

GND

JP102

Jumper\_3

def\_pwm\_a\_alt\_pwm\_a

JP105

Jumper\_3

def\_fault\_n\_a\_\_\_alt\_fault\_n\_a

JP108

Jumper 3

def\_brake\_a\_\_\_alt\_brake\_a

JP110

Jumper\_3

JP113

Jumper\_3

def\_sen\_a\_\_alt\_sen\_a

fault\_n\_a

brake\_a

Alternative pinout to allow stacking

def\_direction\_a alt\_direction\_b alt\_direction\_b

JP103

Jumper\_3

def\_pwm\_b\_\_\_alt\_pwm\_b

JP106

Jumper\_3 def\_fault\_n\_b

JP109

Jumper 3

def\_brake\_b\_\_\_alt\_brake\_b

JP111

Jumper\_3

JP114

Jumper\_3

def\_sen\_b\_\_\_alt\_sen\_b

fault\_n\_b

brake\_b

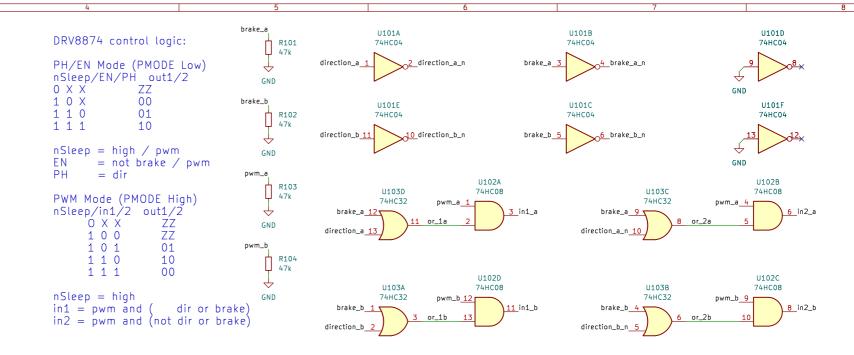
direction\_b

#### Standard Motorshield Assignments: Channel A:

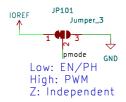
D12 - Direction D3 - PWM (work duty) D9 - Brake AO - current sensing.

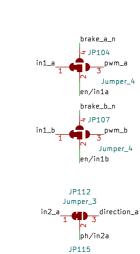
### Channel B:

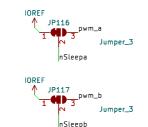
D13 - Direction D11 - PWM (work duty) D8 - Brake A1 - current sensing



## DRV8874 Mode Select

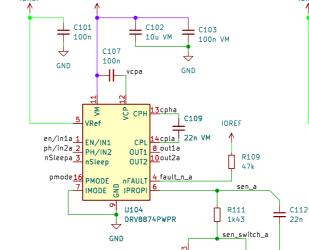




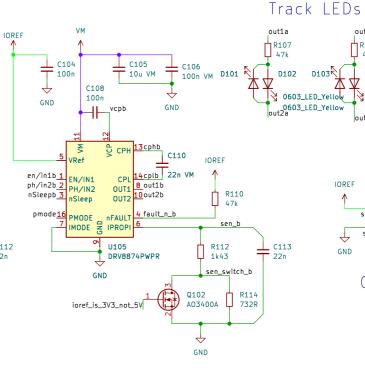


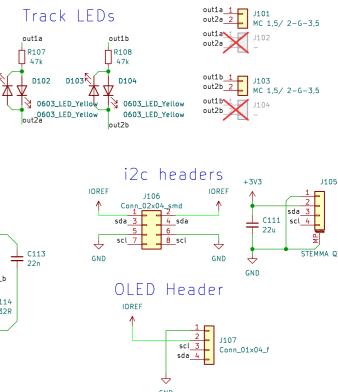
Jumper 3 in2\_b\_\_\_direction\_b

ph/in2b



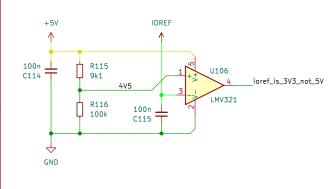
DRV8874 Motor Driver





Track Connector

## OpAmp as IORef Comparator



DRV8874 (max 6A) Current Sensing: V\_prop is limited to VRef inside DRV8874

ioref\_is\_3V3\_not\_5V

n\_channel conducts if gate high

5V = 0.000455\*(1430+732)\*A => A=5.08 .3V = 0.000455\*1430 \*A => A=5.073.3V = 0.000455\*1430

Q101

GND

Q101 R113 A03400A 732R

if subbed with DRV8876 (max 3.5A): 5V = 0.001\*(x+y)\*A => A=  $3.3V = 0.001* \times *A => A=$ 

candidate values: 2k+1k

3.63/1.65 1% 1k8+(680+220) 4.0/1.83 1% 1k5+(680+100) 4.8/2.2 0.2% 1k43+732(extend.) 5.08 0.1% <-- USED HERE (1k2+120)+680 5.5/2.5 0.0% 1k2+(470+180) 5.9/2.7 2%

 $1k2+\dot{6}20(extend.)$  5.9/2.7 0.1% 1k1+560(0603)6.6/3.0 0.4%

# Power Sheet

Licensed under CERN-OHL-W v2 or later Engineer: Erwin Peterlin DCC-EX semify-eda.com

Sheet: / File: motor-shield.kicad\_sch

Title: EX-Motorshield8874

Size: A3 Date: 2024-01-24 KiCad E.D.A. kicad 7.0.9

File: power.kicad\_sch

