## Classical Mechanics: Problem 7.6

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## Part A

For particle one,

$$F_{1x} = m_1 \ddot{x}_1$$
  
 $F_{1y} = m_1 \ddot{y}_1$   
 $F_{1x} = m_1 \ddot{z}_1$ .

For particle two,

$$F_{2x} = m_1 \ddot{x}_2$$
  
 $F_{2y} = m_1 \ddot{y}_2$   
 $F_{2x} = m_1 \ddot{z}_2$ .

## Part B

In order to create the Lagrange equations, we need to determine kinetic energy K and potential energy U for each particle. Kinetic energy for a particle is

$$K = \frac{1}{2}m_1\dot{r}_1^2 + \frac{1}{2}m_2\dot{r}_2^2.$$

We don't know what the potential is, but that shouldn't stop us from turning U in terms of force F as the problem stated. So our Langragian is,

$$\mathcal{L} = T - U$$

$$= \frac{1}{2}m_1\dot{r}_1^2 + \frac{1}{2}m_2\dot{r}_2^2 - U(r_1, r_2)$$

Our Langrange equation of motions are

$$\frac{\partial \mathcal{L}}{\partial r_1} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r_1}}, \qquad \frac{\partial \mathcal{L}}{\partial r_2} = \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r_2}}.$$

Looking at particle one, the right-hand side,

$$\frac{d}{dt}\frac{\partial \mathcal{L}}{\partial \dot{r_1}} = \frac{d}{dt} \left[ \frac{1}{2} m_1(2\dot{r_1}) \right]$$

$$= m\ddot{r_1}.$$
(1)

Now the left-hand side, the only term in  $\mathcal{L}$  that varies with  $r_1$  is potential energy. Since we know that

$$\frac{\partial \mathcal{L}}{\partial r_1} = -\nabla U(r_1).$$

Now,

$$-\nabla U(r_1) = m\ddot{r}_1$$

$$-\frac{\partial U}{\partial x}\hat{x} - \frac{\partial U}{\partial y}\hat{y} - \frac{\partial U}{\partial z}\hat{z} = m(\hat{x} + \hat{y} + \hat{z})$$
(2)

But we know that

$$-\nabla U(r_1) = F(r_1)$$

so by inspection, equation 2 becomes,

$$F_{1x} = m_1 \ddot{x}_1$$
  
 $F_{1y} = m_1 \ddot{y}_1$   
 $F_{1x} = m_1 \ddot{z}_1$ .

The exact same steps follow for particle two.