



AIX LYON PARIS STRASBOURG

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# Introduction to Safety

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#### Safety is about Failing System Natural language Wrong requirement specification Wrong Specification Wrong environment program specification Bad hardware Design Wrong binary Wrong Source code exploitation Failing procedure hardware Wrong $(\mu C, I/O)$ execution Binary code





## Standards for Safety Critical Systems

- Domain-specific standards
- Recommandations (REX, best practices)
  - No definitive recipe to produce safe systems
  - Cover SW, HW and development process
- Safety case
  - Demonstration that feared event won't happen more frequently than expected
  - Quality & correct development required
  - Safety by-design!

- FDA: healthcare
- 26262: automotive
- EN5012{6,8,9}: railways
- IEC61508: industry
- DO178: aeronautics
- CC: µelectronics







# Safety Levels for Safety Critical Systems

- ➤ Safety Integrity Level (SIL)
  - $\triangleright$  Level 3: 1 failure every 100 years (10<sup>-7</sup>/h)
- Systems = SW + HW + Environment
  - > Specification error
  - Development error, programmation error, bad compilation

  - > 2+ processors in parallel, protecting mechanisms, etc.





# Formal Methods for Safety Critical Systems

- ► Accepted for certification
  - Higly recommended (EN50128, IEC61508)
- ► Al not recommended

#### IEC 61508: Software design and dev. (table A.2)

Technique/Measure	Ref	SIL1	SIL2	SIL3	SIL4
1 Fault detection and diagnosis	C.3.1		R	HR	HR
2 Error detecting and correcting codes	C.3.2	R	R	R	HR
3a Failure assertion programming	C.3.3	R	R	R	HR
3b Safety bag techniques	C.3.4		R	R	R
3c Diverse programming	C.3.5	R	R	R	HR
3d Recovery block	C.3.6	R	R	R	R
3e Backward recovery	C.3.7	R	R	R	R
3f Forward recovery	C.3.8	R	R	R	R
3g Re-try fault recovery mechanisms	C.3.9	R	R	R	HR
3h Memorising executed cases	C.3.10		R	R	HR
4 Graceful degradation	C.3.11	R	R	HR	HR
5 Artificial intelligence - fault correction	C.3.12		NR	NR	NR
6 Dynamic reconfiguration	C.3.13		NR	NR	NR
7a Structured methods including for example, USD_MASCOT_SADT and Yourdon.	C.2.1	HR	HR	HR	HR
7b Semi-formal methods	Table B.7	R	R	HR	HR
7c Formal methods including for example, CCS, CSP, HOL, LOTOS, OBJ, temporal logic, VDM and Z	C.2.4		R	R	HR
8 Computer-aided specification tools	B.2.4	R	R	HR	HR

a) Appropriate techniques/measures shall be selected according to the safety integrity level.
 Alternate or equivalent techniques/measures are indicated by a letter following the number. Only one of the alternate or equivalent techniques/measures has to be satisfied.





b) The measures in this table concerning fault tolerance (control of failures) should be considered with the requirements for architecture and control of failures for the hardware of the programmable electronics in part 2 of this standard.

# What for ? Avoid a 60 years old bug

```
public static int binarySearch(int[] a, int key) {
 int low = 0;
  int high = a.length - 1;
  while (low <= high) {
    int mid = (low + high)
    int midVal = a[mid];
    if (midVal < key)</pre>
      low = mid + 1
    else
      if (midVal > key) high = mid - 1;
      else return mid; // key found
  return - (low + 1); // key not found
```

What happens if low+high >  $2^{31} - 1$ ?

- 1946: first publication of the algorithm
- 1962 : first bug-free publication
- 2006: bug present in the Oracle JDK







### **Formal Methods**

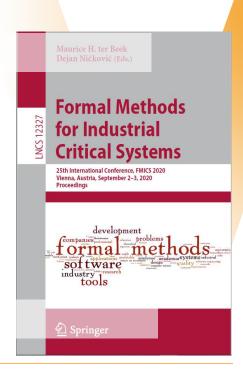
#### Mathematics (language, tool) to demonstrate "things"

Modelling design or verification a posteriori

#### 100+ formalisms & formal tools https://fme-teaching.github.io/

- Level 0: Formal specification + informal development
- Level 1: Formal development and formal verification
- Level 2: Theorem provers for fully machine-checked proofs
- 50+ years of research
- 25+ years of research for Industrial Critical Systems

Fit for industry (planes, trains, IT, cryptocurrencies, smartcards, etc.)







### Bottom-Up Formal Method

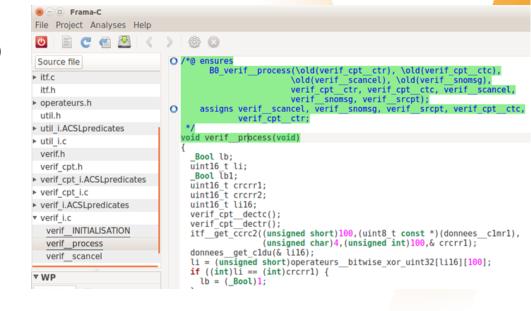
#### Frama-C https://frama-c.com/

- Assertion-based (Hoare logic)
- Source code decorated with pre and post conditions
- Works well for unit testing
- Nightmare for integration testing
- Used by Airbus and Boeing

### Polyspace

- Assertion-based
- Code coloured: OK, NOK, unknown, dead code.









# **Top-Down Formal Method**

#### B METHOD http://www.methode-b.com/

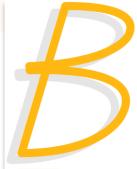
- Invented by French mathematician (J. R. Abrial)
- Assigning programs to meanings
- Top-down approach
- Programs are proved to comply with their specification

#### ATELIER B http://www.atelierb.eu/

- Implement B Method
- First autonomous metro Paris L14 Meteor (1998)
- All metros in Paris to be automated (L1, L4, etc.)
- 30% of automatic metro worldwide
- Maintained & developed by CLEARSY



J-R Abrial







#### « Only inactive sequences can be added to the active sequences execution queue. »

```
activation sequence = /* Activation d'une séquence non active */
PRE ¬(sequences = sequences actives) THEN
    ANY segu WHERE
        sequ ∈ sequences - sequences actives
    THEN
        sequences actives := sequences actives U {sequ}
    END
END;
 activation sequence = /* Activation d'une séquence non active */
 VAR seau IN
     sequ <-- indexSequenceInactive;
     activeSequence (sequ)
 END;
void MO activation sequence (void)
   CTX SEQUENCES sequ;
   sequence manager indexSequenceInactive(&sequ);
   sequence manager activeSequence(sequ);
0x01F970 FFFF 8B4C 2440 89C5 8D7D 0C8B 4110 89CE
0x01F980
0x01F990
0x01F9A0 83C6 0489 450C 8D42 04FC 89C1 C1E9 02F3
```

Natural language requirement

**B** Specification

**B** Implementation

properties

Behaviour

Behaviour properties

C generated code

Binary code





« Only inactive sequences can be added to the active sequences execution queue. »

0x01F9A0 83C6 0489 450C 8D42 04FC 89C1 C1E9 02F3

0x01F990

Natural language requirement

```
activation sequence = /* Activation d'une séquence non active */
PRE ¬(sequences = sequences actives) THEN
                                                                                                              Proof (coherence)
   ANY sequ WHERE
       sequ ∈ sequences - sequences actives
                                                                                B Specification
   THEN
       sequences actives := sequences actives U {sequ}
   END
                                                       Cyclic software
END;
                                                                                            Proof (refinement)
                                                         single-thread
 activation sequence = /* Activation d'une séquence non active */
 VAR secu IN
                                                                               B Implementation
     segu <-- indexSeguenceInactive;
     activeSequence (sequ)
                                                                                                              Proof (coherence)
 END;
void MO activation sequence (void)
   CTX SEQUENCES sequ;
                                                                              C generated code
   sequence manager indexSequenceInactive(&sequ);
   sequence manager activeSequence(sequ);
0x01F970 FFFF 8B4C 2440 89C5 8D7D 0C8B 4110 89CE
0x01F980
                                                                                  Binary code
```

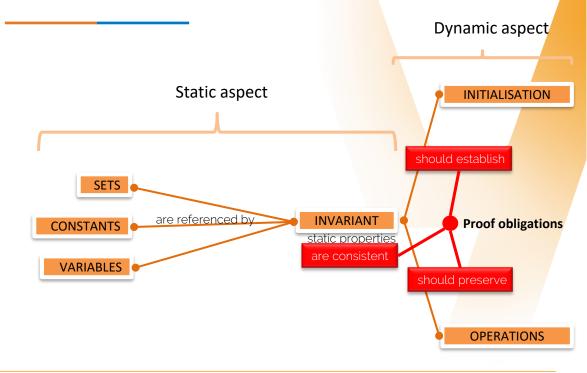
# **B** Proof Obligations

≡ Proof Obligations [POs]

Fully, automatically generated

- Functional
- Well-definedness
- Overflow (option)

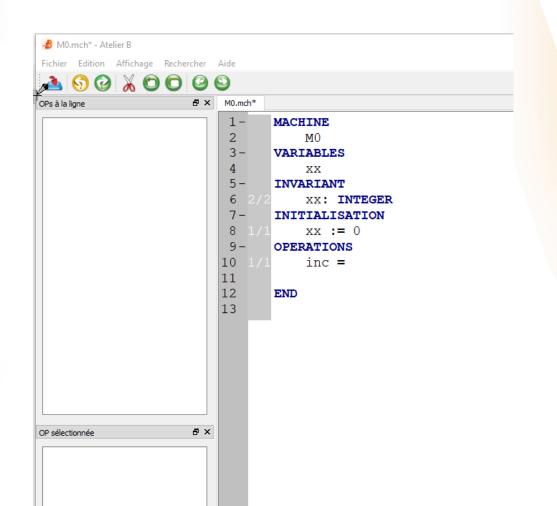
■ B Project CorrectWhen 100% POs are proved

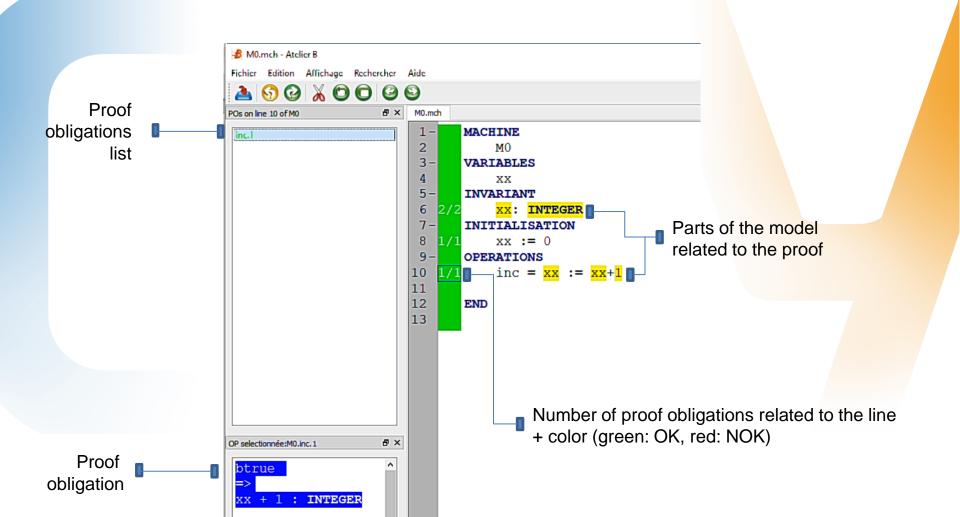












#### MACHINE = specification

M0.mc	h*	
1-		MACHINE
2		MO
3 –		VARIABLES
4		xx
5 –		INVARIANT
6		XX: INTEGER
7 –		INITIALISATION
8		xx := 0
9 –		OPERATIONS
10		inc =
11		
12		END

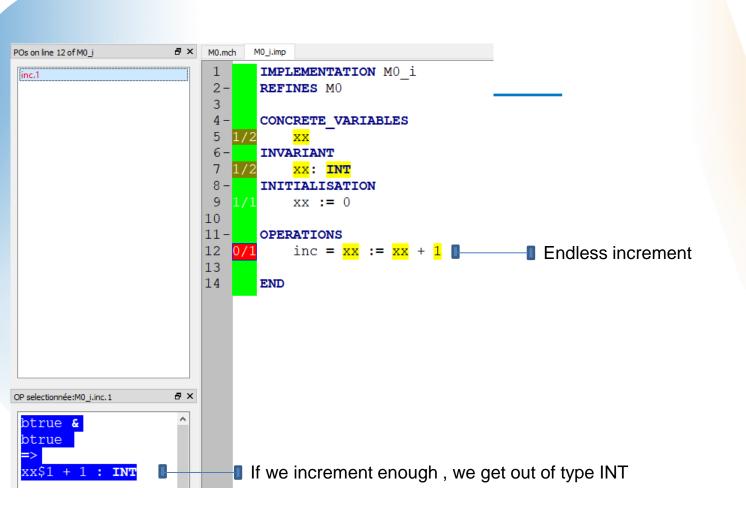
#### IMPLEMENTATION = algorithm

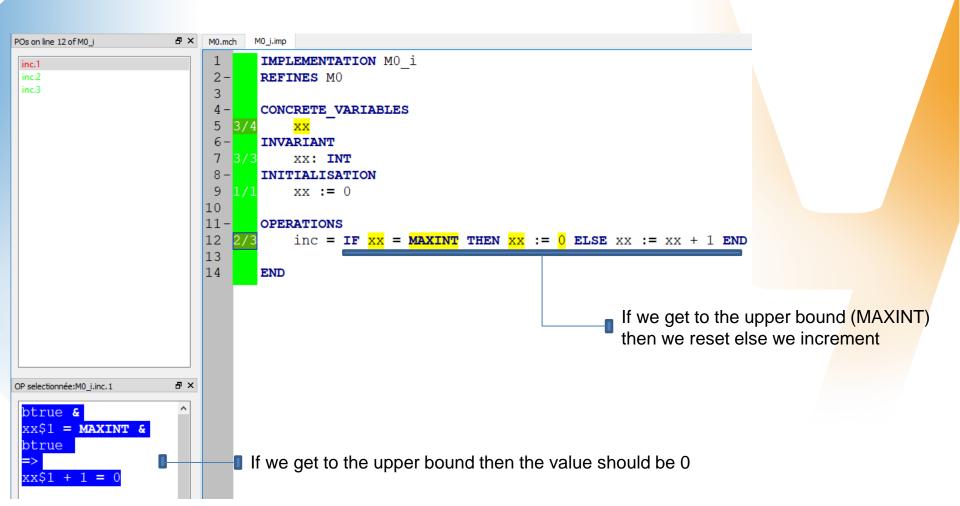
```
M0.mch
     M0_i.imp*
      IMPLEMENTATION M0 i
      REFINES M0
                            Implement its specification
      CONCRETE VARIABLES
                                   Implemented variable
           XX
      INVARIANT
                             Implementable type
           XX: INT
      INITIALISATION
          xx := 0
10
11-
      OPERATIONS
12
           inc =
14
      END
```











```
MACHINE

MO

VARIABLES

XX

SINVARIANT

XX: INTEGER

INITIALISATION

XX := 0

OPERATIONS

inc = CHOICE XX := 0 OR XX := XX + 1 END

EIther we increment or we reset

END

EITHER WE INCREMENT

EITHER WE INCREMENT

EITHER WE INCREMENT OF WE RESET

EITHER WE INCREMENT OF WE RESET

EITHER WE INCREMENT OF WE RESET
```

The 2 models are compatible

```
IMPLEMENTATION MO_i
REFINES MO

CONCRETE_VARIABLES

XX
INVARIANT

XX: INT
INITIALISATION

XX := 0

OPERATIONS

inc = IF XX = MAXINT THEN XX:=0 ELSE XX := XX +1 END

END
```

- Safety critical software development
  - Software formal model(specification and implementation)
  - Coherency: formal proof

#### REFERENCES

- Météor: A Successful Application of B in a Large Project [1] FM 1999, Toulouse
  - Patrick Behm, Paul Benoit, Alain Faivre, Jean Marc Meynadier
- Using B as a High Level Programming Language in an Industrial Project: Roissy VAL ZB 2005, Guildford

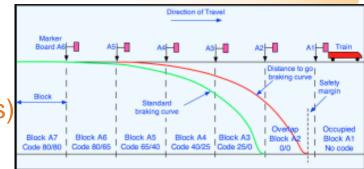
Arnaud Amelot, Frédéric Badeau





- Driving is not safety related
  - No need of formal methods to drive a train
- ► Formal protections (B method)
  - Localization (graphs)

  - Emergency braking (Boolean equations)

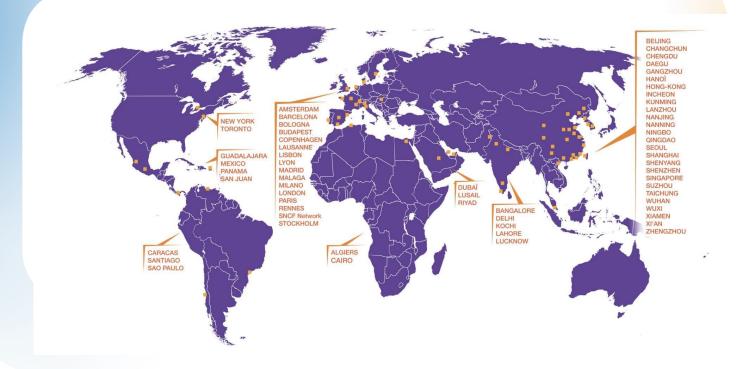


Braking curves





### 30% automatic metros worldwide







Name

Route tx 001

Route vx 002

Switch w 003

Relay s 004 Route tx 005

Relay\_s\_001

Route\_tx\_006

Route vx 128

10 Switch w 009

12 EndLine\_001

13 Signal\_xs\_002

IG Signal\_xs\_003

15 Balise\_b\_001

16 Balise\_b\_002

EndLine 000

243

256 192.16.4.55

242 192.16.4.10

55 192.16.4.125 Y

32 192.16.4.12 G

### Data Formal Verification

- Data formal model (100k cells)
- Conformance with model-checking
- Used by most industry
- Able to handle 10 Mloc generated MACHINE

#### REFERENCES

Formally Checking Large Data Sets in the Railways ICFEM 2012, Kyoto

Thierry Lecomte, Lilian Burdy, Michael Leuschel

[2] Formal Data Validation in the Railways SSS'16, Brighton

Erwan Mottin, Thierry Lecomte









GPS 1

128 23

291

110

145

22

Uplink

Route tx 005 Route vx 002

Route vx 002 EndLine 000

Route vx 128 Route tx 006

Route tx 006 Route vx 128

EndLine 001 Route vx 002

Route\_tx\_006 Route\_vx\_002

Route\_vx\_128 Route\_tx\_005

Route\_vx\_002

Route\_vx\_128

Route\_tx\_006

Route\_vx\_128

Route\_tx\_005

GPS 2

N 50.85 963 O 6.84 201

0 N 50.85 933 O 6.84 508

- Formal analysis of Systems

  - Useful for « *legacy* » systems

#### REFERENCES

- [1] B-specification of Relay-based Railway Interlocking Systems Based on the Propositional Logic of the System State Evolution RSSR 2019, Lille
  - Dalay Israel de Almeida Pereira, David Deharbe, Matthieu Perin and Philippe Bon
- [2] Safety Analysis of a CBTC System: A Rigorous Approach with Event-B RSSR 2017, Pistoia Mathieu Comptier, David Deharbe, Julien Molinero Perez, Denis Sabatier







Clearsy Safety Platfo

- Safety Computer programmed with B
  - > IDE and a hardware platform that natively integrates safety principles
  - > For developing cyclic applications without underlying OS

#### REFERENCES

The CLEARSY Safety Platform: 5 Years of Research, Development and Deployment SBMF 2019, São Paulo

Thierry Lecomte, David Deharbe, Paulin Fournier, Marcel Oliveira















