# Exam, DAT038/TDA417

## Data structures and algorithms

Sample exam, 2019-12-16

There will be **6 basic questions**, and **3 advanced questions**, and **two points per question**. So, the highest possible mark is 18 in total, of which 12 on the basic questions and 6 on the advanced questions. Here is what you need to do to get each grade:

- To pass the course, you must get 8 out of 12 on the basic questions.
- To get a four, you must get 9 out of 12 on the basic questions, and also get 2 out of 6 on the advanced questions.
- To get a five, you must get 10 out of 12 on the basic questions, and also get 4 out of 6 on the advanced questions.

Grade	Total points	Basic points	Advanced
3	≥ 8	≥ 8	_
4	≥ 11	≥ 9	≥ 2
5	≥ 14	≥ 10	≥ 4

Good luck!

Write your anonymous code (not your na	ame) nere:
--	------------

### Basic question 1 (complexity)

What are the order-of-growths for these functions? Assume that each step in the code takes a constant amount of time to run.

The following algorithm takes as input an array, and returns the input array with all the duplicate elements removed. For example, if the input array is  $\{1, 3, 3, 2, 4, 2\}$ , the algorithm returns  $\{1, 3, 2, 4\}$ .

```
S = new empty set
A = new empty dynamic array
for every element x in input array {
  if not S.contains(x) then {
    S.add(x)
    A.add(x)
  }
}
return A
```

1A) What is the order of growth of this algorithm, if the set S is implemented using a red-black tree?

Order of growth:		
Order of growth.		
Oruci or Erowin.		

1B) What is the order of growth of this algorithm, if the set S is implemented using a hash table with linear probing? You may assume that the hash function used is of high quality.

Order of growth:		
oraci or growth.		

### Basic question 2 (binary search)

Your job is to complete the following program for binary search. It takes an array of integers and a key to search for. It should return the index in the array where the key is found, or -1 if the key is not found.

The binary search routine is almost finished, except for the blank spaces marked by "\_\_\_\_\_\_", which you should fill in. The idea of the routine is that, at each point, if the key is present in the array at all then it can be found in the interval array[low]...array[high].

# **Basic question 3 (priority queues)**

Insert the following elements in sequence into an empty binary min heap: 6, 8, 4, 7, 2, 3, 9, 1, 5. Draw both the tree and array representations of the heap.

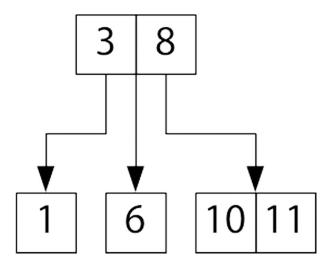
#### 3A) Array representation

1	2	3	4	5	6	7	8	9		

#### 3B) Tree representation

# Basic question 4 (red-black BSTs)

Look at the 2-3 tree below.



4A) Draw the tree as a red-black BST. Draw black nodes as circles and red nodes as squares.

Answer:

Write your anonymous code ( <i>not</i> your name) here:	
---	--

4B) Insert 9 into the tree using the red-black insertion algorithm.

Write down the final tree.

Note: if you are a student of TDA416/DAT037, in the real exam there would be an alternative question about AVL trees for you.

Answer:

## Basic question 5 (hash tables)

Suppose you have the following hash table, implementing using *linear probing*. The hash function we are using is the identity function,  $h(x) = x \pmod{9}$ .

0	1	2	3	4	5	6	7	8
9	18		12	3	14	4	21	

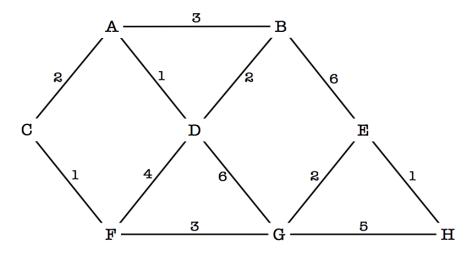
In which order could the elements have been added to the hash table? There are several correct orders, and you should give all of them. Assume that the hash table has never been resized, and no elements have been deleted yet.

- **A)** 9, 14, 4, 18, 12, 3, 21
- **B)** 12, 3, 14, 18, 4, 9, 21
- **C)** 12, 14, 3, 9, 4, 18, 21
- **D)** 9, 12, 14, 3, 4, 21, 18
- **E)** 12, 9, 18, 3, 14, 21, 4

Answer:					

### Basic question 6 (graphs)

You are given the following weighted graph:



#### 6A) Do a breadth-first search of the graph, starting from node A.

Which order do you visit the nodes in? There are several possible orders that a breadth-first search could choose; choose **two** of these orders and write both of them down below.

Node	Α				
Node	Α				

#### 6B) Perform Dijkstra's algorithm starting from node A.

In which order does the algorithm visit the nodes, and what is the computed distance to each of them? There are several possible orders to visit the nodes in - you may choose any of them.

Node	Α				
Distance					

#### Advanced question 7

Consider the following function:

```
public void f(int[] a, int m) {
   int[] b = new int[m];
   for (int i = 0; i < a.length; i++) {
      int j = a[i];
      b[j]++;
   }
   int i = 0;
   for (int j = 0; j < m; j++) {
      for (int k = 0; k < b[j]; k++) {
      a[i] = j;
      i++;
      }
   }
}</pre>
```

7A) What is printed when executing the following code?

```
int[] a = new int[10] {5,3,7,1,0,3,5,4,3,6};
f(a, 8);
// The following line prints the contents of the array
System.out.println(Array.toString(a));
```

Answer:												

7B) What does the function f do? Explain as well the meaning of m.

Answer:

### Advanced question 8

Answer on a separate sheet of paper.

A bidirectional map is a symbol table which supports bidirectional lookup: given a key, you can find the corresponding value, and given a value, you can find the corresponding key.

In a bidirectional map there is always a one-to-one relationship between keys and values. In other words, each key has exactly one value, and each value is found under exactly one key.

A bidirectional map supports the usual symbol table operations:

- new(): create a new, empty bidirectional map
- put(k, v): add the mapping k → v to the map;
   any existing mapping with key k or value v is removed.
- get(k): if the map contains a mapping k → v, return v
- delete(k): if the map contains a mapping k → v, delete it

It also provides an extra reverse operation:

• rlookup(v): if the map contains a mapping  $k \rightarrow v$ , return k

The following example shows what the various operations do.

Operation	Result
new()	Map is {}
put(1,2)	Map is {1 → 2}
put(3,4)	Map is $\{1 \to 2, 3 \to 4\}$
lookup(1)	Returns 2
put(4,2)	Map is $\{3 \rightarrow 4, 4 \rightarrow 2\}$ . Notice that the mapping $1 \rightarrow 2$ is deleted.
rlookup(2)	Returns 4
delete(4)	Map is {3 → 4}

We can implement a bidirectional map as *two* red-black trees:

- forward is a symbol table mapping keys to values. In the example above, it contains  $3 \rightarrow 4$  and  $4 \rightarrow 2$ .
- back is a symbol table mapping values to keys. In the example above, it contains  $4 \rightarrow 3$  and  $2 \rightarrow 4$ .

Write your anony	ymous code (not	your name) here:	

The invariant is that the two maps always contain the same data. More precisely, forward contains the mapping  $k \rightarrow v$ , if and only if back contains the mapping  $v \rightarrow k$ .

We can then implement new, lookup and rlookup as follows:

- new: set forward and back to be empty red-black trees
- lookup(k): look up k in forward using the BST lookup algorithm
- rlookup (v): look up v in back using the BST lookup algorithm

Your task is to implement the remaining operations, insert and delete, so that they take logarithmic time.

- A) Work out how to implement delete, and write down your solution.
- B) Work out how to implement put, and write down your solution.

For both parts, you should write down your answer either as pseudocode or Java code. Your solution must take logarithmic time. You can use the standard red-black tree operations (such as insertion and deletion) without explaining how they are implemented.

Write your anony	ymous code (not	your name) here:	

### Advanced question 9

Answer on a separate sheet of paper.

In this question, you will think about *double-ended priority queues*, a data structure that represents a collection of (e.g.) integers and supports the following operations:

- void add(int x): add a new item to the priority queue
- int deleteMin(): remove and return the minimum item
- int deleteMax(): remove and return the maximum item

#### 9A)

Here is an idea for implementing a double-ended priority queue, which unfortunately *does not work*:

- Maintain a min-heap h1 and a max-heap h2, both initially empty.
- To implement add(x), add x to both h1 and h2.
- To implement deleteMin(), call h1.deleteMin().
- To implement deleteMax(), call h2.deleteMax().

Your job is to work out why this design does not work. Once you have done so, write down a sequence of operations (calls to add, deleteMin and deleteMax) which, if we run them starting from an empty priority queue, give the wrong answer. You should write down your answer in the following format (note that this example gives the right answer, however):

Operation	Right answer	Actual answer
add(3)	-	-
add(5)	-	-
deleteMin()	3	3
deleteMax()	5	5

#### 9B)

In a binary tree, the *level* of a node is defined as follows: the root of the tree has level 0, its children are at level 1, its grandchildren are at level 2, and so on. In other words, the level of a node is the distance from the node to the root.

A *min-max heap* is a complete binary tree satisfying the following invariant:

- If a node is at an *even* level, its value is *less than or equal* to all values in the node's subtree.
- If a node is at an *odd* level, its value is *greater than or equal* to all values in the node's subtree.

Describe how to efficiently find the minimum and maximum elements in a min-max heap. You may assume that the heap is non-empty. Write your answer either as pseudocode or as Java code.

Be careful: there are a number of special cases! Make sure that your algorithm also works for heaps that contain only one item or only two items.

**Hint:** try drawing a min-max heap first, to get a feel for what the invariant means.