Geometric Shapes

Module 3 Lecture 1

CZ200

Lecture 1: Learning Objectives

- To understand how points and curves can be used in solving data visualization problems
- To understand curves as objects with 1 degree of freedom
- To understand what mathematical representation is the most efficient for defining and displaying curves
- To understand how different coordinate systems can be used together for deriving mathematical representations of curves

Geometric Shapes

- · Geometry has no color and texture
- Points 0 degree of freedom shape
- Curves 1 degree of freedom shape
- Surfaces 2 degree of freedom shape
- Solid objects 3 degree of freedom shape
- 2 and 3 dimensional spaces
- · Time is yet another dimension however different
- At the display level, drawn as pixels (picture elements), connected segments (polylines), and shaded polygons (polygon meshes)

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Points

- Individual points
- Reference points
- Point rendering
- Splats (e.g. little oriented disks) rendering example (6 MP, 120M) rays https://www.youtube.com/watch?v=X_wyoroo4co
- 2D pixels (picture elements) and 3D voxels (volume elements)
- Defined by Cartesian coordinates (x, y, z), polar (r, α) , spherical (r, α, β) or cylindrical (h, r, α) coordinates





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Curves

- 2D and 3D
- · Polylines interpolation by connected straight line segments
- Implicit (only 2D)

$$f(x,y)=0$$

• Explicit (only 2D)

$$y=f(x)$$
 or $x=f(y)$

• Parametric (2D and 3D)

$$x=x(t)$$

y=y(t) $t = [t_1, t_2]$

x=x(t)y=y(t)

z=z(t)

 $t = [t_1, t_2]$

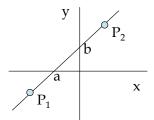
Straight Line. **Implicit Representation**

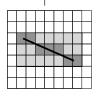
· Straight line

$$Ax + By + C = 0$$

$$\frac{y - y_1}{x - x_1} - \frac{y - y_2}{x - x_2} = 0$$

- Segment: $x \in [x_1, x_2], y \in [y_1, y_2]$ Straight line: $x, y \in (-\infty, \infty)$
- Ray: $x \in [x_1, \infty)$, $y \in [y_1, \infty)$
- Drawing is done by sampling points (pixels) within the x and y domains. It is slow since most of the points within the domain do not belong to the segment.





2D Curves: Study by Example

- Straight Line (Segment, Ray)
- Circle (Arc)
- · Ellipse (Arc)

Straight Line. **Implicit Representation**

· Straight line

$$Ax + By + C = 0$$

$$\frac{y - y_1}{x - x_1} - \frac{y - y_2}{x - x_2} = 0$$

- Segment: $x \in [x_1, x_2], y \in [y_1, y_2]$
- Straight line: $x, y \in (-\infty, \infty)$
- Ray: $x \in [x_1, \infty)$, $y \in [y_1, \infty)$



$$\frac{x}{a} + \frac{y}{b} = 1 \Rightarrow \frac{x}{a} + \frac{y}{b} - 1 = 0$$

Signed coordinates of points a and b

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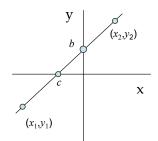
Straight Line. **Explicit Representation**

· Straight line

$$y = ax + b$$
 or $x = dy + c$

$$a = \frac{y - y_1}{x - x_1} = \frac{y - y_2}{x - x_2} = \frac{y_2 - y_1}{x_2 - x_1} = \frac{y_1 - y_2}{x_1 - x_2}$$

- Segment: $x \in [x_1, x_2], y \in [y_1, y_2]$
- Straight line: $x, y \in (-\infty, \infty)$
- Ray: $x \in [x_1, \infty)$, $y \in [y_1, \infty)$



- Drawing is done by incrementing x or y and obtaining y and x, respectively. Fast. Integer version used for drawing segments in all computers.
- Axes dependency: special cases for drawing vertical and horizontal lines x=c, y=b



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Straight Line. **Parametric Representation**

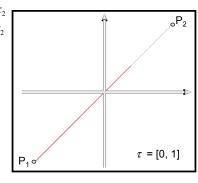
· Parametric definition of a straight line segment $P = P_1 + \tau (P_2 - P_1)$

$$x = x_1 + \tau(x_2 - x_1) = x_1(1 - \tau) + \tau x_2$$

$$y = y_1 + \tau(y_2 - y_1) = y_1(1 - \tau) + \tau y_2$$

$$\tau = [0,1]$$

The animation illustrates drawing of the segment by computing coordinates of its points for every value of the parameter being incremented



Straight Line.

Parametric Representation

· Parametric definition of a straight line segment

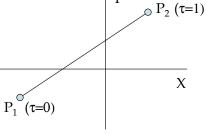
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$$y = y_1 + \tau(y_2 - y_1) = y_1(1 - \tau) + \tau y_2$$

$$\tau = [0,1] \quad \text{One parameter !}$$

- · Straight line $\tau = (-\infty, \infty)$
- · Straight line ray, e.g., $\tau = [0, \infty)$ $\tau = (-\infty, 1]$



• Drawing is done by incrementing parameter τ and obtaining x and y- axes independent, Fast.

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Straight Line. **Parametric Representation**

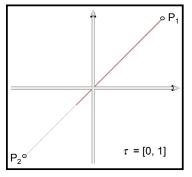
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Straight Line.Parametric Representation

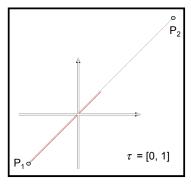
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Straight Line.Parametric Representation

· Parametric definition of a straight line segment

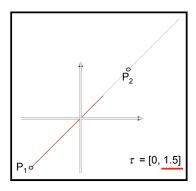
$$P = P_1 + \tau(P_2 - P_1) \tag{1}$$

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$$\tau = [0,1]$$

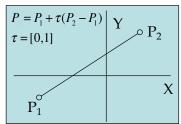
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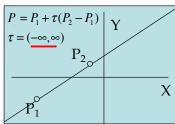


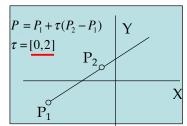
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Straight Line.Parametric Representation







Summary

2D straight lines, segments and rays can be defined analytically by

- Implicit functions

f(x,y)=0 — Slow for rendering

Explicit functionsy=f(x) or x=f(y)

Fast but axes dependent

Parametric functions
 One parameter only

x=x(t), y=y(t) $t=[t_1, t_2]$ – Fast and axes independent