



Novel Scenes & Classes: Towards Adaptive Open-set Object Detection

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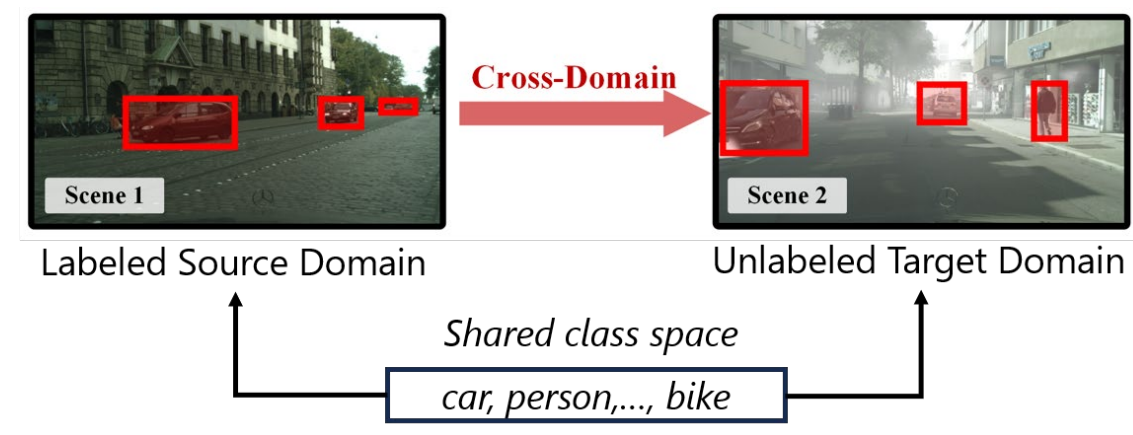


Background

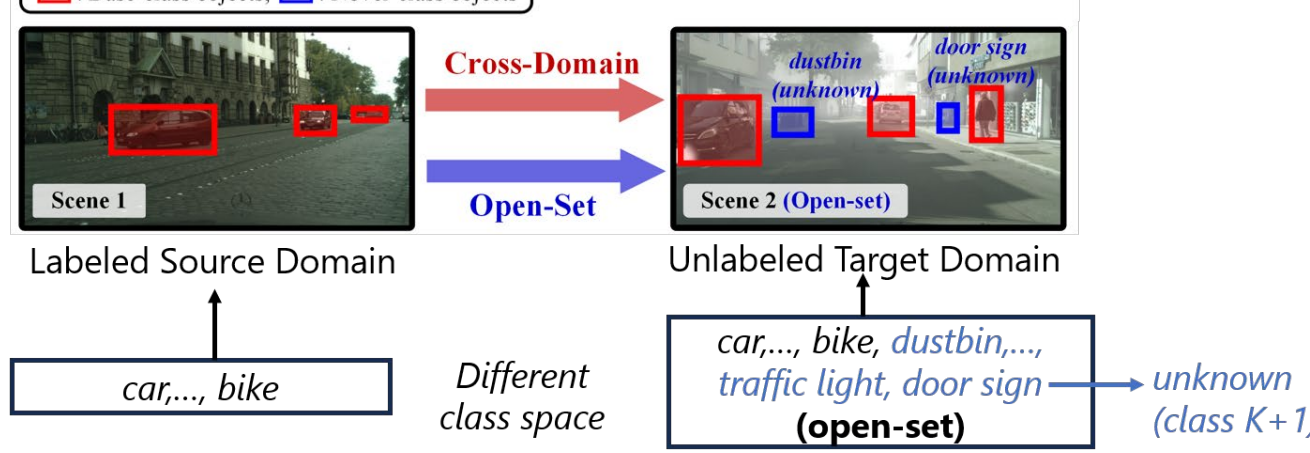
Adaptive Open-set Object Detection (AOOD)

AOOD aims transfer an object detector from a **labeled source domain** to an **unlabeled target domain** with **open-set classes**, different from existing DAOD with shared class definition.

Domain Adaptive Object Detection (DAOD)

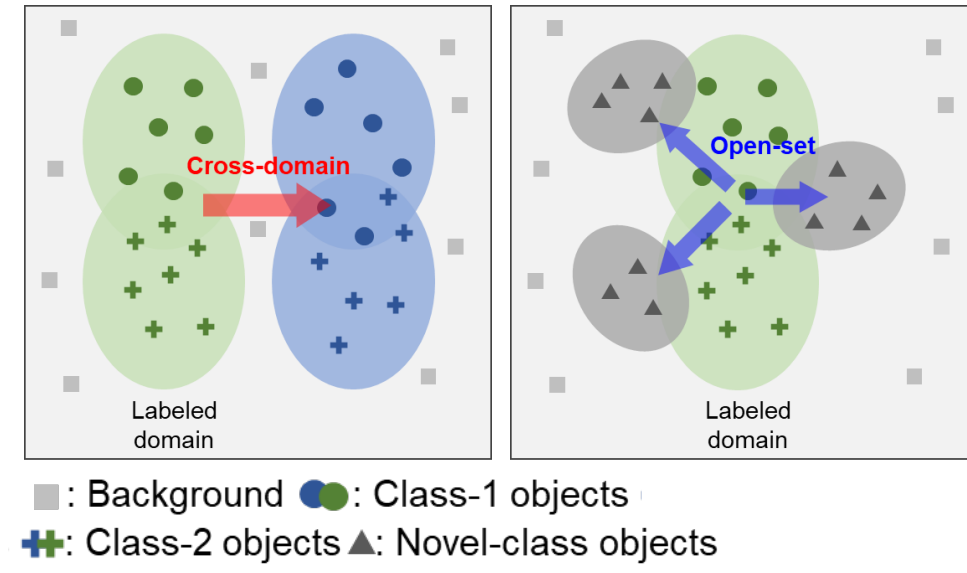


Adaptive Open-set Object Detection (AOOD)



Motivation

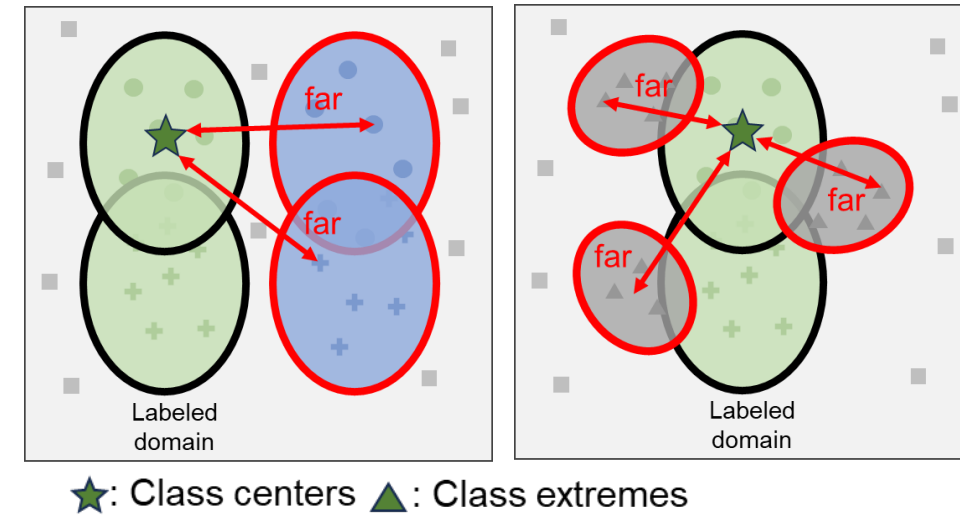
Problem Analysis



AOOD needs to address

- cross-domain challenge
- open-set challenge

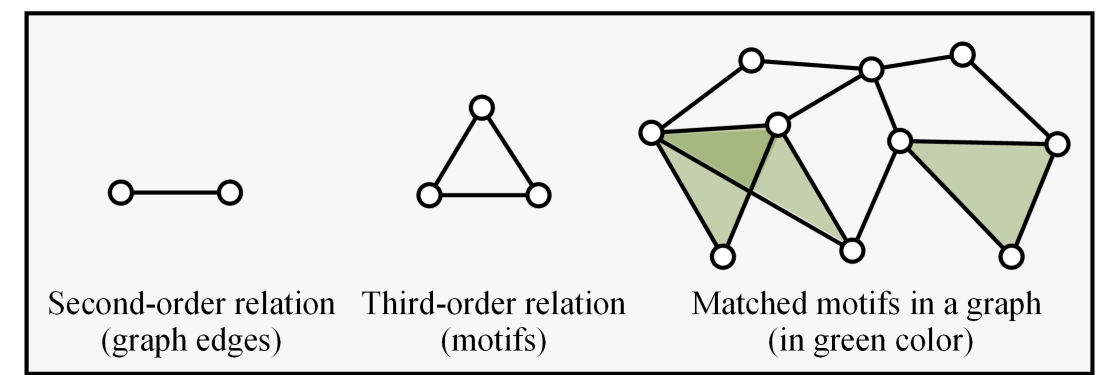
Challenges



What limits AOOD?

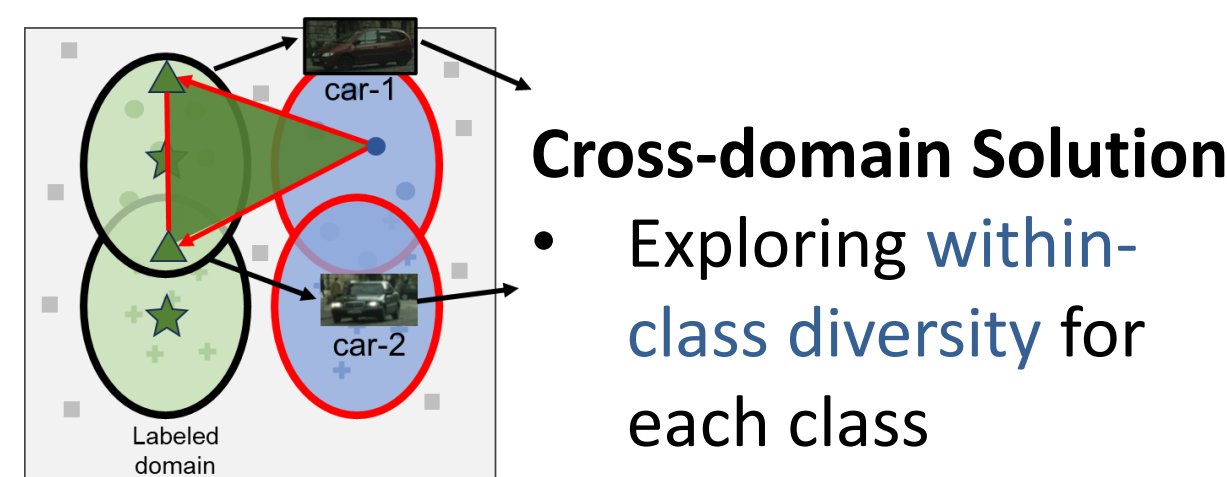
- Cross-domain/open-set objects are both **out of labeled distribution**, leading to the failure of existing **low-order solutions**, e.g., selecting objects with low confidence.

Preliminaries



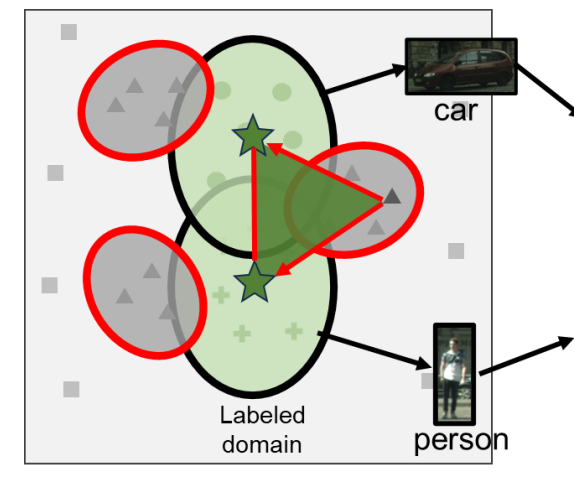
Motif is a statistically significant subgraph with high-order pattern.

The Proposed High-order Solutions



Cross-domain Solution

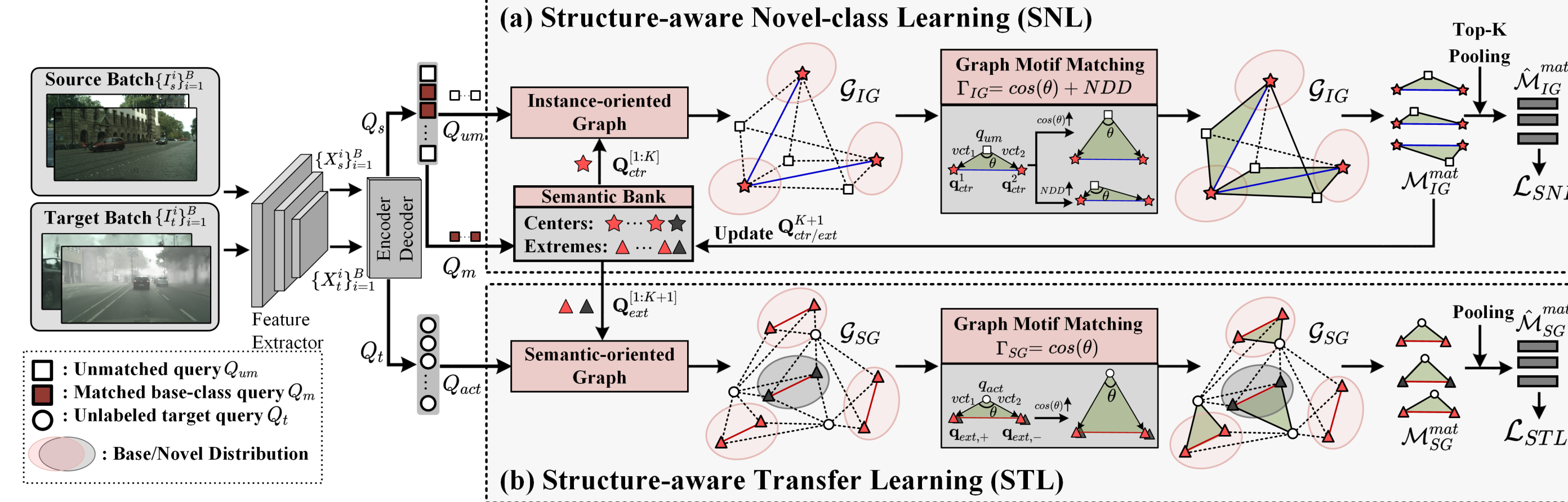
- Exploring **within-class diversity** for each class



Open-set Solution

- Exploring **object-level property** shared among different classes

Methodology



Structure-aware Novel-class Learning (SNL)

- Establish a semantic bank saving class centers and extremes

$$Q_{ctr}^k \leftarrow \alpha f_{\text{mean}}(Q_m^k) + (1 - \alpha) Q_{ctr}^k$$

$$Q_{std}^k \leftarrow \alpha f_{\text{std}}(Q_m^k) + (1 - \alpha) Q_{std}^k$$

- Build up the instance-oriented graph

Link class centers with the farthest counterpart
Link unmatched object queries with class centers

- Select motifs via a high-order metric

$$M_{IG}^{mat} = \text{argmin}_{\Gamma_{IG}} \mathcal{M}_{IG} \quad \text{where} \quad \cos(\theta) := \frac{vct_1 \cdot vct_2}{\|vct_1\|_2 \cdot \|vct_2\|_2}$$

$$\Gamma_{IG} := \cos(\theta) + NDD$$

$$NDD := \frac{\|vct_1\|_2 - \|vct_2\|_2}{\|q_{ctr}^k - q_{std}^k\|_2}$$

- Optimize with selected motifs

$$\mathcal{L}_{SNL} = -\frac{1}{K} \sum_{i=1}^K \log(p(f_{cls}(\hat{M}_{IG,i}^{mat}) = K + 1 | \hat{M}_{IG,i}^{mat}))$$

Unknown posterior

Structure-aware Transfer Learning (STL)

- Build up the semantic-oriented graph
Link class extreme pairs in the same class
Link activated object queries with class extremes

- Select motifs via a high-order metric

$$M_{SG}^{mat} = \text{argmin}_{\Gamma_{SG}} \mathcal{M}_{SG} \quad \text{where} \quad \cos(\theta) := \frac{vct_1 \cdot vct_2}{\|vct_1\|_2 \cdot \|vct_2\|_2}$$

$$\Gamma_{SG} := \cos(\theta)$$

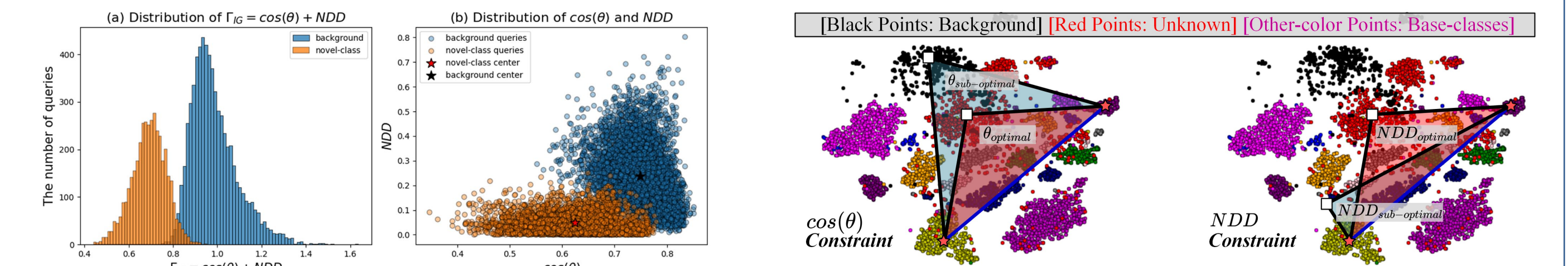
- Optimize with selected motifs

$$\mathcal{L}_{STL} = -\frac{1}{|\mathcal{M}_{SG}^{mat}|} \sum_{i=1}^{|\mathcal{M}_{SG}^{mat}|} \log(p(f_{cls}(\hat{M}_{SG,i}^{mat}) = K + 1 | \hat{M}_{SG,i}^{mat}))$$

Pseudo labels

Experiments

Method	Set	num. novel-class: 3				num. novel-class: 4				num. novel-class: 5			
		mAP _b ↑	AR _n ↑	Wl↓	AOSE↓	mAP _b ↑	AR _n ↑	Wl↓	AOSE↓	mAP _b ↑	AR _n ↑	Wl↓	AOSE↓
DDETR [60]	het-sem	47.52	0.00	0.341	459	45.24	0.00	0.506	1028	42.38	0.00	0.659	1968
PROSER [59]		46.92	1.80	0.271	218	44.19	2.02	0.415	531	41.99	2.00	0.584	1127
OpenDet [19]		47.04	1.92	0.269	221	45.71	1.89	0.499	511	42.09	1.70	0.579	922
OW-DETR [18]		43.31	1.84	0.432	192	42.52	2.10	0.619	451	39.92	1.98	0.684	814
SOMA (ours)		50.87	3.78	0.268	139	48.06	4.41	0.412	340	45.55	4.08	0.526	649
DDETR [60]	hom-sem	44.62	0.00	1.860	2937	43.55	0.00	2.000	3565	40.18	0.00	2.462	6770
PROSER [59]		43.15	4.59	1.842	2146	43.31	4.99	2.018	2641	39.99	5.99	2.563	4963
OpenDet [19]		45.51	5.28	1.336	1458	44.02	5.67	1.653	1798	40.87	6.58	2.303	3416
OW-DETR [18]		43.22	3.15	1.355	1076	42.83	3.46	1.593	1320	39.45	4.38	2.384	3399
SOMA (ours)		48.67	6.96	1.257	915	47.02	7.42	1.527	1232	43.37	8.42	2.281	2886
DDETR [60]	freq-dec	56.99	0.00	0.579	1240	55.02	0.00	0.835	2136	53.89	0.00	0.93	2625
PROSER [59]		55.70	6.68	0.589	536	54.51	7.88	0.780	952	53.43	8.22	0.943	1072
OpenDet [19]		57.28	9.35	0.519	720	54.89	10.59	0.781	1251	53.51	10.37	0.839	1470
OW-DETR [18]		56.63	6.61	0.585	698	55.45	7.90	0.745	930	53.60	7.90	0.807	1105
SOMA (ours)		59.18	11.41	0.507	669	56.85	12.47	0.723	1140	55.63	12.36	0.759	1315
DDETR [60]	freq-inc	44.72	0.00	2.862	2859	43.91	0.00	3.270	4907	41.12	0.00	3.609	8291
PROSER [59]		44.23	2.94	2.881	1090	42.47	2.98	2.745	1866	39.11	3.01	3.119	3242
OpenDet [19]		44.85	3.23	2.579	1700	42.92	3.30	2.741	2835	40.34	3.44	2.970	4965
OW-DETR [18]		43.92	3.85	2.032	1377	43.01	3.99	2.219	1891	40.21	2.98	2.184	2293
SOMA (ours)		46.62	8.32	1.452	733	47.30	8.43	1.566	1166	44.45	7.95	1.792	1974



Conclusion

- A **more practical** problem definition, Adaptive Open-set Object Detection (AOOD) by considering both novel classes and novel scenes.
- Exploring the **low-order limitation** in the AOOD scenario.
- Solving AOOD with a unified **motif-based framework** with **high-order evidence**, including the structure-aware novel-class learning and transfer learning.