerical script file
```

1.1.5 BPG.lumerical_sim module

```
class BPG.lumerical_sim.FDESolver
    Bases: BPG.lumerical_sim.LumericalSimObj
```

Lumerical Simulation Object for Finite-Difference Eigenmode Solver

```
align_to_port (port, offset=(0, 0), align_orient=True)
```

Moves the center of the simulation object to align to the provided photonic port. Overrides the superclass method to support setting the orientation to match port

Parameters

- port (PhotonicPort) Photonic port for the simulation object to be aligned to
- offset (Tuple) (x, y) offset relative to the port location
- align_orient (bool) True to set the orientation to match the port orientation, False to ignore port orientation

```
lsf export()
          Returns a list of Lumerical code describing the creation of a FDESolver object
              Returns 1sf code – list of Lumerical code to create the FDESolver object
              Return type List[str]
     mesh size
     orientation
class BPG.lumerical_sim.FDTDSolver
     Bases: BPG.lumerical_sim.LumericalSimObj
     Lumerical Simulation Object for Finite-Difference Time Domain Solver
     lsf_export()
          Returns a list of Lumerical code describing the creation of a FDESolver object
              Returns lsf_code – list of Lumerical code to create the FDESolver object
              Return type List[str]
class BPG.lumerical sim.LumericalSimObj
     Bases: BPG.photonic_core.Box, BPG.lumerical_generator.LumericalCodeGenerator
     Abstract Base Class for all simulation/monitor objects in Lumerical
     All simulation objects have a common representation for geometry and generate lsf code, so LumericalSimObj
     inherits both from Box and from LumericalCodeGenerator
     content
          Return self so that lsf_export can be called by BAG from the content list
     lsf_export() \rightarrow List[str]
          Returns a list of Lumerical code describing the creation of the simulation object
          Unlike the export_lsf method for photonic objects, this method is not a classmethod, and relies on internal
          access to the instances attributes
1.1.6 BPG.lumerical tb module
class BPG.lumerical tb.LumericalTB(temp db, lib name, params, used names, **kwargs)
     Bases: BPG.photonic_template.PhotonicTemplateBase
     add_EME_port()
     add_EME_solver()
     add_FDE_solver() → BPG.lumerical_sim.FDESolver
          Create a blank FDE solver, add it to the db, and return it to the user for manipulation
     add_FDTD_port()
     add_FDTD_solver()
          Create a blank FDTD solver, add it to the db, and return it to the user for manipulation
     add_effective_index_monitor()
     add_eme_profile()
     add_freq_domain_monitor()
```

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add_gaussian_source()
add index monitor()

```
add_mode_expansion_monitor()
add mode source()
add_movie_monitor()
add_point_source()
add time domain monitor()
add total field source()
add_var_FDTD_solver()
construct_tb()
    Override this method to specify the procedure for generating the testbench and simulation. YOU MUST
    IMPLEMENT THIS METHOD TO CREATE A TESTBENCH!
create dut()
    Create and place the provided layout class and parameters at the origin
draw_layout()
    This method is used internally to assemble the instance and the TB sources. DO NOT CALL THIS
classmethod get params info()
    Returns a dictionary from parameter names to descriptions.
        Returns param_info – dictionary from parameter names to descriptions.
        Return type Optional[Dict[str, str]]
plane wave source()
```

1.1.7 BPG.manh_shapely module

```
BPG.manh_shapely.cleanup_loop(coords_list_ori, eps_grid=0.0001)
BPG.manh_shapely.coords_apprx_in_line(coord1, coord2, coord3, eps_grid=0.0001)
```

Tell if three coordinates are in the same line Expected to have three consecutive coordinates as inputs when the function is called

BPG.manh_shapely.coords_cleanup(coords_list_ori, eps_grid=0.0001, debug=False) clean up coordinates in the list that are redundant or harmful for following Shapely functions

Parameters

- coords_list_ori (list[tuple[float, float]]) list of coordinates that enclose a polygon
- **eps_grid** (*float*) a size smaller than the resolution grid size, if the difference of x/y coordinates of two points is smaller than it, these two points should actually share the same x/y coordinate
- debug (bool) -

BPG.manh_shapely.manh_skill(poly_coords, manh_grid_size, manh_type)

Convert a polygon into the polygon with orthogonal edges, detailed flavors are the same as it is in the SKILL code

Parameters

• poly_coords (list[tuple[float, float]]) - list of coordinates that enclose a polygon

- manh_grid_size (float) grid size for manhattanization, edge length after manhattanization should be larger than it
- manh_type (str) 'inc': the manhattanized polygon is larger compared to the one on the manh grid 'dec': the manhattanized polygon is smaller compared to the one on the manh grid 'non': additional feature, only map the coords to the manh grid but do no manhattanization

```
BPG.manh_shapely.plot_coords(ax, x, y, color='#999999', zorder=1)
BPG.manh_shapely.plot_line(ax, ob, color='r')
BPG.manh_shapely.polyop_manh(geom, manh_grid_size, do_manh)
BPG.manh_shapely.polyop_manh_polygon(geom, manh_grid_size, do_manh)
```

1.1.8 BPG.photonic_core module

```
class BPG.photonic_core.Box
    Bases: object
```

A class representing a 3D rectangle

```
align_to_port(port, offset=(0, 0))
```

Moves the center of the simulation object to align to the provided photonic port

Parameters

- port (PhotonicPort) Photonic port for the simulation object to be aligned to
- **offset** (Tuple) (x, y) offset relative to the port location

```
move\_by(dx, dy, unit\_mode = False)
```

```
set_center_span (dim, center, span)
```

Sets the center and span of a given geometry dimension

Parameters

- dim(str) 'x', 'y', or 'z' for the corresponding dimension
- center (float) coordinate location of the center of the geometry
- span (float) length of the geometry along the dimension

```
set_span (dim, span)
```

Sets the span of a given geometry dimension

Parameters

- dim(str) 'x', 'y', or 'z' for the corresponding dimension
- **span** (float) length of the geometry along the dimension

```
class BPG.photonic_core.CoordBase
```

Bases: object

A class representing the basic unit of measurement for all objects in BPG.

All user-facing values are assumed to be floating point numbers in units of microns. BAG internal functions assume that we receive 'unit-mode' numbers, which are integers in units of nanometers. Both formats are supported.

float

Returns the rounded floating point number closest to a valid point on the resolution grid

```
meters
          Returns the rounded floating point number in meters closest to a valid point on the resolution grid
     micron = Decimal('0.000001')
     microns
     res = Decimal('0.001')
     unit mode
     value
class BPG.photonic_core.PTech
     Bases: object
     finalize_template(a)
     get_layer_id(layer)
     use_flip_parity()
class BPG.photonic_core.PhotonicBaqLayout (grid, use_cybagoa=False)
     Bases: bag.layout.core.BagLayout
     This class contains layout information of a cell.
          Parameters
                • grid (bag.layout.routing.RoutingGrid) - the routing grid instance.
                • use_cybagoa (bool) – True to use cybagoa package to accelerate layout.
     add_monitor_obj (monitor_obj)
          Add a new Lumerical monitor object to the db
     add_round(round_obj)
          Add a new (arrayed) round shape.
              Parameters round_obj (BPG.photonic_objects.PhotonicRound) - the round ob-
                 ject to add.
     add_sim_obj (sim_obj)
          Add a new Lumerical simulation object to the db
     add_source_obj (source_obj)
          Add a new Lumerical source object to the db
     finalize()
          Prevents any further changes to this layout.
     get_content (lib_name, cell_name, rename_fun)
          returns a list describing geometries in this layout.
              Parameters
                  • lib_name (str) - the layout library name.
                  • cell_name (str) – the layout top level cell name.
                  • rename_fun (Callable[[str], str]) - the layout cell renaming function.
              Returns content – a list describing this layout, or PyOALayout if cybagoa package is enabled.
              Return type Union[List[Any], Tuple[str, 'cybagoa.PyOALayout']]
     move\_all\_by (dx=0.0, dy=0.0, unit\_mode=False)
          Move all layout objects in this layout by the given amount.
```

Parameters

```
• dx (Union[float, int]) - the X shift.
```

```
• dy (Union[float, int]) - the Y shift.
```

• unit_mode (bool) – True if shift values are given in resolution units.

```
class BPG.photonic_core.PhotonicBagProject (bag_config_path=None, port=None)
```

Bases: bag.core.BagProject

The main bag controller class.

This class mainly stores all the user configurations, and issues high level bag commands.

Parameters

- bag_config_path (Optional[str]) the bag configuration file path. If None, will attempt to read from environment variable BAG_CONFIG_PATH.
- **port** (Optional[int]) the BAG server process port number. If not given, will read from port file.

```
static load_yaml (filepath)
```

Setup standardized method for yaml loading

```
class BPG.photonic_core.Plane
    Bases: object
```

A class representing a plane that is orthogonal to one of the cardinal axes

TODO: Implement this class

```
class BPG.photonic_core.XY
    Bases: object
```

A class representing a single point on the XY plane

x

x_float

x_meters

хy

xy_float

xy_meters

v

y_float

y_meters

class BPG.photonic_core.XYZ

Bases: object

A class representing a single point on the XYZ space

x

x_float

x_meters

xyz

```
xyz_float
xyz_meters
y
y_float
y_meters
z
z_float
z_meters
```

1.1.9 BPG.photonic_layout_manager module

```
class BPG.photonic_layout_manager.PhotonicLayoutManager(bprj, spec_file)
    Bases: bag.simulation.core.DesignManager
```

Class that manages the creation of Photonic Layouts and Lumerical LSF files

dataprep (debug=False)

Parameters debug (bool) – True to print debug information

```
\begin{tabular}{ll} \beg
```

Generates a batch of layouts with the layout package/class in the spec file with the parameters set by layout_params_list and names them according to cell_name_list. Each dict in the layout_params_list creates a new layout

Parameters

- **generate_gds** (Optional[bool]) Optional parameter: True (default) to generate the GDS
- layout_params_list (List[dict]) Optional list of dicts corresponding to layout parameters passed to the generator class
- **cell_name_list** (List[str]) Optional list of strings corresponding to the names given to each generated layout
- **gen full qds** (bool) True to generate a gds with both physical and design layers
- **gen_design_gds** (bool) True to generate the gds with only photonic design (and port) layers
- $gen_physical_gds (bool)$ True to generate the gds with only physical layers
- **debug** (bool) True to print debug information

```
generate_gds (layout_params_list=None, cell_name_list=None) → None
```

Generates a batch of layouts with the layout package/class in the spec file with the parameters set by layout_params_list and names them according to cell_name_list. Each dict in the layout_params_list creates a new layout

Parameters

• layout_params_list (List[dict]) - Optional list of dicts corresponding to layout parameters passed to the generator class

• **cell_name_list** (List[str]) – Optional list of strings corresponding to the names given to each generated layout

generate_lsf (use_dataprep: bool = False, debug=False)

Converts generated layout to 1sf format for lumerical import

generate_tb (generate_gds=False, debug=False)

Generates the lumerical testbench lsf

static load yaml (filepath)

Setup standardized method for yaml loading

 $make_tdb() \rightarrow None$

Makes a new PhotonicTemplateDB instance assuming all contained layouts are generated independently of the grid

1.1.10 BPG.photonic_objects module

This module defines various layout objects one can add and manipulate in a template.

Bases: bag.layout.objects.Polygon

A layout polygon object.

Parameters

- **resolution** (*float*) the layout grid resolution.
- layer (Union[str, Tuple[str, str]])—the layer name, or a tuple of layer name and purpose name. If purpose name not given, defaults to 'drawing'.
- points (List[Tuple[Union[float, int], Union[float, int]]) the points defining the polygon.
- unit_mode (bool) True if the points are given in resolution units.

Bases: bag.layout.objects.Blockage

A blockage object.

Subclass Polygon for code reuse.

Parameters

- **resolution** (*float*) the layout grid resolution.
- **block_type** (str) the blockage type. Currently supports 'routing' and 'placement'.
- block_layer (str) the blockage layer. This value is ignored if blockage type is 'placement'.
- points (List[Tuple[Union[float, int], Union[float, int]]) the points defining the blockage.
- unit_mode (bool) True if the points are given in resolution units.

classmethod from_content(content, resolution)

Bases: bag.layout.objects.Boundary

A boundary object.

Subclass Polygon for code reuse.

Parameters

- resolution (float) the layout grid resolution.
- boundary_type (str) the boundary type. Currently supports 'PR', 'snap', and 'area'.
- points (List[Tuple[Union[float, int], Union[float, int]]) the points defining the blockage.
- unit_mode (bool) True if the points are given in resolution units.

classmethod from_content(content, resolution)

class BPG.photonic_objects.PhotonicInstance ($parent_grid$, lib_name , master, loc, orient, name=None, nx=1, ny=1, spx=0, spy=0, $unit_mode=False$)

Bases: bag.layout.objects.Instance

A photonic layout instance, with optional arraying parameters.

Parameters

- parent_grid (RoutingGrid) the parent RoutingGrid object.
- lib_name (str) the layout library name.
- master (TemplateBase) the master template of this instance.
- loc (Tuple[Union[float, int], Union[float, int]]) the origin of this instance.
- **orient** (*str*) the orientation of this instance.
- name (Optional[str]) name of this instance.
- **nx** (int) number of columns.
- **ny** (int) number of rows.
- **spx** (Union[float, int]) column pitch.
- **spy** (Union[float, int]) row pitch.
- unit_mode (bool) True if layout dimensions are specified in resolution units.

content

A dictionary representation of this instance.

 ${\tt get_bound_box_of}\ (\textit{row=0}, \textit{col=0})$

Returns the bounding box of an instance in this mosaic.

get photonic port(name, row=0, col=0)

Returns the photonic port object associated with the provided port name

Parameters

- name (str) name of the port to be returned
- row (int) row in the array of instances to be accessed
- col (int) column in the array of instances to be accessed

```
Returns port – photonic port object associated with the provided name
```

Return type PhotonicPort

```
get_port_used(port_name)
```

master

The master template of this instance.

```
move_by (dx=0, dy=0, unit\_mode=False)
```

Move this instance by the given amount.

Parameters

- dx (Union[float, int]) the X shift.
- **dy** (Union[float, int]) the Y shift.
- unit_mode (bool) True if shifts are given in resolution units

```
set_port_used(port_name)
```

```
transform (loc=(0, 0), orient='R0', unit_mode=False, copy=False)
```

Transform this figure.

```
class BPG.photonic_objects.PhotonicInstanceInfo(res, change_orient=True, **kwargs)
```

Bases: bag.layout.objects.InstanceInfo

A dictionary that represents a layout instance.

copy()

Override copy method of InstanceInfo to return a PhotonicInstanceInfo instead.

master_key

 $Bases: \verb|bag.layout.objects.Figure| \\$

A layout path. Only 45/90 degree turns are allowed.

Parameters

- resolution (float) the layout grid resolution.
- layer (string or (string, string)) the layer name, or a tuple of layer name and purpose name. If purpose name not given, defaults to 'drawing'.
- width (float) width of this path, in layout units.
- points (List[Tuple[float, float]]) list of path points.
- **end_style** (*str*) the path ends style. Currently support 'truncate', 'extend', and 'round'.
- **join_style** (str) the ends style at intermediate points of the path. Currently support 'extend' and 'round'.
- unit_mode (bool) True if width and points are given as resolution units instead of layout units.

content

A dictionary representation of this path.

classmethod from_content(content, resolution)

```
laver
          The rectangle (layer, purpose) pair.
     lower
     move_by (dx=0, dy=0, unit\_mode=False)
          Move this path by the given amount.
              Parameters
                  • dx (float) - the X shift.
                  • dy (float) – the Y shift.
                  • unit_mode (bool) – True if shifts are given in resolution units.
     points
     points_unit
     classmethod polygon_pointlist_export (vertices)
              Parameters vertices (List[Tuple[float, float]) - The vertices from the content
                  list of this polygon
              Returns output_list – The positive and negative polygon pointlists describing this polygon
              Return type Tuple[List, List]
     polygon_points
     process_points (pts, width, eps=1e-05, unit_mode=False)
              Parameters
                  • pts -
                  • width -
                  • eps -
                  • unit_mode -
     transform(loc=(0, 0), orient='R0', unit_mode=False, copy=False)
          Transform this figure.
     upper
     valid
          Returns True if this instance is valid.
     width
     width_unit
class BPG.photonic_objects.PhotonicPathCollection (resolution, paths)
     Bases: bag.layout.objects.PathCollection
     A layout figure that consists of one or more paths.
     This class make it easy to draw bus/trasmission line objects.
          Parameters
                • resolution (float) – layout unit resolution.
```

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• paths (List [Path]) - paths in this collection.

```
class BPG.photonic_objects.PhotonicPinInfo(res, **kwargs)
    Bases: bag.layout.objects.PinInfo
    A dictionary that represents a layout pin.
    classmethod from_content(content, resolution)
    param_list = ['net_name', 'pin_name', 'label', 'layer', 'bbox', 'make_rect']
    transform(loc, orient, unit_mode, copy)
class BPG.photonic_objects.PhotonicPolygon(resolution, layer, points, unit_mode=False)
```

A layout polygon object.

Bases: bag.layout.objects.Polygon

Parameters

- resolution (float) the layout grid resolution.
- layer (Union[str, Tuple[str, str]]) the layer name, or a tuple of layer name and purpose name. If purpose name not given, defaults to 'drawing'.
- points (List[Tuple[Union[float, int], Union[float, int]]) the points defining the polygon.
- unit_mode (bool) True if the points are given in resolution units.

classmethod from_content(content, resolution)

```
classmethod lsf_export (vertices, layer_prop) → List[str]
```

Describes the current polygon shape in terms of lsf parameters for lumerical use

Parameters

- **vertices** (List[Tuple[float, float]]) ordered list of x,y coordinates representing the points of the polygon
- layer_prop (dict) dictionary containing material properties for the desired layer

Returns lsf_code – list of str containing the lsf code required to create specified rectangles

Return type List[str]

classmethod polygon_pointlist_export (vertices)

Parameters vertices (List[Tuple[float, float]) - The verticies from the content list of this polygon

Returns output_list – The positive and negative polygon pointlists describing this polygon **Return type** Tuple[List, List]

```
class BPG.photonic_objects.PhotonicRect(layer, bbox, nx=1, ny=1, spx=0, spy=0, unit\_mode=False)

Bases: bag.layout.objects.Rect
```

A layout rectangle, with optional arraying parameters.

Parameters

- layer (string or (string, string)) the layer name, or a tuple of layer name and purpose name. If pupose name not given, defaults to 'drawing'.
- **bbox** (bag.layout.util.BBox or bag.layout.util.BBoxArray) the base bounding box. If this is a BBoxArray, the BBoxArray's arraying parameters are used.
- **nx** (*int*) number of columns.

- **ny** (*int*) number of rows.
- spx (float) column pitch.
- **spy** (*float*) row pitch.
- unit_mode (bool) True if layout dimensions are specified in resolution units.

classmethod from content(content, resolution)

```
classmethod lsf_export (bbox, layer_prop, nx=1, ny=1, spx=0.0, spy=0.0) \rightarrow List[str]
```

Describes the current rectangle shape in terms of lsf parameters for lumerical use. Note that Lumerical uses meters as the base unit, and all input coords are assumed to be in microns. This method inherently resizes

Parameters

- **bbox** ([[float, float], [float, float]]) lower left and upper right corner xy coordinates
- layer_prop (dict) dictionary containing material properties for the desired layer
- **nx** (*int*) number of arrayed rectangles in the x-direction
- **ny** (*int*) number of arrayed rectangles in the y-direction
- **spx** (float) space between arrayed rectangles in the x-direction
- **spy** (float) space between arrayed rectangles in the y-direction

Returns lsf code – list of str containing the lsf code required to create specified rectangles

Return type List[str]

classmethod polygon_pointlist_export (bbox, nx=1, ny=1, spx=0.0, spy=0.0)

Convert the PhotonicRect geometry to a list of polygon pointlists.

Parameters

- **bbox**([[float, float], [float, float]]) lower left and upper right corner xy coordinates
- **nx** (*int*) number of arrayed rectangles in the x-direction
- **ny** (*int*) number of arrayed rectangles in the y-direction
- **spx** (float) space between arrayed rectangles in the x-direction
- **spy** (float) space between arrayed rectangles in the y-direction

Returns output_list – The positive and negative polygon pointlists describing the photonicRect

Return type Tuple[List, List]

class BPG.photonic_objects.PhotonicRound(layer, resolution, center, rout, rin=0, theta0=0, theta1=360, nx=1, ny=1, spx=0, spy=0, unit mode=False)

 $Bases: \verb|bag.layout.objects.Arrayable| \\$

A layout round object, with optional arraying parameters.

Parameters

- layer (string or (string, string)) the layer name, or a tuple of layer name and purpose name. If pupose name not given, defaults to 'drawing'.
- rout -
- rin -

```
 theta1 –

          • nx (int) – number of columns.
          • ny (int) – number of rows.
           • spx (float) – column pitch.
           • spy (float) - row pitch.
          • unit_mode (bool) – True if layout dimensions are specified in resolution units.
center
    The center in layout units
center_unit
    The center in resolution units
content
     A dictionary representation of this rectangle.
classmethod from_content(content, resolution)
layer
    The rectangle (layer, purpose) pair.
classmethod lsf_export (rout, rin, theta0, theta1, layer_prop, center, nx=1, ny=1, spx=0.0,
                              spy=0.0)
         Parameters
             • rout -
             • rin-
             • theta0 -
             • theta1 -
             • layer_prop -
             • center -
             • nx -
             • ny -
             • spx -
             • spy -
move_by (dx=0, dy=0, unit\_mode=False)
    Moves the round object
static num_of_sparse_point_round(radius, res_grid_size)
classmethod polygon_pointlist_export (rout, rin, theta0, theta1, center, nx=1, ny=1,
                                                 spx=0.0, spy=0.0, resolution=0.001)
rin
     The inner radius in layout units
rin_unit
     The inner radius in resolution units
rout
     The outer radius in layout units
```

• theta0 -

rout unit

The outer radius in resolution units

theta0

The starting angle, in degrees

theta1

The ending angle, in degrees

transform(loc=(0, 0), orient='R0', unit_mode=False, copy=False)

Transform this figure.

Bases: bag.layout.objects.TLineBus

A transmission line bus drawn using Path.

assumes only 45 degree turns are used, and begin and end line segments are straight.

Parameters

- resolution (float) layout unit resolution.
- layer (Union[str, Tuple[str, str]]) the bus layer.
- points (List[Tuple[Union[float, int], Union[float, int]]) list of center points of the bus.
- widths (List[Union[float, int]]) list of wire widths. 0 index is left/bottom most wire.
- spaces (List[Union[float, int]]) list of wire spacings.
- end_style (str) the path ends style. Currently support 'truncate', 'extend', and 'round'.
- unit_mode (bool) True if width and points are given as resolution units instead of layout units.

Bases: bag.layout.objects.Via

A layout via, with optional arraying parameters.

Parameters

- tech (bag.layout.core.TechInfo) the technology class used to calculate via information.
- **bbox** (bag.layout.util.BBox or bag.layout.util.BBoxArray) the via bounding box, not including extensions. If this is a BBoxArray, the BBoxArray's arraying parameters are used.
- **bot_layer** (*str* or (*str*, *str*)) the bottom layer name, or a tuple of layer name and purpose name. If purpose name not given, defaults to 'drawing'.
- **top_layer** (*str* or (*str*, *str*)) the top layer name, or a tuple of layer name and purpose name. If purpose name not given, defaults to 'drawing'.
- **bot_dir** (*str*) the bottom layer extension direction. Either 'x' or 'y'.
- nx (int) arraying parameter. Number of columns.

```
• ny (int) – arraying parameter. Mumber of rows.
```

- **spx** (*float*) arraying parameter. Column pitch.
- **spy** (float) arraying parameter. Row pitch.
- **extend** (bool) True if via extension can be drawn outside of bounding box.
- top_dir(Optional[str]) top layer extension direction. Can force to extend in same direction as bottom.
- unit_mode (bool) True if array pitches are given in resolution units.

```
classmethod from_content(content)
```

```
class BPG.photonic_objects.PhotonicViaInfo(res, **kwargs)
    Bases: bag.layout.objects.ViaInfo
```

A dictionary that represents a layout via.

```
param_list = ['id', 'loc', 'orient', 'num_rows', 'num_cols', 'sp_rows', 'sp_cols', 'en
```

1.1.11 BPG.photonic_port module

```
class BPG.photonic_port.PhotonicPort (name, center, orientation, width, layer, resolution, unit mode=False)
```

Bases: object

center

Return the center coordinates as np array

center_unit

Return the center coordinates as np array in resolution units

classmethod from_dict (center, name, orient, port_width, layer, resolution, unit_mode=True)
 Creates a new PhotonicPort object from a set of arguments

Parameters

- center (Tuple[Union[float, int], Union[float, int]]) the (x, y) point of the port
- name (str) the name of the port
- **orient** (str) the orientation pointing into the object of the port
- port_width (Union[float, int]) the port width
- layer (Union[Tuple[str, str], str]) the layer / layer purpose pair on which the port should be drawn. If the purpose is not specified, it is defaulted to the 'port' purpose
- resolution (float) the grid resolution
- unit_mode (bool) True if layout dimensions are specified in resolution units

Returns port – the generated port

Return type PhotonicPort

is_horizontal()

Returns True if port orientation is R0 or R180

is_vertical()

Returns True if port orientation is vertical (R90 or R270)

layer

Returns the layer of the port

name

Returns the name of the port

orientation

Returns the orientation of the port

resolution

Returns the layout resolution of the port object

```
transform(loc=(0, 0), orient='R0', unit_mode=False)
```

Return a new transformed photonic port

Parameters

- loc (Tuple [Union[float, int], Union[float, int]]) the x, y coordinate to move the port
- **orient** (*str*) the orientation to rotate the port
- unit_mode (bool) true if layout dimensions are specified in resolution units

Returns port – the transformed photonic port object

Return type PhotonicPort

used

Returns True if port is used

width

Returns the width of the port

width_unit

Returns the width of the port in layout units

```
width_vec (unit_mode=True, normalized=True)
```

Returns a normalized vector pointing into the port object

Parameters

- unit_mode (bool) True to return vector in resolution units
- **normalized** (bool) True to normalize the vector. If False, vector magnitude is the port width

Returns vec – a vector whos orientation points into the port and whos magnitude is either 1 or the waveguide port width

Return type np.array

1.1.12 BPG.photonic_template module

Parameters

- master (TemplateBase) the master template object.
- inst_name (Optional[str]) instance name. If None or an instance with this name already exists, a generated unique name is used.
- loc (Tuple[Union[float, int], Union[float, int]]) instance location.
- orient (str) instance orientation. Defaults to "R0"
- **nx** (*int*) number of columns. Must be positive integer.
- **ny** (*int*) number of rows. Must be positive integer.
- **spx** (*Union*[float, int]) column pitch. Used for arraying given instance.
- **spy** (*Union*[float, int]) row pitch. Used for arraying given instance.
- unit_mode (bool) True if dimensions are given in resolution units.

Returns inst – the added instance.

Return type Instance

Instantiates a new instance of the inst_master template. The new instance is placed such that its port named 'instance_port_name' is aligned-with and touching the 'self_port' or 'self_port_name' port of the current hierarchy level.

The new instance is rotated about the new instance's master's origin until desired port is aligned. Optional reflection is performed after rotation, about the port axis.

The self port being connected to can be specified either by passing a self_port PhotonicPort object, or by passing the self_port_name, which refers to a port that must exist in the current hierarchy level.

Parameters

- inst_master (PhotonicTemplateBase) the template master to be added
- instance_port_name (str) the name of the port in the added instance to connect to
- **self_port** (Optional [PhotonicPort]) the photonic port object in the current hierarchy to connect to. Has priority over self_port_name
- **self_port_name** (Optional[str]) the name of the port in the current hierarchy to connect to
- instance_name (Optional[str]) the name to give the new instance
- **reflect** (bool) True to flip the added instance after rotation

Returns new_inst – the newly added instance

Return type PhotonicInstance

```
add_monitor_obj (monitor_obj)
```

Add a new Lumerical monitor object to the db

add_path (path)

Adds a PhotonicPath to the layout object

Parameters path (PhotonicPath) -

Returns path

Return type *PhotonicPath*

add_photonic_port (name=None, center=None, orient=None, width=None, layer=None, resolution=None, unit_mode=False, port=None, overwrite=False, show=True)

Adds a photonic port to the current hierarchy. A PhotonicPort object can be passed, or will be constructed if the proper arguments are passed to this function.

Parameters

- name (str) name to give the new port
- **center** (coord_type) (x, y) location of the port
- **orient** (str) orientation pointing INTO the port
- width (dim_type) the port width
- layer (Union[str, Tuple[str, str]]) the layer on which the port should be added. If only a string, the purpose is defaulted to 'port'
- resolution (Union[float, int]) the grid resolution
- unit_mode (bool) True if layout dimensions are specified in resolution units
- port (Optional [PhotonicPort]) the PhotonicPort object to add. This argument can be provided in lieu of all the others.
- **overwrite** (bool) True to add the port with the specified name even if another port with that name already exists in this level of the design hierarchy.
- **show** (bool) True to draw the port indicator shape

Returns port – the added photonic port object

Return type PhotonicPort

add_polygon (polygon=None, layer=None, points=None, resolution=None, unit_mode=False)
Add a polygon to the layout. If photonic polygon object is passed, use it. User can also pass information to create a new photonic polygon.

Parameters

- polygon (Optional [PhotonicPolygon]) the polygon to add
- layer (Union[str, Tuple[str, str]]) the layer of the polygon
- resolution (float) the layout grid resolution
- points (List[coord_type]) the points defining the polygon
- unit_mode (bool) True if the points are given in resolution units

Returns polygon – the added polygon object

Return type PhotonicPolygon

Parameters

- layer (Union[str, Tuple[str, str]]) the layer name, or the (layer, purpose) pair.
- **x_span** (*Union*[int, float]) horizontal span of the rectangle.
- y_span (Union[int, float]) vertical span of the rectangle.

- center (Union[int, float]) coordinate defining center point of the rectangle.
- **coord1** (*Tuple[Union[int, float], Union[int, float]]*) **point defining one corner of rectangle boundary**.
- coord2 (Tuple[Union[int, float], Union[int, float]]) opposite corner from coord1 defining rectangle boundary.
- **bbox** (bag.layout.util.BBox or bag.layout.util.BBoxArray) the base bounding box. If this is a BBoxArray, the BBoxArray's arraying parameters are used.
- nx (int) number of columns.
- **ny** (*int*) number of rows.
- spx (float) column pitch.
- **spy** (float) row pitch.
- unit_mode (bool) True if layout dimensions are specified in resolution units.

Returns rect – the added rectangle.

Return type PhotonicRect

add_round(round_obj)

Parameters round_obj (Optional[PhotonicRound]) - the polygon to add

Returns polygon – the added round object

Return type PhotonicRound

add_sim_obj(sim_obj)

Add a new Lumerical simulation object to the db

add_source_obj (source_obj)

Add a new Lumerical source object to the db

add_via_stack (bot_layer, top_layer, loc, min_area_on_bot_top_layer=False, unit_mode=False)
Adds a via stack with one via in each layer at the provided location. All intermediate layers will be enclosed with an enclosure that satisfies both via rules and min area rules

Parameters

- bot_layer (str) Name of the bottom layer
- top_layer (str) Name of the top layer
- loc (x, y) location of the center of the via stack
- min_area_on_bot_top_layer (bool) True to have enclosures on top and bottom layer satisfy minimum area constraints
- unit_mode True if input argument is specified in layout resolution units

delete_port (port_names)

Removes the given ports from this instances list of ports. Raises error if given port does not exist.

Parameters port_names (Union[str, List[str]]) -

draw layout()

```
Draw the layout of this template.
          Override this method to create the layout.
          WARNING: you should never call this method yourself.
     extract photonic ports (inst, port names=None, port renaming=None, unmatched only=True,
                                    show=True)
          Brings ports from lower level of hierarchy to the current hierarchy level
              Parameters
                  • inst (PhotonicInstance) - the instance that contains the ports to be extracted
                  • port_names (Optional[Union[str, List[str]]) - the port name or list of
                    port names re-export. If not supplied, all ports of the inst will be extracted
                  • port_renaming (Optional [Dict [str, str]]) - a dictionary containing key-
                    value pairs mapping inst's port names (key) to the new desired port names (value). If not
                    supplied, extracted ports will be given their original names
                  • unmatched_only (bool) -
                  • show (bool) -
     finalize()
     get_photonic_port(port_name=")
          Returns the photonic port object with the given name
              Parameters port_name (Optional[str]) - the photonic port terminal name. If None or
                  empty, check if this photonic template has only one port, and return it
              Returns port – The photonic port object
              Return type PhotonicPort
     has_photonic_port(port_name)
          Checks if the given port name exists in the current hierarchy level.
              Parameters port_name (str) - the name of the port
              Returns
                  • boolean
                  • true if port exists in current hierarchy level
     photonic_ports_names_iter()
     update_port()
class BPG.photonic_template.PhotonicTemplateDB(lib_defs,
                                                                             routing_grid,
                                                                                                lib-
                                                                                     name_prefix=",
                                                                       prj=None,
                                                               name,
                                                               name_suffix=",
                                                                               use_cybagoa=False,
                                                               gds_lay_file=",
                                                                                      flatten=False,
                                                               gds_filepath=", lsf_filepath=", dat-
                                                               aprep_file=",
                                                                               lsf_export_filepath=",
                                                               **kwargs)
     Bases: bag.layout.template.TemplateDB
     by_layer_polygon_list_to_flat_for_gds_export()
          Converts a LPP-keyed dictionary of polygon pointlists to a flat content list format for GDS export
```

 $\textbf{dataprep_file: } \textit{str}, \textit{push_portshapes_through_dataprep: bool = False}, \textit{debug: bool = False})$

→ None Takes the flat content list and performs the specified transformations on the shapes for the purpose of cleaning DRC and prepping tech specific functions.

- 1. Take the shapes in the flattened content list and convert them to gdspy format
- 2. Parse the dataprep spec file to extract the desired procedure defined through dataprep_groups
- 3) Perform each dataprep operation on the provided layers in order. dataprep_groups is a list where each element contains 2 other lists:
 - 3a) lpp_in defines the layers that the operation will be performed on 3b) lpp_ops defines the operation to be performed 3c) Maps the operation in the spec file to its gdspy implementation and performs it
- 4. Performs a final over_under_under_over operation
- 5. Take the dataprepped gdspy shapes and import them into a new post-dataprep content list

Parameters

- dataprep_file (str) path to yaml containing dataprep procedure
- **debug** (bool) True to print debug information
- push_portshapes_through_dataprep (bool) True to perform dataprep and convert the port indicator shapes

```
get_content_on_layer(layer)
```

Returns only the content that exists on a given layer

Parameters layer (Tuple[str, str]) – the layer whose content is desired

Returns content – the shape content on the provided layer

Return type Tuple

get_polygon_point_lists_on_layer(layer, debug=False)

Returns a list of all shapes

Parameters

- layer (Tuple[str, str]) the layer purpose pair to get all shapes in shapely format
- **debug** (bool) true to print debug info

 $\begin{tabular}{ll} \textbf{instantiate_flat_masters} & (\textit{master_list}, & \textit{name_list=None}, & \textit{lib_name="}, & \textit{debug=False}, & \textit{re-name_dict=None}, & \textit{draw_flat_gds=True}, & \textit{sort_by_layer=True}) & \rightarrow & \texttt{None} & \texttt$

Create all given masters in the database to a flat hierarchy.

Parameters

- master_list (Sequence [DesignMaster]) list of masters to instantiate.
- name_list (Optional[Sequence[Optional[str]]]) list of master cell names. If not given, default names will be used.
- **lib_name** (str) Library to create the masters in. If empty or None, use default library.
- **debug** (bool) True to print debugging messages
- rename_dict (Optional[Dict[str, str]]) optional master cell renaming dictionary.

 $\begin{array}{ll} \textbf{instantiate_masters} \ (\textit{master_list}, & \textit{name_list=None}, & \textit{lib_name="}, & \textit{debug=False}, & \textit{re-name_dict=None}) \ \rightarrow \ \text{None} \end{array}$

Create all given masters in the database. Currently, this is being overridden so that the content_list is stored locally. This is a little hacky, and may need to be changed pending further testing

Parameters

- master list (Sequence [DesignMaster]) list of masters to instantiate.
- name_list (Optional[Sequence[Optional[str]]]) list of master cell names. If not given, default names will be used.
- $lib_name(str)$ Library to create the masters in. If empty or None, use default library.
- **debug** (bool) True to print debugging messages
- rename_dict (Optional[Dict[str, str]]) optional master cell renaming dictionary.

sort_flat_content_by_layers()

Sorts the flattened content list into a dictionary of content lists, with keys corresponding to a given lpp

to_lumerical ($gds_layermap$: str, lsf_export_config : str, $lsf_filepath$: str, $use_lataprep$: bool = False, debug: bool = False) \rightarrow None

Exports shapes into the lumerical LSF format

Notes

- 1. Import tech information for the layermap and lumerical properties
- 2. Make sure that a flat content list has been generated for the layout already
- 3. If dataprep is called, run the procedure in the lsf export config
- 4. For each element in the flat content list, convert it into lsf code and append to running export file
- 5. lsf code is generated by sending properties and tech info to the lsf_export static method in each shape class
- 6. Isf code is appended to the running file with LumericalDesignGenerator

Parameters

- gds_layermap (str) path to yaml containing tech specific gds layer information
- **lsf_export_config** (str) path to yaml containing lumerical export configurations
- **lsf filepath** (str) path to where new lsf will be created
- **use_dataprep** (bool) True to use the content list generated by dataprep, otherwise uses flat content list
- **debug** (bool) True to display profiling information

to_polygon_pointlist_from_content_list (content_list, debug=False)

Convert the provided content list into two lists of polygon pointlists. The first returned list represents the positive boundaries of polygons. The second returned list represents the 'negative' boundaries of holes in polygons. All shapes in the passed content list are converted, regardless of layer. It is expected that the content list passed to this function only has a single LPP's content

Parameters

• **content_list** (*List*) – The content list to be converted to a polygon pointlist

• **debug** (bool) – True to print debug information

Returns positive_polygon_pointlist, negative_polygon_pointlist – The positive shape and negative shape (holes) polygon boundaries

Return type Tuple[List, List]

1.1.13 BPG.poly_simplify module

```
BPG.poly_simplify.coord_to_shapely (pos_neg_list_list)
Converts list of coordinate lists into shapely polygon objects

Parameters pos_neg_list_list -

BPG.poly_simplify.shapely_to_gdspy (geom_shapely)

BPG.poly_simplify.shapely_to_gdspy_polygon (polygon_shapely)

BPG.poly_simplify.simplify_coord_to_gdspy (pos_neg_list_list, tolerance=0.0005)
```

1.1.14 BPG.test_setup module

```
BPG.test_setup.bpg_setup()

Creates the BAG project instance to be used
```

1.1.15 Module contents

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b

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