

A STORY



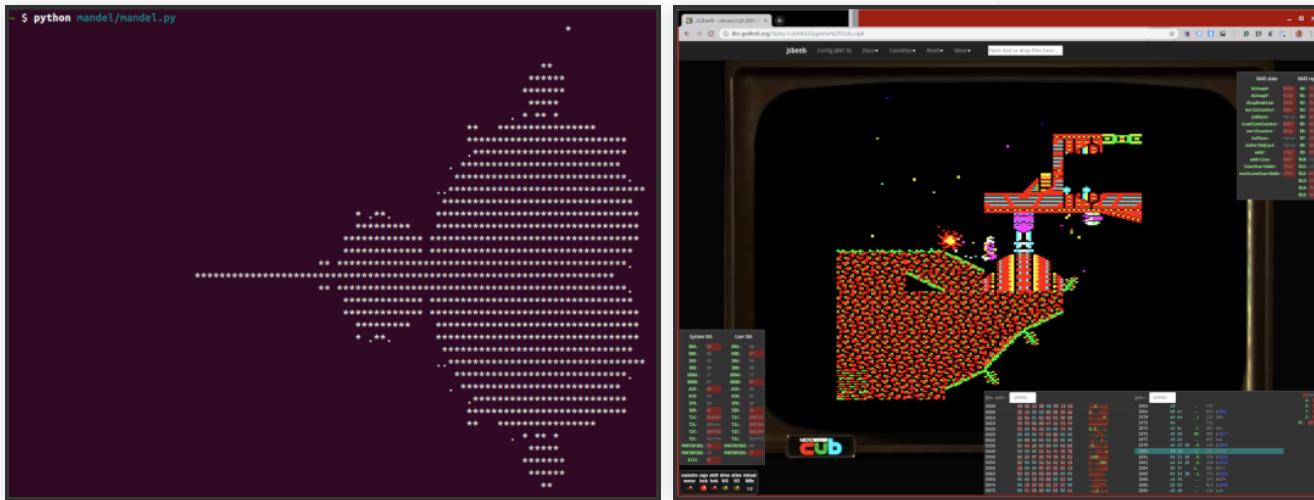
A STORY



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A STORY



APPLY TO C++

THIS TALK IS NOT

- Expert advice on:
 - Path tracing
 - C++ code styles
 - Style “X” is best!
-

BUT IT IS

- My interpretation
 - Real code
-

BUT IT IS

- My interpretation
 - Real code
 - Interesting & fun (hopefully)
-

STYLES

STYLES

- Object Oriented
-

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- Object Oriented
 - Functional Programming
-

STYLES

- Object Oriented
 - Functional Programming
 - Data-Oriented Design
-

PATH TRACING

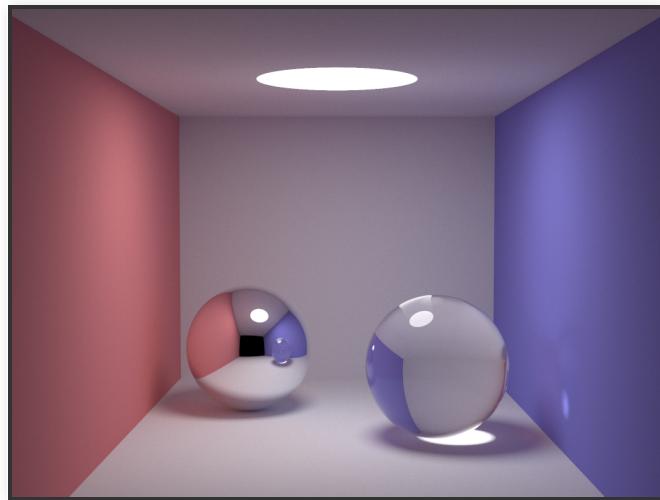


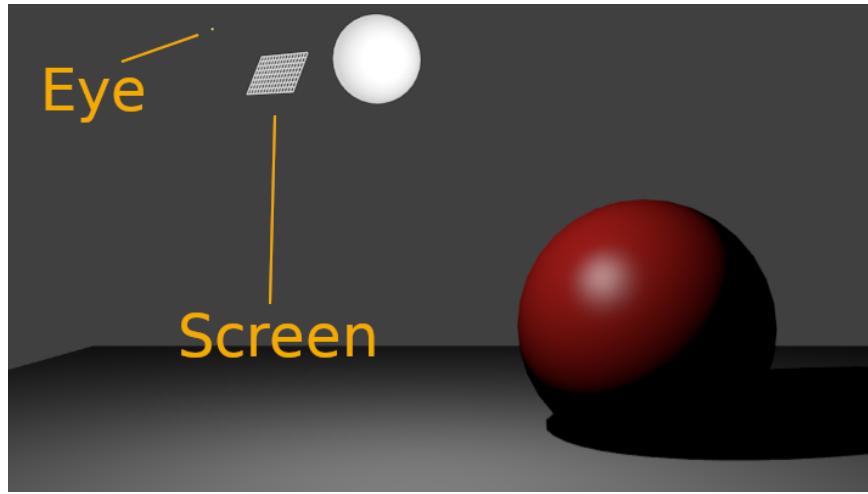
Image credit: Kevin Beason

PATH TRACING

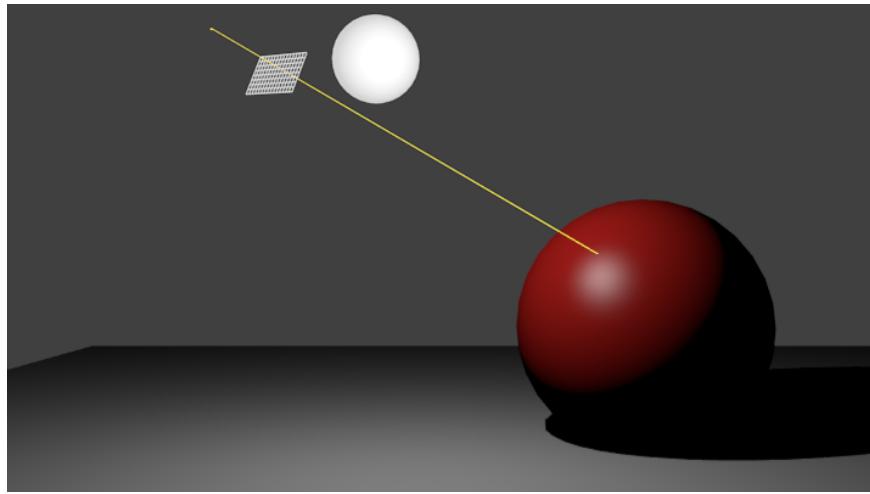
```
36.     Sphere(1e5, Vec(50,-1e5+81.6,81.6),Vec(),Vec(.75,.75,.75),DIFF),//Top
37.     Sphere(16.5,Vec(27,16.5,47),      Vec(),Vec(1,1,1)*.999, SPEC),//Mirr
38.     Sphere(16.5,Vec(73,16.5,78),      Vec(),Vec(1,1,1)*.999, REFR),//Glas
39.     Sphere(680, Vec(50,681.6-.27,81.6),Vec(12,12,12), Vec(), DIFF) //Lite
40. };
41. inline double clamp(double x){ return x<0 ? 0 : x>1 ? 1 : x; }
42. inline int toInt(double x){ return int(pow(clamp(x),1/2.2)*255+.5); }
43. inline bool intersect(const Ray &r, double &t, int &id){
44.     double n=siz eof(spheres)/siz eof(Sphere), d, inf=t=1e20;
45.     for(int i=int(n);i--;) if((d=spheres[i].intersect(r))&&d<t){t=d;id=i;}
46.     return t<inf;
47. }
48. Vec radiance(const Ray &r, int depth, unsigned short *Xi){
49.     double t;                                // distance to intersection
50.     int id=0;                                // id of intersected object
51.     if (!intersect(r, t, id)) return Vec(); // if miss, return black
52.     const Sphere &obj = spheres[id];          // the hit object
53.     Vec x=r.o+r.d*t, n=(x-obj.p).norm(), nl=n.dot(r.d)<0?n*-1, f=obj.c;
54.     double p = f.x*f.y && f.x>f.z ? f.x : f.y>f.z ? f.y : f.z; // max refl
55.     if (++depth>5) if (erand48(Xi)<p) f=f*(1/p); else return obj.e; //R.R.
56.     if (obj.refl == DIFF){                      // Ideal DIFFUSE reflection
57.         double r1=2*M_PI*erand48(Xi), r2=erand48(Xi), r2s=sqrt(r2);
58.         Vec w=nL, u=(fabs(w.x)>.1?Vec(0,1):Vec(1))%wL.norm(), v=w*u;
59.         Vec d = (u*cos(r1)*r2s + v*sin(r1)*r2s + w*sqrt(1-r2)).norm();
60.         return obj.e + f.mult(radiance(Ray(x,d),depth,Xi));
61.     } else if (obj.refl == SPEC)                // Ideal SPECULAR reflection
62.         return obj.e + f.mult(radiance(Ray(x,r.d-n*2*n.dot(r.d)),depth,Xi));
63.     Ray reflRay(x, r.d-n*2*n.dot(r.d));        // Ideal dielectric REFRACTION
64.     bool into = n.dot(nL)<0;                   // Ray from outside going in?
65.     double nc=1, nt=1.5, nnt=nt*nc/nt:nt/nc, ddn=r.d.dot(nL), cos2t;
66.     if ((cos2t=1-nnt*nnt*(1-ddn*ddn))<0)    // Total internal reflection
67.         return obj.e + f.mult(radiance(reflRay,depth,Xi));
```

Image credit: Kevin Beason

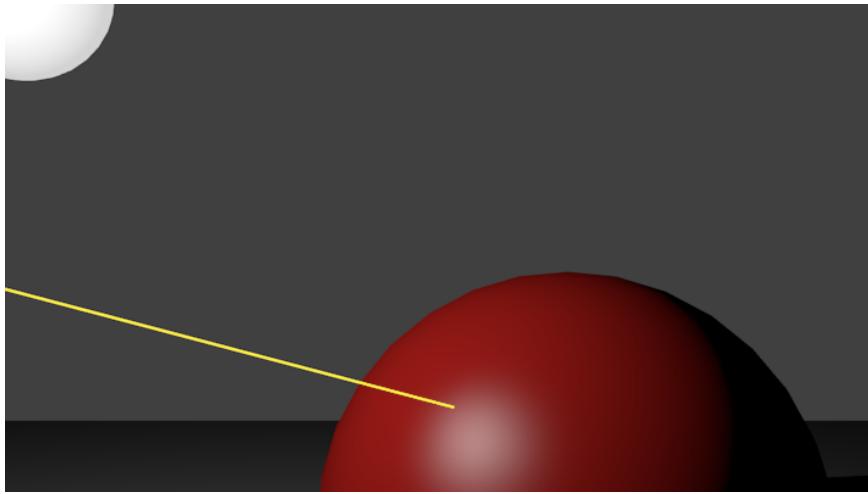
PATH TRACING



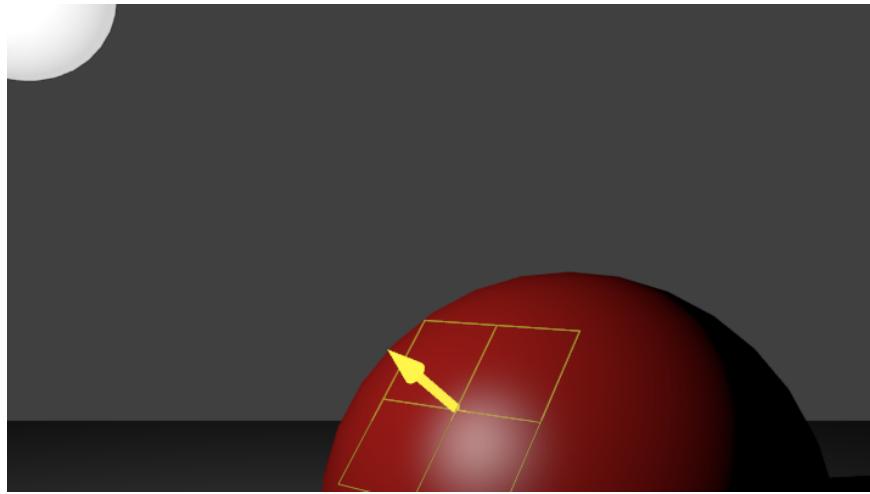
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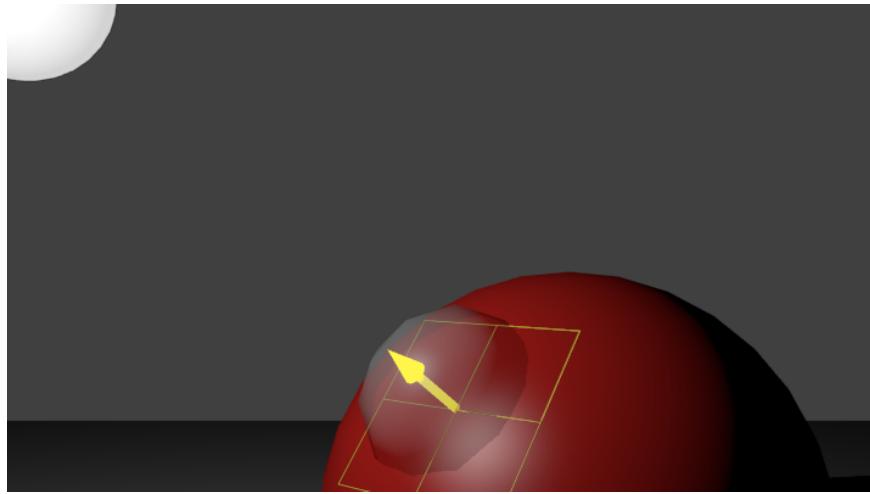
PATH TRACING



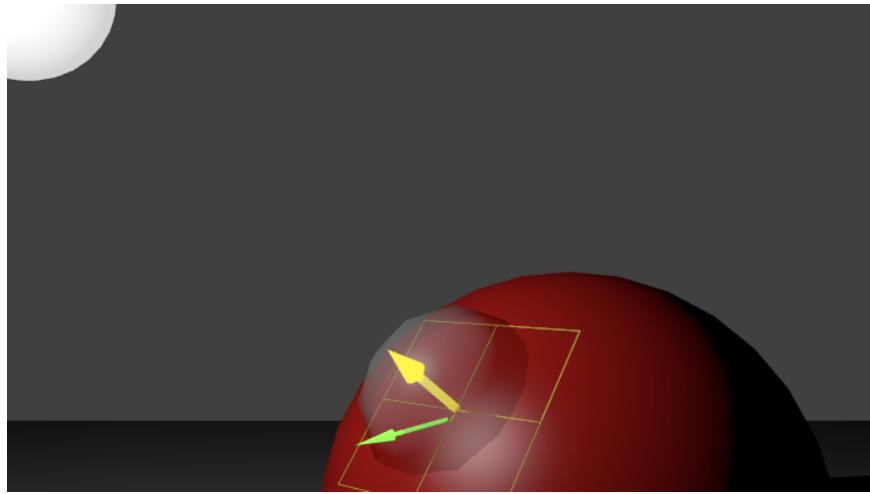
PATH TRACING



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PATH TRACING



PATH TRACING

For each pixel:

PATH TRACING

For each pixel:

1. Fire a zillion rays into the scene
-

PATH TRACING

For each pixel:

1. Fire a zillion rays into the scene
 2. Bounce randomly; accumulate intensity & colour
-

PATH TRACING

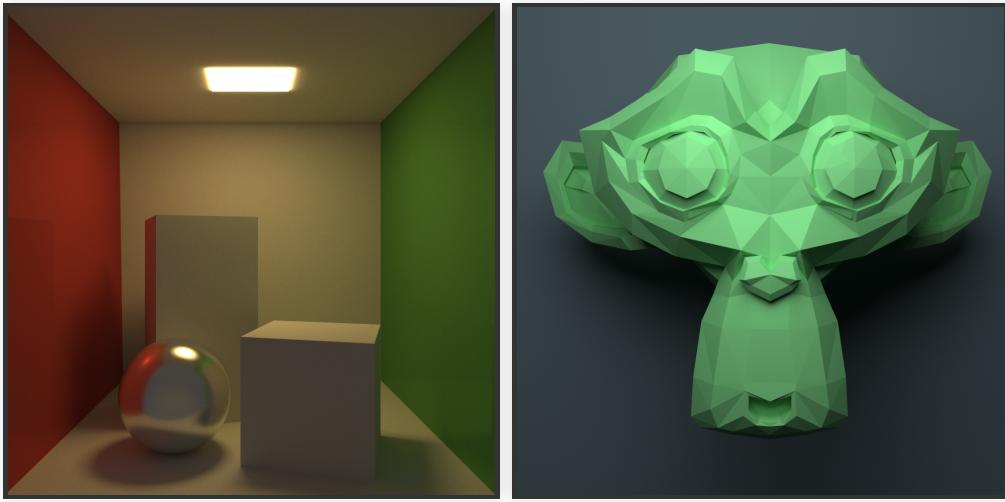
For each pixel:

1. Fire a zillion rays into the scene
 2. Bounce randomly; accumulate intensity & colour
 3. Average them out
-

MY PATH TRACER

- Simple materials
 - Spheres & triangles only
 - Scenes in code
 - Written 3 times!
-

MY PATH TRACER



*Model credit: "Suzanne" from Blender
With thanks to [Michael Fogleman](#)*

GENERAL APPROACH

- Shared basic math library
 - Vec3 / Norm3
 - Ray
 - Hit
 - Some simple “util” classes
 - MaterialSpec struct
 - Camera
-

OBJECT ORIENTED

MAJOR COMPONENTS

- Scene
 - Renderer
 - Radiance calculation
 - Materials
 - Intersection
-

SCENE

```
class Primitive {
public:
    virtual ~Primitive() = default;

    struct IntersectionRecord {
        Hit hit;
        const Material *material = nullptr;
    };

    [[nodiscard]] virtual bool intersect(
        const Ray &ray,
        IntersectionRecord &intersection) const = 0;
};
```

SCENE

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class Primitive {
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};
```

RENDER

```
for (int y = 0; y < height; ++y) {
    for (int x = 0; x < width; ++x) {
        Vec3 colour;
        for (int sample = 0; sample < numSamples; ++sample) {
            auto ray = camera_.randomRay(x, y, rng);
            colour += radiance(rng, ray, 0);
        }
        output.plot(x, y, colour / numSamples);
    }
}
```

RENDER

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for (int y = 0; y < height; ++y) {
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            colour += radiance(rng, ray, 0);
        }
        output.plot(x, y, colour / numSamples);
    }
}
```

RADIANCE

```
Vec3 Renderer::radiance(
    std::mt19937 &rng, const Ray &ray, int depth) const {
    if (depth >= MaxDepth)
        return Vec3();

    Primitive::IntersectionRecord intersectionRecord;
    if (!scene_.intersect(ray, intersectionRecord))
        return Vec3();

    int numUSamples = depth == 0 ? renderParams_.firstBounceUSamples : 1;
    int numVSamples = depth == 0 ? renderParams_.firstBounceVSamples : 1;
```

RADIANCE

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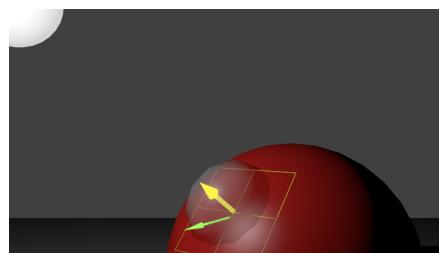
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```



```
Vec3 result;
Sampler sampler(*this, rng, depth + 1);
for (auto uSample = 0; uSample < numUSamples; ++uSample) {
    for (auto vSample = 0; vSample < numVSamples; ++vSample) {
        auto u = (uSample + unit(rng)) / numUSamples;
        auto v = (vSample + unit(rng)) / numVSamples;
        auto p = unit(rng);

        result += material.sample(hit, ray, sampler, u, v, p);
    }
}
return material.totalEmission(result / (numUSamples * numVSamples));
}
```

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}
return material.totalEmission(result / (numUSamples * numVSamples));
}
```

INTERSECTION

```
struct SpherePrimitive : Primitive {
    Sphere sphere;
    std::unique_ptr<Material> material;

    [[nodiscard]]
    bool intersect(const Ray &ray,
                   IntersectionRecord &rec) const override {
        Hit hit;
        if (!sphere.intersect(ray, hit))
            return false;
        rec = IntersectionRecord{hit, material.get()};
        return true;
    }
};
```

INTERSECTION

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        if (!sphere.intersect(ray, hit))
            return false;
        rec = IntersectionRecord{hit, material.get()};
        return true;
    }
};
```

```
bool Sphere::intersect(const Ray &ray, Hit &hit) const noexcept {
    auto op = centre_ - ray.origin();
    auto b = op.dot(ray.direction());
    auto determinant = b * b - op.lengthSquared() + radius_ * radius_;
    if (determinant < 0)
        return false;
    auto root = sqrt(determinant);
    // [...more maths elided for clarity...]
    hit = Hit{t, inside, hitPosition, normal};
    return true;
}
```

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        return false;
    auto root = sqrt(determinant);
    // [...more maths elided for clarity...]
    hit = Hit{t, inside, hitPosition, normal};
    return true;
}
```

```
bool Triangle::intersect(const Ray &ray, Hit &hit) const noexcept {  
    // similarly...  
}
```

MATERIALS

```
class Material {
public:
    virtual ~Material() = default;

    class RadianceSampler {
public:
    virtual ~RadianceSampler() = default;

        [[nodiscard]] virtual Vec3 sample(const Ray &ray) const = 0;
    };

    [[nodiscard]] virtual Vec3 sample(
        const Hit &hit, const Ray &incoming,
        const RadianceSampler &radianceSampler,
        double u, double v, double p) const = 0;
};
```

MATERIALS

```
class Material {
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    virtual ~Material() = default;

    class RadianceSampler {
public:
    virtual ~RadianceSampler() = default;

        [[nodiscard]] virtual Vec3 sample(const Ray &ray) const = 0;
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    [[nodiscard]] virtual Vec3 sample(
        const Hit &hit, const Ray &incoming,
        const RadianceSampler &radianceSampler,
        double u, double v, double p) const = 0;
};
```

```
class ShinyMaterial : public Material {
    MaterialSpec mat_;
public:
    Vec3 sample(
        const Hit &hit, const Ray &incoming,
        const RadianceSampler &radianceSampler, double u,
        double v, double p) const override {

    if (p < mat_.reflectivity) {
        return radianceSampler.sample(
            Ray(hit.position, coneSample(/*...reflection...*/, u, v)));
    }

    return mat_.diffuse
        * radianceSampler.sample(
            Ray(hit.position, hemisphereSample(hit.normal, u, v)));
}
};
```

```
class ShinyMaterial : public Material {
    MaterialSpec mat_;
public:
    Vec3 sample(
        const Hit &hit, const Ray &incoming,
        const RadianceSampler &radianceSampler, double u,
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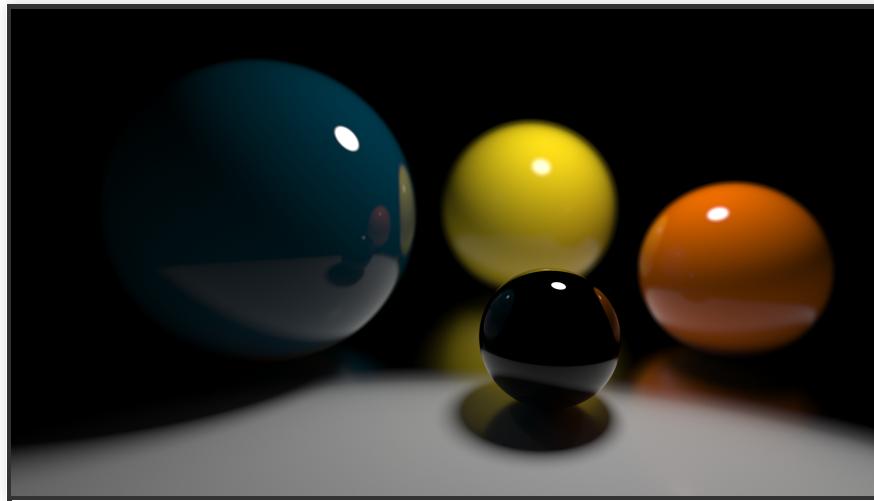
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        * radianceSampler.sample(
            Ray(hit.position, hemisphereSample(hit.normal, u, v)));
}
};
```

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class ShinyMaterial : public Material {
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public:
    Vec3 sample(
        const Hit &hit, const Ray &incoming,
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        double v, double p) const override {

    if (p < mat_.reflectivity) {
        return radianceSampler.sample(
            Ray(hit.position, coneSample(/*...reflection...*/, u, v)));
    }

    return mat_.diffuse
        * radianceSampler.sample(
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```

RESULTS



Scene credit: Michael Fogelman

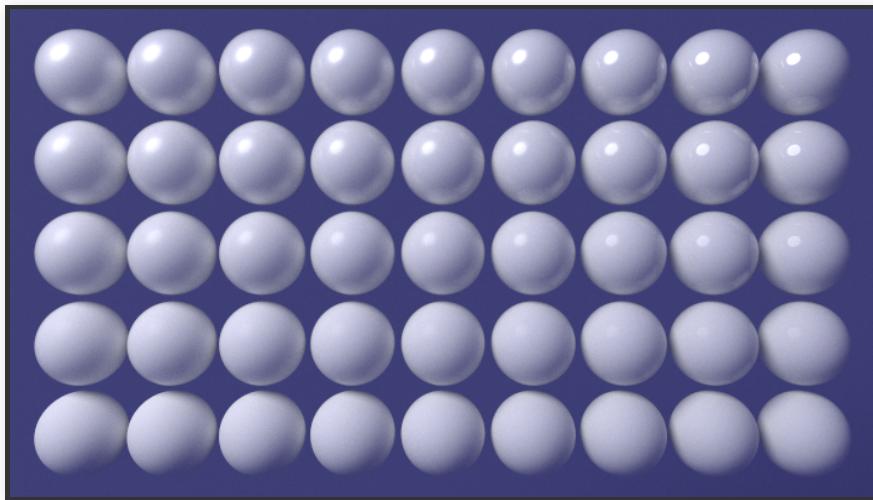
THINGS I LIKED

- Code layout
 - Testability
 - Performance
-

THINGS I DIDN'T LIKE

- Giving up std::optional
 - (Arguable) overuse of virtual
-

FUNCTIONAL PROGRAMMING



FUNCTIONAL PROGRAMMING

- ranges_v3
 - tl::optional
-

SCENE

```
struct TrianglePrimitive {
    Triangle shape;
    Material material;
};

struct SpherePrimitive {
    Sphere shape;
    Material material;
};

using Primitive = std::variant<TrianglePrimitive, SpherePrimitive>;
```

SCENE

```
struct TrianglePrimitive {
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};

using Primitive = std::variant<TrianglePrimitive, SpherePrimitive>;
```

RENDER

```
auto renderOnePixel = [...] (auto tuple) {
    auto [y, x] = tuple;
    std::mt19937 rng(...);
    return radiance(scene, rng,
                    camera.randomRay(x, y, rng), 0, renderParams);
};

return ArrayOutput(width, height,
    view::cartesian_product(view::ints(0, height),
                           view::ints(0, width))
| view::transform(renderOnePixel));
```

RENDER

```
auto renderOnePixel = [...] (auto tuple) {
    auto [y, x] = tuple;
    std::mt19937 rng(...);
    return radiance(scene, rng,
                    camera.randomRay(x, y, rng), 0, renderParams);
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                           view::ints(0, width))
| view::transform(renderOnePixel));
```

RADIANCE

```
auto radianceForRay = [&] (const Ray &ray) {
    return radiance(scene, rng, ray, depth + 1, renderParams);
};

const auto incomingLight = accumulate(
    views::cartesian_product(views::ints(0, numVSamples),
                             views::ints(0, numUSamples))
| views::transform(toUVSample)
| views::transform([&] (auto s) {
    return radianceAtIntersection(
        radianceForRay, *intersectionRecord,
        ray, s.first, s.second, unit(rng));
}),
Vec3());
```

RADIANCE

```
auto radianceForRay = [&] (const Ray &ray) {
    return radiance(scene, rng, ray, depth + 1, renderParams);
};

const auto incomingLight = accumulate(
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| views::transform(toUVSample)
| views::transform([&] (auto s) {
    return radianceAtIntersection(
        radianceForRay, *intersectionRecord,
        ray, s.first, s.second, unit(rng));
}),
Vec3());
```

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| views::transform([&] (auto s) {
    return radianceAtIntersection(
        radianceForRay, *intersectionRecord,
        ray, s.first, s.second, unit(rng));
}),
Vec3());
```

RADIANCE

```
auto radianceForRay = [&] (const Ray &ray) {
    return radiance(scene, rng, ray, depth + 1, renderParams);
};

const auto incomingLight = accumulate(
    views::cartesian_product(views::ints(0, numVSamples),
                             views::ints(0, numUSamples))
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```

```
template <typename RadianceFunc>
Vec3 radianceAtIntersection(
    RadianceFunc &&radiance,
    const IntersectionRecord &intersectionRecord,
    const Ray &ray, double u, double v, double p) {
// [...lots of material stuff...]
if (p < reflectivity) {
    const auto newRay =
        Ray(hit.position, coneSample(/*...*/, u, v));
    return radiance(newRay);
} else {
    const auto newRay = Ray(hit.position,
        hemisphereSample(/*...*/, u, v));
    return mat.diffuse * radiance(newRay);
}
}
```

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}
```

INTERSECTION

```
struct IntersectVisitor {
    const Ray &ray;

    template <typename PrimT>
    auto operator()(const PrimT &primitive) const {
        return primitive.shape.intersect(ray)
            .map([&primitive])(auto hit) {
                return IntersectionRecord{hit, primitive.material};
            });
    }
};

tl::optional<IntersectionRecord> intersect(
    const Primitive &primitive, const Ray &ray) {
    return std::visit(IntersectVisitor{ray}, primitive);
}
```

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```

```
tl::optional<Hit> Sphere::intersect(const Ray &ray) const noexcept {
    const auto determinant = /*...maths...*/;
    return safeSqrt(determinant)

        .and_then([&b] (double root) -> tl::optional<double> {
            /* ...calc minusT, plusT.. */
            if /* ...too close to zero...*/
                return tl::nullopt;
            return minusT > Epsilon ? minusT : plusT;
        })

        .map([this, &ray] (double t) {
            return Hit{t, /*...*/};
        });
}
```

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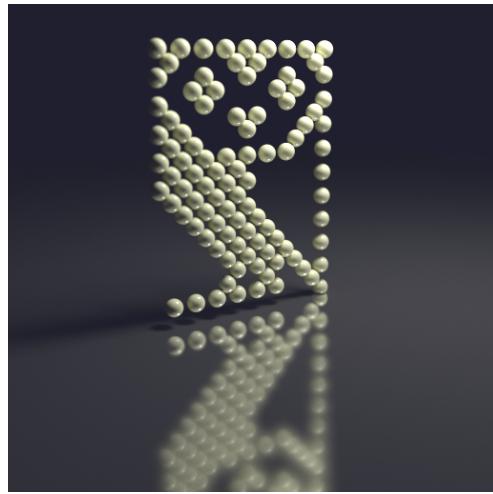
THINGS I LIKED

- const :allthethings:
 - Code clearer...maybe?
 - Testability
-

THINGS I DIDN'T LIKE

- Cryptic compiler error messages
- Concern I've broken FP rules (rng...)
- Performance
 - `std::mt19937` rng per pixel?

DATA-ORIENTED DESIGN



- Design around most common operations
 - Design data by access patterns
 - Avoid branches
 - Polymorphism by separation
-

CHANGES

- Intersection is most common operation
 - Only need nearest
 - Two types of object
 - Separate into two lists
-

SCENE

```
class Scene {
    std::vector<TriangleVertices> triangleVerts_;
    std::vector<TriangleNormals> triangleNormals_;
    std::vector<Material> triangleMaterials_;

    std::vector<Sphere> spheres_;
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INTERSECTION - SPHERES

```
double nearestDist = nearerThan;
std::optional<size_t> nearestIndex;

for (size_t sphereIdx = 0; sphereIdx < spheres_.size(); ++sphereIdx) {
    // ...maths...
    if (!hit) continue;

    if (distance < currentNearestDist) {
        nearestIndex = sphereIdx; nearestDist = distance;
    }
}

if (!nearestIndex) return {}; // missed all spheres
// ...more maths to calc hit positions, normal...
return IntersectionRecord{Hit{...}, sphereMaterials_[*nearestIndex]};
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    // ...calc u...maths, only needs triangle vertices...  
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// ...more maths to calculate actual normal...  
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REST BROADLY THE SAME

THINGS I LIKED

- Ability to optimise
 - Performance
-

THINGS I LIKED

- Ability to optimise
- Performance
 - with caveat

THINGS I DIDN'T LIKE

- Testability
 - Difficulty to change
-

CONCLUSIONS

FAVOURITE?

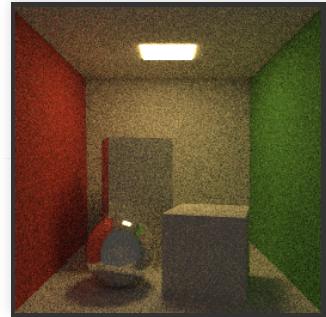
- All of the above!!
- C++ is best when we can blend all its features

PERFORMANCE

- Intel(R) Core(TM) i9-9980XE CPU @ 3.00GHz
 - cpupower frequency-set --governor performance
 - Single threaded
 - GCC 9.2
-

CORNELL BOX SCENE

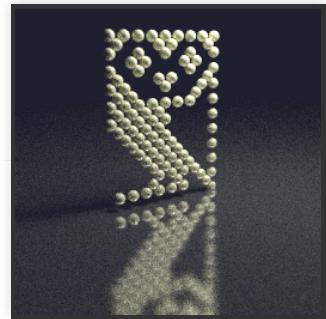
256x256 32spp (1 sphere, 38 triangles)



Style	Render time (secs)
Object Oriented	72
Functional	82
Data-Oriented	72

OWL SCENE

128spp (100 spheres, 12 triangles)



Style	Render time (secs)
Object Oriented	96
Functional	101
Data-Oriented	64

SUZANNE

256x256 8spp (2 spheres, 970 triangles)



Style	Render time (secs)
Object Oriented	80
Functional	119
Data-Oriented	106

SUZANNE

256x256 8spp (2 spheres, 970 triangles)



Style	Render time (secs)
Object Oriented	80
Functional	119
Data-Oriented	106

What on earth!?!

WHAT HAPPENED?

OBJECT ORIENTED

252,203,645,149	instructions	# 2.71	insn per cycle
23,158,824,048	branches	# 845.438	M/sec
139,741,218	branch-misses	# 0.60%	of all branches

FUNCTIONAL

238,866,691,159	instructions	# 1.78	insn per cycle
21,881,070,251	branches	# 560.513	M/sec
1,105,066,725	branch-misses	# 5.05%	of all branches

DATA-ORIENTED DESIGN

154,821,779,748	instructions	# 1.34	insn per cycle
10,353,392,805	branches	# 305.213	M/sec
1,242,670,094	branch-misses	# 12.00%	of all branches

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1,242,670,094	branch-misses	# 12.00%	of all branches

12% of all branches!?!

Samples: 70K of event 'branch-misses:p', 2250 Hz, Event count (approx.): 1199803307
dod::Scene::intersect /home/matthew/dev/pt-three-ways/cmake-build-release/bin/pt_thre

Percent	Instruction
	vmovsd 0x8(%rsp),%xmm14
	vfmadd231sd %xmm11,%xmm9,%xmm10
	vfmadd231sd %xmm2,%xmm0,%xmm10
	vmulsd %xmm10,%xmm7,%xmm0
	vcomisd %xmm0,%xmm14
44.86	ja 350
	vcomisd 0x5e89a(%rip),%xmm0 # 6de48 <sRGB_xy+0x1c8>
6.66	↓ ja 350
	vmulsd %xmm2,%xmm12,%xmm9
	vfmsub231sd %xmm13,%xmm6,%xmm9
	vmulsd %xmm11,%xmm6,%xmm6
	vfmsub231sd %xmm2,%xmm1,%xmm6
	vmulsd %xmm13,%xmm1,%xmm1
	vmulsd %x38(%rsp),%xmm6,%xmm10
	vfmsub132sd %xmm12,%xmm1,%xmm11
	vfmadd231sd 0x28(%rsp),%xmm9,%xmm10
	vfmadd231sd 0x30(%rsp),%xmm11,%xmm10
	vmulsd %xmm10,%xmm7,%xmm10
	vcomisd %xmm10,%xmm14
1.40	↓ ja 350
	vaddsd %xmm10,%xmm0,%xmm1
	vcomisd 0x5e84a(%rip),%xmm1 # 6de48 <sRGB_xy+0x1c8>
0.49	↓ ja 350
	vmulsd %xmm6,%xmm5,%xmm6
	vfmadd132sd %xmm9,%xmm6,%xmm4
	vfmadd132sd %xmm3,%xmm4,%xmm11
	vmulsd %xmm11,%xmm7,%xmm7
	vcomisd 0x5b925(%rip),%xmm7 # 6af40 <std::_Sp_make_shared_tag::
	seta %sil
	vcomisd %xmm7,%xmm15
0.09	seta %8b
	and %r8b,%sil
	↓ je 350
	test %dil,%dil
0.02	↓ je 3e0
	vmovsd %xmm10,0x10(%rsp)
	vmovsd %xmm0,0x18(%rsp)
	vmovsd %xmm8,0x20(%rsp)
	mov %rax,%r9
	vmoveapd %xmm7,%xmm15
	xchq %ax,%ax
46.09	lnc %rax
	add \$0x48,%rdx
350:	

```
for /* all triangles */ {
    auto u = calcU(/*...*/);
    if (u < 0 || u > 1) {
        continue;
    }
    auto v = calcV(/*...*/);
    if (v < 0 || u + v > 1) {
        continue;
    }
    auto dist = calcD(/*..*/);
    if (dist < nearest) {
        nearest = dist;
    }
}
```

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}
```

```
vcomisd xmm14, xmm0 ; 0 >= u?
ja skip
vcomisd xmm0, [1.0] ; u >= 1.0?
ja skip
```

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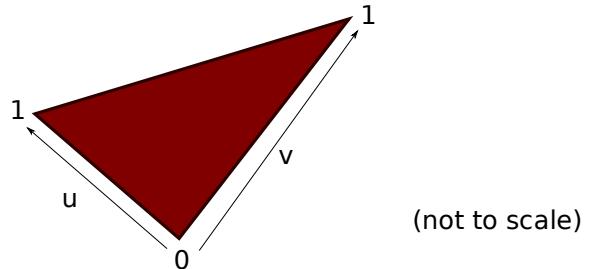
```

```

vcomisd xmm14, xmm0 ; 0 >= u?
ja skip
vcomisd xmm0, [1.0] ; u >= 1.0?
ja skip

```

ray/plane intersection point
X



BRANCH PREDICTION

- $u < \theta$ unpredictable
 - $u > \theta$ unpredictable
-

BRANCH PREDICTION

- $u < \theta$ unpredictable
 - $u > 1$ unpredictable
 - $(u < \theta \text{ } || \text{ } u > 1)$ *should be* predictable*
-

BRANCH PREDICTION

- $u < 0$ unpredictable
 - $u > 1$ unpredictable
 - $(u < 0 \text{ } || \text{ } u > 1)$ *should be* predictable*
 - $(u < 0 \text{ } || \text{ } u > 1 \text{ } || \text{ } v < 0 \text{ } || \text{ } u + v > 1)$ more so
-

BRANCH PREDICTION

- $u < 0$ unpredictable
- $u > 1$ unpredictable
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 - * Provided compiler combines conditions...

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 - * Provided compiler combines conditions...
 $(u < 0) \text{ } | \text{ } (u > 1) \text{ } | \text{ } \dots$

```
auto u = calcU(/*...*/);
if (u < 0 || u > 1) {
    continue;
}
auto v = calcV(/*...*/);
if (v < 0 || u + v > 1) {
    continue;
}
```

```
auto u = calcU(/*...*/);
auto v = calcV(/*...*/);
if ((u < 0) | (u > 1)
    | (v < 0) | (u + v > 1)) {
    continue;
}
```

FINAL STATS

Suzanne DoD: 106s → 68s (36% faster)

FINAL STATS

Scene	OO	FP	DoD
Cornell	72 → 64	82 → 64	72 → 56
Owl	96 → 96	101 → 100	64 → 64
Suzanne	80 → 104 (!)	119 → 82	106 → 68

IF I HAD MORE TIME...

- Code on [GitHub](#)
 - Threading
 - Devirtualisation
 - Future directions...
 - DoD improvements
 - Thanks
-

GO WRITE SOMETHING COOL!

