Linear Algebra

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Introduction

- We have seen that an orthogonal basis for a subspace W of \mathbb{R}^n is particularly nice.
 - For **y** in \mathbb{R}^n , we compute the orthogonal projection of **y** onto W by

$$\hat{\mathbf{y}} = \operatorname{proj}_W \mathbf{y} = c_1 \mathbf{u}_1 + c_2 \mathbf{u}_2 + \ldots + c_p \mathbf{u}_p$$
 with weights $c_i = \frac{\mathbf{y} \cdot \mathbf{u}_i}{\mathbf{u}_i \cdot \mathbf{u}_i}$.

▶ When we choose an orthonormal basis, the calculations are even simpler.

$$\hat{\mathbf{y}} = \operatorname{proj}_W \mathbf{y} = (UU^T)\mathbf{y}.$$

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Example

Let
$$W = \operatorname{Span}\left\{\mathbf{x}_1,\mathbf{x}_2\right\}$$
 denote the subspace of \mathbb{R}^3 where $\mathbf{x}_1 = \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix}$ and $\mathbf{x}_2 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$.

How can we find an orthogonal basis for W?

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$$v_1 = x_1$$
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- ▶ Let $\mathbf{v}_1 = \mathbf{x}_1$.
- ▶ Let \mathbf{v}_2 be the orth proj of \mathbf{x}_2 onto the orth compl of $Y = \text{Span}\{\mathbf{v}_1\}$. By the Orth Decomp Thm, $\mathbf{x}_2 = \operatorname{proj}_{\mathbf{Y}} \mathbf{x}_2 + \mathbf{z}$, where \mathbf{z} is in \mathbf{Y}^{\perp} .

$$\operatorname{proj}_{Y} \mathbf{x}_{2} = \operatorname{proj}_{\mathbf{v}_{1}} \mathbf{x}_{2} = \begin{pmatrix} \mathbf{x}_{2} \cdot \mathbf{v}_{1} \\ \mathbf{v}_{1} \cdot \mathbf{v}_{1} \end{pmatrix} \mathbf{v}_{1} = \frac{15}{45} \begin{bmatrix} 3 \\ 6 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$$

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$$\blacktriangleright \text{ Hence } \mathbf{v}_{2} = \mathbf{z} = \mathbf{x}_{2} - \operatorname{proj}_{\mathbf{v}_{1}} \mathbf{x}_{2} = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}.$$

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- Since $\mathbf{v}_2 = \mathbf{x}_2 \operatorname{proj}_{\mathbf{v}_1} \mathbf{x}_2 = \mathbf{x}_2 + c\mathbf{x}_1$, \mathbf{v}_2 is in the subspace W.

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 - Since $\mathbf{v}_2 = \mathbf{x}_2 \operatorname{proj}_{\mathbf{v}_1} \mathbf{x}_2 = \mathbf{x}_2 + c\mathbf{x}_1$, \mathbf{v}_2 is in the subspace W.
- Thus $\{\mathbf{v}_1, \mathbf{v}_2\} = \left\{ \begin{bmatrix} 3 \\ 6 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}$ is an orthogonal basis for W.

Given a basis $\{\mathbf{x}_1,\mathbf{x}_2,\ldots,\mathbf{x}_p\}$ for a nonzero subspace W of \mathbb{R}^n , define

$$\mathbf{v}_1 = \mathbf{x}_1$$
 $Y_1 = \mathsf{Span}\{\mathbf{v}_1\}$

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$$\begin{aligned} \mathbf{v}_1 &= \mathbf{x}_1 & Y_1 &= \mathsf{Span}\{\mathbf{v}_1\} \\ \mathbf{v}_2 &= \mathsf{proj}_{Y_1^\perp} \mathbf{x}_2 = \mathbf{x}_2 - \mathsf{proj}_{Y_1} \mathbf{x}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 & Y_2 &= \mathsf{Span}\{\mathbf{v}_1, \mathbf{v}_2\} \\ \mathbf{v}_3 &= \mathsf{proj}_{Y_2^\perp} \mathbf{x}_3 = \mathbf{x}_3 - \mathsf{proj}_{Y_2} \mathbf{x}_3 = \mathbf{x}_3 - \left(\frac{\mathbf{x}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 - \left(\frac{\mathbf{x}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2}\right) \mathbf{v}_2 & Y_3 &= \mathsf{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} \end{aligned}$$

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Given a basis $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_p\}$ for a nonzero subspace W of \mathbb{R}^n , define

$$\begin{aligned} \mathbf{v}_1 &= \mathbf{x}_1 & Y_1 &= \mathsf{Span}\{\mathbf{v}_1\} \\ \mathbf{v}_2 &= \mathsf{proj}_{Y_1^\perp} \mathbf{x}_2 = \mathbf{x}_2 - \mathsf{proj}_{Y_1} \mathbf{x}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 & Y_2 &= \mathsf{Span}\{\mathbf{v}_1, \mathbf{v}_2\} \\ \mathbf{v}_3 &= \mathsf{proj}_{Y_2^\perp} \mathbf{x}_3 = \mathbf{x}_3 - \mathsf{proj}_{Y_2} \mathbf{x}_3 = \mathbf{x}_3 - \left(\frac{\mathbf{x}_3 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 - \left(\frac{\mathbf{x}_3 \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2}\right) \mathbf{v}_2 & Y_3 &= \mathsf{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} \\ &\vdots \\ \mathbf{v}_p &= \mathsf{proj}_{Y_{p-1}^\perp} \mathbf{x}_p = \mathbf{x}_p - \mathsf{proj}_{Y_{p-1}} \mathbf{x}_p \\ &= \mathbf{x}_p - \left(\frac{\mathbf{x}_p \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 - \left(\frac{\mathbf{x}_p \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2}\right) \mathbf{v}_2 - \ldots - \left(\frac{\mathbf{x}_p \cdot \mathbf{v}_{p-1}}{\mathbf{v}_{p-1} \cdot \mathbf{v}_{p-1}}\right) \mathbf{v}_{p-1}. & Y_p &= \mathsf{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \ldots, \mathbf{v}_p\} \end{aligned}$$

Theorem

Then $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ is an orthogonal basis for W.

Given a basis $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_p\}$ for a nonzero subspace W of \mathbb{R}^n , define

Theorem

Then $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ is an orthogonal basis for W. In addition,

$$\operatorname{Span}\left\{\mathbf{x}_{1},\mathbf{x}_{2},\ldots,\mathbf{x}_{k}\right\}=Y_{k}=\operatorname{Span}\left\{\mathbf{v}_{1},\mathbf{v}_{2},\ldots,\mathbf{v}_{k}\right\}\quad\text{for }1\leq k\leq p.$$

Find an orthogonal basis for the subspace $W = \operatorname{Span} \left\{ \begin{bmatrix} 1 \\ -4 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 7 \\ -7 \\ -4 \\ 1 \end{bmatrix} \right\}$ in \mathbb{R}^4 .

Find an orthogonal basis for the subspace
$$W = \operatorname{Span} \left\{ \begin{bmatrix} 1 \\ -4 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 7 \\ -7 \\ -4 \\ 1 \end{bmatrix} \right\}$$
 in \mathbb{R}^4 . We have $\mathbf{v}_1 = \mathbf{x}_1 = \begin{bmatrix} 1 \\ -4 \\ 0 \\ 1 \end{bmatrix}$.

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We have
$$\mathbf{v}_1 = \mathbf{x}_1 = egin{bmatrix} 1 \ -4 \ 0 \ 1 \end{bmatrix}$$
 .

Then we find
$$\mathbf{v}_2 = \mathbf{x}_2 - \begin{pmatrix} \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \end{pmatrix} \mathbf{v}_1 = \begin{bmatrix} 7 \\ -7 \\ -4 \\ 1 \end{bmatrix} - \begin{pmatrix} \frac{36}{18} \end{pmatrix} \begin{bmatrix} 1 \\ -4 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 1 \\ -4 \\ -1 \end{bmatrix}.$$

Thus an orthogonal basis for
$$W$$
 is $\left\{ \begin{bmatrix} 1 \\ -4 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ 1 \\ -4 \\ -1 \end{bmatrix} \right\}$.

Consider the matrix
$$A = \begin{bmatrix} 3 & -5 & 1 \\ 1 & 1 & 1 \\ -1 & 5 & -2 \\ 3 & -7 & 8 \end{bmatrix}$$
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First we find a basis for the column space by checking the reduced row echelon form of A:

$$\begin{bmatrix} 3 & -5 & 1 \\ 1 & 1 & 1 \\ -1 & 5 & -2 \\ 3 & -7 & 8 \end{bmatrix} \xrightarrow{\mathsf{RREF}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \text{ so a basis for Col } A \text{ is } \left\{ \begin{bmatrix} 3 \\ 1 \\ -1 \\ 3 \end{bmatrix}, \begin{bmatrix} -5 \\ 1 \\ 5 \\ -7 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 8 \end{bmatrix} \right\}.$$

Next we use the Gram-Schmidt Process to convert the basis into an orthogonal basis.

Example, continued

Col
$$A = \operatorname{Span} \left\{ \begin{bmatrix} 3\\1\\-1\\3 \end{bmatrix}, \begin{bmatrix} -5\\1\\5\\-7 \end{bmatrix}, \begin{bmatrix} 1\\1\\-2\\8 \end{bmatrix} \right\}$$
. We first define $\mathbf{v}_1 = \begin{bmatrix} 3\\1\\-1\\3 \end{bmatrix}$.

Example, continued

$$\operatorname{Col} A = \operatorname{Span} \left\{ \begin{bmatrix} 3 \\ 1 \\ -1 \\ 3 \end{bmatrix}, \begin{bmatrix} -5 \\ 1 \\ 5 \\ -7 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 8 \end{bmatrix} \right\}. \text{ We first define } \mathbf{v}_1 = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 3 \end{bmatrix}.$$

Then we continue with Gram–Schmidt process:

$$\mathbf{v}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 = \begin{bmatrix} -5\\1\\5\\-7 \end{bmatrix} - \left(\frac{-40}{20}\right) \begin{bmatrix} 3\\1\\-1\\3 \end{bmatrix} = \begin{bmatrix} 1\\3\\3\\-1 \end{bmatrix}$$

Example, continued

$$\operatorname{Col} A = \operatorname{Span} \left\{ \begin{bmatrix} 3 \\ 1 \\ -1 \\ 3 \end{bmatrix}, \begin{bmatrix} -5 \\ 1 \\ 5 \\ -7 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 8 \end{bmatrix} \right\}. \text{ We first define } \mathbf{v}_1 = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 3 \end{bmatrix}.$$

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$$\mathbf{v}_{3} = \mathbf{x}_{3} - \left(\frac{\mathbf{x}_{3} \cdot \mathbf{v}_{1}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}}\right) \mathbf{v}_{1} - \left(\frac{\mathbf{x}_{3} \cdot \mathbf{v}_{2}}{\mathbf{v}_{2} \cdot \mathbf{v}_{2}}\right) \mathbf{v}_{2} = \begin{bmatrix} 1 \\ 1 \\ -2 \\ 8 \end{bmatrix} - \left(\frac{30}{20}\right) \begin{bmatrix} 3 \\ 1 \\ -1 \\ 3 \end{bmatrix} - \frac{-10}{20} \begin{bmatrix} 1 \\ 3 \\ 3 \\ -1 \end{bmatrix} = \begin{bmatrix} -3 \\ 1 \\ 1 \\ 3 \end{bmatrix}$$

Normalizing the Basis

For the 4 × 3 matrix
$$A = \begin{bmatrix} 3 & -5 & 1 \\ 1 & 1 & 1 \\ -1 & 5 & -2 \\ 3 & -7 & 8 \end{bmatrix}$$
, we therefore have

An orthogonal basis for Col A is $\left\{ \begin{bmatrix} 3\\1\\-1\\3 \end{bmatrix}, \begin{bmatrix} 1\\3\\3\\-1 \end{bmatrix}, \begin{bmatrix} -3\\1\\1\\3 \end{bmatrix} \right\}$.

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► An orthonormal basis for Col *A* is $\left\{ \begin{bmatrix} 3/\sqrt{20} \\ 1/\sqrt{20} \\ -1/\sqrt{20} \\ 3/\sqrt{20} \end{bmatrix}, \begin{bmatrix} 1/\sqrt{20} \\ 3/\sqrt{20} \\ 3/\sqrt{20} \\ -1/\sqrt{20} \end{bmatrix}, \begin{bmatrix} -3/\sqrt{20} \\ 1/\sqrt{20} \\ 1/\sqrt{20} \\ 3/\sqrt{20} \end{bmatrix} \right\}$.