## Response Tensors up to 4th rank in $C_{3v}-1$

## — polar tensors —

$$C^{(0,Q)} = (C^{(0,Q)})$$

$$C^{(0,Q)} = Q_0$$

$$C^{(1,Q)} = \begin{pmatrix} 0 & 0 & C_z^{(1,Q)} \end{pmatrix}$$

$$C_z^{(1,Q)} = Q_z$$

$$S^{(2,Q)} = \begin{pmatrix} S_{xx}^{(2,Q)} & 0 & 0\\ 0 & S_{xx}^{(2,Q)} & 0\\ 0 & 0 & S_{zz}^{(2,Q)} \end{pmatrix}$$

$$S_{xx}^{(2,Q)} = Q_0 - Q_u$$
$$S_{zz}^{(2,Q)} = Q_0 + 2Q_u$$

$$S^{(3,Q)} = \begin{pmatrix} S_{1x}^{(3,Q)} & 0 & S_{1z}^{(3,Q)} \\ -S_{1x}^{(3,Q)} & 0 & S_{2z}^{(3,Q)} \\ 0 & 0 & 0 & S_{3z}^{(3,Q)} \\ 0 & \frac{5S_{1z}^{(3,Q)}}{4} - \frac{7S_{2z}^{(3,Q)}}{4} + \frac{S_{3z}^{(3,Q)}}{2} & 0 \\ \frac{9S_{1z}^{(3,Q)}}{4} - \frac{11S_{2z}^{(3,Q)}}{4} + \frac{S_{3z}^{(3,Q)}}{2} & 0 & 0 \\ 0 & -S_{1z}^{(3,Q)} & 0 \end{pmatrix}$$

$$\begin{split} S_{1x}^{(3,Q)} &= Q_3^{\gamma} \\ S_{1z}^{(3,Q)} &= -3Q_3^{\alpha} + Q_z[2] \\ S_{2z}^{(3,Q)} &= -Q_3^{\alpha} + Q_z[2] \\ S_{3z}^{(3,Q)} &= 2Q_3^{\alpha} + 2Q_z[1] + Q_z[2] \end{split}$$

$$A^{(3,Q)} = \begin{pmatrix} 0 & A_{4y}^{(3,Q)} & 0 \\ -A_{4y}^{(3,Q)} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$A_{4y}^{(3,Q)} = Q_z[3]$$

$$S^{(4,Q)} = \begin{pmatrix} S_{11}^{(4,Q)} & S_{12}^{(4,Q)} & S_{13}^{(4,Q)} & 0 & S_{15}^{(4,Q)} & 0 \\ S_{12}^{(4,Q)} & S_{11}^{(4,Q)} & S_{13}^{(4,Q)} & 0 & -S_{15}^{(4,Q)} & 0 \\ S_{13}^{(4,Q)} & S_{13}^{(4,Q)} & S_{33}^{(4,Q)} & 0 & 0 & 0 \\ 0 & 0 & 0 & S_{44}^{(4,Q)} & 0 & -S_{15}^{(4,Q)} \\ S_{15}^{(4,Q)} & -S_{15}^{(4,Q)} & 0 & 0 & S_{44}^{(4,Q)} & 0 \\ 0 & 0 & 0 & -S_{15}^{(4,Q)} & 0 & \frac{S_{11}^{(4,Q)}}{2} - \frac{S_{12}^{(4,Q)}}{2} \end{pmatrix}$$

$$\begin{split} S_{11}^{(4,Q)} &= Q_0[1] + 2Q_0[2] + 3Q_4 - 2Q_u[1] - 4Q_u[2] \\ S_{12}^{(4,Q)} &= Q_0[1] + Q_4 - 2Q_u[1] \\ S_{13}^{(4,Q)} &= Q_0[1] - 4Q_4 + Q_u[1] \\ S_{15}^{(4,Q)} &= Q_4^{\alpha} \\ S_{33}^{(4,Q)} &= Q_0[1] + 2Q_0[2] + 8Q_4 + 4Q_u[1] + 8Q_u[2] \\ S_{44}^{(4,Q)} &= Q_0[2] - 4Q_4 + Q_u[2] \end{split}$$

$$\bar{S}^{(4,Q)} = \begin{pmatrix} 0 & 0 & \bar{S}_{13}^{(4,Q)} & 0 & \bar{S}_{15}^{(4,Q)} & 0 \\ 0 & 0 & \bar{S}_{13}^{(4,Q)} & 0 & -\bar{S}_{15}^{(4,Q)} & 0 \\ -\bar{S}_{13}^{(4,Q)} & -\bar{S}_{13}^{(4,Q)} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \bar{S}_{15}^{(4,Q)} \\ -\bar{S}_{15}^{(4,Q)} & \bar{S}_{15}^{(4,Q)} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -\bar{S}_{15}^{(4,Q)} & 0 & 0 \end{pmatrix}$$

$$\bar{S}_{13}^{(4,Q)} = 3Q_u[3]$$

$$\bar{S}_{15}^{(4,Q)} = -2G_3^{\beta}[1]$$

$$A^{(4,Q)} = \begin{pmatrix} A_{xx}^{(4,Q)} & 0 & 0\\ 0 & A_{xx}^{(4,Q)} & 0\\ 0 & 0 & A_{zz}^{(4,Q)} \end{pmatrix}$$

$$A_{xx}^{(4,Q)} = Q_0[3] - 2Q_u[6]$$
  
$$A_{zz}^{(4,Q)} = Q_0[3] + 4Q_u[6]$$

$$M^{(4,Q)} = \begin{pmatrix} 0 & M_{1y}^{(4,Q)} & 0 \\ 0 & -M_{1y}^{(4,Q)} & 0 \\ 0 & 0 & 0 \\ M_{4x}^{(4,Q)} & 0 & 0 \\ 0 & -M_{4x}^{(4,Q)} & 0 \\ M_{1y}^{(4,Q)} & 0 & 0 \end{pmatrix}$$

$$M_{1y}^{(4,Q)} = G_3^{\beta}[2]$$
  
 $M_{4x}^{(4,Q)} = -3Q_u[4]$ 

$$\bar{M}^{(4,Q)} = \begin{pmatrix} 0 & 0 & 0 & \bar{M}_{x4}^{(4,Q)} & 0 & \bar{M}_{x6}^{(4,Q)} \\ \bar{M}_{x6}^{(4,Q)} & -\bar{M}_{x6}^{(4,Q)} & 0 & 0 & -\bar{M}_{x4}^{(4,Q)} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\bar{M}_{x4}^{(4,Q)} = -3Q_u[5]$$

$$\bar{M}_{x6}^{(4,Q)} = G_3^{\beta}[3]$$

## — axial tensors —

$$A^{(2,G)} = \begin{pmatrix} 0 & A_{xy}^{(2,G)} & 0\\ -A_{xy}^{(2,G)} & 0 & 0\\ 0 & 0 & 0 \end{pmatrix}$$

$$A_{xy}^{(2,G)} = Q_z$$

$$S^{(3,G)} = \begin{pmatrix} 0 & S_{1y}^{(3,G)} & 0\\ 0 & -S_{1y}^{(3,G)} & 0\\ 0 & 0 & 0\\ S_{4x}^{(3,G)} & 0 & 0\\ 0 & -S_{4x}^{(3,G)} & 0\\ S_{1y}^{(3,G)} & 0 & 0 \end{pmatrix}$$

$$\begin{split} S_{1y}^{(3,G)} &= G_3^{\beta} \\ S_{4x}^{(3,G)} &= -3Q_u[1] \end{split}$$

$$A^{(3,G)} = \begin{pmatrix} A_{4x}^{(3,G)} & 0 & 0\\ 0 & A_{4x}^{(3,G)} & 0\\ 0 & 0 & A_{6z}^{(3,G)} \end{pmatrix}$$

$$A_{4x}^{(3,G)} = Q_0 - Q_u[2]$$
  
$$A_{6z}^{(3,G)} = Q_0 + 2Q_u[2]$$

$$S^{(4,G)} = \begin{pmatrix} 0 & 0 & 0 & S_{14}^{(4,G)} & 0 & 0 \\ 0 & 0 & 0 & -S_{14}^{(4,G)} & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ S_{14}^{(4,G)} & -S_{14}^{(4,G)} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & S_{14}^{(4,G)} \\ 0 & 0 & 0 & 0 & S_{14}^{(4,G)} & 0 \end{pmatrix}$$

$$S_{14}^{(4,G)} = G_4^{\beta}$$

$$\bar{S}^{(4,G)} = \begin{pmatrix} 0 & 0 & 0 & \bar{S}^{(4,G)}_{14} & 0 & \bar{S}^{(4,G)}_{16} \\ 0 & 0 & 0 & 0 & -\bar{S}^{(4,G)}_{14} & 0 & \bar{S}^{(4,G)}_{26} \\ 0 & 0 & 0 & 0 & 0 & 0 & -\bar{S}^{(4,G)}_{16} - \bar{S}^{(4,G)}_{26} \\ -\bar{S}^{(4,G)}_{14} & \bar{S}^{(4,G)}_{14} & 0 & 0 & \frac{7\bar{S}^{(4,G)}_{16}}{4} + \frac{9\bar{S}^{(4,G)}_{26}}{4} & 0 \\ 0 & 0 & 0 & -\frac{7\bar{S}^{(4,G)}_{16}}{4} - \frac{9\bar{S}^{(4,G)}_{26}}{4} & 0 & -\bar{S}^{(4,G)}_{14} \\ -\bar{S}^{(4,G)}_{16} & -\bar{S}^{(4,G)}_{26} & \bar{S}^{(4,G)}_{16} + \bar{S}^{(4,G)}_{26} & 0 & \bar{S}^{(4,G)}_{14} & 0 \end{pmatrix}$$

$$\begin{split} \bar{S}_{14}^{(4,G)} &= 2Q_3^{\gamma}[1] \\ \bar{S}_{16}^{(4,G)} &= -6Q_3^{\alpha}[1] + 2Q_z[1] \\ \bar{S}_{26}^{(4,G)} &= 2Q_3^{\alpha}[1] - 2Q_z[1] \end{split}$$

$$\bar{A}^{(4,G)} = \begin{pmatrix} 0 & \bar{A}_{xy}^{(4,G)} & 0 \\ -\bar{A}_{xy}^{(4,G)} & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\bar{A}_{xy}^{(4,G)} = Q_z[6]$$

$$M^{(4,G)} = \begin{pmatrix} M_{1x}^{(4,G)} & 0 & M_{1z}^{(4,G)} \\ -M_{1x}^{(4,G)} & 0 & M_{2z}^{(4,G)} \\ 0 & 0 & 0 & M_{2z}^{(4,G)} \\ 0 & \frac{5M_{1z}^{(4,G)}}{4} - \frac{7M_{2z}^{(4,G)}}{4} + \frac{M_{3z}^{(4,G)}}{2} & 0 \\ \frac{9M_{1z}^{(4,G)}}{4} - \frac{11M_{2z}^{(4,G)}}{4} + \frac{M_{3z}^{(4,G)}}{2} & 0 & 0 \\ 0 & -M_{1x}^{(4,G)} & 0 \end{pmatrix}$$

$$\begin{split} M_{1x}^{(4,G)} &= Q_3^{\gamma}[2] \\ M_{1z}^{(4,G)} &= -3Q_3^{\alpha}[2] + Q_z[3] \\ M_{2z}^{(4,G)} &= -Q_3^{\alpha}[2] + Q_z[3] \\ M_{3z}^{(4,G)} &= 2Q_3^{\alpha}[2] + 2Q_z[2] + Q_z[3] \end{split}$$

$$\bar{M}^{(4,G)} = \begin{pmatrix} \bar{M}_{x1}^{(4,G)} & -\bar{M}_{x1}^{(4,G)} & 0 & 0 & \bar{M}_{x5}^{(4,G)} & 0 \\ 0 & 0 & 0 & \bar{M}_{y4}^{(4,G)} & 0 & -\bar{M}_{x1}^{(4,G)} \\ \bar{M}_{z1}^{(4,G)} & -\bar{M}_{x5}^{(4,G)} + \bar{M}_{y4}^{(4,G)} + \bar{M}_{z1}^{(4,G)} & -\frac{7\bar{M}_{x5}^{(4,G)}}{2} + \frac{11\bar{M}_{y4}^{(4,G)}}{2} + \bar{M}_{z1}^{(4,G)} & 0 & 0 \end{pmatrix}$$

$$\begin{split} \bar{M}_{x1}^{(4,G)} &= Q_3^{\gamma}[3] \\ \bar{M}_{x5}^{(4,G)} &= -3Q_3^{\alpha}[3] + Q_z[4] \\ \bar{M}_{y4}^{(4,G)} &= -Q_3^{\alpha}[3] + Q_z[4] \\ \bar{M}_{z1}^{(4,G)} &= -3Q_3^{\alpha}[3] + Q_z[5] \end{split}$$