# Stochastic Model-based Algorithm can be Accelerated by Minibatching for Sharp Functions

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# 1 Literature Review

Algorithm	Convexity	Randomness	Stepsize	Complexity
SGD	Convex	Determinic	Constant	$\log(1/\varepsilon)$
			Geometrically	$\log(1/\varepsilon)$
		Stochastic	Constant	_
			Geometrically	$\log(1/\varepsilon)$
	Weakly	Deterministic	Constant	$\log(1/\varepsilon)$
			Geometrically	$\log(1/\varepsilon)$
		Stochastic	Constant	_
			Geometrically	$\log(1/\varepsilon)$
SPL/SPP	Convex	Deterministic	Constant	$\log \log (1/\varepsilon)$
			Geometrically	Needed
		Stochastic	Constant	$\log(1/\varepsilon)^{\dagger}$
			Geometrically	$\log(1/\varepsilon)$
	Weakly	Deterministic	Constant	$\log \log (1/\varepsilon)$
			Geometrically	Needed
		Stochastic	Constant	Needed
			Geometrically	$\log(1/\varepsilon)$

Table 1: Literature over optimization with sharpness

†: minibatch acceleration is already proven for easy problems (arg  $\min_x f(x,\xi) = x^*, \forall \xi$ ).

### 2 Preliminaries

Consider the following optimization problem

$$\min_{x \in \mathcal{X}} \quad \mathbb{E}_{\xi}[f(x,\xi)]$$

**Assumption 1**. It is possible to sample i.i.d.  $\{\xi_1, \dots, \xi_n\}$ .

**Assumption 2**. f is  $\lambda$ -weakly convex.

We assume that  $f + \frac{\lambda}{2} ||x||^2$  is convex.

**Assumption 3.** f is sharp. In other words,

$$\mu \cdot \operatorname{dist}(x, \mathcal{X}^*) \le f(x) - f^*, \forall x \in \mathcal{X}^*,$$

where  $\mathcal{X}^*$  is the set of optimal solutions to the problem.

**Assumption 4**. f is locally Lipschitz-continuous.

Define the tube  $\mathcal{T}_{\gamma} := \left\{ x \in \mathcal{X} : \operatorname{dist}(x, \mathcal{X}^*) \leq \frac{\gamma \mu}{\tau} \right\}$  and we have

$$\min_{g \in \partial f_x(x,\xi)} \|g\| \le L, \forall x \in \mathcal{T}_2, \xi.$$

**Assumption 5**. Two-sided accuracy is available. i.e.,

$$|f(y) - f_x(y,\xi)| \le \frac{\tau}{2} ||x - y||^2.$$

It is already known that in the convex case, the proximal point method converges quadratically [1] and its stochastic variant has linear convergence when using a geometrically decaying stepsize [2]. Hence there is space for acceleration.

## 3 Convex Optimization

To analyze the case of convex optimization, we specially let  $\lambda = 0$  and further assume that global Lipschitzness of the model  $f_x(\cdot, \xi)$  holds.

#### 3.1 Restarting Strategy with Decaying Stepsize

**Lemma 1** The algorithm in [SMOD] initialized with  $y_0$  and satisfies

$$\mathbb{E}[f(x^{K+1}) - f^*] \le \frac{2\tau \operatorname{dist}^2(y_0, \mathcal{X}^*)}{(K+1)(K+2)} + \frac{4\sqrt{2}L \operatorname{dist}(y_0, \mathcal{X}^*)}{\sqrt{3m_t(K+1)}}.$$

**Lemma 2** For some growth function g > 0, denote  $E_t := \left\{ \operatorname{dist}(x_t, \mathcal{X}^*) \leq \frac{R_0}{g(t)} \right\}$  and we have the following relation holds

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{T-1} \left[ \frac{2\tau R_0}{\mu K^2} \cdot \frac{g(t+1)}{g(t)^2} + \frac{4\sqrt{6}L}{3\sqrt{m_t(K+1)}} \cdot \frac{g(t+1)}{g(t)} \right].$$

**Proof** Without loss of generality we have

$$\mathbb{P}(E_{t+1})$$
=  $\mathbb{P}(E_{t+1}|\overline{E_t})\mathbb{P}(\overline{E_t}) + \mathbb{P}(E_t)\mathbb{P}(E_{t+1}|E_t)\mathbb{P}(E_t)$   
>  $\mathbb{P}(E_t)\mathbb{P}(E_{t+1}|E_t)$ 

and that

$$\mathbb{P}(E_{t+1}|E_t) = 1 - \mathbb{P}(\overline{E_{t+1}}|E_t) 
= 1 - \mathbb{P}\left(\operatorname{dist}(x_{t+1}, \mathcal{X}^*) \ge \frac{R_0}{g(t+1)}|E_t\right) 
\ge 1 - \frac{\mathbb{E}[\operatorname{dist}(x_{t+1}, \mathcal{X}^*)|E_t]}{R_0/g(t+1)} 
= 1 - \frac{\mathbb{E}[\operatorname{dist}(x_{t+1}, \mathcal{X}^*)\mathbb{I}\{E_t\}]}{R_0/g(t+1)} \frac{1}{\mathbb{P}(E_t)},$$

where the inequality is by Markov's inequality.

Then we consider

$$\mathbb{E}[\operatorname{dist}(x_{t+1}, \mathcal{X}^*)\mathbb{I}\{E_t\}] \leq \frac{1}{\mu}\mathbb{E}[(f(x_{t+1}) - f^*)\mathbb{I}\{E_t\}]$$

$$\leq \frac{1}{\mu} \left\{ \frac{2\tau \mathbb{E}[\operatorname{dist}^2(x_t, \mathcal{X}^*)\mathbb{I}\{E_t\}]}{(K+1)(K+2)} + \frac{4\sqrt{2}L\mathbb{E}[\operatorname{dist}(x_t, \mathcal{X}^*)\mathbb{I}\{E_t\}]}{\sqrt{3m_t(K+1)}} \right\}$$

$$\leq \frac{2\tau R_0^2}{\mu K^2} \cdot \frac{1}{g(t)^2} + \frac{4\sqrt{6}LR_0}{3\mu\sqrt{m_t(K+1)}} \cdot \frac{1}{g(t)}.$$

Next we combine the above and obtain that

$$\mathbb{P}(E_{t+1}) \\
\geq \mathbb{P}(E_t) \left\{ 1 - \frac{\mathbb{E}[\operatorname{dist}(x_{t+1}, \mathcal{X}^*)\mathbb{I}\{E_t\}]}{R_0/g(t+1)} \frac{1}{\mathbb{P}(E_t)} \right\} \\
= \mathbb{P}(E_t) - \frac{\mathbb{E}[\operatorname{dist}(x_{t+1}, \mathcal{X}^*)\mathbb{I}\{E_t\}]}{R_0/g(t+1)} \\
\geq \mathbb{P}(E_t) - \left[ \frac{2\tau R_0}{\mu K^2} \cdot \frac{g(t+1)}{g(t)^2} + \frac{4\sqrt{6}L}{3\mu\sqrt{m_t(K+1)}} \cdot \frac{g(t+1)}{g(t)} \right].$$

Summing over t = 0, ..., T - 1 gives

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{T-1} \left[ \underbrace{\frac{2\tau R_0}{\mu K^2} \cdot \frac{g(t+1)}{g(t)^2}}_{\text{Quadratic}} + \underbrace{\frac{4\sqrt{6}L}{3\mu\sqrt{m_t(K+1)}} \cdot \frac{g(t+1)}{g(t)}}_{\text{Linear}} \right]$$

**Remark 1** For SPP algorithm we have  $\tau=0$  and the quadratic acceleration term is not present and we hence have

$$\mathbb{P}(E_T) \geq 1 - \frac{4\sqrt{6}L}{3\mu\sqrt{m(K+1)}} \sum_{t=0}^{T-1} \frac{g(t+1)}{g(t)}$$

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**Remark 2** To recover the deterministic quadratic convergence, we let  $m \to \infty$  and get

$$\mathbb{P}(E_T) \geq 1 - \frac{2\tau R_0}{\mu K^2} \sum_{t=0}^{T-1} \frac{g(t+1)}{g(t)^2}$$

and this allows us to take growth function to  $g(t) = 2^{2^t}$  such that  $\frac{g(t+1)}{g(t)^2} = 2 = \mathcal{O}(1)$ . Then we can follow [Dmitri] to recover the quadratic convergence.

Now we analyze the way to choose  $(g, \{m_t\})$  for faster convergence. Consider taking  $m_t = m(t)$  and we get

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{T-1} \left( \frac{2\tau R_0}{\mu K^2} \cdot \frac{g(t+1)}{g(t)^2} + \frac{4\sqrt{6}L}{3\mu\sqrt{K+1}} \cdot \frac{g(t+1)}{\sqrt{m_t}g(t)} \right).$$

For brevity we first consider the proximal point method with  $\tau=0$  and we get the bound

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{T-1} \left( \frac{4\sqrt{6}L}{3\mu\sqrt{K_t + 1}} \cdot \frac{g(t+1)}{\sqrt{m_t}g(t)} \right).$$

#### Super-linear Batchsize

Take  $g(t) = 2^{t^2}$  and we have

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{T-1} \left( \frac{8\sqrt{6}L}{3\mu\sqrt{K_t + 1}} \cdot \frac{4^t}{\sqrt{m_t}} \right).$$

Take  $m_t = 16^t, T = \left\lceil \sqrt{\log_2\left(\frac{R_0}{\varepsilon}\right)} \right\rceil$  and  $K_t \equiv \left\lfloor \frac{128T^2}{3} \cdot \left(\frac{L}{\delta\mu}\right)^2 \right\rfloor$ , we have the total sample complexity of

$$\sum_{t=0}^{T-1} m_t K_t = \frac{128T^2}{3} \left(\frac{L}{\delta\mu}\right)^2 \sum_{t=0}^{T-1} 16^t$$

$$\leq \frac{128T^2}{45} \left(\frac{L}{\delta\mu}\right)^2 \exp\left(4\sqrt{\log_2\left(\frac{R_0}{\varepsilon}\right)}\right)$$

$$\leq \frac{128\log_2\left(\frac{R_0}{\varepsilon}\right)}{45} \left(\frac{L}{\delta\mu}\right)^2 \exp\left(4\sqrt{\log_2\left(\frac{R_0}{\varepsilon}\right)}\right)$$

#### **Optimal Choice for Parameters**

Last we consider the general choice of g(t),  $m_t$  and  $K_t$ . For brevity we use m(t) and K(t) as functions of discrete values t. Then due to monotonicity of g we have  $T = g^{-1}(t)$  and that

$$\mathbb{P}(E_T) \geq 1 - \sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} \left( \frac{8\sqrt{6}L}{3\mu\sqrt{K(t)+1}} \cdot \frac{g(t+1)}{g(t)\sqrt{m(t)}} \right).$$

Also, we have the total sample complexity given by

$$\sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} m(t)K(t).$$

Then we use K(t) + 1 to replace K(t) and get an abstract optimization problem

$$\min_{g,m,K} \qquad \sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} m(t)K(t)$$
 subject to 
$$\sum_{t=0}^{g^{-1}(R_0/\varepsilon)-1} \left(\frac{8\sqrt{6}L}{3\mu} \cdot \frac{g(t+1)}{g(t)\sqrt{m(t)K(t)}}\right) \le \delta$$

To solve the problem, we first denote  $\alpha:=R_0/\varepsilon, \theta:=\frac{\sqrt{6}\mu\delta}{16L}, u(t):=m(t)K(t)$  and get

$$\begin{aligned} & \min_{g,u} & & \sum_{t=0}^{g^{-1}(\alpha)-1} u(t) \\ & \text{subject to} & & \sum_{t=0}^{g^{-1}(\alpha)-1} \frac{1}{\sqrt{u(t)}} \cdot \frac{g(t+1)}{g(t)} \leq \theta \end{aligned} .$$

Now we consider the following cases.

#### Linear Convergence

In this case we have  $\frac{g(t+1)}{g(t)} = \beta$  and by optimality condition we know that it is optimal to let  $u(t_1) = u(t_2), \forall t_1, t_2$  and the constraint is transformed into

$$\frac{\log_{\beta}(\alpha)}{\sqrt{u(0)}} \le \theta/\beta \Rightarrow u(0) \ge \frac{\beta^2 \log_{\beta}^2(\alpha)}{\theta^2} = \frac{128L^2\beta^2 \log_{\beta}^2(\alpha)}{3\mu^2\delta^2}.$$

Also the objective is into

$$\sum_{t=0}^{g^{-1}(\alpha)-1} u(t) = \log_{\beta}(\alpha)u(0) \ge \left(\frac{\beta}{\log^{3}(\beta)}\right) \left(\frac{128L^{2}}{3\mu^{2}\delta^{2}}\right) \log^{3}(\alpha).$$

Hence the best bound in terms of linear convergence is attained by  $\beta=e^3\Rightarrow \frac{\beta}{\log^3(\beta)}=\frac{e^3}{27}$  with constant batchsize and this gives the best sample complexity

$$\frac{128e^3}{81} \left( \frac{L^2}{\mu^2 \delta^2} \right) \log^3 \left( \frac{R_0}{\varepsilon} \right).$$

#### Constant Sample per Iteration

In this case we assume that  $u(t) \equiv u$  and we have

$$\min_{g,u} \qquad g^{-1}(\alpha)$$
 subject to 
$$\sum_{t=0}^{g^{-1}(\alpha)-1} \frac{g(t+1)}{g(t)} \leq \theta \sqrt{u} \quad .$$

Or more abstractly, we have to solve

$$\min_{f} \qquad f^{-1}(\alpha)$$
 subject to 
$$\int_{0}^{f^{-1}(\alpha)} \frac{f(x+1)}{f(x)} dx \le 1$$

**Super-linear**  $\exp(t \log(t+1))$ 

In this case we have  $\frac{g(t+1)}{g(t)} = \left(1 + \frac{1}{t+1}\right)^t (t+2)$  and in this case we have

$$\begin{split} & \min_{g,u} & \sum_{t=0}^{W(R_0/\varepsilon)-1} u(t) \\ \text{subject to} & \sum_{t=0}^{W(eR_0/\varepsilon)-2} \frac{1}{\sqrt{u(t)}} \cdot \left(1 + \frac{1}{t}\right)^t (t+1) \leq \theta \quad , \end{split}$$

where W(x) is the Lambert-W function. By taking  $m(t) \equiv m, K(t) = \frac{512L^2e^2}{3m\mu^2\delta^2}\log^4\left(\frac{R_0}{\varepsilon}\right)$  we have the sample complexity of  $o\left(\frac{512L^2}{3\mu^2\delta^2}\log^5\left(\frac{R_0}{\varepsilon}\right)\right)$ . Hence we achieve superlinear convergence.

#### Super-linear $\exp(\mathcal{P}(t))$

In this case we consider a special case of super-linear convergence with  $g(t) = e^{\beta t^p}$ . In this case we have  $\frac{g(t+1)}{g(t)} = \exp(\beta(t+1)^p - \beta t^p)$  and  $T = g^{-1}(\alpha) = [\log(\alpha)]^{1/p}$ . Hence we have the optimization problem given by

$$\min_{p,u} \qquad \sum_{t=0}^{\lceil \log(\alpha) \rceil^{1/p} - 1} u(t)$$
  
subject to 
$$\sum_{t=0}^{\lceil \log(\alpha) \rceil^{1/p} - 1} \frac{1}{\sqrt{u(t)}} \cdot \exp((t+1)^p - t^p) \le \theta.$$

A trivial selection is p=2 and  $\frac{g(t+1)}{g(t)}=\exp(2\beta t+\beta)$ . Then we have  $[\log(\alpha)]^{1/p}-1=\sqrt{\log(\alpha)}-1$ , giving

$$\min_{u} \qquad \sum_{t=0}^{\sqrt{\log(\alpha)}-1} u(t)$$
 subject to 
$$\sum_{t=0}^{\sqrt{\log(\alpha)}-1} \frac{\exp(2\beta t)}{\sqrt{u(t)}} \le \theta e^{-\beta}.$$

Then by writing the Lagrangian function

$$\mathcal{L}(\{u(t)\}, \lambda) := \sum_{t=0}^{\sqrt{\log(\alpha)}-1} u(t) - \lambda \left(\theta e^{-\beta} - \sum_{t=0}^{\sqrt{\log(\alpha)}-1} \frac{\exp(2\beta t)}{\sqrt{u(t)}}\right)$$

we have

$$\partial_{u(t)}\mathcal{L} = 1 - \frac{\lambda \exp(2\beta t)}{2} u(t)^{-3/2}$$

and that

$$u(t) = \lambda^{2/3} \left( \frac{\exp(2\beta t)}{2} \right)^{2/3}$$

$$\sum_{t=0}^{\sqrt{\log(\alpha)}-1} \frac{\exp(2\beta t)}{\sqrt{u(t)}} = \left[\sum_{t=0}^{\sqrt{\log(\alpha)}-1} \frac{\exp(2\beta t)^{2/3}}{2^{-1/3}}\right] \lambda^{-1/3}$$
$$= \theta e^{-\beta}.$$

Hence we have  $\lambda^{*2/3} = \frac{\left(\sum_{t=0}^{\sqrt{\log(\alpha)}-1} \frac{\exp(2\beta t)^{2/3}}{2^{-1/3}}\right)^2}{\theta^2 e^{-2\beta}}$  and

$$u(t) = \frac{\left(\sum_{t=0}^{\sqrt{\log(\alpha)}-1} \exp(2\beta t)^{2/3}\right)^2}{\theta^2 e^{-2\beta}} (\exp(2\beta t))^{2/3},$$

giving

$$\sum_{t=0}^{\sqrt{\log(\alpha)}-1} u(t) = \frac{1}{\theta^2 e^{-2\beta}} \left( \sum_{t=0}^{\sqrt{\log(\alpha)}-1} \exp(4\beta t/3) \right)^2$$

$$= \frac{1}{\theta^2 e^{-2\beta}} \left( \sum_{t=0}^{\sqrt{\log(\alpha)}-1} \exp(4\beta/3)^t \right)^2$$

$$= \frac{1}{\theta^2 e^{-2\beta}} \left( \sum_{t=0}^{\sqrt{\log(\alpha)}-1} \exp(4\beta/3)^t \right)^2$$

$$= \frac{1}{\theta^2 e^{-2\beta}} \left( \frac{\exp(4\beta/3)^{\sqrt{\log(\alpha)}}-1}{\exp(4\beta/3)-1} \right)^2$$

$$= \frac{1}{\theta^2} \frac{\exp(2\beta) \left( \exp(4\beta/3)^{\sqrt{\log(\alpha)}}-1 \right)^2}{[\exp(4\beta/3)-1]^2}.$$

For some given  $\beta$ , we get the total complexity of

$$\frac{128L^2}{3\mu^2\delta^2} \cdot \frac{\exp(2\beta)\left(\exp(4\beta/3)^{\sqrt{\log(\alpha)}} - 1\right)^2}{[\exp(4\beta/3) - 1]^2} = \mathcal{O}\left(\frac{128L^2}{3\mu^2\delta^2}e^{\sqrt{\log(R_0/\varepsilon)}}\right)$$

- [1] Bertsekas, Dimitri.  ${\it Convex~optimization~algorithms}.$  Athena Scientific, 2015.
- [2] Davis, D. , D. Drusvyatskiy , and V Charisopoulos. "Stochastic algorithms with geometric step decay converge linearly on sharp functions." arXiv (2019).
- [3] Davis, Damek, et al. "Subgradient methods for sharp weakly convex functions." *Journal of Optimization Theory and Applications* 179.3 (2018): 962-982.