

```

462
463
464 def spiMasterMultimodeCmd(self,
465                             spi_cmd,
466                             address=None,
467                             data_length=None,
468                             data_buffer=None):
469     # -> self.SpiResult
470
471
472 def submitQueue(queue_handle, channel_handle, ctrlID):
473     if self.m_debug_devCollect:
474         self.m_testutil.bufferDetailInfo(" queue_handle %d ; channel_handle %d ; ctrlID %d"
475                                         % (queue_handle, channel_handle, ctrlID))
476     collect, _dc = pmact.ps_queue_submit(queue_handle, channel_handle, ctrlID)
477     if collect < 0:
478         raise self.PromiraError("ps_queue_submit", collect, self.m_pm_msg.apiIfError(collect))
479
480     return collect
481
482
483
484 if self.m_spi_initialized != True:
485     self.m_testutil.fatalError("attempt to transact on uninitialized SPI bus")
486
487 cmd_byte=spi_cmd[0]
488 cmd_spec=protocol.precedentCmdSpec(spi_cmd)
489 spi_session=protocol.spiTransaction(spi_cmd, cmd_spec)
490 spi_session.setInitialPhase()

```

# SPI EEPROM Read vs. Frequency Test

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Bob Honea

## Overview

A SPI interface connected EEPROM must be tested across a range of interface parameters to verify function within system requirements. A Python script with supporting modules is developed to sweep testing across combinations of interface parameters for multiple target device types.

## Goals

1. Support testing on present system configuration and target EEPROM spec.
2. Modular design, maintainable, upgradeable.

## Specifications

Three EEPROM devices are provided as targets:

1. Microchip SST26VF032B
2. Micron 3.3V MT25Qxxxx
3. Micron 1.8V MT25Qxxxx
4. Promira Serial Platform SPI/I2C/GPIO Adapter
5. Python language to operate within the Lab's Test Harness
6. Use SPI Single Data Wire and Dual Data Wire modes.

## Completed Milestones

- I. Demonstrate SPI Communications
- II. Demonstrate Multi-Configuration Characterization Test Sweeps
- III. Demonstrate that the SPI Proxy Device meets, or fails specs.

## Design Outline

The test program is composed in these key modules:

### I. Frequency Sweeping SPI EEPROM Read Test Driver : testspidut.py

- A. Configuration management provides a readable means of configuration parameter specification, and an accessible table of supported configurations to enable characterization sweeps.
- B. Test command and data read accuracy in a sweep through all supported interface and device configurations.
- C. Display test results for all configurations.

### II. EEPROM Command Interface : eeprom.py

- A. A minimum set of commands are implemented to configure the EEPROM and SPI interface for test operation.
- B. The command set varies between devices of different manufacture, and is taken into account.

### III. Multimode SPI Master Transaction API : spi\_io.py

- A. The SPI\_IO module employs Promira Active User API to manage SPI transactions through the Promira Serial Platform SPI Host Adapter.
- B. Promira Serial Platform does not provide error-free operation. Error rate is at least 1 in every 10K transactions, during sustained communication. These relatively rare failures are recognized with "Promira Error"-Exceptions and fault tolerant responsive exception handling.
- C. The core SPI transaction processor design prioritizes readability and maintainability. Table driven EEPROM SPI command-transaction specification keeps the transaction processor simple, maintainable, and extendable.

## Design Capabilities and Limitations

- I. Target Device Protocol
  - A. Per requirements, only Single bit/per/clock and Dual bit/per/clock SPI transactions are implemented and tested.
  - B. Quad bit/per/clock mode transactions are implemented in the foundation modules.
  - C. Quad bit/per/clock mode transactions are untested, and therefore, not reliable until tested and debugged.
  - D. Multimode transactions are fully implemented, per the specification that Dual bit/per/clock mode be implemented for a Single/Single/Dual mode read command. I.e. Single Mode Cmd Phase, Single Mode Address Phase, Dual Mode Data Phase.
- II. Promira SPI Parameters
  - A. The maximum frequency for the Promira Spi Master transaction processing is between 31 kHz and 80 MHz.
  - B. Testing has exercised the device up to 60 MHz.
  - C. In direct/no-proxy SPI EEPROM testing with Promira and the target DUT board, successful transactions have occurred reliable up to and beyond 50MHz.
- III. Device Power
  - A. Power is set statically on the Bench Power Supply. It is not currently a proven software configurable parameter.
  - B. Promira provides 3.3V, however it cannot provide BOTH 3.3v, and 1.8v for configurations where the DUT and the SPI EEPROM require different supply voltages.
- IV. Promira Device Errors
  - A. The Promira SPI APIs sometimes return error codes, which disrupts processing of a particular SPI EEPROM command.
  - B. Exception processing has been implemented to abort the command, and restart the current sub-test.
  - C. It is proven that these errors are unpredictable, though trending upward with intensity of usage.
  - D. The error statistics for Promira's errors are kept with the test statistics display for transparency, and as an aid to communicating with Totalphase (Promira's Mfgr.) about this problem.



## Supporting Features

The test program is supported by these additional modules:

### IV. Test Result Reporting : `err_fault_histogram.py`

- A. Testing is basically composed in multiple sessions of reading data from the target EEPROM with a mix of read command types. Configuration sweeps, at present are limited to slewing through a range of SPI clock frequencies.
- B. Results reported for each configuration include:
  - 1. Total Read Command Pass/Fail Counts
  - 2. Histogram of Error Counts for each SPI clock frequency
  - 3. Count of failures where all bytes read were a single value.
  - 4. Report of each Promira Adapter fault exceptions.

### V. EEPROM Command Table Implementation : `cmd_protocol.py`

- A. The SPI Transaction Processor executes according to a Command Specification Tuple which enumerates each phase of a transaction's protocol, and includes operational details for each phase. The Command Specification Tuple and any relevant data origin/destination and quantity are sufficient for execution of a command.
- B. The tuple is built from specifications found in the target device's datasheet. The data can be manually transcribed into structures within the command protocol module.
- C. The program `xxxxxxx.py` is able to reduce time and errors by reducing manual operations to extracting the target device command specifications to a spreadsheet, followed by editing for consistency. The program draws the detail from the spreadsheet and generates the python Command Specification Tuples.

## VI. Target EEPROM Configuration Management : `spi_cfg_mgr.py`

- A. A minimum set of commands are implemented to configure the EEPROM and SPI interface for test operation.
  - 1. SPI Clock Frequency
  - 2. Target Device Logic Level and Supply
  - 3. SPI Clock Polarity
  - 4. SPI Clock Level
  - 5. SPI Bit Order
  - 6. EEPROM Base Address
- B. Parameters 3 through 6 may not be changed by SPI EEPROM commands. Synchronizing changes of these device and system parameters can be done with manual edits to the configuration spec data structure.

## VII. EEPROM Read/Write : `testspidut.py`, `eeeprom.py`, `eeeprom_map.py`

- A. The primary function for testing is the data Read function.
- B. The secondary function is to pattern-write the target device in a controlled, and convenient way, requiring a management layer for EEPROM erasure and writing.
- C. EEPROM writing management is implemented with erase-before write logic.
- D. Writing is limited to data aligned on 256 byte page address boundaries.
- E. The writability status of the EEPROM is maintained at the Block, Sector, and Page granularities.

## VIII. EEPROM Recognition, API Configuration: `eeeprom.py`

- A. The read JEDEC ID command is standard on SPI EEPROM command sets, and is used to ID the target device, and select its host-side configuration data. This recognition allows the program to self-configure whenever the JEDEC ID is accessible. In cases where the JEDEC ID is obscured, the device can be manually identified in the Configuration Parameters Table.

## IX. Miscellaneous Support Features: test\_util.py

- A. Display and Debug Detail logging: Results Display and Debug Information can be logged to the screen or a file, or dropped based on a set of control functions.
- B. Fatal errors optionally dump the most recent Detail and Debug information to screen and/or log file.
- C. Functional and Fixed-Seeded Random data patterns are available to pre-format the EEPROM, and to compare read results.
- D. Classified data display distinguishes generic error filled pages from completely single-valued pages (all 0's or FF's). Classified error statistics Annotation classifies erroneous received bytes aids failure analysis.
- E. Display of Promira Spi Adapter errors provides transparency of the devices limitations, as it may not have been intended for our high bandwidth use-case.



SPI Proxy Test Python Modules		
Name	Description	Comments
TestSPIDut	Test Runner	Class implements 'RunTest' method for harness. Impements high-level control of multi frequency (and other multivalued-parameter) SPI Proxy Test.
spi_io	SPI-Promira interface	Transaction Processor
spi_config_mgr	Generates all the tested configurations.	Table based, with code to generate all combinations of test parameters.
promactive_msg	Translates Promira error codes to text descriptions.	
err_fault_histogram	Test progress/statistics display.	Implements a histogram, and special error type histories.
eeeprom	SPI-EEPROM Command Interface.	Single module for Micron and Microchip devices. (alternative per-chip modules in progress)
eeeprom_map	A per page/sector/block erase/write status class.	Facilitates efficient erase/read/write during pattern writing, and other read/write activities.
eeeprom_devices	Configuration tables for various target EEPROM devices.	
cmd_protocol	Transaction Descriptor Tables, and transaction descriptor class.	The 'spi_transaction' object is the template for the spiMasterMultimodeCmd transaction processor.



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