



Combining Co-Routines and Functions into a Job System

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20
21



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About Myself

- Professor for Computer Science
- University of Vienna, Austria: founded 1365, >90000 students
- Entertainment Computing Research Group
 - Efficiency and performance of game engines, AI, networking, VR ...
- Teaching: 3D Graphics, AI, Physics for games, Game Streaming, ...
- **IFIP** (International Federation for Information Processing)
Technical Committee 14 *Entertainment Computing*



Creating Game Engines with C++

- **Vienna Game Job System +**
- **Graphics API Abstraction Layer +**
- **Vienna Entity Component System + Vienna Type List Library**
- Vienna Physics Engine +
- Vienna Game AI Engine +
- GUI
- = Vienna Vulkan Game Engine 2.0

<https://github.com/hlavacs>



```
auto prev = high_resolution_clock::now();

while( !finished() ) {

    auto now = high_resolution_clock::now();

    duration<double> delta_t = duration_cast<duration<double>>(now - prev);

    prev = now;

    window.tick(delta_t.count());

    network.tick(delta_t.count());

    physics.tick(delta_t.count());    //https://gafferongames.com/post/fix_your_timestep/

    game_logic.tick(delta_t.count());

    AI.tick(delta_t.count());

    //...

    prepare_render_next_frame();    //get idle frame buffer and record command buffers for it

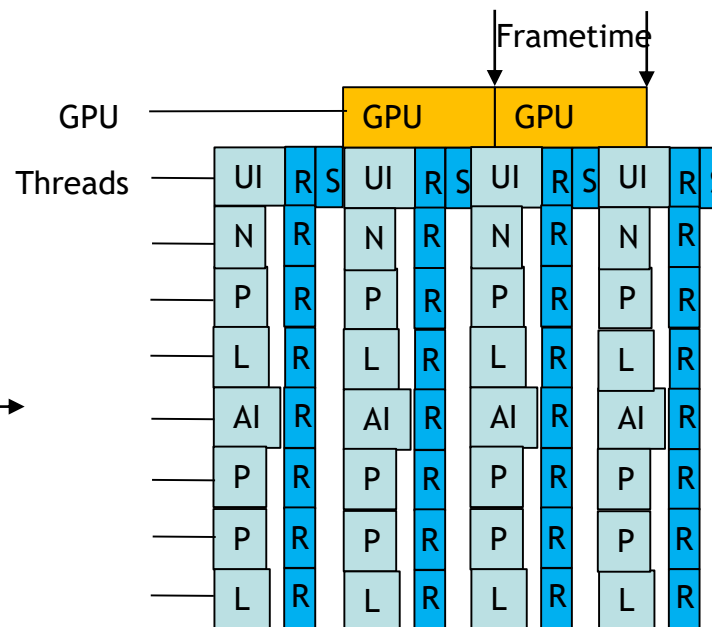
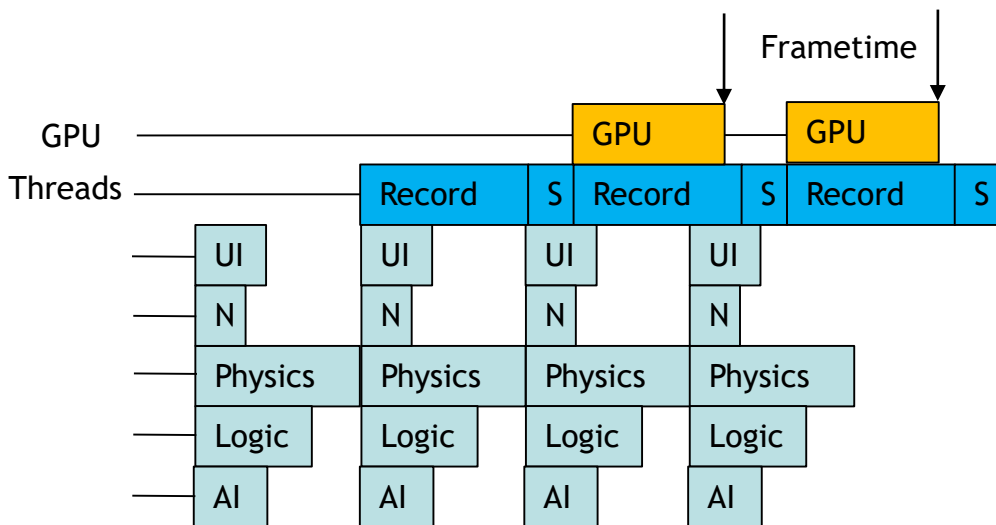
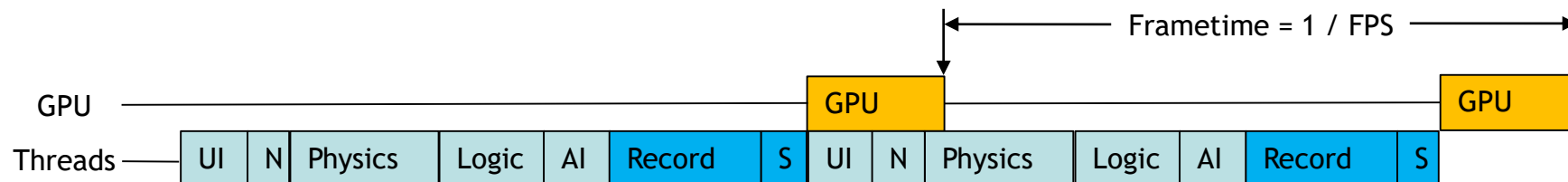
    submit_for_render();            //submit command buffers

}
```

Modern Multicore CPUs

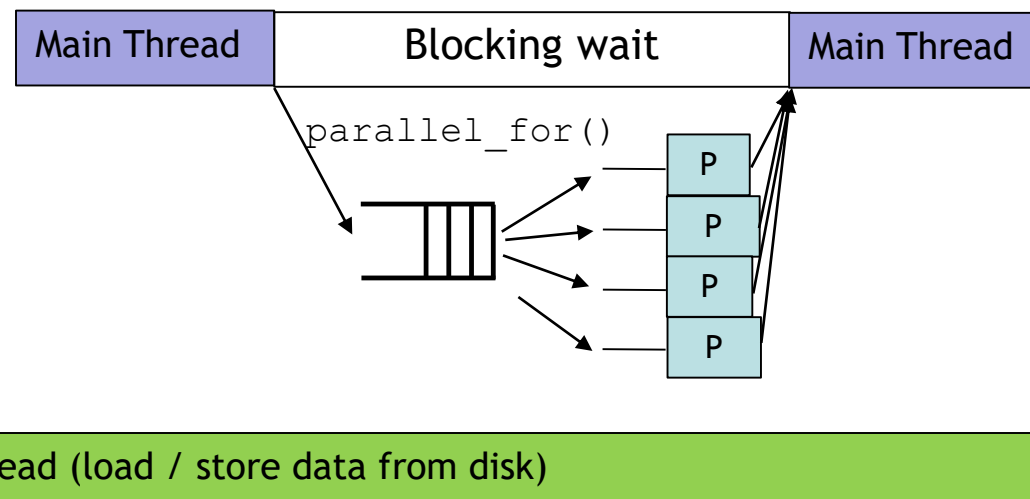
- $N > 1$ independent *cores*
- Each core : 1 thread of execution (MIMD)
- Cores share main **memory**, can share **caches**
- Simultaneous multithreading (x86 / x64) -> $2N$ **virtual** cores
- Query number of cores: `std::thread::hardware_concurrency()`
- AMD : Ryzen: 2-64, Epyc 4-64
- Intel: Core i9: 6-18, Xeon: 4-56
- Apple: M1: 4+4

Reducing the Frametime

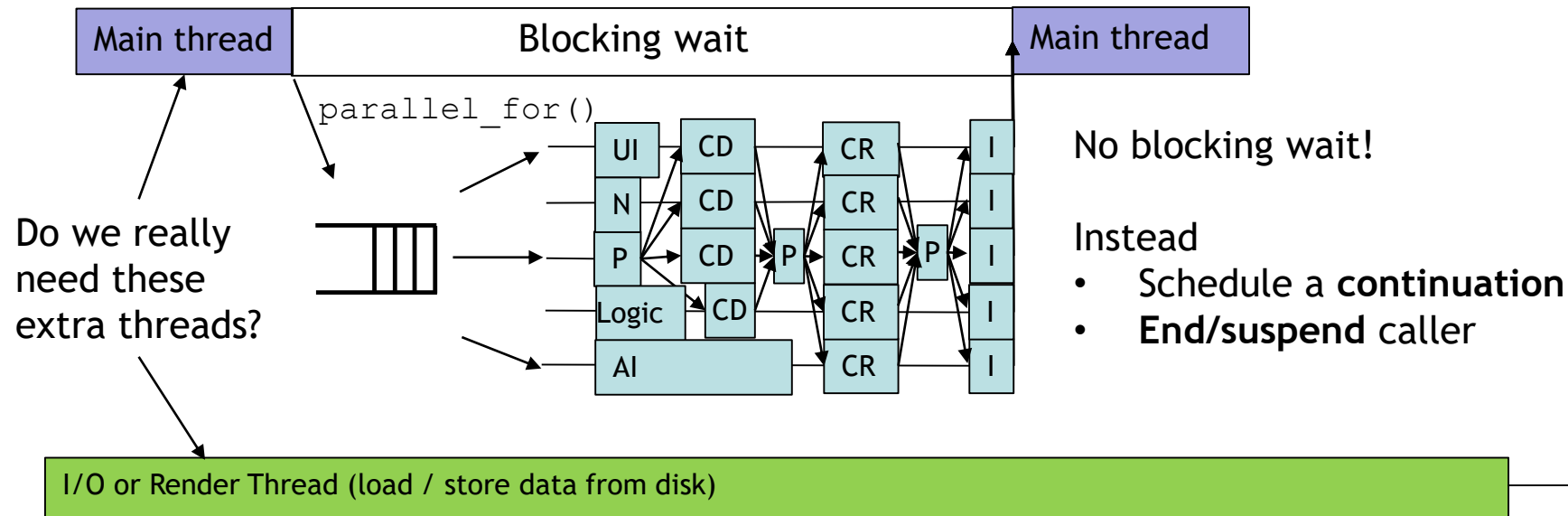
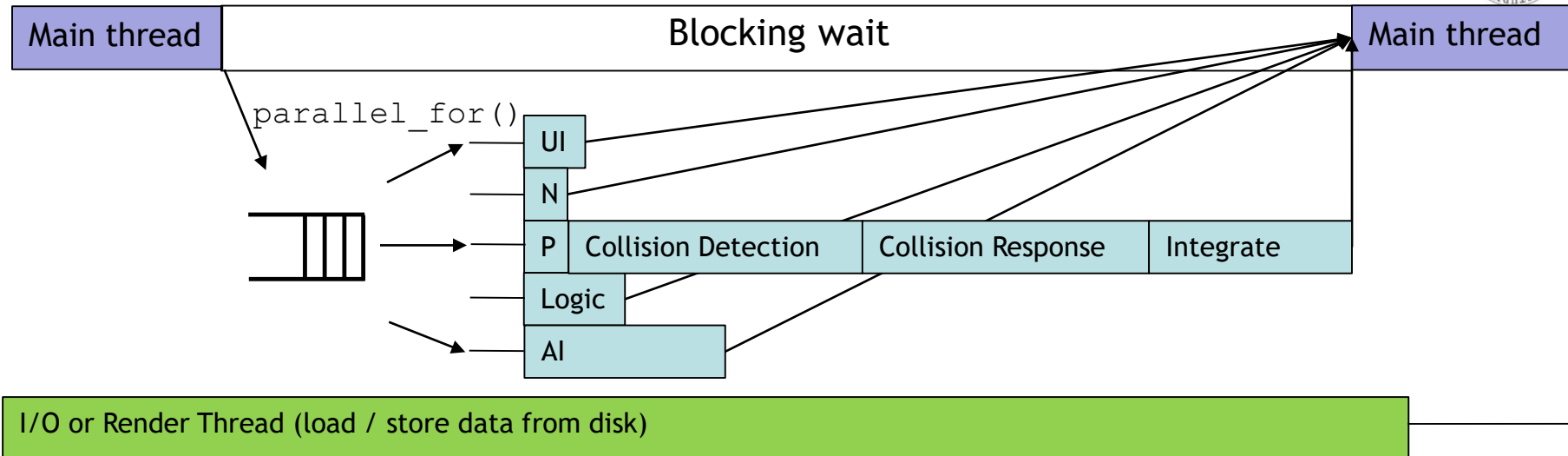


Job Systems and Thread Pools

- Starting threads is expensive -> **Thread Pool**
- **Job System** = Thread Pool + **Job Queues**
- **Main Thread** calls `parallel_for()`
 - Put jobs into queue
 - Threads take jobs out of queue



Main Thread + Job System + I/O Threads



Do we really need extra threads? No we Don't!

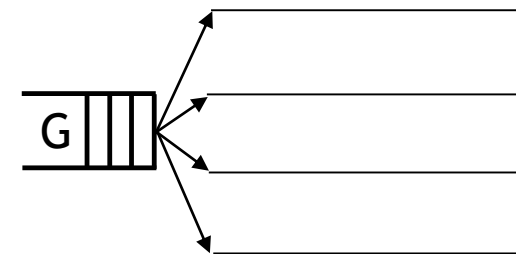
“Fun fact: Doom Eternal does not have a main or render thread. It's all jobs with one worker thread per core.”

Axel Gneiting, ID Software, March 21 2020

Further Improvements

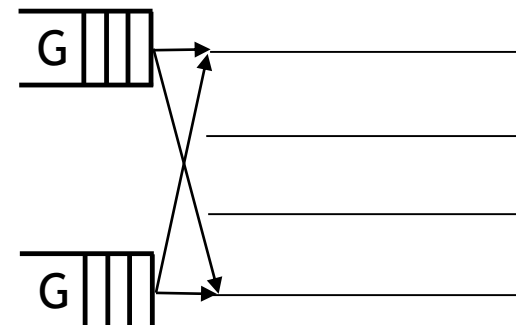
Thread-Pool only

- No thread outside the thread pool active



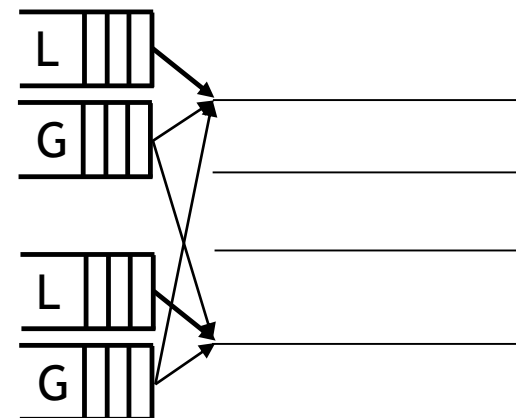
Work stealing: Each thread has its own (globally visible) job queue

- Steal jobs from other (global) queues -> **load balancing**

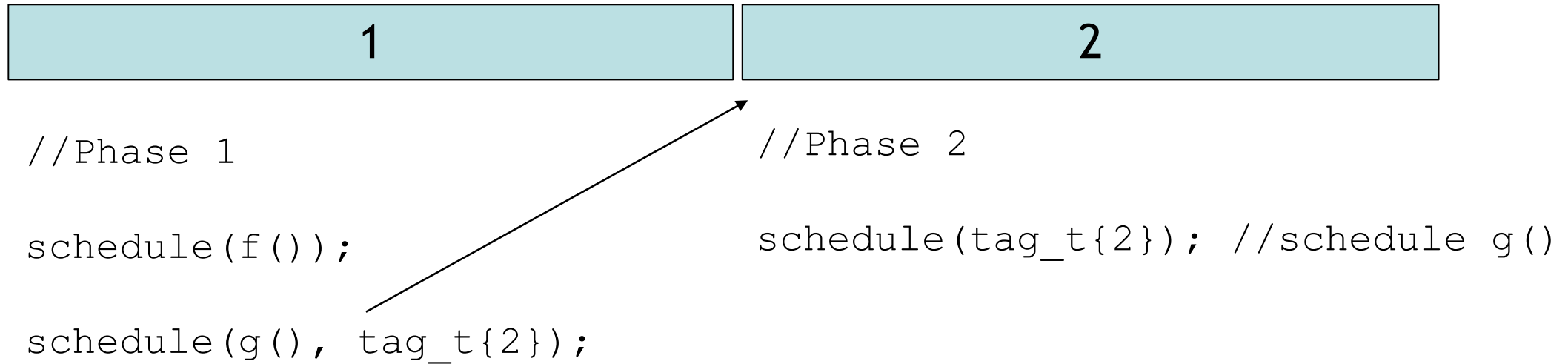


Locally and Globally visible Queues

- Local and a global (default) queue
- Steal from **global** queues



Tagged Scheduling



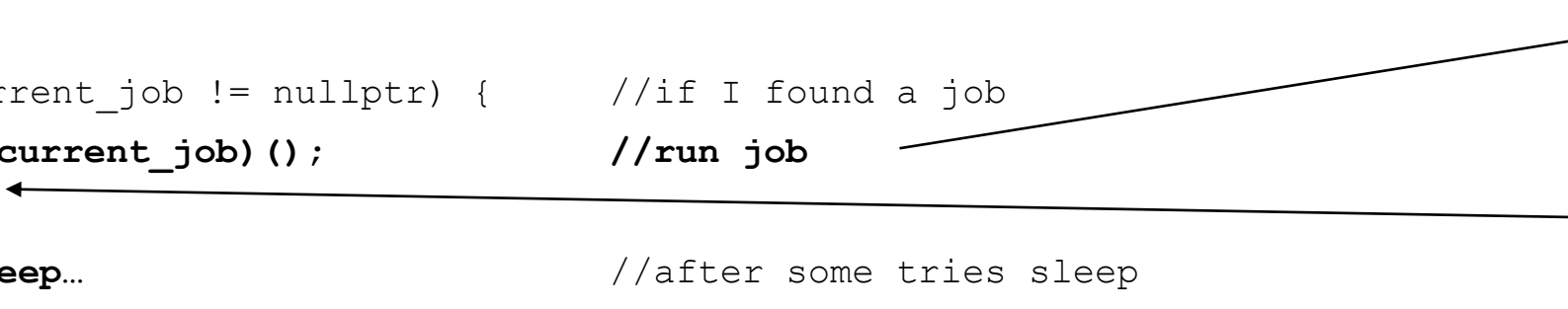
The Vienna Game Job System (VGJS)

- Experimental job system for teaching and research,...
- <https://github.com/hlavacs/ViennaGameJobSystem>
- Thread Pool only, main thread can enter thread pool as worker, include file only
- Work stealing, 1 local and 1 global queue per thread, **tagged** scheduling
- Allocate from heap or memory resource
- Log performance and visualize in Google Chrome *chrome://tracing/*
- Scheduling jobs
 - `schedule(...)`
 - `continuation(...)`
 - `co_await ...`

VGJS Thread Loop

```
void thread_task() noexcept {
    //initialize...
    while (!m_terminate) { //Run until the job system is terminated
        m_current_job = m_local_queues[myidx.value].pop(); //get a job from local queue
        if (m_current_job == nullptr) {
            m_current_job = m_global_queues[m_thread_index.value].pop(); //get a job from global queue
        }
        num_try = ...;
        while (m_current_job == nullptr && --num_try > 0) {
            if (++next >= m_thread_count) next = 0;
            m_current_job = m_global_queues[next].pop(); //try steal job from other global queue
        }
    }
    if (m_current_job != nullptr) { //if I found a job
        (*m_current_job)(); //run job
    } else {
        // sleep... //after some tries sleep
    }
}
}
```

```
void f() {
    int var;
    //...
    return;
}
```



What can we schedule?

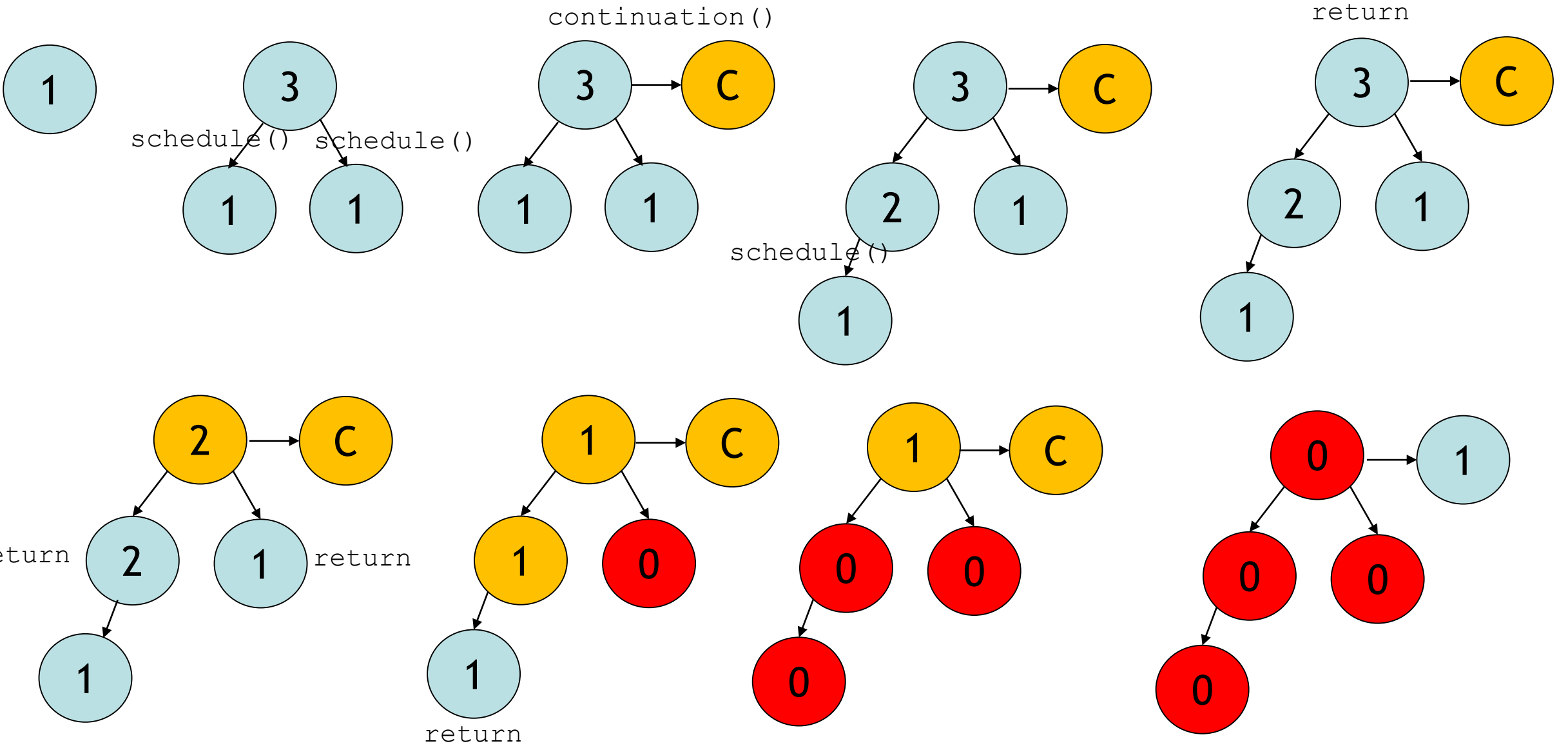
- **Normal Functions /class member functions**
 - Lambdas, `std::function<void(void)>`
 - `std::bind`
 - `void (*function)()`
 - `struct Function{}: std::function<void(void)>`, thread, type and id for logging
 - Tags
- **Coroutines of type `Coro<RETURNTYPE>`**
 - Thread, type and id with `operator()`
- **`std::tuple` and `std::vector` containing an arbitrary number of them**

Finishing and Continuations

- ***Finishing:*** `return` + all children finished (`counter == 0`)
- *Notify* parent (if there is any)
- If *continuation*, then schedule it

Dependencies and Continuations

active inactive finished



Examples - Functions

```
void driver(int i) {
    //...
}

void end() {
    //schedule()/continuation()...
}

void test() {
    schedule([] () { driver(1); }); //lambda

    std::function<void(void)> f1([] () { driver(2); }); //std::function
    schedule(f1);

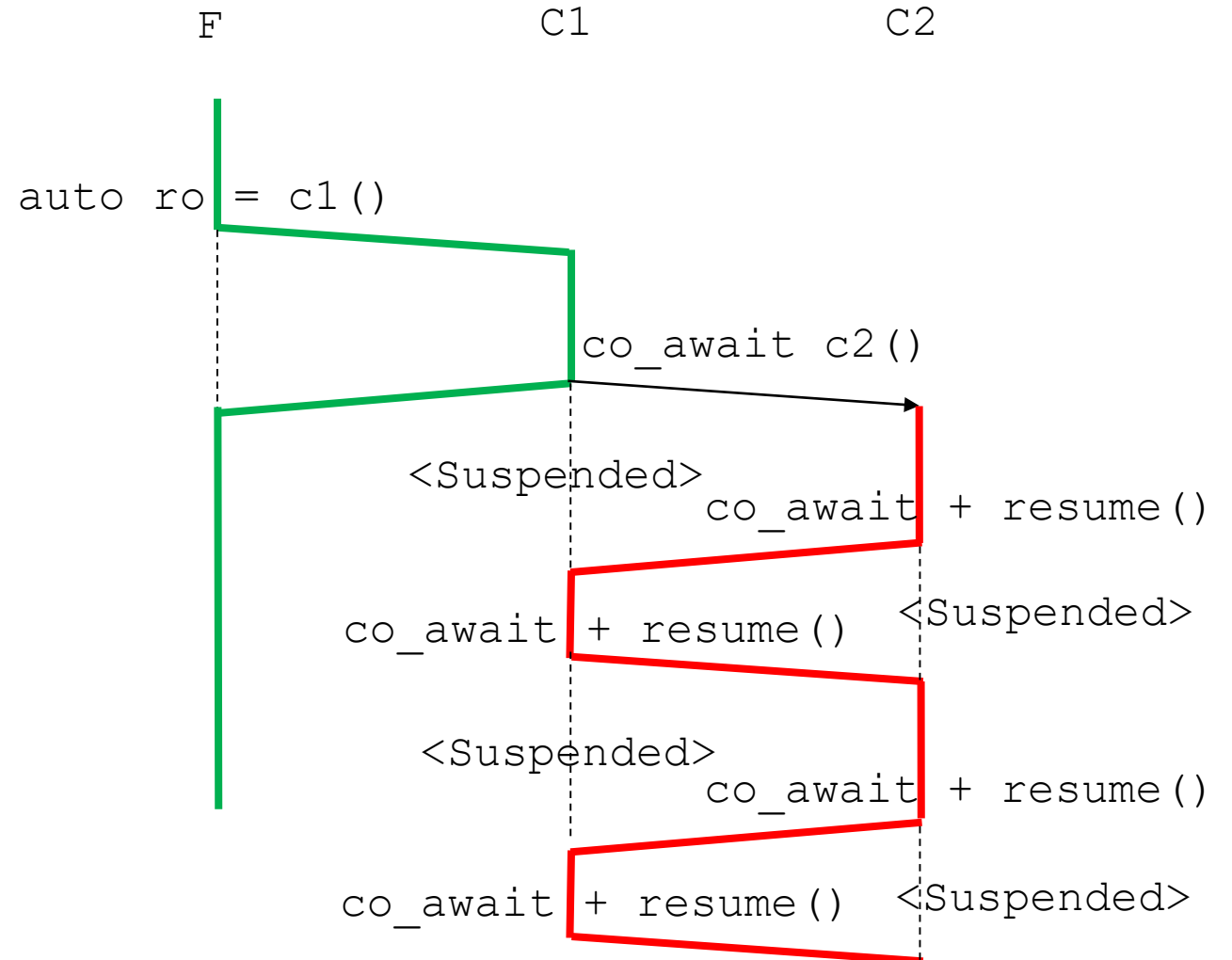
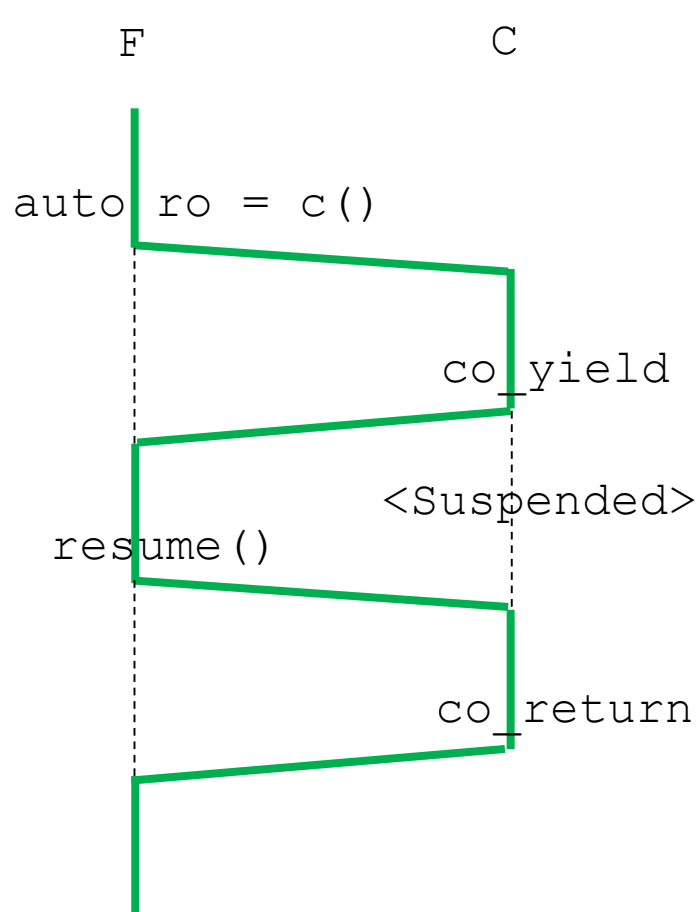
    schedule(std::bind( driver, 3 )); //callable object

    schedule( Function{ [=] () {driver(3); },
        thread_index_t{ 0 }, thread_type_t{ 0 }, thread_id_t{ 1 } }); //Function

    continuation( end ); //void(void)
}
```

- Normal functions (synchronous)
 - Stack frame
 - **Gone** after `return`
- **Coroutines (asynchronous) can**
 - *Suspend* to wait for a result, *resume* with same state
 - **First time called:** allocate heap memory (*coroutine frame*)
 - **Suspend:** stack frame -> coroutine frame, **return** to caller/resumer
 - **Resume:** coroutine frame -> stack frame, **resume**
 - **Destroy:** deallocate coroutine frame

Coroutine Call Examples



Coroutines in VGJS

- Coroutines are created by **calling** them

```
Coro<float> retObj = driver(13); //create coro fr, return ret obj
```

- Schedule into VGJS queue

- `schedule(retObj);` //from function
- `continuation(retObj);` //from function
- `co_await retObj;` //from coroutine
- `co_await parallel(retObj, Coro_vector, std_f1, ...);` //from coro

- Thread grabs and *resumes* it

Coroutines in VGJS - Example

```
void test() {
    Coro<float> retObj = driver(13);
    schedule(retObj); //put promise into a VGJS queue, a thread will grab it in its loop
    if(retObj.ready()) std::cout << "Result " << retObj.get() << std::endl;
    return;
}

Coro<float> driver(int i) {
    int res = co_await coroTest(i); //or co_await parallel(a(), vector, ...)
    //resume here, a coroutine is its own continuation!
    co_return 0.0f;
}

Coro<int> coroTest(int i) {
    co_await thread_index_t{ 0 };
    co_yield 10;
    co_return 0;
}
```

VGJS Coroutines

```
void test() {
```

```
    Coro<float> retObj = driver(13);  
    schedule(retObj);  
}
```

Coroutine Frame

Suspend point

Function parameters

Stack frame

```
Coro_promise<float> promise;  
promise.get_return_object()
```

Return Object Coro<T>

```
using promise_type =  
    Coro_promise<T>;
```

Coro_promise<T>

```
Coro<float> driver(int i) {  
    Coro<int> retObj = coroTest(i);  
    try {  
        int res = co_await retObj;  
        Coro<int> defObj = coroTest(i);  
    } int res = co_await retObj;  
    co_return 0.0f;  
}  
  
catch (...) {  
    promise.unhandled_exception();  
}  
  
FinalSuspend:  
    co_await promise.final_suspend();  
}
```

Awaiter

Awaiter

Coro_promise<T>

```
Coro<int> coroTest(int i) {  
    co_await thread index t{ 0 };  
    co_yield 10;  
    co_return i;  
}
```

Awaiter

Awaiter

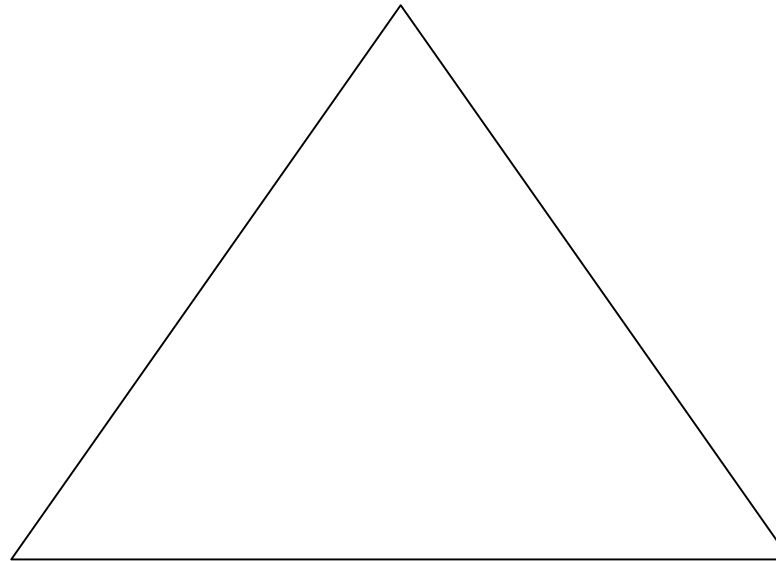
Awaiter

Awaiter

Coroutine returning an int result

Main Classes to adapt Coroutine Behavior

Return Object for the caller

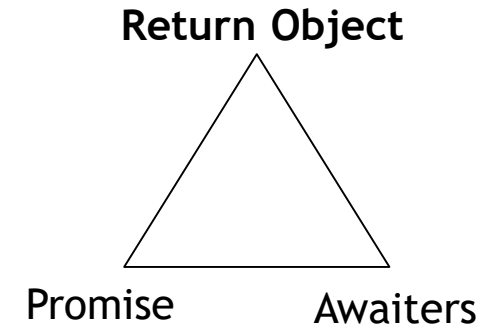


Promise:
Adapts the coroutine,
determines the **awaiters**

Awaiter:
Manages `co_await`
(suspend and resume)

Return Object

- Specifies `promise_type` (alternative: *coroutine_traits*)
- Created by the **promise** via `get_return_object()`
- Returned to the caller (at first suspension point / completion)

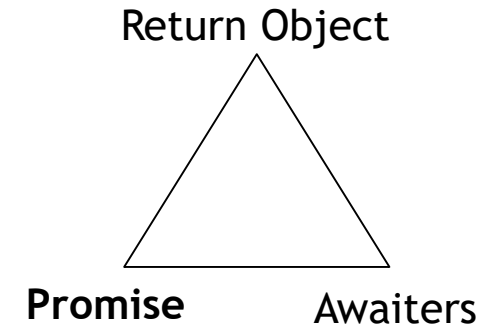


```
void test() {  
    Coro<float> retObj = driver(13);  
    //...  
}
```

- VGJS return objects: test whether results **ready**, **get** results/promise ptr, **resume** coro, **set** thread index, type, id

Promises

- Alter **behavior** of coroutine through **API**
- Created by **first call to coroutine**, part of the **coroutine frame**
- **Return object class determines promise type** (`promise_type`), but **promise creates the return object**
- Destroyed when the coroutine frame gets destroyed



The Promise API in VGJS

```
template<typename T = void>
class Coro_promise : public Coro_promise_base {
protected:
    //...

public:
    Coro_promise() noexcept;
    suspend_always      initial_suspend() noexcept { return {}; }
    Coro<T>              get_return_object() noexcept;

    void                return_value(T t) noexcept;
    final_awaiter<T>    final_suspend() noexcept { return {}; };

    template<typename U>
    awaitable_tuple<T, U>      await_transform(U&& func) noexcept;
    template<typename... Ts>
    awaitable_tuple<T, Ts...> await_transform(std::tuple<Ts...>&& tuple) noexcept; //ca parallel(...);

    awaitable_resume_on<T>    await_transform(thread_index_t index) noexcept; //co_await thread_index_t
    awaitable_tag<T>         await_transform(tag_t tg) noexcept;             //co_await tag_t

    yield_awaiter<T>         yield_value(T t) noexcept;
};
```

Coro<float> driver(int i) {
co_await promise.initial_suspend();
 try {
 Coro<int> retObj = coroTest(i);
 int res = **co_await** retObj;
co_return 0.0f;
 }
 catch (...) {
 promise.unhandled_exception();
 }
FinalSuspend:
co_await promise.final_suspend();
//Coro<float> retObj = driver(13);

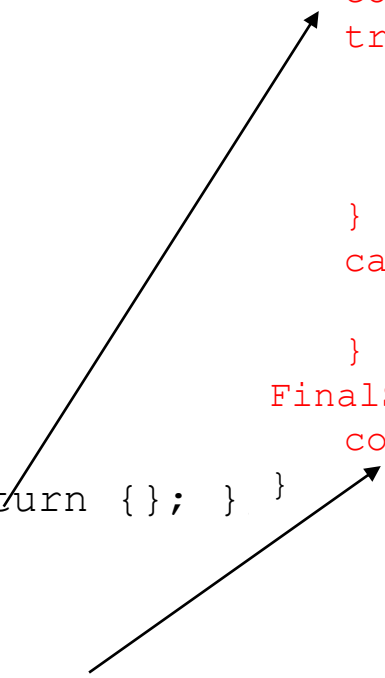
//co_return <value>

//co_await f();

//ca parallel(...);

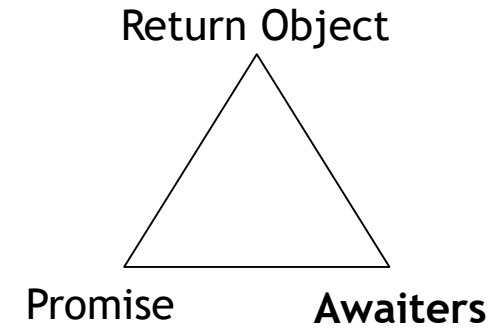
//co_await thread_index_t
//co_await tag_t

//co_yield <value>
}



Awaiters

- Manage `co_await` and `co_yield`



- **Default awaiters available** (e.g. for `initial_suspend()` etc.)
 - `suspend_always`
 - `suspend_never`
- Inherit default behavior
- Use directly, via **awaitable** (operator `co_await`) or **`promise.await_transform(<expr>)`** (`co_await`)

What happens when you call `co_await <expr>`?

```
{
    auto&& awaiter = getawaiter( promise, <expr> ); //promise.await_transform(<expr>)

    if (!awaiter.await_ready()) {                                     //suspend?
        using handle_t = std::experimental::coroutine_handle<P>;

        <suspend-coroutine>                                         //suspend the coroutine

        if (awaiter.await_suspend(handle_t::from_promise(promise))) { //code after suspend
            <return-to-caller-or-resumer>
        }
        <resume-point>                                             //resume the coroutine
    }

    return awaiter.await_resume(); //after resume, return result
}
```

VGJS Awaiters

- `Initial_suspend (suspend_always)`
- `Final_suspend`
- `co_await parallel(...)` //wrapper for `std::tuple<...>`
- `co_await thread_ID_t{...}`
- `co_await tag_t{...}`
- `co_yield <value>`

```
Coro<float> driver(int i) {  
    co_await promise.initial_suspend();  
    try {  
        Coro<int> retObj = coroTest(i);  
        int res = co_await retObj;  
        co_return 0.0f;  
    }  
    catch (...) {  
        promise.unhandled_exception();  
    }  
    FinalSuspend:  
    co_await promise.final_suspend();  
}
```

VGJS Awaiter for `co_await parallel(...)`

```
template<typename PT, typename... Ts>
struct awaitable_tuple : suspend_always {
    tag_t          m_tag;          ///
```

```
//co_await thread_index_t{0}

template<typename PT>
struct awaitable_resume_on : suspend_always {
    thread_index_t m_thread_index;           //the thread index to use

    //do not go on with suspension if the job is already on the right thread
    bool await_ready() noexcept {
        return (m_thread_index == JobSystem().get_thread_index());
    }

    void await_suspend(n_exp::coroutine_handle<Coro_promise<PT>> h) noexcept {
        h.promise().m_thread_index = m_thread_index;
        JobSystem().schedule_job(&h.promise());
    }

    awaitable_resume_on(thread_index_t index) noexcept : m_thread_index(index) {};
};
```

- **Coroutine A coawaiting coroutine C**
 - In sync, **return object** in A can destroy C
- **Function F scheduling coroutine C**
 - F may return before C is finished -> C must destroyed **itself**
 - What if F tries to get the result but C is destroyed?
 - Store result in `std::shared_ptr<std::pair<bool, T>` shared by **return object** in F and **promise** of C

```
Coro<> A() {  
    int res = co_await C();  
}
```

```
void F() {  
    Coro<int> ro = C();  
    schedule(ro);  
    if(ro.ready()) {  
        int res = ro.get()  
    }  
    return;  
}
```


VGJS Final Awaiter of a Coroutine

```
//bool await_suspend()  
//if true -> suspend (do not destroy the coroutine frame)  
//if false -> do not suspend (destroy the coroutine frame)
```

```
template<typename U>  
struct final_awaiter : public suspend_always {
```

```
    bool await_suspend(n_exp::coroutine_handle<Coro_promise<U>> h) noexcept {  
        bool is_parent_function = ...; //true if parent is a function
```

```
        //indicate parent that child has finished
```

```
        //if parent is coroutine -> suspend (return true)  
        //if parent is function -> destroy (return false)  
        return !is_parent_function;
```

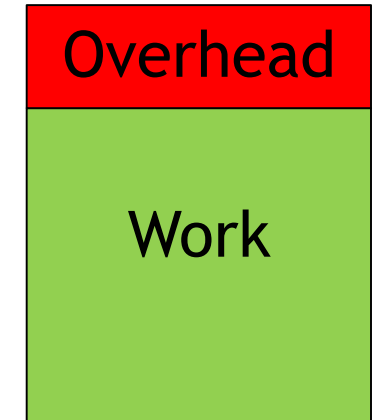
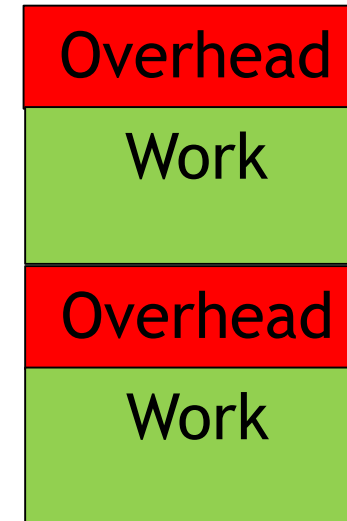
```
    }
```

```
};
```

```
Coro<float> driver(int i) {  
    co_await promise.initial_suspend();  
    try {  
        Coro<int> retObj = coroTest(i);  
        int res = co_await retObj;  
        co_return 0.0f;  
    }  
    catch (...) {  
        promise.unhandled_exception();  
    }  
    FinalSuspend:  
    co_await promise.final_suspend();  
}
```

Performance Considerations

- Job Systems do have some **overhead**
- Scheduling, managing jobs, queues
- **Jobs should not be too small** (overhead would dominate)
- Increase **job size** to increase **efficiency**



Speed Up and Efficiency

Speed Up $S(n) := \frac{T_1}{T_n}$

Example: $T_1 = 100\mu s, T_4 = 50\mu s$ then $S(4) = 2$

Efficiency $E(n) := \frac{S(n)}{n}$

Example: $E(4) = 0.5$ or 50%

Questions

1. Minimum job size (CPU time) for 85/90/95% efficiency?
2. What is more efficient: function pointers, `std::function`, or coroutines?

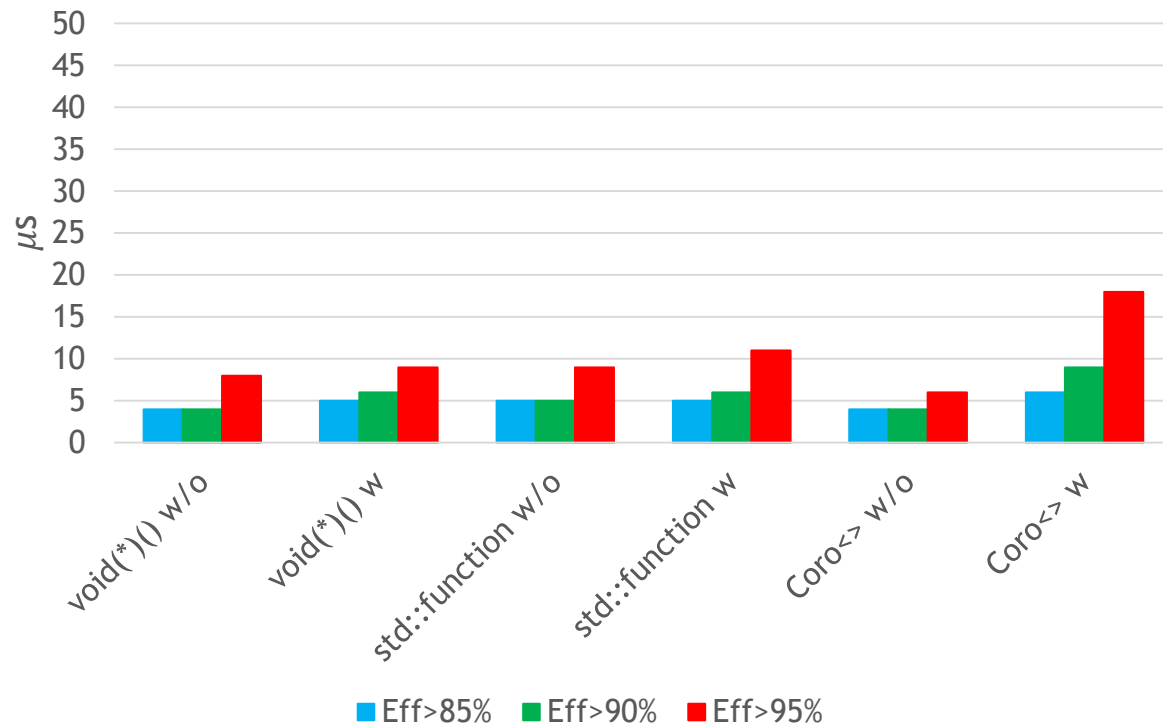
System under Test

- AMD Ryzen 7 3900X, 12/24 cores, 3793 MHz
- X570 AORUS ULTRA
- 768 KB L1, 6 MB L2, 64 MB L3 Cache
- 32 GB DDR4 RAM, 2133 MHz, DIMM
- MS Windows 10, Ver 10.0.19043

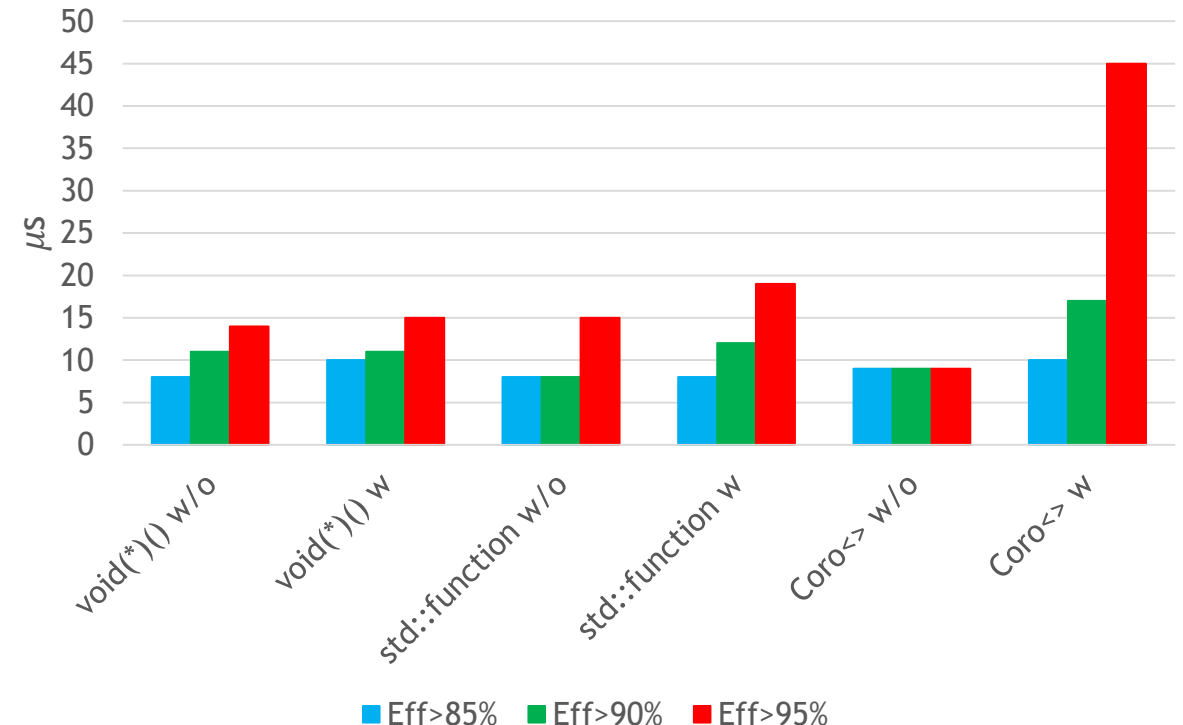
Measurement Results

Minimum Job Size (μ s) to reach efficiency X %

12 Threads



24 Threads



w/o: not including job allocation
w: job allocation included

Conclusions

- Vienna Game Job System (VGJS)
- Thread Pool only, **tagged** jobs for **phases**
- Combines **coroutines** with normal **functions**
- Coroutines can return results
- Functions can interact with Coros, but complications
- Good efficiency for larger amounts of threads
- **Allocating** coroutines comes with a price

Thank you!

Any Questions?

Reach me at

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<http://entertain.univie.ac.at/~hlavacs/>

<https://github.com/hlavacs/ViennaGameJobSystem>

<https://www.linkedin.com/in/helmut-hlavacs-972b9aa/>