

Level 4 - Button Modes

```
#include <UltraDistSensor.h>
#include <LiquidCrystal_I2C.h>
#include <Wire.h>

UltraDistSensor Sensor Name ;
LiquidCrystal_I2C lcd(The LCD Address , 20, 4);

int Button Name = ButtonPin ;
int Button Value = 0;
int Button Clicks Variable = 0;

void setup() {

    lcd.init( );
    lcd.backlight( );
    Sensor Name .attach(TrigPin Name, EchoPin Name);

    pinMode(Button Name , INPUT);

}

void loop() {

    lcd.setCursor(X Coordinate , Y Coordinate);
    Button Value = digitalRead(Button Name );

    if(Button Value == HIGH){

        Button Clicks Variable ++;
        if (Button Clicks Variable >= 4){
            Button Clicks Variable = 0;
        }

    }

}
```

```

if (Button Clicks Variable == 0){

    lcd.print(" FirstName");
    lcd.setCursor(X Coordinate , Y Coordinate);
    lcd.print(" LastName");

} else if (Button Clicks Variable == 1) {

    lcd.clear( );
    lcd.print(" Distance: ");
    int Distance Variable = Function Name();

    if( Distance Variable == 0 || Distance Variable == -1 ){
        lcd.setCursor(0, 1);
        lcd.print("Object Not Found");
    } else {
        lcd.print(Function Name);
    }

} else if (Button Clicks Variable == 2){

    int Value 1 Name = Function Name ;
    delay(200);
    int Value 2 Name = Function Name ;
    lcd.clear( );

    lcd.setCursor(X Coordinate , Y Coordinate);
    lcd.print("Object");

    if(Value 1 Name > Value 2 Name ){

        lcd.setCursor(X Coordinate , Y Coordinate);
        lcd.print("Outgoing");

    } else if(Value 1 Name < Value 2 Name ){

        lcd.setCursor(X Coordinate , Y Coordinate);
        lcd.print("Incoming");

    } else {

        lcd.setCursor(X Coordinate , Y Coordinate);
        lcd.print("Stationary");

    }

}

```

```

} else if (Button Clicks Variable == 3){

    int Value 1 Name = Function Name ;
    delay(500);
    int Value 2 Name = Function Name ;
    lcd.clear( );

    int Speed value = ;
    lcd.setCursor(X Coordinate , Y Coordinate);
    lcd.print("Speed: ");
    lcd.setCursor(X Coordinate , Y Coordinate);
    lcd.print(Speed value);
    lcd.print(" inches/sec");

}

delay(300);

}

```

```

int Function Name () {

    float distances = 0;
    float numTimes = 0;
    float Distance Storage Variable;

    for(int i = 0; i < Number of Readings; i++){

        Distance Storage Variable = Sensor Name.distanceInInch( );

        if(Distance Storage Variable != 0.0){
            distances += Distance Storage Variable ;
            numTimes;
        }

    }

    int averageDistance = Calculate the Average Distance ;
    return averageDistance;

}

```