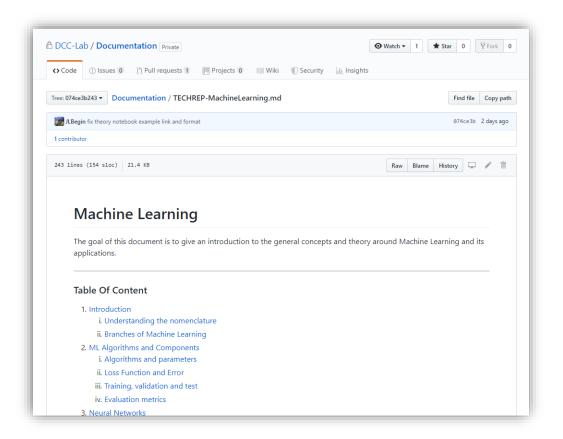
# Machine Learning

**DCCLab** 





DCC-Lab/Documentation/TECHREP-MachineLearning.md - .html

### Machine Learning

- 1. Introduction
- 2. ML Algorithms and components
- 3. Neural Networks
- 4. Convolutional Neural Networks

( + Coding procedure & example)

### Machine Learning

#### 1. Introduction

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### **ARTIFICIAL INTELLIGENCE**

A program that can sense, reason, act, and adapt

### **MACHINE LEARNING**

Algorithms whose performance improve as they are exposed to more data over time

### DEEP LEARNING

Subset of machine learning in which multilayered neural networks learn from vast amounts of data

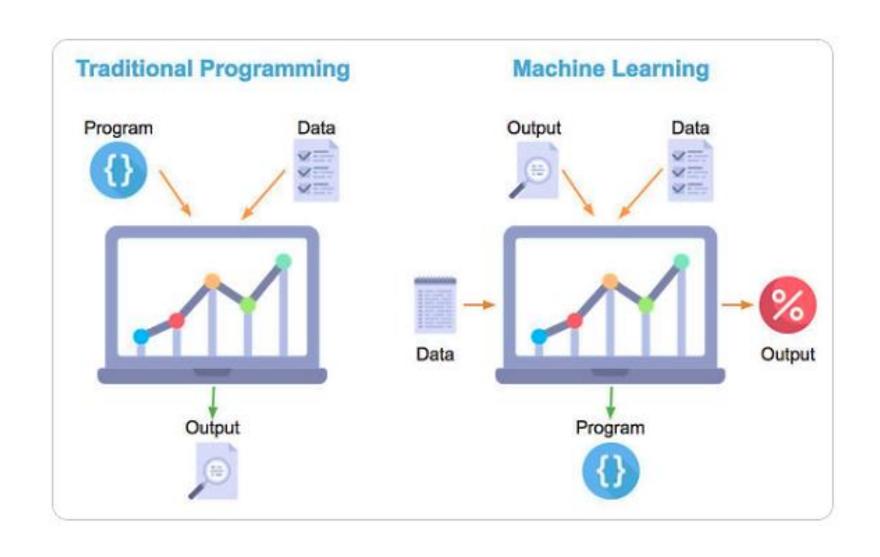
## What is Machine Learning?

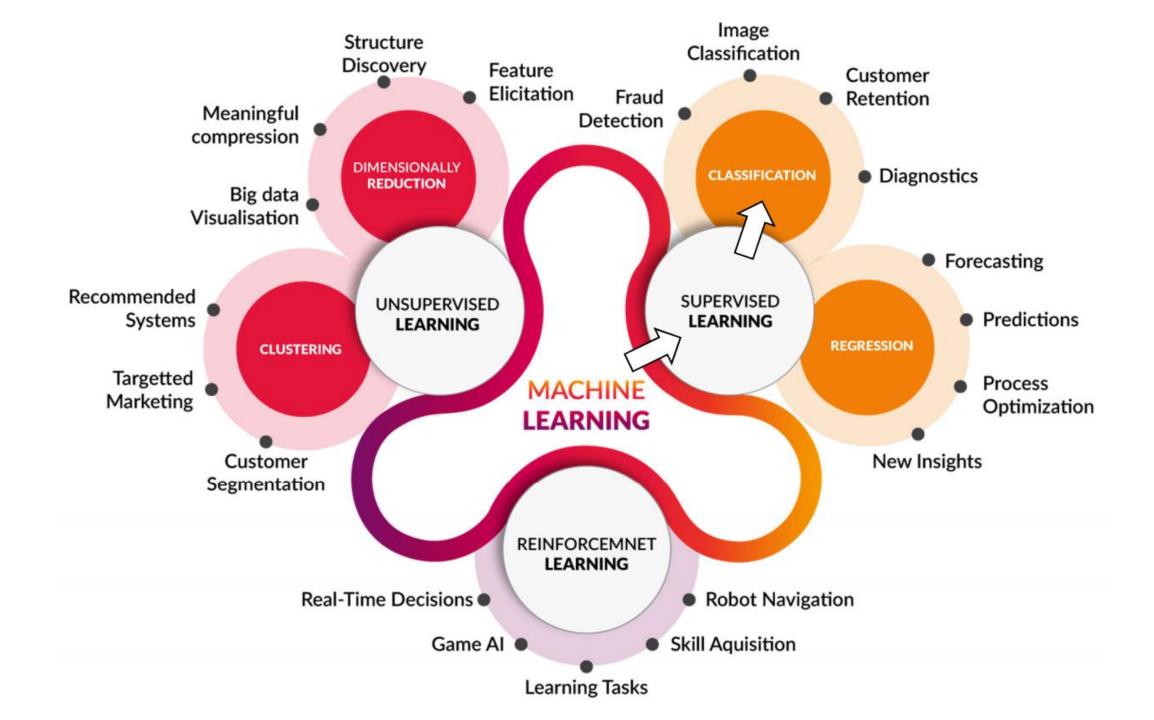
(Apprentissage automatique)

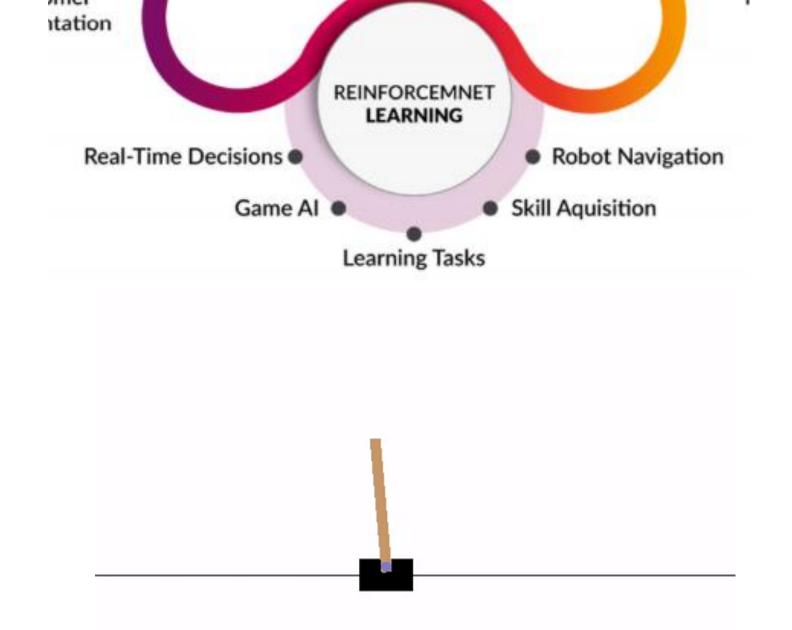
Machine Learning is a field of study that gives computers the ability to learn without being explicitly programmed.

- Arthur Samuel (1959)

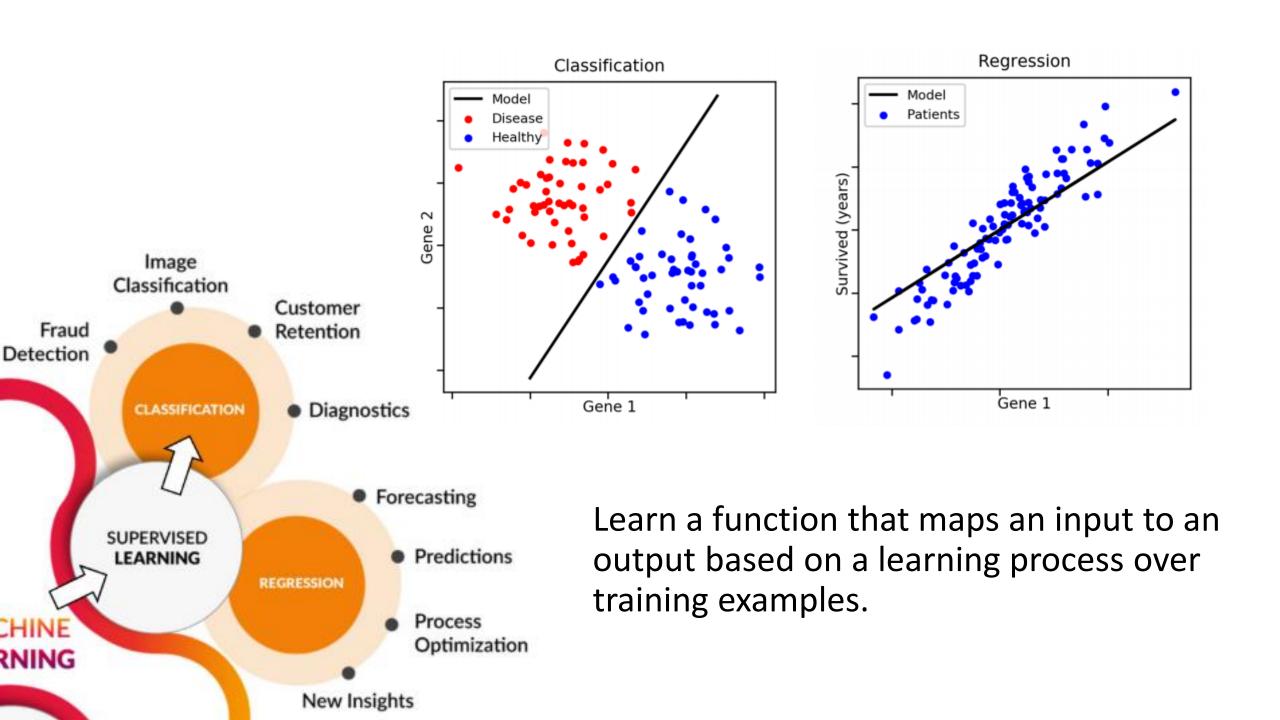
### Traditional programming VS Machine Learning

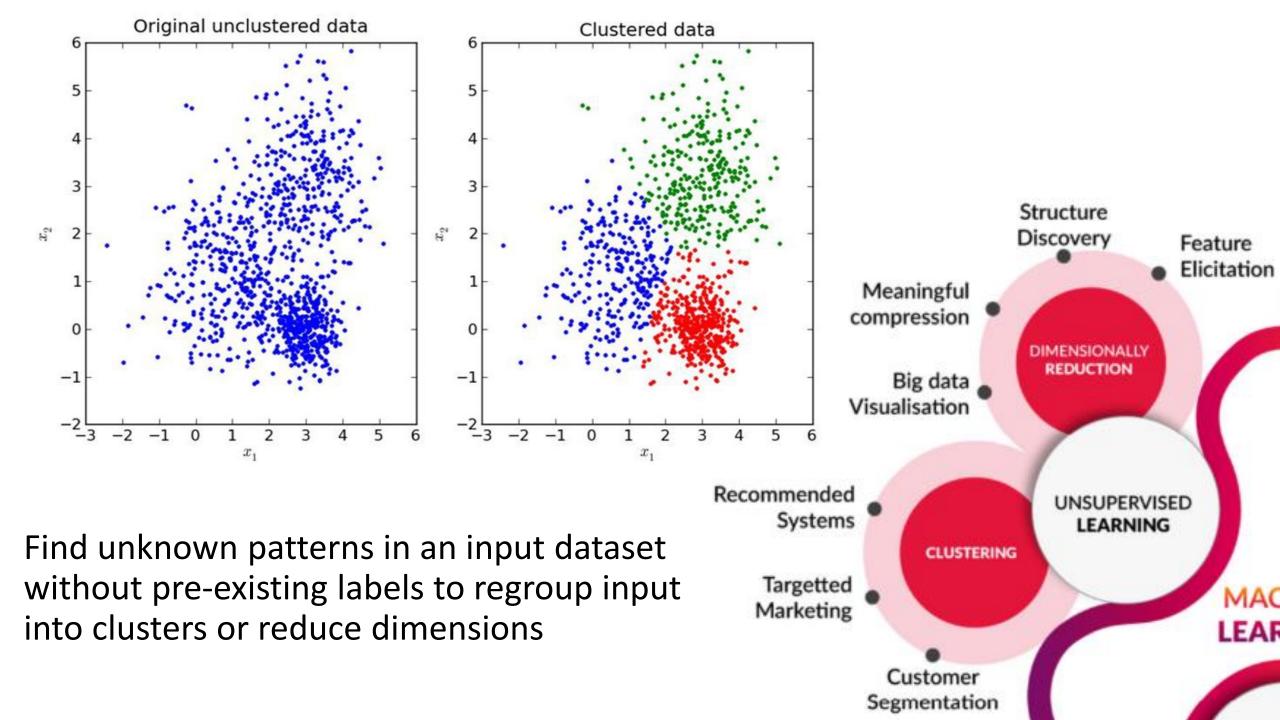




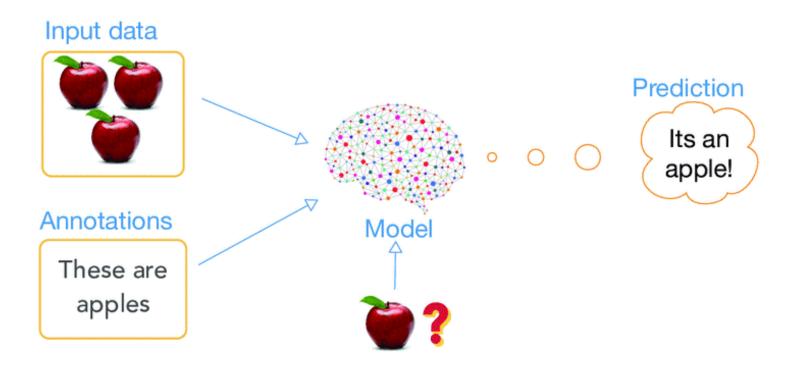


Optimizing a decision making policy with experiences and rewards.

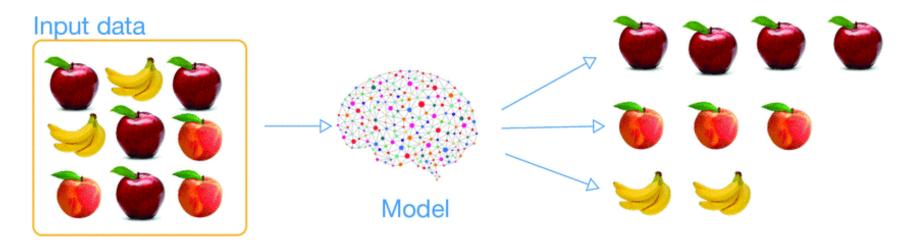




#### supervised learning



unsupervised learning



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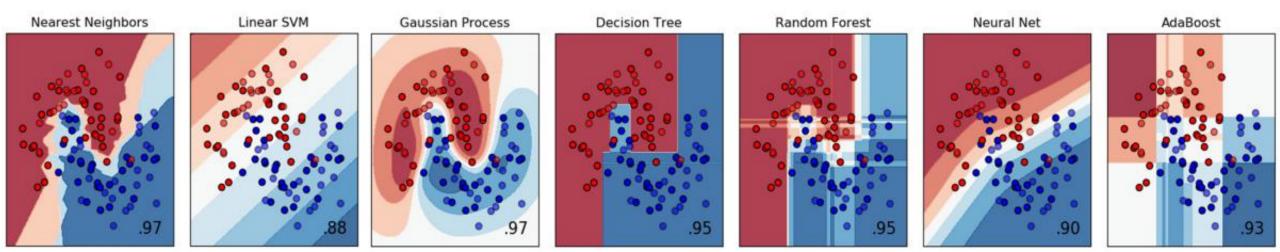
## 2. ML Algorithms and components

- 1. Algorithms and parameters
- 2. Loss Function and Error
- 3. Training, validation and test
- 4. Evaluation metrics

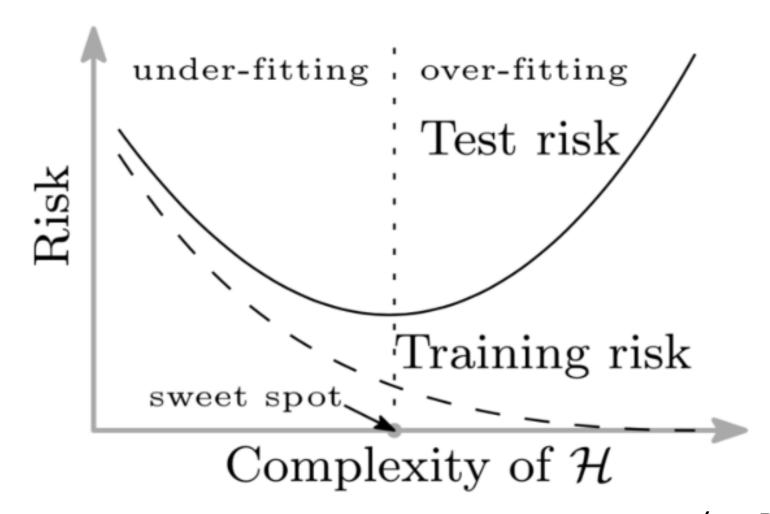
## Algorithms and parameters

- Parameters vs hyperparameters
- Not all algorithms are parametric (k-nearest neighbors)

• More parameters ≈ more **capacity** to learn complex task



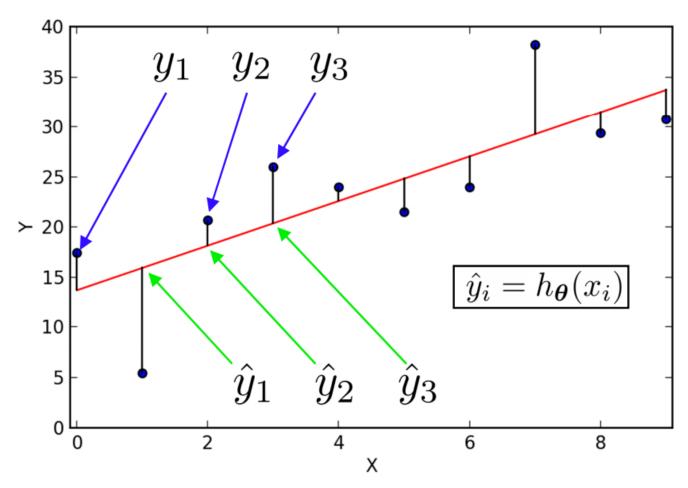
## Capacity



(=> Regularization!)

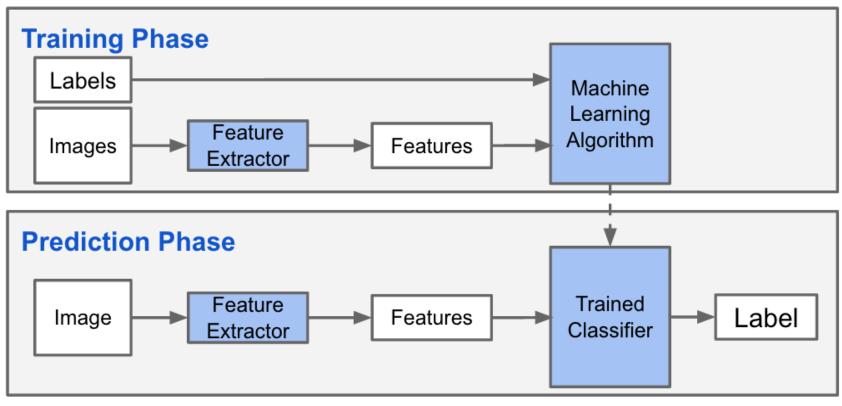
### Error and Loss Function

$$R_{emp}(h_{\boldsymbol{\theta}}) = \frac{1}{N} \Big( \mathcal{L}(y_1, \hat{y}_1) + \mathcal{L}(y_2, \hat{y}_2) + \dots + \mathcal{L}(y_N, \hat{y}_N) \Big)$$



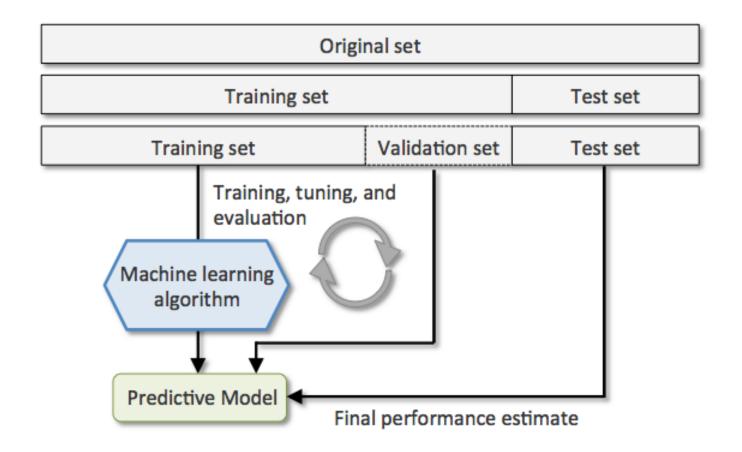
## Training

- Batch size
- Epochs

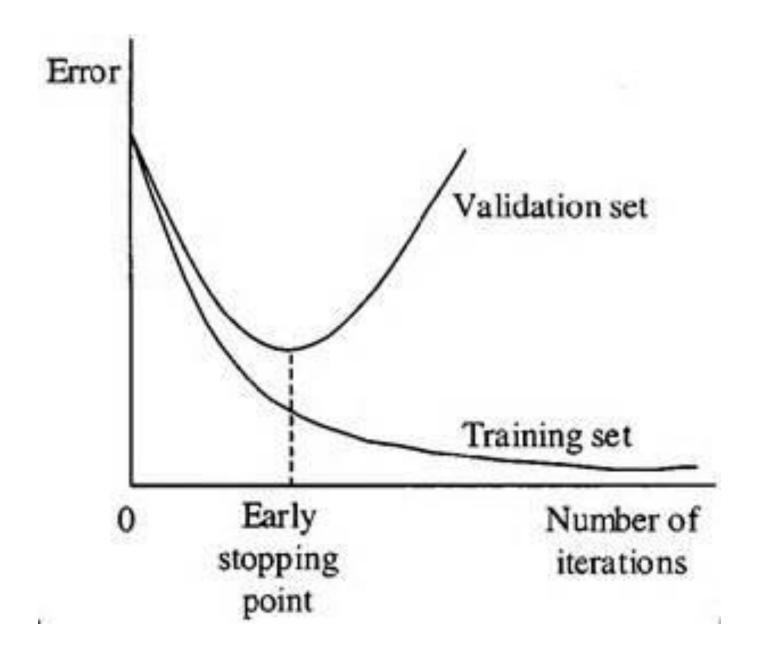


**Machine Learning Phases** 

### Train, validation and test



\* Training and validation errors give a **biased** approximation of the risk of the model.



### **Evaluation** metrics

#### Regression

- R^2
- MSE/MAE

#### Classification

- Classification Accuracy
- Area under ROC curve
- Precision
- F1-Score

		Actual	
		Positive	Negative
cted	Positive	True Positive	False Positive
Predic	Negative	False Negative	True Negative

## Classification accuracy

$$\begin{array}{l} \textbf{Accuracy} \ = \ \frac{\text{Number of correct predictions}}{\text{Total number of predictions}} \end{array}$$

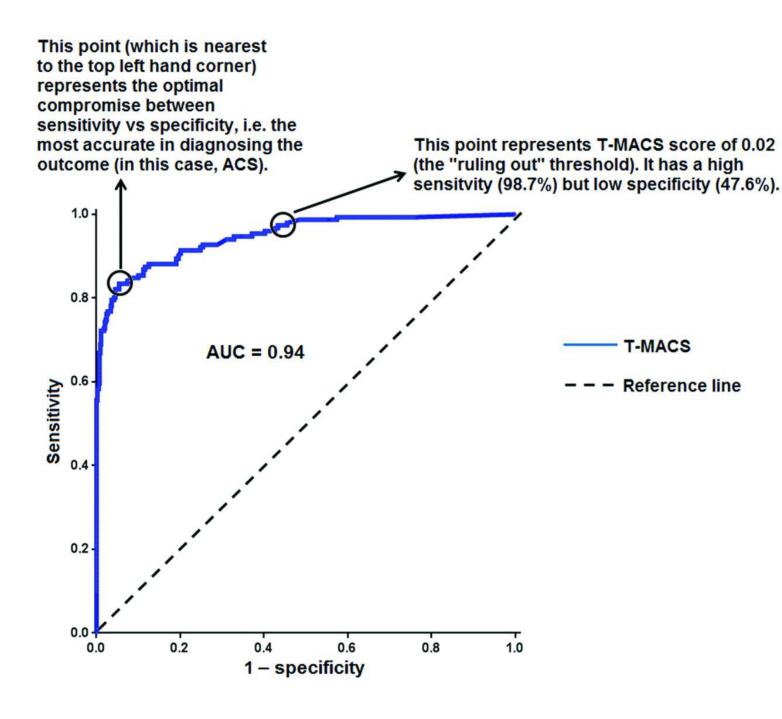
Only suitable when there is an **equal amount of observations for each class** and that all predictions are **equally important**.

### AUC

(Area under ROC curve)

For binary classification

Plot of the true positive rate against the false positive rate at various threshold settings.



### Confusion Matrix



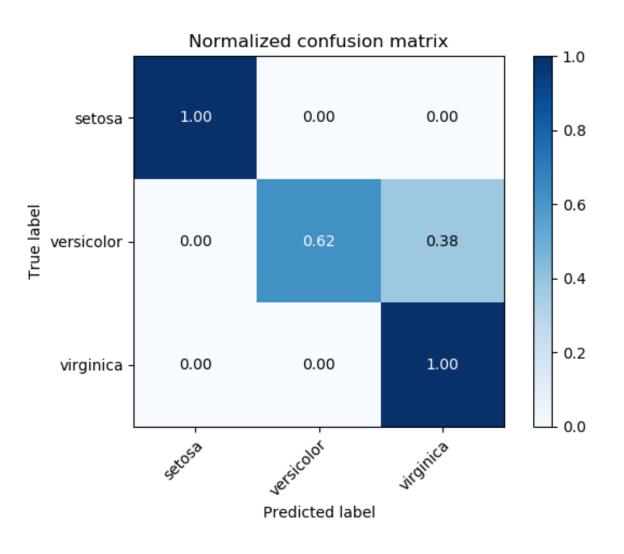
**Iris Setosa** 



Iris Virginica

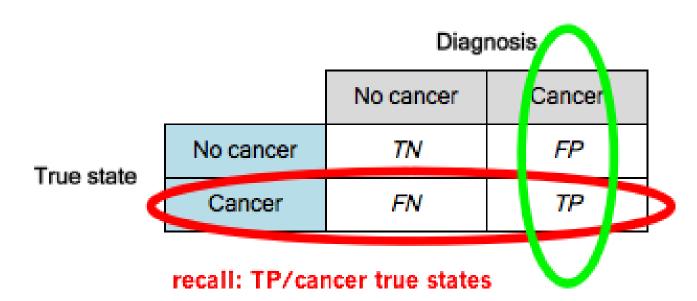


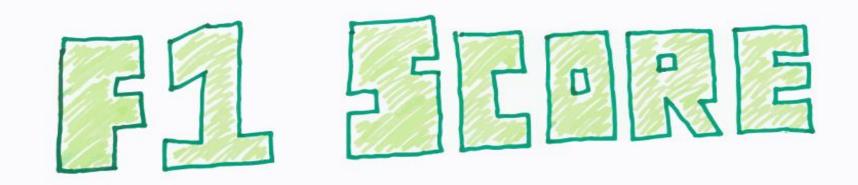
**Iris Versicolor** 



### Precision and sensitivity (recall)

precision: TP/cancer diagnoses





F1 score is the harmonic mean of precision and recall. Values range from 0 (bad) to 1 (good).

ChrisAlbon

### **Evaluation** metrics

#### Regression

- R^2
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#### Classification

- Classification Accuracy
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### Maxence Larose

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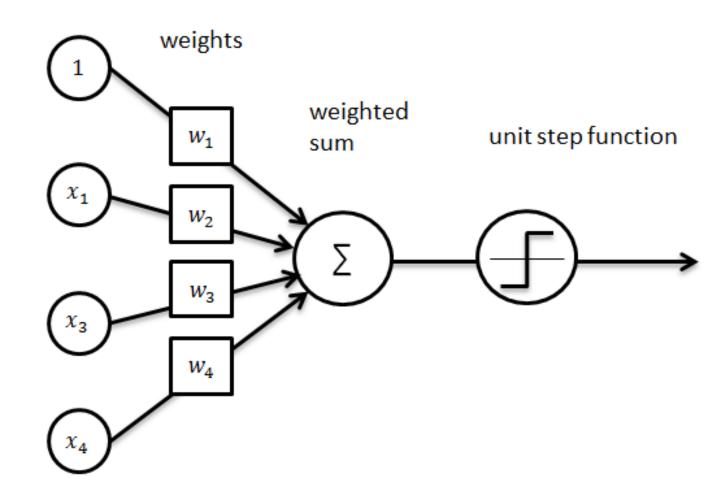
### Neural Networks

- 1. Perceptron (single-layer)
- 2. Neural Network (multi-layer)
- 3. Backpropagation

## Perceptron

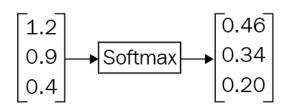
**Linear binary classifier** 

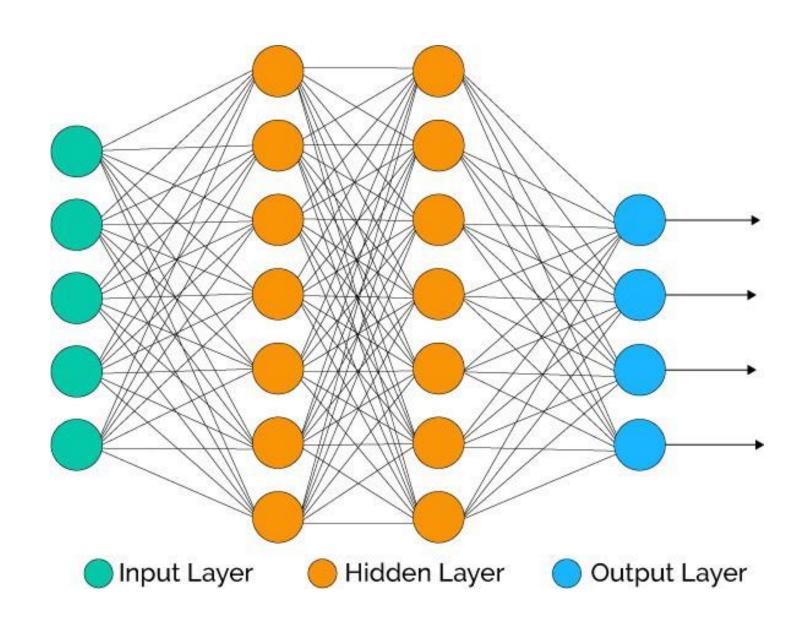
#### inputs



### Neural Network

- **≻** Nodes
- > Edges
- **➤ Weights** (and bias)
- ➤ Activation (non-linear)
  (Sigmoid, Tanh, ReLU)
- **≻**Softmax

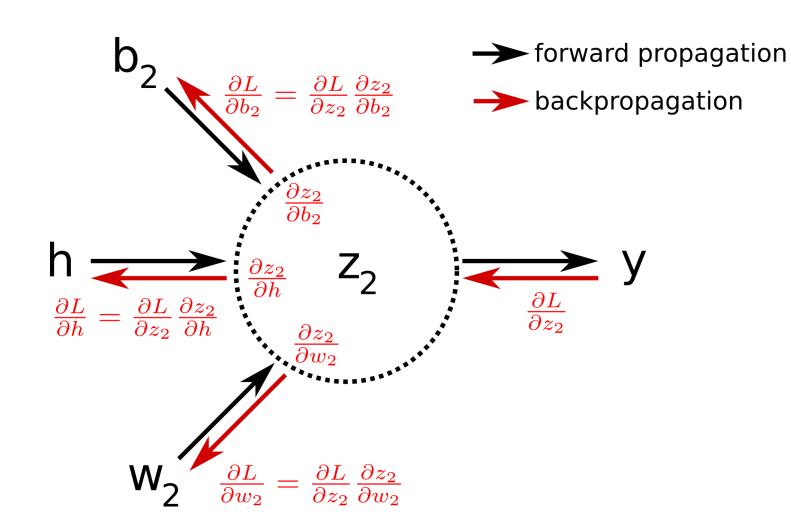




## Backpropagation

 Compute the error and its derivative at each node!

Update weight with gradient descent



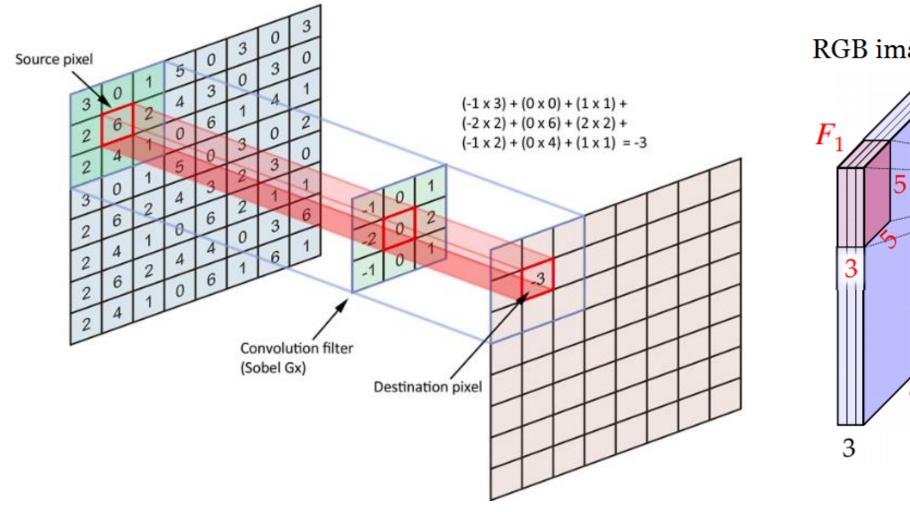
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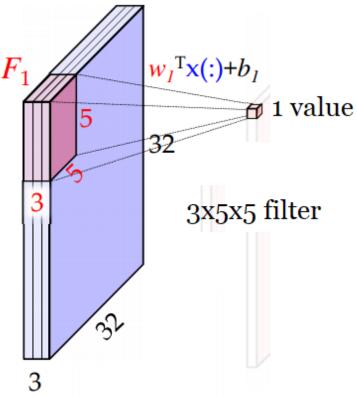
### Convolutional Neural Networks

- 1. Convolutional filters
- 2. Convolutional layers
- 3. Pooling layers
- 4. Dense layers
- 5. Deep learning
- 6. Transfer learning

### Convolutional Filters

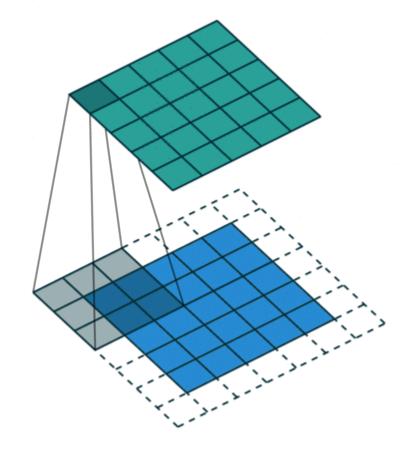


#### RGB image as input

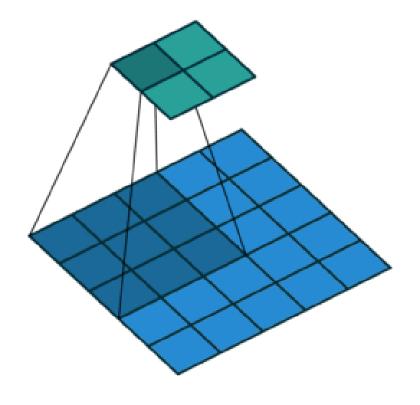


### Convolutional Filters

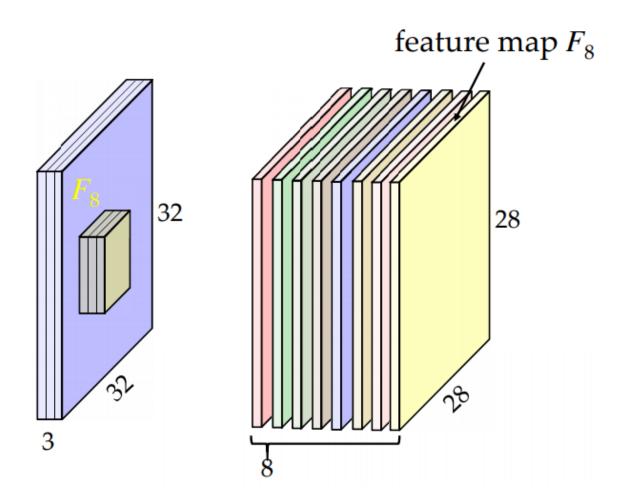
Padding = 1

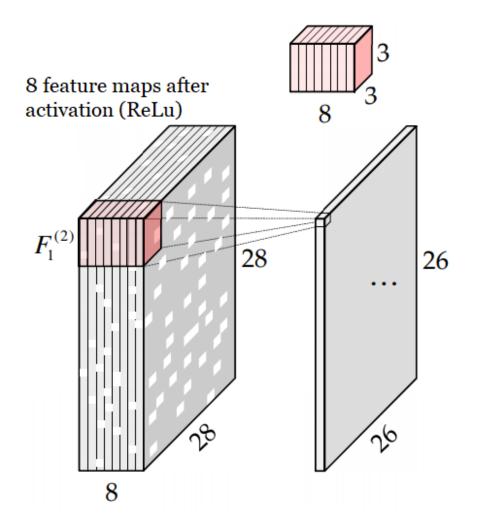


Stride = 2

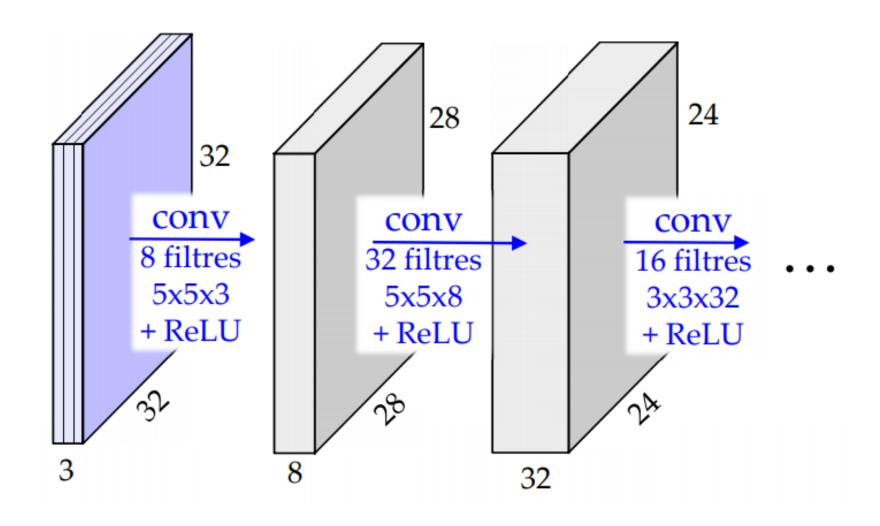


## Convolutional Layers



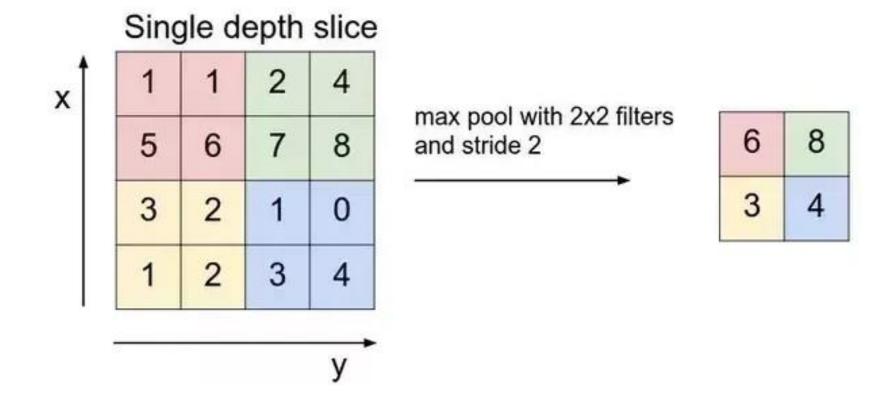


## Convolutional Layers



### Pooling Layers

(scales down the output size, like *stride*)

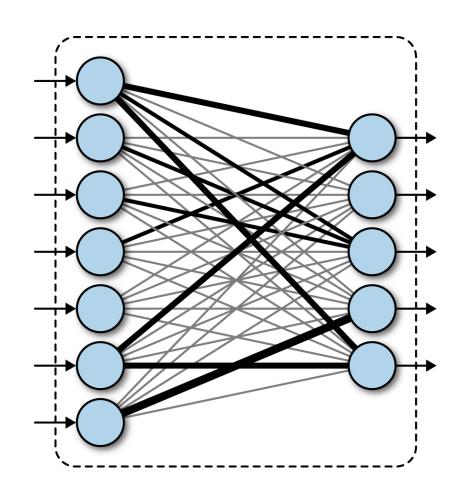


### Dense layers or fully-connected layers

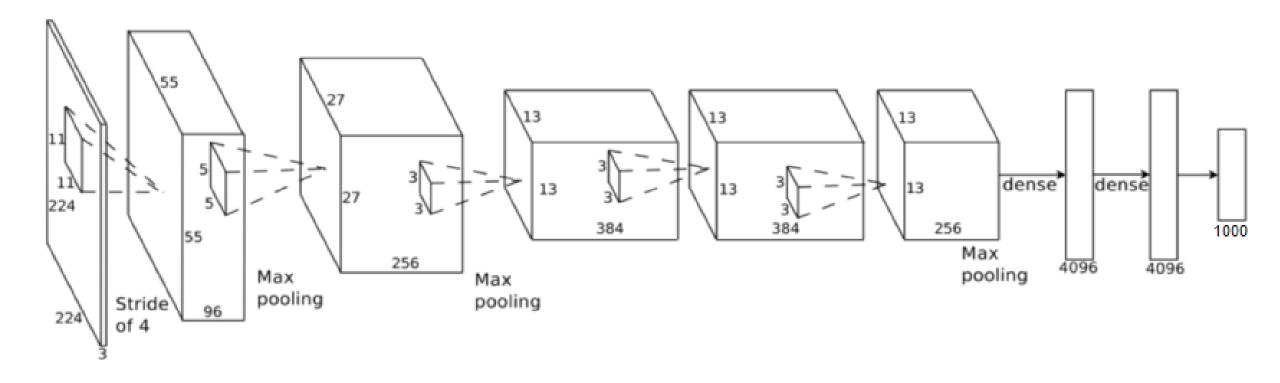
Simple Neural Network layer

➤ Used for final classification from a flattened array

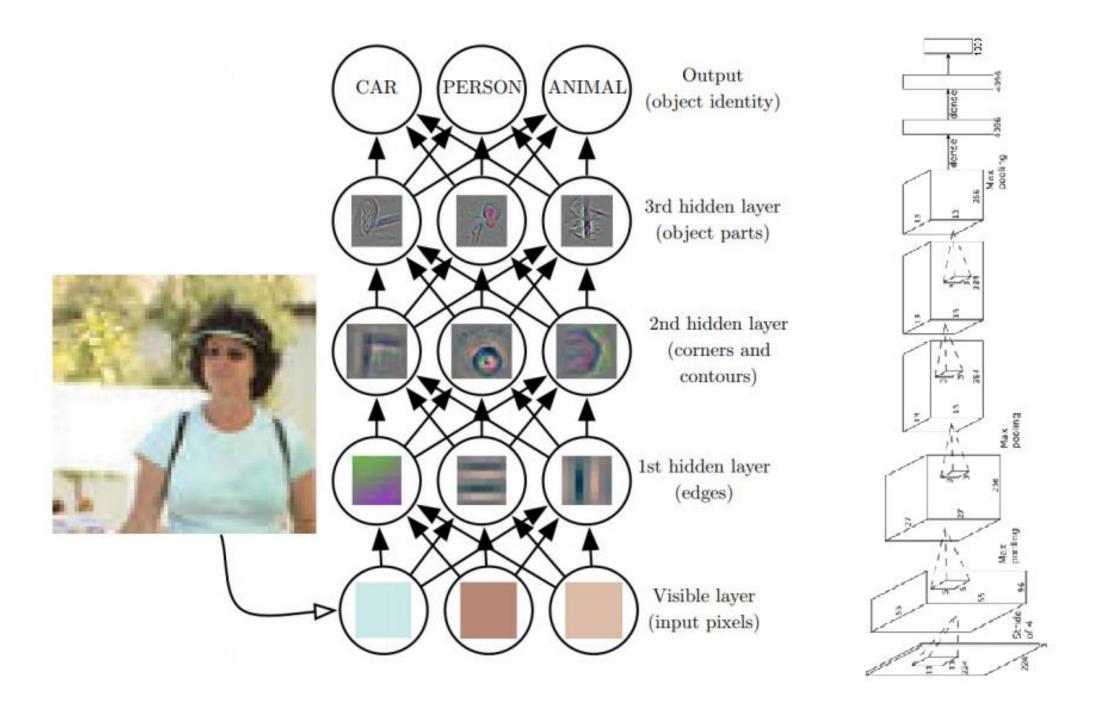
a.k.a. the classifier



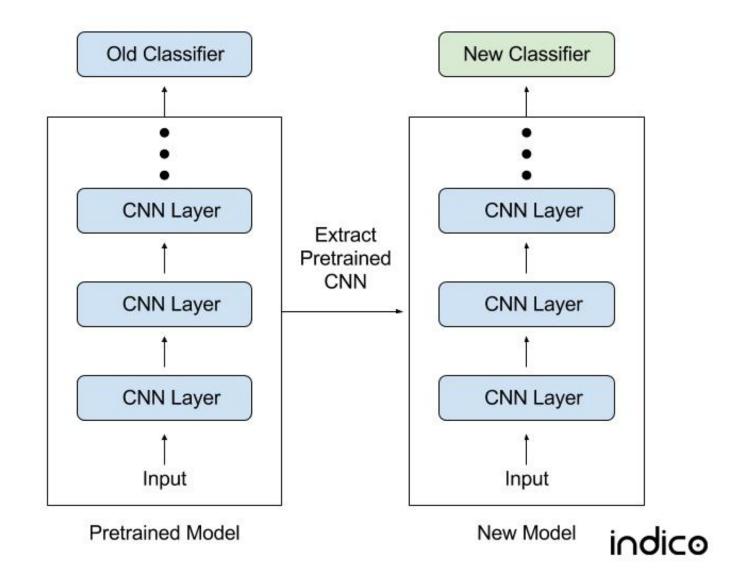
## Deep Learning



AlexNet's architecture (half) for image classification into 1000 different classes.



## Transfer Learning



## The architecture depends on the problem

Classification > Convolutional NN, ResNets ...

Semantic Classification > U-Net

Denoising > Autoencoder / U-Net

Speech recognition (time-dependent) > Recurrent Neural Network (RNN)

... > ...

#### **Procedure**

Load data and labels

Might have to resize images, apply filters...

If its too big to load, think about writing a DataGenerator class.

• Split dataset into training, validation and test

Usually around 60% training, 20% validation, 20% test. Make sure the data is different for each set

Scale

Simple normalization (remove minimum, divide by max value)
Or StandardScale (unit-variance and zero-mean)

• Build the model

Look at other models online, recycle, transfer learning if possible.

Compile with an appropriate loss function and optimizer for your problem.

Train

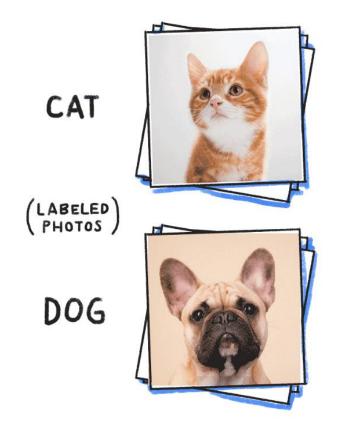
Batch size usually around 32, 64, 128.
Use callbacks for early stopping, checkpoints. Then nb. of epochs can be anything high enough...

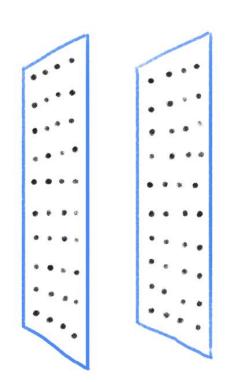
Evaluate on test set

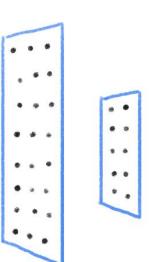
## Coding Example

Supervised classification









OUTPUT