# Linear difference equations

wontdo: nonlinear

wontdo: Stochastic difference equations

Let  $u_t$  be a random variable. Then so will be x:

$$x_t = ax_{t-1} + u_t$$

$$\mathbf{x}_t = \mathbf{A}\mathbf{x}_{t-1} + \mathbf{B}\mathbf{u}_t$$

with x is K by 1, A K by K, u is M by 1, B K by M.

TODO: clean up theoretical results

# Break until 14:38

Markov chains

**Dynamic programming with Markov chains** 

... and difference equations

Application 1: Diamond-Mortensen-Pissarides search model

Application 2: A GE technology adoption problem (Julia vs Matlab)

## **Markov chains**

Suppose  $x_t \in \{1, 2, \dots, K\}$ . discrete or categorical variables, with K different "states".

To make it stochastic, assume random variable, give it a probability mass function:

$$\pi_{tk} = \Pr(x_t = k)$$

Suppose K=2 and 1=employment, 2=unemployment. Then  $\pi_{t1}$  is the prob of being employed in period t,  $\pi_{t2} = 1 - \pi_{t1}$ .

#### **PMFs**

Because pmfs have

and

$$\sum_{k=1}^K \pi_k = 1.$$

How do we transition from employment to unemployment? Suppose  $x_1 = 1$ . What is the probability that  $x_2 = 1$ ? This will be characterized by a PMF.

### Markov property

My forecast, that is, my PMF can only depend on the current value of x. Then I will have K PMFs, each of length K.

For every i, collect PMF into a row vector of probs:

$$\Pr(x_2 = k | x_1 = i) = \pi_{ik}$$

So let's arrange them in a square matrix, KxK:

$$\mathbf{P} = egin{bmatrix} \pi_{11} & \pi_{12} \ \pi_{21} & \pi_{22} \end{bmatrix}$$

But we know that

$$1 \ge \mathbf{P} \ge 0 \tag{*}$$

and

$$\sum_k \pi_{ik} = 1 ext{ for all } i$$

in matrix notation:

$$\mathbf{P1} = \mathbf{1} \tag{**}$$

P is called a **transition matrix**. Square matrices satisfying (\*) and (\*\*) are **stohastic matrices**.

$$\mathbf{P} = egin{bmatrix} 0.95 & 0.05 \ 0.12 & 0.88 \end{bmatrix}$$