Vector Spaces and Subspaces

Linear Algebra

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Introduction

We have seen that vector addition and scalar multiplication are key concepts for linear algebra:

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- vector equations (linear systems and matrix equations),
- linear transformations.

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So far our vectors have been vectors in \mathbb{R}^n .

We will now generalize "vectors" to be any objects that we can add and do scalar mult.

Vector Spaces

A vector space is a nonempty set V of objects called **vectors** on which we define two operations, called addition and scalar multiplication, for which the following properties hold for all vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} in V and all scalars c and d:

1. Closed under addition:

$$\mathbf{u} + \mathbf{v}$$
 is in V .

2. Addition is commutative:

$$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$$

3. Addition is associative:

$$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$$

- 4. Additive identity (zero vector): There exists $\mathbf{0}$ in V such that $\mathbf{u} + \mathbf{0} = \mathbf{u}$.
- 5. Additive inverse: For each **u** in *V*, there
- 5. Additive inverse: For each \mathbf{u} in V, ther exists $\mathbf{a} \mathbf{u}$ in V where $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$.

- 6. Closed under scalar multiplication: *cu* is in *V*.
- 7. Distributive property 2:

$$(c+d)\mathbf{u}=c\mathbf{u}+d\mathbf{u}$$

8. Distributive property 1:

$$c(\mathbf{u}+\mathbf{v})=c\mathbf{u}+c\mathbf{v}$$

- 9. Scalar multiplication is associative: $c(d\mathbf{u}) = (cd)\mathbf{u}$
- 10. Multiplicative identity: 1u = u

Examples

 $V=\mathbb{R}^2$ with usual vector addition and scalar multiplication.

1.
$$\mathbf{u} + \mathbf{v}$$
 is in \mathbb{R}^2 .

2.
$$u + v = v + u$$

3.
$$(u + v) + w = u + (v + w)$$

4.
$$u + 0 = u$$
.

5.
$$\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$$
.

6.
$$c\mathbf{u}$$
 is in \mathbb{R}^2 .

7.
$$c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$$

8.
$$(c+d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$$

9.
$$c(d\mathbf{u}) = (cd)\mathbf{u}$$

10.
$$1u = u$$

Examples

 $V=\mathbb{P}_2$ denote the set of all polynomials of degree at most two, with the usual operations.

$$V = \{a_2x^2 + a_1x + a_0 : a_2, a_1, a_0 \in \mathbb{R}\}\$$

Examples

 $V = \mathbb{P}_2$ denote the set of all polynomials of degree at most two, with the usual operations.

$$V = \{a_2x^2 + a_1x + a_0 : a_2, a_1, a_0 \in \mathbb{R}\}\$$

1.
$$(a_2x^2 + a_1x + a_0) + (b_2x^2 + b_1x + b_0) = 6$$
. $cf(x) = ca_2x^2 + ca_1x + ca_0$ in \mathbb{P}_2
 $(a_2 + b_2)x^2 + (a_1 + b_1)x + (a_0 + b_0)$

6.
$$cf(x) = ca_2x^2 + ca_1x + ca_0$$
 in \mathbb{P}_2

2.
$$f(x) + g(x) = g(x) + f(x)$$

7.
$$c(f(x) + g(x)) = cf(x) + cg(x)$$

3.
$$(f(x)+g(x))+h(x) = f(x)+(g(x)+h(x))$$

8.
$$(c+d)f(x) = cf(x) + df(x)$$

4.
$$\mathbf{0} = 0x^2 + 0x + 0 = 0$$

9.
$$c(df(x)) = (cd)f(x)$$

5.
$$-f(x) = -a_2x^2 - a_1x - a_0$$
.

10.
$$1f(x) = f(x)$$

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 with usual scalar multiplication and $\mathbf{u}+\mathbf{v}=egin{bmatrix} u_1+v_2\ u_2+v_2\ u_3+v_2 \end{bmatrix}$.

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- 1. $\mathbf{u} + \mathbf{v}$ is in \mathbb{R}^3 .
- 2. $\mathbf{u} + \mathbf{v} = \begin{bmatrix} u_1 + v_2 & u_2 + v_2 & u_3 + v_2 \\ \mathbf{v} + \mathbf{u} = \begin{bmatrix} v_1 + u_2 & v_2 + u_2 & v_3 + u_2 \end{bmatrix}$.
- 3. $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = [(u_1 + v_2) + w_2 \quad (u_2 + v_2) + w_2 \quad (u_3 + v_2) + w_2]$ $\mathbf{u} + (\mathbf{v} + \mathbf{w}) = [u_1 + (v_2 + w_2) \quad u_2 + (v_2 + w_2) \quad u_3 + (v_2 + w_2)]$
- 4. $\mathbf{u} + \mathbf{0} = \mathbf{u}$, then $\mathbf{0} = \begin{bmatrix} a & 0 & b \end{bmatrix}$.
- 5. $\mathbf{u} = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}$ has no additive inverse.

- 6. $c\mathbf{u}$ is in \mathbb{R}^3 .
- 7. $c(\mathbf{u} + \mathbf{v}) = \begin{bmatrix} c(u_1 + v_2) & c(u_2 + v_2) & c(u_3 + v_2) \end{bmatrix}$ $c\mathbf{u} + c\mathbf{v} = \begin{bmatrix} cu_1 + cv_2 & cu_2 + cv_2 & cu_3 + cv_2 \end{bmatrix}$
- 8. $(c+d)\mathbf{u} = [(c+d)u_1 \quad (c+d)u_2 \quad (c+d)u_3]$ $c\mathbf{u} + d\mathbf{u} = [cu_1 + du_2 \quad cu_2 + du_2 \quad cu_3 + du_2]$
- 9. $c(d\mathbf{u}) = (cd)\mathbf{u}$
- 10. 1u = u

Uniqueness of Zero Vector and Additive Inverse

If V is a vector space, then there exists a unique zero vector $\mathbf{0}$.

Proof. Suppose \mathbf{w} in V with $\mathbf{u} + \mathbf{w} = \mathbf{u} = \mathbf{w} + \mathbf{u}$ for all \mathbf{u} in V. Thus, if $\mathbf{u} = \mathbf{0}$, then we have $\mathbf{0} + \mathbf{w} = \mathbf{0}$, and so $\mathbf{w} = \mathbf{0}$.

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If V is a vector space, then for each \mathbf{u} in V there exists a unique additive inverse $-\mathbf{u}$.

Proof. Suppose for \mathbf{u} in V, $\mathbf{u} + \mathbf{w} = \mathbf{0} = \mathbf{u} + \mathbf{z}$.

Add \mathbf{z} to both sides of $\mathbf{u} + \mathbf{w} = \mathbf{0}$. $\Longrightarrow \mathbf{w} = \mathbf{z}$.

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- 1. $\mathbf{u} + \mathbf{v}$ is in \mathbb{R}^3 .
- 2. u + v = v + u
- 3. (u + v) + w = v + (u + w)
- 4. $\mathbf{0} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$
- $5. -\mathbf{u} = \begin{bmatrix} -u_1 \\ -u_2 \\ -u_3 \end{bmatrix}$

- 6. $c\mathbf{u}$ is in \mathbb{R}^3 .
- 7. $c(\mathbf{u} + \mathbf{v}) = \begin{bmatrix} -c(u_1 + v_1) & -c(u_2 + v_2) & -c(u_3 + v_3) \end{bmatrix}$ $c\mathbf{u} + c\mathbf{v} = \begin{bmatrix} -cu_1 - cv_1 & -cu_2 - cv_2 & -cu_3 - cv_3 \end{bmatrix}$
- 8. $(c+d)\mathbf{u} = \begin{bmatrix} -(c+d)u_1 & -(c+d)u_2 & -(c+d)u_3 \end{bmatrix}$ $c\mathbf{u} + d\mathbf{u} = \begin{bmatrix} -cu_1 - du_1 & -cu_2 - du_2 & -cu_3 - du_3 \end{bmatrix}$
- 9. $c(d\mathbf{u}) \neq (cd)\mathbf{u}$
- 10. Multiplicative identity fails since $1\mathbf{u} \neq \mathbf{u}$.

 $V = 3 \times 3$ matrices with usual operations.

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Let A, B, and C denote 3×3 matrices and c and d scalars.

1.
$$A + B$$
 is a 3×3 matrix.

2.
$$A + B = B + A$$

3.
$$(A + B) + C = A + (B + C)$$

$$4. \ \mathbf{0} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

5.
$$-A = \begin{bmatrix} -a_{11} & -a_{12} & -a_{13} \\ -a_{21} & -a_{22} & -a_{23} \\ -a_{31} & -a_{32} & -a_{33} \end{bmatrix}$$

6.
$$cA$$
 is a 3×3 matrix.

7.
$$c(A + B) = cA + cB$$

$$8. (c+d)A = cA + dA$$

9.
$$(cd)A = c(dA)$$

10.
$$1A = A$$

V is all 3×3 matrices with determinant 1.

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V is all continuous functions $f: \mathbb{R} \to \mathbb{R}$ with usual scalar multiplication and f(x) + g(x) = f(g(x)).

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No!

Addition is not commutative: $\sin(x^2) \neq (\sin x)^2$.

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$$\begin{bmatrix} a_{11} & a_{12} \\ 0 & a_{22} \end{bmatrix} + \begin{bmatrix} b_{11} & 0 \\ b_{21} & b_{22} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & a_{12} \\ b_{21} & a_{22} + b_{22} \end{bmatrix}$$

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Subspaces

Definition

A subspace of a vector space V is a subset H of V such that H along with the addition and scalar multiplication of V forms a vector space.

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A subspace of a vector space V is a subset H of V such that H along with the addition and scalar multiplication of V forms a vector space.

Some of the vector space properties are satisfied for H since V is a vector space.

If a subset H of a vector space V has the following three properties, it is a subspace.

- 1. Nonempty. There exists some vector \mathbf{u} in H.
- 2. Closed under vector addition. If \mathbf{u} and \mathbf{v} are both in H, then their sum $\mathbf{u} + \mathbf{v}$ is in H.
- 3. Closed under scalar multiplication. If \mathbf{u} is in H, then for all scalars c, $c\mathbf{u}$ is in H.

Let $V=\mathbb{R}^3$ with usual operations. Consider the subset $H=\left\{\begin{bmatrix}x\\y\\0\end{bmatrix}:x,y\in\mathbb{R}\right\}$.

Theorem

Let V be a vector space. For any vector \mathbf{u} in V, $0\mathbf{u} = \mathbf{0}$.

Thus, nonempty plus closure of scalar mult implies that the zero vector is in a subspace.

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Proof. Note that $0\mathbf{u} = (0+0)\mathbf{u} = 0\mathbf{u} + 0\mathbf{u}$. Subtracting $0\mathbf{u}$ from both sides, we have $\mathbf{0} = 0\mathbf{u}$.

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Proof. Note that $\mathbf{0} = 0\mathbf{u} = (1-1)\mathbf{u} = 1\mathbf{u} + (-1)\mathbf{u} = \mathbf{u} + (-1)\mathbf{u}$.

Since the additive inverse is unique, $(-1)\mathbf{u} = -\mathbf{u}$.

- 1. Nonempty.
- 2. Closed under addition.
- 3. Closed under scalar mult.

Let $V = \mathbb{R}^4$ with usual operations.

It.
$$H = \left\{ \begin{bmatrix} 2a + 3b \\ -d \\ 0 \\ 6c + 2a - b \end{bmatrix} : a, b, c, d \text{ in } \mathbb{R} \right\}.$$

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- 1. $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ is in H.
- 2. $\begin{bmatrix} 2a_1 + 3b_1 \\ -d_1 \\ 0 \\ 6c_1 + 2a_1 b_1 \end{bmatrix} + \begin{bmatrix} 2a_2 + 3b_2 \\ -d_2 \\ 0 \\ 6c_2 + 2a_2 b_2 \end{bmatrix} = \begin{bmatrix} 2(a_1 + a_2) + 3(b_1 + b_2) \\ -(d_1 + d_2) \\ 0 \\ 6(c_1 + c_2) + 2(a_1 + a_2) (b_1 + b_2) \end{bmatrix}.$
- 3. $k \begin{bmatrix} 2a+3b \\ -d \\ 0 \\ 6c+2a-b \end{bmatrix} = \begin{bmatrix} 2(ka)+3(kb) \\ -(kd) \\ 0 \\ 6(kc)+2(ka)-(kb) \end{bmatrix}$.

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$$\begin{bmatrix} 2a_1 + 3b_1 \\ -d_1 \\ 0 \\ 6c_1 + 2a_1 - b_1 \end{bmatrix} + \begin{bmatrix} 2a_2 + 3b_2 \\ -d_2 \\ 0 \\ 6c_2 + 2a_2 - b_2 \end{bmatrix} = \begin{bmatrix} 2(a_1 + a_2) + 3(b_1 + b_2) \\ -(d_1 + d_2) \\ 0 \\ 6(c_1 + c_2) + 2(a_1 + a_2) - (b_1 + b_2) \end{bmatrix}.$$

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. So H is a subspace of \mathbb{R}^4 .

- 1. Nonempty.
- 2. Closed under addition.
- 3. Closed under scalar mult.

Let $V = \mathbb{R}^3$ with usual operations.

$$H = \left\{ \begin{bmatrix} 3a+b\\a+5\\2a-5b \end{bmatrix} : a, b \text{ in } \mathbb{R} \right\}.$$

- 1. Nonempty.
- 2. Closed under addition.
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Let $V = \mathbb{R}^3$ with usual operations.

$$H = \left\{ \begin{bmatrix} 3a+b\\a+5\\2a-5b \end{bmatrix} : a, b \text{ in } \mathbb{R} \right\}.$$

- 1. Nonempty: $\begin{bmatrix} 0 \\ 5 \\ 0 \end{bmatrix}$ is in H.
- 2. Consider $\begin{bmatrix} 3(3)+0\\3+5\\2(3)-0 \end{bmatrix} + \begin{bmatrix} 0+1\\0+5\\0-5(1) \end{bmatrix} = \begin{bmatrix} 10\\13\\1 \end{bmatrix} = \begin{bmatrix} 3(3)+1\\3+10\\2(3)-5(1) \end{bmatrix}$ is NOT in H.
- 3. If k=0, then $k\mathbf{h}=\mathbf{0}$ is NOT in H. We need a=-5, which means b=15. This gives 2a-5b=-10-75=-85. We cannot find values for a, b, and c in \mathbb{R} such that $\mathbf{0}$ is in H.

Theorem

Let $\mathbf{v}_1, \dots \mathbf{v}_p$ be vectors from a vector space V. Then Span $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is a subspace of V.

- ▶ We call Span $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ the subspace spanned by $\mathbf{v}_1, \dots, \mathbf{v}_p$.
- ▶ Given any subspace of H of V, a spanning set for H is a set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in H such that $H = \operatorname{Span} \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$.

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Proof.

1. $\mathbf{0} = 0\mathbf{v}_1 + 0\mathbf{v}_2 + \ldots + 0\mathbf{v}_p$ is in Span $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$. So Span $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$ is nonempty.

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Proof.

- 1. $\mathbf{0} = 0\mathbf{v}_1 + 0\mathbf{v}_2 + \ldots + 0\mathbf{v}_p$ is in Span $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$. So Span $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$ is nonempty.
- 2. Let $\mathbf{x} = \mathbf{a_1}\mathbf{v_1} + \mathbf{a_2}\mathbf{v_2} + \ldots + \mathbf{a_p}\mathbf{v_p}$ and $\mathbf{y} = b_1\mathbf{v_1} + b_2\mathbf{v_2} + \ldots + b_p\mathbf{v_p}$. Then we have $\mathbf{x} + \mathbf{y} = (\mathbf{a_1} + b_1)\mathbf{v_1} + (\mathbf{a_2} + b_2)\mathbf{v_2} + \ldots + (\mathbf{a_p} + b_p)\mathbf{v_p}$. So $\mathbf{x} + \mathbf{y}$ is in Span $\{\mathbf{v_1}, \ldots, \mathbf{v_p}\}$.

Theorem

Let $\mathbf{v}_1, \dots \mathbf{v}_p$ be vectors from a vector space V. Then Span $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is a subspace of V.

- ▶ We call Span $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$ the subspace spanned by $\mathbf{v}_1, \dots, \mathbf{v}_p$.
- ▶ Given any subspace of H of V, a spanning set for H is a set $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ in H such that $H = \operatorname{Span} \{\mathbf{v}_1, \dots, \mathbf{v}_p\}$.

Proof.

- 1. $\mathbf{0} = 0\mathbf{v}_1 + 0\mathbf{v}_2 + \ldots + 0\mathbf{v}_p$ is in Span $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$. So Span $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$ is nonempty.
- 2. Let $\mathbf{x} = \mathbf{a_1}\mathbf{v_1} + \mathbf{a_2}\mathbf{v_2} + \ldots + \mathbf{a_p}\mathbf{v_p}$ and $\mathbf{y} = b_1\mathbf{v_1} + b_2\mathbf{v_2} + \ldots + b_p\mathbf{v_p}$. Then we have $\mathbf{x} + \mathbf{y} = (\mathbf{a_1} + b_1)\mathbf{v_1} + (\mathbf{a_2} + b_2)\mathbf{v_2} + \ldots + (\mathbf{a_p} + b_p)\mathbf{v_p}$. So $\mathbf{x} + \mathbf{y}$ is in Span $\{\mathbf{v_1}, \ldots, \mathbf{v_p}\}$.
- 3. Let $\mathbf{x} = \mathbf{a_1}\mathbf{v_1} + \mathbf{a_2}\mathbf{v_2} + \ldots + \mathbf{a_p}\mathbf{v_p}$. Then for a scalar c, we have $c\mathbf{x} = (c\mathbf{a_1})\mathbf{v_1} + (c\mathbf{a_2})\mathbf{v_2} + \ldots + (c\mathbf{a_p})\mathbf{v_p}$. So $c\mathbf{x}$ is in Span $\{\mathbf{v_1}, \ldots, \mathbf{v_p}\}$.

- 1. Nonempty.
- 2. Closed under addition.
- 3. Closed under scalar mult.

Let $V = \mathbb{R}^4$ with usual operations.

It.
$$H = \left\{ \begin{bmatrix} 2a + 3b \\ -d \\ 0 \\ 6c + 2a - b \end{bmatrix} : a, b, c, d \text{ in } \mathbb{R} \right\}.$$

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Notice that
$$\begin{bmatrix} 2a+3b \\ -d \\ 0 \\ 6c+2a-b \end{bmatrix} = a \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix} + b \begin{bmatrix} 3 \\ 0 \\ 0 \\ -1 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 0 \\ 6 \end{bmatrix} + d \begin{bmatrix} 0 \\ -1 \\ 0 \\ 0 \end{bmatrix}.$$
 Thus we have:

$$H = \operatorname{Span} \left\{ \begin{bmatrix} 2 \\ 0 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 6 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \\ 0 \end{bmatrix} \right\}. \quad \text{Thus, } H \text{ is a subspace of } \mathbb{R}^4.$$

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Let $V = Mat_{2\times 2}$ with the usual operations.

$$H = \left\{ \begin{bmatrix} a & c \\ c & b \end{bmatrix} : a, b, c \in \mathbb{R} \right\}$$

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YES!
$$H = \operatorname{Span} \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

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Let $V = Mat_{3\times3}$ with the usual operations.

$$H = \left\{ \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} : a, b, c \in \mathbb{R} \text{ with } a + b + c = 0 \right\}$$

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$$YES! \ H = Span \left\{ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \right\}$$

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Let $V = \mathbb{P}$ (all polynomials) with usual operations. H is the set of polynomials of degree at most 2.

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H is the set of polynomials with integer coefficients.

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Let V be all continuous functions with the usual operations. H is the set of all differentiable functions.

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YES! But cannot be described as a finite span.