

Remove Noise By Adaptive Filtering

This example shows how to use the `wiener2` function to apply a Wiener filter (a type of linear filter) to an image adaptively. The Wiener filter tailors itself to the local image variance. Where the variance is large, `wiener2` performs little smoothing. Where the variance is small, `wiener2` performs more smoothing. This approach often produces better results than linear filtering. The adaptive filter is more selective than a comparable linear filter, preserving edges and other high-frequency parts of an image. In addition, there are no design tasks; the `wiener2` function handles all preliminary computations and implements the filter for an input image. `wiener2`, however, does require more computation time than linear filtering. `wiener2` works best when the noise is constant-power ("white") additive noise, such as Gaussian noise. The example below applies `wiener2` to an image of Saturn with added Gaussian noise. Read the image into the workspace.

```
RGB = imread("Kaguya_Sama.png");
```

Convert the image from truecolor to grayscale.

```
I = im2gray(RGB);  
imshow(I);  
title('Image');
```



Add Gaussian noise to the image.

```
J = imnoise(I,'gaussian',0,0.025);  
imshow(J);  
title('Image with Added Gaussian Noise');
```

Image with Added Gaussian Noise



Remove the noise using the wiener2 function.

```
K = wiener(J,[5 5]);
```

Display the processed image.

```
figure  
imshow(K);  
title('Image with Noise Removed by Wiener Filter');
```

Image with Noise Removed by Wiener Filter

