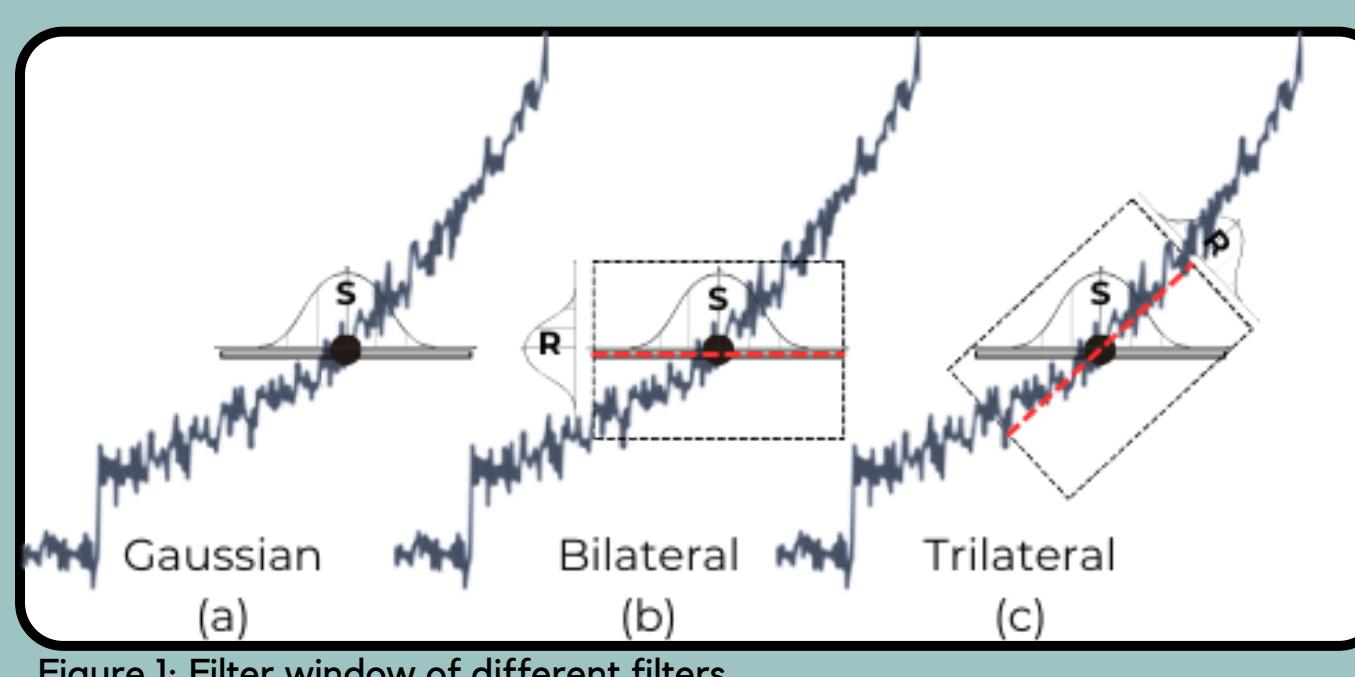


CURVATURE BASED BILATERAL FILTER

1. BACKGROUND

- Bilateral Filter - fast, edge-preserving, smoothing filter.
- Used in image denoising, tone mapping, low-light photography, etc.
- Uses distance and colour difference of neighbouring pixels.



- Trilateral Filter - Uses linear plane approximation to account for gradients in an image.

- Linear approximation is not always suitable. Can we improve it by accounting for curvature in the signal?

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2. RESEARCH QUESTION

- How can integration of local curvature approximation improve the bilateral filter for the distribution of pixel values?

- The idea is to reconstruct local curvature geometry from noisy input.
- It uses the Bilateral filter to approximate partial derivatives of the input.
- Approximate local geometry by fitting a quadratic surface through input using Taylor's second-order approximation.

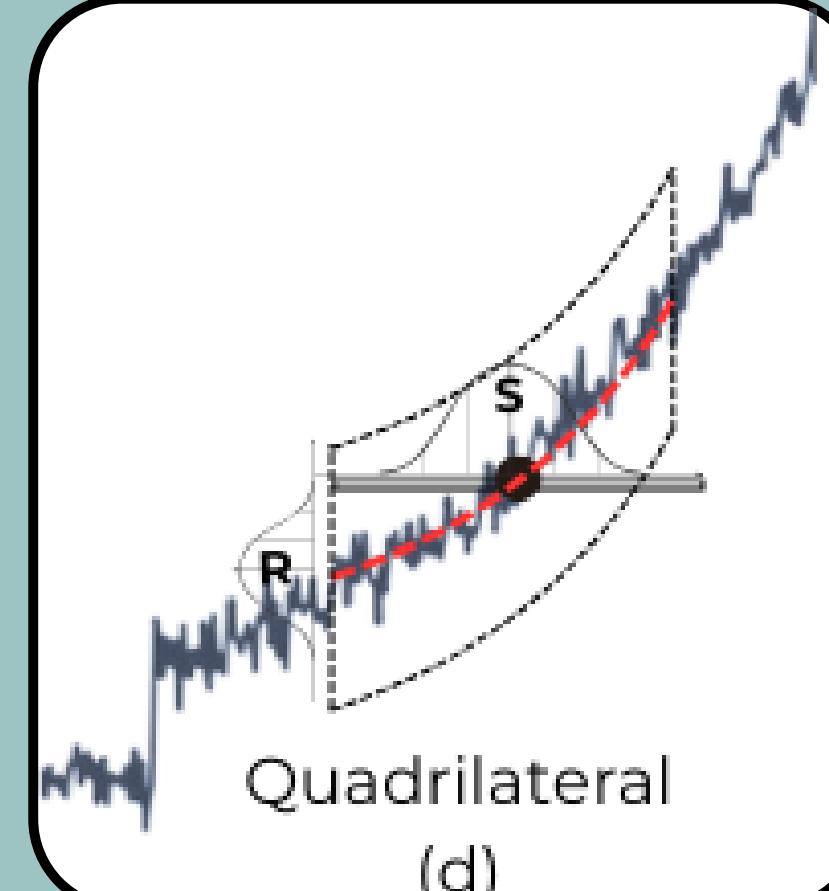


Figure 2: Filter window of a Quadrilateral filter.

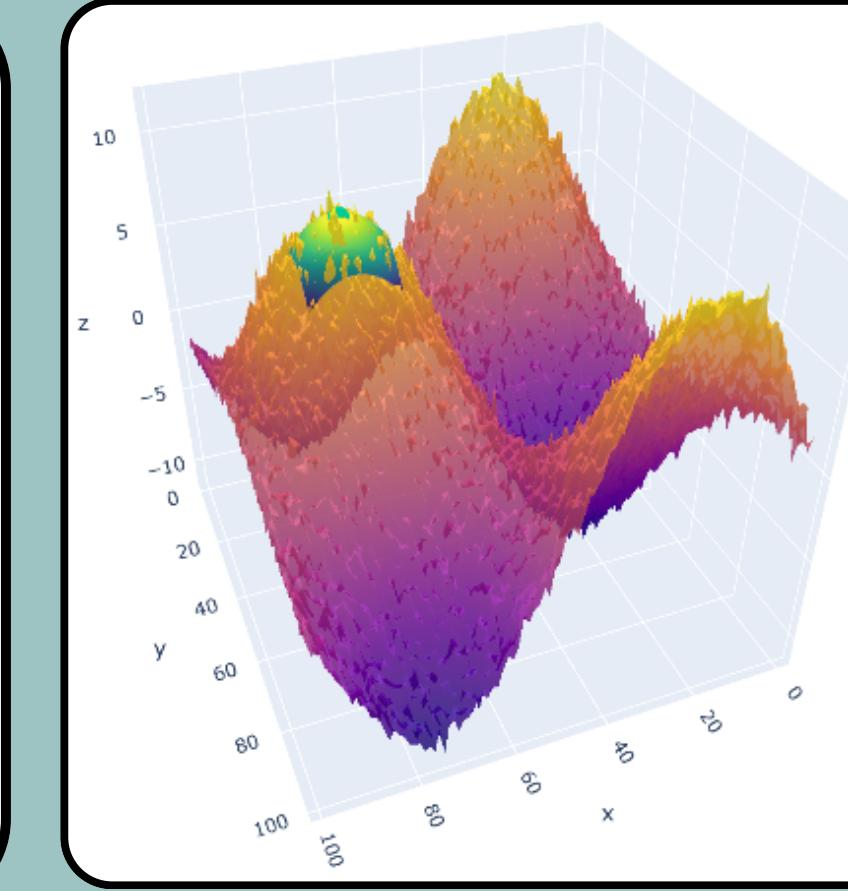


Figure 3: Noisy signal with a quadratic surface approximation.

- If the quadratic surface does not match the neighbouring pixels, we fall back on a simpler geometry approximation: the Bilateral filter.
- The closer the plane matches the neighbouring pixels, the better the approximation and the lower the uncertainty value.
- Uncertainty decides the level of interpolation with the Bilateral filter.

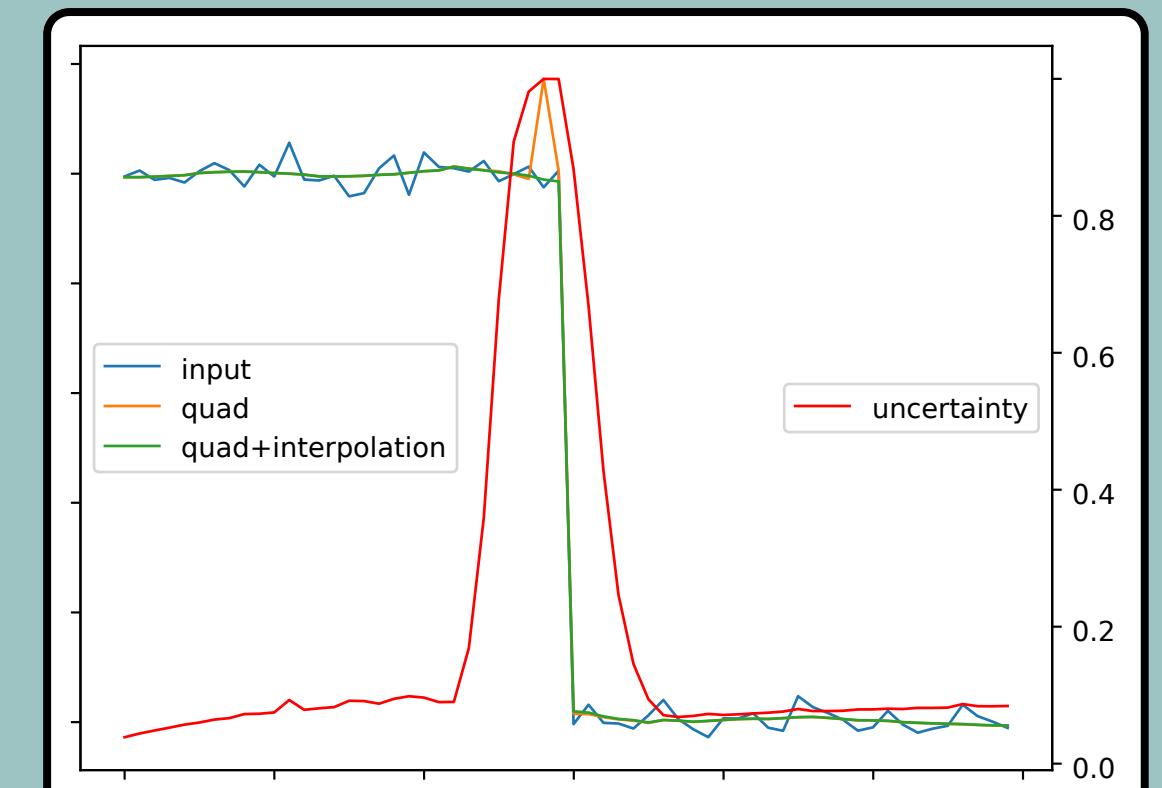


Figure 4: Reducing artifacts of Quadrilateral filter by using interpolation with the Bilateral filter

5. FUTURE WORK

- Multi-stage interpolation process with Trilateral, Bilateral and Gaussian.
- Automatic parameter selection for uncertainty for better usability.
- Computational efficiency.

4. RESULTS

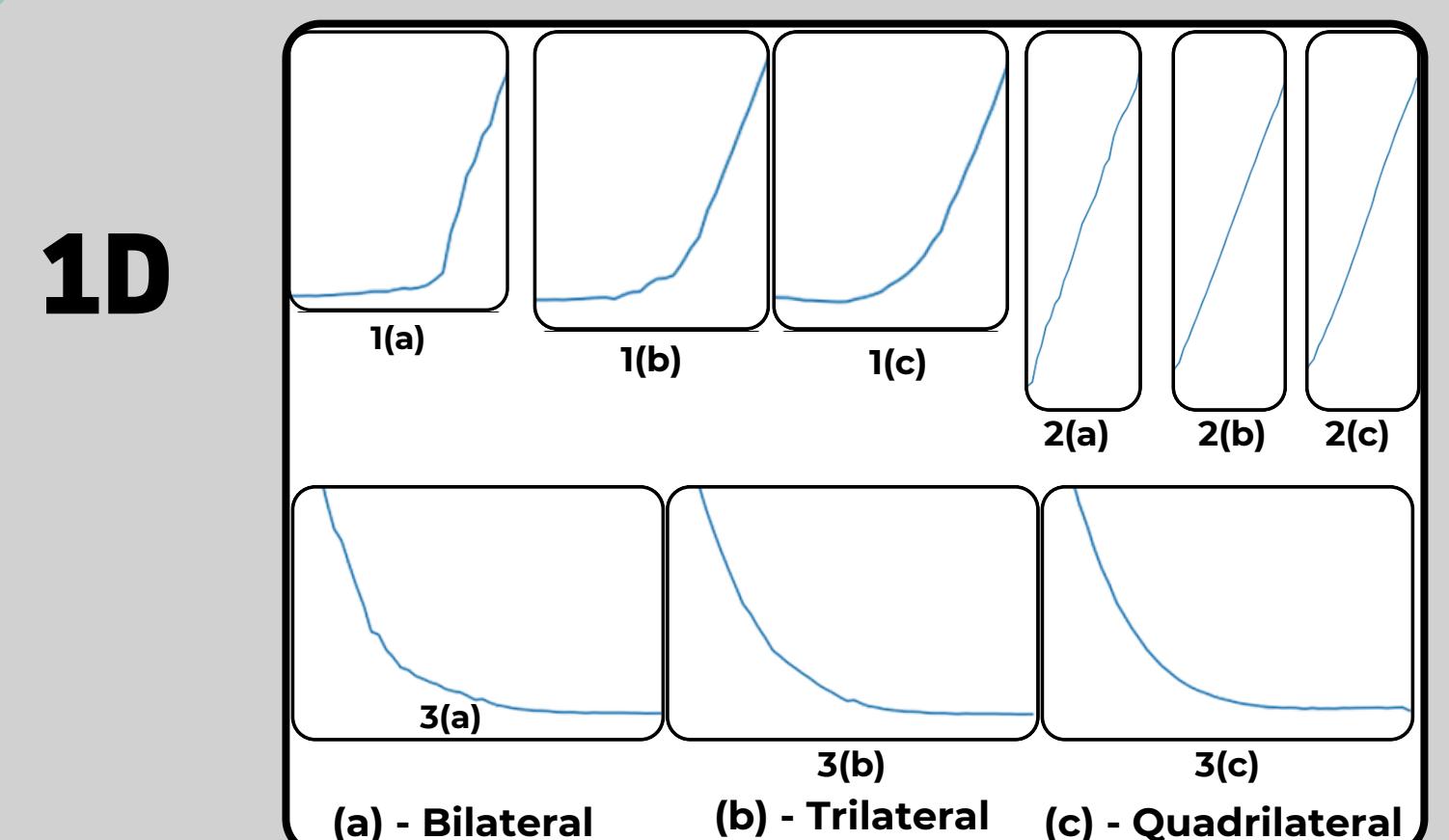
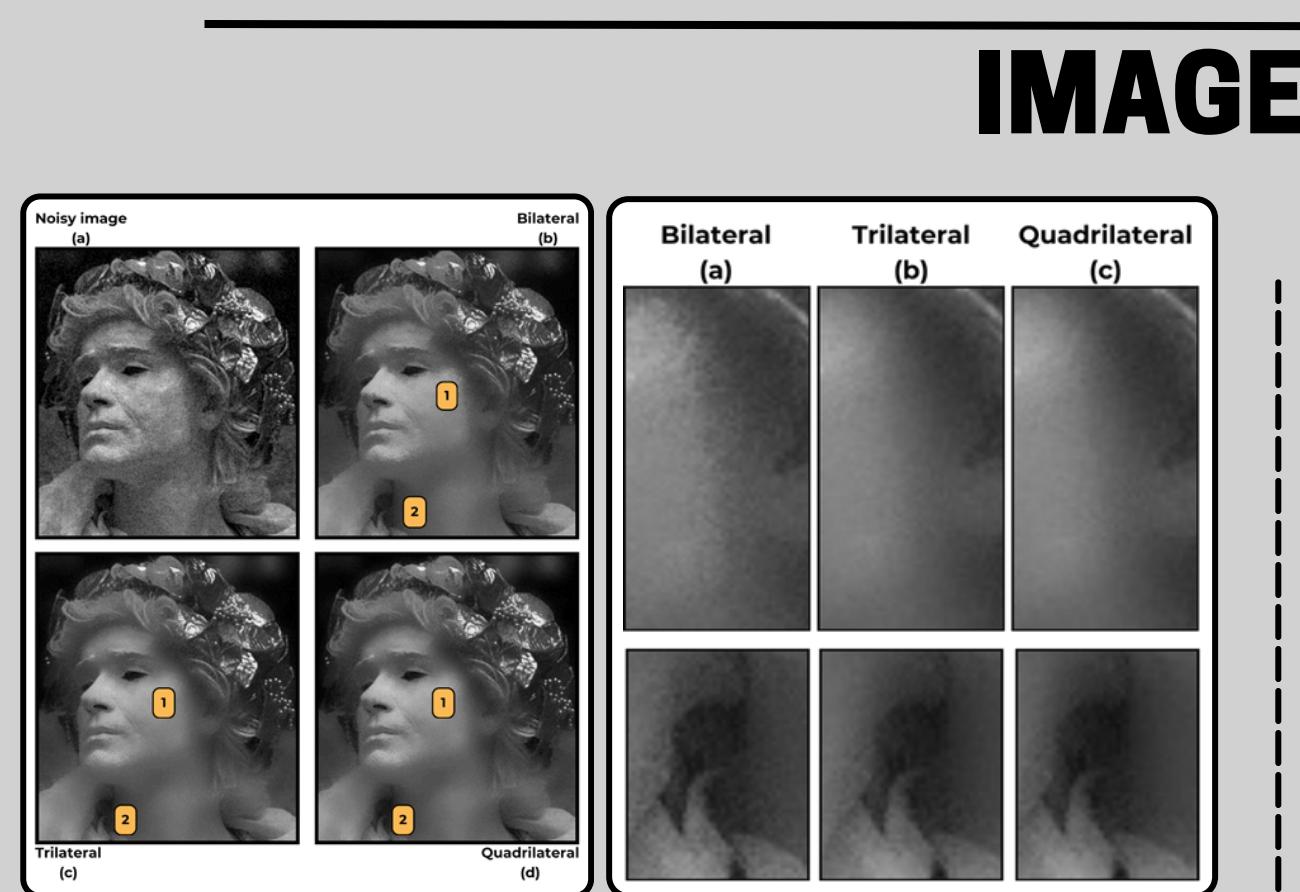


Figure 5: Performance of filters with noisy 1D signal.

- Bilateral filter struggles to remove noise in high gradient areas.
- Quadrilateral filter achieves an overall smoother result, especially in curved areas.



- Quadrilateral filter successfully removes noise from high gradient regions, achieving the smoothest result - Figure 6.
- The Quadrilateral filter distorts the original signal less than the Trilateral filter - Figure 7.

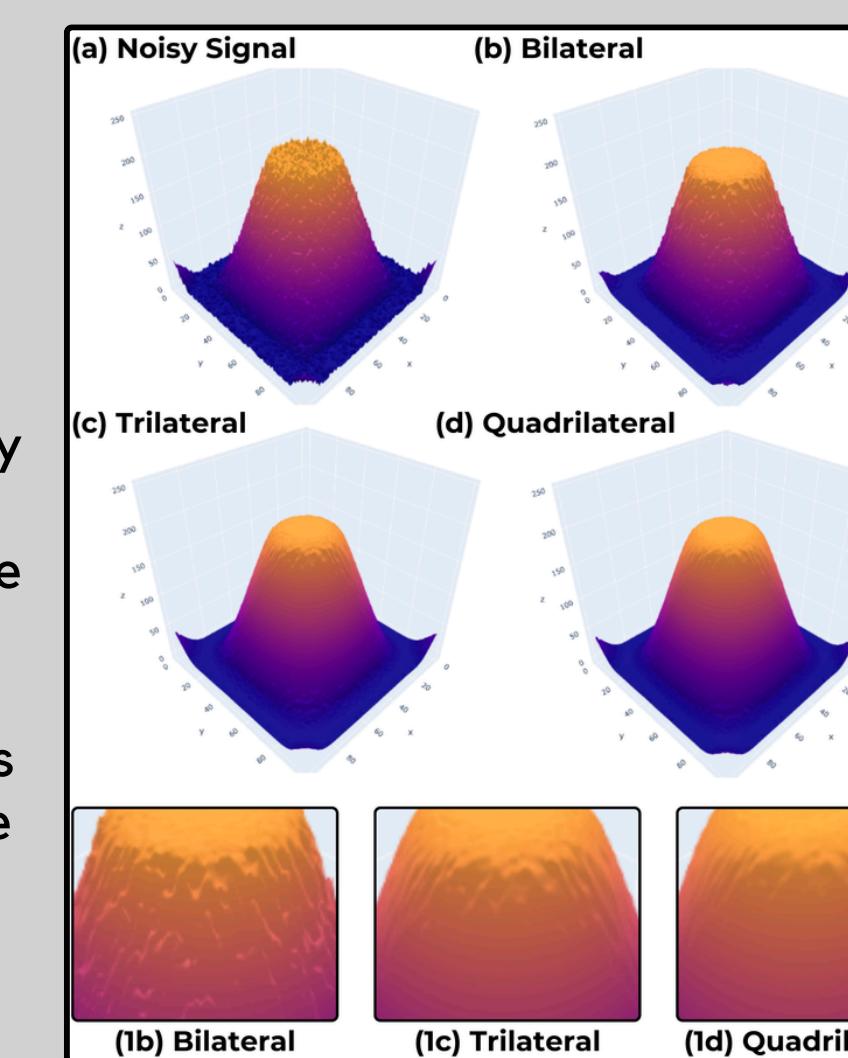


Figure 6: Performance of filters on a 2D signal.

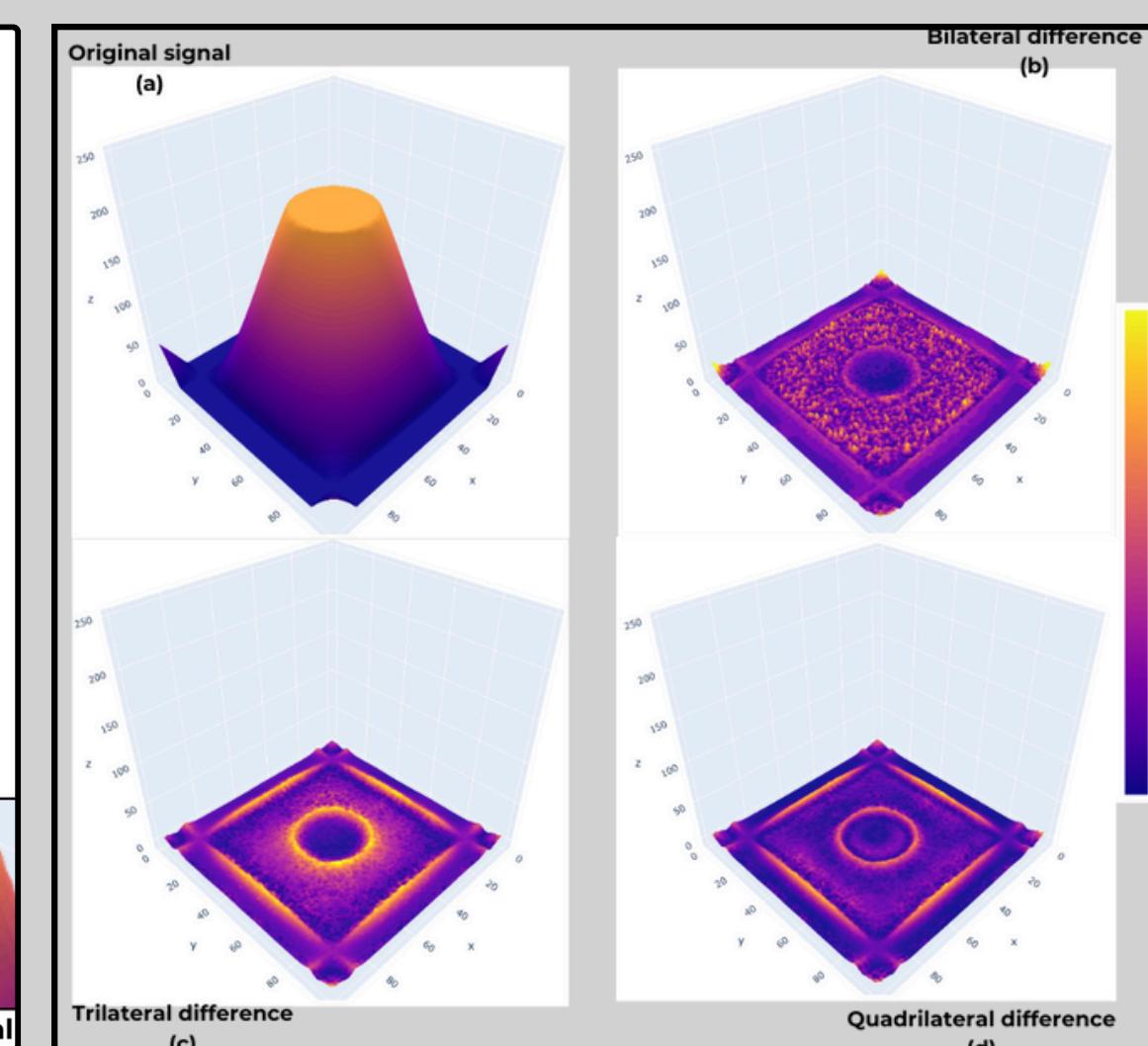


Figure 7: Difference of the original signal and the filtered output.

TONE-MAPPING

- (1) White areas represent the filter not affecting the input image.
- The Bilateral fails to denoise in these areas.
- (2) Patches of one color represent distortion of the image.
- Trilateral filter darkens originally bright areas due to poorer geometry approximation.

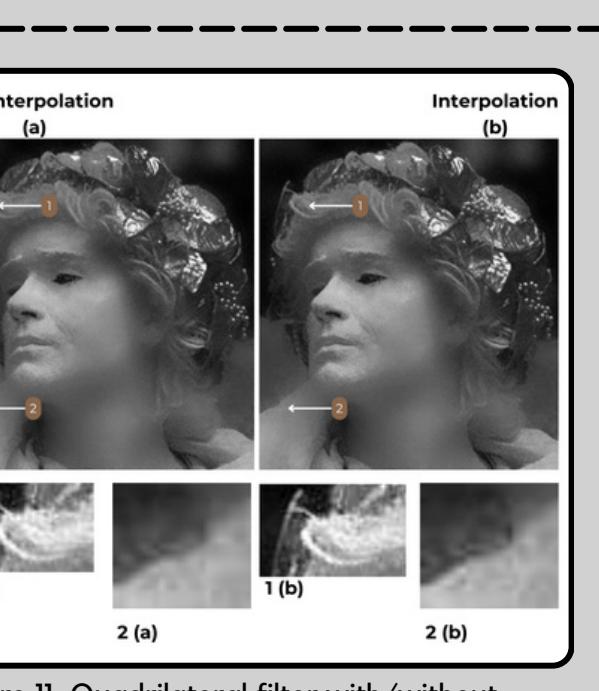


Figure 8: Filtered sculpture image.

- The Bilateral filter leaves the noise in gradient regions.
- Both Trilateral and Quadrilateral filters successfully remove the noise.

- Utilizing Interpolation with the Bilateral filter results in image with sharper edges.

Figure 11: Quadrilateral filter with/without interpolation.

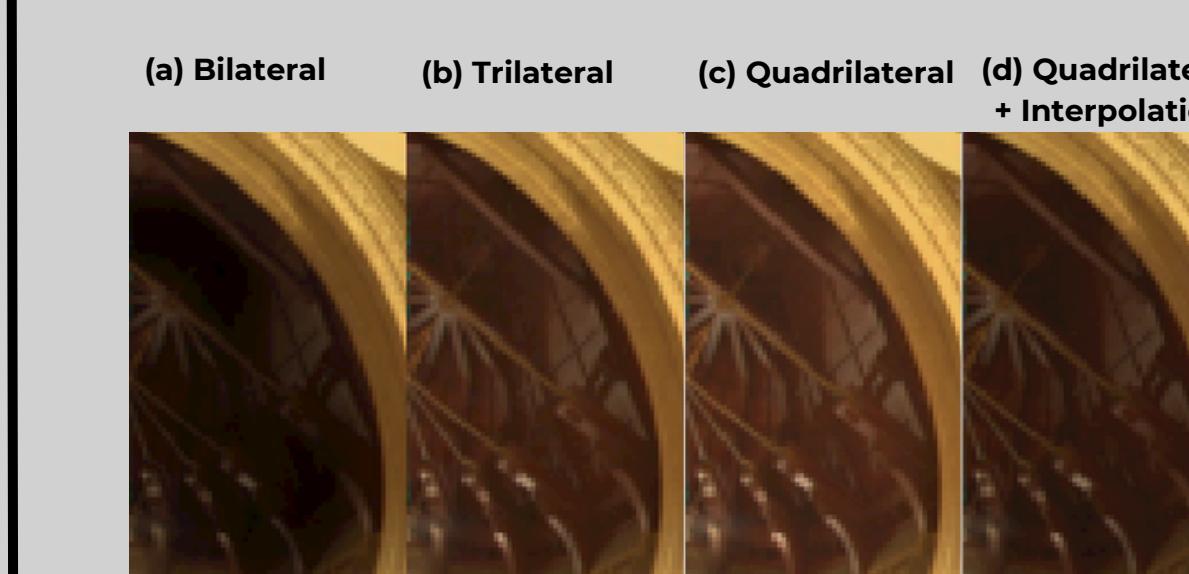


Figure 9: Highlights of Figure 8.

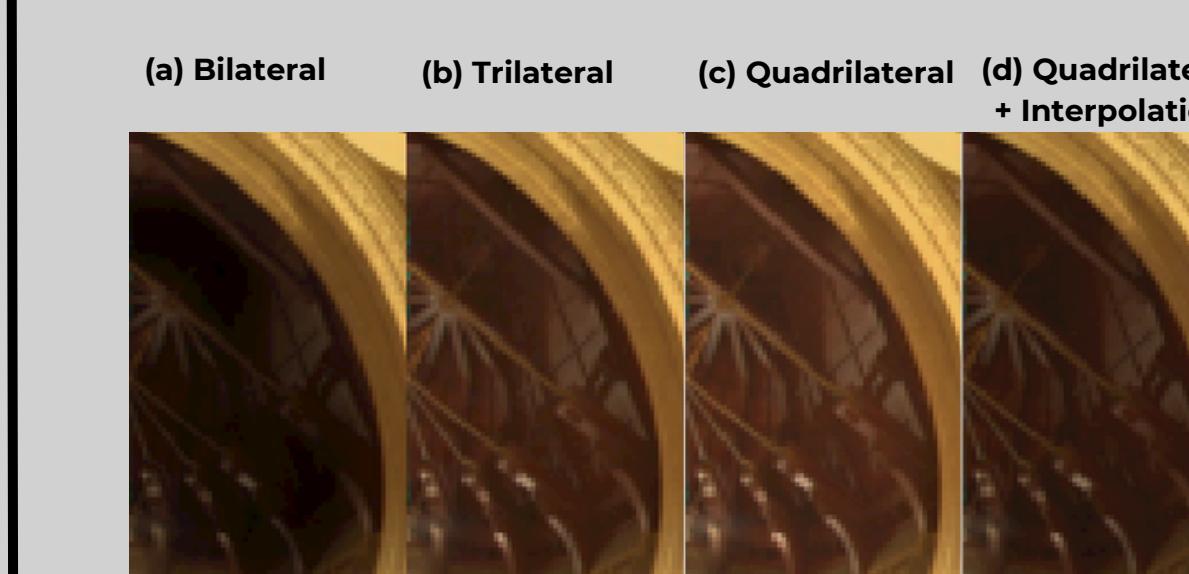


Figure 10: Detail layer - effect of the filter on the input image.

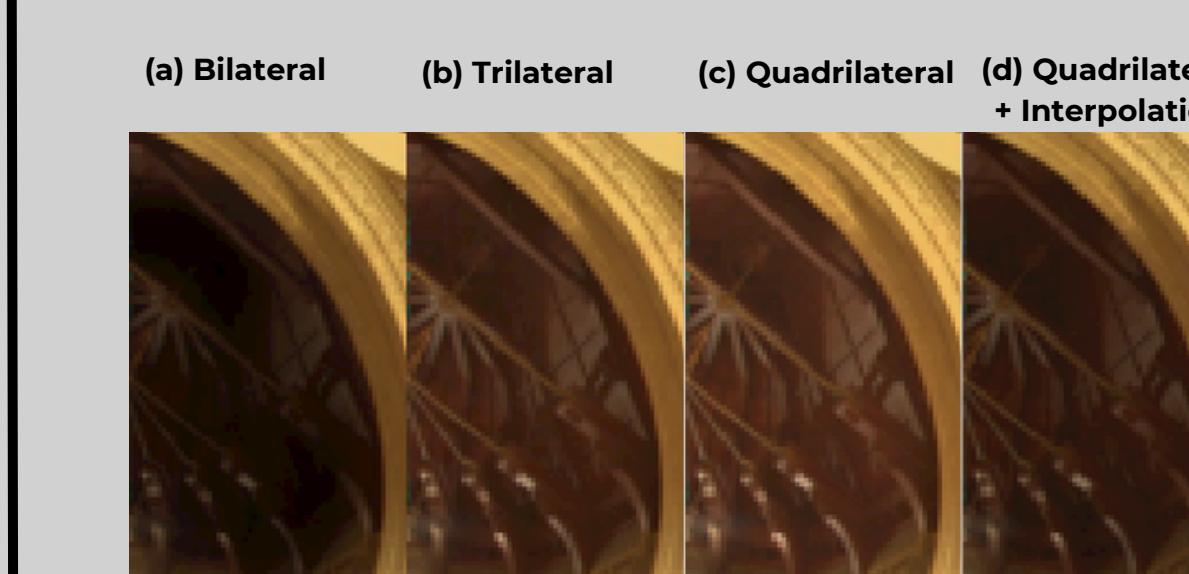


Figure 12: Dark areas tone-mapping.

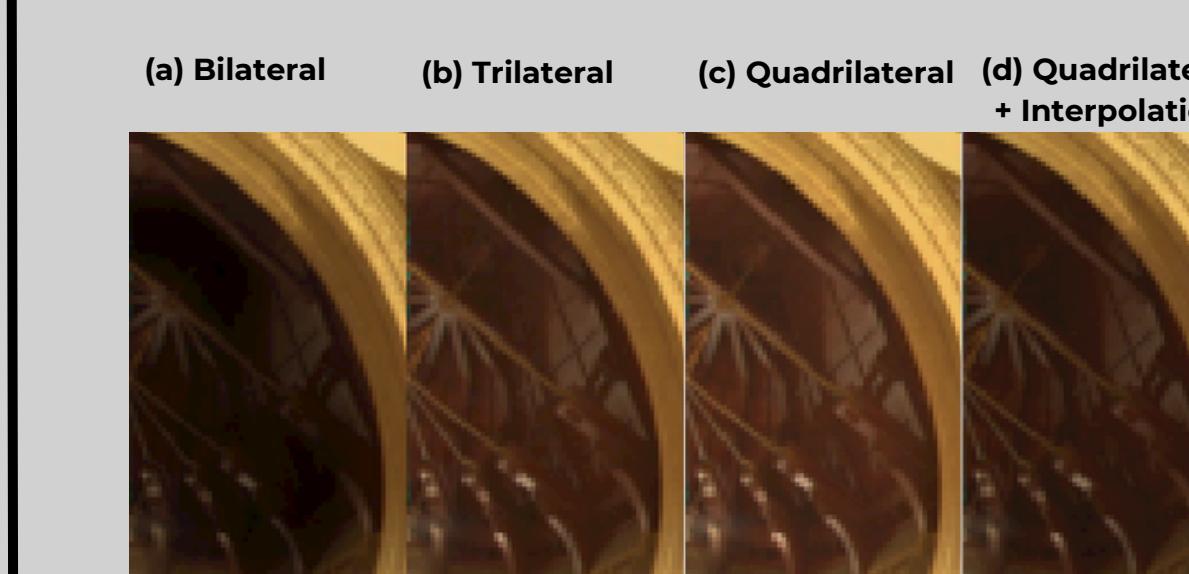


Figure 13: Tone-mapped image.

6. CONCLUSION

- Edge-preserving smoothing filter considering local curvature.
- Smoothing in high-gradient areas while preserving the original distribution of pixel intensities.
- Improved edge preservation by using interpolation with the Bilateral filter.
- Potential applications: multimedia analysis, denoising, tone-mapping and more.

7. REFERENCES

- [1] C. Tomasi and R. Manduchi, "Bilateral filtering for gray and color images," 1998.
- [2] P. Choudhury and J. Tumblin, "The trilateral filter for high contrast images and meshes," in ACM SIGGRAPH 2005 Courses, 2005, p. 5–es.