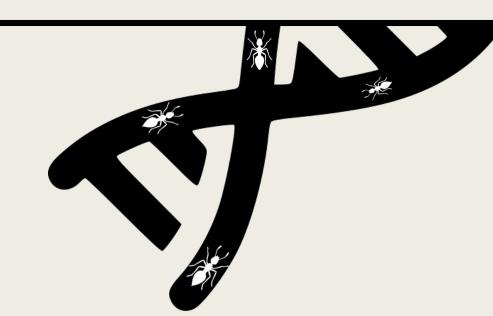


AN HYBRID METAHEURISTIC APPROACH TO THE TRAVELLING SALESMAN PROBLEM



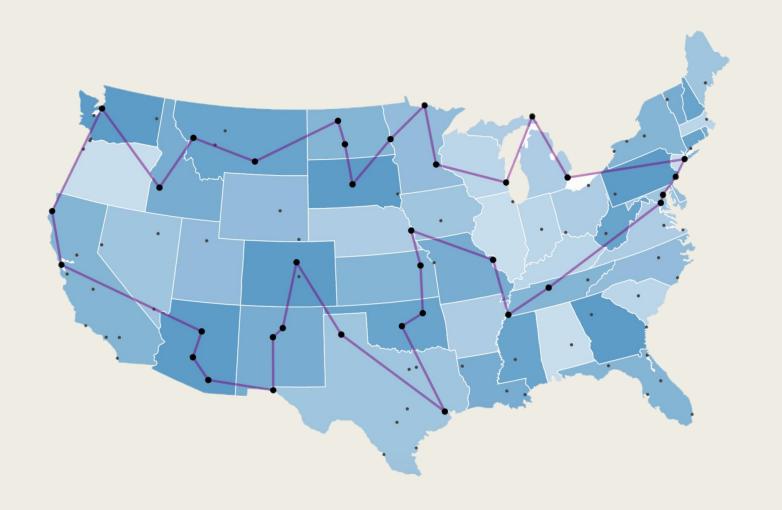
Decision ModelsFinal Project



DARIO BERTAZIOLI FABRIZIO D'INTINOSANTE MASSIMILIANO PERLETTI

INTRODUCTION

Travelling Salesman Problem



TSP

is an algorithmic problem tasked with finding the shortest route between a set of points and locations that must be visited

DATASETS

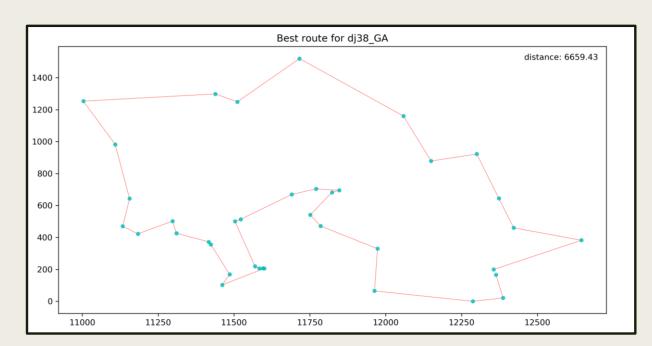
■ dj38

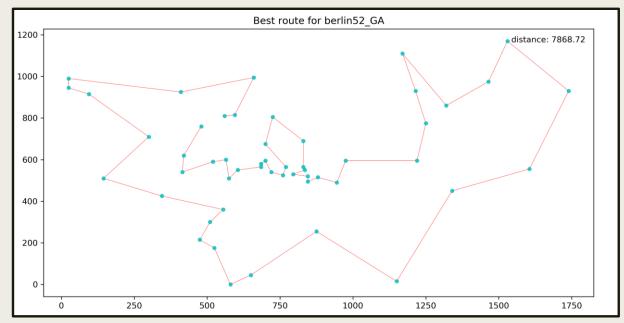
■ berlin52

■ ch130

■ d198

■ pr1002





METHODOLOGICAL APPROACH

ACO - Ant-Q - GA - KGA

ANT FAMILY ALGORITHMS

- inspiration from biology
- accomplish difficult tasks exploiting collaboration
- pheromone as a communication channel
- the more ants follow a specific path,
 the more likely it becomes to be followed
- shortest path problems



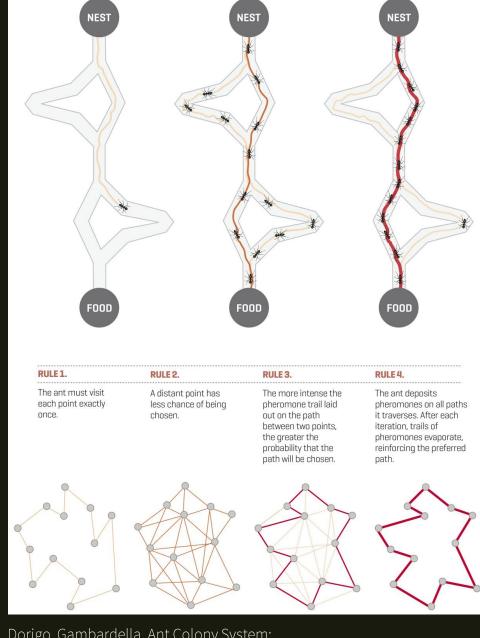
Ant Colony Optimization

- multi-agent collaborative approach
- pheromone evaporation and deposit
 - exploration vs exploitation tradeoff

$$\tau_{ij} = (1 - \rho)\tau_{ij} + \Delta\tau_{ij}$$

- artificial ants might have different aims
 - pheromone guided moves vs heuristically driven ones

$$p_{ij}^k = \frac{[\tau_{ij}]^{\alpha} [\eta_{ij}]^{\beta}}{\sum_{l \in N_i^k} [\tau_{il}]^{\alpha} [\eta_{il}]^{\beta}} \quad \text{if } j \in N_i^k$$



Dorigo, Gambardella, Ant Colony System:

A Cooperative Learning Approach to the Travelling Salesman Problem. In: IEEE Transactions on Evolutionary Computation, Vol.1 No.1, pp.53-66

Ant-Q

a reinforcement learning approach

main idea

■ integrate a Q-learning-like rule in the pheromone update procedure

$$\tau_{ij} = (1 - \alpha)\tau_{ij} + \alpha(\Delta\tau_{ij} + \gamma \max_{l \in N_j^k} \tau_{jl})$$

and in the single decision process

$$s = \begin{cases} arg \ max_{a \in J_k(s)}[Q(s, a)]^{\alpha} [\eta(s, a)]^{\beta} & \text{if } q \leq q_0 \\ S & \text{otherwise} \end{cases}$$

Parallel Implementation Hints

ACO algorithm are quite memory expensive, but... naturally parallelizable!



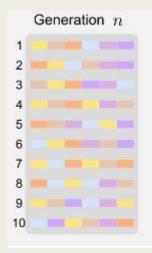
- parallel systems (parent/children)
 - running on each core
- local pheromone matrices
- global updates every iteration (parent)
 - providing each child with an updated mean pheromone matrix
- technically
 - Open MPI (https://www.open-mpi.org)
 - mpi4py (https://mpi4py.readthedocs.io/en/stable)

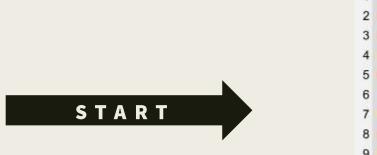
GENETIC ALGORITHM

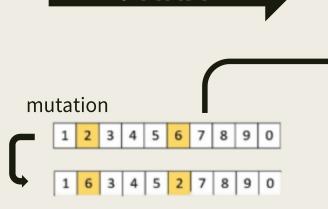
- based on a biological metaphor (Darwinism)
- individuals as chromosomes (genotypes) into a population
- individuals' features as phenotypes
- crossover operator as gene transfer
- random mutation at each generation

Genetic Algorithm

Generate random population *(chromosomes)*







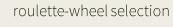
Evaluation (rank pop)



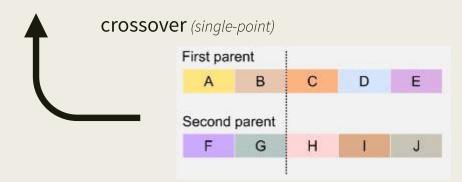


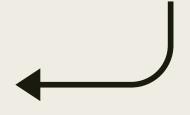
selection mechanism and elitism



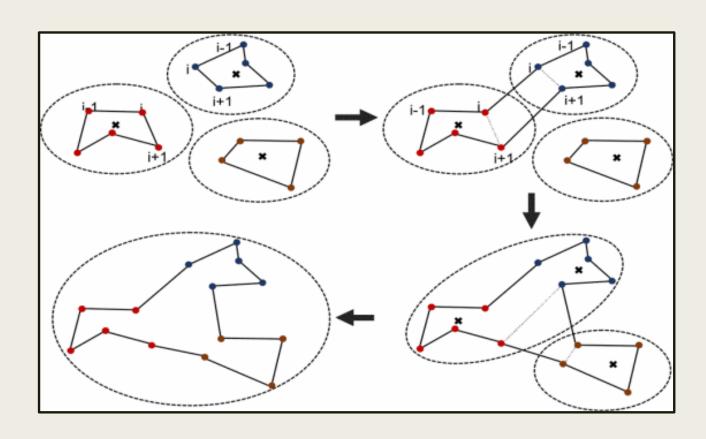








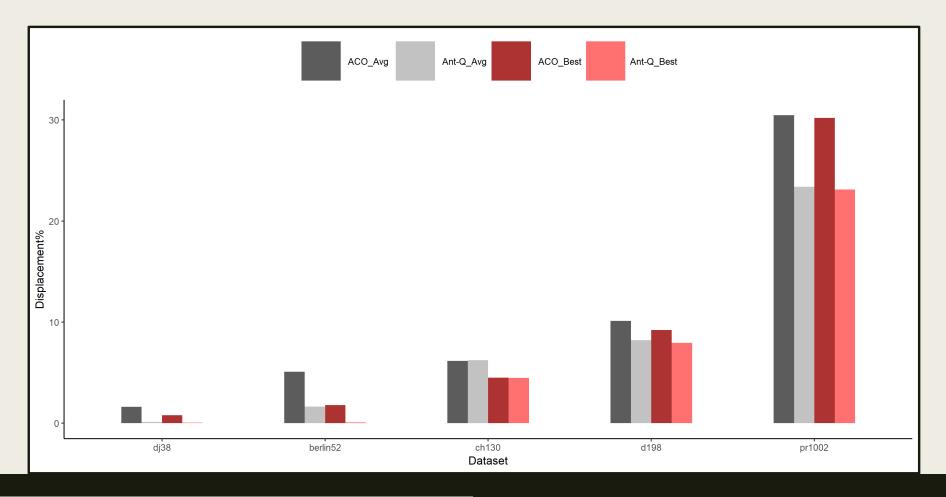
K-means Genetic Algorithm



- hybrid implementation of GA
- transform wide problem intosmaller sub-problems (clusters)
- solve sub-problems with GA
- reconstruct optimal solutionfrom sub-problems solutions

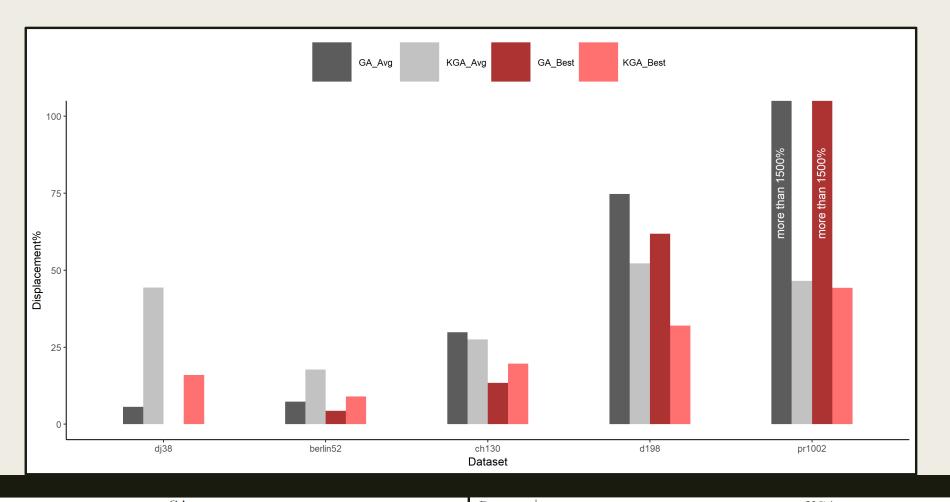
RESULTS

ACO - ANT-Q



Dataset	ACO							Dataset	Ant-Q						
	OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)		OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)
dj38 (1000 it)	6656	6763.03	75.16	6708.04	1.61	0.78	75	dj38 (1000 it)	6656	6663.99	4.16	6659.43	0.12	0.05	37
berlin $52 (1000 it)$	7542	7925.39	162.00	7677.66	5.08	1.80	320	berlin52 (1000 it)	7542	7666.17	113.87	7548.99	1.65	0.09	170
ch130 (500 it)	6110	6487.19	74.20	6385.46	6.17	4.51	9240	ch130 (500 it)	6110	6491.31	70.01	6383.42	6.24	4.47	8400
d198 (100 it)	15780	17376.23	105.81	17235.44	10.12	9.22	6540	d198 (100 it)	15780	17075.81	39.69	17032.75	8.21	7.94	2880
pr1002 (10 it)	259054	337976.61	833.96	337309.96	30.47	30.21	6180	pr1002 (10 it)	259054	319646.49	1009.39	318960.00	23.39	23.12	6120

GA - KGA



Dataset				GA				Dataset				KGA			
	OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)		OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)
dj38	6656	7032.91	574.34	6659.43	5.66	0.05	263	dj38	6656	9608.77	1817.02	7720.03	44.36	15.99	140
berlin52	7542	8095.35	167.27	7868.72	7.34	4.33	286	berlin52	7542	8879.59	446.69	8218.95	17.74	8.98	188
ch130	6110	7933.02	1041.27	6929.81	29.84	13.42	435	ch130	6110	7790.85	312.17	7314.08	27.51	19.71	409
d198	15780	27579.73	1869.54	25537.85	74.78	61.84	604	d198	15780	24023.86	3066.94	20830.94	52.24	32.01	1413
pr1002	259045	4666413.09	12608.57	4652556.08	1701.39	1696.04	2641	pr1002	259045	379495.87	6343.57	373865.26	46.50	44.32	4456

CONCLUSIONS

KEY POINTS



EFFECTIVE IMPROVEMENT OF THE HYBRIDIZED APPROACH WITH RESPECT TO THE CLASSIC VERSION OF EACH ALGORITHM



ANT FAMILY – BEST PERFORMANCES ON SMALL/MEDIUM SIZED PROBLEMS



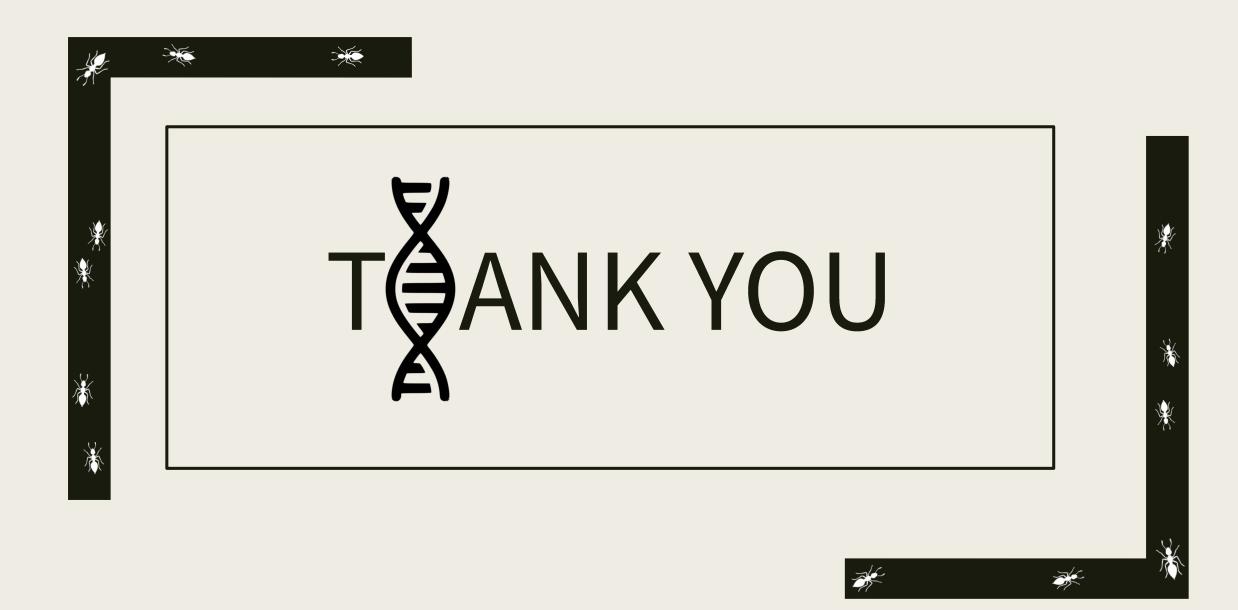
KGA – MORE PERFROMANT ON LARGE DATASETS

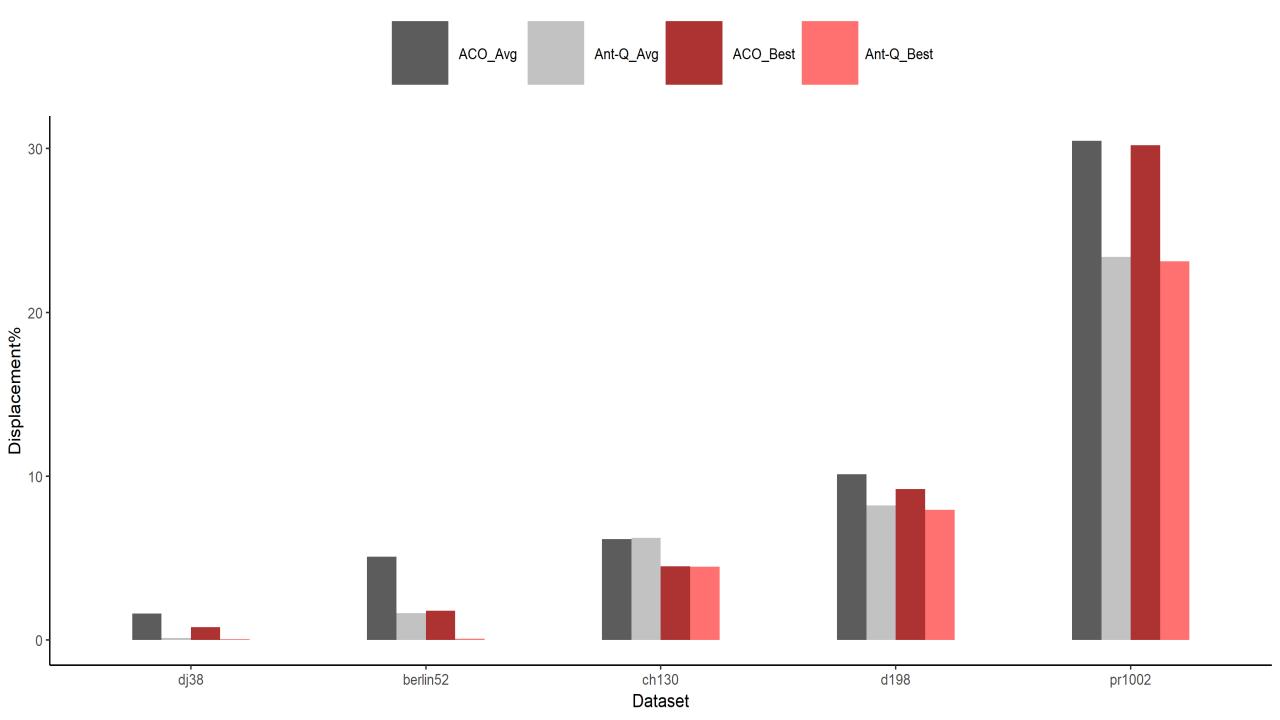


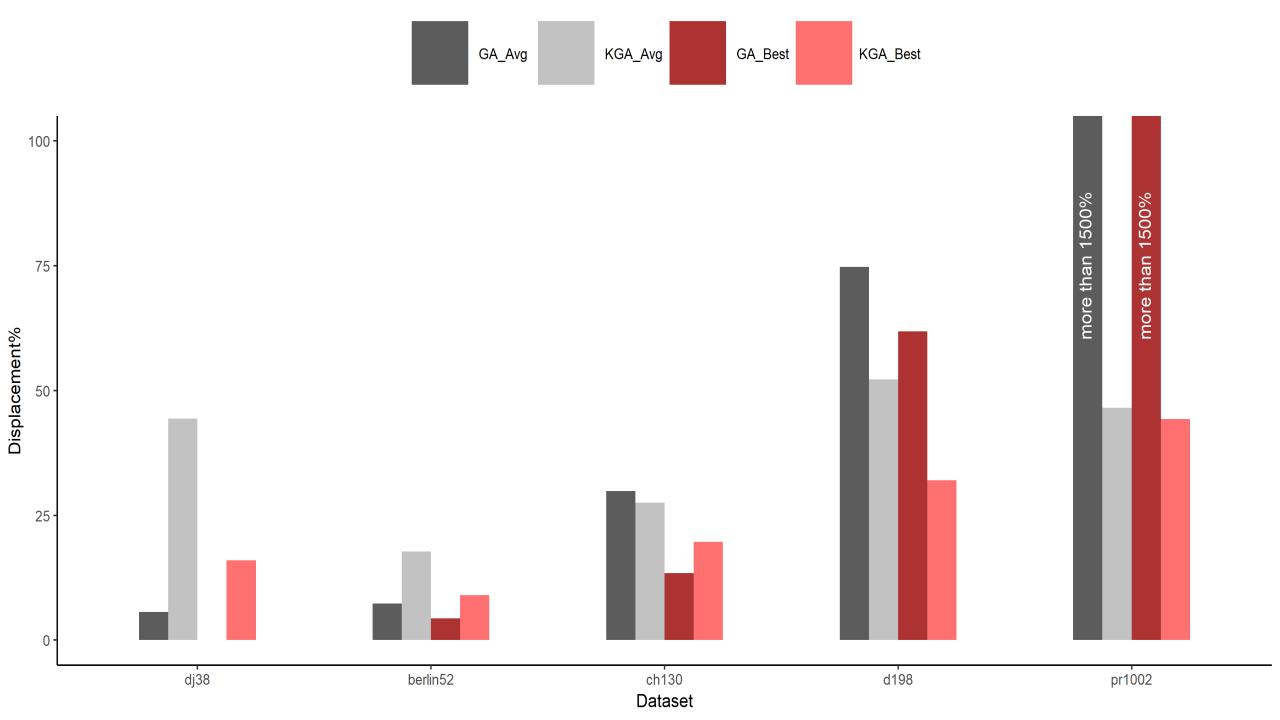
ACO AND ANT-Q SLOWER ON HIGHER
DIMENSIONS BUT FIND BETTER
SOLUTIONS THAN EA

FUTURE WORK

it could be interesting to further combine Ant-Q and KGA







Dataset				ACO			
	OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)
dj38 (1000 it)	6656	6763.03	75.16	6708.04	1.61	0.78	75
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ch130 (500 it)	6110	6487.19	74.20	6385.46	6.17	4.51	9240
d198 (100 it)	15780	17376.23	105.81	17235.44	10.12	9.22	6540
pr1002 (10 it)	259054	337976.61	833.96	337309.96	30.47	30.21	6180
Dataset				Ant-Q			
	OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)
dj38 (1000 it)	6656	6663.99	4.16	6659.43	0.12	0.05	37
berlin52 (1000 it)	7542	7666.17	113.87	7548.99	1.65	0.09	170
ch130 (500 it)	6110	6491.31	70.01	6383.42	6.24	4.47	8400
d198 (100 it)	15780	17075.81	39.69	17032.75	8.21	7.94	2880
pr1002 (10 it)	259054	319646.49	1009.39	318960.00	23.39	23.12	6120

Dataset				GA			
	OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)
dj38	6656	7032.91	574.34	6659.43	5.66	0.05	263
berlin52	7542	8095.35	167.27	7868.72	7.34	4.33	286
ch130	6110	7933.02	1041.27	6929.81	29.84	13.42	435
d198	15780	27579.73	1869.54	25537.85	74.78	61.84	604
pr1002	259045	4666413.09	12608.57	4652556.08	1701.39	1696.04	2641
Dataset				KGA			
	OptimalTour	Mean	SD	Best	% Avg Dist	% Best Dist	Avg time (s)
dj38	6656	9608.77	1817.02	7720.03	44.36	15.99	140
berlin52	7542	8879.59	446.69	8218.95	17.74	8.98	188
ch130	6110	7790.85	312.17	7314.08	27.51	19.71	409
d198	15780	24023.86	3066.94	20830.94	52.24	32.01	1413
pr1002	259045	379495.87	6343.57	373865.26	46.50	44.32	4456

Algorithm Ant Colony Optimization	Algorithm Ant-Q algorithm					
Main Algorithm	Main Algorithm					
0: initialize best_dist and best_path to None 1: for generation in generations:	0: initialize best_dist and best_path to None 1: for generation in generations: 2: create n_ants artificial ants					
2: create n_ants artificial ants 3: for one_ant in ants: 4: make a single ant path (see Make path) 5: compute the path length 6: update best_dist and best_path 7: update the pheromone matrix (local update only for child processes, according to Eq. (10)) 8: every a certain n of iterations: 9: update the global pheromone matrix (charaction MDI appring process of a process of school of the	3: for each ant: 4: make a single ant path (see Make path) 5: compute the path length 6: update best_dist and best_path 7: update pheromone matrix with delayed rewards (according to Eq. (14)) 8: update the global pheromone matrix (shared in MPI environment among master&child.) 9: return best_dist, best_sol Make path 1: start from a vertex					
(shared in MPI environment among master&child.) 10: return best_dist, best_sol Make path	2: add start vertex to visited nodes3: for each remaining vertex:4: list the neighbours					
1: start from a vertex 2: add start vertex to visited nodes	 5: list the not yet visited neighb 6: generate a random number q ∈ {0,1} 7: if q < q₀: (threshold) 					
3: for each remaining vertex: 4: list the neighbours 5: list the not yet visited neighb 6: calculate the probability of choosing a vertex (according to Eq. (7)) 7: choose the vertex according to probability 8: add the chosen vertex to the visited list 9: return the chosen vertex id	8: select next vertex according to Eq. (12) 9: else: 10: calculate the probability of choosing a vertex 11: (according to Eq. (7)) 12: choose the vertex according to probability 13: add the chosen vertex to the visited list 14: give local rewards (local update pheromone matrix)					
Local update pheromone matrix 1: for ant in ant_colony:	15: return the chosen vertex id					
 for each vertex of one_ant_path : increase pheromone_matrix between current and next vertex of Δτ (according to Eq. (10)) 	Local update pheromone matrix 1: for ant in ant_colony: 2: for each vertex of one_ant_path: 3: increase pheromone_matrix between current and part vertex of a Ax (according to Fig. (11))					
Global update pheromone matrix (parallelism) 1: gather from MPI env all the pheromone matrices 2: if process is the parent process (rank==0): 3: for each element average over the n_cores matrices. 4: broadcast obtained pheromone matrix to the other processes	 and next vertex of a Δτ (according to Eq. (11)) Global update pheromone matrix (parallelism) 1: gather from MPI env all the pheromone matrices 2: if process is the parent process (rank==0): 3: for each element average over the n_cores matrices. 4: broadcast obtained pheromone matrix to the other processes 					

Algorithm Genetic Algorithm

- 1: procedure Genetic(Tm, Tp, elite_n, Selection, MaxGen)
- 2: $Pop \leftarrow GeneratePopulation(Tp)$
- $3: Pop \leftarrow Evaluation(Pop)$
- 4: for $i = 1 \dots MaxGen$ do
- 5: $Pop \leftarrow Selection(elite_n from Pop)$
- 6: $Pop \leftarrow Crossover(Pop)$
- 7: With probability Tm do:
- 8: $Pop \leftarrow Mutation(Pop)$
- 9: end for
- 10: **return** the best solution in *Pop*
- 11: end procedure

Algorithm K-Means Algorithm

- 1: Set the K cluster centers randomly;
- 2: repeat
- 3: for each vertex do
- 4: Calculate distance measure to each cluster;
- 5: Assign it to the closest cluster;
- 6: end
- 7: recompute the cluster centers positions;
- 8: **until** stop criteria are met;

Algorithm KGA

- 1: **input** an TSP;
- 2: K-Means is adopted to cluster the TSP into k *sub-problems*
- 3: For each sub-prob i = 1 to k, do:
- 4: repeat
- 5: GA procedure
- 6: until stop criteria are met
- 7: **Output** shortest path for sub-problem i;
- 8: End
- 9: Seek for the best combining seq S with GA
- 10: Combine all those shortest path into one tour
- 11: Output the shortest whole travelling tour.