Adaptive Procedural Generation in Minecraft

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2 Introduction

Minecraft is a sandbox video game, created by Mojang in 2009, where players explore and build in a procedurally generated 3D grid-like world with infinite terrain. The main game-play element of Minecraft consists of collecting various types of materials and using them to build tools and structures. The world is divided into 1x1x1 blocks which can vary in material, spawning location, and usability. Aside from the popularity of the base game, Minecraft has become well known for it's customization possibilities through a variety of open source application program interfaces. These application program interfaces allow players to modify textures and color palettes, add new items, block types and enemies, and more.
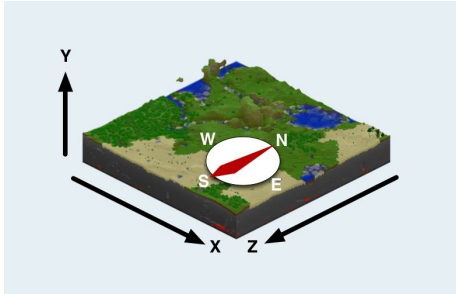
(a) Grid   (b) Developer Overlay

Figure 1: Observable Minecraft Environment

The open source nature and in-game environment of Minecraft has also caught the attention of artificial intelligence researchers. The environment of Minecraft is ideal for research in AI because of the endless possibilities, from training an agent on simple tasks like searching for a specific object or material, to building complex structures or navigating obstacle courses. Since the environment is divided into a three-dimensional grid of equal sized cubes, it is also easy to measure and evaluate the performance of AI in Minecraft.

This project is focused on the application of AI for Procedural Content Generation (PCG) within Minecraft. PCG is defined as the algorithmic creation of game content with limited or indirect user input [11]. Content in the context of PCG can be described as most of what can be contained within a game including maps, rules, textures, items, quests, music, characters, and more [11]. Many popular games have made use of PCG including Rogue, Dwarf Fortress, Diablo, Spore, Civilization, Spelunky, as well as Minecraft itself [11]. The usage of PCG varies from game to game and can range from fully autonomous game design, to automating routine or common aspects of game design. One major critique of PCG in game design has to do with repetition and functionality; rule-based agents are likely to create good looking and functional content that looks similar, and search-based

agents are likely to create more diverse content, but takes more time and resources to ensure that it is functional for the player [5].

Most instances of PCG in video games operate from a 'clean-state' where the generator does not have to consider interaction with preexisting in-game elements [5]. Exploring PCG within Minecraft opens up a new challenge within AI, in which the goal is to produce a functional and believable village settlement that adapts to different environments within a Minecraft map [9]. Instead of generating a village on a clean slate, this problem restricts the generator with the presence of preexisting game elements and focuses on adaptive generation of artifacts [5]. A map in Minecraft is made up of various biomes which contain different types of terrain, elevation gradients, fauna, and bodies of water. In order for a procedurally generated settlement to be functional and believable, it must be adaptive and able to build on top of and in response to elements that already exist in the Minecraft environment. The Generative Design in Minecraft Competition (GDMC) AI settlement generation competition initially proposed this problem in 2018 [8]. GMDC has ran a yearly open competition for researchers and students to submit their algorithm, which is scored by a panel in terms of the algorithms adaptability and functionality [4].

We propose to develop a Procedural Content Generation AI that is capable of generating a functional and believable Minecraft settlement, which is adaptive to varying environmental factors. Based on our review of literature, it is apparent that developing multiple different algorithms to handle individual pieces of the problem has led to better outcomes in previous research.

3 Related Work

3.1 PCG in Games

Procedural generation of dungeons [14].

Survey of pcg dungeon creations [15].

Search based procedural content generation [13].

Declarative procedural generation of architecture with semantic architectural profiles [1].

Procedural content generation via reinforcement learning [7].

Speedtree

3.2 PCG in Minecraft

Multi agent settlement gen in minecraft [3].

World GAN [2].

Growing artefacts and machines with neural cellular automata in minecraft [12].

Green et al. generate floor plans using a constrained growth algorithm and cellular automata [5].

4 Methodology

4.1 Interface Mod and Python Client

We chose to implement our various algorithms & methodologies using Python, but we still needed some way of communicating with Minecraft. To do this we chose to make use of the Generative Design in Minecraft Challenge (GDMC) HTTP Interface Mod and corresponding Generative Design Python Client (GDPC). As mentioned before, GDMC is a yearly competition for researchers and students to submit their procedural generation algorithms for Minecraft. In order to allow competitors to focus more on the algorithms themselves as well as to foster more consistency between how the submissions communicated with Minecraft, some members of GDMC developed these tools & made them open source for all to use.

The GDMC HTTP Interface Mod, is, as it sounds, a mod for Minecraft. A Minecraft mod, or modification, is a user made piece of additional software that adds onto the core source code of Minecraft. Countless mods exist for Minecraft, most of which are for the purpose of enhancing the game's performance/visuals or adding new content to the game, but many functional mods such as this interface mod also exist. In order to make additional software work with Minecraft, however, an API needs to be in place that will make Minecraft recognize and properly implement the mod's code (since Minecraft's code itself is closed & not directly modifiable). The most popular of which is Minecraft Forge, so we had to set up Forge for our machines. With Forge set up, we simply installed the GDMC HTTP Interface Mod and that was that.

The mod itself does one simple yet vital thing within Minecraft: whenever a world is opened a corresponding HTTP server is launched on localhost port 9000. Thus, with the mod set up on our machines, as long as we had a Minecraft world open, we could communicate to it through this HTTP server via basic HTTP requests to certain endpoints. For example, if we wanted to know what block was at a certain (x, y, z) coordinate in the world, we could make a GET request to the server at the blocks endpoint (i.e., "localhost:9000/blocks") with the coordinates as parameters and it would return information about the block at those coordinates. On the other side of things, if we wanted to place a block, we could perform the same request but as a PUT rather than GET request as well as provide a block ID as a parameter, and the corresponding block would be placed at those coordinates in the world. There are multiple other endpoints which serve multiple other purposes, all of which can be found in the GDMC documentation.

Technically the mod alone is enough for us to communicate with Minecraft, although having to write the HTTP requests ourselves is tedious. Luckily the mod's developers also thought of this and created the GDPC, which we will refer to simply as the Python client, to alleviate this tediousness. The Python client is a framework strictly to be used alongside the GDMC HTTP Interface Mod in order to make sending the necessary HTTP requests much easier. It can essentially be thought of as a wrapper, which allows us to simply call

functions to communicate with Minecraft rather than write the HTTP requests ourselves. For example, rather than writing GET & PUT requests to get & place blocks manually, the Python client defines two functions to do exactly that, getBlock & placeBlock. It even goes beyond the basic operations and defines functions such as placeCuboid & placeCenteredCylinder to make building larger more involved structures easier. The Python client also makes obtaining information about the world substantially easier. For example, in one line of code the Python client allows us to obtain a world slice, which, in short, contains all of the information about a certain section of the Minecraft world that we could ever need & puts it in a nicely packaged data structure for us. The rest of the functionality provided by the Python client can again be found in the GDMC documentation, however, the functionality described here is largely all that was needed for this project.

4.2 Terraforming

When testing our program, we quickly encountered an issue specific to Minecraft for this type of procedural village generation, trees. Trees in Minecraft can appear in almost any biome, & can be densely populated or sparsely populated. Trying to place a building on an patch of land that already contains trees leads to various undesirable results, as seen in figure 2. Building on top of preexisting trees can lead to houses being filled with trees, trees poking out the tops of houses, & sometimes even houses being placed on top of trees. Since our goal is to build a settlement in any randomized location within Minecraft, handling the presence of trees is a key factor of an adaptable village generator.

(a) Trees in house   (b) Trees on house
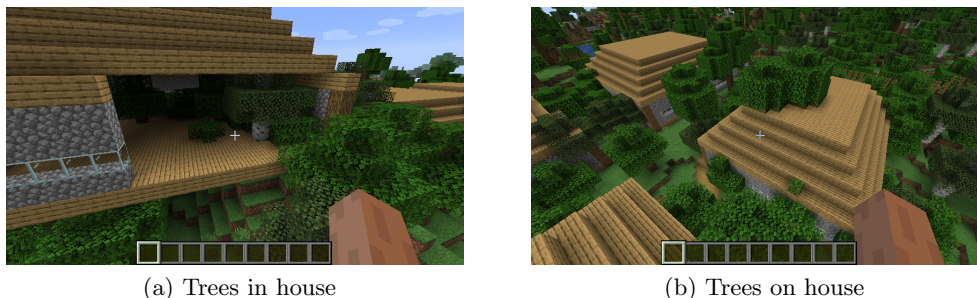
Figure 2: Building on trees examples

This problem of adapting to existing structures is one unique to our project. As discussed previously, procedural content generation most typically operates on a clean slate. Since this problem is somewhat unique to our project, there is not an accepted methodology for handling preexisting tree structures. While this is a problem that any teams who submit or have submitted work to the GDMC competition would have to address, few teams have produced written work detailing their methodology.

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To solve this problem, we used our knowledge of trees & the data structures that are accessible via the GDMC Python client to devise an algorithm that can efficiently locate & remove trees that are present in a randomly selected build area. Trees in Minecraft have the same attributes as real-life trees; they grow straight up from the ground, are made of wood, & typically have leaves surrounding the canopy. Trees in Minecraft are made specifically from wood blocks, which are solely found in the form of trees. With this knowledge, we could create an algorithm that searches the 3-dimensional space until it finds a wood block, then searches the y-coordinate space up & down from that block until wood isn't found any more in either direction. This was our first approach, but it was computationally expensive. The typical build area size we tested on is 128 x 128 x 128 blocks, so at worst this algorithm would explore roughly 2 million blocks. To come up with a more efficient algorithm, we needed to find a better way to search the 3D space - this was quite difficult as there is no maximum number or minimum number of trees in any given x,y,z boundaries within Minecraft.

Figure 3: Example of an 8 x 8 heightmap [3]

In order to restrict the search space, we extracted a height map of the given build area using the GDMC Python client - which is a 2D array the size of the the x,z coordinate space that contains the highest y coordinate value (not containing air or leaves) at each x,z coordinate combination. See figure 3 for an example of a height map for an 8 x 8 area. Instead of searching potentially the entire 3D space, we could search the 2D height map for the presence of wood blocks instead, which would give us a starting node for each tree - the top block of each tree. Since the height map is the highest y coordinate in each x,z coordinate combination, we can assume that any given coordinate in a height map is the top of a tree if the coordinate contains a wood block.

Once the height map has been searched for the presence of wood blocks, the 3D space can be searched, using the tree top coordinates obtained from the height map search as starting nodes. Each node is expanded downwards until wood blocks are not found, giving us the full coordinate map of trees in the build area. An inverted conical buffer is applied to each tree's coordinate space to ensure the removal of leaves, and then the tree coordinates

and buffer space are replaced with blank space. This search algorithm is much more efficient than the first search algorithm used, & at worst searches roughly 16,000 blocks in a 128 x 128 x 128 build area.

4.3 Plot Analysis

Talk about plot analysis

4.4 House Building

With land cleared & plot locations determined, the next step was to build a structure at each plot. To start off we chose to implement arguably the most common structure in Minecraft, something that is a must for any settlement, a house. There are different methods out there that other researchers have developed which make use of various AI techniques to build a house which changes based on different factors, but as our focus was more on the settlement as a whole and making the layout adapt to the land around it, we chose to implement a basic house building procedure. This allowed us to put more time into plot analysis & path building, which were both more important to our overall goal than each individual house.

In the end, we developed one main function which takes in six parameters: a set of starting x, y, & z coordinates, and a set of ending x, y, & z coordinates. The starting x & z coordinates determine the bottom left most point of the house & the ending x & z coordinates determine the top right most point of the house. The starting y coordinate determines floor level & the ending y coordinate determines ceiling level (this does not account for the roof, which goes about five blocks above ceiling level). With these parameters set up & some predetermined materials in place (i.e., oak planks for the floor, cobblestone for the wall, etc.), the function iterates through the different dimensions, placing the floor & some support pillars, followed by the walls & windows, followed by the roof, and finishes off with a door.

Finally. as one last step, we added one supplementary function on top of the main house building function. This function takes in an array of coordinates to build houses at (i.e., the result of our plot analysis) and calls the build house function with a slight random adjustment to each of the parameters. This not only made sense from a code organization perspective, but allowed us to add some random naturalness to our houses rather than have them be all the same size.

4.5 Path Building

With the all of the houses placed, our settlement is nearly completely built, save for one final piece: the paths. Every settlement has paths connecting the different structures, even in real life, so we had to come up with a methodology to generate paths between each of

our structures in a natural looking yet still functional way. The immediate choice that comes to mind, which also turned out to be the best choice for our situation, was A*.

This is not the place to be reviewing the exact details of what A* is, but in short it is a state space searching technique popular in the field of AI. The reason it is popular within AI, and considered an AI technique itself, is because it takes into account the cost of the path (i.e., $cost(p)$) as well as a heuristic evaluation of the path (i.e., $h(p)$), rather than simply calculating the exact optimal path outright. This means we had to determine how to evaluate the cost of our path so far as well as how to heuristically evaluate it in such a way that led to a natural looking yet functional path within Minecraft. As it turns out, the most typical cost & heuristic functions used in standard grid search problems worked incredibly well in Minecraft. In short, the cost function was simply equal to how many blocks the path had stretched so far, and the heuristic function was equal to the Manhattan distance from the end of the path to the goal destination. More specifically, we calculated the Manhattan distance as $|x' - x| + |z' - z|$, where (x, z) are the coordinates for the end of the current path & (x', z') are the coordinates for the goal destination. One might understandably ask why the vertical y coordinate is excluded, and it is simply because the resulting paths were better without it. This is most likely because we did not ultimately want to traverse vertically all that often, and all that really mattered was the horizontal traversal of the path.

With the cost & heuristic functions set up, there is only one thing left to determine: the boundaries of our path. More specifically, where can A* look when determining where to place the path, or even more accurately, where can it not look? This is where our implementation of A* had to become slightly modified from most. See, most implementations of A* are concerned with two dimensional grids/planes of some sort, and they do not have to worry about a third, vertical dimension. Simply ignoring the third dimension would not work though, as if we ran it normally it would lead to massive, immediate vertical jumps in the path which not only do not look natural, are non-functional. Also, simply restricting the path to only work in two dimensions is not only does not make sense theoretically since the player is entirely capable of moving vertically, but almost never works in practice since the land in Minecraft is rarely perfectly flat. Thus, this led us to determine that the path should be able to move vertically, but only by one block at a time because any more and the player would not be able to traverse it. This, unsurprisingly, worked very well and led to natural looking & functional paths.

There was still one problem, however, and that was the horizontal boundaries at which A* was able to place paths. If A* is unable to reach its destination in a relatively direct way, it will start trying increasingly indirect ways to reach its destination. In fact, by default, it will exhaustively search the entire possible set of paths within the grid it is searching to determine if there is a possible path. This does not work in Minecraft, however, because the world of Minecraft is, for all intensive purposes, infinitely large. Thus, if there was no immediate direct path, or even a relatively indirect one, A* would continue for as long as possible before terminating. Not only did this lead to ridiculously long run times, but it

also led to extremely inefficient paths. To solve this, we simply put in a restriction that said A* cannot go outside a certain border that was predefined along with the settlement itself. If it was not possible to reach the destination within these boundaries it would simply place the best path it could before terminating.

With all of these parameters & rules in place, we simply had A* run and then place a chunk of blocks at each point along its determined path (as one block did not look natural enough). Then, we set up a simple function which took in the coordinates of the front of each house & built paths between each of the houses such that everything was interconnected. All said & done, this implementation of A* led to relatively natural looking & functional paths.

5 Discussion

5.1 Results

Results here.

5.2 Limitations

Limitations here.

6   Acknowledgments

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