

Classical Mechanics: Problem 7.8

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Part A

From the given information, the kinetic energy for particle 1 with mass $m_1 = m$ is

$$T_1 = \frac{1}{2}m\dot{x}_1^2.$$

And the kinetic energy for particle 2 with mass $m_2 = m$ is

$$T_2 = \frac{1}{2}m\dot{x}_2^2.$$

The potential energy for a displacement of $x = (x_1 - x_2 - l)$ is

$$U = \frac{1}{2}k(x_1 - x_2 - l)^2.$$

Together, these produce a Lagrangian,

$$\mathcal{L} = \frac{1}{2}m\dot{x}_1^2 + \frac{1}{2}m\dot{x}_2^2 - \frac{1}{2}k(x_1 - x_2 - l)^2 \quad (1)$$

Part B

To get equation 1 in terms of X and x , we leverage that we have two equations, $X = \frac{1}{2}(x_1 + x_2)$ and $x = (x_1 - x_2 - l)$, with two unknowns (x_1 and x_2). First, let's solve for x_1 .

$$\begin{aligned} X &= \frac{1}{2}(x_1 + x_2) \\ x_1 &= 2X - x_2 \end{aligned}$$

Let's put this into $x = (x_1 - x_2 - l)$ to solve for x_2 ,

$$\begin{aligned} x &= (2X - x_2) - x_2 - l \\ x_2 &= -\frac{(x + l - 2X)}{2} \\ &= X - \frac{x}{2} - \frac{l}{2} \end{aligned}$$

Great! Now take the derivative of this so we can input into equation 1.

$$\dot{x}_2 = \dot{X} - \frac{\dot{x}}{2} - 0$$

All that is left is using our expression for x_2 to solve for an expression for x_1 that is only in terms of X and x . Starting with our expression for x_1

$$\begin{aligned} x_1 &= 2X - \left(X - \frac{x}{2} - \frac{l}{2}\right) \\ &= X + \frac{x}{2} + \frac{l}{2} \end{aligned}$$

and taking the derivative,

$$\dot{x}_1 = \dot{X} + \frac{\dot{x}}{2} + 0.$$

Finally, making the substitutions for x , \dot{x}_1 , and \dot{x}_2 into equation 1,

$$\begin{aligned} \mathcal{L} &= \frac{1}{2}m\dot{x}_1^2 + \frac{1}{2}m\dot{x}_2^2 - \frac{1}{2}k(x_1 - x_2 - l)^2 \\ &= \frac{1}{2}m\left(\dot{X} + \frac{1}{2}\dot{x}\right)^2 + \frac{1}{2}m\left(\dot{X} - \frac{1}{2}\dot{x}\right)^2 - \frac{1}{2}kx^2 \\ &= m\dot{X}^2 + \frac{1}{4}m\dot{x}^2 - \frac{1}{2}kx^2 \\ &= \frac{1}{4}m[4\dot{X}^2 + \dot{x}^2] - \frac{1}{2}kx^2 \end{aligned}$$

Great. Now we can start working on the Lagrange equations. For X ,

$$\begin{aligned}
\frac{\partial \mathcal{L}}{\partial \dot{X}} &= \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \ddot{X}} \\
\frac{\partial}{\partial \dot{X}} \left[\frac{1}{4} m (4\dot{X}^2 + \dot{x}^2) - \frac{1}{2} k x^2 \right] &= \frac{\partial}{\partial t} \frac{\partial}{\partial \ddot{X}} \left[\frac{1}{4} m (4\dot{X}^2 + \dot{x}^2) - \frac{1}{2} k x^2 \right] \\
0 &= \frac{\partial}{\partial t} \left[\frac{1}{4} m (8\ddot{X} + 0) - 0 \right] \\
&= \frac{\partial}{\partial t} [2m\ddot{X}] \\
&= 2m\ddot{\ddot{X}}
\end{aligned}$$

Thus,

$$\ddot{\ddot{X}} = 0. \quad (2)$$

For x ,

$$\begin{aligned}
\frac{\partial \mathcal{L}}{\partial \dot{x}} &= \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \ddot{x}} \\
\frac{\partial}{\partial \dot{x}} \left[\frac{1}{4} m (4\dot{x}^2 + \dot{X}^2) - \frac{1}{2} k x^2 \right] &= \frac{\partial}{\partial t} \frac{\partial}{\partial \ddot{x}} \left[\frac{1}{4} m (4\dot{x}^2 + \dot{X}^2) - \frac{1}{2} k x^2 \right] \\
-\frac{2}{2} k x &= \frac{\partial}{\partial t} \left[\frac{1}{4} m (0 + 2\ddot{x}) - 0 \right] \\
-kx &= \frac{\partial}{\partial t} \left[\frac{1}{2} m \ddot{x} \right] \\
&= \frac{1}{2} m \ddot{\ddot{x}}.
\end{aligned}$$

Thus,

$$\ddot{\ddot{x}} = - \left(\frac{2k}{m} \right) x.$$

Part C

The general solution by integration to $\ddot{\ddot{X}} = 0$ for some initial velocity v_0 and center of mass position X_0 ,

$$\begin{aligned}
\ddot{\ddot{X}} &= 0 \\
\dot{\ddot{X}} &= v_0 \\
\ddot{X}(t) &= v_0 t + x_0.
\end{aligned}$$

The general solution to $\ddot{x} = -\left(\frac{2k}{m}\right)x$ is something we've seen lots of time before. The fact that our potential energy was $\frac{1}{2}kx^2$ should have hinted that this is a oscillator of the form $\ddot{x} = -\omega^2 x$, which has the general solution

$$x(t) = A \cos(\omega t + \phi)$$

where A is the amplitude, $\omega = \sqrt{\frac{2k}{m}}$, and ϕ is the phase.

What this means is that the two connected particles will oscillator relative to each other, but the center of mass $X(t)$ moves as a regular free particle!