

Note7 Power Series Solutions

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- 1 Summary of Power Series Ansatz
- 2 ODE with Analytic Coefficients
- 3 ODE with Coefficients having Singular Points
 - 3.1 Regular Singular Points
- 4 Euler's Equation
- 5 The Method of Frobenius
 - 5.1 Basic Method
 - 5.2 Find a Second Independent Solution

For **homogeneous linear ODEs** with **variable coefficients**, sometimes finding an explicit solution is difficult, then we use the method of **power series ansatz** to solve/approximate solutions.

Recall: **homogeneous, linear, ordinary, variable coefficients**.

1 Summary of Power Series Ansatz

- 1. Analyze the equation, decide whether we can use power series ansatz around some point
- 2. Choose which form of ansatz to use
- 3. Plug into the ansatz, get recurrence relationship of the coefficients
- 4. Set initial value of coefficients. solve for coefficients to get one or more independent solutions
- 5. If not enough independent solutions are found, using reduction of order to find more solutions
- 6. Obtain the general solution

2 ODE with Analytic Coefficients

$$x'' + p(t)x' + q(t)x = 0$$

Where $P(t)$ and $Q(t)$ are **analytic in a neighborhood of t_0** .

"a neighborhood of t_0 " contains t_0

Then we can choose the ansatz

$$x(t) = \sum_{k=0}^{\infty} a_k (t - t_0)^k$$

Accordingly,

$$x'(t) = \sum_0^\infty k a_k (t - t_0)^{k-1}$$

$$x''(t) = \sum_0^\infty k(k-1) a_k (t - t_0)^{k-2}$$

Plug the three equations back, we can obtain the relationship of the coefficients $\{a_0, a_1, a_2, \dots\}$.

Depending on the situation, after setting values for first n terms (always 2), we can solve 1 to n (expected) independent solutions.

If not enough independent solutions are found, sometimes we can use reduction of order to find more.

Comments:

- The solutions found should be valid within its radius of convergence

Radius of Convergence of a Power Series:

- $\frac{1}{R} = \lim_{n \rightarrow \infty} \frac{|c_{n+1}|}{|c_n|}$
- $\frac{1}{R} = \lim_{n \rightarrow \infty} |c_n|^{1/n}$

3 ODE with Coefficients having Singular Points

The general form of a **homogeneous linear second-order ODE** with **variable coefficients**:

$$P(t)x'' + Q(t)x' + R(t)x = 0$$

It is said to have a **singular point** at t_0 if $P(t_0) = 0$.

Generally around singular points, it's hard to decide or find continuous solutions. But there're some specific cases we can deal with.

3.1 Regular Singular Points

$$x'' + p(t)x' + q(t)x = 0$$

is said to have a **regular singular point** at t_0 if the functions $(t - t_0)p(t)$ and $(t - t_0)^2 q(t)$ are analytic in a neighborhood of t_0 . A singular point which is not regular is said to be **irregular**.

The general claim is: if an equation has a regular singular point at t_0 , then we can assume

$$p(t) = \frac{p_{-1}}{t-t_0} + \sum_{j=0}^\infty p_j(t-t_0)^j$$
$$q(t) = \frac{q_{-2}}{(t-t_0)^2} + \frac{q_{-1}}{t-t_0} + \sum_{j=0}^\infty q_j(t-t_0)^j \text{ and use the ansatz } x(t) = (t-t_0)^r \sum_{k=0}^\infty a_k(t-t_0)^k$$

to find solutions.

4 Euler's Equation

$$t^2 x'' + \alpha t x' + \beta x = 0, \quad \alpha, \beta \in \mathbb{R}$$

Analysis:

This is exactly the case where the equation $x'' + \alpha \frac{1}{t} x' + \beta \frac{1}{t^2} x = 0$, $\alpha, \beta \in \mathbb{R}$ is having a regular singular point at $t = 0$.

Then we can choose the ansatz

$$x(t) = t^r$$

Inserting back and solve for r we get

$$r = -\frac{\alpha - 1}{2} \pm \frac{1}{2} \sqrt{(\alpha - 1)^2 - 4\beta}$$

- $(\alpha - 1)^2 - 4\beta > 0$

$$x(t; c_1, c_2) = c_1 t^{r_1} + c_2 t^{r_2}, \quad c_1, c_2 \in \mathbb{R}$$

- $(\alpha - 1)^2 - 4\beta = 0$, $r_1 = r_2 = \frac{1-\alpha}{2}$, need to use reduction of order

$$x(t; c_1, c_2) = c_1 t^{r_1} + c_2 t^{r_1} \ln t, \quad c_1, c_2 \in \mathbb{R}$$

Reduction of order:

For equation $y'' + p(t)y' + q(t)y = 0$, and a known solution $y_1(x)$, let $y_2(x) = v(x)y_1(x)$, then you can solve for $v(x)$ using

$$y_1(t)v'' + (2y_1'(t) + p(t)y_1(t))v' = 0$$

- $(\alpha - 1)^2 - 4\beta < 0$

After getting $x_1(t) = t^{r_1} = t^\lambda (\cos(\mu \ln t) + i \sin(\mu \ln t))$.

$x_2(t) = t^{r_1} = t^\lambda (\cos(\mu \ln t) - i \sin(\mu \ln t))$, further have

$$x(t; c_1, c_2) = c_1 t^\lambda \cos(\mu \ln t) + c_2 t^\lambda \sin(\mu \ln t), \quad c_1, c_2 \in \mathbb{R}$$

5 The Method of Frobenius

5.1 Basic Method

$$x'' + p(t)x' + q(t)x = 0$$

$$t^2 x'' + t(tp(t))x' + t^2 q(t)x = 0$$

If it has a **regular singular point** at $t = 0$, then we can write out

$$tp(t) = \sum_{j=0}^{\infty} p_j t^j$$

$$t^2 q(t) = \sum_{j=0}^{\infty} q_j t^j$$

p_j and q_j are known constants for us

We choose the **Frobenius ansatz**

$$x(t) = t^r \sum_{k=0}^{\infty} a_k t^k \quad a_0 \neq 0$$

Accordingly,

$$x'(t) = \sum_{k=0}^{\infty} (r+k) a_k t^{r+k-1}$$

$$x''(t) = \sum_{k=0}^{\infty} (r+k)(r+k-1) a_k t^{r+k-2}$$

Plug back into the equations we then get

$$(r(r-1) + p_0 r + q_0) a_0 = 0$$

$$((r+m)(r+m-1) + q_0 + (r+m)p_0) a_m + \sum_{k=0}^{m-1} (q_{m-k} + (r+k)p_{m-k}) a_k = 0 \quad m \geq 1$$

Setting

$$F(x) := x(x-1) + p_0 x + q_0$$

We get the **indicial equation** and **recurrence equations** to solve for a_k

$$F(r) = 0$$

$$a_m F(r+m) = - \sum_{k=0}^{m-1} (q_{m-k} + (r+k)p_{m-k}) a_k, \quad m \geq 1$$

With the recurrence equations, you can usually generate out a easier recurrence equation.

For good and different r_i solved by the indicial equation, llus some assumed initial values for a_0, a_1, \dots , we are possible to solve for all a_k .

If everything goes fine, with $r_1 \neq r_2$ are two GOOD solutions, you get two INDEPENDENT solutions.

Question

Find the series solution to the below equation in the vicinity of $x_0 = 0$

$$2x^2 y'' + 7x(x+1)y' - 3y = 0$$

Answer

5.2 Find a Second Independent Solution

But things can go wrong if

- $r_1 = r_2$: then need further work to obtain another solution (how? Later.)
- $r_1 = r_2 + N$: then though r_1 gives a solution, for r_2 , due to $F(r_2 + N) = F(r_1) = 0$,
 - if the right-side of the recurrence equation vanishes for $F(r_2 + m) = F(r_2 + N)$, then a_N is arbitrary, by setting a_N as zero when dealing with r_1 , and as an arbitrary non-zero number when dealing with r_2 , we can further find a second independent solution. Though we can also use another general method (how? Later.)
 - if the right-side of the recurrence equation doesn't vanish, need further work to obtain another solution (how? Later.)

Noticing the above 3 cases have one thing in common: $r_1 = r_2 + N$, $N \in \mathbb{N}$ including 0. There's a general method for the above cases.

The recurrence equations can give a relationship $a_k(r)$. Then we have

$$x_2(t) = \frac{\partial}{\partial r} \left(t^r \sum_{k=0}^{\infty} a_k(r) t^k \right) \Big|_{r=r_2} = c \cdot x_1(t) \ln t + t^{r_2} \sum_{k=0}^{\infty} a'_k(r_2) t^k$$

where the constant $c \in \mathbb{R}$ may vanish. If $r_1 = r_2$, then $c = 1$.

And a tricky way to find $a'_{2k}(r_2)$ is to use

$$\frac{a'_{2k}(r)}{a_{2k}(r)} = \frac{d}{dr} \ln |a_{2k}(r)|$$