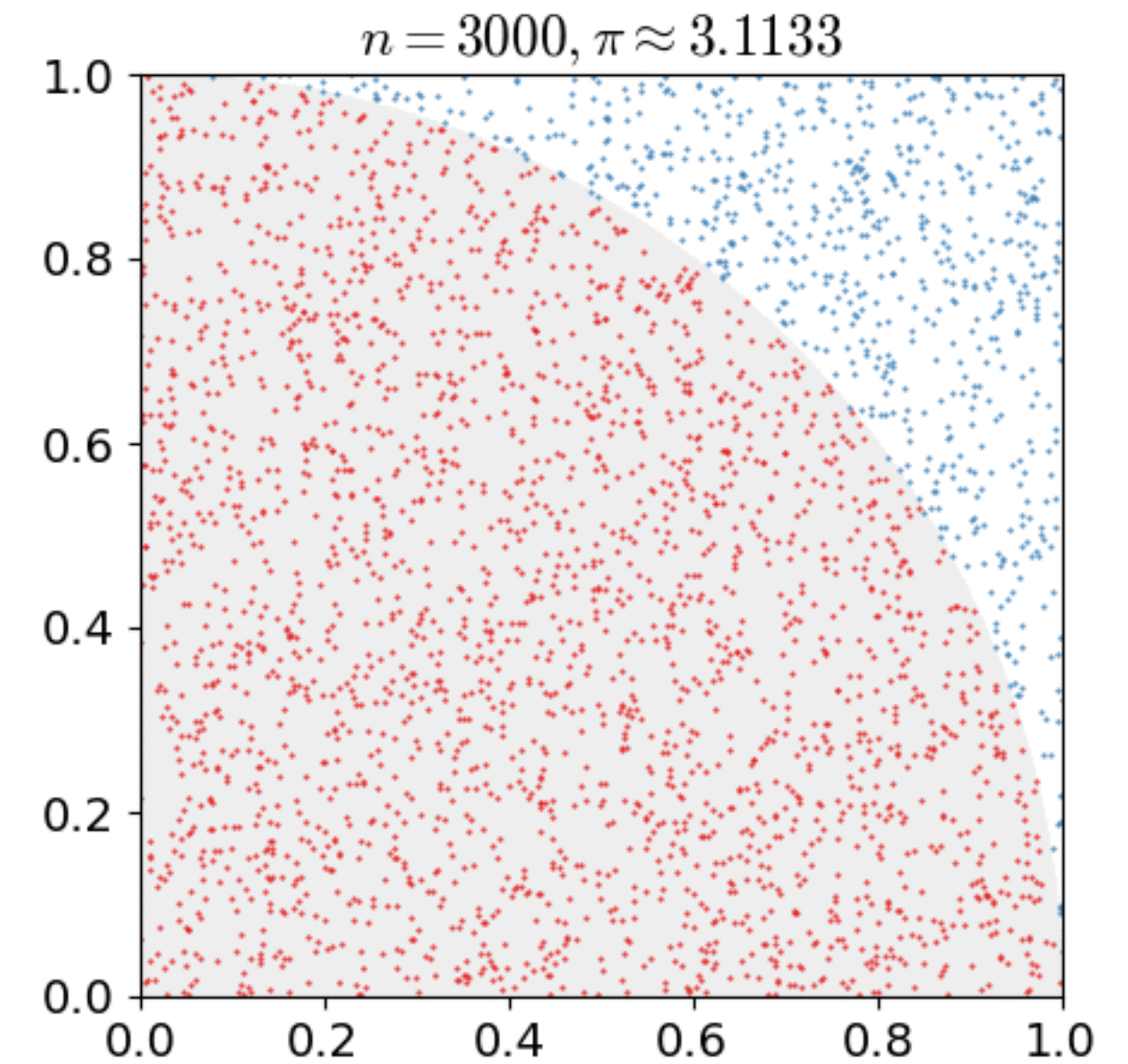


International Workshop on Modeling Biological Macromolecules

- This module will consist of a
 - mini-lecture on molecular simulation including Markov Chain Monte Carlo, Molecular Dynamics and Hybrid Monte Carlo
 - walk-through of a python script to run HMC with Robosample
- At the end of this module, you should be able to address these questions:
 - What is Markov Chain Monte Carlo and Molecular Dynamics?
 - What is Hybrid Monte Carlo and why do people use it?
 - Generally speaking, how does a Hybrid Monte Carlo simulation work?
- You should also be able to run a simulation of a simple system using Robosample

Monte Carlo

- Monte Carlo simulation:
 - named after famous gambling city
 - uses random numbers
 - usually applied to hard deterministic or probabilistic problems
- Examples:
 - pi approximation
 - virtually tossing a coin or rolling a dice many times
 - estimating financial risk (uncertainty in unit price, sales...)
 - solving integrals / differential equations
- Hard to use for complex highly dimensional problems



Markov Chains

- Stochastic process: Sequence of indexed random variables

X = stochastic process

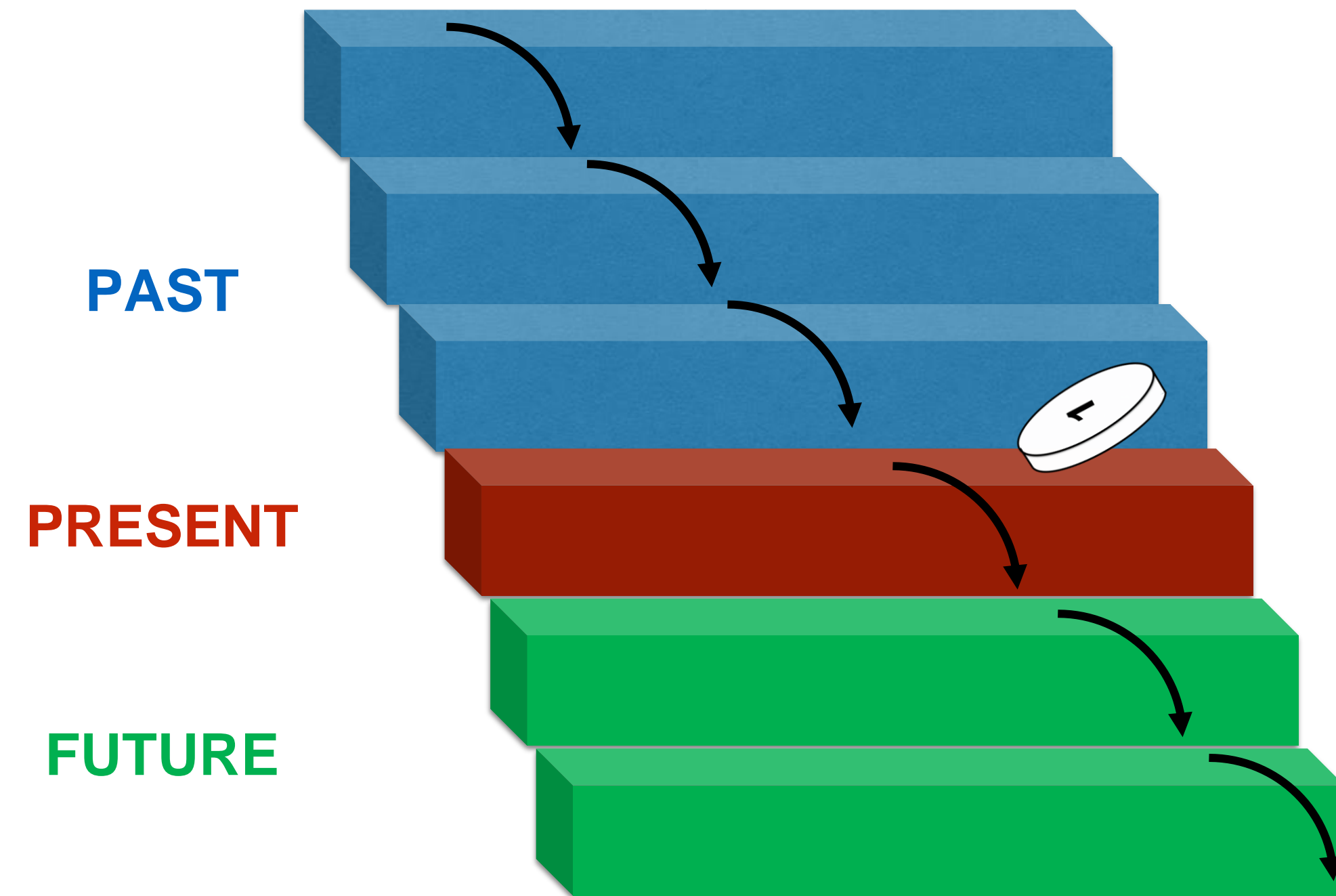
\mathcal{X} = state space

π = probability vector; $\pi = [\pi(A), \pi(B)]$, $\pi(A) = P(X = A)$

$X = \{X_0, X_1, X_2, \dots\}$, $X_i = x \in \mathcal{X}$, $\pi(\mathcal{X})$

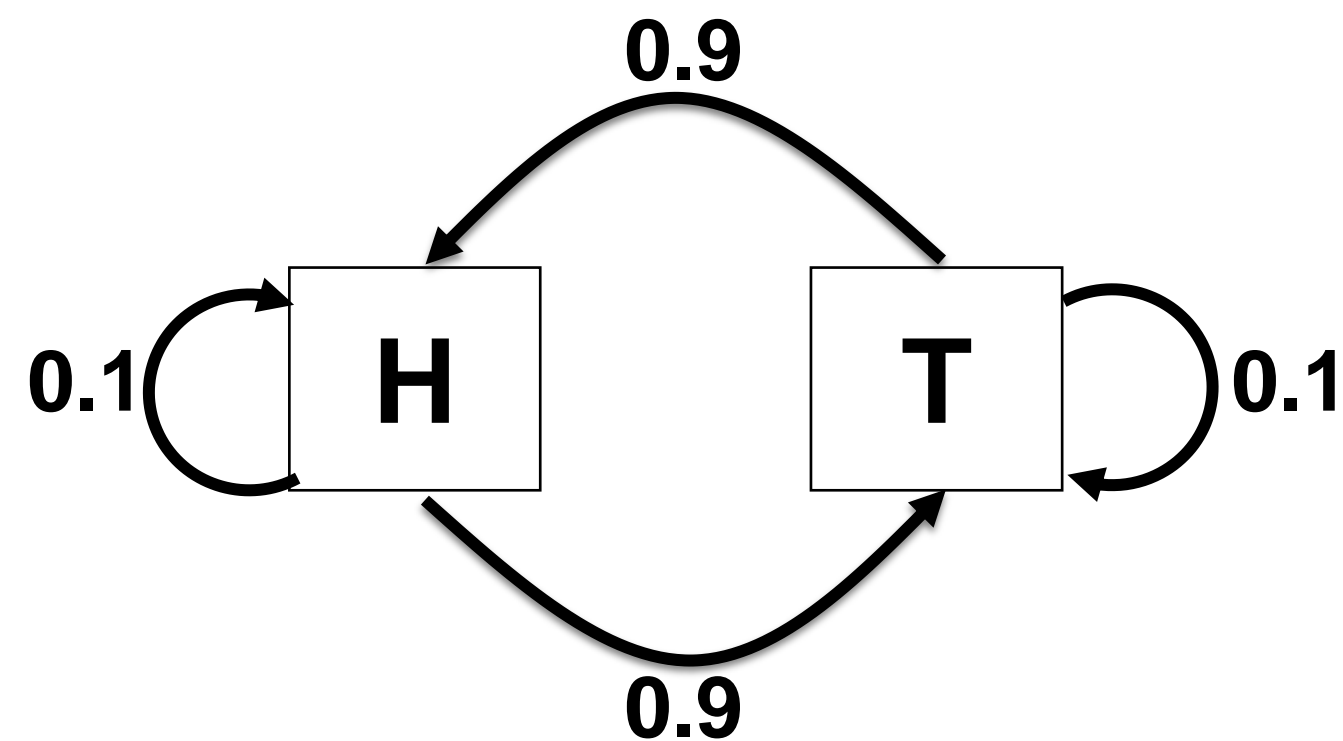
- Markovian property: memoryless:
future only depends on the present

$$P(X_{i+1} | X_i = x_i, X_{i-1} = x_{i-1}, \dots, X_0 = x_0) = P(X_{i+1} | X_i = x_i)$$



Markov Chains

- Markov chains can be represented as graph diagrams where nodes are states and edges can be weighted by transition probabilities



- Transition probabilities can be expressed as a **transition matrix**

transition matrix

$$Q = \begin{pmatrix} 0.9 & 0.1 \\ 0.1 & 0.9 \end{pmatrix}$$

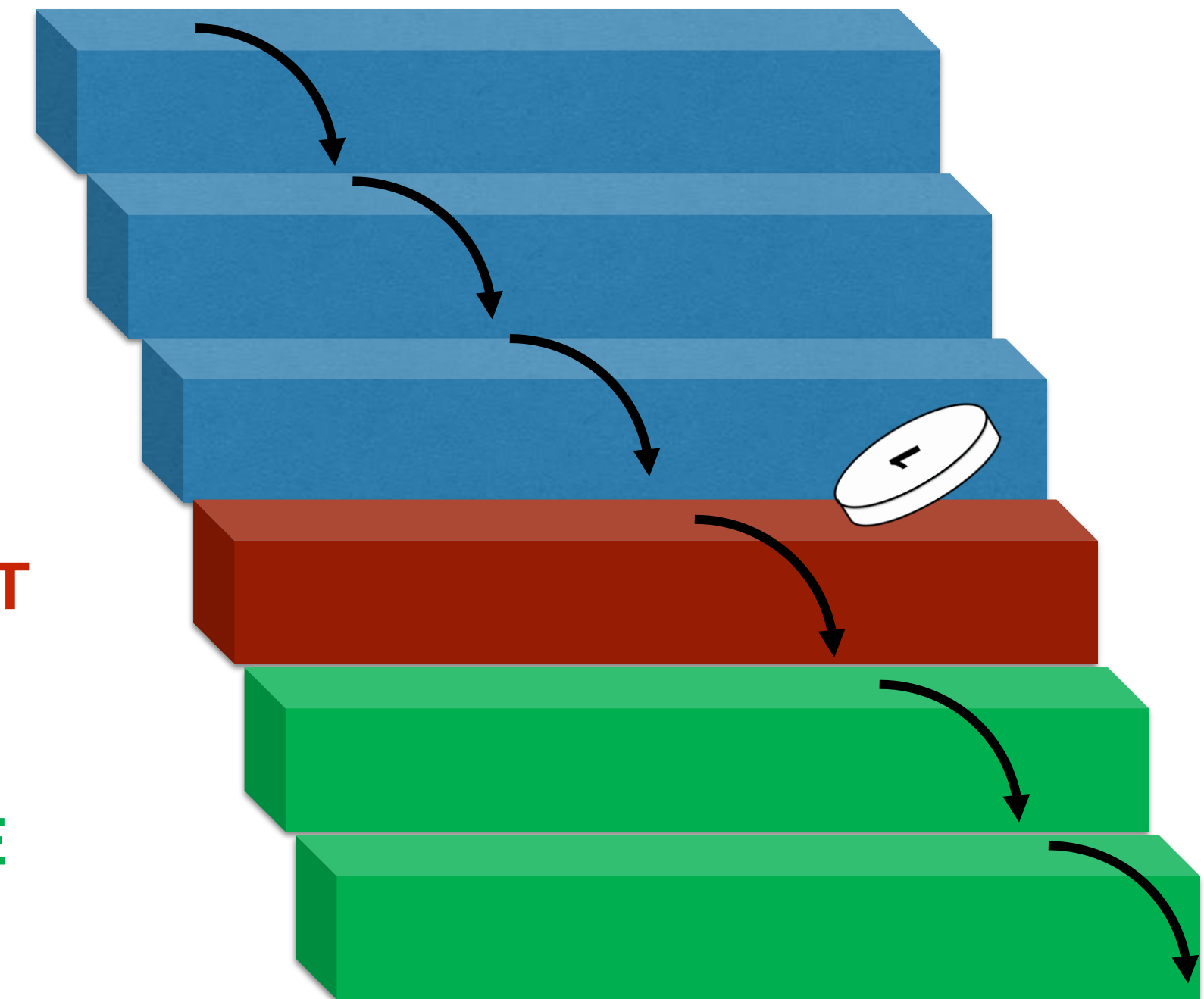
probability vector evolution

$$\pi_{k+1} = \pi_k Q$$

PAST

PRESENT

FUTURE

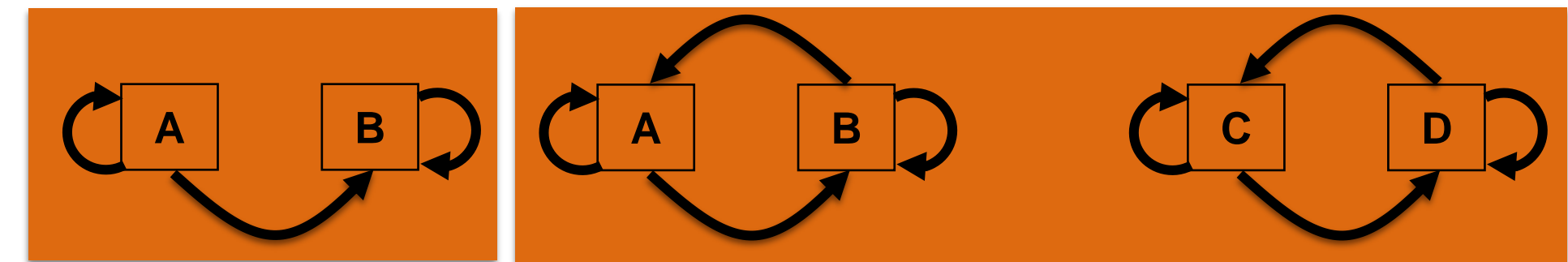


Markov Chains Properties

Stationarity (equilibrium): $\pi Q = \pi$

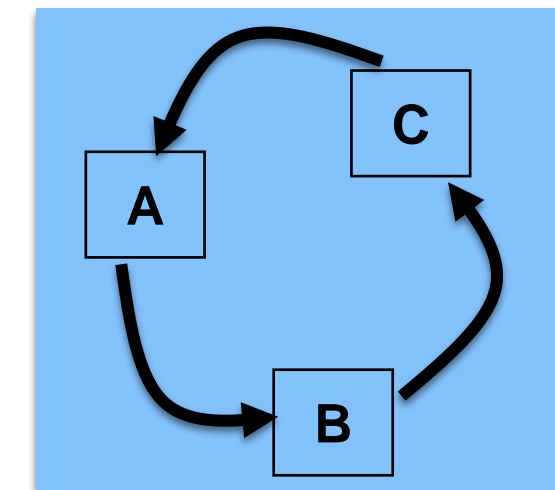
- **Irreducibility**

for any two states A, B, if we start in A, we will eventually get to B



- **Aperiodicity**

states are reached at integer multiples



- **Reversibility** guarantees convergence to a stationarity distribution (detailed balance condition)

$$\pi(A)P(A \rightarrow B) = \pi(B)P(B \rightarrow A)$$

Metropolis – Hastings Algorithm

Derivation

- Markov Chain Monte Carlo usefulness: construct our own Markov Chain that converges to a specific probability distribution.

for molecules : the states are the configurations

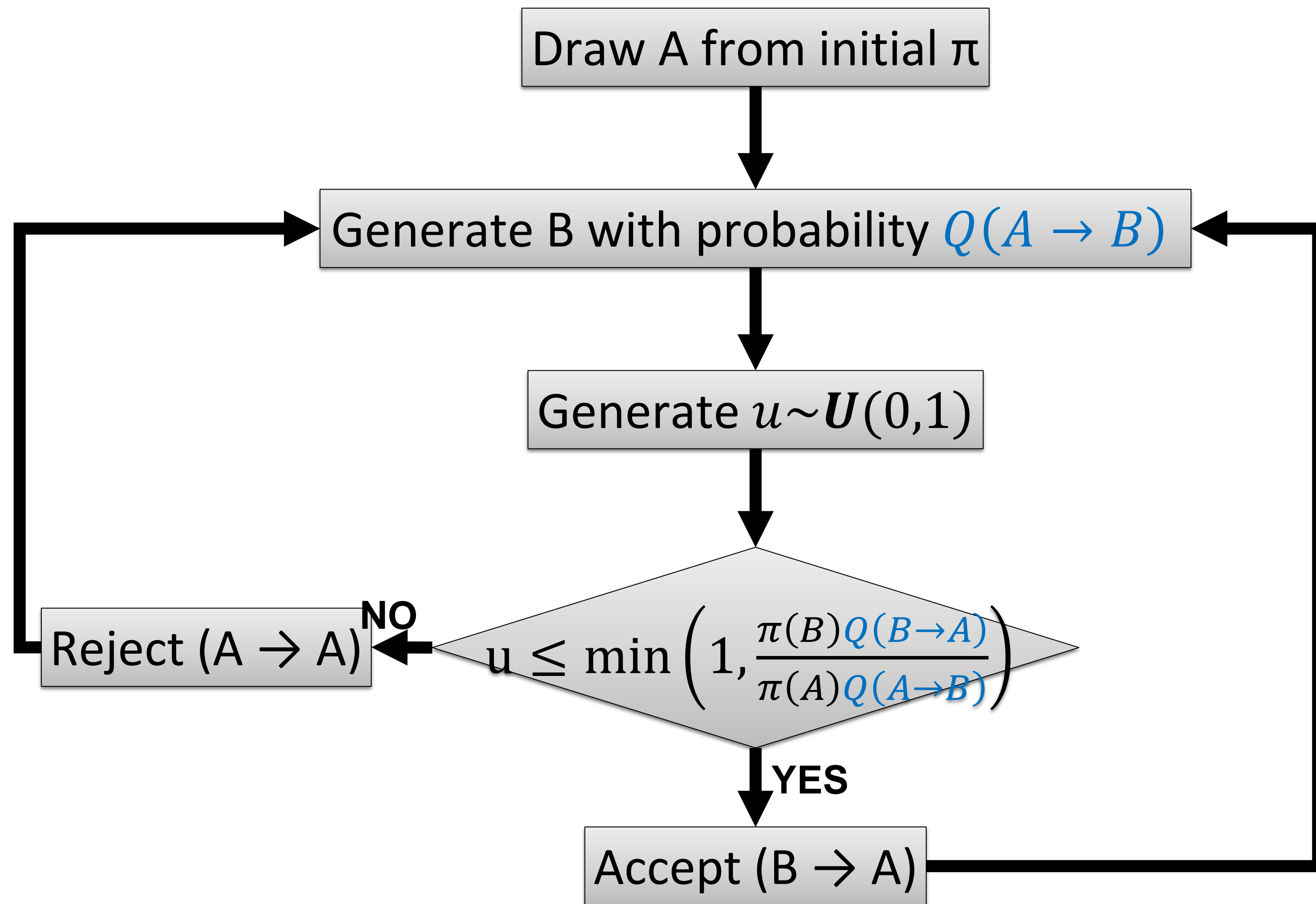
detailed balance $\pi(A)P(A \rightarrow B) = \pi(B)P(B \rightarrow A)$

proposal distribution $\pi(A)Q(A \rightarrow B) \neq \pi(B)Q(B \rightarrow A)$

correcting term $\pi(A)Q(A \rightarrow B)\alpha(A, B) = \pi(B)Q(B \rightarrow A)\alpha(B, A) \Leftrightarrow \frac{\alpha(A, B)}{\alpha(B, A)} = \frac{\pi(B)Q(B \rightarrow A)}{\pi(A)Q(A \rightarrow B)}$

Metropolis-Hastings $\alpha(A, B) = \min\left(1, \frac{\pi(B)Q(B \rightarrow A)}{\pi(A)Q(A \rightarrow B)}\right)$

Metropolis – Hastings Algorithm

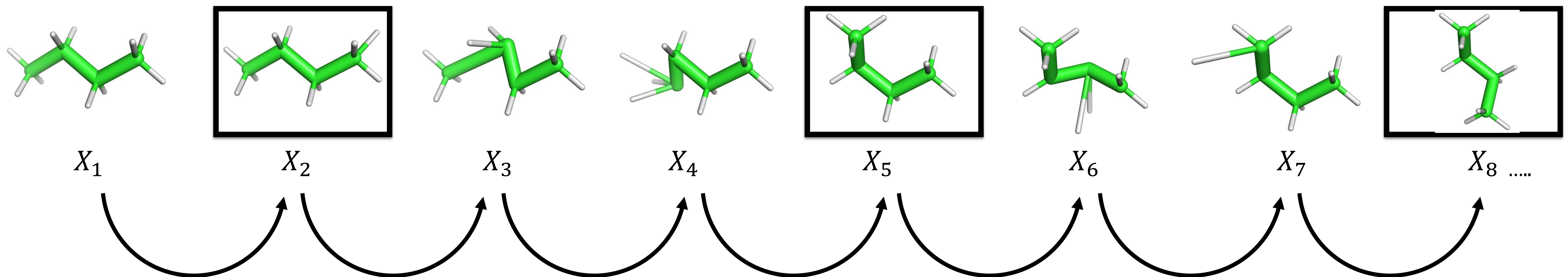


$\pi(u \leq R) = R$ for any $R \in [0,1]$
and $u \sim U(0,1)$



Markov Chain Monte Carlo for molecules

- Randomly choose configurations



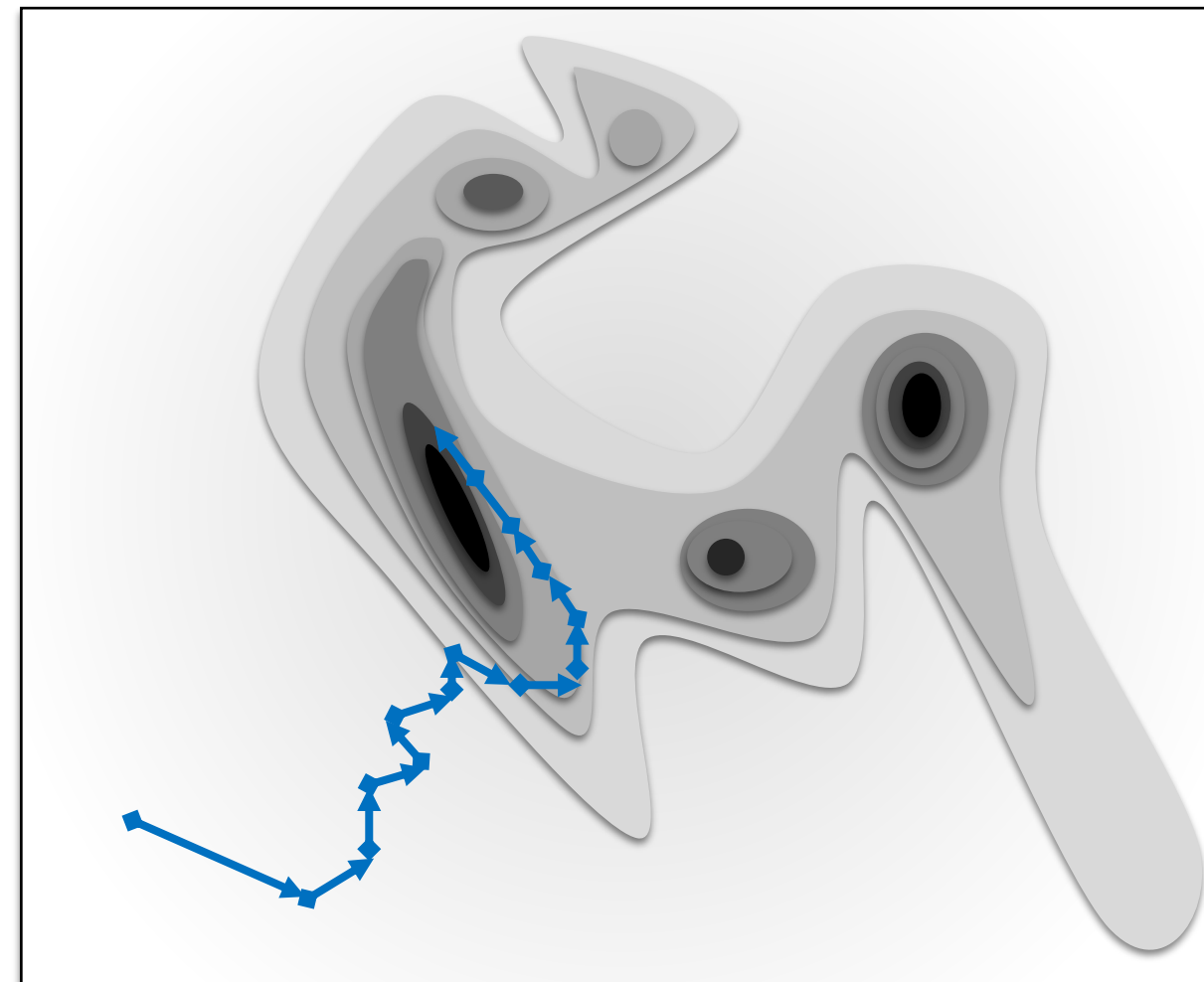
$$\pi(X) = \frac{1}{Z} e^{-\frac{1}{kT} \cdot E(X)}$$

MCMC In Practice:

When do we start recording?

- The initial distribution is not known. Burn-in
 - achieve “stationarity” within a certain threshold
 - get to a high probability region

$$\bar{X}_n \rightarrow \mu \text{ as } n \rightarrow \infty$$



MCMC In Practice:

When do we stop recording?

- Convergence of π^N towards the limiting distribution π_{true} $dist(\pi^N, \pi_{true}) \leq \varepsilon$
- Total variation distance (TVD)

$$dist(\pi^N, \pi_{true}) = \frac{1}{2} \sum_{\mathcal{X}} |\pi^N(x) - \pi_{true}(x)| \quad dist(\pi^N, \pi_{true}) = \sup_{E \text{ is any event}} (\pi^N(E) - \pi_{true}(E)),$$

- Hellinger distance

$$dist(\pi^N, \pi_{true}) = \frac{1}{\sqrt{2}} \sqrt{\sum_{\mathcal{X}} \left(\sqrt{\pi^N(x)} - \sqrt{\pi_{true}(x)} \right)^2}$$

- Relative entropy (information gain, Kullback–Leibler divergence)

$$dist(\pi^N, \pi_{true}) = \sum_x \pi^N(x) [-\log \pi_{true}(x)] - \left(\sum_x \pi^N(x) [-\log \pi^N(x)] \right)$$

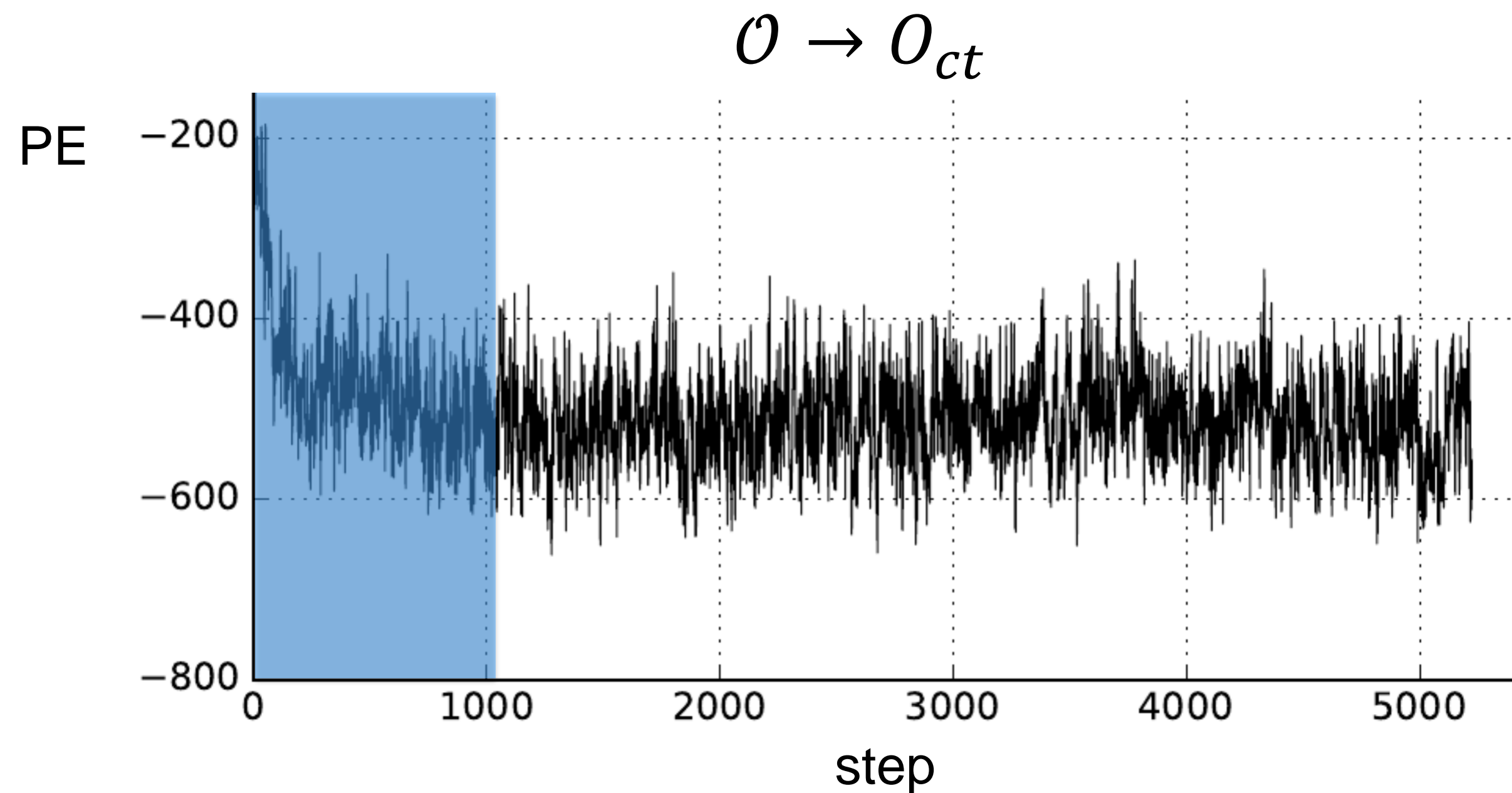
- Mixing time

$$t_{mix}(\varepsilon) = \min\{t: dist(t) \leq \varepsilon\}$$

MCMC Simulation In Practice.

When do we stop recording?

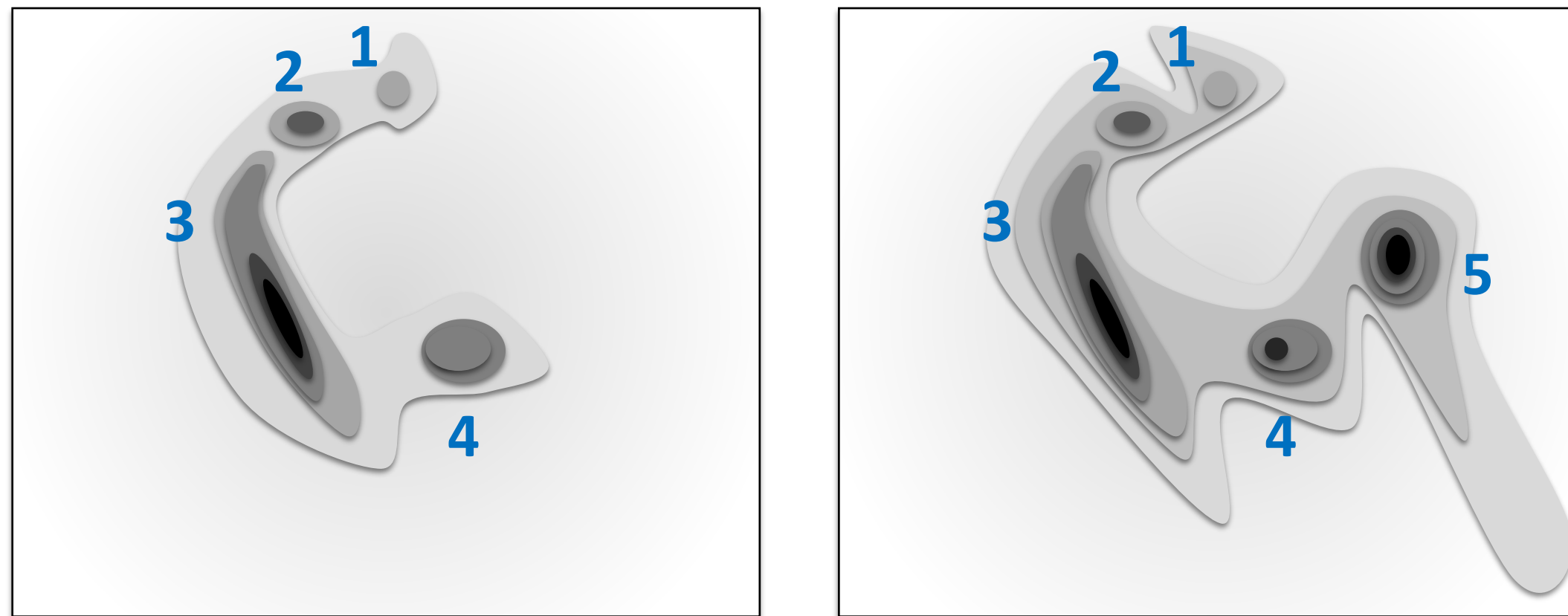
- Convergence of observables tests when the reference π_{true} is not known



MCMC Simulation In Practice.

When do we stop recording?

- Self-consistency tests: “monitoring the overlap between full and partial trajectories”. E.g. constant number of clusters.



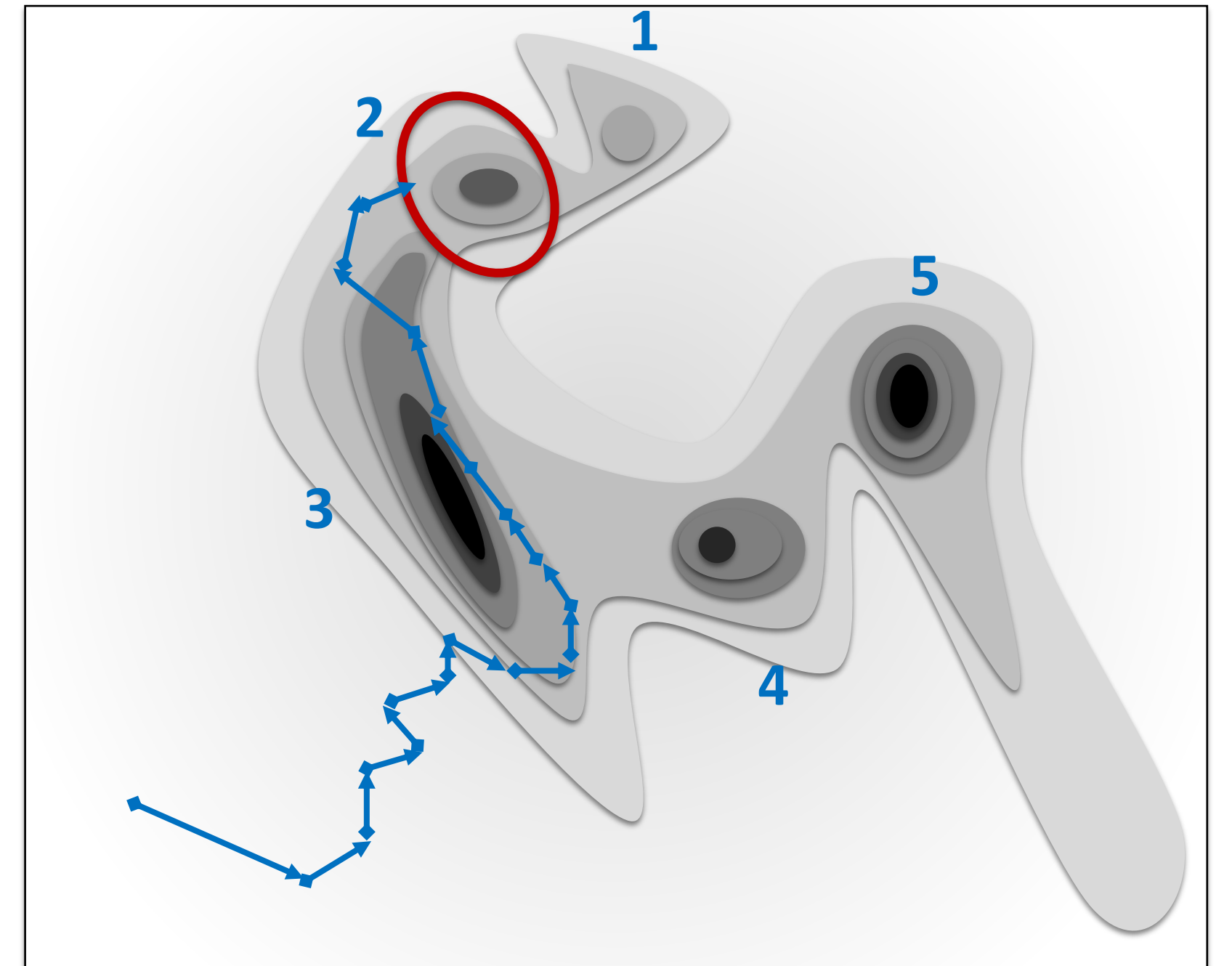
Sawle and Ghosh, “Convergence of Molecular Dynamics Simulation of Protein Native States: Feasibility vs Self-Consistency Dilemma.”
Grossfield A, Zuckerman DM. Quantifying uncertainty and sampling quality in biomolecular simulations.

MCMC In Practice:

How efficient is it?

- Correlation time analysis: time required to lose memory of previous values
- Hitting time
- Cover time
- Mean first passage matrix

	1	2	3	4	5
1					
2					
3					
4					
5					



What is Molecular Dynamics?

- Add energy to a system modeled by molecular mechanics and simulate its progress with time using Newton's second law of motion $\vec{F} = ma$
- See 0:45 to 2:20 of “An Introduction to Molecular Dynamics” (<https://www.youtube.com/watch?v=ILFEqKI3sm4>)
- See a separation of alkane and water: <https://www.youtube.com/watch?v=xcMSHy3CqXA>

Why do biological molecular dynamics?

- “everything that living things do can be understood in terms of the jiggings and wiggings of atoms” - Richard Feynman
- Check out David’s molecular dynamics YouTube playlist:
https://www.youtube.com/playlist?list=PLYEyeVFrqfAu0ft6sF4vVe5FOEbJYyi_L

General MD Algorithm

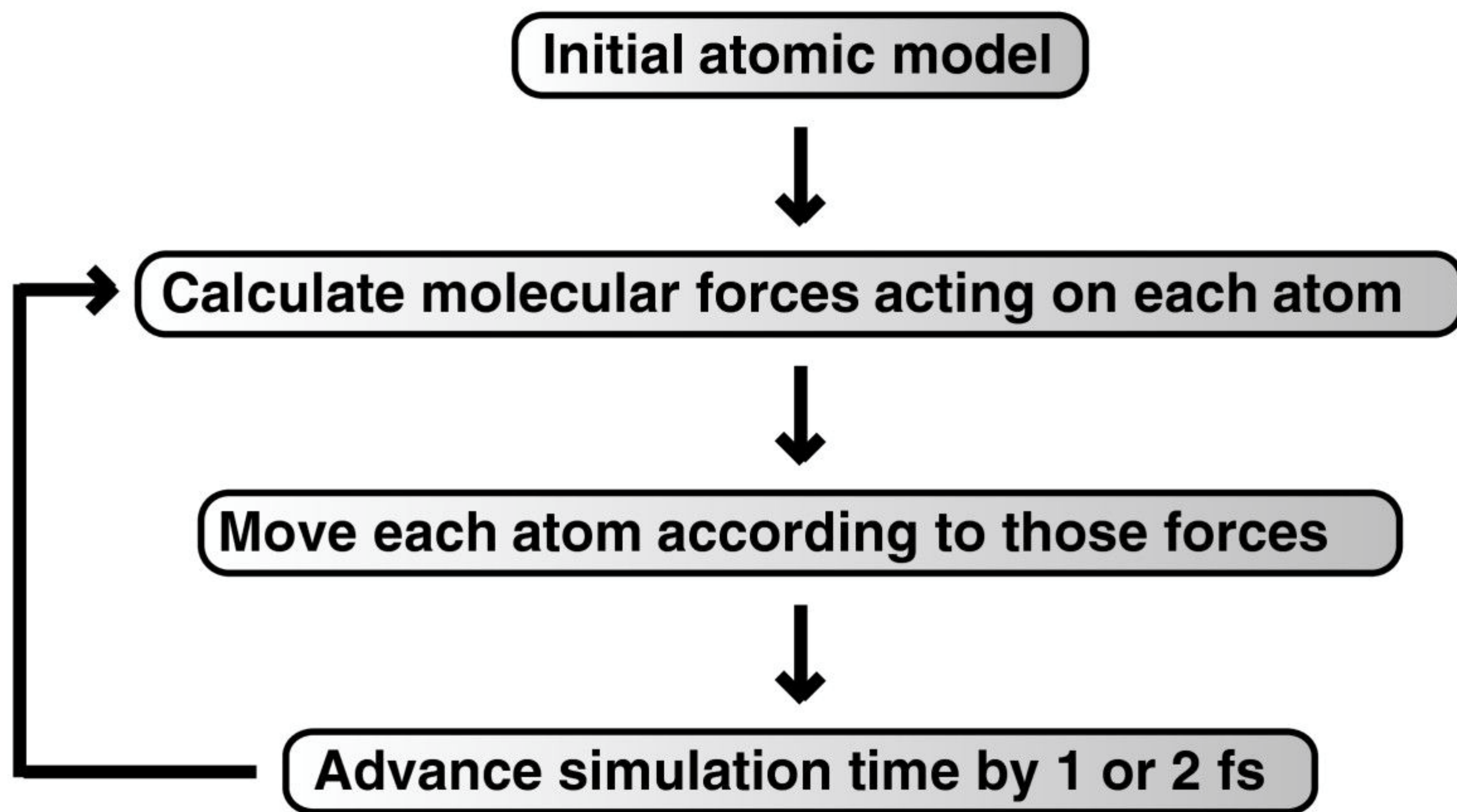


Figure 2 of Durrant & McCammon, 2011

How do we calculate trajectories?

- Evolution in time given is by classical mechanics:

$$\begin{array}{l} \mathbb{T}: \\ \text{Force: } \frac{dp}{dt} = -\frac{\partial \mathcal{H}}{\partial x} \\ \text{Velocity: } \frac{dx}{dt} = \frac{\partial \mathcal{H}}{\partial p} \end{array}$$

- Integrate trajectory using Taylor expansion

$$x(t) = \frac{1}{0!} x(t_0)(t - t_0)^0 + \frac{1}{1!} \frac{dx}{dt}(t_0)(t - t_0)^1 + \frac{1}{2!} \frac{d^2x}{dt^2}(t_0)(t - t_0)^2 + \frac{1}{3!} \frac{d^3x}{dt^3}(t_0)(t - t_0)^3 + \dots$$

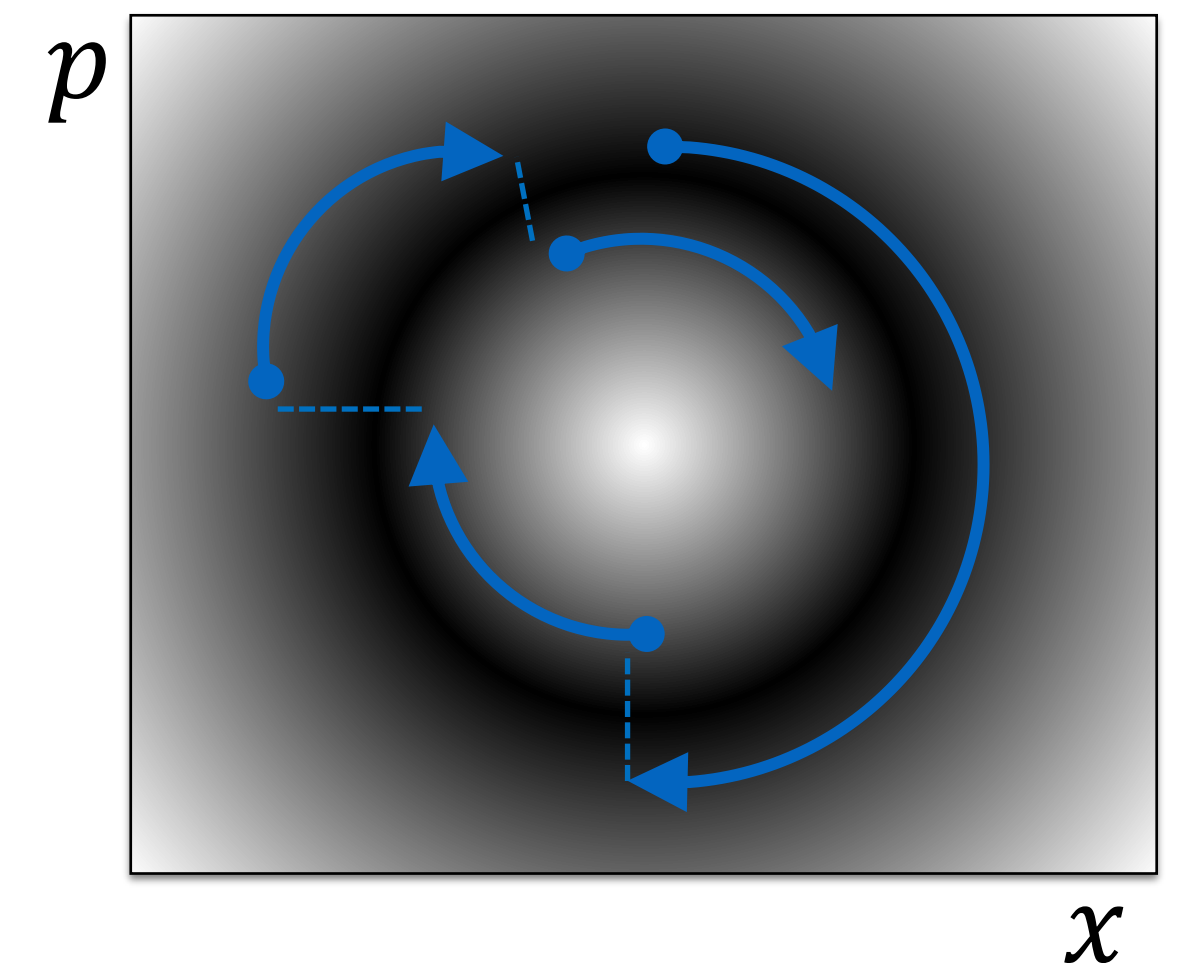
Ergodic Hypothesis

- Evolution in time given by classical mechanics:

$$\begin{aligned} &\mathbb{T}: \\ \text{Force: } &\frac{dp}{dt} = -\frac{\partial \mathcal{H}}{\partial r} \\ \text{Velocity: } &\frac{dr}{dt} = \frac{\partial \mathcal{H}}{\partial p} \end{aligned}$$

- Time averages equals space averages

$$\frac{1}{t} \int_0^t \mathcal{O}(\mathbb{T}^s(r_0, p_0)) ds = \int_{\Gamma} \pi(r, p) \mathcal{O}(r, p) dr dp$$

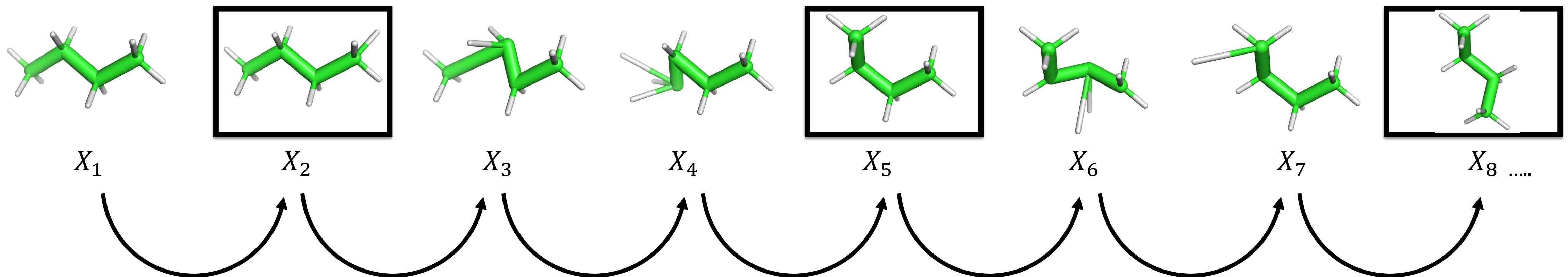


Discussion

	MCMC	MD
Uses random numbers as its main tool		
Needs accelerations during calculation		
May use the Metropolis-Hastings algorithm		
Allows the calculation of averages		
In principle, has memory of its past		

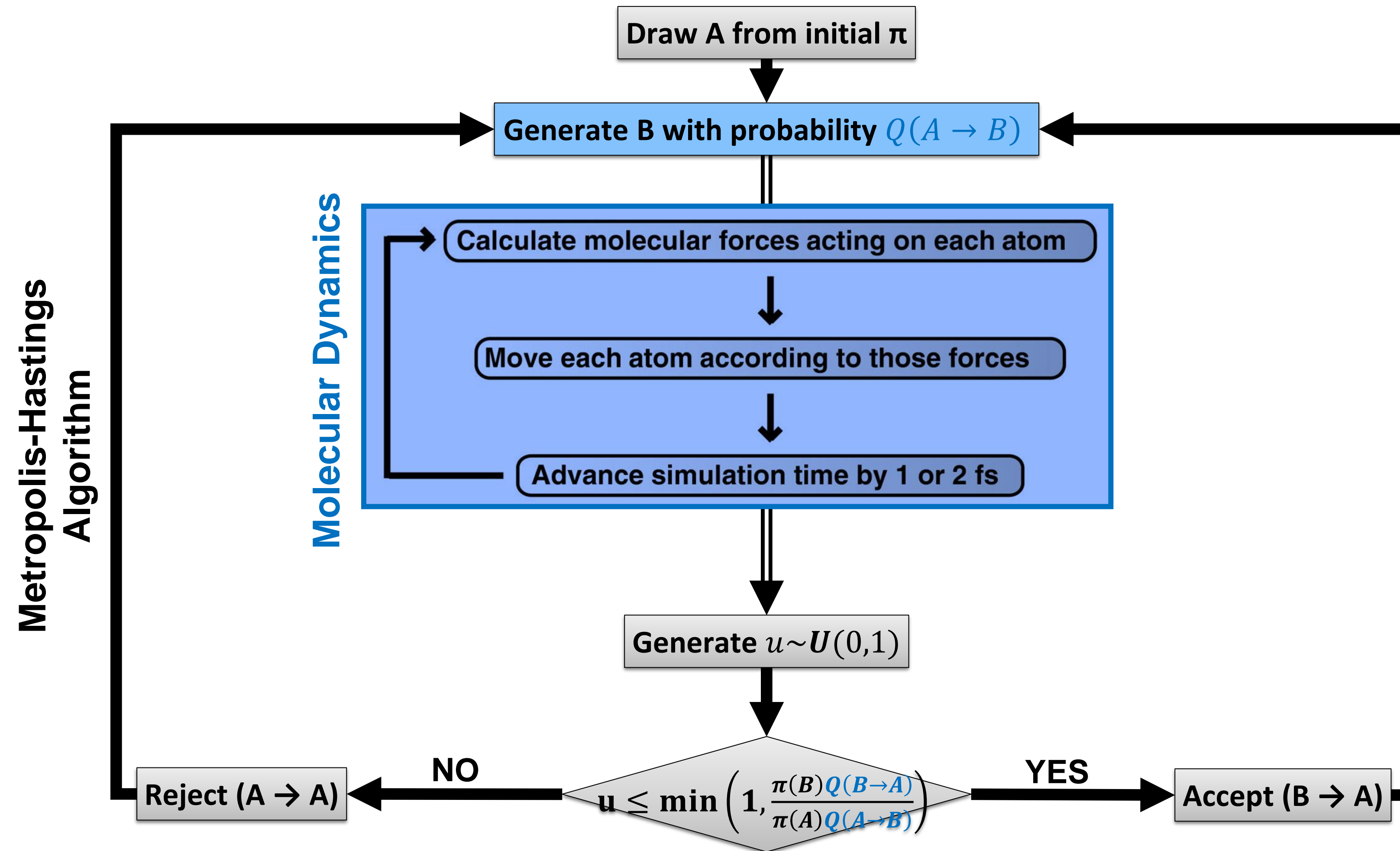
Markov Chain Monte Carlo for biological molecules

- Randomly chosen configurations lead to low acceptance rates



- Can we do better?

Hybrid Monte Carlo



Why does it work?

- Sample from the joint distribution $\pi(\mathbf{r}, \mathbf{p})$ and use the marginal $\pi(\mathbf{r})$ because \mathbf{r} does not depend on \mathbf{p}

$$\pi(\mathbf{r}, \mathbf{p}) \propto e^{-\beta U(\mathbf{r})} e^{-\beta \frac{1}{2} \mathbf{p}^T \mathbf{M}^{-1} \mathbf{p}} = e^{-\beta U(\mathbf{r})} \mathcal{N}(\mathbf{0}, \mathbf{M})$$

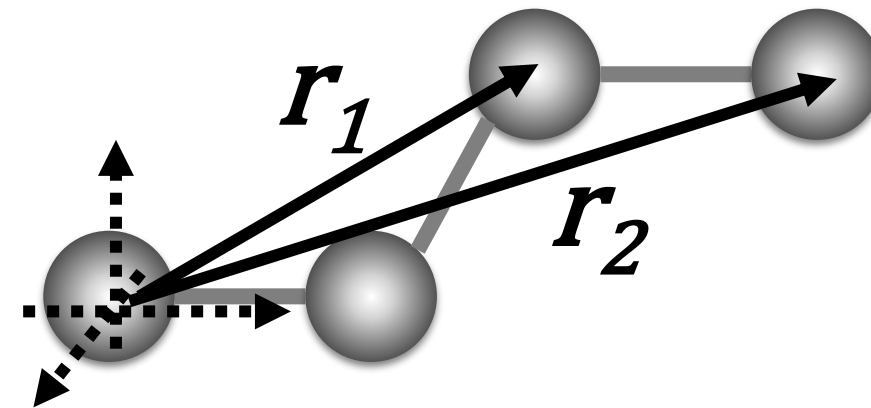
- What potential energy function should we use?
 - solve for potential energy above and get $U(\mathbf{r}) = -\log[\pi(\mathbf{r})]$

Why use constraints?

- Target distribution is highly dimensional and too complex to get conclusive results in reasonable amount of time
- Heavier bodies allows the increase of the timestep
- E.g. :
 - rigid water molecules (TIP3P model)
 - hydrogen bond lengths
 - constant bond lengths and bond angles: torsional dynamics
 - constrain specific regions of molecules or even entire domains

How to impose constraints?

- Cartesian coordinates



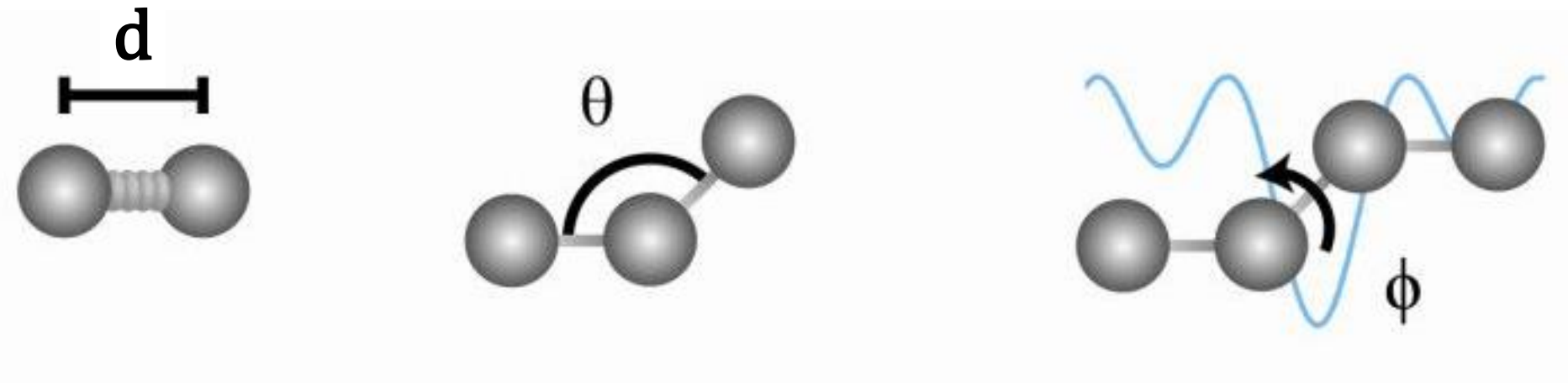
- Dynamics with maximal coordinates (Lagrange multipliers)

$$\begin{aligned}
 & \text{Force: } \frac{dp}{dt} = -\frac{\partial \mathcal{H} + \lambda c(r)}{\partial r} & c(r) = \|r_1 - r_2\|^2 - d^2 \\
 & \text{Velocity: } \frac{dr}{dt} = \frac{\partial \mathcal{H}}{\partial p} \\
 & r(t) = \frac{1}{0!} r(t_0)(t - t_0)^0 + \frac{1}{1!} \frac{dr}{dt}(t_0)(t - t_0)^1 + \frac{1}{2!} \frac{d^2 r}{dt^2}(t_0)(t - t_0)^2 + \dots
 \end{aligned}$$

- Example SHAKE algorithm

How to impose constraints?

- Internal coordinates
BAT



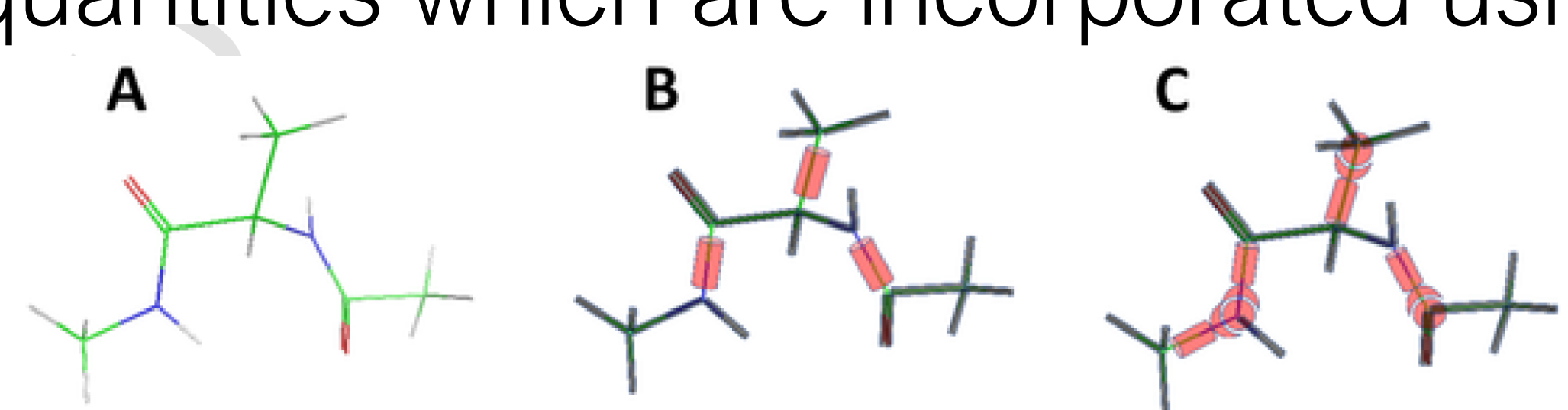
- Dynamics with reduced coordinates (Featherstone)

$$\text{Force: } \frac{dp}{dt} = -\frac{\partial \mathcal{H}}{\partial \phi}$$

$$\text{Velocity: } \frac{d\phi}{dt} = \frac{\partial \mathcal{H}}{\partial p}$$

$$\phi(t) = \frac{1}{0!} \phi(t_0)(t - t_0)^0 + \frac{1}{1!} \frac{d\phi}{dt}(t_0)(t - t_0)^1 + \frac{1}{2!} \frac{d^2\phi}{dt^2}(t_0)(t - t_0)^2 + \dots$$

- Rigid body dynamics includes rotational quantities which are incorporated using Euler's laws of motion



Gibbs sampling

- Why?
 - Only simulating with constraints is not enough. The simulation does not cover the entire conformational space
 - Sampling from complex multivariate joint probability.
- How?
 - Take turns in sampling from conditionals. Allow oversampling easier to sample variables.

$$1. \pi(X|Y)$$

$$2. \pi(Y|X)$$

- Robosample scheme: constrained dynamics combined with all-atom dynamics

$$1. \pi(\phi|d, \theta)$$

$$2. \pi(d, \theta, \phi)$$

Why Robosample?

- Many choices of software for molecular dynamics
 - https://en.wikipedia.org/wiki/Comparison_of_software_for_molecular_mechanics_modeling
 - https://www.rcsb.org/pages/thirdparty/modeling_and_simulation
- Robosample is
 - rigid body dynamics
 - free
 - GPU-accelerated
 - can be used in python scripts/C++ programs

Review Questions

- Generally speaking, how does a HMC simulation work?

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