

On the design of a dual potential reduction solver

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In this note we describe the implementation of a dual potential reduction solver that exploits either the embedding or the big- M potential reduction method to solve

$$\begin{aligned} \min_x \quad & \langle c, x \rangle \\ \text{subject to} \quad & \mathcal{A}x = b \\ & x \succeq_{\mathcal{K}} 0 \end{aligned}$$

via its dual

$$\begin{aligned} \max_{y, s} \quad & b^\top y \\ \text{subject to} \quad & \mathcal{A}^*y + s = c \\ & s \succeq_{\mathcal{K}^*} 0. \end{aligned}$$

The main solver contains the following components

- ▶ Solver/data
Interface: set data, set parameter, set solution, optimize, get solution
Sparse, dense, rank-one
- ▶ Algorithm
HSD/infeasible start/dual potential reduction
Presolve, phase A, phase B
Schur complement setup*, potential line-search, barrier line-search
- ▶ Linear algebra
sparse, dense, low rank; eigen, trace, decomposition (Cholesky)
Lanczos, conjugate gradient, block buffer computation*
- ▶ Other utilities
Parameter tuner, IO and things like that

1 SDP Data structures

1.1 Factorized data

The following structure stores the eigen-decomposition of a data matrix $A = \sum_{i=1}^r \lambda_i u_i u_i^\top$. The structure should support the following operations.

- ▶ $\langle A, B \rangle = \sum_{i=1}^r \lambda_i u_i^\top B u_i$
- ▶ $B = S^{-1} A S^{-1} = \sum_{i=1}^r \lambda_i (S^{-1} u_i) (S^{-1} u_i)^\top$
In this case the LHS serves as a buffer

```

1 typedef struct {
2
3     int     nCol;
4     int     rank;
5     double *evals;
6     double *evecs;
7
8 } eigFactor;

```

1.2 SDP coefficient matrix

NOTE: Only lower triangular is stored.

We use the following structures to store A and C matrices from SDP coefficients. They should support the following functionalities

- $B \leftarrow \alpha A + B$
- $\langle A_i, A_j \rangle$ (TODO)
- $\|A\|_F$
- $\sum_{ij} |a_{ij}|$
- $A \leftarrow \alpha A$
- $[V, e] = \text{eig}(A)$ (TODO)
- $\text{full}(A)$

```

1 typedef struct {
2
3     int     nCol;
4     void     *dataMat;
5     eigFactor *eig;
6
7     void     (*dataMatApB) (void *, double, void *);
8     double   (*dataMatDot) ( void *, double * );
9     void     (*dataMatScal) (void *, double);
10    double   (*dataMatNorm) (void *, int);
11    hdsdp_retcode (*dataMatEig) (void *, void **);
12    int       (*dataMatGetNnz)(void *);
13    void      (*dataMatDump) (void *, double *);
14
15 } sdpCoeffMat;

```

1.2.1 Sparse matrix

```

1 typedef struct {
2
3     int     nSDPCol;
4     int     nTriMatElem;
5     int     *triMatCol;
6     int     *triMatRow;
7     double *triMatElem;
8
9 } sdpSparseData;

```

1.2.2 Dense matrix

```
1 typedef struct {
2
3     int      nSDPCol;
4     double *dsMatElem;
5
6 } sdpDenseData;
```

1.2.3 Rank-one sparse matrix

```
1 typedef struct {
2
3     int      nSDPCol;
4     int      nSpR1FactorElem;
5     int      *spR1MatIdx;
6     double   *spR1MatElem;
7
8 } sdpRankOneSpData;
```

1.2.4 Rank-one dense matrix

```
1 typedef struct {
2
3     int      nSDPCol;
4     double *r1MatFactor;
5
6 } sdpRankOneSpData;
```

1.3 SDP variable and step

We use the following structures to store S .

- ▶ S^{-1}
- ▶ $L = \text{chol}(S)$
- ▶ $L \setminus z, L' \setminus z$
- ▶ $y \leftarrow \alpha Sx + y$

coming...

1.4 Schur complement matrix

2 Contribution and formats

- ▶ Indentation, bracket
Default as in Xcode, following the samples below
- ▶ Doxygen string and comments
Using @file, @brief, /* */
- ▶ Function with void return value should return;
- ▶ Name style
Bottom-level routine: extern void csp_Axpby

Medium-level routine: `hdsdpSpMatTrace`

- Use `assert` whenever necessary
- Static before extern
- ...

```
static int pdsCreate( void **pdl1, int n ) {

    int retcode = RETCODE_OK;
    pds_linsys *pds = NULL;

    POTLP_INIT(pds, pds_linsys, 1);

    if ( !pds ) {
        retcode = RETCODE_FAILED;
        goto exit_cleanup;
    }

    pds->n = n;
    *pdl1 = pds;

    /* Initialize pardiso */
    POTLP_ZERO(pds->pt, void *, 64);
    POTLP_ZERO(pds->iparm, int, 64);

    int mtype = PARDISO_SYM_INDEFINITE;
    pardisoinit(pds->pt, &mtype, pds->iparm);

    set_pardiso_param(pds->iparm, PARDISO_PARAM_NONDEFAULT, 1);
    set_pardiso_param(pds->iparm, PARDISO_PARAM_SYMBOLIC, PARDISO_PARAM_SYMBOLIC_MMD);
    set_pardiso_param(pds->iparm, PARDISO_PARAM_PERTURBATION, 3);
    set_pardiso_param(pds->iparm, PARDISO_PARAM_INPLACE, 1);
    set_pardiso_param(pds->iparm, PARDISO_PARAM_INDEX, PARDISO_PARAM_INDEX_C);

exit_cleanup:
    return retcode;
}
```

```
extern void potVecScal( pot_vec *pVexX, double sVal ) {

    scal(&pVexX->n, &sVal, pVexX->x, &potIntConstantOne);

    if ( pVexX->nrm != -1.0 ) {
        pVexX->nrm = pVexX->nrm * fabs(sVal);
    }

    return;
}
```