Homogeneous Systems of Linear Equations

Linear Algebra

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Homogeneous Solutions

A system of equations is homogeneous if it can be written in the form $A\mathbf{x} = \mathbf{0}$.

$$x_1 + x_2 + x_3 = 7$$

 $x_1 - x_2 + 2x_3 = 7$
 $5x_1 + x_2 + x_3 = 11$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 2 \\ 5 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 7 \\ 7 \\ 11 \end{bmatrix}$$

NOT a homogeneous system.

$$x_1 + x_2 + x_3 = 0$$

$$x_1 - x_2 + 2x_3 = 0$$

$$5x_1 + x_2 + x_3 = 0$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & 2 \\ 5 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

YES, this is a homogeneous system.

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Every homogeneous system has a trivial solution $\mathbf{x} = \mathbf{0}$, and so is consistent.

Does the homogeneous system have a nontrivial solution? ie, infinite number of solutions?

Existence of Nontrivial Solutions

Recall that if the system $A\mathbf{x} = \mathbf{b}$ is consistent, then it has:

- ► A unique solution if, when forming the RREF of A, there is a pivot position in every column (ie, all variables are basic).
- An infinite number of solutions if there is a column of A without a pivot position (ie, there is at least one free variable).

Theorem

The homogeneous equation $A\mathbf{x} = \mathbf{0}$ has a nontrivial solution if and only if the solution set has at least one free variable.

Example

Find the solution set to the homogeneous system

$$x_{1} + 3x_{2} + 7x_{3} = 0$$

$$x_{2} + 3x_{3} = 0$$

$$-2x_{1} - 4x_{2} - 8x_{3} = 0$$

$$\begin{bmatrix} 1 & 3 & 7 & 0 \\ 0 & 1 & 3 & 0 \\ -2 & -4 & -8 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 7 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 2 & 6 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 7 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Notice x_3 is a free variable, and the solution set can therefore be given by

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_3 \\ -3x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} = x_3 \mathbf{v} , \text{ where } \mathbf{v} = \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix}.$$

Example

Find the solution set to the homogeneous system

$$3x_1 - 2x_2 + x_3 = 0
-6x_1 + 4x_2 - 2x_3 = 0$$

$$\begin{bmatrix} 3 & -2 & 1 & 0 \\ -6 & 4 & -2 & 0 \end{bmatrix} \sim \begin{bmatrix} 3 & -2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & \frac{-2}{3} & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Both x_2 and x_3 are free variables, and the solution set can therefore be given by

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{2}{3}x_2 - \frac{1}{3}x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} \frac{2}{3} \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix} = x_2 \mathbf{u} + x_3 \mathbf{v}.$$

Nonhomogeneous Linear Systems

Find the solution set to the nonhomogeneous system

$$x_1$$
 + $3x_2$ + $7x_3$ = 4
 x_2 + $3x_3$ = 5
 $-2x_1$ - $4x_2$ - $8x_3$ = 2

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$$\begin{bmatrix} 1 & 3 & 7 & 4 \\ 0 & 1 & 3 & 5 \\ -2 & -4 & -8 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 7 & 4 \\ 0 & 1 & 3 & 5 \\ 0 & 2 & 6 & 10 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & 7 & 4 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 & -11 \\ 0 & 1 & 3 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Notice x_3 is a free variable, and the solution set can therefore be given by

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -11 + 2x_3 \\ 5 - 3x_3 \\ x_3 \end{bmatrix} = \begin{bmatrix} -11 \\ 5 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} = \mathbf{p} + t\mathbf{v} \quad (t \text{ in } \mathbb{R}).$$

Comparing Homogeneous and Nonhomogeneous Solutions

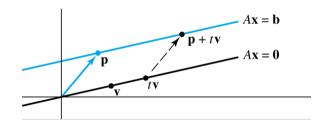
$$x_1$$
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 x_2 + $3x_3$ = 0
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$$x_1 + 3x_2 + 7x_3 = 4$$

 $x_2 + 3x_3 = 5$
 $-2x_1 - 4x_2 - 8x_3 = 2$

$$\mathbf{x} = x_3 \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} = t \mathbf{v} \quad (t \text{ in } \mathbb{R}).$$

$$\mathbf{x} = \begin{bmatrix} -11 \\ 5 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ -3 \\ 1 \end{bmatrix} = \mathbf{p} + t\mathbf{v} \quad (t \text{ in } \mathbb{R}).$$



Suppose $A\mathbf{x} = \mathbf{b}$ is consistent and has a solution $\mathbf{x} = \mathbf{p}$. If \mathbf{v} is any solution to the homogeneous equation $A\mathbf{x} = \mathbf{0}$, then

$$\mathbf{x} = \mathbf{p} + \mathbf{v}$$

is a solution to the nonhomogeneous equation $A\mathbf{x} = \mathbf{b}$.

Proof.

Suppose $A\mathbf{x} = \mathbf{b}$ is consistent and has a solution $\mathbf{x} = \mathbf{p}$. If \mathbf{v} is any solution to the homogeneous equation $A\mathbf{x} = \mathbf{0}$, then

$$\mathbf{x} = \mathbf{p} + \mathbf{v}$$

is a solution to the nonhomogeneous equation $A\mathbf{x} = \mathbf{b}$.

Proof.

We have
$$Ax = A(p + v) = Ap + Av = b + 0 = b$$
.



Suppose $A\mathbf{x} = \mathbf{b}$ is consistent and has a solution $\mathbf{x} = \mathbf{p}$. If \mathbf{v} is **any** solution to the homogeneous equation $A\mathbf{x} = \mathbf{0}$, then

$$x = p + v$$

is a solution to the nonhomogeneous equation Ax = b.

Proof.

We have
$$A\mathbf{x} = A(\mathbf{p} + \mathbf{v}) = A\mathbf{p} + A\mathbf{v} = \mathbf{b} + \mathbf{0} = \mathbf{b}$$
.

Theorem

Every solution **x** of $A\mathbf{x} = \mathbf{b}$ can be written as $\mathbf{x} = \mathbf{p} + \mathbf{v}$ for **some** solution **v** of $A\mathbf{x} = \mathbf{0}$.

Proof.

Suppose $A\mathbf{x} = \mathbf{b}$ is consistent and has a solution $\mathbf{x} = \mathbf{p}$. If \mathbf{v} is **any** solution to the homogeneous equation $A\mathbf{x} = \mathbf{0}$, then

$$x = p + v$$

is a solution to the nonhomogeneous equation Ax = b.

Proof.

We have $A\mathbf{x} = A(\mathbf{p} + \mathbf{v}) = A\mathbf{p} + A\mathbf{v} = \mathbf{b} + \mathbf{0} = \mathbf{b}$.

Theorem

Every solution **x** of $A\mathbf{x} = \mathbf{b}$ can be written as $\mathbf{x} = \mathbf{p} + \mathbf{v}$ for **some** solution **v** of $A\mathbf{x} = \mathbf{0}$.

Proof.

Let **y** be a solution to $A\mathbf{x} = \mathbf{b}$. Let $\mathbf{v} = \mathbf{y} - \mathbf{p}$. Then $A\mathbf{v} = A(\mathbf{y} - \mathbf{p}) = A\mathbf{y} - A\mathbf{p} = \mathbf{b} - \mathbf{b} = \mathbf{0}$. Hence, **v** is a solution to $A\mathbf{x} = \mathbf{0}$.