

Data Structures & Algorithms 2

Topic 3 – Quicksort

Quicksort

- Quicksort is the most popular sorting algorithm of all
- In the majority of situations it operates in $O(n \log n)$ time (a quicker $O(n \log n)$ than mergesort)
- It also doesn't need additional memory to run (mergesort needed an extra $O(n)$ amount to store the workspace array)
- Like mergesort, quicksort is a recursive sorting algorithm, splitting up an array and calling itself on each half

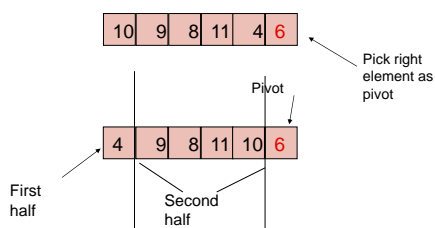
Overview

- Partition array (or subarray) into two halves, putting low values into one half and high values into the other half
- Call **quicksort** on the left half
- Call **quicksort** on the right half

Choosing a pivot

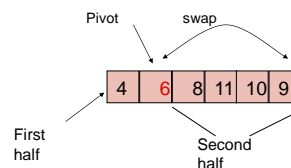
- The idea is that all the elements will be split into two separate lists depending on whether they are bigger or smaller than some **pivot** value
- Lets start off by just picking a random pivot – the **rightmost** element in the array to be sorted
- Now split the numbers apart depending on whether they are bigger or smaller than this element

Split into two halves



Put the pivot in place

- Now swap the pivot with the first element in the second half
- The pivot is now in its final resting position!



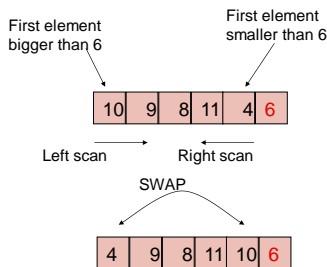
The code for that...

```
public void recQuickSort(int left, int right) {
    if(right-left <= 0) Base Case // if size <= 1,
        return; // already sorted
    else{ // size is 2 or larger
        long pivot = theArray[right]; // rightmost item
        int partition = partitionIt(left, right, pivot); // partition range
        recQuickSort(left, partition-1); // sort left side
        recQuickSort(partition+1, right); // sort right side
    }
}
```

Sorting into two halves

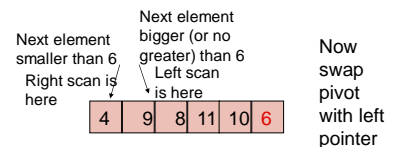
- The sorting works using two 'scans' of the array
 - One from left to right →
 - One from right to left ←
- The left scan starts at the beginning and searches for the first element that is bigger than the pivot
- The right scan starts at the end and searches for the first element that is smaller than the pivot
- These elements are then swapped

Scan & swap

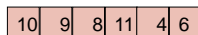


Keeping swapping

- The scans keep moving onto the next element and swapping each other's values
- As soon as one scan has gone past the other the swapping method stops
- Now all the values have been separated into two groups



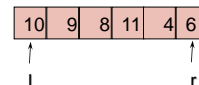
Quicksort, Notation



QS(A, Left array position, Right array position)

L: Leftmost position
 R: Rightmost position
 i: L-R scan positions
 j: R-L scan positions
 pivot: We will pick the rightmost element of the array as pivot

Quicksort



QS(A, 1, 6)

L: 1
 R: 6
 i: 1
 j: 6
 pivot: 6

Quicksort

Here the element at position i is $>$ pivot while the element at position j is $<$ pivot so swap the elements in i and j

```

QS (A, 1, 6)
L:      1
R:      6
i:      1
j:      6 5
pivot:  6
  
```

Quicksort

```

QS (A, 1, 6)
L:      1
R:      6
i:      1
j:      6 5
pivot:  6
  
```

Quicksort

$j \leq i$ so swap i and pivot

```

QS (A, 1, 6)
L:      1
R:      6
i:      1 2
j:      6 5 4 3 2 1
pivot: 10
  
```

Quicksort

Now recursively Quicksort the sublist to the left of 6 (4) and the sublist to the right of 6 (8, 11, 10, 9)

```

QS (A, 1, 6)
L:      1
R:      6
i:      1 2
j:      6 5 4 3 2 1
pivot: 10
  
```

Quicksort

```

QS (A, 1, 6)
L:      1
R:      6
i:      1 2 3 4
j:      6 5 4
pivot: 10
  
```

```

QS (A, 2, 6)
L:      3
R:      6
i:      4
j:      3
pivot:  9
  
```

Quicksort

i and j have gone past each other again so swap pivot with i

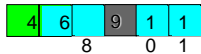
```

QS (A, 1, 6)
L:      1
R:      6
i:      1 2 3 4
j:      6 5 4
pivot: 10
  
```

```

QS (A, 2, 6)
L:      3
R:      6
i:      4
j:      3
pivot:  9
  
```

Quicksort



QS(A, 1, 6)

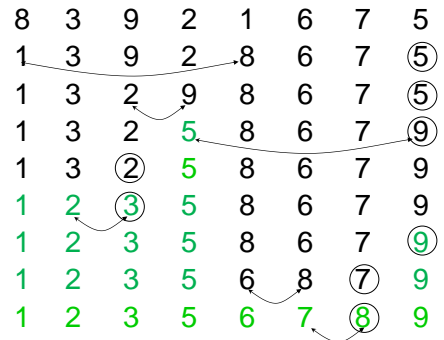
```
L: 1
R: 6
i: 1 2 3 4
j: 6 5 4
pivot: 10
```

QS(A, 3, 6)

```
L: 3
R: 6
i: 4
j: 3
pivot: 9
```

Sort the sublist to the left of the pivot (8) and the sublist to the right (10, 11)

- Sort the following numbers showing pivots and swaps:



Code

```
public int partitionIt(int left, int right, long pivot){
    int leftPtr = left-1;        // left (after ++)
    int rightPtr = right;        // right-1 (after --)
    while(true)
    {
        while( theArray[++leftPtr] < pivot ){} // scan to the right
        while(rightPtr > 0 && theArray[--rightPtr] > pivot){} // scan to the left

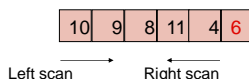
        if(leftPtr >= rightPtr) // if pointers cross,
            break;            // partition done
        else // not crossed, so
            swap(leftPtr, rightPtr); // swap elements
    }
    swap(leftPtr, right); // swap pivot into correct place
    return leftPtr;       // return pivot location
}
```

Things to notice

- The left scan will always stop on the pivot (because the pivot is not smaller than the pivot)
- At this point, the two scans are guaranteed to have crossed paths
- However, the right scan **might go below 0** off the edge of the range so we need to introduce a check to make sure we don't go too far
- This slows down the performance – we'd like to get rid of this
- Leftscan** starts at -1 and **rightscan** at the pivot because they are incremented /decremented before they're used for the first time

Swaps and Comparisons

- Comparisons**
 - For each partition there will be at most $n+1$ or $n+2$ comparisons
 - Every item will be encountered and compared by one or other of the scans, leading to n comparisons
 - The scans will overshoot each other before they realise it, leading to some additional comparisons



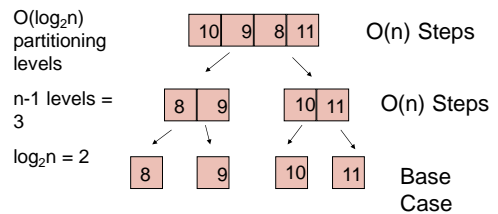
Swaps and Comparisons

- Swaps**
 - The number of swaps depends on how the data is arranged
 - If the data is inversely arranged then every pair of values must be swapped, a total of about $n/2$ (actually $(n-1)/2 + 1$)
 - For random data, half of the elements will already be in the right half position meaning only $n/4$ swaps will be required

Overall complexity

- The order of the algorithm is decided by whichever of swaps or comparisons is greater
- Both are $O(n)$ for one partition
- If each partition halves the array (or subarrays) then the total number of partitionings required is the number of times that n can be halved $\rightarrow \log_2 n$
- $O(n) * \log_2 n$ gives us $O(n \log n)$

Complexity



Quicksort performance

- The performance of divide-and-conquer algorithms comes from splitting the problem each time
- If the problem is halved by each split the algorithm will be $O(\text{splitting code}) * O(\log n)$ since the problem can only be split $\log_2 n$ times before resulting in single units
- However, if the problem isn't being split in half then the efficiency is going to be lower
- The split in quicksort depends on the pivot

Choice of pivot

- If the pivot is the middle value in the array, then the array will be split in half perfectly
- However, if the pivot is the highest or lowest element then the split will be completely lop-sided
- In the worst case scenario n number of splits will be required meaning that the performance of quicksort degenerates to $O(n^2)$

Must be split 4 times using rightmost element as a pivot

Worse pivot choice

4 Steps for 4 items = $O(n)$

1 2 3 4

1 2 3 4

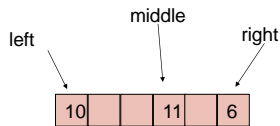
1 2 3 4

1 2 3 4

Choice of pivot

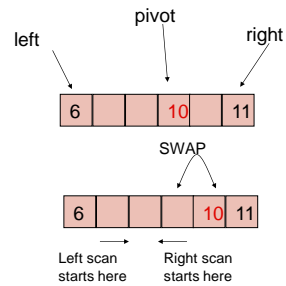
- Ideally we should pick a mid-range value for the pivot (as opposed to just a random number)
- If you were to examine all the numbers and calculate the mid-value this would take longer than the sort itself
- A compromise involves **median of three partitioning**
- Pick the first, middle and last elements of the array (or subarray) and take the middle of them

Median of Three



- Select middle value as the pivot
- Sort the three values into the correct positions
- Swap the pivot to the right

Median of Three



Bonus

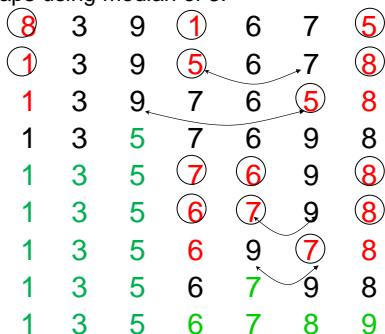
- We can start the partition algorithm at **left+1** and **right-1** because we have already sorted the left and right elements
- We know they are smaller and bigger than the pivot and are therefore in the right place
- These extreme values act as buffers which stop the left scan from scanning an element below 0
- The right scan will always stop at the leftmost element because it is guaranteed to be less than the pivot

Increases efficiency

- Small increase in code efficiency – no check required for scanning left

```
while( theArray[++leftPtr] < pivot ) {} // scan right
while( theArray[--rightPtr] > pivot ) {} // scan left
```

- Sort the following numbers showing pivots and swaps using median of 3:



Median of Three

```
public long medianOf3(int left, int right) {
    int center = (left+right)/2;
    // order left & center
    if( theArray[left] > theArray[center] )
        swap(left, center);
    // order left & right
    if( theArray[left] > theArray[right] )
        swap(left, right);
    // order center & right
    if( theArray[center] > theArray[right] )
        swap(center, right);
    swap(center, right-1); // put pivot on right
    return theArray[right-1]; // return median value
}
```

New problem

- If you use median-of-three partitioning then the quicksort algorithm can't work for partitions of three or fewer items
- You could implement a "manual sort" method to sort three elements
- Another option is to use **insertion sort** when the subarray to be sorted becomes suitably small (insertion sort works really well for nearly sorted data)
- Rather than a cutoff of 3, you could employ the insertion sort method as soon as the size to be sorted falls below 10 or 20

Switching between sorting algorithms

```
public void recQuickSort(int left, int right) {  
    int size = right-left+1;  
    if(size < 10) // insertion sort if small  
        insertionSort(left, right);  
    else // quicksort if large  
    {  
        long median = medianOf3(left, right);  
        int partition = partitionIt(left, right, median);  
        recQuickSort(left, partition-1);  
        recQuickSort(partition+1, right);  
    }  
}
```

Maximizing efficiency

- **Knuth** recommends a cut-off of 9 for maximal efficiency
- The optimum number depends on the computer, operating system, compiler and of course the data you're sorting
- Another idea is to sort the whole array without bothering to sort small partitions smaller than the cutoff
- Finally, the array is nearly sorted and you can use insertion sort to tidy the whole thing up