STA 141C - Big Data & High Performance Statistical Computing

Spring 2022

Week 2-2: Flop counts and high-performance matrix commutations

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Announcement

- Group members
- Homework due Apr 21
- Final report due June, 06 2022 @ 11:59pm

Last time

- Computer storage
- Fixed-point and floating-point number systems
- Catastrophic cancellation

Today

- Flop counts and big-O notation
- BLAS and LAPACK

1 Flops and Big-O notations

Algorithm is loosely defined as a set of instructions for doing something (Input \rightarrow Output). Basic unit for measuring efficiency of an algorithm is flops (floating point operation). A *flop* serves as a basic unit of computation, which consists of a floating point addition (+), subtraction (-), multiplication (\times), and division (/). Some books also consider $\sqrt{}$ and > (<) as a flop, although, in general, addition is faster than $\sqrt{}$, in practice, since we only interested in rough (not exact) flop counts, their difference is minor.

How to (roughly) measure efficiency of an algorithm? We use Big-O notation. If n is the size of a problem, we say a function f(n) = O(g(n)) if $f(n) \le ag(n)$, a is a constant. This means that f(n) grows at most in the order of g(n). For example,

•
$$2n^2 - n/2 - 1 = O(n^2)$$

- $n = O(n), n = O(n^2), n = O(n \log n)$
- $n^2 \neq O(n \log n)$

More examples:

- 1. The vector-vector operations: for $a, b \in \mathbb{R}^n$, c is a scalar
 - a + b: n flops, O(n)
 - c * a: n flops, O(n)
 - a'b: n multiplications and n-1 additions, total 2n-1 flops, O(n)
 - what about ab' (outer product)?
- 2. Matrix-vector multiplication: Ab, $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^n$: mn multiplications and m(n-1) additions, total 2mn-m flops, O(mn)
- 3. Matrix-matrix multiplication: AB, $A \in \mathbb{R}^{m \times n}$ and $B \in \mathbb{R}^{n \times p}$: mnp multiplications and mp(n-1) additions, total 2mnp mp flops, O(mnp)

Read more examples: https://mediatum.ub.tum.de/doc/625604/625604

Big-O notation is not the only one used to measure efficiency of an algorithm, there are other notations, such as Θ and Ω . We will introduce them during next week's discussion session.

Knowing how to count flops is important. Compare flops of the two expressions:

$$G \times X \times y$$
 and $G \times (X \times y)$

for $G \in \mathbb{R}^{p \times p}$, $X \in \mathbb{R}^{p \times n}$, and $y \in \mathbb{R}^n$. We will get familiar with the flop counts for common numerical tasks in statistics.

2 BLAS, LINPACK and LAPACK

2.1 BLAS

BLAS stands for basic linear algebra subroutines (see [this] for a complete listing of BLAS functions and [this] explains why it matters). BLAS is the low-level part of the system that is responsible for efficiently performing numerical linear algebra.

```
# find out my BLAS library in numpy
import numpy as np
np.show_config()

blas_mkl_info:
    libraries = ['mkl_rt', 'pthread']
    library_dirs = ['/Users/yuchien/opt/anaconda3/lib']
    define_macros = [('SCIPY_MKL_H', None), ('HAVE_CBLAS', None)]
    include_dirs = ['/Users/yuchien/opt/anaconda3/include']

blas_opt_info:
    libraries = ['mkl_rt', 'pthread']
    library_dirs = ['/Users/yuchien/opt/anaconda3/lib']
    define_macros = [('SCIPY_MKL_H', None), ('HAVE_CBLAS', None)]
    include_dirs = ['/Users/yuchien/opt/anaconda3/include']
```

```
15 lapack_mkl_info:
      libraries = ['mkl_rt', 'pthread']
16
      library_dirs = ['/Users/yuchien/opt/anaconda3/lib']
17
      define_macros = [('SCIPY_MKL_H', None), ('HAVE_CBLAS', None)]
18
      include_dirs = ['/Users/yuchien/opt/anaconda3/include']
19
20 lapack_opt_info:
      libraries = ['mkl_rt', 'pthread']
21
22
      library_dirs = ['/Users/yuchien/opt/anaconda3/lib']
      define_macros = [('SCIPY_MKL_H', None), ('HAVE_CBLAS', None)]
23
      include_dirs = ['/Users/yuchien/opt/anaconda3/include']
```

R default uses BLAS, see [tutorial] to install optimized BLAS/LAPACK libraries.

Level	Operation	Name	Dimension	Flops
1	$\alpha \leftarrow x'y$	dot product	$x,y \in \mathbb{R}^n$	O(n)
	$y \leftarrow y + ax$	saxpy	$a \in \mathbb{R}, x, y \in \mathbb{R}^n$	O(n)
2	$y \to y + Ax$	gaxpy	$A \in \mathbb{R}^{m \times n}, \ x \in \mathbb{R}^n, \ y \in \mathbb{R}^m$	O(mn)
	$A \leftarrow A + yx'$	rank one update	$A \in \mathbb{R}^{m \times n}, \ x \in \mathbb{R}^n, \ y \in \mathbb{R}^m$	O(mn)
3	$C \leftarrow C + AB$	matrix multiplication	$A \in \mathbb{R}^{m \times n}, B \in \mathbb{R}^{n \times p}, C \in \mathbb{R}^{m \times p}$	

Table 1.1: Flop counts for BLAS functions

Note: saxpy is short for scalar a x plus y; gaxpy is short for generalized saxpy. Generally speaking, Level 1 BLAS subroutine does vector-vector operations; Level 2 BLAS subroutine does matrix-vector operations; and Level 3 BLAS subroutine does matrix-matrix operations.

Some operations appear as level-3 but indeed are level-2, for example,

- Column scaling: $A \leftarrow AD, A \in \mathbb{R}^{m \times n}, D = \operatorname{diag}(d_1, \dots, d_n)$ is O(mn)
- Row scaling: $A \leftarrow DA$, $A \in \mathbb{R}^{m \times n}$, $D = \text{diag}(d_1, \dots, d_m)$ is O(mn)

Matrix inversion is more complicate, we will learn that $E \leftarrow E^{-1}$, $E \in \mathbb{R}^{n \times n}$ takes $O(n^3)$.

Example: Computing $X'W^{-1}X$ (e.g., the weighted least square), where $X \in \mathbb{R}^{n \times p}$ and $W = \operatorname{diag}(w_1, \dots, w_n) \in \mathbb{R}^{n \times n}$:

- 1. X' % * % solve(W) % * % X (or np.linalg.solve(W)): takes $O(n^3 + n^2p + np^2)$ flops, matrix inversion is expensive! (transpose requires no flops)
- 2. $X' \% * \% \operatorname{diag}(1/w) \% * \% X$ (or np.diag(1/w)): takes $O(n^2p + np^2)$ flops, why? Can we improve?
- 3. X' % * % (X/w): takes $O(np^2 + np) = O(np^2)$ flops. In numpy, do $X.T \star (X/w)$ and in R, do crossprod(X, X/w). This is fine for R, not for numpy. Why?

More about the crossprod (and tcrossprod) function: [see here]

Bottom line: Always be aware flop counts when writing code!

```
# clean up workspace
mm( list=ls() )

# simple linear regression design matrix X

n <- 100  # dim of matrix

K <- cbind( rep(1,n), (1:n) )</pre>
```

```
7 X
8
9 # weight vector w
10 w <- sqrt( (1:n) )
                        # just so they're different
11 W
# weight matrix
14 W <- diag(w)
# now calculate (X' * inv(W) * X) in four ways:
# first: Correct, but slow, W takes lots of space
17 ptw1 <- proc.time()</pre>
18 W <- diag(w)
19 xwx1 <- t(X) %*% solve(W) %*% X
20 xwx1
proc.time() - ptw1
22
# second: Correct, less slow, takes lots of space
ptw2 <- proc.time()</pre>
25 xwx2 <- t(X) %*% diag(1/w) %*% X
26 xwx2
proc.time() - ptw2
28
29 # third: Wrong, but faster -- recycles w wrong
30 ptw3 <- proc.time()
31 xwx3 <- ( t(X) / w ) %*% X
                                      # ****wrong****
32 xwx3
33 proc.time() - ptw3
34
# fourth: Correct, but looks wrong
36 ptw4 <- proc.time()
37 \text{ xwx4} \leftarrow t(X) \%*\% (X/w)
                            # uses recycling correctly, fast
38 xwx4
39 proc.time() - ptw4
40
_{\rm 41} # fourth: looks different but same execution
42 ptw5 <- proc.time()
43 crossprod(X,X/w)
                                       # correct, fast
44 proc.time() - ptw5
45
46 # done
47 rm( list=ls() )
49 # In numpy, use
50 import time
51 import numpy as np
52 t = time.time()
53
print np.round_(time.time() - t, 3), 'sec elapsed'
```