## Create the following files:

- 1. myArray.h: Implement a dynamic array similar to the STL vector, which should support the following operations at least:
  - $push\_back()$ : Add a new element at the end of the array, after its current last element.
  - pop\_back(): Remove the last element in the array if there exits elements. Whether reducing the container capacity or not is OK for simplicity.
  - iterator: It can be used to access elements and iterate through the array
  - begin(): Return an iterator pointing to the first element in the array
  - end(): Return an iterator to one beyond the last element
  - size(): Return the number of elements in the array
  - capacity(): Return the size of the storage space currently allocated for the array, expressed in terms of elements. It can be equal or greater than size(). When the capacity is exhausted and more is needed, you could simply double it.
  - operator[]: [n] will return the element at position n in the array.
  - operator =: Assign new contents to the container, replacing its current contents, and modifying its size accordingly.

```
template<typename Elem>
  class myArray {
      // representation and implementation details
  public:
      class iterator; // member type: iterator
      void push_back(const Elem& v); // insert v at end
      void pop_back();// remove the last element
      iterator begin(); // iterator to first element
      iterator end( );// iterator to one beyond last element
11
12
      int size(); // the number of elements
13
      int capacity();
14
15
      Elem& operator[] (const int i);
      Elem& operator= (const Elem i);
18
 };
```

**Note:** Change or add more functions if needed.

2. myData.h: Define a Struct or Class myData with two fields val and addr. Complete  $Cmp\_by\_val$  and  $Cmp\_by\_addr$  to sort arrays according to myData.val and myData.addr respectively in ascending order.

```
template<typename T>
  struct myData{
      T val;
      myData < T > * addr;
      //...
  };
  template<typename T>
  struct Cmp_by_val {
      bool operator()(myData<T> a, myData<T> b) {
10
          return a.val < b.val; //compare val
13 };
14
  template<typename T>
  struct Cmp_by_addr {
      bool operator()(myData<T> a, myData<T> b) {
17
          return a.addr < b.addr; //compare addr
      }
19
  };
```

**Note:** Change or add more functions if needed.

3. mySort.h: Implement a generic sorting algorithm like the built-in sort, which is able to serve your dynamic array defined in myArray.h.

```
template <class Iterator >
void mySort(Iterator first , Iterator last)

template <class Iterator , class Compare>
void mySort(Iterator first , Iterator last , Compare comp)
```

The *comp* means that users can parameterize sort by the comparison criteria.

**Note**: You can do with any sorting algorithms, e.g. merge sort, insertion sort, quick sort and so on. But don't use the built-in *sort* directly!

- 4. main.cpp: The main.cpp is given by us. Use it to test whether your myArray.h, myData.h and mySort.h are correct. The process of the code is as follows, which also can be seen in main.cpp.
  - Test my Array.h: Create an my Array object and call its members.
  - Test myData.h: Create an object of myArray < myData >. Randomly input some numerical values. Each element in myArray < myData > object stores each input and the address of this element. Figure 1 illustrates the process.

• Test mySort.h: Sort the myArray < myData > object above using mySort by val and addr fields respectively.

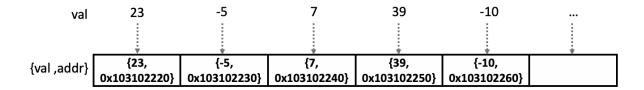


Figure 1: Elements in the dynamic arrays.

**Note**: You can modify some details of main.cpp to satisfy requirements.

## **Important Notes:**

- Reference: The book, Programming: Principles and Practice Using C++, Stroustrup., in the Reading Material. Please refer to Chapter 20 Containers and Iterators and Chapter 21 Algorithms and Maps, which are also covered in Lecture 8.
- Remember to submit your makefile!
- Due: 2019/10/19 11:59pm