Basic question 1: Sorting

Perform in-place insertion sort *and* in-place selection sort on the array [77, 63, 57, 24, 41, 38]. Show the array after each iteration of the outer loop in the algorithm.

Insertion sort						S	electi	on so	rt		
0	1	2	3	4	5	0	1	2	3	4	5
77	63	57	24	41	38	77	63	57	24	41	38
0	1	2	3	4	5	0	1	2	3	4	5
0	1	2	3	4	5	0	1	2	3	4	5
0	1	2	3	4	5	0	1	2	3	4	5
0	1	2	3	4	5	0	1	2	3	4	5
0	1	2	3	4	5	0	1	2	3	4	5

Basic question 2: Hash tables

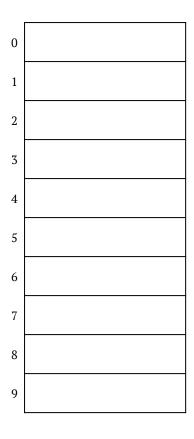
You are given the following five strings:

cat bird horse dog salamander

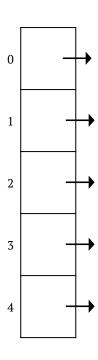
The hash function is h(s) = the number of letters = the length of the string.

Insert the elements *in the given order* into the following two empty hash tables. The left one is an open addressing table (using +1 linear probing, the way it is always done in this course), and the right one is a separate chaining table (using linked lists). Both use normal modular hashing.

Open addressing

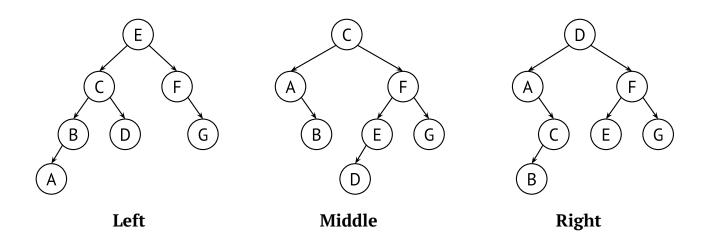


Separate chaining



Basic question 3: Search trees

You are given the following three binary search trees:



One of the trees is <u>not</u> a correctly balanced AVL tree, which one?

Which node is imbalanced?

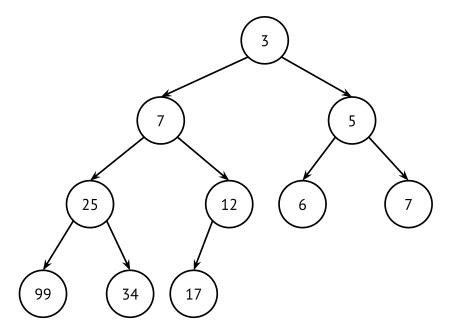
Perform AVL rotations to rebalance the tree.
(Recall that you need at most two rotations.)

Which rotation(s) did you perform?

How does the final tree look? Draw it below:

Basic question 4: Priority queues

You are given a minimum priority queue implemented as the following binary heap:



How does the above heap look when represented as an array?

0	1	2	3	4	5	6	7	8	9	10	11	

Now remove the minimum element from the priority queue (using the standard heap removal algorithm). How does the heap look afterwards?

0	1	2	3	4	5	6	7	8	9	10	11

Basic question 5: Graphs

Run Prim's or Kruskal's algorithm on each of the following two graphs. (If you choose Prim you should start from node A).

Left graph Right graph A 9 B 7 E 6 E 9 3 2 8 7 C

Mark the edges in each minimum spanning tree (MST) directly in the graphs above.

In what order are the edges added to each of the MSTs? (Write XY for the edge between X and Y.)

Left graph:		 	
Right graph:			

Basic question 6: Complexity

Here are implementations of two different sorting algorithms. Both of them are not-in-place, meaning that they don't change the original array, but instead return a new array with the sorted elements. What is their asymptotic complexity in the size of the array, and which one is asymptotically more efficient?

The input array is the variable A, and N is the size of the array. The result is stored in R.

Which of Algorithm 1 or 2 is more efficient (when the input size N is large)?

Explanation:

Explanation:

Algorithm 1

```
Complexity: ____
```

```
function sort1(A):
    N = size of A
    R = new array of size N

    for i = 0, 1, ..., N-1:
        j = i

        while j > 0 and R[j-1] > A[i]:
        R[j] = R[j-1]
        j = j - 1

        R[j] = A[i]

    return R
```

Algorithm 2

Complexity: _____

```
function sort2(A):
    N = size of A
    H = new empty binary heap
    for i = 0 to N-1:
        H.add(A[i])
    R = new array of size N
    for j in 0, 1, ..., N-1:
        R[j] = H.removeMin()
```

Advanced question 7: Complete binary trees

In this question, your task is to write an algorithm for checking if a given binary tree is *complete*.

Assume the following standard definitions. A (binary) *tree* is either null (None in Python) or a (binary) *node* with left and right child trees:

A binary tree is *complete* if:

- every level is completely filled with nodes,
- except possibly the last level, which from the left is filled with nodes up to some point and empty afterwards (that is, no null tree occurs to the left of a node.)

Design an algorithm for testing if a given tree is complete or not. You may answer using pseudocode or your favourite programming language.

Hint: Recall that a complete binary tree can be efficiently represented using an array (which is how binary heaps are implemented, as you already know).

Answer:

```
function isComplete(root) -> boolean:
```

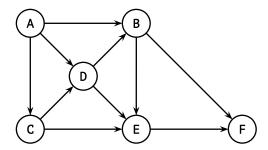
Note: For 1 point you need a good solution idea. For 2 points the implementation must be correct.

Advanced question 8: *k*-length paths in a graph

In the following, your task is to provide an algorithm that returns the number of k-length paths between two given vertices in a DAG (directed acyclic graph).

More formally, you are given an unweighted DAG G = (V, E), two vertices v_{start} and v_{goal} in V, and a natural number k. Your algorithm should return the number of paths of length k from v_{start} to v_{goal} . You may answer using pseudocode or your favourite programming language, and you can make use of any additional data structure that we covered in the course.

Here, the length of a path between two nodes is the number of its edges. For example, in the graph below, there are 3 paths of length 4 from vertex A to vertex F, namely: ADBEF, ACDEF, ACDBF.



You can assume the following data type for graphs and extend it as needed for your solution:

class DirectedGraph<Vertex>:

successors: Map<Vertex, List<Vertex>>

predecessors: Map<Vertex, List<Vertex>>

vertices: Set<Vertex>

Answer:

function Count(G, start, goal, k) -> integer:

Note: For 1 point you need a correct solution. For 2 points it must be efficient as well.

Advanced question 9: Amortized complexity

Consider the following implementation of a queue:

- 1. The queue is composed of two stacks: STACK-1 and STACK-2
- 2. ENQUEUE(x) adds an element x to the queue by applying PUSH(x) on STACK-1
- 3. DEQUEUE(), removes an element from the queue, as follows:
 - a. If STACK-2 is not empty, then simply POP from STACK-2 and return the element
 - b. If STACK-2 is empty, then:
 - i. while STACK-1 is not empty, POP it and PUSH onto STACK-2
 - ii. POP from STACK-2 and return the result

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A.	What is the worst-case complexity in the size of the queue for the operations ENQU	EUE
	and DEOUEUE? Explain your solution!	

B. What is the amortized cost for DEQUEUE?

Justify your answer! We recommend using the *aggregate method*; however, you are free to use any other known methods for analyzing the amortized complexity (such as the *potential method* or the *accounting method*).

Note: For 1 point you need to get the costs for both A and B correct.

For 2 points the explanations must also be correct.