

# Distance Metric Learning Formula

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Because there is no detailed derivation processes for the first derivative and second derivative used in Newton-Raphson update rule. Here we give a little more information about the how to get first derivative and Hessian Matrix.

$$g(A) = g(A_{11}, \dots, A_{nn}) = \sum_S \|x_i - x_j\|_A^2 - \log(\sum_D \|x_i - x_j\|_A)$$

Let

$$x_{ij} = [(x_{i1} - x_{j1})^2, \dots, (x_{id} - x_{jd})^2]^T$$
$$A = [A_{11}, \dots, A_{dd}]$$

Here

$$\|x_i - x_j\|_A^2 = (x_i - x_j)^T A (x_i - x_j) = x_{ij}^T A$$
$$g(A) = \sum_S x_{ij}^T A - \log(\sum_D (x_{ij}^T A)^{\frac{1}{2}})$$

Then

$$g'(A) = \sum_S x_{ij}^T A - \log(\sum_D (x_{ij}^T A)^{\frac{1}{2}})$$
$$= \sum_S x_{ij} - \frac{1}{\sum_D (x_{ij}^T A)^{\frac{1}{2}}} \sum_D \frac{1}{2} (x_{ij}^T A)^{-\frac{1}{2}} x_{ij}$$

$g'(A)$  is a vector with the same size as  $A$ . In this case, we want to use Newton-Raphson method to get the parameter  $A$ , so we need to derivate the Hessian Matrix ( $g''(A)$ ) to be used in the update rule. Here we give the derivation as follows.

$$\begin{aligned}
g''(A) &= \partial g'(A)^T / \partial A \\
&= \partial [-[\sum_D (x_{ij}^T A)^{\frac{1}{2}}]^{-1} \sum_D \frac{1}{2} (x_{ij}^T A)^{-\frac{1}{2}} x_{ij}^T] / \partial A \\
&= [\sum_D (x_{ij}^T A)^{\frac{1}{2}}]^{-2} \sum_D \frac{1}{2} (x_{ij}^T A)^{\frac{1}{2}} x_{ij} \sum_D \frac{1}{2} (x_{ij}^T A)^{-\frac{1}{2}} x_{ij}^T - \\
&\quad [\sum_D (x_{ij}^T A)^{\frac{1}{2}}]^{-1} \sum_D -\frac{1}{4} (x_{ij}^T A)^{-\frac{3}{2}} x_{ij} x_{ij}^T
\end{aligned}$$