

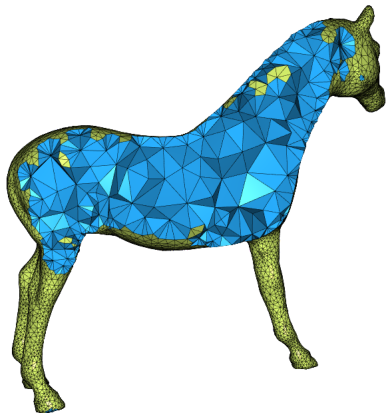
# Applications to Computer Graphics

## Linear Algebra

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# Applications of Linear Algebra to Computer Graphics



<https://www.cg.tu-berlin.de/research/projects/harmonic-triangulations/>



Image Credit: Star Wars low poly portraits, designed by Vladan Filipovic

Let's examine some ways to manipulate and display graphical images using matrices.

# Scaling One Triangle

Consider one triangular piece. If we want to scale the triangle by a factor of three, then we apply the transformation

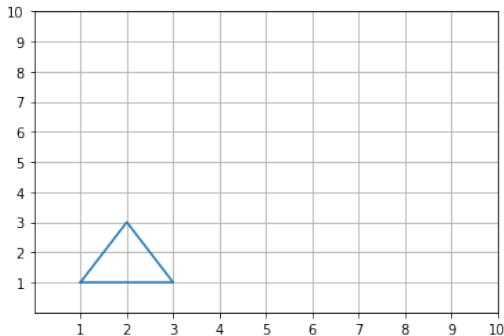
$$S : \mathbb{R}^2 \rightarrow \mathbb{R}^2 : \mathbf{x} \mapsto \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} \mathbf{x}.$$

We have:

$$\begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 9 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 9 \end{bmatrix}$$



# Vertical Scaling

If we would like to vertically scale the triangle by a factor of 2, we have

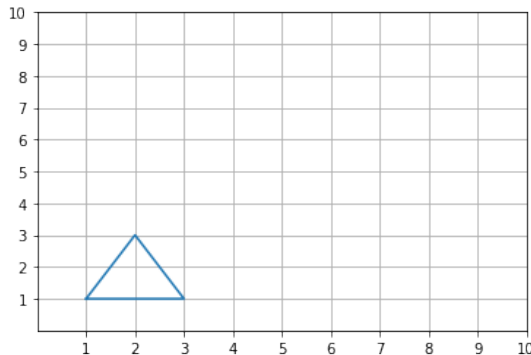
$$V : \mathbb{R}^2 \rightarrow \mathbb{R}^2 : \mathbf{x} \mapsto \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \mathbf{x}.$$

We have:

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$$



# Rotation

If we would like to rotate the triangle counter-clockwise by an angle of  $\theta$  around the origin, we have

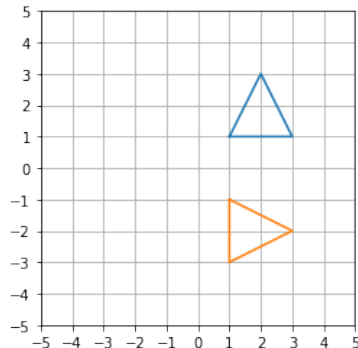
$$R : \mathbb{R}^2 \rightarrow \mathbb{R}^2 : \mathbf{x} \mapsto \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \mathbf{x}.$$

For example a counterclockwise rotation by  $\theta = \frac{3\pi}{2}$  would be given by

$$R : \mathbb{R}^2 \rightarrow \mathbb{R}^2 : \mathbf{x} \mapsto \begin{bmatrix} \cos \frac{3\pi}{2} & -\sin \frac{3\pi}{2} \\ \sin \frac{3\pi}{2} & \cos \frac{3\pi}{2} \end{bmatrix} \mathbf{x} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \mathbf{x}.$$

We have:

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \quad \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -3 \end{bmatrix}, \quad \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \end{bmatrix}$$



# Composing Maps

Imagine we want to apply three transformations to the triangle in the following order:

1. Scale the triangle by a factor of three.
2. Then vertically scale by a factor of 2 (in vertical direction only).
3. Finally rotate counter-clockwise around the origin by  $\theta = 270^\circ = \frac{3\pi}{2}$  radians.

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First apply the scaling matrix using matrix  $S$ :    Then apply the vertical scaling using  $V$ :    Finally, we rotate this result counter-clockwise by  $\theta = \frac{3\pi}{2}$  using  $R$ :

$$\begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix}.$$

$$\begin{bmatrix} \cos\left(\frac{3\pi}{2}\right) & -\sin\left(\frac{3\pi}{2}\right) \\ \sin\left(\frac{3\pi}{2}\right) & \cos\left(\frac{3\pi}{2}\right) \end{bmatrix} \begin{bmatrix} 3 \\ 6 \end{bmatrix} = \begin{bmatrix} 6 \\ -3 \end{bmatrix}.$$

The image under the composition of these three transformations is  $R\left(V(S(\mathbf{x}))\right) = (RVS)(\mathbf{x})$

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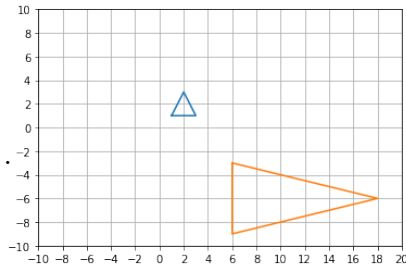
$$M : \mathbb{R}^2 \rightarrow \mathbb{R}^2 : \mathbf{x} \mapsto RVS\mathbf{x}.$$

where

$$RVS = \begin{bmatrix} \cos\left(\frac{3\pi}{2}\right) & -\sin\left(\frac{3\pi}{2}\right) \\ \sin\left(\frac{3\pi}{2}\right) & \cos\left(\frac{3\pi}{2}\right) \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 0 & 6 \\ -3 & 0 \end{bmatrix}.$$

Thus we have

$$\begin{bmatrix} 0 & 6 \\ -3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 6 \\ -3 \end{bmatrix}$$





# Composing Linear Transformations

The composition of linear transformations with associated matrices  $A$ ,  $B$ , and  $C$  in the following order:

1. first apply transformation given by matrix  $A$ ,
2. then apply transformation given by matrix  $B$ , and
3. finally apply transformation given by matrix  $C$

is equivalent to the linear transformation with associated matrix given by  $CBA$ .

Note we can extend this idea to compose any number of linear transformations.

# Translations

To translate the vertex of the triangle at  $(1,1)$  to the left by 2 units and up by 3 units, **we add vectors**:

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -2 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 4 \end{bmatrix}$$

Doing the same for the other two vertices, we have

$$\begin{bmatrix} 3 \\ 1 \end{bmatrix} + \begin{bmatrix} -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \end{bmatrix} \quad \begin{bmatrix} 2 \\ 3 \end{bmatrix} + \begin{bmatrix} -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \end{bmatrix}.$$



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  - These operations can be defined by **matrix multiplication**.

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# Homogeneous Coordinates

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- ▶ A translation is not a linear transformation. We add vectors rather than multiply.
- ▶ How can we compose translations with the other linear transformations if translation cannot be represented as matrix multiplication?

One common way is to introduce **homogeneous coordinates**:

- ▶ Each point  $(x, y)$  in  $\mathbb{R}^2$  can be identified with the point  $(x, y, 1)$  in  $\mathbb{R}^3$ .
- ▶ We say  $(x, y)$  has homogeneous coordinates  $(x, y, 1)$ .

# Homogeneous Coordinates

Now we can perform translation by matrix multiplication. For example, if we want to shift the point  $(3, 1)$  to the left by 2 units and up by the 3 units, then we have the product

$$\begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 - 2 \\ 1 + 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix}$$

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In general, if we want to translate by  $h$  units in the horizontal direction and  $k$  units in the vertical direction, using homogeneous coordinates we have:

$$\begin{bmatrix} 1 & 0 & h \\ 0 & 1 & k \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} = \begin{bmatrix} x + h \\ y + k \\ 1 \end{bmatrix} .$$

Let's perform a composition of three different transformations to the triangle in the following order:

1. Scale the triangle by a factor of 3.
2. Rotate the triangle counter-clockwise around the origin by  $\frac{\pi}{2}$ .
3. Translate to the right by 5 units and down by 2 units.

We have the following three matrices for the scaling  $S$ , rotation  $R$ , and translation  $B$ , respectively,

$$S = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad R = \begin{bmatrix} \cos \frac{\pi}{2} & -\sin \frac{\pi}{2} & 0 \\ \sin \frac{\pi}{2} & \cos \frac{\pi}{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & 5 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}.$$

We can now compose all three maps by multiplying matrices:

$$BRS = \begin{bmatrix} 1 & 0 & 5 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -3 & 5 \\ 3 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix}.$$



1. Scale the triangle by a factor of 3.
2. Rotate the triangle counter-clockwise around the origin by  $\frac{\pi}{2}$ .
3. Translate to the right by 5 units and down by 2 units.

Then we have each vertex (given in homogeneous coordinates) mapped as follows

$$\begin{bmatrix} 0 & -3 & 5 \\ 3 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & -3 & 5 \\ 3 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix} \mapsto \begin{bmatrix} 2 \\ 7 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & -3 & 5 \\ 3 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix} \mapsto \begin{bmatrix} -4 \\ 4 \\ 1 \end{bmatrix}.$$

