What is learnable?

Readings for today

• Fulop, S. A., & Chater, N. (2013). Learnability theory. Wiley Interdisciplinary Reviews: Cognitive Science, 4(3), 299-306.

Topics

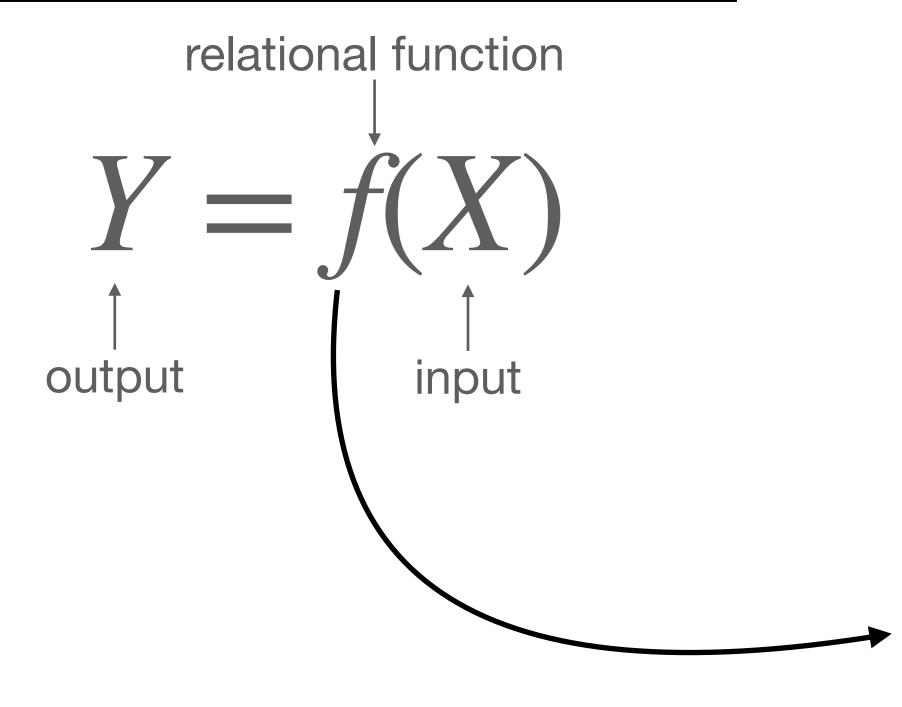
1. The two parts of a statistical model

2. Understanding what is learnable

The two parts of a statistical model

Fundamental form of a statistic

Fundamental form of a statistic



<u>Sample</u>

$$S = \{(X_i, Y_i)\}_{i=1}^n$$

- h : hypothesis \rightarrow prediction based on X
- g: learner \rightarrow system that finds the best h for a particular S

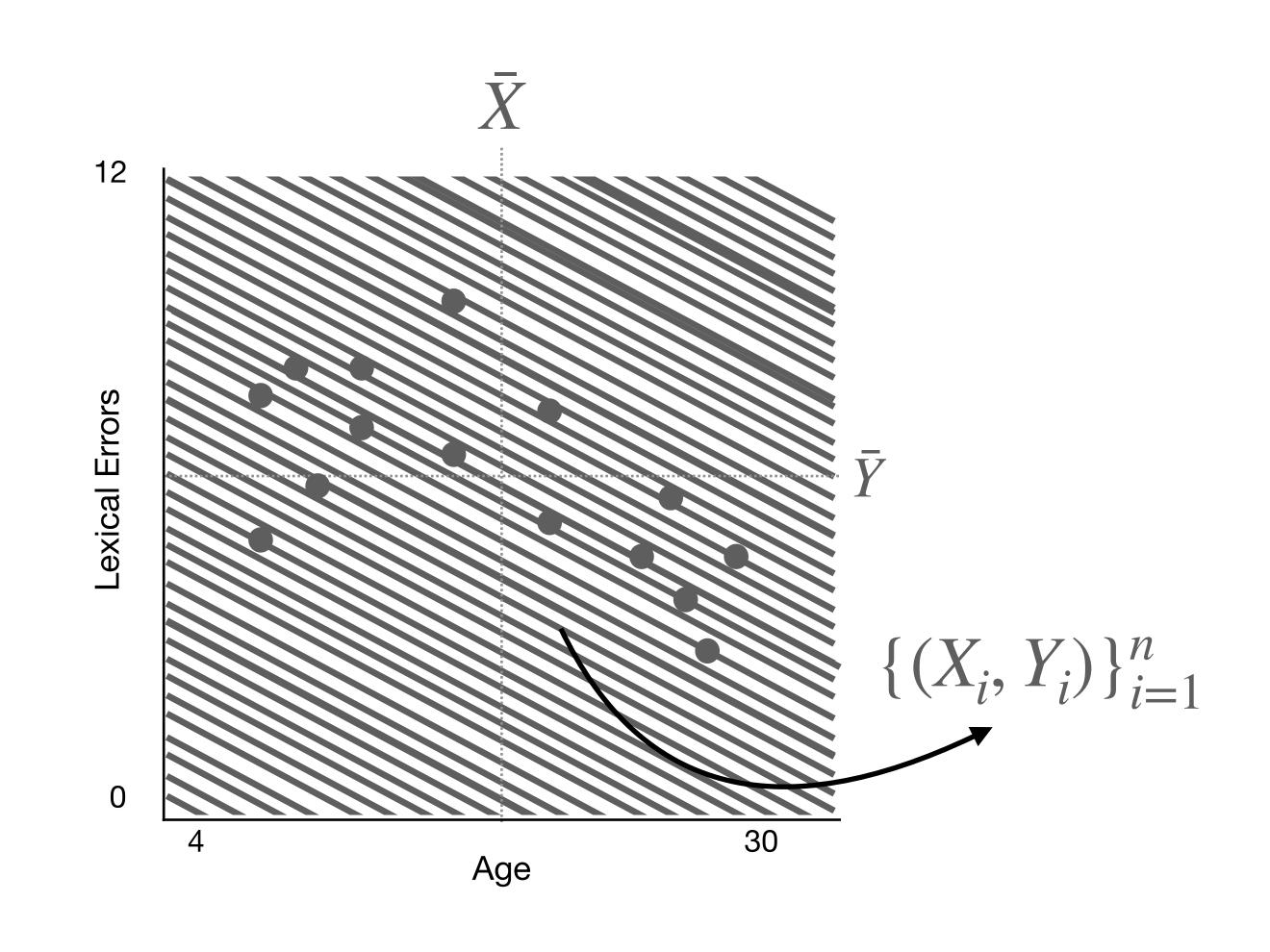
The learning problem: $h \& g \rightarrow f$

<u>Hypothesis</u>

$$h: Y = \hat{\beta}_1 X + \hat{\beta}_0$$

<u>Learner</u>

$$g:\beta=(X'X)^{-1}X'Y$$



Empirical Risk Minimization

Risk: how well a hypothesis does in practice with new (test) data.

$$R(h) =$$

$$\mathcal{E}(h(X), Y)$$

loss function

Goal of learner

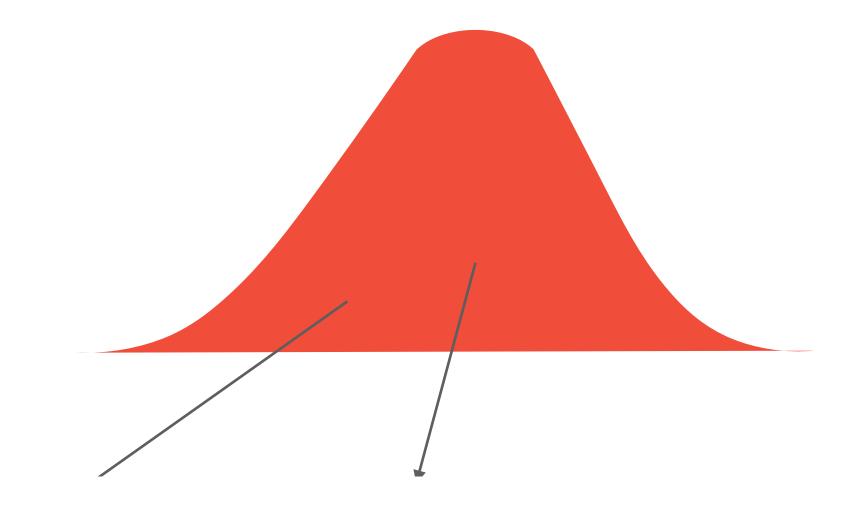
$$g = \underset{h \in H}{\operatorname{arg min}} R(h)$$

$$\mathcal{E}(h(X), Y) = \begin{cases} 1, & h(X) \neq Y \\ 0, & h(X) = Y \end{cases}$$

Empirical Risk Minimization

Expected Risk

$$E_{\mathsf{risk}}\left(h,n,P\right) = \underbrace{\int_{(\mathbf{X},\mathbf{Y})_n} \underbrace{R(h)}_{\mathsf{risk}} \underbrace{dP_{(X,Y)_n}}_{\mathsf{train}}$$
 risk distribution



Assumption: Both the training and test data come from the same distribution.

Understanding what is learnable

What is learnable?

Learnability theory: Can the true h be learned?

Determine whether the true h is able to be learned given a particular data scenario (e.g., particular $P_{(\mathbf{X},\mathbf{Y})}$)?

Computational theory: Can the solution for the true h be computed?

P: Problem can be computed in polynomial time. We can only work with "P hard" problems

NP: Problem requires non-deterministic polynomial time.

Bayesian Learning

Bayes Rule:

$$P(H_i | \{(X, Y)\}_{i=1}^n) = \frac{P(D | H_i) P(H_i)}{P(D)}$$

 H_i : individual hypothesis

Naive prior:

$$P(H_i) = U(-\infty, +\infty)$$

$$P(H_i | D) = P(D | H_i)$$

Bernstein-von Mises Theorem

- If: (X, Y) are independent and identically distributed
 - limited to a finite space of outcomes.

Assuming: • The true *h* is learnable at all.

Then: The posterior probability converges to the true h among almost all samples.

--- e.g., testing & training sets

Model selection

$$h_{true} \rightarrow h_{best}$$

Generalization: Given a fixed training data set, find the model that *best* predicts future unseen (test) data set.

$$E_{\mathsf{risk}}\left(h,n,P\right) = \underbrace{\int_{(\mathbf{X},\mathbf{Y})_n} \underbrace{\int_{(\mathbf{X},\mathbf{Y})} \ell(h(X),Y)}_{\mathsf{loss function}} \underbrace{\frac{dP_{X,Y}}{dP_{X,Y}}}_{\mathsf{destion distribution}} \underbrace{\frac{dP_{X,Y}}{dP_{X,Y}}}_{\mathsf{destin distribution}}$$

Model selection

Bayesian evidence:

Relative evidence in favor of H_m over H_j

$$\frac{P(H_m | D)}{P(H_j | D)} = \frac{P(H_m)}{P(H_j)} \times \frac{P(D | H_m)}{P(D | H_j)}$$

Naive prior:

$$P(H_i) = U(-\infty, +\infty)$$

Neyman-Pearson Lemma:

When probabilities are known, the optimal decision rule for selecting one H over another is a likelihood ratio test.

Probably Approximately Correct (PAC) Learning

Q: How do you get "good enough" learning so as to be useful?

PAC learning requires a learner to:

- 1. Approximate the true h
- 2. Be computationally feasible (P problem)

Approximately: A hypothesis $h \in H$ is approximately correct if its error over the training data $P_{(X,Y)}$ is bounded by some ϵ , with $0 \le \epsilon \le \frac{1}{2}$.

Probably: The h is probably approximately correct at a generalization error rate of δ , if its prediction accuracy is $1-\delta$, with $0 \le \delta \le \frac{1}{2}$.

Probably Approximately Correct (PAC) Learning

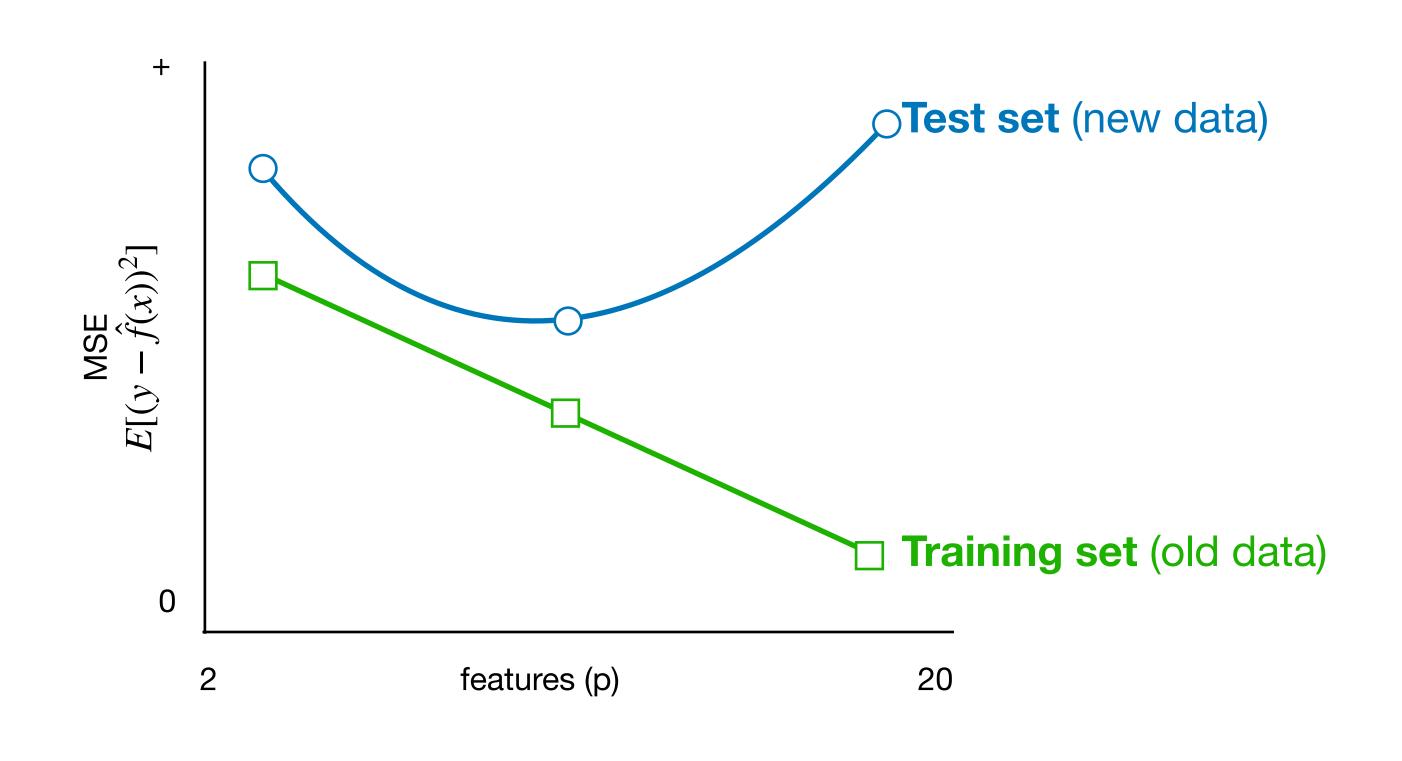
Bounding the sample size:

• as $\downarrow \epsilon \& \downarrow \delta$, or $\uparrow H$, then $\uparrow n$

$n \ge \frac{1}{\epsilon} (\ln|H| + \ln\frac{1}{\delta})$ $n \ge \frac{1}{\epsilon} (\ln|H| + \ln\frac{1}{\delta})$ e.g., complexity of model

The bias-variance tradeoff:

- $\cdot \delta \rightarrow$ Test error
- $\cdot \epsilon \rightarrow$ Training error



Take home message

- A statistical model consists of two parts: 1) a hypothesis, h, that predicts an output from an input and 2) a learner, g, that finds the best h for a given sample.
- Before running any analysis, you first must confirm whether your h (aka- model) is learnable and computable given the expected data set it will be applied to.