# **DSA/ISE 5103 Intelligent Data Analytics**

# Principles of Modeling

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University of Oklahoma
Gallogly College of Engineering
School of Industrial and Systems Engineering

#### **Outline**

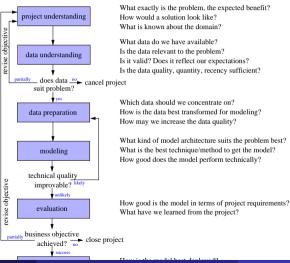
- Principles of Modeling
  - Analysis Task and Model Class
  - Statistical Learning
  - Modeling Error
  - Modeling Steps
  - Assessing Prediction Performance
  - Overfitting and Resampling
  - Data Strategies for Testing
  - Modeling Conventions in R

#### credits

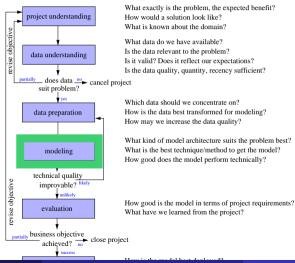
Credits – some images / excerpts are taken from:

- the textbook "An Introduction to Statistical Learning with Applications in R" by Gareth James, Daniela Witten, Trevor Hastie and Robert Tibshirani
- The *useR! 2013 Tutorial* by Max Kuhn: Predictive Modeling with R and the caret Package (one of the authors of the course text)

# modeling



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   Tomorrow's stock price...
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   Identify numbers in a handwritten ZIP code from a digitized image
- Clustering
   Determine distinct customer groups
- Dependence/Association Analysis
   Discover interesting buying behaviors

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The *data preparation* phase should work in concert with the chosen modeling method(s).

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- Tree models
- k-nearest Neighbor classification, prediction
- Support vector machines classification, prediction
- Cluster Analysis clusterina
- Association rule induction association analysis



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## two types of statistical learning

Most statistical learning problems fall into one of two categories:

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# two types of statistical learning

Most statistical learning problems fall into one of two categories:

- Supervised learning: inputs and outputs are known
- Unsupervised learning: no outputs in the data

- Model is *trained* to identify/predict a known output data.
- For each of the n cases of predictors  $X_i$ , i = 1, ..., p there is a response measurement  $y_i$ .
- Goal: fit a model that relates response to predictors
  - for accurately predicting the response of other observations
  - or understanding the relationship between the response and the predictors (inference).
- Examples: linear and logistic regression, decision trees, SVM
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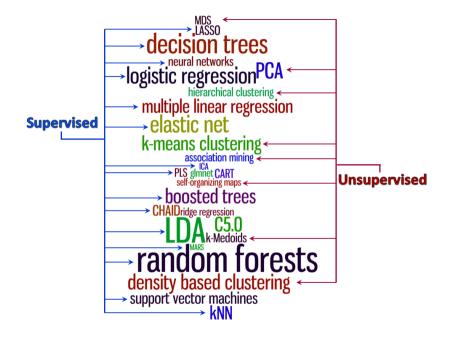
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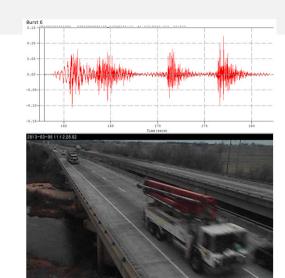
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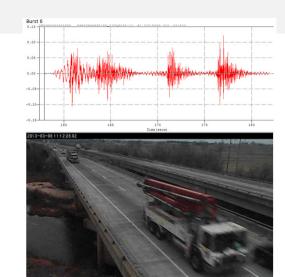
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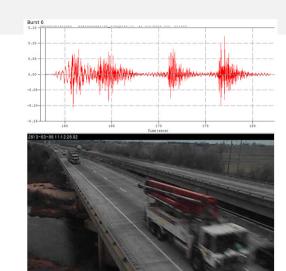
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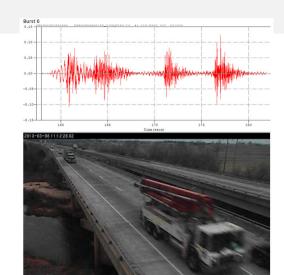
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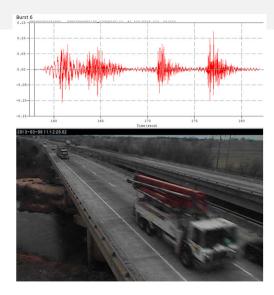


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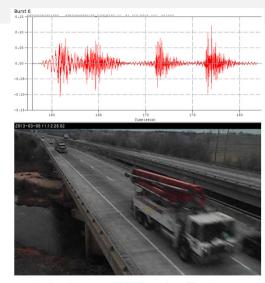
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Semi-supervised learning is a third option which attempts to blend supervised and unsupervised learning. The above motivation is provided by Xiaojin Zhu (2007) Semi-Supervised Learning Tutorial. ICML. The truck-bridge sensor problem, well, that one is mine...

# what and why?

In supervised learning, we believe

$$Y = f(X) + \epsilon$$

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$$\hat{Y} = \hat{f}(X)$$

Principles of Modeling

# what and why?

In supervised learning, we believe

$$Y = f(X) + \epsilon$$

and we are trying to learn f to predict Y:

$$\hat{Y} = \hat{f}(X)$$

where X is our predictor inputs,  $\hat{f}$  is our estimate of f, and  $\hat{Y}$  is the resulting prediction for Y.

# what and why?

The two possible motivations:

- Inference
- Prediction

#### inference

This study examined the relationship of age to sexual recidivism using data from 10 follow-up studies of adult male sexual offenders (combined sample of 4,673). Rapists were younger than child molesters, and the recidivism risk of rapists steadily decreased with age. In contrast, extrafamilial child molesters showed relatively little reduction in recidivism risk until after the age of 50. The recidivism rate of intrafamilial child molesters was generally low (less than 10%), except for the intrafamilial offenders in the 18- to 24-year-old age group, whose recidivism risk was comparable to that of rapists and extrafamilial child molesters. The results are discussed in terms of developmental changes in sexual drive, self-control, and opportunities to offend.

# Recidivism and Age Follow-Up Data From 4,673 Sexual Offenders

#### R. KARL HANSON

Department of the Solicitor General of Canada

*The public is justifiably concerned* about the risk posed by sexual offenders. Although the observed sexual recidivism rates are only 10% to 15% after 5 years (Hanson & Bussière, 1998), the rates continue to increase gradually with extended follow-up periods (Hanson, Steffy, & Gauthier, 1993a). Do sexual offenders remain at risk throughout their lives, or is there some age

#### inference

TABLE 2: The Relationship Between Age (years) and Sexual Recidivism (1 = yes, 0 = no)

Sample	Sample Size	Step	Logistic Regression Coefficients		
			Intercept	Linear	Curvilinear
Rapists	1,133	1	-0.334 (0.319)	-0.040 (0.010)	
		2	-0.585 (0.995)	-0.024 (0.060)	0.00023 (0.00088)
Extrafamilial child molesters	1,411	1	-0.411 (0.232)	-0.028 (0.006)	
		2	-2.344 (0.778)	0.082 (0.043)	-0.00144 (0.00056)
Incest offenders	1,207	1	-0.069 (0.448)	-0.064 (0.013)	
		2	1.359 (1.154)	-0.144 (0.061)	0.00108 (0.00079)
Total	4,673	1	-0.324 (0.140)	-0.035 (0.004)	
		2	-0.489 (0.410)	-0.026 (0.023)	0.00013 (0.00030

NOTE: Standard deviations in parentheses.

<sup>\*</sup>p < .05. \*\*p < .01. \*\*\*p < .001.

# what and why?

The two possible motivations:

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Many real-world applications will require a combination or these two approaches.

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21/91

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- It is impossible to overcome this error by the choice of a suitable model.

#### sample error

- Data is not a good representation of the underlying data
- Smaller the sample, smaller the probability of a good model

# sample error

- Data is not a good representation of the underlying data
- Smaller the sample, smaller the probability of a good model

e.g., throw 6-sided dice and compute mean of pips



There are different models for the data:

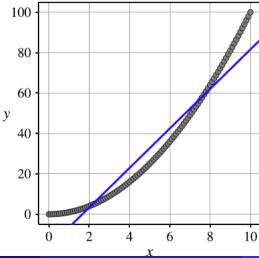
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- simpler model ⇒ bigger error
- more complex model ⇒ overfitting and larger error on new data
- type of model ⇒ different "fit" to data



- training minimizes error on the training data
- model performance on different or new data may be different
- to estimate this, we evaluate models on test data (data is not used in training the model)
- the resulting error is known as the test error
- no guarantee that the model with the smallest training error will have the smallest test error
- usually, more flexible/complex models have less training error
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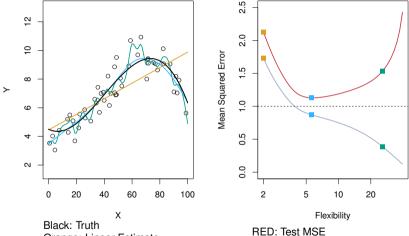
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#### example: test vs. train



Orange: Linear Estimate
Blue: smoothing spline
Green: smoothing spline (more fle

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Grey: Training MSE

Dashed: Minimum possible test MSE (irreducible)

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http://scott.fortmann-roe.com/docs/BiasVariance.html

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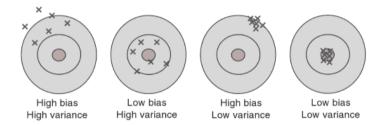
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#### bias and variance



## bias and variance decomposition

Assume the true model is:  $Y = f(X) + \epsilon$  and we develop the model  $\hat{f}(X)$  to predict Y. At the point X = x, the test error is:

$$\mathsf{Err}(x) = E\left(Y - \hat{f}(x)\right)^2$$

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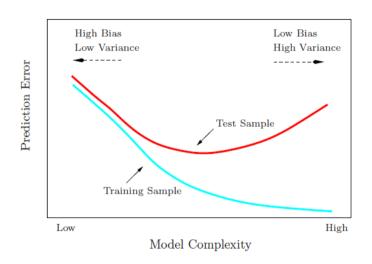
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which can be decomposed as,

$$\operatorname{Err}(x) = \left(E\left[\hat{f}(x)\right] - f(x)\right)^{2} + E\left[\left(\hat{f}(x) - E\left[\hat{f}(x)\right]\right)^{2}\right] + \sigma_{e}^{2}$$

$$= \operatorname{Bias}^{2} + \operatorname{Variance} + \operatorname{Irreducible Error}$$

# a fundamental picture



#### After

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## fitting function and assessment function

There are two functions necessary to build and assess models; sometimes they are the same; sometimes they are different.

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There are two functions necessary to build and assess models; sometimes they are the same; sometimes they are different.

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In either case, we need to:

- ullet define function  $g:\mathcal{M} o {
  m I\!R}$
- which, evaluates the quality of the model
- in order to fit or detect the "best" model

#### Example

Simple linear regression model  $\mathcal{M}: \hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$ 

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#### Example

Simple linear regression model  $\mathcal{M}: \hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$ Mean squared error:

$$g(\hat{\beta}_0, \hat{\beta}_1) = \frac{1}{n} \sum_{i=1}^n \left( y_i - \mathcal{M}(\hat{\beta}_0, \hat{\beta}_1) \right)^2$$
$$= \frac{1}{n} \sum_{i=1}^n \left( y_i - \left( \hat{\beta}_0 + \hat{\beta}_1 x_i \right) \right)^2$$

## prediction and classification assessment

#### Assessment measures for:

- prediction (e.g., regression-based)
- classification (we will discuss later)

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MSE (mean-squared error)

$$\frac{1}{n}\sum_{i=1}^n (y_i - \hat{y}_i)^2$$

### regression assessment

MSE (mean-squared error)

$$\frac{1}{n}\sum_{i=1}^n (y_i - \hat{y}_i)^2$$

RMSE (root mean squared error)

$$\sqrt{\frac{1}{n}\sum_{i=1}^{n}(y_i-\hat{y}_i)^2}$$

MAE (mean-absolute error)

$$\frac{1}{n}\sum_{i=1}^n|y_i-\hat{y}_i|$$

MAE (mean-absolute error)

$$\frac{1}{n}\sum_{i=1}^n|y_i-\hat{y}_i|$$

• MAPE (mean-absolute percentage error)

$$\frac{1}{n}\sum_{i=1}^{n}\left|\frac{y_{i}-\hat{y}_{i}}{y_{i}}\right|$$

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where n is number of observations; p is number of predictors

# regression assessment

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39/91

### regression assessment

• AIC (Akaike information criterion):  $2k - 2\ln(L)$ 

- L is the "log likelihood"; k is number of estimated parameters: p + 1
- lower scores are better
- penalize model complexity

39/91

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  - BIC is asymptotically consistent as a selection criterion
  - For small or moderate samples, BIC often chooses models that are too simple, because of its heavy penalty on complexity
- L is the "log likelihood"; k is number of estimated parameters: p + 1
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40/91

# likelihood and log likelihood

A quick digression on "log likelihood"

lf

$$x_i \sim F(\Theta), i = 1, \ldots, n$$

then the likelihood function is

$$L(\lbrace x_i\rbrace_{i=1}^n,\Theta)=\prod_{i=1}^nF(x_i;\Theta)$$

The likelihood function L can be maximized w.r.t. model parameters  $\Theta$ 

## likelihood and log likelihood

An important trick!  $\rightarrow$  We usually maximize the log of the likelihood function instead of the likelihood directly:

$$\log (L(\lbrace x_i \rbrace_{i=1}^n, \Theta)) = \log \left( \prod_{i=1}^n F(x_i; \Theta) \right)$$
$$= \sum_{i=1}^n \log (F(x_i; \Theta))$$

What does L look like for a normal error simple linear regression?

What does *L* look like for a normal error simple linear regression?

$$y_i = \beta_0 + \beta_1 + \epsilon_i$$

- $y_i$  is the value of the response in the  $i^{th}$  observation
- $\beta_0$  and  $\beta_1$  are regression coefficients
- $x_i$  is a known constant
- $\epsilon_i \sim i.i.d.N(0, \sigma^2)$
- $\bullet$   $i = 1, \ldots, n$

What does *L* look like for a normal error simple linear regression?

$$\begin{split} L\left(\beta_{0},\beta_{1},\sigma^{2}\right) &= \prod_{i=1}^{n} \frac{1}{(2\pi\sigma^{2})^{1/2}} e^{-\frac{1}{2\sigma^{2}}(y_{i}-\beta_{0}-\beta_{1}x_{i})^{2}} \\ &= \frac{1}{(2\pi\sigma^{2})^{n/2}} e^{-\frac{1}{2\sigma^{2}}\sum_{i=1}^{n}(y_{i}-\beta_{0}-\beta_{1}x_{i})^{2}} \\ &= \frac{1}{(2\pi\sigma^{2})^{n/2}} e^{-\frac{1}{2\sigma^{2}}\sum_{i=1}^{n}r_{i}^{2}} \end{split}$$

where  $r_i = y_i - \beta_0 - \beta_1 x_i$ 

 $\log L\left(\beta_0, \beta_1, \sigma^2\right) = \log \left(\frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n r_i^2}\right)$ 

 $= \log 1 - \frac{n}{2} \log 2\pi - \frac{n}{2} \log \sigma^2 - \frac{1}{2} \sum_{i=1}^{n} \frac{r_i^2}{\sigma^2}$ 

 $=-\frac{n}{2}\left(\log 2\pi + \log \sigma^2 + 1\right)$ 

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 $=-\frac{n}{2}\left(\log 2\pi + \log \sum_{i=1}^{n} r_i^2 - \log n + 1\right)$ 

Example with the mtcars data set (n=32):

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> fit<-lm(data=mtcars, mpg~disp+wt)
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[1] -78.08389
```

And using the logLik function in R:

```
> logLik(fit)
'log Lik.' -78.08389 (df=4)
```

#### And finally,

**AIC**: 
$$2k - 2\ln(L)$$
 =  $2(4) - 2(-78.08389) = 164.1678$   
**BIC**:  $k\ln(n) - 2\ln(L)$  =  $4\ln(32) - 2(-78.08389) = 170.0307$ 

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$$\mathbf{AIC}: \quad 2k - 2\ln(L)$$

BIC: 
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Commands available in R:

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 $= 4 \ln(32) - 2(-78.08389) = 170.0307$ 
> AIC(fit)
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46/91

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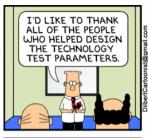
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## regression assessment

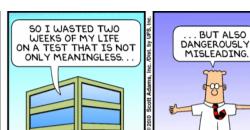
Common assessment for predictive (regression) models:

- $R^2$ ,  $R^2_{\text{adjusted}}$
- MSE, RMSE, MAE, MAPE
- AIC, BIC

There are many more tools available to help you measure, diagnose, and improve regression models. We discuss these in detail in another lecture.















#### **Overfitting**

Fitting the **noise** rather than fitting the *underlying relationship*.

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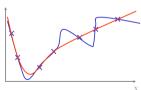
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Typical indicator for overfitting: "Perfect fit"



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#### Questions:

- How would a kNN be used to classify data?
- 2 What is the "tuning parameter" to control model complexity?

## lazy and eager leaners

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kNN is different than most of the classifiers that we will work with. It is known as a lazy learner; most of the methods we deal with are eager learners.

**Eager learning**: construct general, explicit description of target function based on training samples – this is used for predictions/classification of new data

**Lazy learning**: store the training data – generalizing beyond these data is deferred until an explicit request is made (e.g. by new data)

# classifying using kNN

Given a positive integer k and a *test* observation  $x_0$ , the kNN classifier identifies the k points in the training data that are closest to  $x_0$ , represented by  $\mathcal{N}_0$ .

It then estimates the conditional probability for class j as the fraction of points in  $\mathcal{N}_0$  whose response values equal j:

$$P(Y = j | X = x_0) = \frac{1}{k} \sum_{i \in \mathcal{N}_0} I(y_i = j)$$

# classifying using kNN

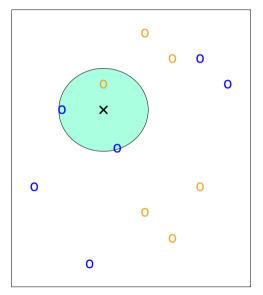
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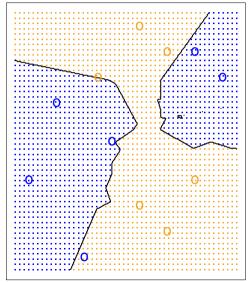
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The tuning parameter is the value for k.

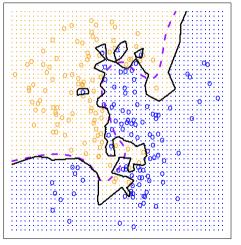
### classification example: KNN k=3

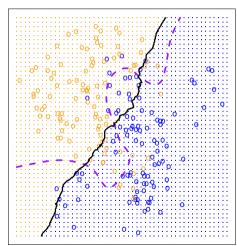




### classification example: KNN

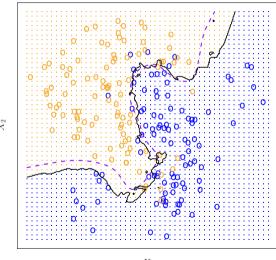
KNN: K=1 KNN: K=100



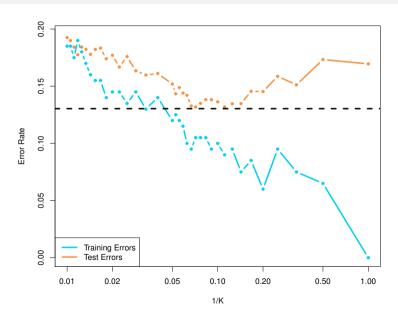


### classification example: KNN k = 10

KNN: K=10



### classification example: kNN - train vs. test



## data strategies for testing

There are multiple strategies useful in:

- model selection (i.e., determine tuning parameters)
- estimate error rates on new data

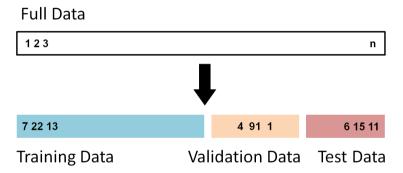
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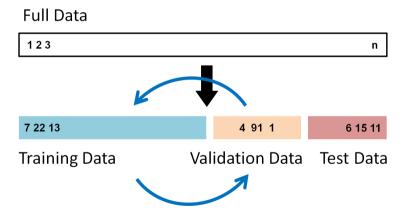
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- estimate error rates on new data

They are two basic approaches:

- Holdout validation
- Resampling
  - cross-validation (and nested cross-validation)
  - bootstrap sampling



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#### Split data into different subsets:

- Training set: data used for learning; to fit the model
- Validation set: data used to tune the parameters; select the model
- Test set: used to assess the generalization error for the final chosen model.
   After assessing the final model on the test set, you must not tune the model any further!

#### kaggle.com competition site



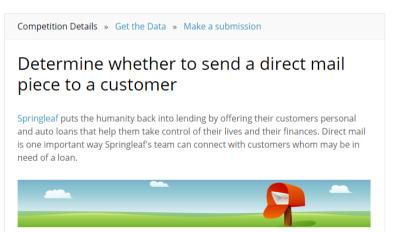
\$100,000 • 1,681 teams

#### **Springleaf Marketing Response**

Fri 14 Aug 2015 Mon 19 Oct 2015 (24 days to go)

Merger and 1st Submission Deadline





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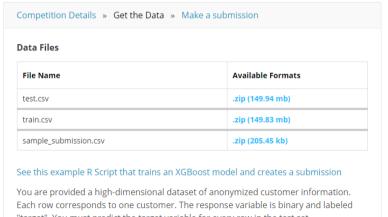
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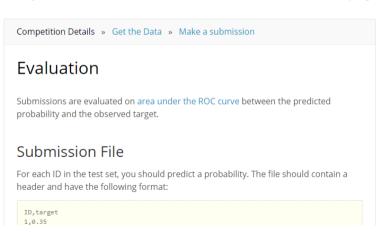


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In many cases, you will have data rich environments. In fact, to perform in-memory computations even on modern machines you may only use a small sample of your overall data.

For example: if you have 1,000,000,000 observations – do you really need *all* of them for modeling? if not, maybe a random sampling of 100,000 is sufficient...

In such a case, you could create **many** INDEPENDENT training, validation, and test samples... this could work well.

Splitting strategies

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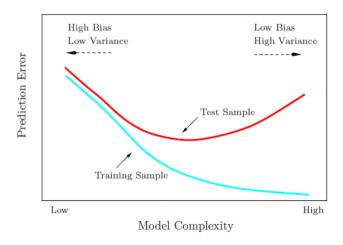
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  - After selecting a final model complexity re-train on all of train and validation data to produce the final model
  - Evaluate final model on untouched, unseen, test data set

### a fundamental picture



### test error

What can we see from the preceding graph?

• There is an optimal model complexity that gives minimum test error.

### test error

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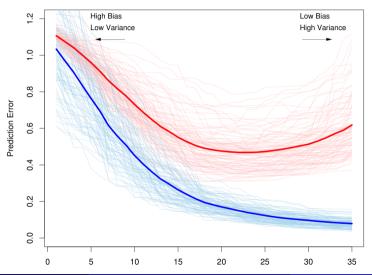
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- There is an optimal model complexity that gives minimum test error.
- Training error is not a good estimate of the test error.
- There is a bias-variance trade-off in choosing the appropriate complexity of the model.

#### another important picture...



#### test error

#### What can we see from the preceding graph?

- There is a *distribution* of both train and test error
- If you do have smaller datasets partitioning off a large chunk for testing might hurt your model more than it helps your model!
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- We must have multiple assessments of test error to understand the distribution of test error!

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70/91

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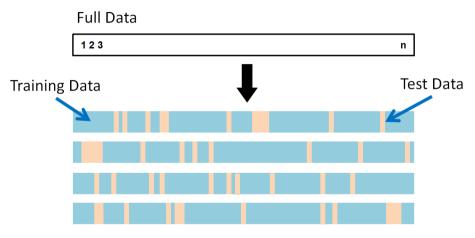
# resampling methods

**Resampling methods**: Tools that involve repeatedly drawing samples from a training set and refitting a model of interest on each sample in order to obtain more information about the fitted model.

#### Types of resampling:

- cross-validation (CV)
  - random subset sampling (a.k.a. leave-group-out CV)
  - k-fold CV
  - leave-one-out CV
- bootstrap sampling

# random subset sampling a.k.a. LGOCV



Same percentage withheld each time.

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- split the data into k distinct blocks of roughly equal size
- leave out a block of data and fit the model on the rest
- the model is used to predict the held-out block
- repeat (go back to step 2) until we've predicted all k held-out blocks
- final performance is based on hold-out predictions and error (averaged across all k predicted blocks)

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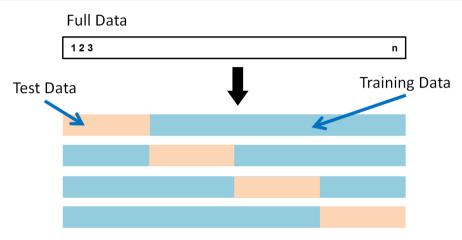
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Note: k is usually 5 or 10

A possible improvement on this is **repeated k-fold CV** which just means doing the whole thing multiple times. e.g., 5 repeats of 10-fold CV would give 50 total re-samples that are averaged.

Note: This is not the same as 50-fold CV.

### leave-one-out cross-validation

- Use everything except of one data point for training
- This single data point is used for testing
- Identical to k-fold CV where k = n

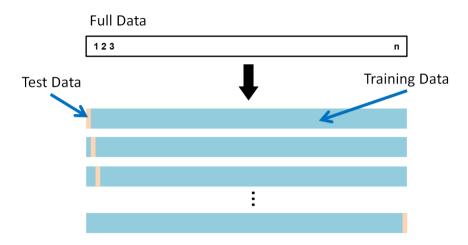
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- Identical to k-fold CV where k = n

#### leave-one-out cross-validation

- Use everything except of one data point for training
- This single data point is used for testing
- Identical to k-fold CV where k = n

### **LOOCV**



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#### "pull yourself up by your bootstraps"

This refers to the physically impossible task of actually lifting yourself up by grabbing your own bootstraps and pulling.

It is common saying which basically means: improve your situation by your own efforts, without anyone else's help, and usually in some difficult or seemingly impossible way.



- Bootstrap sample: random sample taken with replacement
- Bootstrapping has wide application, e.g., bootstrap aggregation ( bagging
- Observations not selected in the bootstrap are called out-of-bag samples
- Here: each of the B bootstraps are same size as original data
- Model is built on the bootstrap and tested against the out-of-bag data.

79/91

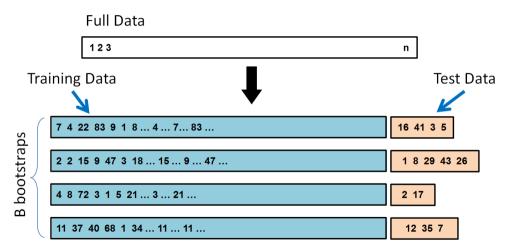
# bootstrap sampling

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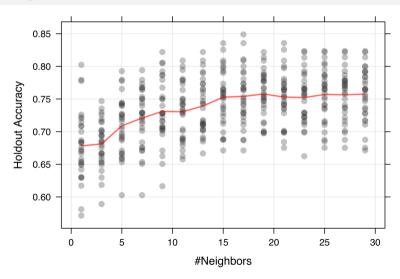
# model tuning

The resampling techniques can give us good estimates of model performance on new data, but there is still the issue of selecting the right model complexity – that is, determining the best hyperparameters for a model class.

# model tuning algorithm

```
define sets of model parameter values to evaluate:
for each parameter set do
   for each resampling iteration do
       hold-out specific samples;
      fit the model on the remainder:
       predict the hold-out samples;
   end
   calculate the average performance across hold-out predictions:
end
determine the optimal parameter set
```

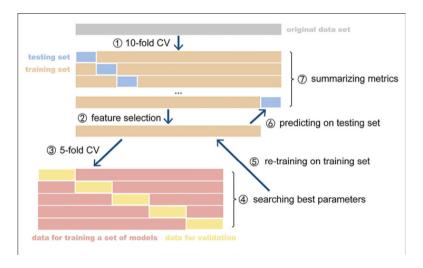
#### example: tuning kNN



### to summarize

- A single evaluation of a model (e.g. using one test set) has limited ability to characterize the uncertainty in the results
- Resampling methods can help with tuning and performance estimates on new data.
  - error is average of error across all resampled predictions
  - k-fold is very common technique; k = 5 or 10
  - LOOCV less biased, but more variance than k-fold CV
  - for large data, the bias and variance difference in 5-fold, 10-fold, and bootstrapping becomes insignificant
  - repeated k-fold less bias and less variance than single k-fold
- Final model for resampled techniques: after selecting best complexity level, build model on full data

#### there are other approaches, e.g., nested cv is probably the best



# model specifications

Two main conventions for specifying models in R:

- the formula interface
- the non-formula (or "matrix") interface

### formula interface

The formula interfaces explicitly lists the predictors:

outcome 
$$\sim \text{var1} + \text{var2} + \dots$$

### formula interface

The formula interfaces explicitly lists the predictors:

```
outcome \sim var1 + var2 + ...
```

for example,

```
modelFunction(price ~ numBed + numBath + acres, data= housingData)
```

would predict house price based on 3 quantitative characteristics: number of bedrooms, bathrooms, and acreage

where modelFunction is a command such as lm, kNN, rpart, etc.

### formula interface

The shortcut  $\mathbf{y} \sim$  . indicates that all columns in the data (except y) should be used as a predictor.

The formula interface has many conveniences, e.g.

- some transformations can be specified in-line, e.g. log(acres)
- automatically converts factor predictors into dummy variables (for some model functions)

### matrix interface

The matrix interface specifies predictors using a matrix (or data frame). All the predictors in the object are used in the model.

Outcome data are specified as a vector object.

for example,

```
modelFunction(x = housePredictors, y = price)
```

Any transformations or dummy coding must be performed prior to being passed to the function.

Note that not all R functions have both interfaces.

Modeling in R generally follows a workflow:

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- Create the model using the appropriate function, e.g. fit <- knn(trainingData, outcome, k =5)</p>
- Assess the properties of the model using print, plot, summary or other methods
- Predict outcomes for samples using the predict method: predict(fit, newSamples)

Several modeling packages in R, written by different people. Some inconsistencies in model specification/prediction syntax.

#### For example,

- many models have only one method of specifying the model (e.g. formula method only)
- generating class probabilities may be different,

command	package	predict function syntax
lda	MASS	<pre>predict(obj) (no options needed)</pre>
glm	stats	<pre>predict(obj, type ="response")</pre>
rpart	rpart	<pre>predict(obj, type ="prob")</pre>