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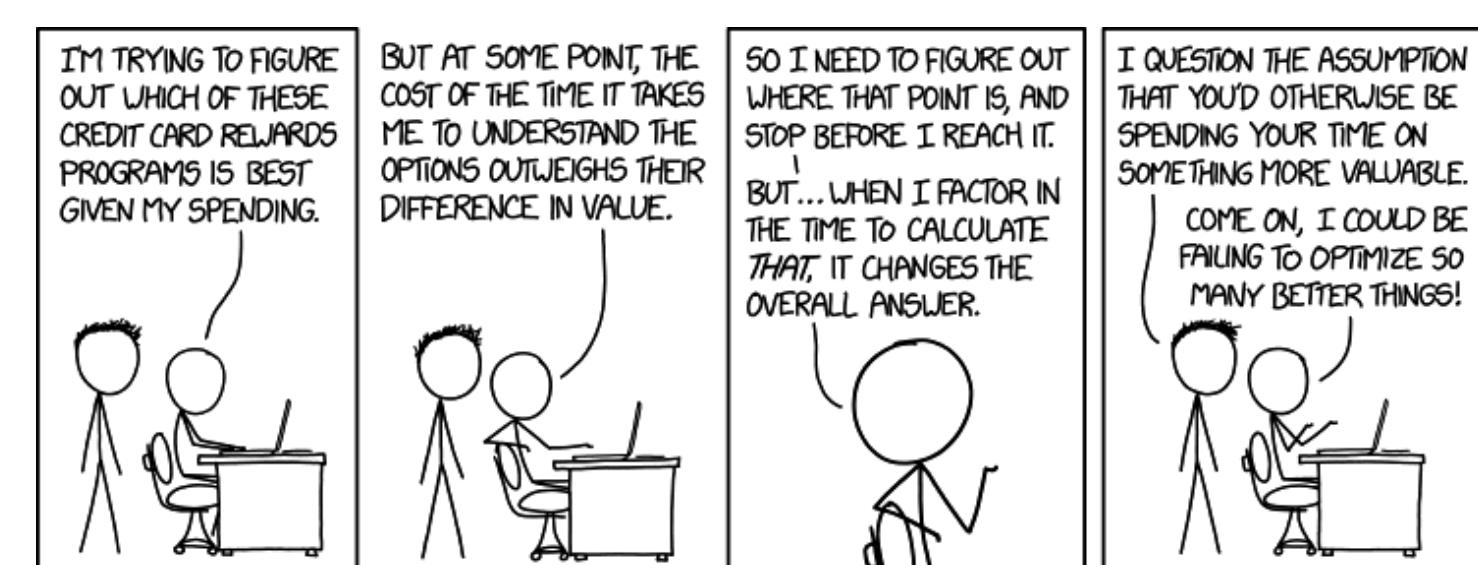
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## Introduction

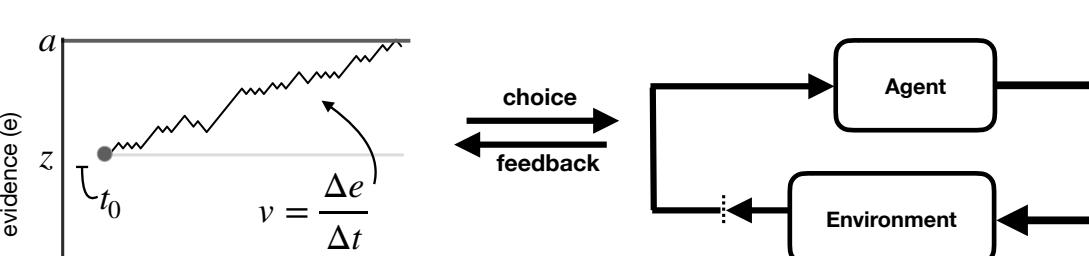
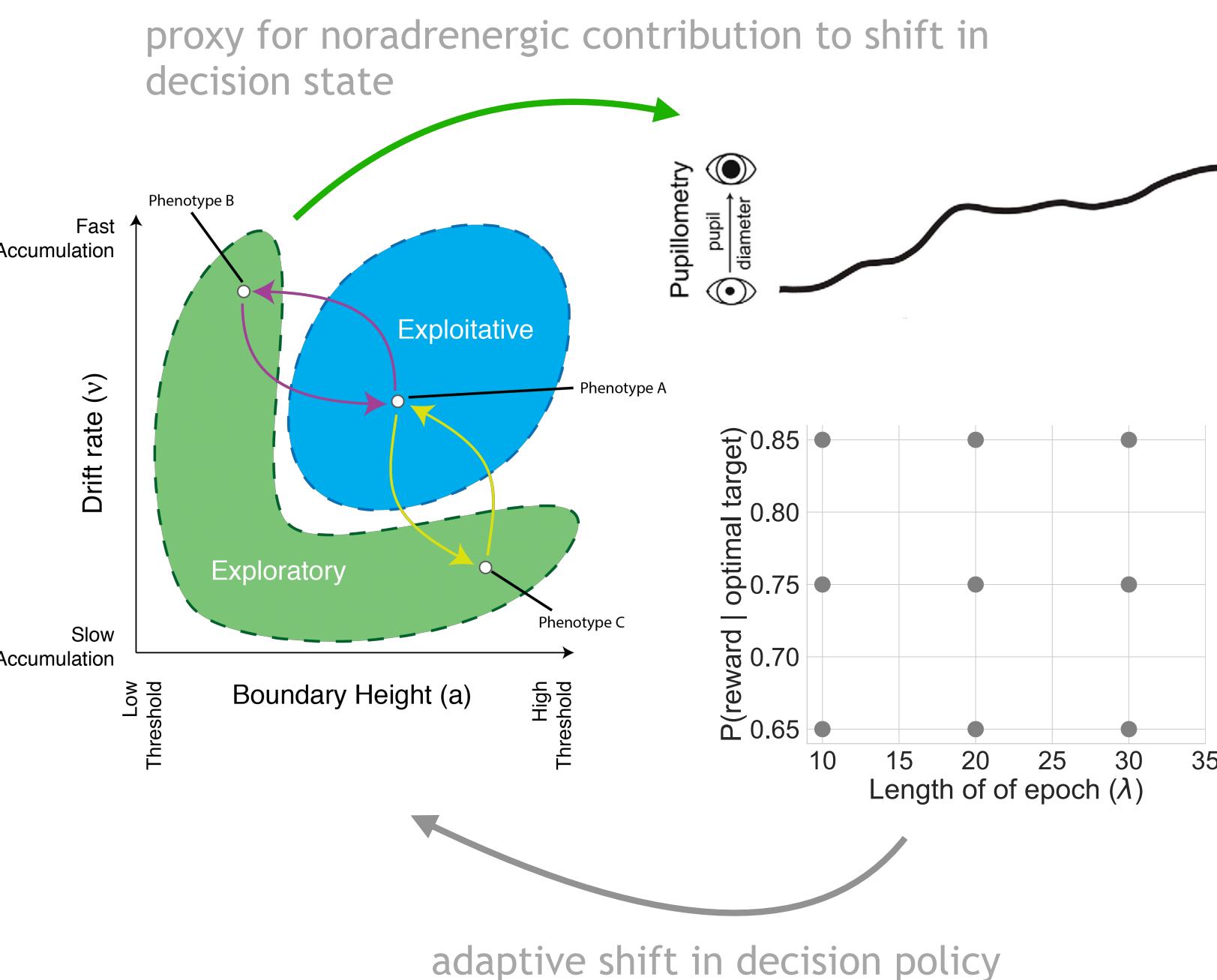
### How do we make good decisions under multiple forms of uncertainty?

**conflict:** a state of uncertainty in the relative estimate of action-value

**volatility:** sudden shifts in action-value associations over time



## Hypotheses



- The amount of evidence needed to make a decision decreases with environmental instability while the rate of evidence accumulation increases with belief in optimal choice value (Bond, Dunovan, & Verstynen, 2018)
- Hypothesized replication using a more expansive manipulation of belief and change point probability
- A phasic increase in noradrenaline will mediate the relationship between environmental instability and the amount of information needed to make a decision, facilitating the exploration process in response to change point detection.

### Relative action-value

$$\begin{aligned} B_{t+1,c} &= B_{t,c} + \alpha_t \delta_t \\ B_{t+1,u} &= B_{t,u}(1 - \Omega_t) + \Omega_t E(r) \\ E(r) &= \frac{\tilde{r}_{t_0} + \tilde{r}_t}{2} \\ B_{\Delta t+1} &= B_{t,1} - B_{t,0} \end{aligned}$$

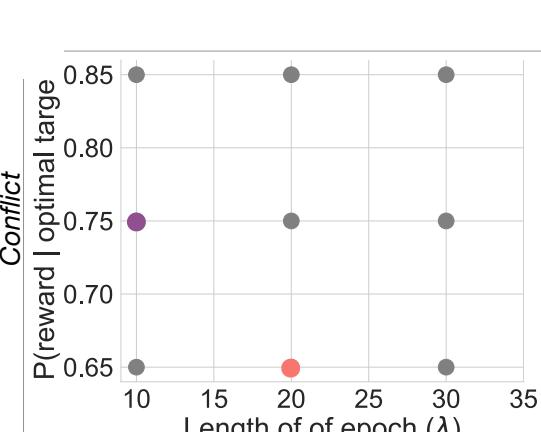
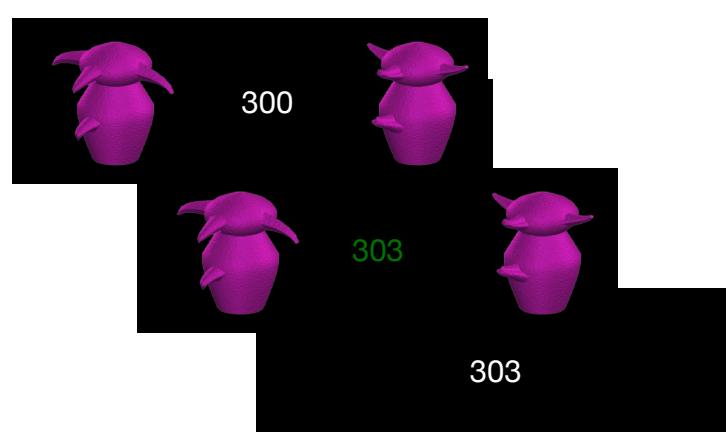
### Action-value updates

$$\begin{aligned} \Omega_t &= \frac{U(r_{\Delta t})H}{U(r_{\Delta t})H + N(r_{\Delta t}|B_{\Delta t}, \sigma_t^2)(1-H)} \\ RU_t &= \frac{\Omega_t \sigma_n^2 + (1-\Omega_t)(1-\phi_t)\sigma_n^2 + \Omega_t(1-\Omega_t)(\delta_t \phi_t)^2}{\Omega_t \sigma_n^2 + (1-\Omega_t)(1-\phi_t)\sigma_n^2 + \Omega_t(1-\Omega_t)(\delta_t \phi_t)^2 + \sigma_n^2} \\ \phi_{t+1} &= 1 - RU \end{aligned}$$

### Update rules

$$\begin{aligned} \alpha_t &= \Omega_t + (1 - \Omega)(1 - \phi_t) \\ \delta_t &= r_t - B_{t,c} \\ a_{t+1} &= \hat{\beta}_a \cdot \Omega_t + a_0 \\ \sigma_t^2 &= \sigma_n^2 + \frac{(1 - \phi_t)\sigma_n^2}{\phi_t} \\ v_{t+1} &= \hat{\beta}_v \cdot B_{\Delta t} + v_t \end{aligned}$$

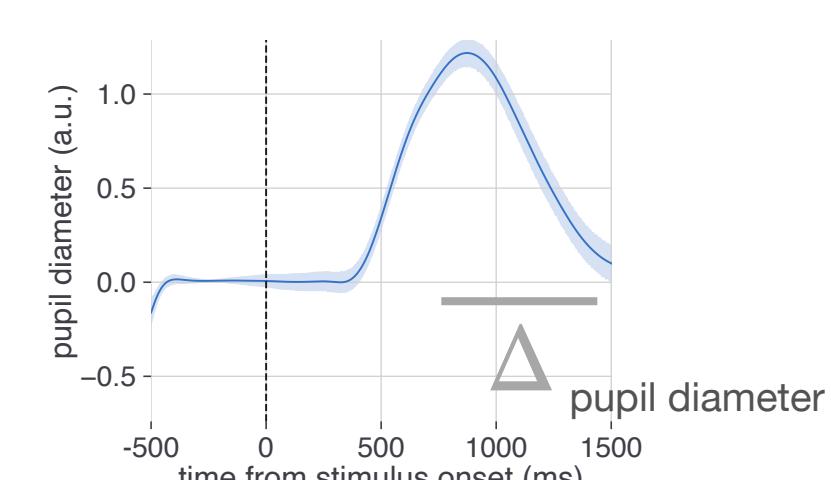
## Methods



### Task

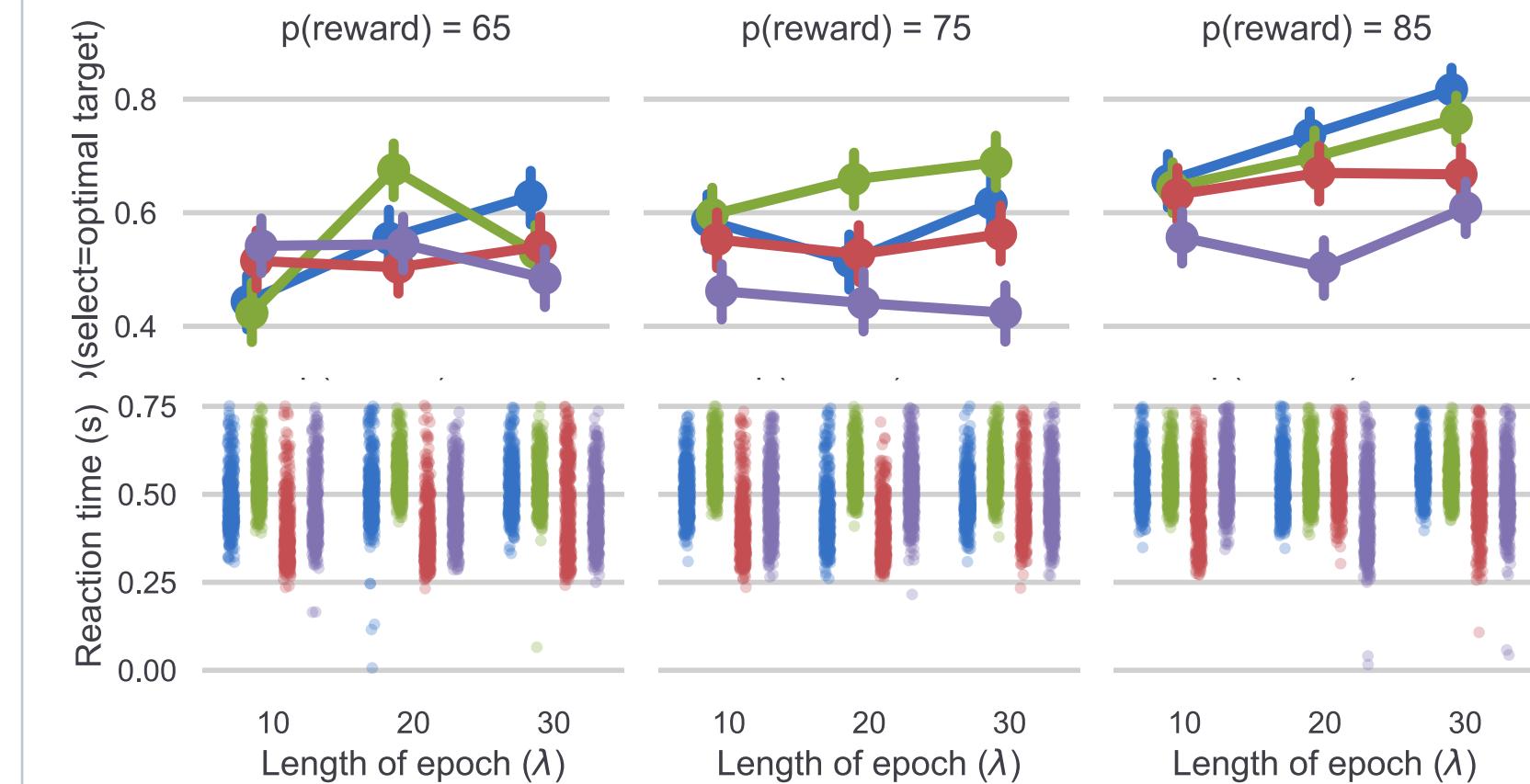
- Two-armed bandit task with constrained reaction time (.1 - .7 s)
- Within-subjects, replication-based design (N = 4)
- 400 trials per condition, 3600 trials per subject
- Manipulated expected value of rewards for each target (conflict) and how frequently the most rewarding target changed (volatility)
- Reward contingencies changed across epochs
- Participants instructed to select the sex identity of the greeble that maximized reward

### Pupillometry



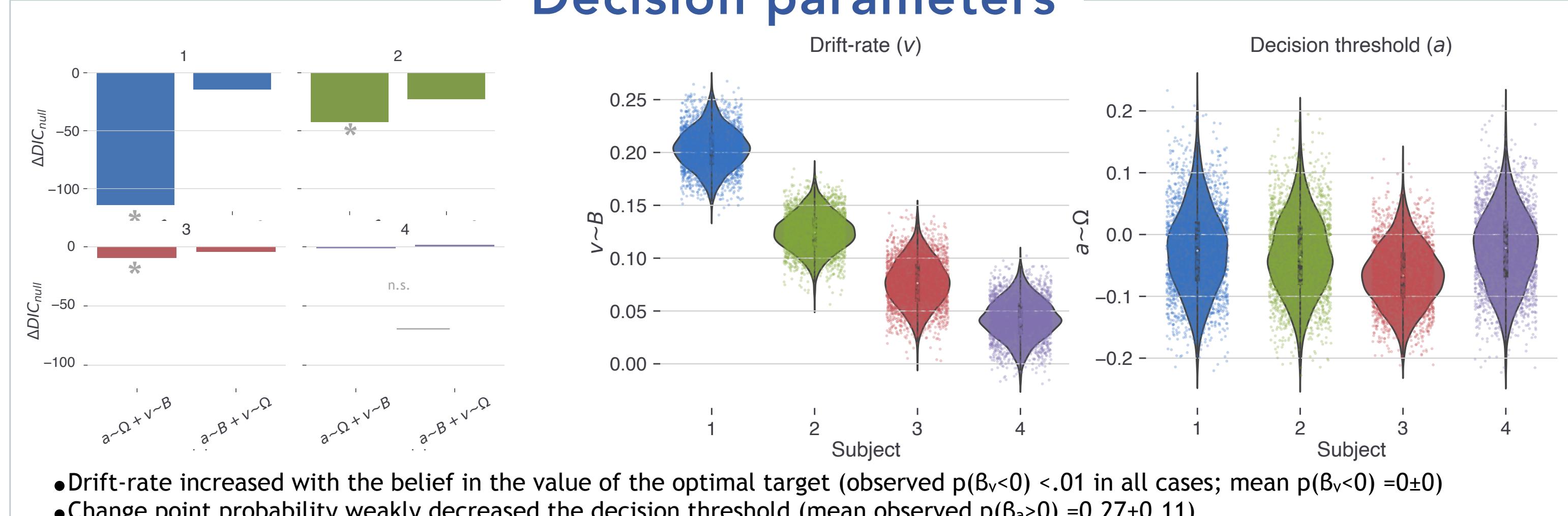
- Pupillometry data were sampled at 1 kHz
- Isoluminant conditions in a booth that minimized fluctuations in ambient light sources

## Behavior

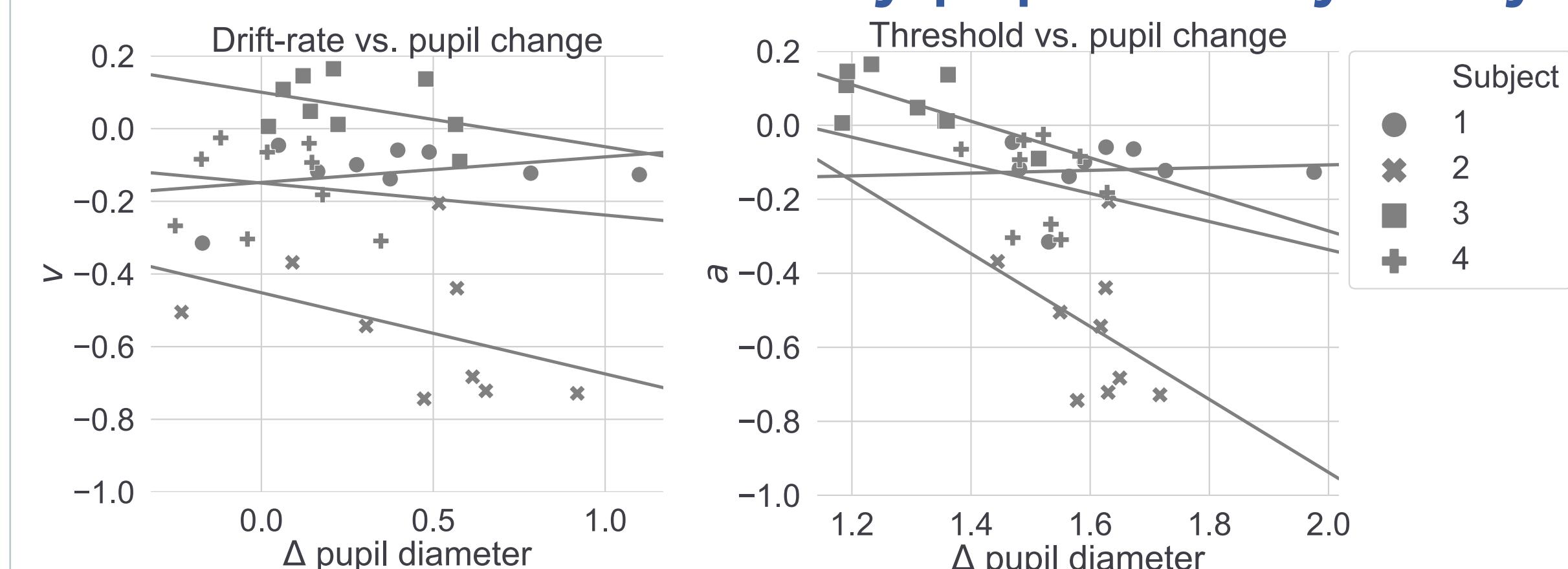


- As change point probability (CPP) increased, accuracy decreased ( $p<0.01$  in 3/4 replicates,  $B=-0.55\pm 0.24$ )
- Accuracy increased with belief in optimal target value ( $p<0.03$ ,  $B=0.00\pm 0.1$  in 4/4 subjects)
- RTs decreased as CPP increased ( $p<0.03$  in 3/4 replicates,  $B=-0.02\pm 0.01$ )
- The belief in the value of the optimal target minimally impacted RTs ( $B=0.00\pm 0.1$  in 4/4 subjects)

## Decision parameters



## Preliminary pupillometry analysis



## Conclusions and Future Directions

- Belief in the value difference between options had the greatest influence on decision processes, impacting drift-rate, while estimates of environmental change had a weak but detectable influence on the decision threshold.
- Taken together, these findings validate our previous model of adaptive decision-making showing how separate environmental signals impact different aspects of the decision algorithm. These previous findings were supported using:
  - new data
  - a more expansive sampling of the conflict and volatility space
  - a task with different superficial features
- Future work will test how phasic LC firing mediates the relationship between environmental instability and the amount of information needed to make a decision.

