Basics of Probability

Bayes Algorithm

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1/30

Probability and Statistics

- \bullet Probability \neq Statistics
- Probability: Known distributions ⇒ what are the outcomes?
- Statistics: Known outcomes ⇒ what are the distributions?

Probability Theory

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- In probability, we start with a model that describes how likely a random event is going to happen. Then predict the likelihood of the event happening.
- In statistics, using actual observed data, we make an inference of the model that is used to generate this set of data.

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- Example: Assume there are 1 dog and 2 cats in a room. You pick an animal randomly. What is the probability P_1 that this is a dog? If you pick two animals randomly, what is the probability P_2 that these are a dog and a cat?
- Answer: You have the possible outcomes: (D), (C1), (C2) so

$$P_1 = \frac{\# \text{ "successful" events}}{\# \text{ events}} = \frac{\# \text{ dogs}}{\# \text{ dogs} + \# \text{ cats}} = \frac{1}{3}.$$

To compute P_2 , you can think of all the possible events: (D,C1), (D,C2), (C1,C2) so

$$P_2 = \frac{\# \text{ "successful" events}}{\# \text{ events}} = \frac{2}{3}.$$

Definition

The *sample space* S of an experiment (whose outcome is uncertain) is the set of all possible outcomes of the experiment.

• Example (one coin): When determining the outcome of a single coin toss, $S = \{head, tails\}$.

6/30

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- Example (horse race): Assume you have an horse race with 12 horses. If the experiment is the order of finish in a race, then

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$$S = \{(H, H), (H, T), (T, H), (T, T)\}.$$

• Example (lifetime): If the experiment consists of measuring the lifetime (in years) of your pet then the sample space consists of all nonnegative real numbers: $S = \{x; 0 \le x < \infty\}$.

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- If the outcome of the experiment is in *E*, then we say that *E* has occurred.

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- Example (coins): The event $E = \{(H, T), (T, T)\}$ is the event that a tail appears on the second coin.
- Example (lifetime): The event $E = \{x : 3 \le x \le 15\}$ is the event that your pet will live more than 3 years but won't live more than 15 years.

Given events E and F, $E \cup F$ is the set of all outcomes *either* in E or F or in *both* E and F.

 $E \cup F$ occurs if *either* E or F occurs.

 $E \cup F$ is the **union** of events E and F

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10 / 30

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- Example (lifetime): If $E = \{x : 0 \le x \le 10\}$ and $F = \{x : 15 \le x < \infty\}$ then $E \cup F$ is the event that your pet will die before 10 or will die after 15.

February 27-March 3, 2023

Given events E and F, $E \cap F$ is the set of all outcomes which are *both* in E and F.

 $E \cap F$ is also denoted as EF.

• Example (coins): If we have $E = \{(H, H), (H, T), (T, H)\}$ (event that one H at least occurs) and $F = \{(H, T), (T, H), (T, T)\}$ (even that one T at least occurs) then $E \cap F = \{(H, T), (T, H)\}$ is the event that one H and one T occur.

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- Example (lifetime): If we have $E = \{x : 0 \le x \le 15\}$ and $F = \{x : 10 \le x < 15\}$ then $E \cap F = \{x : 10 \le x \le 15\}$ is the event that your pet will die between 10 and 15.

February 27-March 3, 2023

Notations and Properties

• For any event E, E^c denote the *complement* set of all outcomes in S which are not in E.

Hence we have $E \cup E^c = S$ and $E \cap E^c = \emptyset$.

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• For any two events E and F, we write $E \subset F$ is all the outcomes of E are in F.

February 27-March 3, 2023

• Consider an experiment with sample space S. For each event E, we assume that a number P(E), the *probability* of the event E, is defined and satisfies the following 3 axioms.

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14 / 30

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Axiom 2

$$P(S)=1$$

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Axiom 2

$$P(S)=1$$

• **Axiom 3**. For any sequence of mutually exclusive events $\{E_i\}_{i\geq 1}$, i.e. $E_i\cap E_i=\varnothing$ when $i\neq j$, then

$$P\left(\cup_{i=1}^{\infty}E_{i}\right)=\sum_{i=1}^{\infty}P\left(E_{i}\right)$$



February 27-March 3, 2023

Properties

• **Proposition**: $P(E^c) = 1 - P(E)$.

February 27-March 3, 2023

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- **Proposition**: If $E \subset F$ then $P(E) \leq P(F)$.
- **Proposition**: We have $P(E \cup F) = P(E) + P(F) P(E \cap F)$.

Conditional Probabilities

• Conditional Probability. Consider an experiment with sample space S. Let E and F be two events, then the conditional probability of E given F is denoted by P(E|F) and satisfies if P(F) > 0

$$P(E|F) = \frac{P(E \cap F)}{P(F)}$$

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• Intuition: If F has occured, then, in order for E to occur, it is necessary that the occurence be both in E and F, hence it must be in $E \cap F$. Once F has occured, F is the new sample space.

Conditional Probabilities

• Equally likely outcomes. In this case, we have

$$P(E|F) = \frac{\# \text{ outcomes in } E \cap F}{\# \text{ outcomes in } F}$$

$$= \frac{\# \text{ outcomes in } E \cap F}{\# \text{ outcomes in } S} / \underbrace{\left(\frac{\# \text{ outcomes in } F}{\# \text{ outcomes in } S}\right)}_{P(E)}.$$

17 / 30

Independence

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- Equivalent to P(A|B) = P(A)
- One event occurring does not effect the probability of another occurring

The Multiplication Rule

Let E_1, E_2, \ldots, E_n be a sequence of events, then we have

$$P(E_1 \cap E_2 \cap \cdots \cap E_n) = P(E_1) P(E_2 | E_1) \times P(E_3 | E_1 \cap E_2) \cdots P(E_n | E_1 \cap \cdots \cap E_{n-1})$$

Example

• **Example**: You have a box with 3 blue marbles, 2 red marbles, and 4 yellow marbles. You are going to pull out one marble, record its color, put it back in the box and draw another marble. What is the probability of pulling out a red followed by a blue?

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- **Example**: Consider the same box of marbles. However, we are going to pull out the first marble, leave it out and then pull out the second marble. What is the probability of pulling out a red marble followed by a blue marble?

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- Range of R is the real line

Example: Discrete Random Variable

Experiment: flip 10 coins

Desired outcome: the number of heads

We care about: the number of heads that appear among 10 tosses (not

the probability of getting a particular sequence of heads and tails)

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Probability of a random variable R taking on some specific value k is: $P(R = k) = P(\{s : R(s) = k\})$, with R(s) - number of heads occurring after s tosses

Example: Continuous Random Variable

R(s) - random variable indicating the amount of time it takes for a fast food burger to decay

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Probability that R takes on a value between two real constants a and b is:

$$P(a \le R \le b) = P(\{s : a \le R(s) \le b\})$$

A probability distribution is a a summary of probabilities for the values of a random variable.

- It is a list/table/equation that links all possible outcomes of a random variable to their corresponding probability values.

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- It is a list/table/equation that links all possible outcomes of a random variable to their corresponding probability values.
 - **Mean** is the arithmetical average value of the data.
 - **Median** is the middle value of the data.
 - Mode is the most frequently occurring value of the data.
 - Expected value of some a random variable X with respect to a distribution P(X=x) is the mean value of X when x is drawn from P.
 - Variance is the measure of variability in the data from the mean value.

Binomial: the random variable can have only two outcomes.

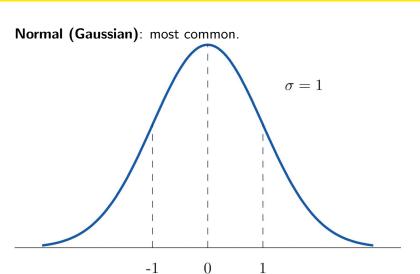
```
import numpy as np
n=100 # number of trials
p=0.5 # probability of success
s=1000 # size
np.random.binomial(n,p,s)
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Uniform: equal likelihood.

```
import numpy as np
np.random.uniform(low=1, high=10,size=100)
```



Bayesian approach provides mathematical rule explaining how you should change your existing beliefs in the light of new evidence.

•
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- $P(R=r|e) = \frac{P(e|R=r)P(R=r)}{P(e)}$
- P(R = r | e): probability that random variable R has value r given evidence e

- $posterior = \frac{likelihood * prior}{marginal likelihood}$
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- P(R = r | e): probability that random variable R has value r given evidence e
- The denominator is just a normalizing constant (called marginal likelihood) that ensures the posterior adds up to 1; it can be computed by summing up the numerator over all possible values of R, i.e.,

$$P(e) = P(R = 0, e) + P(R = 1, e) + ... = \sum_{r} P(e|R = r)P(R = r)$$

Naive Bayes Algorithm

- Simple ("naive") classification method based on Bayes rule.
- It is fast and robust.

Given features $X_1, ..., X_n$, predict label Y

• arg $max_Y P(Y|X_1,...,X_N)$

Classification Overview

Classification Methods:

- Model a classification rule directly
 - Examples: k-NN, decision trees, perceptron, SVM
- 2 Model the probability of class memberships given input data
 - Example: multi-layered neural networks
- Make a probabilistic model of data within each class
 - Examples: naive Bayes, model-based classifiers