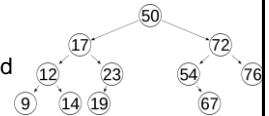


# Data Structures & Algorithms 2

## Topic 4 – Balanced Binary Trees

### Balanced Trees

- We know from our study of Binary Search Trees (BST) that the average search and insertion time is  $O(\log n)$



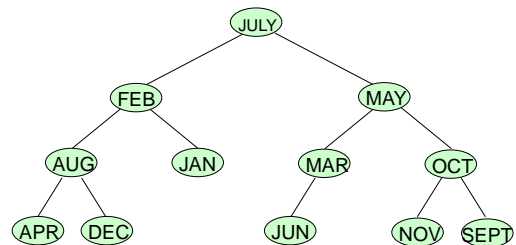
- If there are  $n$  nodes in the binary tree it will take, on average,  $\log_2 n$  comparisons/probes to find a particular node (or find out that it isn't there)

### However...

- However, this is only true if the tree is 'balanced'
  - The tree usually ends up reasonably balanced when the elements are inserted in **random order**
  - But how can we guarantee that this will always be the case?



### Balanced Trees

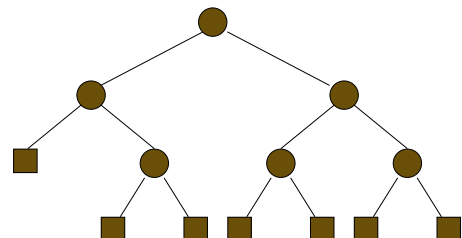


A Balanced Tree for the Months of the Year (alphabetically)

### Binary Tree Terminology

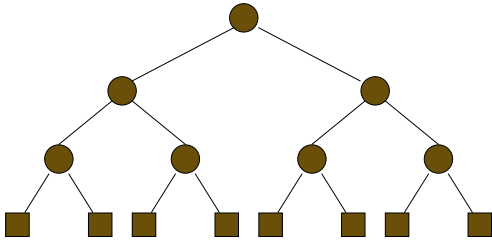
- **Complete Binary Trees (Fat Trees)**
  - the external nodes appear on at most two adjacent levels
- **Perfect Trees**
  - complete trees having all their external nodes on one level
- **Left-complete Trees**
  - the internal nodes on the lowest level are in the leftmost possible position

### Complete Tree



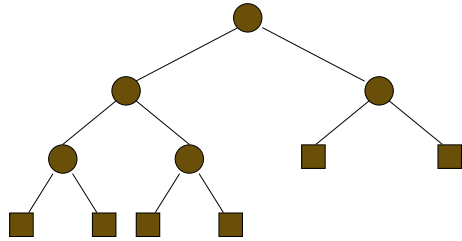
## Perfect Tree

```
graph TD; A(( )) --- B(( )); A --- C(( )); B --- D(( )); B --- E(( )); C --- F(( )); C --- G(( )); D --- H[ ]; D --- I[ ]; E --- J[ ]; E --- K[ ]; F --- L[ ]; F --- M[ ]; G --- N[ ]; G --- O[ ]
```




## Left-Complete Tree

```
graph TD; A(( )) --- B(( )); A --- C(( )); B --- D(( )); B --- E(( )); C --- F[ ]; C --- G[ ]; D --- H[ ]; D --- I[ ]; E --- J[ ]; E --- K[ ]
```



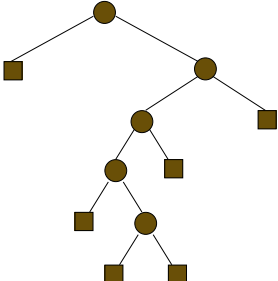
# Skinny Trees

- However, if the elements are inserted in sorted order (e.g. lexicographic order) then the tree degenerates into a skinny tree
- In a skinny tree, every internal node has at most one internal child

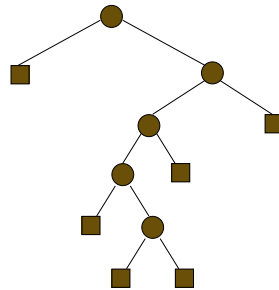


- 

# Skinny Tree



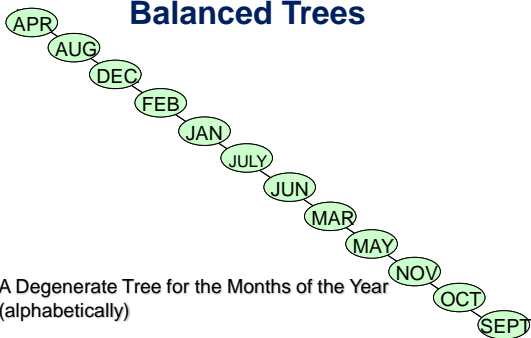
```
graph TD; A(( )) --- B[ ]; A --- C(( )); C --- D(( )); C --- E[ ]; D --- F(( )); D --- G[ ]; F --- H[ ]; F --- I(( )); I --- J[ ]; I --- K[ ]
```



## Balanced Trees


```
graph LR; APR((APR)) --> AUG((AUG)); AUG --> DEC((DEC)); DEC --> FEB((FEB)); FEB --> JAN((JAN)); JAN --> JULY((JULY)); JULY --> JUN((JUN)); JUN --> MAR((MAR)); MAR --> MAY((MAY)); MAY --> NOV((NOV)); NOV --> OCT((OCT)); OCT --> SEPT((SEPT));
```

A Degenerate Tree for the Months of the Year (alphabetically)



# Balanced Trees

- If we are dealing with a dynamic tree nodes are being inserted and deleted over time
  - directory of files
  - index of university students
- We may need to restructure (balance) the tree so that we keep it **fat**

A photograph of a large, mature, rounded tree with dense green foliage, standing on a patch of dry ground. The tree's shape is symmetrical and full, visually representing a balanced tree structure.

-

## AVL Trees

- Adelson-Velskii and Landis in 1962 invented the first balanced binary tree algorithm
- Insertions (and deletions) are made such that the tree starts off and remains **height-balanced**
- The idea is that every node stays balanced with respect to the heights of its subtrees
- The height of one subtree is never allowed to exceed the height of the other by more than 1 level
- If an insertion causes a tree to become unbalanced, a **rotation** is carried out to fix it

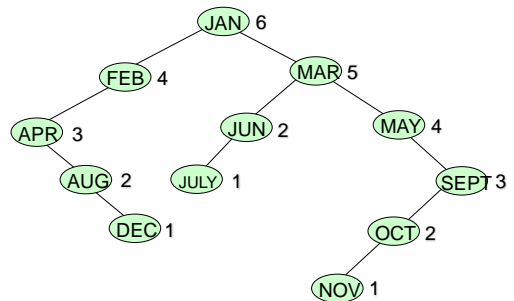
## Tree Height

- The **height** of  $T$  is defined recursively as  
0 if  $T$  is empty and  
 $1 + \max(\text{height}(T_1), \text{height}(T_2))$  otherwise,  
where  $T_1$  and  $T_2$  are the subtrees of the root.
- The height of a tree is the length of a longest chain of descendents

## Tree Height

- The height of a node is the height of the subtree rooted at that node
- Height numbering
  - Number all bottom nodes 1
  - Number each internal node to be one more than the maximum of the numbers of its children
  - Then the number of the root is the height of  $T$

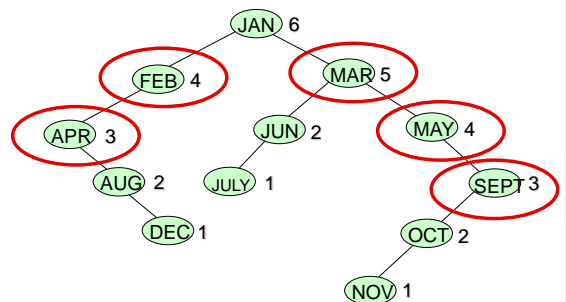
## Tree Heights



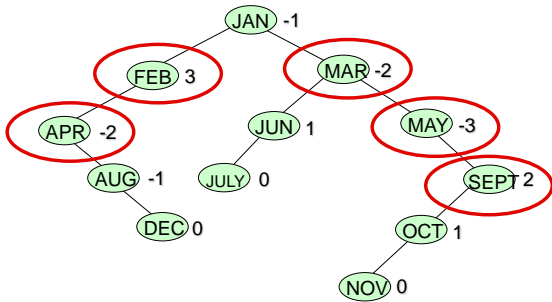
## AVL height balancing

- An empty tree is always height-balanced
- If  $T$  is a non-empty binary tree with left and right sub-trees  $T_1$  and  $T_2$ , then
- $T$  is height-balanced iff (if and only if)
  - $T_1$  and  $T_2$  are height-balanced, and
  - $|\text{height}(T_1) - \text{height}(T_2)| \leq 1$
- The balance factor is the difference between the heights of a node's left and right subtrees:  $\text{height}(T_1) - \text{height}(T_2)$
- For balanced AVL trees, balance factors can only be **-1, 1** or **0**

## AVL height violations



## Balance factors

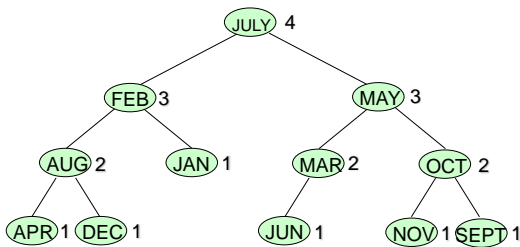


## AVL algorithm

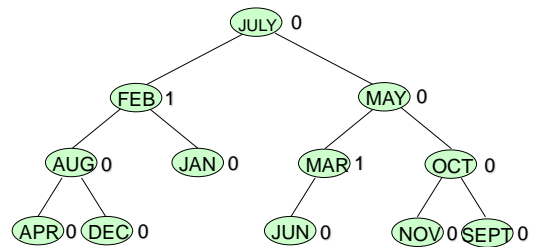
- Every time a new node is inserted check if all nodes are still height balanced
  - Check that the absolute difference in heights between a node's left and right subtrees is no greater than 1
- If any part of the tree is not height balanced, adjust the structure of the tree so that it becomes height balanced again



## AVL Heights

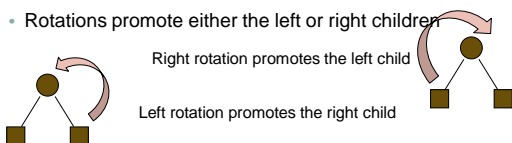


## AVL Balance Factors

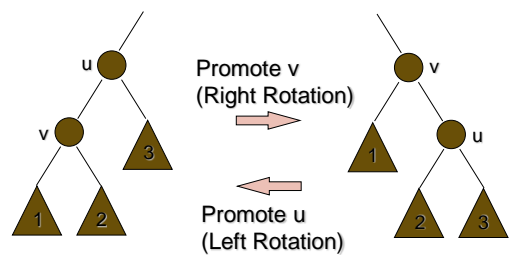


## Rotations

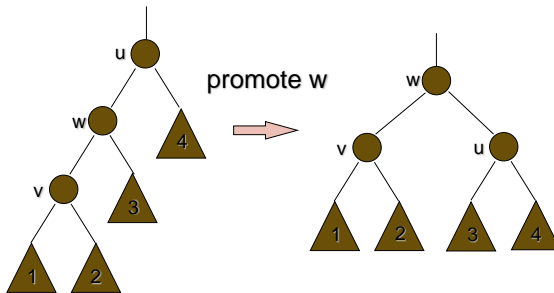
- In order to keep the tree balanced following an insertion we use rotations
- A rotation is when a node is promoted to a higher level by twisting the tree at a particular point in either the **left** or **right** direction
- Rotations promote either the left or right children



## Rotations

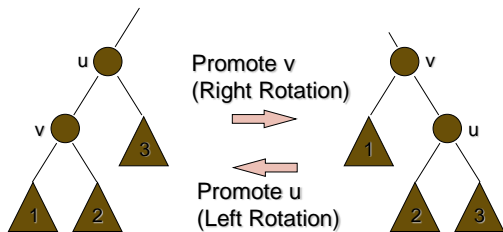


## Rotation with child nodes



## Binary search preserved

- We can carry out as many rotations as we want because rotations always preserve the binary search feature of the tree
  - Smaller values on the left
  - Bigger values on the right



$\text{keys}(1) < \text{key}(v) < \text{key}(u)$   
 $\text{key}(v) < \text{keys}(2) < \text{key}(u)$   
 $\text{key}(u) < \text{keys}(3)$

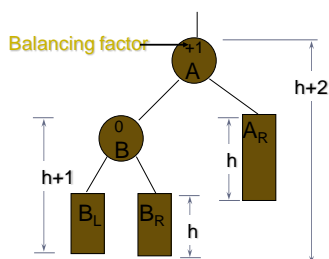
$\text{keys}(1) < \text{key}(v)$   
 $\text{key}(v) < \text{keys}(2) < \text{key}(u)$   
 $\text{key}(v) < \text{key}(u) < \text{keys}(3)$

## Balancing AVL Trees

- Let's refer to the inserted node as **X**
  - Let's refer to the nearest ancestor having balance factor +2 or -2 as **A**
- If X is inserted in the left subtree of the left subtree of A promote A's left child once (*LL rebalancing*)
  - If X is inserted in the right subtree of the left subtree of A promote A's right-left grandchild twice (*RL rebalancing*)
  - If X is inserted in the right subtree of the right subtree of A promote A's right child once (*RR rebalancing*)
  - If X is inserted in the left subtree of the right subtree of A promote A's left-right grandchild twice (*LR rebalancing*)

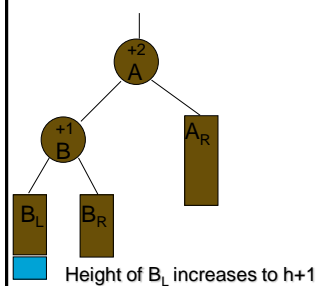
## AVL Trees

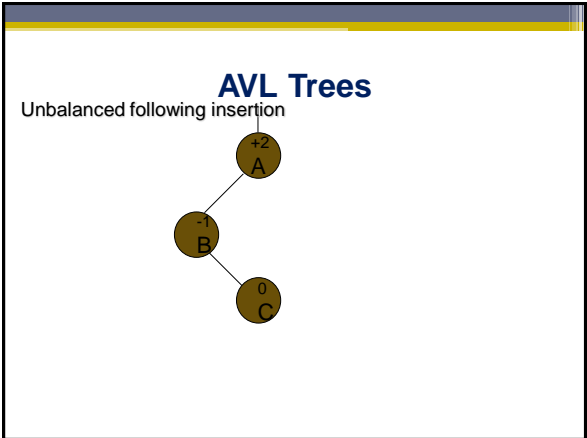
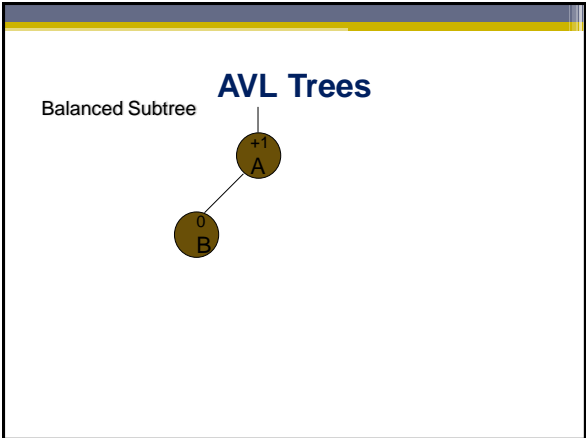
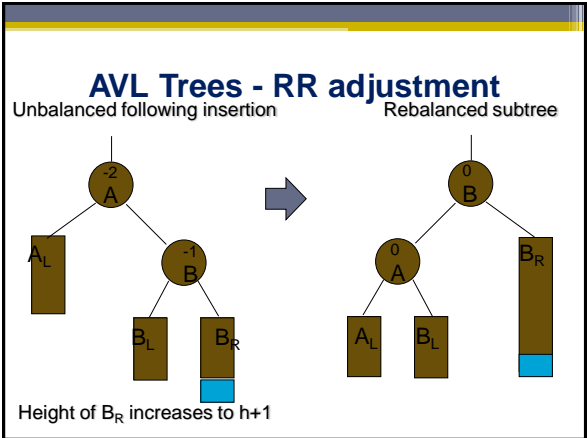
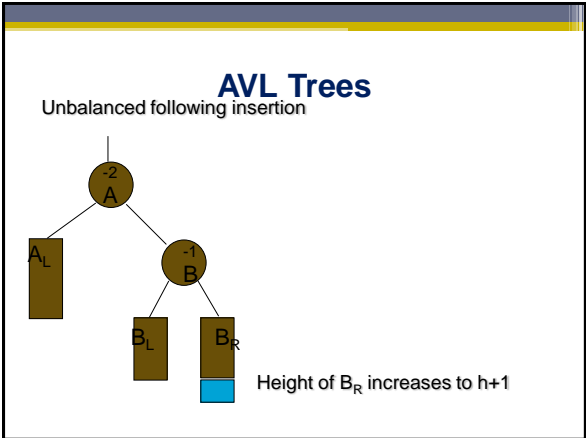
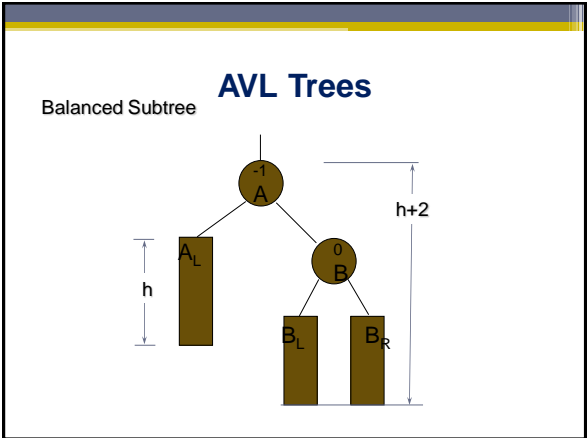
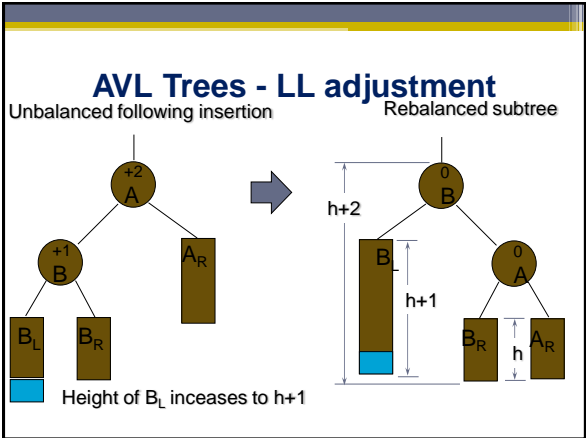
Balanced Subtree



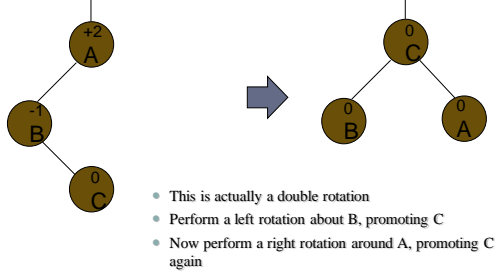
## AVL Trees

Unbalanced following LL insertion

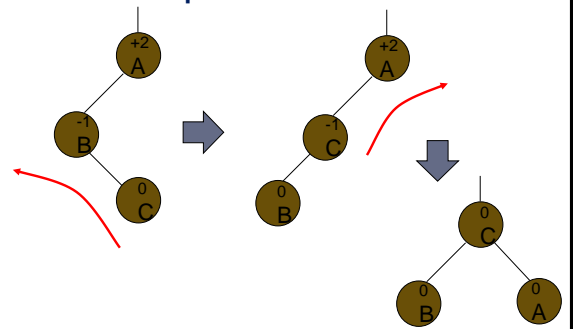




## AVL Trees - LR adjustment

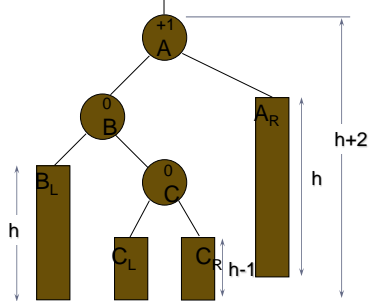


## LR and RL adjustments involve two promotions



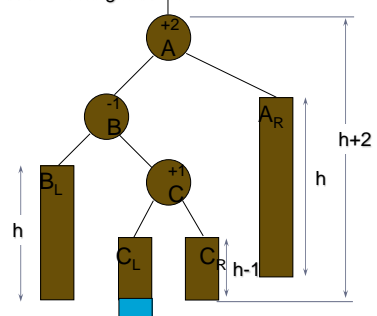
## AVL Trees

Balanced Subtree

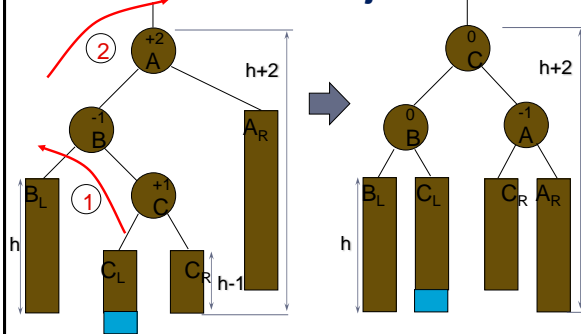


## AVL Trees

Unbalanced following insertion

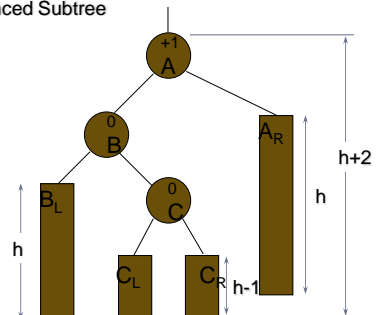


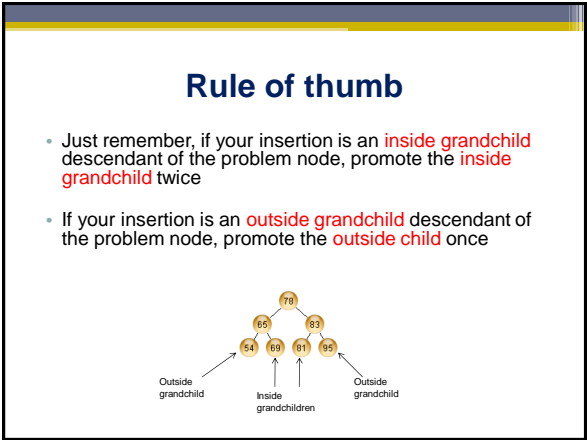
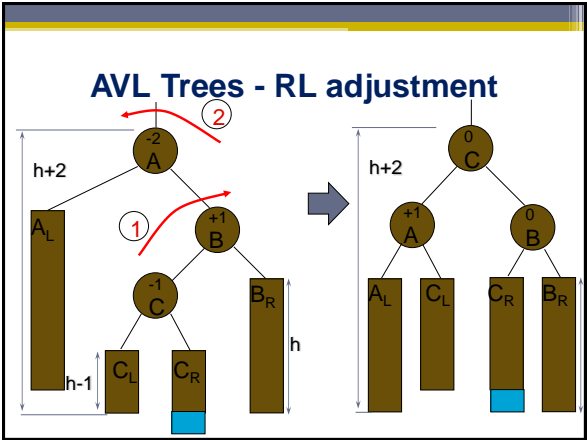
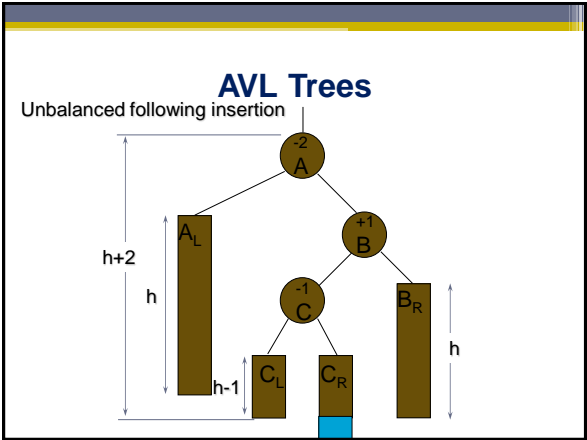
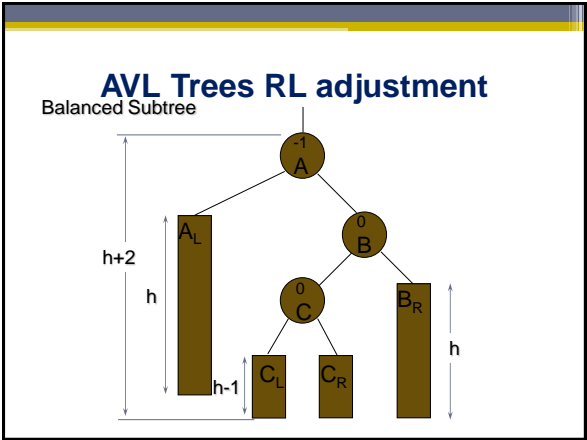
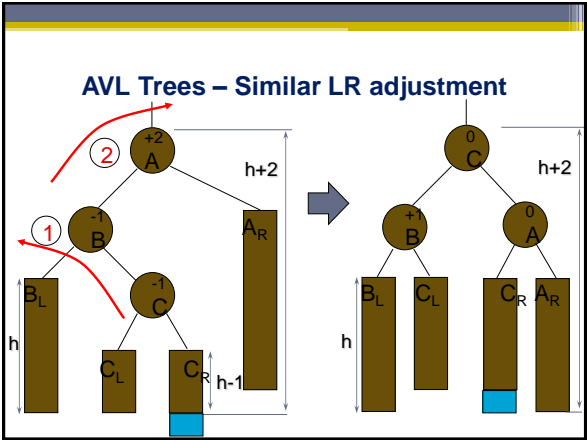
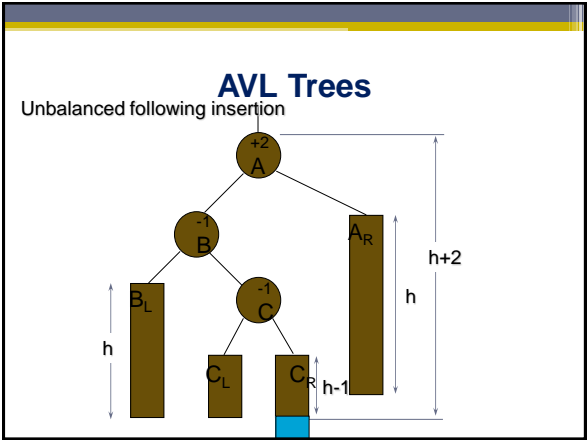
## AVL Trees - LR adjustment



## AVL Trees

Balanced Subtree







# AVL Tree Algorithm

- When a node is inserted you check back up the path of insertion looking for nodes with a BF of  $\pm 2$
- End the search when you reach a node with a BF of either 0 or a BF of  $\pm 2$
- If you reach a node with a BF of 0, no adjustments are needed
  - None of the BFs above this will be affected because the height of that node is the same as before
- If you reach a node with a BF of  $\pm 2$ , rebalance that subtree
  - After rebalancing, BF at A (the problem node) will end up as 0
  - No further adjustment needed

New Identifier	After Insertion	After Rebalancing
----------------	-----------------	-------------------

MARCH		
-------	---	--

New Identifier	After Insertion	After Rebalancing
----------------	-----------------	-------------------

MARCH	 BF = 0	NO REBALANCING NEEDED
-------	--	-----------------------


New Identifier	After Insertion	After Rebalancing
----------------	-----------------	-------------------

MARCH	 BF = 0	NO REBALANCING NEEDED
-------	---	-----------------------

MAY		
-----	--	--

New Identifier	After Insertion	After Rebalancing
----------------	-----------------	-------------------


MARCH	 BF = 0	NO REBALANCING NEEDED
-------	--	-----------------------

MAY	 BF = -1	NO REBALANCING NEEDED
-----	---	-----------------------


	 BF = 0	
--	--	--

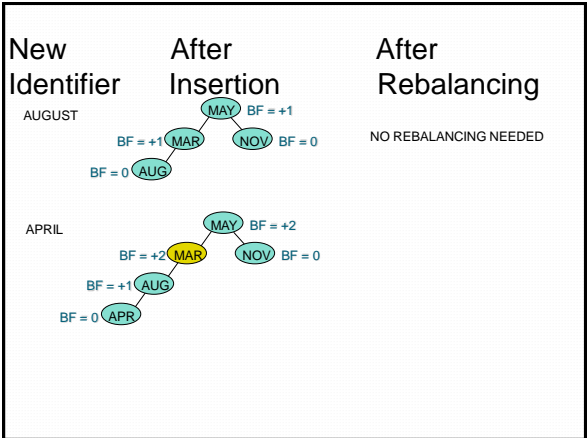
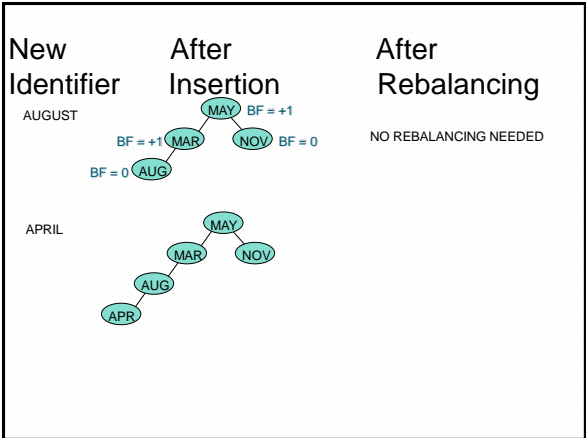
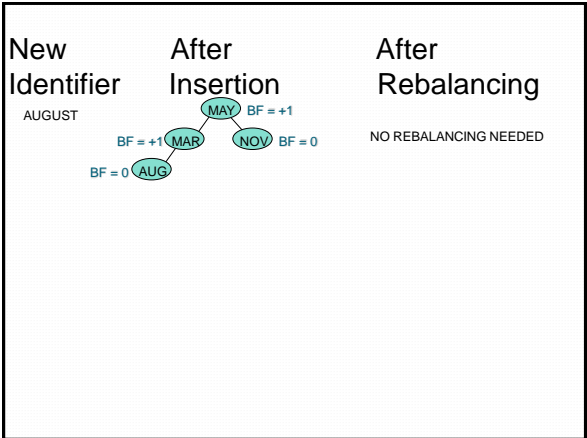
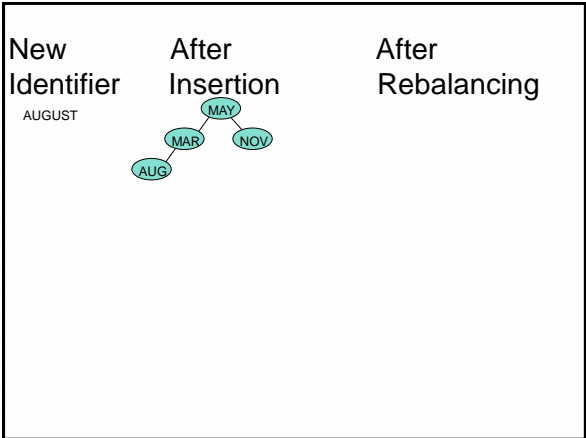
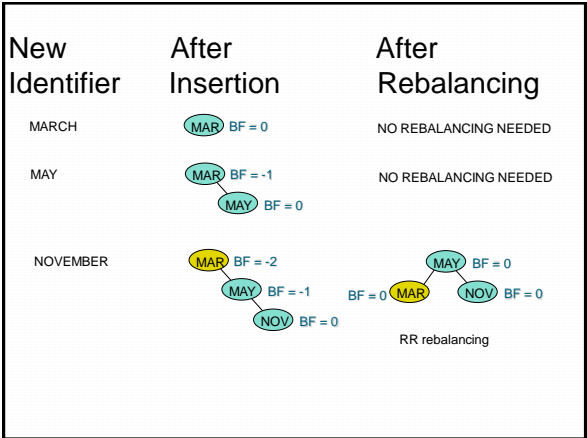
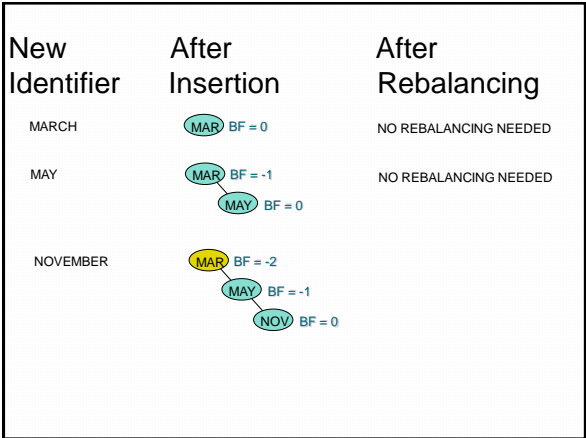
New Identifier	After Insertion	After Rebalancing
----------------	-----------------	-------------------

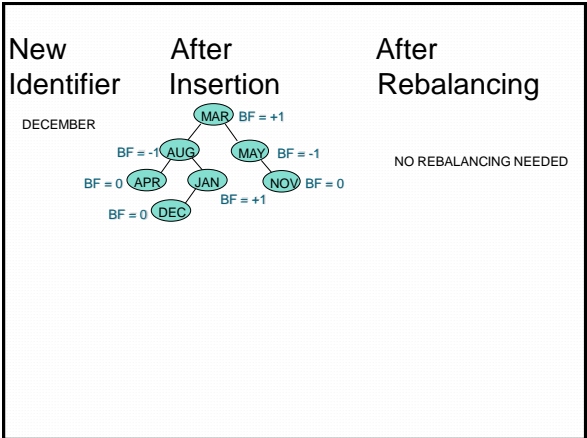
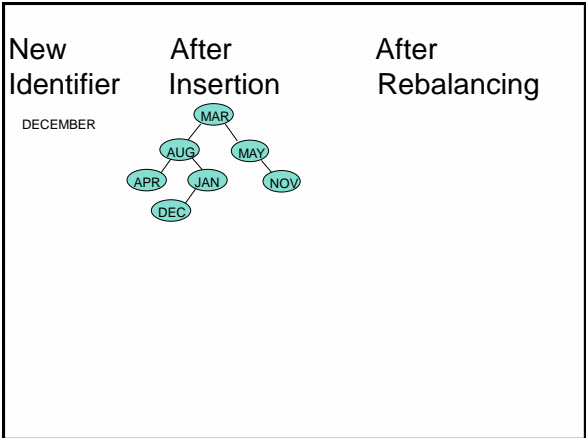
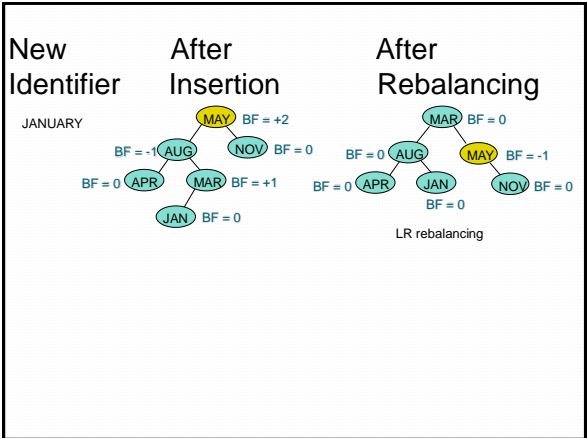
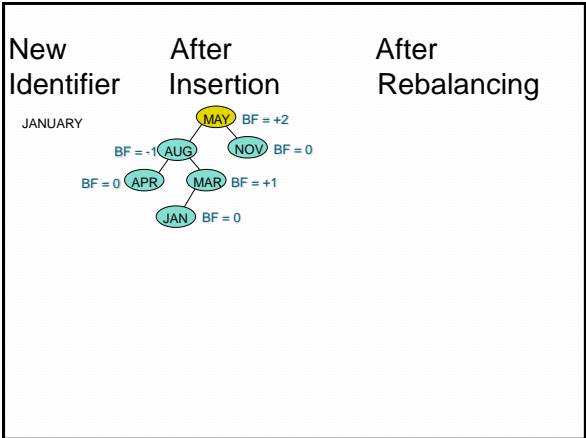
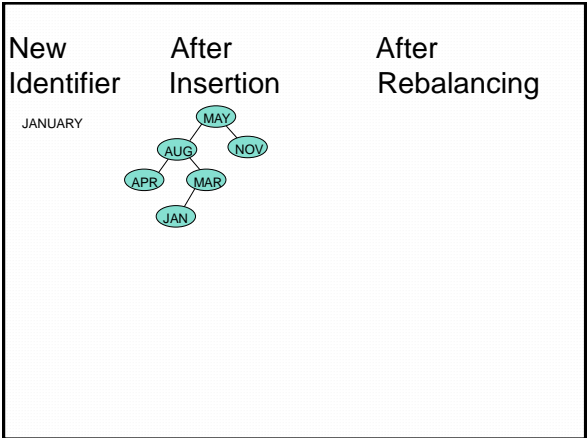
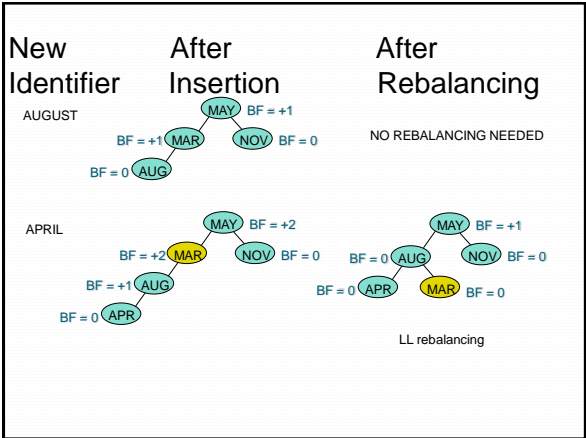
MARCH	 BF = 0	NO REBALANCING NEEDED
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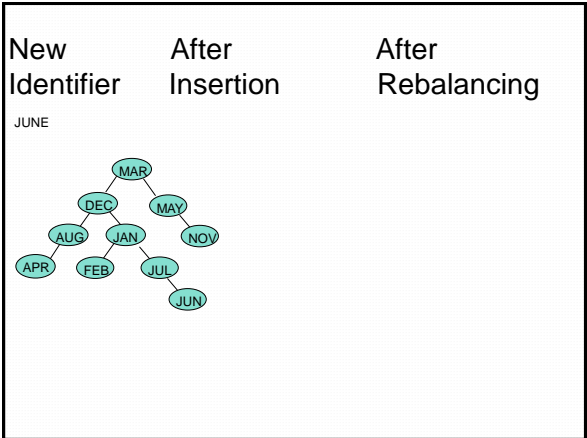
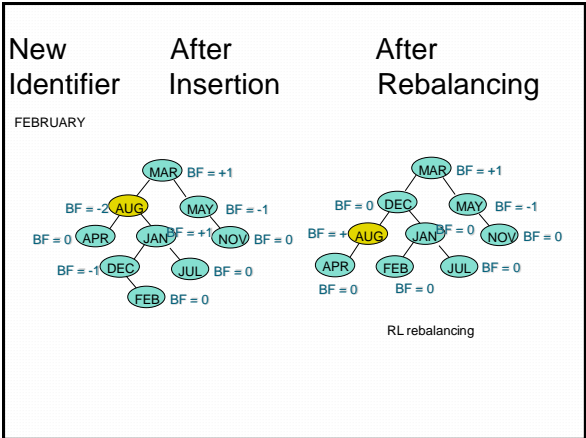
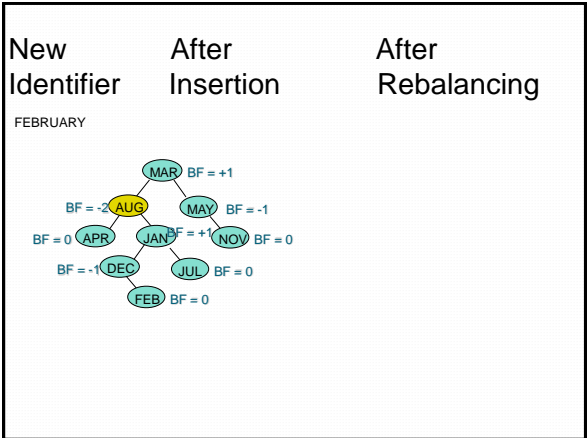
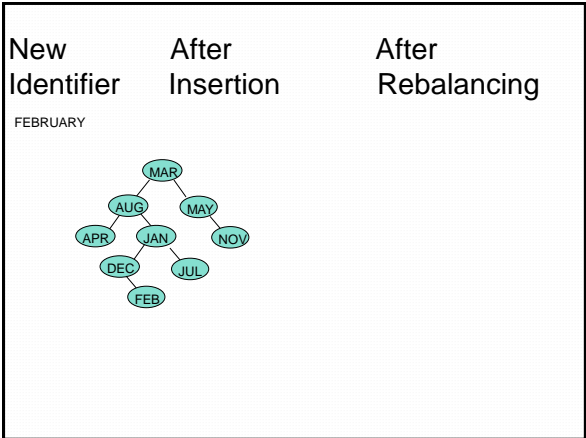
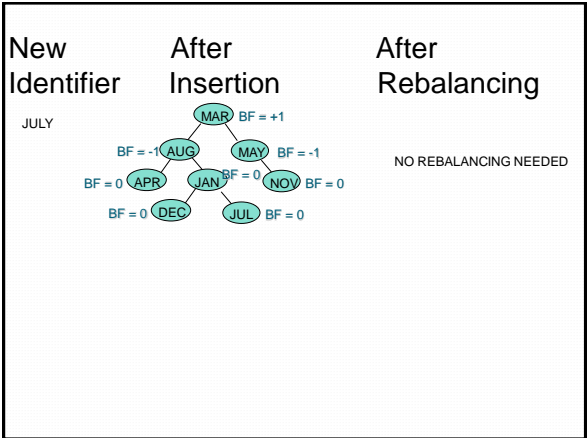
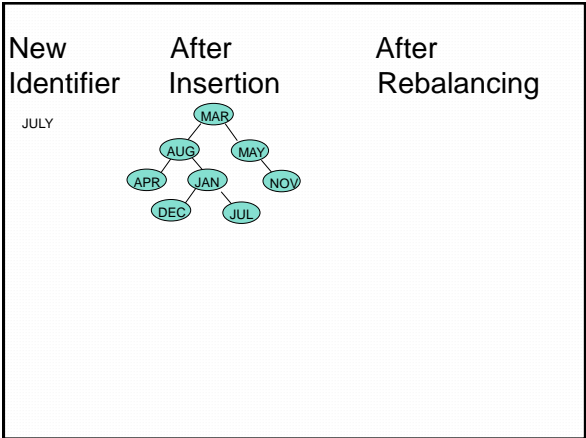
MAY	 BF = -1	NO REBALANCING NEEDED
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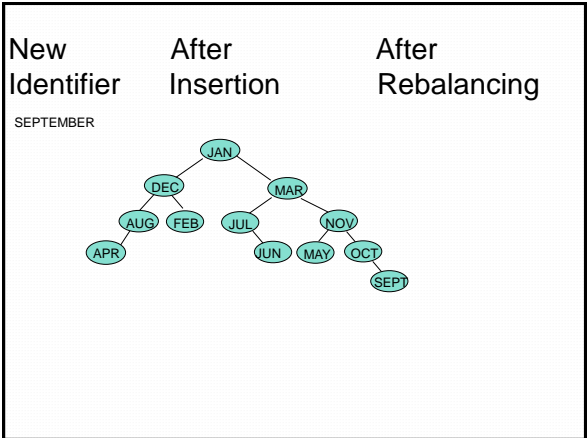
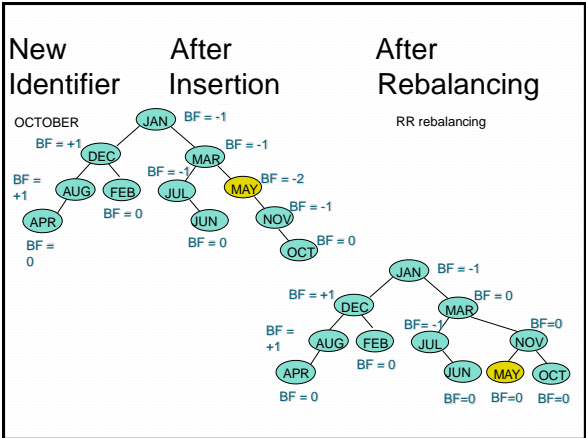
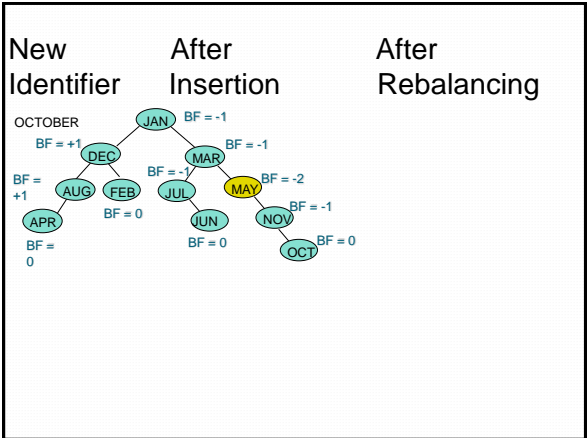
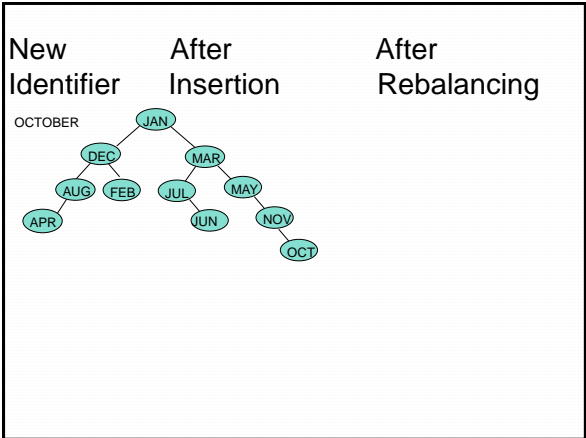
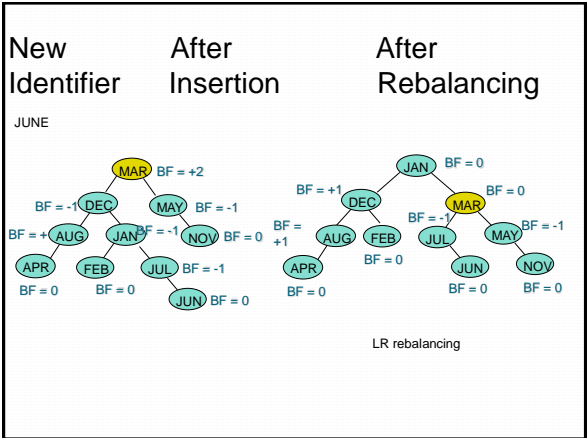
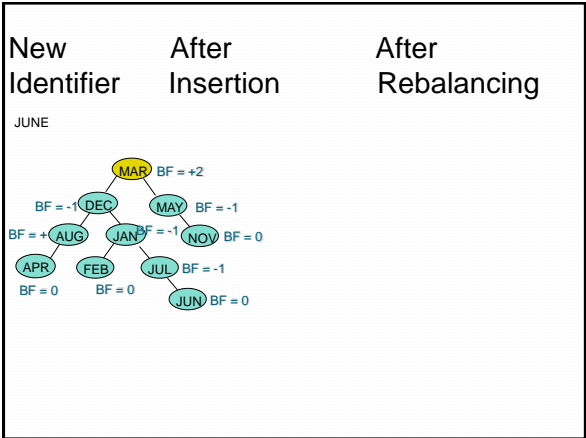
	 BF = 0	
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NOVEMBER		
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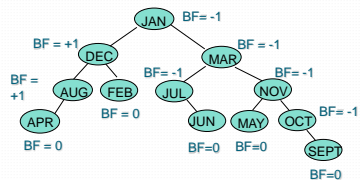
New Identifier

After Insertion

After Rebalancing

SEPTEMBER

NO REBALANCING NEEDED



## Red-Black Trees



- Red-black trees are less rigidly balanced than AVL
- Although they still guarantee a search time of  $O(\log N)$ , they are somewhat skinnier than AVL trees
  - max height  $2 \cdot \log N$  as opposed to  $1.4 \cdot \log N$
- The original structure was invented in 1972 by Rudolph Bayer
- Keeping a red-black tree balanced requires only an average of one rotation per insertion and deletion
  - AVL requires  $O(\log N)$  rotations per deletion
- A small disadvantage is that each node must store its colour

## Red-Black Trees

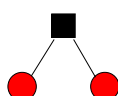
- A red-black tree is a binary tree whose nodes can be coloured either red or black to satisfy the following conditions:
  - ♦ Black condition: Each root-to-leaf path contains exactly the same number of black nodes (black height)
  - ♦ Red condition: You can't have two red nodes together
  - ♦ The root is always black
  - ♦ Inserted nodes are always red

## Red-Black Trees



Red-black tree (root must be black)

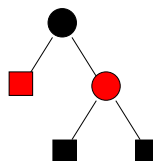
## Red-Black Trees



Red-black tree

Root is black  
Black height is maintained

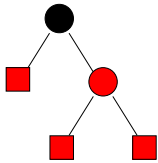
## Red-Black Trees



Rule violation!

Black height not preserved

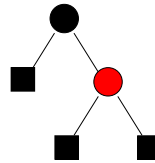
## Red-Black Trees



Rule violation!

Two red nodes together

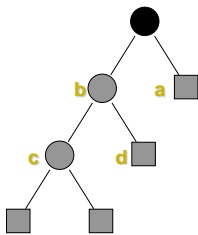
## Red-Black Trees



Valid Red-Black Tree

Black height equal  
Root is black  
Red nodes have black children

## Red-Black Trees



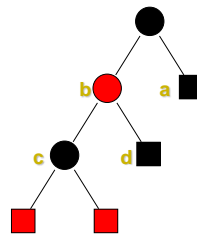
To satisfy black condition →

If b is black then black height cannot be preserved

Node b is red and node c and d are therefore black

a has to be black to preserve black height

## Red-Black Trees

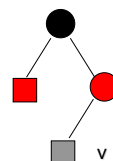


Solution

## Red-Black Trees

- For all  $n \geq 1$ , every red-black tree of size  $n$  has height  $O(\log_2 n)$
- Thus, red-black trees provide a guaranteed worst-case search time of  $O(\log_2 n)$
- However a best case path could involve all black nodes
- A worst case path could involve a red-black red-black path which would be at worst twice as long as the best case scenario
- Worst possible search time is  $2 \cdot \log_2 n$

## Red-Black Trees



insertion at v

If new node is red, is the tree red-black?  
If the new node is black, is the tree red-black?  
v cannot be either, therefore we need to change the structure

## Red-Black Trees

- Just as with ordinary trees, we perform the insertion by
  - first searching the tree until an external node is reached (if the key is not already in the tree)
  - then inserting the new (internal) node
- Insertions and deletions can cause red and black conditions to be violated
- Trees then have to be restructured
  - We can use rotations
  - We can also flip colours

red  $\leftrightarrow$  black

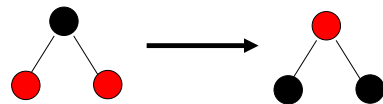
## Terminology

- X is the node that has caused a rule violation
- P is the parent of X
- G is the grandparent of X (parent of P)

## Complete Algorithm

- To insert a node you go left and right, searching for the place where the node should go
- On the way down the tree perform a colour flip whenever you find a black node with two red children
- This flip can cause a red-red conflict (the child node is denoted X)
- Conflict is fixed by a single or double rotation, depending on whether X is an outside or inside grandchild of G
- When you get to the insertion point insert your new node

## Colour Flips all the way down

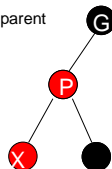


Make your way down the tree from the root

If you encounter a black node with two red children flip the colours

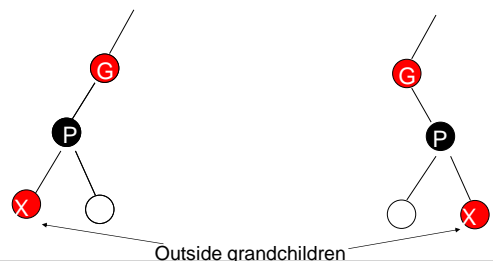
## Problems

- A colour flip can't cause the black height rule to be violated
  - There are the same number of black nodes on any path
- The red rule might be violated because of a red-red conflict
  - One of the nodes you turned red already has a red parent
  - Let this node you turned red be called X
  - It's parent is P and grandparent is G
- Use rotations and colour flips to solve the problem



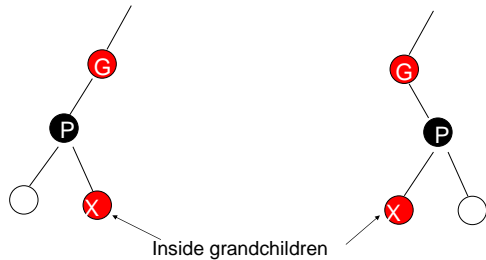
## Outside Grandchildren

- We need some new terminology





## Inside Grandchildren

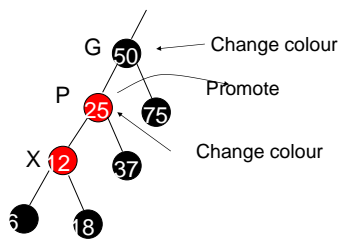


## Eliminating red-red violations

- If X is an outside grandchild:
  - Switch the colour of X's grandparent G
  - Switch the colour of X's parent P
  - Promote the parent P by right rotating around the grandparent G
- If X is an inside grandchild:
  - Change the colour of the grandparent G
  - Change the colour of X
  - Promote X by rotating about P
  - Finally, promote X again by rotating about G

## Outside Grandchild

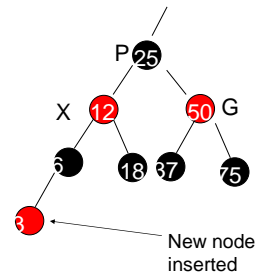
- Let X be the child in the red-red conflict



This tree has been created by inserting 25, 75, 12, 37, 6, 18

Now we want to insert 3

## Solution

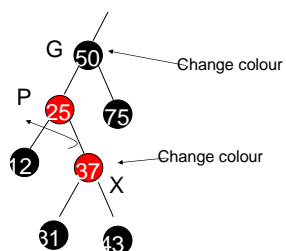


## Inside Grandchild

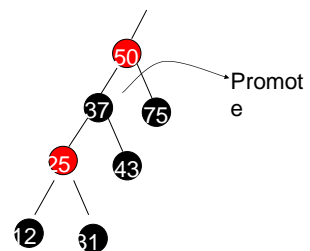
- Again, let X be the child in the red-red conflict

This tree has been created by inserting 50, 25, 75, 12, 37, 31, 43

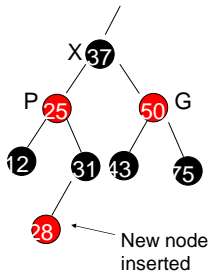
Now we want to insert 28



## Second promotion



## Insertion

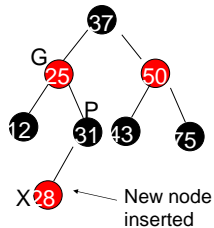


## Insertion

- When the colour flips all the way down have been completed we are ready to insert
- A newly inserted node is always red
- There are 3 possibilities:
  1. P is black (no problem)
  2. P is red and X is an outside grandchild (red-red violation)
  3. P is red and X is an inside grandchild (red-red violation)
- Solve the red-red violation in the same way

### 1. P is black

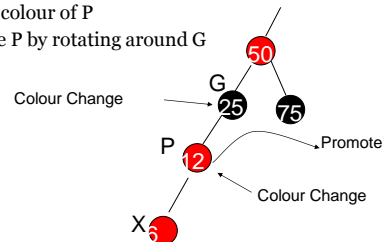
- The newly inserted node is red
- If P is black then there is no problem
- Just insert



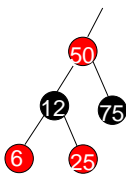
### 2. P is red, X is outside grandchild

- Change colour of G
- Change colour of P
- Promote P by rotating around G

This tree was created by inserting 50, 25, 75, 12 and finally 6



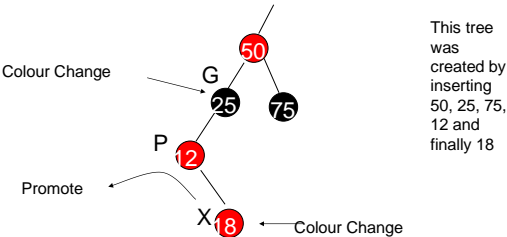
## Final Tree with Insertion



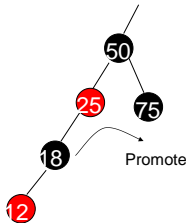
### 3. P is red, X is inside grandchild

- 2 rotations, 2 colour changes
- Flip the colour of the grandparent G
- Flip the colour of X
- Promote X by rotating around P
- Promote X again by rotating around its new parent (its original grandparent G)

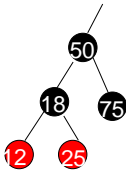
3. P is red, X is inside grandchild



Second Promotion



Finally



An example

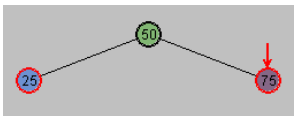
- As an example of a red black tree construction consider the following
- Insert the following integers into a red black tree structure:

50 25 75 12 37 31 28

Insert 50



Insert 25 and 75

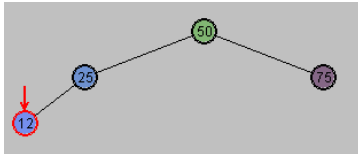


A black node with two red children...

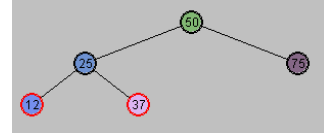
## Insert 12 - First problem

As we go down we find a black node with two red children – flip their colours

Root always stays black



## Insert 37

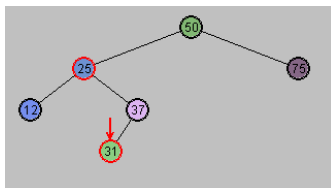


Again here is a situation where a black node has two red children

The colours will be flipped at the next insertion

## Insert 31

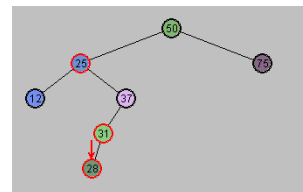
We flip the colours of 25, 12 and 37 on the way down and then insert 31



## Insert 28

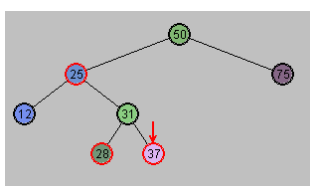
We now have our first double red situation

Change the colour of 31 and 37 and promote 31



## Insert 37

Just keep following the steps!



## Deletions

- Deletion for an ordinary binary tree is complicated enough - deletion for a red-black tree is even more complicated!
- One way to avoid the problem is to use a **boolean** value to mark a node as deleted without actually deleting it
- Disadvantage is that the tree starts to fill up with deleted nodes, increasing search times
- This can be acceptable if deletions are uncommon

## Efficiency

- Like any binary search tree, red black trees allows for searching, insertion and deletion in  $O(\log n)$  time
- Insertion and deletion have the same order because in order to insert or delete a node you have to find it first – the adjustment processes are also  $O(\log n)$  at worst
- Insertion and deletion will only be a slightly slower  $O(\log n)$  than with a binary search tree but having a balanced tree far outweighs this cost
- The red-black structure of the tree is irrelevant during searching
- The only memory penalty for having this structure is having to store a **boolean** with each node (is it red or black?)

## Implementation

- Include an extra boolean variable in the node class to record node colour
- Adapt the insertion routine from the ordinary binary tree so that it checks on the way down to the insertion point if the current node is black with two **red** children
- If so, colour flip then check for **red-red** violations
- When you get to the insertion point, insert a **red** node and check for **red-red** violations
- Write methods for doing colour flips and for resolving red-red violations
- Write a method for promoting a node

## Implementation

- Rules for removing **red-red** violation

```

if inside grandchild {
    change colour of grandparent and child
    and promote child twice
}

if outside grandchild {
    change colour of parent and grandparent
    and promote parent once
}
    
```

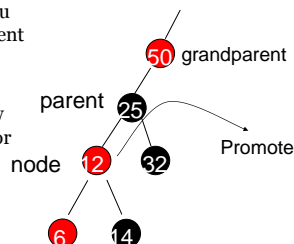
## Implementation

- If ever we come across a **red-red** violation then we need to know whether X is an inside or outside grandchild which means we need to know X's grandparent
- If we're doing a rotation about this **grandparent** then we need to know the **great-grandparent**
- A simple solution is just to track the last four nodes that you've come across on your path down the tree and the relationships between them
- This way you will always have access to **child**, **parent**, **grandparent** and **great-grandparent**



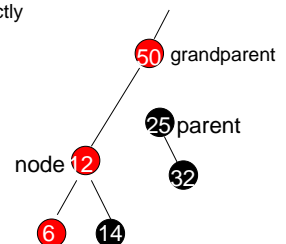
## Step 1

- To promote a node you need the node, its parent and its grandparent
- You also need to know whether they are left or right descendants



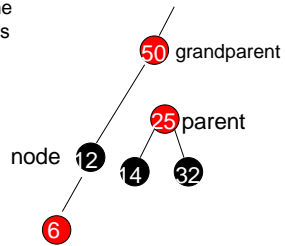
## Step 2

- Connect the node directly to its grandparent
- It replaces its parent



### Step 3

- The parent takes on the node's left/right child as its own left/right child



### Step 4

- The parent can now be connected to the node as one of its children
- The node has been promoted

