Hackathon Docs

cosmiQ

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Introduction

Task 1

Task 2

$$\begin{split} \hat{D} &= \sum_{t_0}^{t_f-1} \sum_{i} -\mu(i,t) \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(i,t,q) \right] + \frac{\gamma}{2} \sum_{t=t_0}^{t_f-1} \sum_{ij} \sum_{j} \sum_{q=0}^{t_f} d^q \hat{n}(i,t,q) \right] \left[\frac{1}{K} \sum_{\bar{q}=0}^{N_q-1} d^q \hat{n}(j,t,\bar{q}) \right] \\ &+ \sum_{t_0}^{t_f-1} \sum_{ij} \lambda(t,i) \lambda(t,j) \left\{ \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(j,t+1,q) \right] \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(i,t+1,q) \right] \right. \\ &- 2 \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(i,t+1,q) \right] \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(j,t,q) \right] + \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(i,t,q) \right] \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(j,t,q) \right] \right\} \\ &+ \rho \sum_{t_0}^{t_f} \sum_{ij} \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(i,t,q) \right] \left[\frac{1}{K} \sum_{\bar{q}=0}^{N_q-1} d^q \hat{n}(j,t,\bar{q}) \right] - 2\rho \sum_{t_0}^{t_f} \sum_{i} \left[\frac{1}{K} \sum_{q=0}^{N_q-1} d^q \hat{n}(i,t,q) \right] + N_t \cdot N^2 \end{split}$$

Which we may further simplify by collecting terms:

$$\begin{split} K\hat{D} &= \sum_{t_0}^{t_f-1} \sum_{i} \sum_{q=0}^{N_q-1} (-\mu(i,t) - 2\rho) d^q \hat{n}(i,t,q) \\ &+ \frac{1}{K} \sum_{t_0}^{t_f-1} \sum_{ij} \sum_{q=0}^{N_q-1} \sum_{\bar{q}=0}^{N_q-1} \left[\frac{\gamma}{2} \sum_{ij}^{t} + \lambda(t,i) \lambda(t,j) + \rho \right] d^q \hat{n}(i,t,q) d^q \hat{n}(j,t,\bar{q}) \\ &+ \frac{1}{K} \sum_{t_0}^{t_f-1} \sum_{ij} \sum_{q=0}^{N_q-1} \sum_{\bar{q}=0}^{N_q-1} \lambda(t,i) \lambda(t,j) \left[d^q \hat{n}(i,t+1,q) d^q \hat{n}(j,t+1,\bar{q}) - 2 d^q \hat{n}(i,t+1,q) d^q \hat{n}(j,t,\bar{q}) \right] \\ &+ \frac{\rho}{K} \sum_{ij} \sum_{q=0}^{N_q-1} \sum_{\bar{q}=0}^{N_q-1} d^q \hat{n}(i,t_f,q) d^q \hat{n}(i,t_f,\bar{q}) - 2 \rho \sum_{i} \sum_{q=0}^{N_q-1} d^q \hat{n}(i,t_f,q) \\ &+ K \cdot N_t \cdot N^2 \end{split}$$

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Note that while the boundary term contributes to the inner Hamiltonian, it only appears as a separate term due to the constraint. We have no information available about relative profits $(\mu(i,t_f))$, risk $(\Sigma_{ij}^{t_f})$, and transaction cost $(\lambda(t,i))$ at the final time $t=t_f$.

References