

Lambdas from First Principles

A Whirlwind Tour of C++

Plain old functions

```
int plus1(int x)
{
    return x+1;
}
```

```
__Z5plus1i:
    leal 1(%rdi), %eax
    retq
```

Function overloading

```
int plus1(int x)
{
    return x+1;
}
```

```
double plus1(double x)
{
    return x+1;
}
```

```
__Z5plus1i:
    leal  1(%rdi), %eax
    retq

__Z5plus1d:
    addsd LCPI1_0(%rip), %xmm0
    retq
```

Function templates

```
template<typename T>
T plus1(T x)
{
    return x+1;
}
```

```
auto y = plus1(42);
auto z = plus1(3.14);
```

```
__Z5plus1IiET_S0_:
    leal    1(%rdi), %eax
    retq

__Z5plus1IdET_S0_:
    addsd   LCPI1_0(%rip), %xmm0
    retq
```

Class member functions

```
class Plus {  
    int value;  
public:  
    Plus(int v);  
  
    int plusme(int x) const {  
        return x + value;  
    }  
};
```

```
__ZN4PlusC1Ei:  
    movl %esi, (%rdi)  
    retq
```

```
__ZN4Plus6plusmeEi:  
    addl (%rdi), %esi  
    movl %esi, %eax  
    retq
```

“Which function do we call?”

```
auto plus = Plus(1);  
auto x = plus.plusme(42);  
  
assert(x == 43);
```

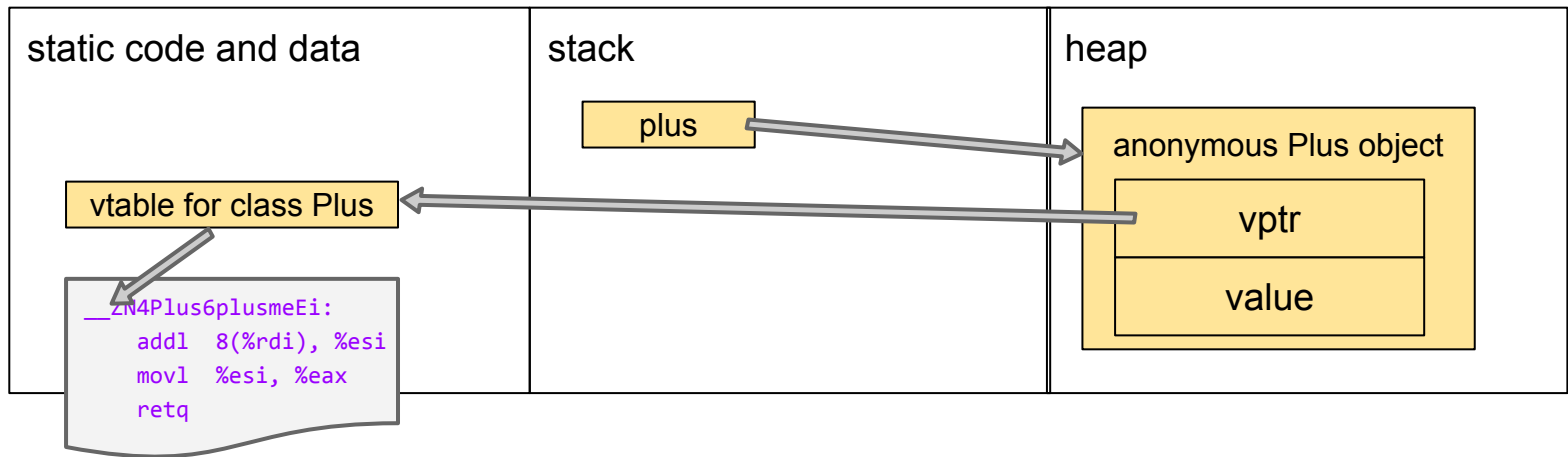
“The plusme function of the Plus class”

C++ is not Java!

The Java approach

```
auto plus = Plus(1);  
auto x = plus.plusme(42);  
assert(x == 43);
```

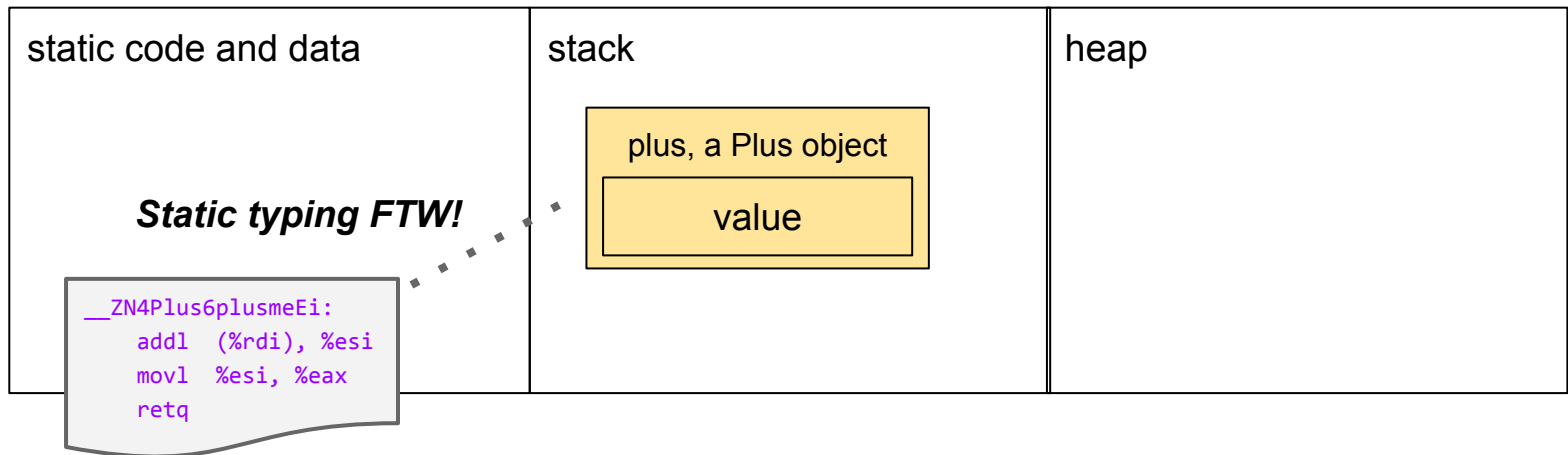
C++ lets you do this,
but it's not the default.



The C++ approach

```
auto plus = Plus(1);  
auto x = plus.plusme(42);  
assert(x == 43);
```

```
movl  $1, %esi  
leaq  -16(%rbp), %rdi  
callq __ZN4PlusC1Ei  
movl  $42, %esi  
leaq  -16(%rbp), %rdi  
callq __ZN4Plus6plusmeEi
```



Class member functions (recap)

```
class Plus {  
    int value;  
public:  
    Plus(int v);  
  
    int plusme(int x) const {  
        return x + value;  
    }  
};
```

```
__ZN4PlusC1Ei:  
    movl %esi, (%rdi)  
    retq
```

```
__ZN4Plus6plusmeEi:  
    addl (%rdi), %esi  
    movl %esi, %eax  
    retq
```

```
auto plus = Plus(1);  
auto x = plus.plusme(42);
```

Operator overloading

```
class Plus {  
    int value;  
public:  
    Plus(int v);  
  
    int operator() (int x) const {  
        return x + value;  
    }  
};
```

```
__ZN4PlusC1Ei:  
    movl %esi, (%rdi)  
    retq
```

```
__ZN4PlusclEi:  
    addl (%rdi), %esi  
    movl %esi, %eax  
    retq
```

```
auto plus = Plus(1);  
auto x = plus(42);
```

**So now we can make
something kind of nifty...**

Lambdas reduce boilerplate

```
class Plus {  
    int value;  
public:  
    Plus(int v): value(v) {}  
  
    int operator() (int x) const {  
        return x + value;  
    }  
};
```

```
auto plus = Plus(1);  
assert(plus(42) == 43);
```

Lambdas reduce boilerplate

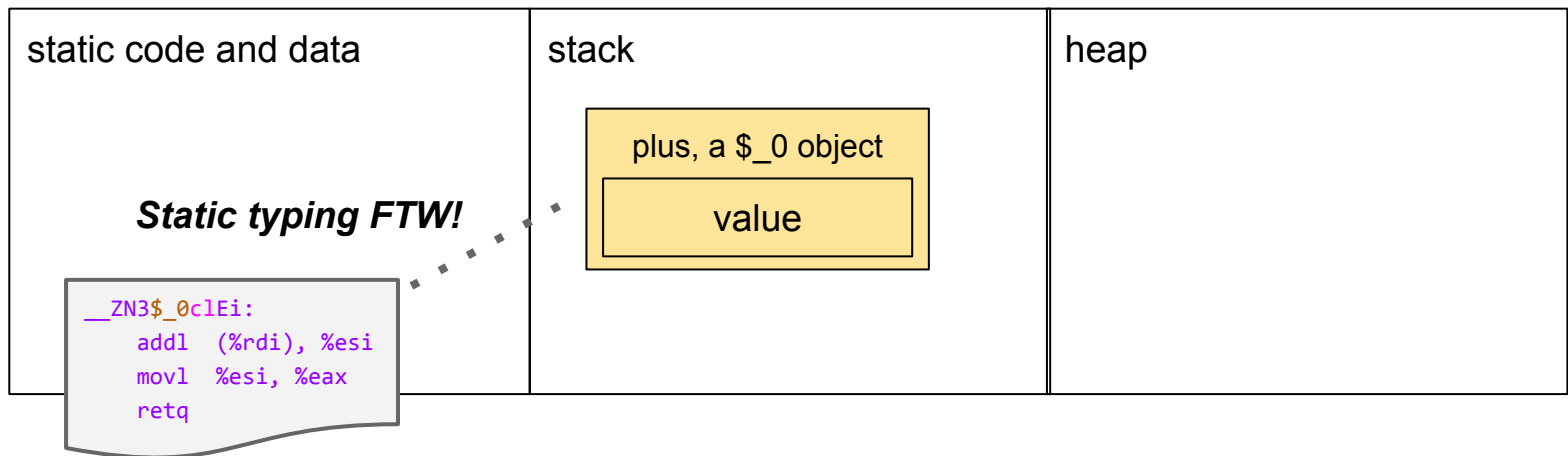
```
auto plus = [value=1](int x) { return x + value; };
```

```
assert(plus(42) == 43);
```

Same implementation

```
auto plus = [value=1](int x) {  
    return x + value;  
};
```

```
movl  $1, %esi  
leaq  -16(%rbp), %rdi  
callq __ZN3$_0clEi  
movl  $42, %esi  
leaq  -16(%rbp), %rdi  
callq __ZN3$_0clEi
```



Closures without garbage collection

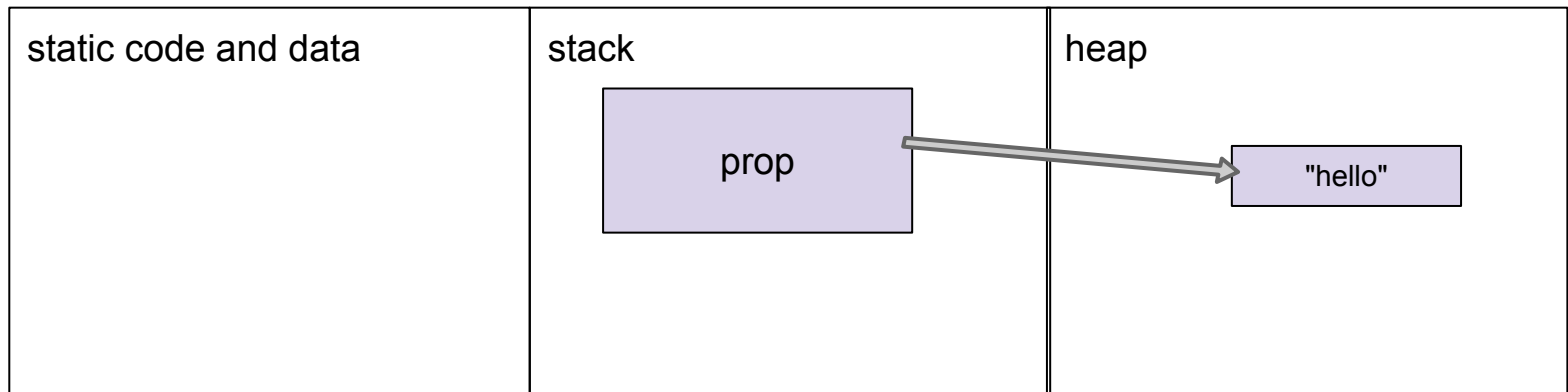
```
using object = std::map<std::string, int>;

void sort_by_property(std::vector<object>& v, std::string prop)
{
    auto pless = [p=prop](object& a, object& b) {
        return a[p] < b[p];
    };

    std::sort(v.begin(), v.end(), pless);
}
```

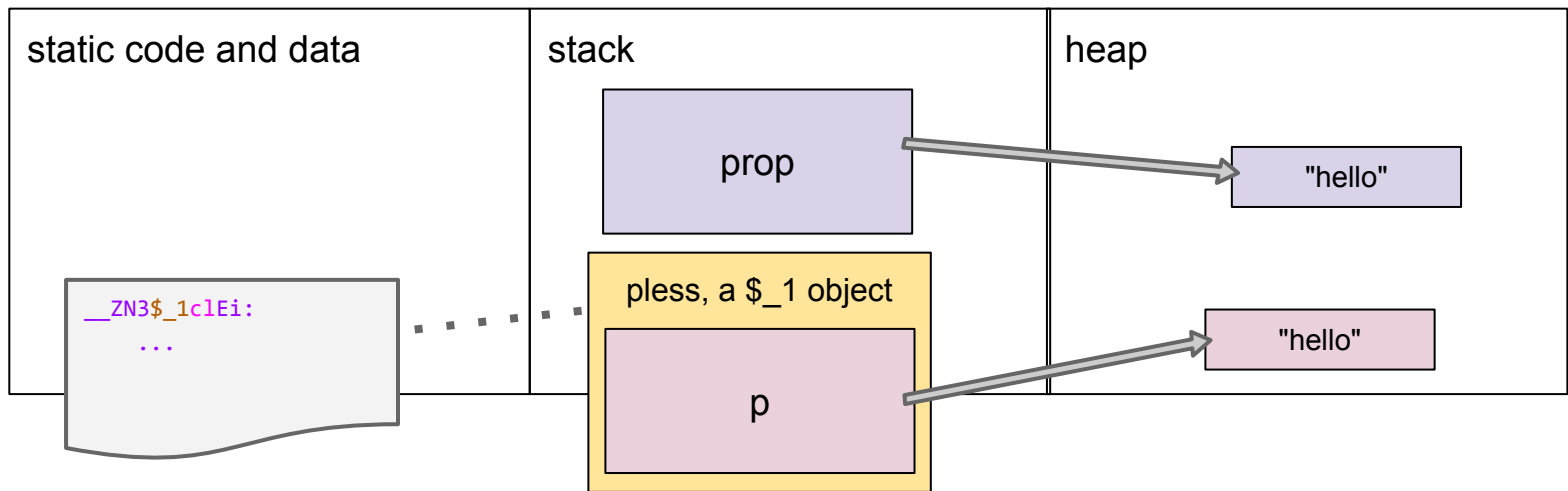

Closures without garbage collection

... std::string prop ...



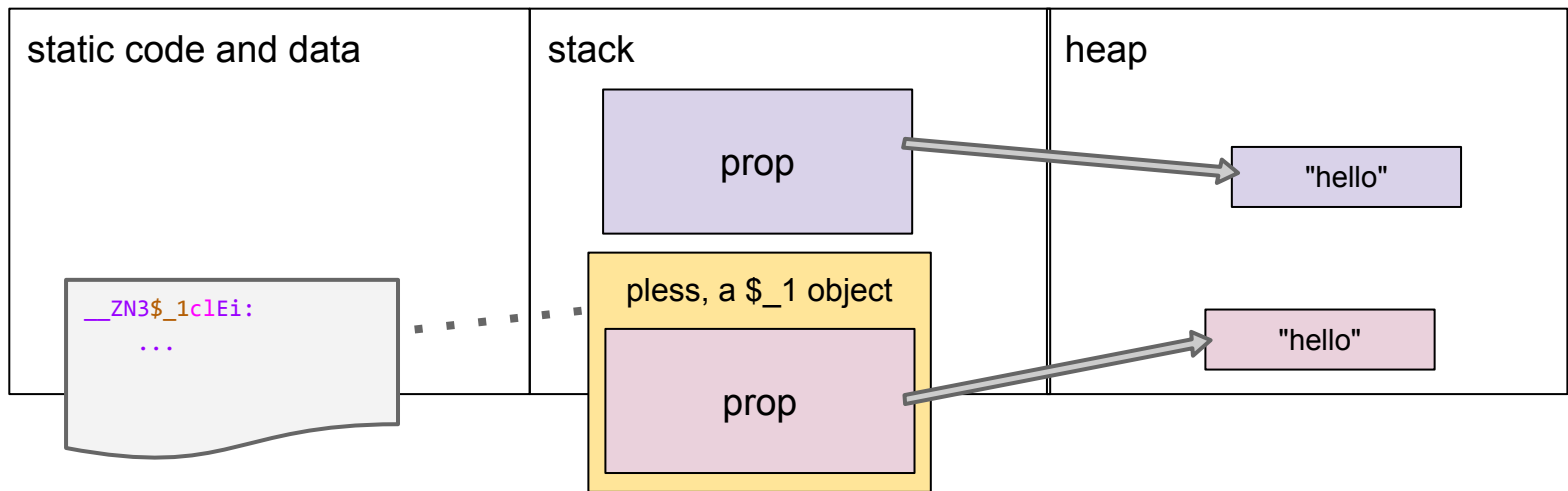
Closures without garbage collection

```
... std::string prop ...  
    auto pless = [p=prop](object& a, object& b) {  
        return a[p] < b[p];  
    };  
};
```



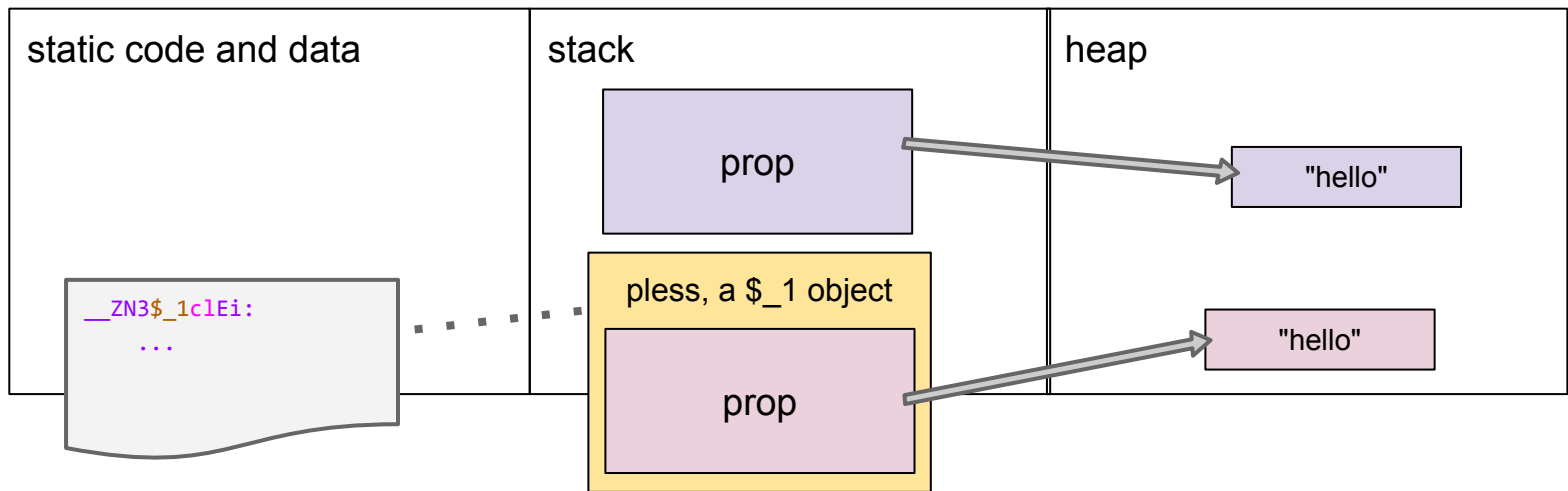
Closures without garbage collection

```
... std::string prop ...  
    auto pless = [prop](object& a, object& b) {  
        return a[prop] < b[prop];  
    };
```



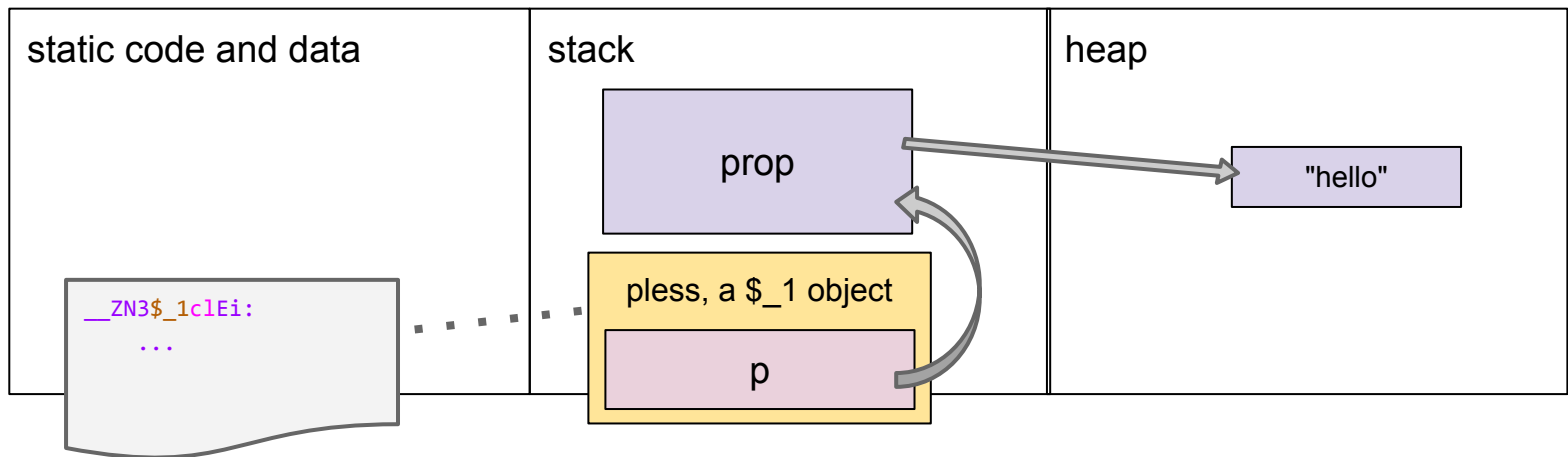
Copy semantics by default

```
... std::string prop ...  
    auto pless = [=](object& a, object& b) {  
        return a[prop] < b[prop];  
    };
```



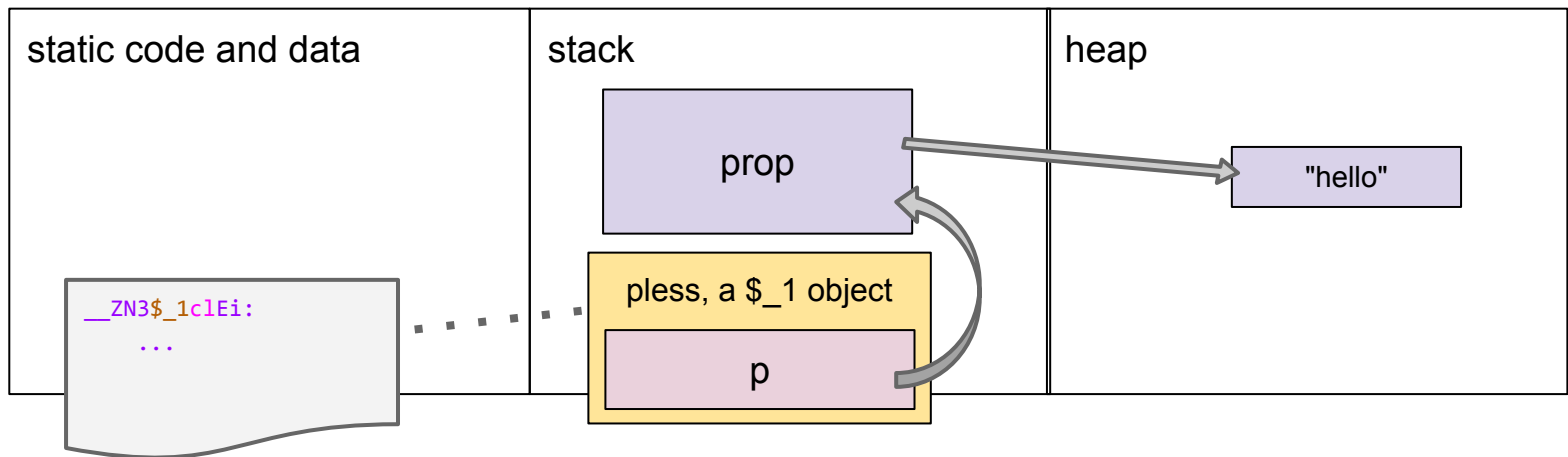
Capturing a reference

```
... std::string prop ...  
    auto pless = [p=?????](object& a, object& b) {  
        return a[p] < b[p];  
    };  
};
```



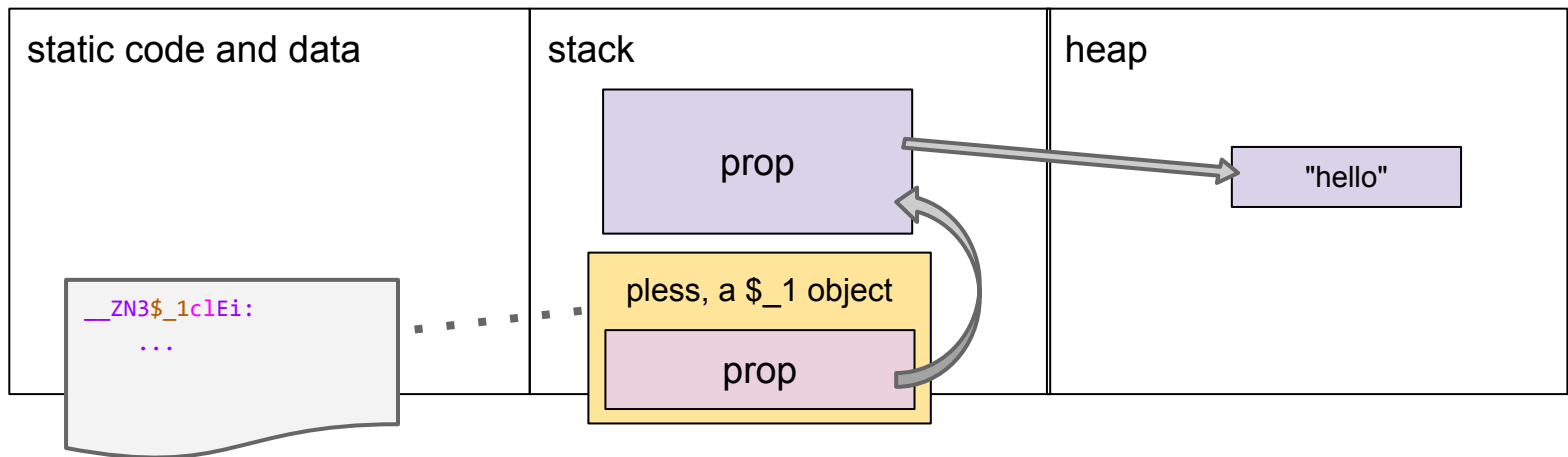
Capturing by reference

```
... std::string prop ...  
    auto pless = [&p=prop](object& a, object& b) {  
        return a[p] < b[p];  
    };
```



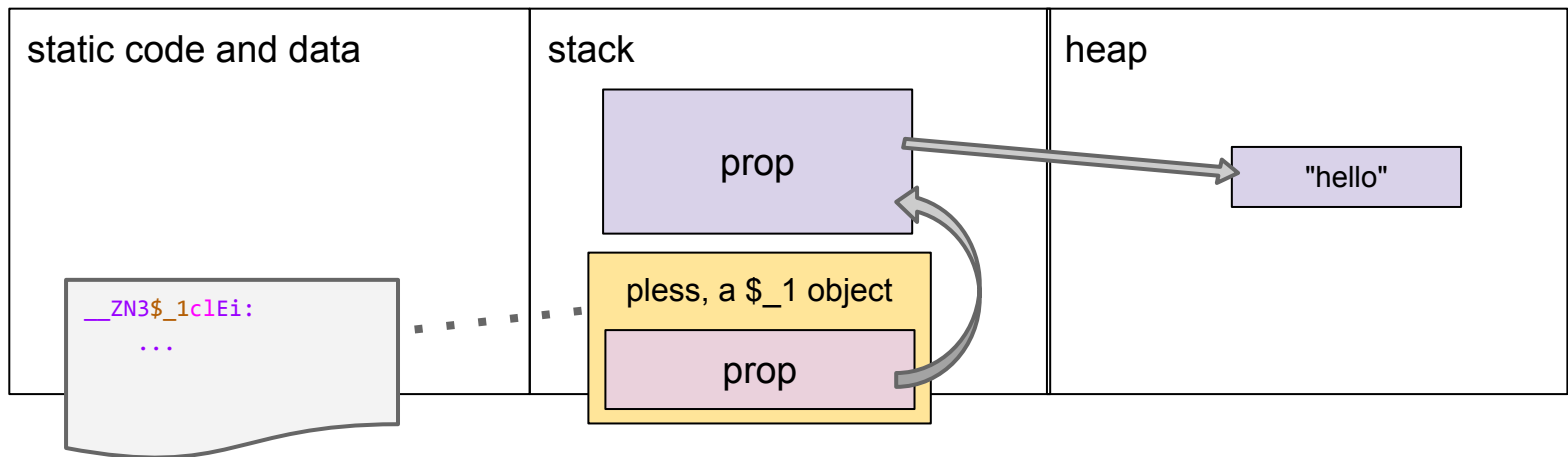
Capturing by reference

```
... std::string prop ...  
    auto pless = [&prop](object& a, object& b) {  
        return a[prop] < b[prop];  
    };
```



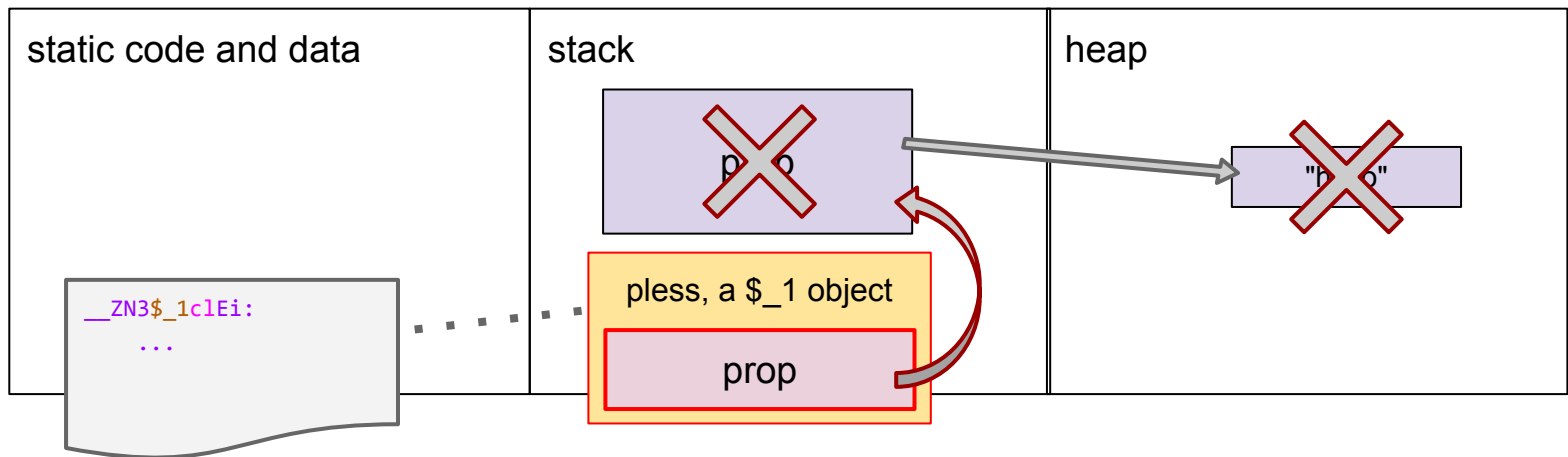
Capturing by reference

```
... std::string prop ...  
    auto pless = [&](object& a, object& b) {  
        return a[prop] < b[prop];  
    };
```



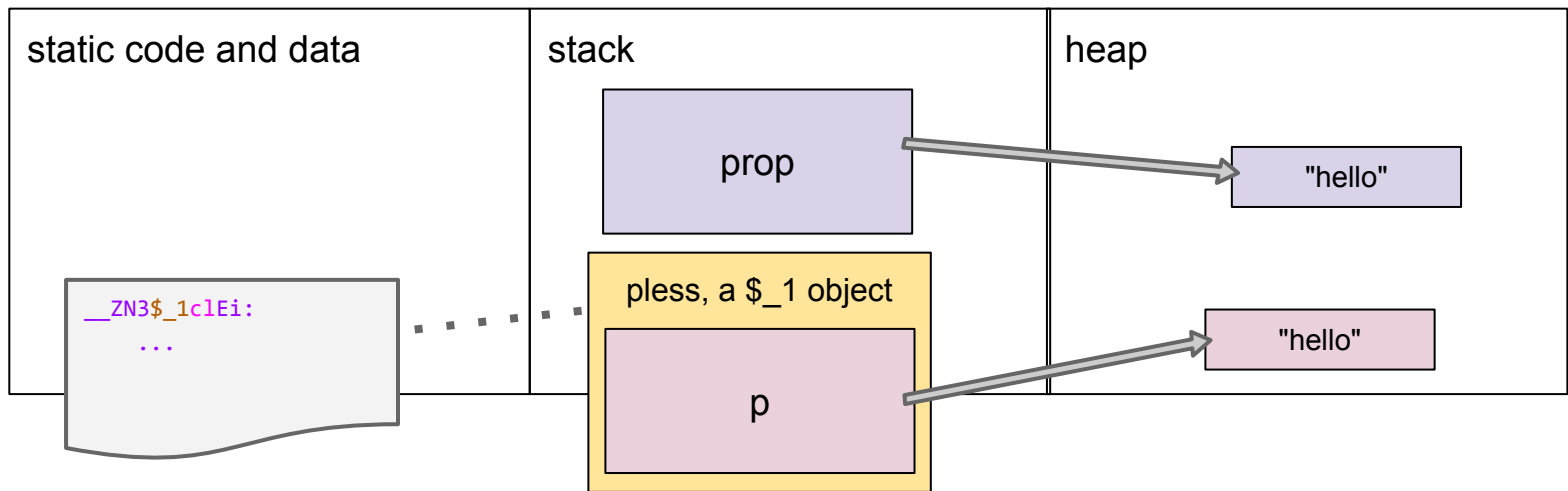
Beware of dangling references

```
... std::string prop ...  
    auto pless = [&](object& a, object& b) {  
        return a[prop] < b[prop];  
    };
```



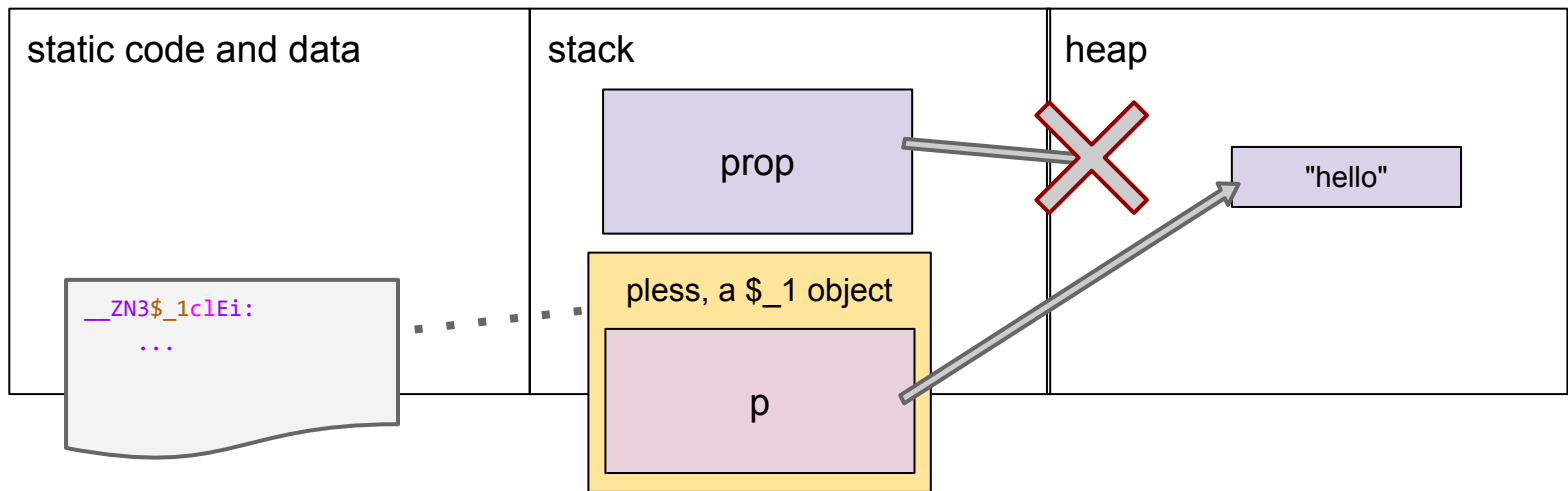
Capturing “by move”

```
... std::string prop ...  
    auto pless = [p=prop](object& a, object& b) {  
        return a[p] < b[p];  
    };
```



Capturing “by move”

```
... std::string prop ...  
    auto pless = [p=std::move(prop)](object& a, object& b) {  
        return a[p] < b[p];  
    };
```



Other features of lambdas

- Convertible to raw function pointer
(when there are no captures involved)
- Variables with file/global scope are not captured
- Lambdas may have local state
(but not in the way you think)

Puzzle

```
#include <stdio.h>
```

```
int g = 10;
```

```
auto kitten = [=]() { return g+1; };
```

```
auto cat = [g=g]() { return g+1; };
```

```
int main() {
```

```
    g = 20;
```

```
    printf("%d %d\n", kitten(), cat());
```

```
}
```

Puzzle

```
#include <stdio.h>
```

```
int g = 10;
```

```
auto kitten = [=]() { return g+1; };
```

```
auto cat = [g=g]() { return g+1; };
```

```
int main() {
```

```
    g = 20;
```

```
    printf("21 11\n", kitten(), cat());
```

```
}
```

Puzzle footnote

```
int g = 10;  
auto ocelot = [g]() { return g+1; };
```

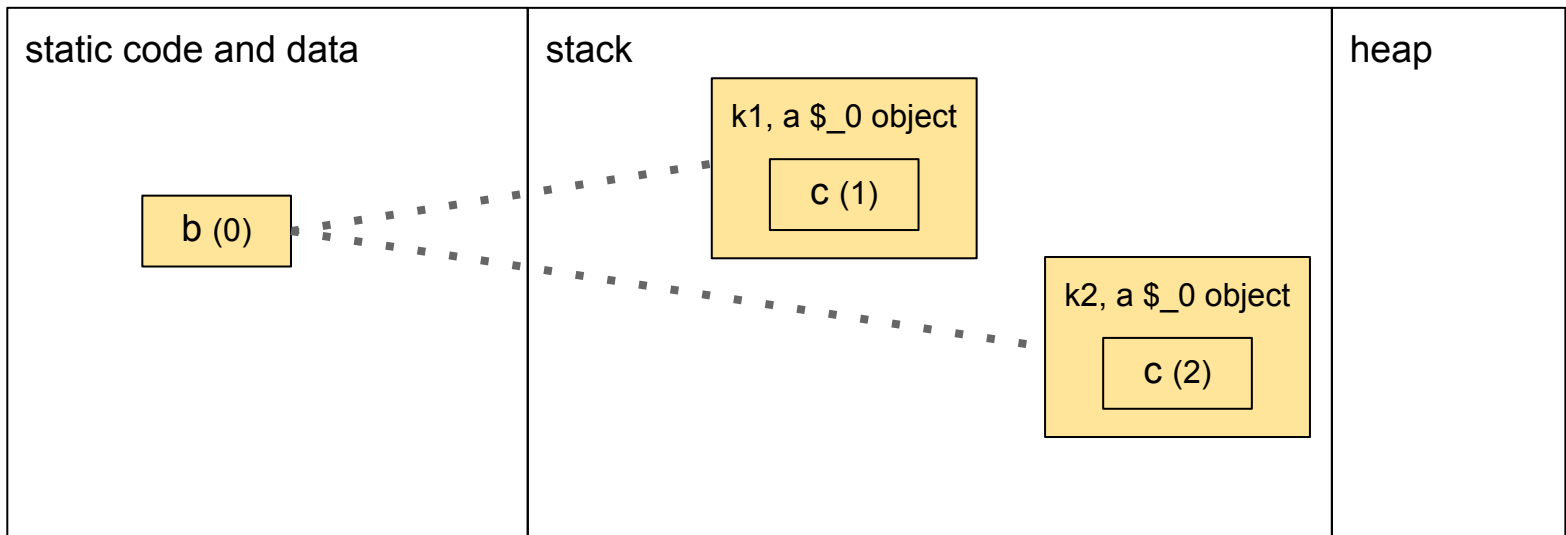
The above is ill-formed and requires a diagnostic.

5.1.2 [expr.prim.lambda]/10: The *identifier* in a *simple-capture* is looked up using the usual rules for unqualified name lookup (3.4.1); each such lookup **shall** find an entity. An entity that is designated by a *simple-capture* is said to be *explicitly captured*, and **shall** be this or a variable **with automatic storage duration** declared in the reaching scope of the local lambda expression.

In GCC this is just a warning, and the lambda does *not* capture *g*'s value.

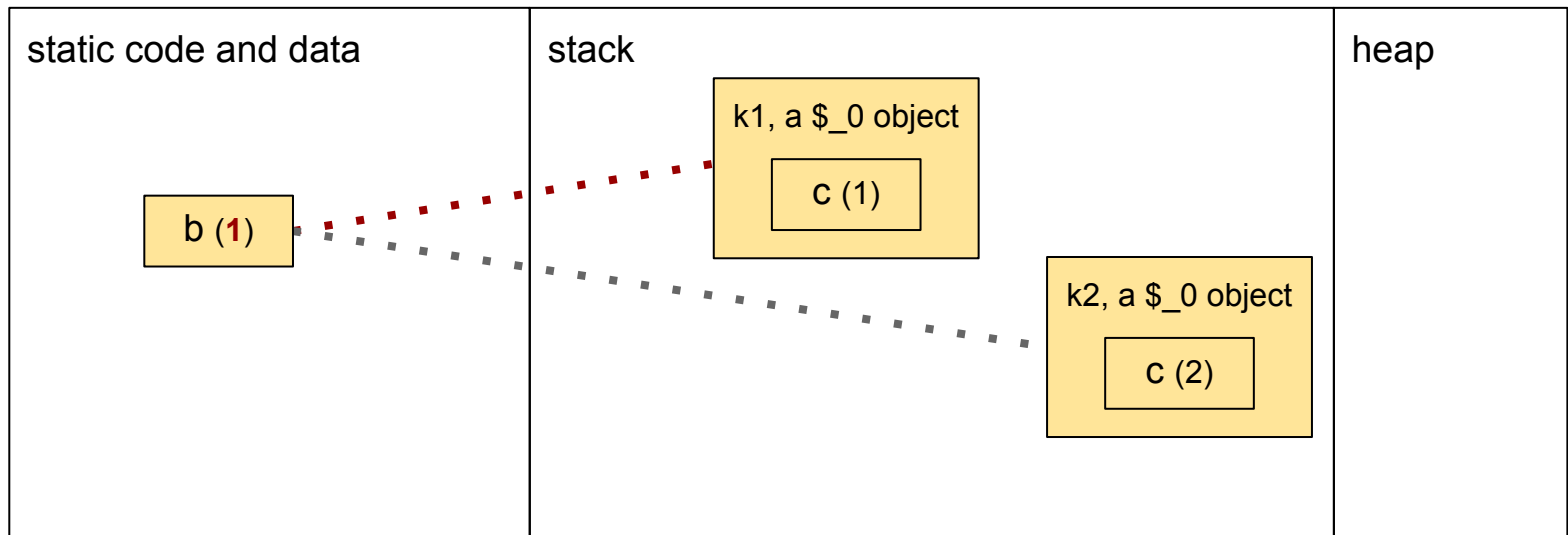
Per-lambda mutable state (wrong!)

```
... [c](int d) { static int b; ... } ...
```

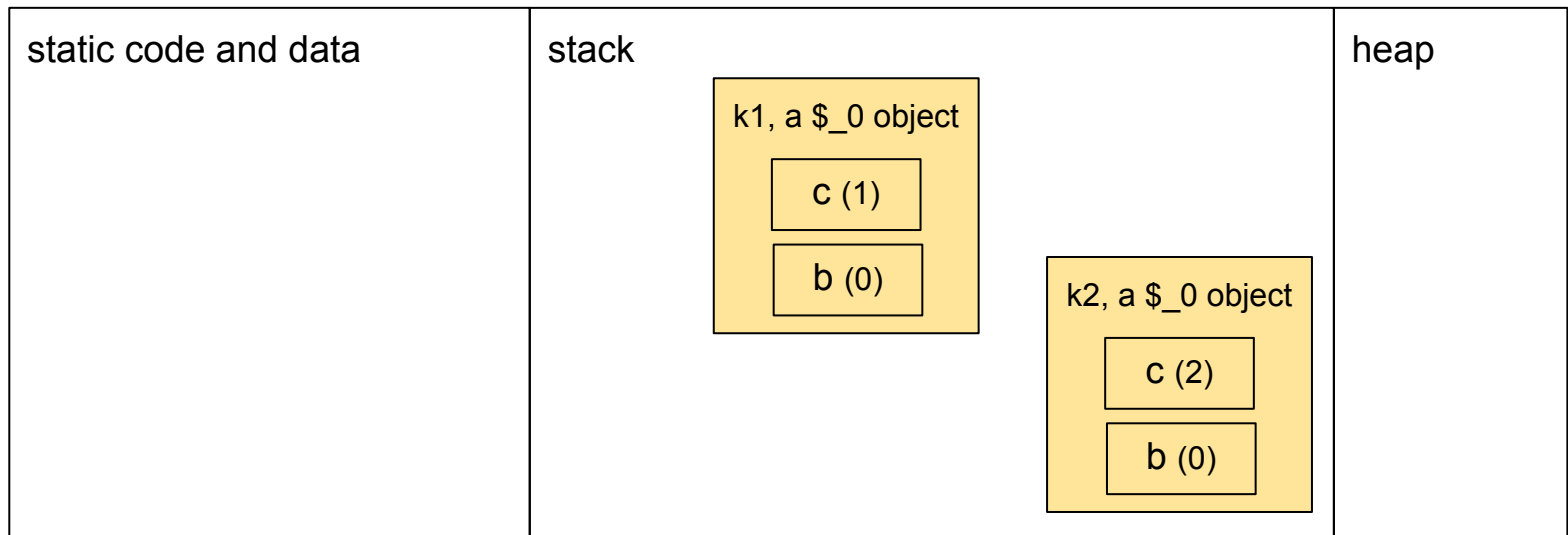


Per-lambda mutable state (wrong!)

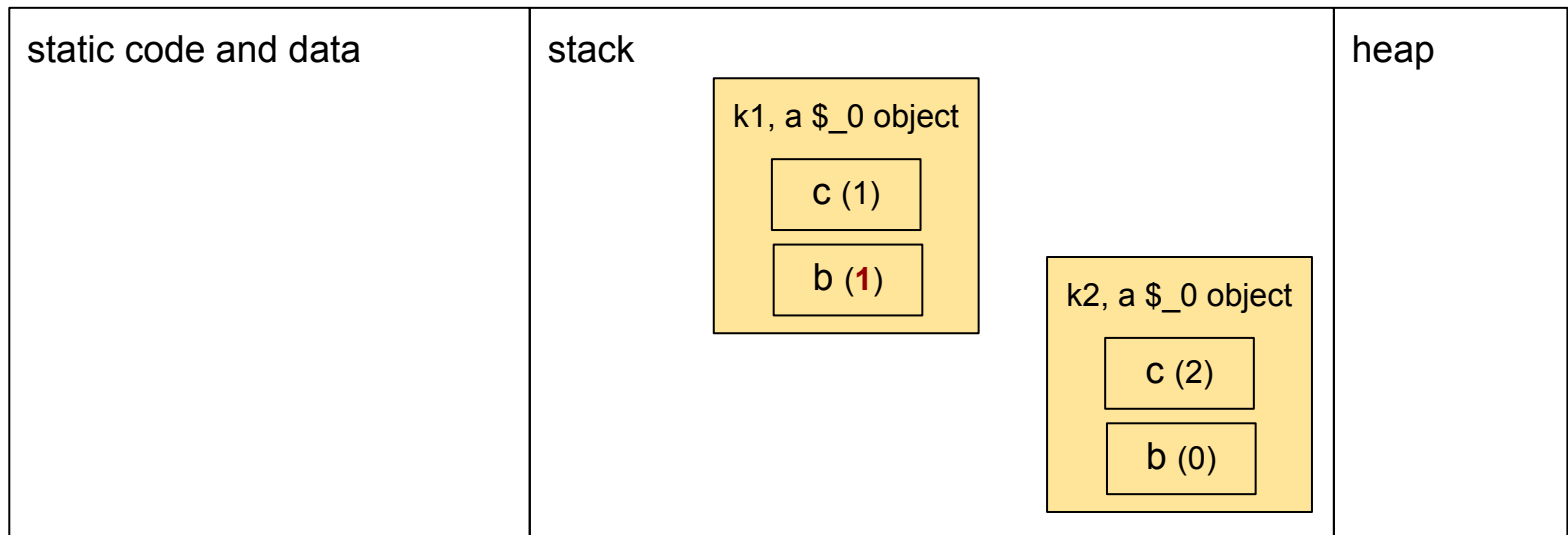
```
... [c](int d) { static int b; ... } ...
```



Per-lambda mutable state (right)



Per-lambda mutable state (right)



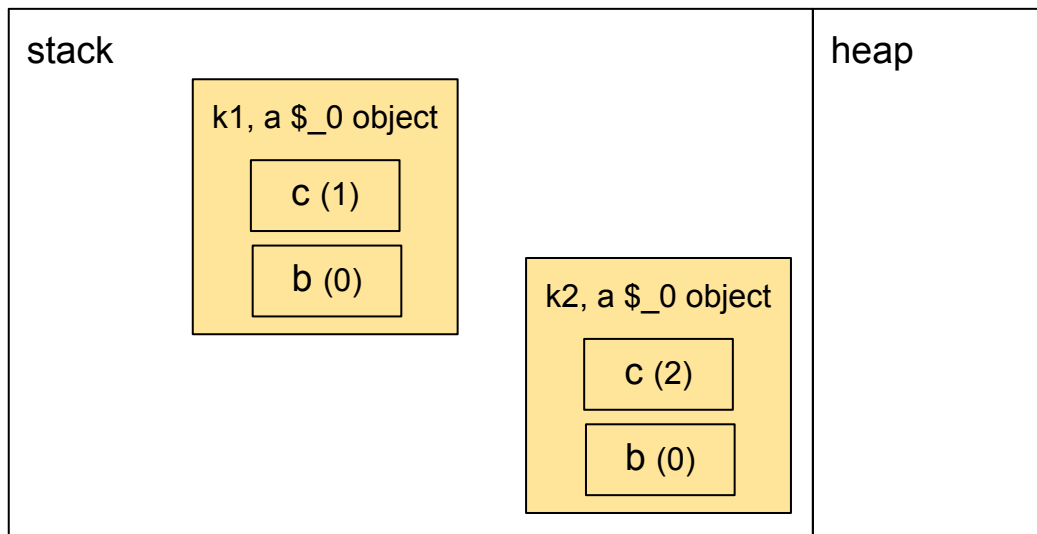
Per-lambda mutable state (right)

```
[c, b=0](int d) mutable { ... b++ ... }
```

Footnote:

mutable is all-or-nothing.

Generally speaking, captures aren't modifiable... and you usually don't want them to be.



Lambdas + Templates
=
Generic Lambdas

Class member function templates

```
class Plus {  
    int value;  
public:  
    Plus(int v);  
  
    template<class T>  
    T plusme(T x) const {  
        return x + value;  
    }  
};
```

```
__ZNK4Plus6plusmeIiEET_S1_:  
    addl    (%rdi), %esi  
    movl    %esi, %eax  
    retq
```

```
__ZNK4Plus6plusmeIdEET_S1_:  
    cvtsi2sdl (%rdi), %xmm1  
    addsd    %xmm0, %xmm1  
    movaps   %xmm1, %xmm0  
    retq
```

```
auto plus = Plus(1);  
auto x = plus.plusme(42);  
auto y = plus.plusme(3.14);
```

Class member function templates

```
class Plus {  
    int value;  
public:  
    Plus(int v);
```

```
    template<class T>  
    T operator()(T x) const {  
        return x + value;  
    }
```

```
};
```

```
__ZNK4PluscIiEET_S1_:  
    addl    (%rdi), %esi  
    movl    %esi, %eax  
    retq
```

```
__ZNK4PluscIdEET_S1_:  
    cvtsi2sd    (%rdi), %xmm1  
    addsd       %xmm0, %xmm1  
    movaps      %xmm1, %xmm0  
    retq
```

```
auto plus = Plus(1);  
auto x = plus(42);  
auto y = plus(3.14);
```

**So now we can make
something kind of nifty...**

Generic lambdas reduce boilerplate

```
class Plus {  
    int value;  
public:  
    Plus(int v): value(v) {}  
  
    template<class T>  
    auto operator() (T x) const {  
        return x + value;  
    }  
};
```

```
auto plus = Plus(1);  
assert(plus(42) == 43);
```

Generic lambdas reduce boilerplate

```
auto plus = [value=1](auto x) { return x + value; };
```

```
assert(plus(42) == 43);
```

**Generic lambdas
are just templates
under the hood.**

Variadic function templates

```
class Plus {  
    int value;  
public:  
    Plus(int v);
```

```
    template<class... A>  
    auto operator()(A... a) {  
        return sum(a..., value);  
    }  
};
```

```
__ZNK4PlusclIJidiEEEDaDpT_:  
    cvtsi2sd1 %esi, %xmm2  
    addl (%rdi), %edx  
    cvtsi2sd1 %edx, %xmm1  
    addsd %xmm1, %xmm0  
    addsd %xmm2, %xmm0  
    retq
```

```
__ZNK4PlusclIJPKciEEEDaDpT_:  
    addl (%rdi), %edx  
    movslq %edx, %rax  
    addq %rsi, %rax  
    retq
```

```
auto plus = Plus(1);  
auto x = plus(42, 3.14, 1);  
auto y = plus("foobar", 2);
```

Variadic lambdas reduce boilerplate

```
class Plus {  
    int value;  
public:  
    Plus(int v): value(v) {}  
  
    template<class... P>  
    auto operator() (A... a) const {  
        return sum(a..., value);  
    }  
};
```

```
auto plus = Plus(1);  
assert(plus(42, 3.14, 1) == 47.14);
```

Variadic lambdas reduce boilerplate

```
auto plus = [value=1](auto... a) {  
    return sum(a..., value);  
};
```

```
assert(plus(42, 3.14, 1) == 47.14);
```

What is this in a lambda?

What is `this` in a lambda?

```
... std::string prop ...  
    auto pless = [p=prop](object& a, object& b) {  
        return a[p] < b[p];  
    };  
};
```

You might think that `p` (being a member of the underlying closure instance) should also be accessible inside the lambda via “`this->p`.”

Not so!

The underlying closure instance is just that: *underlying*. It's how the lambda is *implemented*. But at the source level, we want `this` to expose a different property...

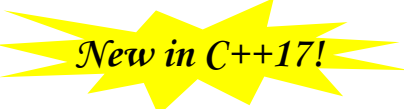
What is this in a lambda?

```
class Widget {  
    void work(int);  
  
    void synchronous_foo(int x) {  
        this->work(x);  
    }  
  
    void asynchronous_foo(int x) {  
        fire_and_forget([=]() {  
            this->work(x);  
        });  
    }  
};
```

It's good that these two
“this” expressions mean
the same thing!

We can reuse code
snippets without counting
brackets so carefully.

Ways of capturing this

- [=]() { **this**->work(); }
- [**this**]() { **this**->work(); }
 - Both equivalent to [**ptr=this**]() { **ptr**->work(); }
- [&]() { **this**->work(); }
 - Also equivalent to [**ptr=this**]() { **ptr**->work(); }
-  *New in C++17!* [***this**]() { **this**->work(x); }
 - Equivalent to [**obj=*this**]() { **obj**.work(); }
- “Capture ***this** by move” has no shorthand equivalent.
 - Just write [**obj=std::move(*this)**]() { **obj**.work(x); }

**“So are lambdas kind of like
std::function, then?”**

“Why does C++ have both?”

Type Erasure From Scratch

std::function is a *vocabulary type*

Before we can talk about `<math.h>`, we need `double`.

Before we can talk about stringstreams, we need `std::string`.

Before we can talk about callbacks, we need `std::function`.

`std::function` allows us to pass lambdas, functor objects, etc.,
across *module boundaries*.

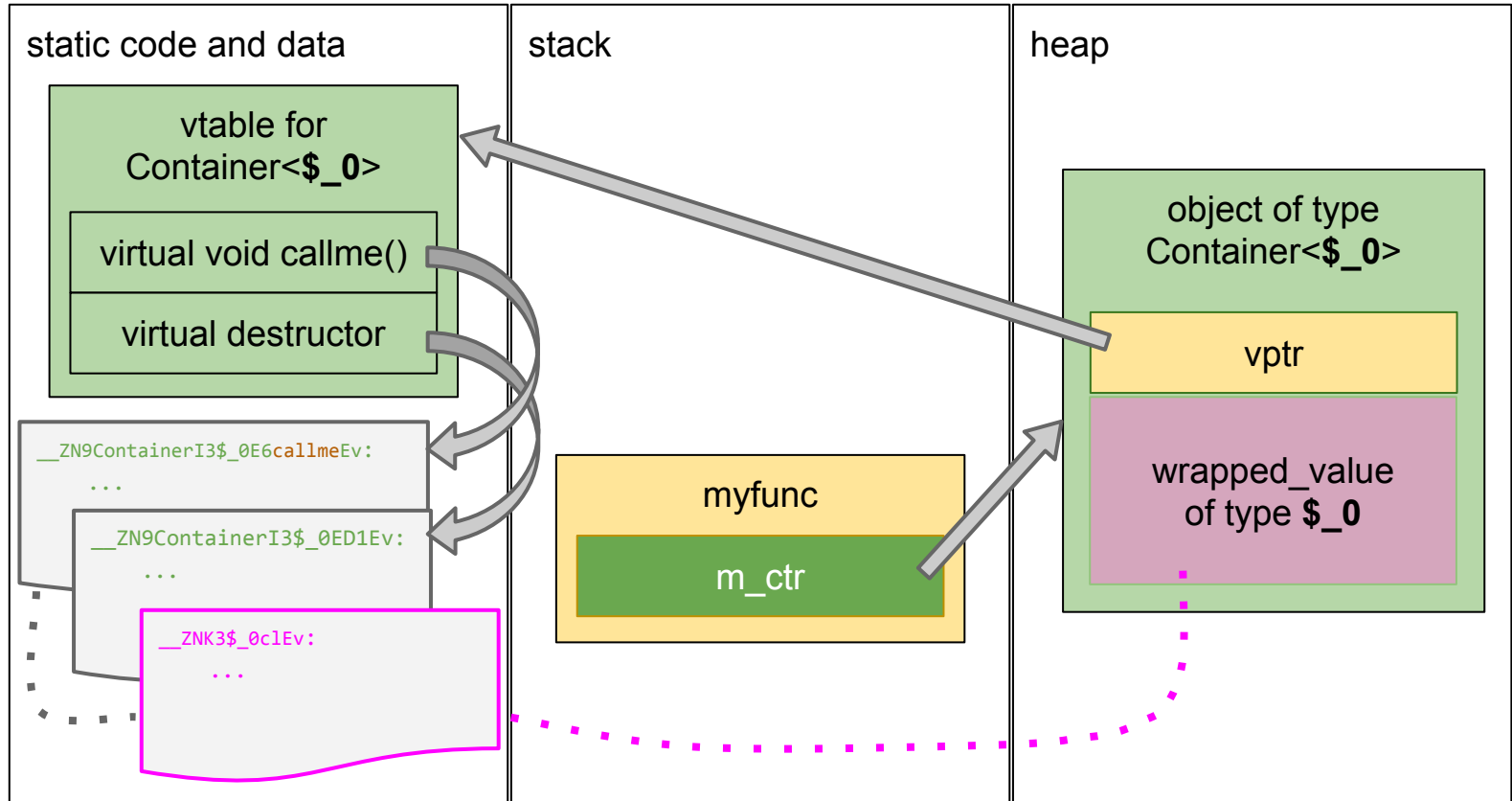
Type erasure in a nutshell

```
struct ContainerBase {
    virtual int callme(int) = 0;
    virtual ~ContainerBase() = default;
};

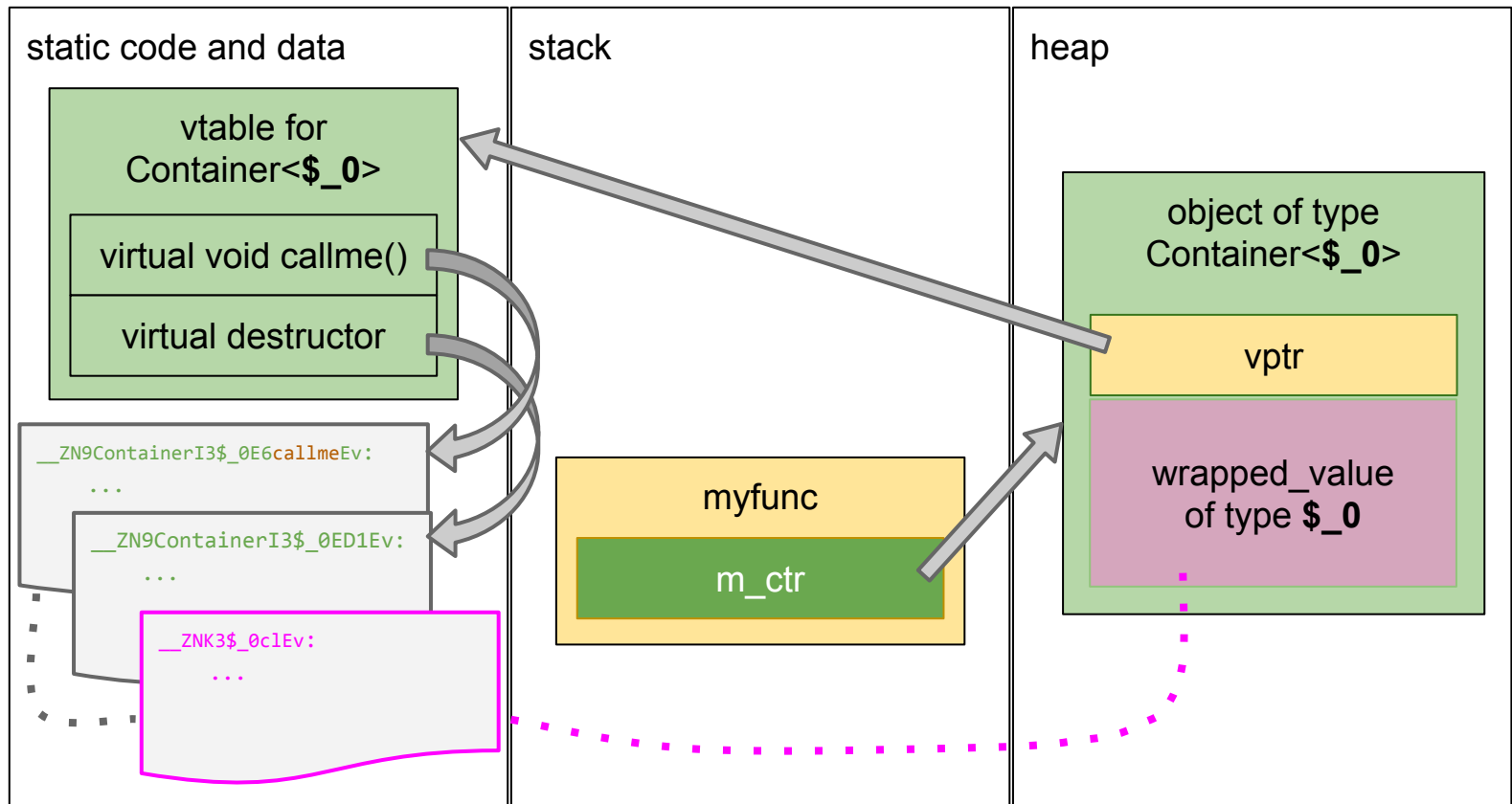
template <class Wrapped> struct Container : ContainerBase {
    Wrapped wrapped_value;
    Container(const Wrapped& wv) : wrapped_value(wv) {}
    int callme(int i) override { return wrapped_value(i); }
};

class i2i { // equivalent to std::function<int(int)>
    ContainerBase *m_ctr;
public:
    template<class F> i2i(const F& wv)
        : m_ctr(new Container<F>(wv)) {}
    int operator()(int i) { return m_ctr->callme(i); } // virtual dispatch
    ~i2i() { delete m_ctr; } // virtual dispatch
};
```

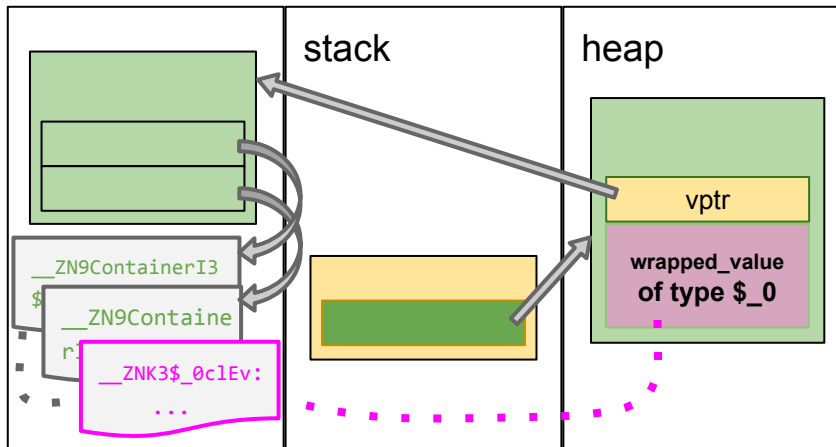
Type erasure diagrammatically



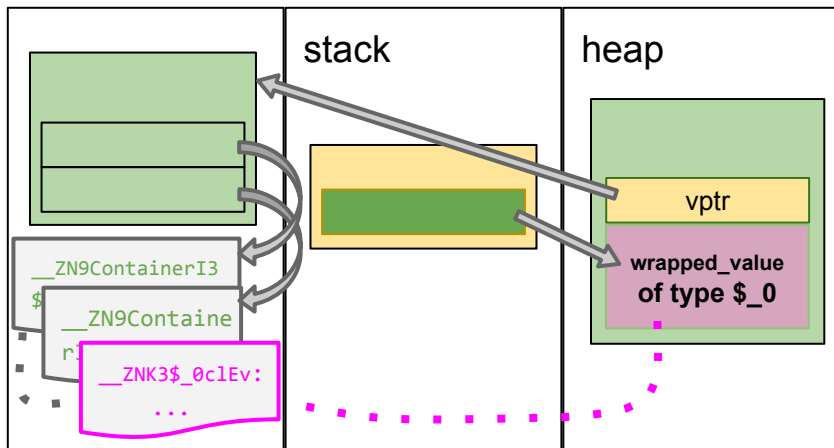
myfunc is nothrow moveable.



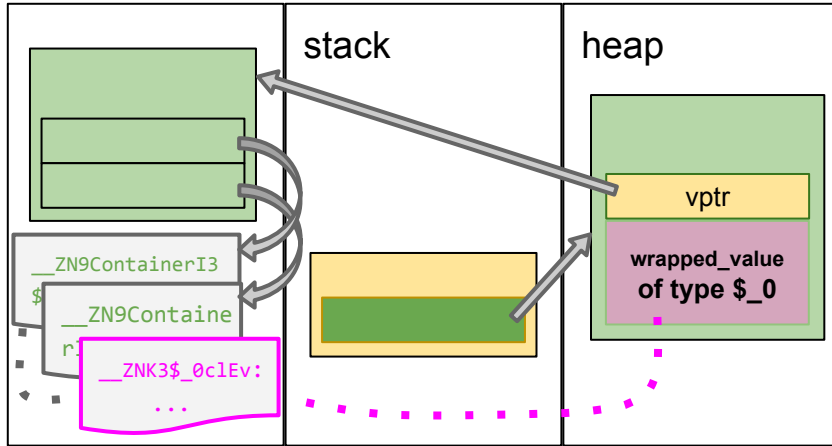
myfunc is nothrow moveable.



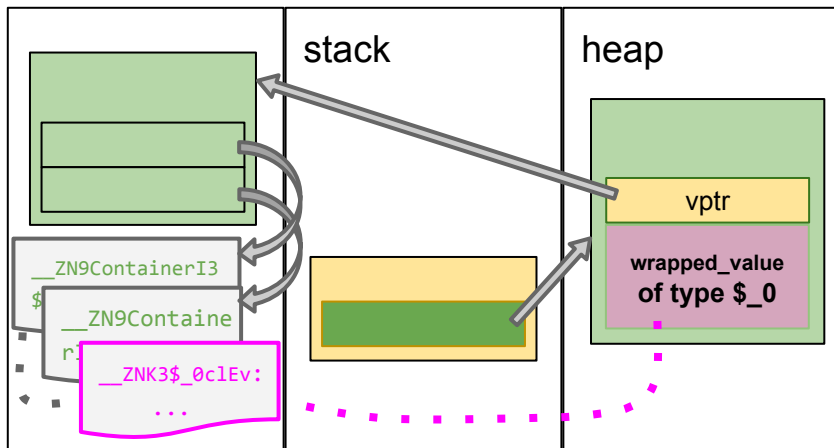
myfunc is nothrow moveable.



Is myfunc copyable?



Is myfunc copyable?



No, myfunc is not copyable.

In order to make a copy of myfunc, we'd have to allocate a second `Container<$_0>`, containing a copy of myfunc's wrapped value.

But the copy constructor of myfunc (that is, `class i2i`'s copy constructor) doesn't remember the identity of type `$_0` anymore — we've erased it!

“Copying” is an operation, just like *“calling with signature `int(int)`” is an operation*. If we want it to be supported, we must explicitly support it via a virtual method in `ContainerBase`.

Make our i2i copyable

```
struct ContainerBase {  
    virtual int callme(int) = 0;  
    virtual ContainerBase *copyme() = 0;  
    virtual ~ContainerBase() = default;  
};  
template <class Wrapped> struct Container : ContainerBase {  
    Wrapped wrapped_value;  
    Container(const Wrapped& wv) : wrapped_value(wv) {}  
    int callme(int i) override { return wrapped_value(i); }  
    ContainerBase *copyme() override { return new Container(wrapped_value); }  
};
```

New

New

```
class i2i { // Even more equivalent to std::function<int(int)>  
    ContainerBase *m_ctr;  
public:  
    template<class F> i2i(const F& wv) : m_ctr(new Container<F>(wv)) {}  
    i2i(const i2i& rhs) : m_ctr(rhs->copyme()) {} // virtual dispatch  
    int operator()(int i) { return m_ctr->callme(i); } // virtual dispatch  
    ~i2i() { delete m_ctr; } // virtual dispatch  
};
```

Lambdas may be copyable or not

```
std::unique_ptr<int> prop;  
auto lamb = [p = std::move(prop)]() { };  
auto lamb2 = std::move(lamb); // OK  
auto lamb3 = lamb; // error: call to implicitly-deleted copy constructor
```

A lambda's type is copyable, moveable, or neither, depending as its captures are copyable, moveable, or neither.

`std::function` is always copyable.

Therefore, there are some lambdas that can't be stored in a `std::function`.

```
std::function<void()> f = std::move(lamb); // cascade of errors
```

Working around noncopyability (bad)

Hot-potato the single instance à là auto_ptr.

```
std::function<void()> f2 = AwfulPtr(lamb);
```

```
template<class T>
class AwfulPtr {
    std::optional<T> o;
public:
    explicit AwfulPtr(T& t) : o(std::move(t)) {}
    AwfulPtr(const AwfulPtr& rhs) : o((T&&)rhs.o.value()) {
        ((AwfulPtr&)rhs).o.reset();
    }
    template<class... Args>
    decltype(auto) operator()(Args&&... args) const {
        return o.value()(std::forward<Args>(args)...);
    }
};
```

Casting away constness

Casting away constness

Working around noncopyability (good)

```
auto lamb = something move-only;
```

Consider placing the single instance on the heap and *sharing* access to it:

```
std::function<void()> f3 = [  
    p = std::make_shared<decltype(lamb)>(std::move(lamb))  
]() { (*p)(); };
```

Or use a *moveable function type* such as `folly::Function`.

```
my::unique_function<void()> f4 = std::move(lamb); // OK
```

Every codebase needs a moveable function type!

Questions?

Thanks for coming!