

Comp Sci, Dec 13, 2022

Taylor expand  $C(\beta)$

$$(\hat{\beta} = \beta)$$

$$C(\beta) \approx C(\beta^{(n)}) + g^{(n)T} (\beta - \beta^{(n)}) \\ + \frac{1}{2} (\beta - \beta^{(n)})^T H^{(n)} (\beta - \beta^{(n)})$$

$$\beta = \beta^{(n)} - H^{(n)-1} g^{(n)}$$

$\swarrow$   
 $\gamma^{(n)} = \text{learning rate}$

$$\beta = \beta^{(n)} - \gamma g^{(n)}$$

Expand around this value

$$C(\beta^{(n)} - \gamma g^{(n)}) = C(\beta^{(n)}) \\ - \gamma g^{(n)T} g^{(n)} + \frac{1}{2} \gamma^2 g^{(n)T} H^{(n)} g^{(n)} + \dots$$

Truncate at  $\gamma^2$ .

optimal  $\gamma$   $\frac{\partial C}{\partial \gamma} = 0$

$$\gamma = \frac{g^T g}{g^T H g}$$

Taylor expansion problems  
when  $g^T H g > g^T g$

Assume  $g$  is an eigenvector  
of  $H$

$$H g = \lambda \cdot g \quad g^T g = 1$$

$$\gamma = \frac{1}{\lambda}$$

smallest step size ( $\gamma$ ) given

by  $\gamma = \frac{1}{\lambda_{\max}}$

Largest learning rate/step size  
given by

$$\gamma = \frac{1}{\lambda_{\min}}$$

Can show  $\gamma < \frac{2}{\lambda_{\max}}$

$\lambda$  is eigenvalue of  $H$

Steepest descent

$$f(x) = \frac{1}{2} x^T A x - x^T b$$

$$\frac{\partial f}{\partial x} = 0 = Ax - b \Rightarrow$$

$$Ax = b$$

Define residual  $r = b - Ax$

have solution when  $r = 0$

Start with a guess for

$$x = x_0$$

$$r_0 = b - Ax_0$$

in general

$$r_{k+1} = b - Ax_{k+1}$$

$$x_{k+1} = x_k + \alpha_k r_k$$

$$\begin{aligned}
 r_{k+1} &= b - A(x_k + \alpha_k r_k) \\
 &= \underbrace{(b - Ax_k)}_{r_k} - \alpha_k A r_k \\
 &= r_k - \alpha_k A r_k
 \end{aligned}$$

$$r_{k+1} = 0$$

$$\begin{aligned}
 r_k^T r_{k+1} &= 0 = r_k^T r_k - \alpha_k r_k^T A r_k \\
 \Rightarrow \alpha_k &= \frac{r_k^T r_k}{r_k^T A r_k} \quad A = \text{Hessian}
 \end{aligned}$$

$$\begin{aligned}
 x_{k+1} &= x_k + \alpha_k r_k \\
 &\quad \uparrow \\
 &\quad \text{plays the role} \\
 &\quad \text{of the gradient} \\
 &\quad g(\beta^{(n)})
 \end{aligned}$$

$$(\beta_{k+1} = \beta_k - \gamma_k g_k)$$

Gradient descent with momentum

particle moving in a field

$$F = - \nabla V(x)$$

$$m \frac{d^2 x}{dt^2} + \underset{\substack{\uparrow \\ \text{drag/friction} \\ \text{etc}}}{\mu} \frac{dx}{dt} = - \nabla V(x)$$

discretize second derivative

$$\frac{d^2 x}{dt^2} \approx \frac{x_{t+\Delta t} - 2x_t + x_{t-\Delta t}}{(\Delta t)^2}$$

$$\frac{dx}{dt} \approx \frac{x_{t+\Delta t} - x_t}{\Delta t}$$

$$m \frac{(x_{t+\Delta t} - 2x_t + x_{t-\Delta t}))}{(\Delta t)^2} + \mu \frac{(x_{t+\Delta t} - x_t)}{\Delta t} = - \nabla V(x)$$

$$\Delta x_{t+\Delta t} = x_{t+\Delta t} - x_t$$

$$\Delta x_t = x_t - x_{t-\Delta t}$$

$$\Delta X_{t+\Delta t} = - \frac{(\Delta t)^2}{m+\mu\Delta t} \vec{\nabla} V(\mathbf{x})$$

$$+ \frac{m}{m+\mu\Delta t} \Delta X_t$$

$$\delta = \frac{m}{m+\mu\Delta t} \quad \wedge \quad \gamma = \frac{(\Delta t)^2}{m+\mu\Delta t}$$

$$\Delta X_{t+\Delta t} = -\gamma \vec{\nabla} V(\mathbf{x}) + \delta \Delta X_t$$

$$x_t \rightarrow \beta_i \quad x_{t+\Delta t} \Rightarrow \beta_{i+1}$$

$$\Delta \beta_{i+1} = \beta_{i+1} - \beta_i$$

$$\beta_{i+1} = \beta_i - \gamma g(\beta_i) + \delta (\beta_i - \beta_{i-1})$$

Memory  
term