

# Stochastic Model-based Algorithm can be Accelerated by Minibatching for Sharp Functions

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## 1 Literature Review

Algorithm	Convexity	Randomness	Stepsize	Complexity
SGD	Convex	Deterministic	Constant	$\log(1/\varepsilon)$ [Ber15]
			Geometrically	$\log(1/\varepsilon)$ [DDMP18]
		Stochastic	Constant	—
			Geometrically	$\log(1/\varepsilon)$ [DDC19]
	Weakly	Deterministic	Constant	$\log(1/\varepsilon)$ [DDMP18]
			Geometrically	$\log(1/\varepsilon)$ [DDMP18]
		Stochastic	Constant	—
			Geometrically	$\log(1/\varepsilon)$ [DDC19]
SPL/SPP	Convex	Deterministic	Constant	$\log \log(1/\varepsilon)$ [Ber15]
			Geometrically	Needed
		Stochastic	Constant	$\log(1/\varepsilon)^\dagger$ [AD19]
			Geometrically	$\log(1/\varepsilon)$ [DDC19]
	Weakly	Deterministic	Constant	$\log \log(1/\varepsilon)$ [CCD <sup>+</sup> 21]
			Geometrically	Needed
		Stochastic	Constant	Needed
			Geometrically	$\log(1/\varepsilon)$ [DDC19]

Table 1: Literature over optimization with sharpness

$\dagger$ : minibatch acceleration is already proven for easy problems ( $\arg \min_x f(x, \xi) = x^*, \forall \xi$ ) in [ACCD20].

## 2 Preliminaries

Consider the following optimization problem

$$\min_{x \in \mathcal{X}} \mathbb{E}_\xi[f(x, \xi)]$$

**Assumption 1.** It is possible to sample i.i.d.  $\{\xi_1, \dots, \xi_n\}$ .

**Assumption 2.**  $f$  is  $\lambda$ -weakly convex. i.e.,  $f + \frac{\lambda}{2}\|x\|^2$  is convex.

**Assumption 3.**  $f$  is sharp. In other words,

$$\mu \cdot \text{dist}(x, \mathcal{X}^*) \leq f(x) - f^*, \forall x \in \mathcal{X}^*,$$

where  $\mathcal{X}^*$  is the set of optimal solutions to the problem.

**Assumption 4.**  $f$  is locally Lipschitz-continuous.

Define the tube  $\mathcal{T}_\gamma := \{x \in \mathcal{X} : \text{dist}(x, \mathcal{X}^*) \leq \frac{\gamma\mu}{\tau}\}$  and we have

$$\min_{g \in \partial f_x(x, \xi)} \|g\| \leq L, \forall x \in \mathcal{T}_2, \xi.$$

**Assumption 5.** Two-sided accuracy is available. i.e.,

$$|f(y) - f_x(y, \xi)| \leq \frac{\tau}{2} \|x - y\|^2.$$

### 3 Convex Optimization

To analyze the case of convex optimization, we specially let  $\lambda = 0$  and further assume that global Lipchitzness of the model  $f_x(\cdot, \xi)$  holds.

#### 3.1 Restarting Strategy with Decaying Stepsize

**Lemma 1** *The algorithm in [DG21] initialized with  $y_0$  satisfies*

$$\mathbb{E}[f(x^{K+1}) - f^*] \leq \frac{2\tau \text{dist}^2(y_0, \mathcal{X}^*)}{(K+1)(K+2)} + \frac{4\sqrt{2}L \text{dist}(y_0, \mathcal{X}^*)}{\sqrt{3m(K+1)}}.$$

**Lemma 2** *For some growth function  $g > 0$ , denote  $E_t := \left\{ \text{dist}(x_t, \mathcal{X}^*) \leq \frac{R_0}{g(t)} \right\}$  and we have the following relation holds*

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{T-1} \left[ \frac{2\tau R_0}{\mu K^2} \cdot \frac{g(t+1)}{g(t)^2} + \frac{4\sqrt{6}L}{3\sqrt{m(K+1)}} \cdot \frac{g(t+1)}{g(t)} \right].$$

**Proof** Without loss of generality we have

$$\begin{aligned} & \mathbb{P}(E_{t+1}) \\ &= \mathbb{P}(E_{t+1} | \overline{E_t}) \mathbb{P}(\overline{E_t}) + \mathbb{P}(E_t) \mathbb{P}(E_{t+1} | E_t) \mathbb{P}(E_t) \\ &\geq \mathbb{P}(E_t) \mathbb{P}(E_{t+1} | E_t) \end{aligned}$$

and that

$$\begin{aligned} \mathbb{P}(E_{t+1} | E_t) &= 1 - \mathbb{P}(\overline{E_{t+1}} | E_t) \\ &= 1 - \mathbb{P}\left(\text{dist}(x_{t+1}, \mathcal{X}^*) \geq \frac{R_0}{g(t+1)} | E_t\right) \\ &\geq 1 - \frac{\mathbb{E}[\text{dist}(x_{t+1}, \mathcal{X}^*) | E_t]}{R_0/g(t+1)} \\ &= 1 - \frac{\mathbb{E}[\text{dist}(x_{t+1}, \mathcal{X}^*) \mathbb{I}\{E_t\}]}{R_0/g(t+1)} \frac{1}{\mathbb{P}(E_t)}, \end{aligned}$$

where the inequality is by Markov's inequality. Then we consider

$$\begin{aligned} \mathbb{E}[\text{dist}(x_{t+1}, \mathcal{X}^*) \mathbb{I}\{E_t\}] &\leq \frac{1}{\mu} \mathbb{E}[(f(x_{t+1}) - f^*) \mathbb{I}\{E_t\}] \\ &\leq \frac{1}{\mu} \left\{ \frac{2\tau \mathbb{E}[\text{dist}^2(x_t, \mathcal{X}^*) \mathbb{I}\{E_t\}]}{(K+1)(K+2)} + \frac{4\sqrt{2}L \mathbb{E}[\text{dist}(x_t, \mathcal{X}^*) \mathbb{I}\{E_t\}]}{\sqrt{3m(K+1)}} \right\} \\ &\leq \frac{2\tau R_0^2}{\mu K^2} \cdot \frac{1}{g(t)^2} + \frac{4\sqrt{6}LR_0}{3\sqrt{m(K+1)}} \cdot \frac{1}{g(t)}. \end{aligned}$$

Next we combine the above and obtain that

$$\begin{aligned}
& \mathbb{P}(E_{t+1}) \\
& \geq \mathbb{P}(E_t) \left\{ 1 - \frac{\mathbb{E}[\text{dist}(x_{t+1}, \mathcal{X}^*) \mathbb{I}\{E_t\}]}{R_0/g(t+1)} \frac{1}{\mathbb{P}(E_t)} \right\} \\
& = \mathbb{P}(E_t) - \frac{\mathbb{E}[\text{dist}(x_{t+1}, \mathcal{X}^*) \mathbb{I}\{E_t\}]}{R_0/g(t+1)} \\
& \geq \mathbb{P}(E_t) - \left[ \frac{2\tau R_0}{\mu K^2} \cdot \frac{g(t+1)}{g(t)^2} + \frac{4\sqrt{6}L}{3\sqrt{m(K+1)}} \cdot \frac{g(t+1)}{g(t)} \right].
\end{aligned}$$

Summing over  $t = 0, \dots, T-1$  gives

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{T-1} \left[ \underbrace{\frac{2\tau R_0}{\mu K^2} \cdot \frac{g(t+1)}{g(t)^2}}_{\text{Quadratic}} + \underbrace{\frac{4\sqrt{6}L}{3\sqrt{m(K+1)}} \cdot \frac{g(t+1)}{g(t)}}_{\text{Linear}} \right]$$

□

**Remark 1** For SPP algorithm we have  $\tau = 0$  and the quadratic acceleration term is not present and we hence have

$$\mathbb{P}(E_T) \geq 1 - \frac{4\sqrt{6}L}{3\sqrt{m(K+1)}} \sum_{t=0}^{T-1} \frac{g(t+1)}{g(t)}$$

**Remark 2** To recover the deterministic quadratic convergence, we let  $m \rightarrow \infty$  and get

$$\mathbb{P}(E_T) \geq 1 - \frac{2\tau R_0}{\mu K^2} \sum_{t=0}^{T-1} \frac{g(t+1)}{g(t)^2}$$

and this allows us to take growth function to  $g(t) = 2^{2^t}$  such that  $\frac{g(t+1)}{g(t)^2} = 2 = \mathcal{O}(1)$ . Then we can follow [DDC19] to recover the quadratic convergence.

From now on we assume that  $\tau = 0$  (proximal point) and carry out the analysis.

### 3.2 Optimal Choice for Parameters

Now we consider the general choice of  $g(t)$ ,  $m_t$  and  $K_t$ . For brevity we use  $m(t)$  and  $K(t)$  as functions of discrete values  $t$ . Then due to monotonicity of  $g$  we have  $T = g^{-1}(t)$  and that

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} \left( \frac{8\sqrt{6}L}{3\mu\sqrt{K(t)+1}} \cdot \frac{g(t+1)}{g(t)\sqrt{m(t)}} \right).$$

Also, we have the total sample complexity given by

$$\sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} m(t)K(t).$$

Then we use  $K(t) + 1$  to replace  $K(t)$  and get an abstract optimization problem

$$\begin{aligned} \min_{g, m, K} \quad & \sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} m(t)K(t) \\ \text{subject to} \quad & \sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} \left( \frac{8\sqrt{6}L}{3\mu} \cdot \frac{g(t+1)}{g(t)\sqrt{m(t)K(t)}} \right) \leq \delta. \end{aligned}$$

To solve the problem, we first denote  $\alpha := R_0/\varepsilon$ ,  $\theta := \frac{\sqrt{6}\mu\delta}{16L}$ ,  $u(t) := m(t)K(t)$  and get

$$\begin{aligned} \min_{g, u} \quad & \sum_{t=0}^{g^{-1}(\alpha)-1} u(t) \\ \text{subject to} \quad & \sum_{t=0}^{g^{-1}(\alpha)-1} \frac{1}{\sqrt{u(t)}} \cdot \frac{g(t+1)}{g(t)} \leq \theta. \end{aligned}$$

#### Linear Convergence

In this case we have  $\frac{g(t+1)}{g(t)} = \beta$  and by optimality condition we know that it is optimal to let  $u(t_1) = u(t_2), \forall t_1, t_2$  and the constraint is transformed into

$$\frac{\log_\beta(\alpha)}{\sqrt{u(0)}} \leq \theta/\beta \Rightarrow u(0) \geq \frac{\beta^2 \log_\beta^2(\alpha)}{\theta^2} = \frac{128L^2 \beta^2 \log_\beta^2(\alpha)}{3\mu^2 \delta^2}.$$

Also the objective is into

$$\sum_{t=0}^{g^{-1}(\alpha)-1} u(t) = \log_\beta(\alpha) u(0) \geq \left( \frac{\beta}{\log^3(\beta)} \right) \left( \frac{128L^2}{3\mu^2 \delta^2} \right) \log^3(\alpha).$$

Hence the best bound in terms of linear convergence is attained by  $\beta = e^3 \Rightarrow \frac{\beta}{\log^3(\beta)} = \frac{e^3}{27}$  with constant batchsize and this gives the best sample complexity

$$\frac{128e^3}{81} \left( \frac{L^2}{\mu^2 \delta^2} \right) \log^3 \left( \frac{R_0}{\varepsilon} \right).$$

**Super-linear**  $\exp(t \log(t+1))$

In this case we have  $\frac{g(t+1)}{g(t)} = \left(1 + \frac{1}{t+1}\right)^t (t+2)$  and in this case we have

$$\begin{aligned} \min_{g,u} \quad & \sum_{t=0}^{W(R_0/\varepsilon)-1} u(t) \\ \text{subject to} \quad & \sum_{t=0}^{W(eR_0/\varepsilon)-2} \frac{1}{\sqrt{u(t)}} \cdot \left(1 + \frac{1}{t}\right)^t (t+1) \leq \theta, \end{aligned}$$

where  $W(x)$  is the Lambert-W function. By taking  $m(t) \equiv m, K(t) = \frac{512L^2e^2}{3m\mu^2\delta^2} \log^4\left(\frac{R_0}{\varepsilon}\right)$  we have the sample complexity of  $o\left(\frac{512L^2}{3\mu^2\delta^2} \log^5\left(\frac{R_0}{\varepsilon}\right)\right)$ . Hence we achieve super-linear convergence.

**Remark 3** Currently for  $\exp(t \log(t+1))$  we can preserve the order of the  $\log\left(\frac{R_0}{\varepsilon}\right)$  term in sample complexity.

### Constant Sample per Iteration

In this case we assume that  $u(t) \equiv u$  and we have

$$\begin{aligned} \min_{g,u} \quad & g^{-1}(\alpha) \\ \text{subject to} \quad & \sum_{t=0}^{g^{-1}(\alpha)-1} \frac{g(t+1)}{g(t)} \leq \theta\sqrt{u}. \end{aligned}$$

Or more abstractly, we have to solve

$$\begin{aligned} \min_f \quad & f^{-1}(\alpha) \\ \text{subject to} \quad & \int_0^{f^{-1}(\alpha)} \frac{f(x+1)}{f(x)} dx \leq 1. \end{aligned}$$

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