DSA/ISE 5103 Intelligent Data Analytics

Data Preparation

Charles Nicholson, Ph.D. cnicholson@ou.edu

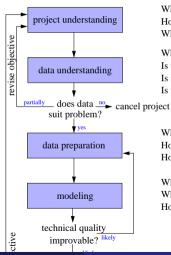
University of Oklahoma
Gallogly College of Engineering
School of Industrial and Systems Engineering

Outline



- Data Understanding and Preparation
- Improve data quality
- Treat Outliers
- Resolving Missing Values
- Feature Engineering

data preparation



What exactly is the problem, the expected benefit?

How would a solution look like?

What is known about the domain?

What data do we have available?

Is the data relevant to the problem?

Is it valid? Does it reflect our expectations?

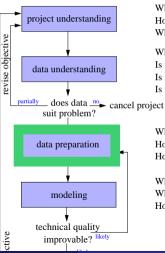
Is the data quality, quantity, recency sufficient?

Which data should we concentrate on?

How is the data best transformed for modeling? How may we increase the data quality?

What kind of model architecture suits the problem best? What is the best technique/method to get the model? How good does the model perform technically?

data preparation



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level of quality

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feature extraction feature construction feature selection

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which may alter data understanding

data scrubbing

Data cleansing or data scrubbing refers to detecting, correcting and/or removing

- inaccurate
- incorrect
- incomplete

records from a data set.

- Turn all characters into capital letters
- Remove spaces and non-printing characters
- Split fields that carry mixed information into two separate attributes, e.g. "Chocolate, 100g" into "Chocolate" and "100.0". This is known as field overloading.
- Use spell-checker to normalize spelling in free text entries.
- Replace abbreviations by their long form
- Normalize the writing of addresses and names

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improve data quality

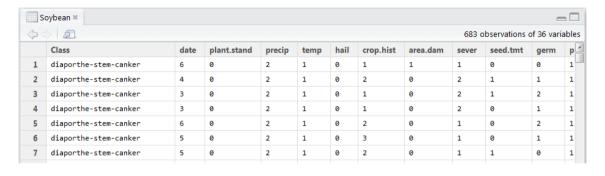
Ensure the computer is storing the values in appropriate system data types:

- e.g., computers store "dates" in several ways
 - as text
 - number of days since Jan, 1, 1960
 - number of seconds since Jan 1, 1960

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improve data quality

- e.g., are your "numeric" fields really numeric?
 - in the Soybean data (from the mlbench package), the value for hail is not numeric



> mean(Soybean\$hail)
[1] NA

Warning message:

In mean.default(Soybean\$hail):

argument is not numeric or logical: returning NA

FYI- the str command is a useful way to look at the structure of an R object.

None of the "numeric" looking data in the Soybean data is actually stored as numeric values!

```
> str(Soybean)
'data frame': 683 obs. of 36 variables:
             : Factor w/ 19 levels "2-4-d-injury",..: 11 11 11 11 11 11 11 11 11 11 ...
$ Class
 $ date
                : Factor w/7 levels "0", "1", "2", "3"...: 7 5 4 4 7 6 6 5 7 5 ...
                  : Ord.factor w/ 2 levels "0"<"1": 1 1 1 1 1 1 1 1 1 1 ...
$ plant.stand
                 : Ord.factor w/ 3 levels "0"<"1"<"2": 3 3 3 3 3 3 3 3 3 3 ...
$ precip
                 : Ord.factor w/ 3 levels "0"<"1"<"2": 2 2 2 2 2 2 2 2 2 2 ...
$ temp
 $ hail
                : Factor w/ 2 levels "0", "1": 1 1 1 1 1 1 1 2 1 1 ...
                 : Factor w/ 4 levels "0","1","2","3": 2 3 2 2 3 4 3 2 4 3 ...
$ crop.hist
                  : Factor w/ 4 levels "0"."1"."2"."3": 2 1 1 1 1 1 1 1 1 1 1 ...}
 $ area.dam
```

digression: converting data types in R

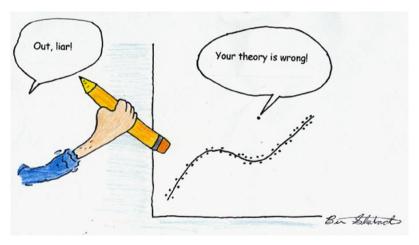
Data type conversion in R is relatively simple (assuming the values and types are compatible)

e.g., Soybean\$hail <- as.numeric(Soybean\$hail)

There are many resources online that explain type conversion in R.

e.g., www.statmethods.net/management/typeconversion.html

treating outliers



http://davidmlane.com/ben/cartoons.html

treating outliers

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Knowing why an observation is an outlier is important.

- Are they mistakes? If so, fix.
- Unusual circumstances that differ from the study objectives? If so, delete them - but explain the reason clearly.
- Are they just unusual? If so, discuss why they are unusual.
 Does it suggest other variables that might be included in the model?
- In many analyses the outliers are the most interesting things.

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Falsification is manipulating research materials, equipment, or processes or changing or **omitting data or results** such that the research is not accurately represented in the research record. ¹

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 - en masse deletion is usually not a good idea
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Outlier analysis and treatment requires context.

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Non-ignorable: It is difficult to provide sensible estimations for the missing values.

- It can be difficult to distinguish MCAR, MAR, and MNAR.
- MNAR is the most likely missing value mechanism.

```
x<-rexp(1000) # with exponential distribution
y<-rnorm(1000) # with normal distribution
z<-runif(1000) # with uniform distribution</pre>
```

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x<-rexp(1000) # with exponential distribution
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df<-data.frame(x,y)
df[df$x>2.1, "y"]<-NA</pre>
```

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    df < -data.frame(x,y)
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    df < -data.frame(x,v)
    df[df$v>1.10, "v"]<-NA
```

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    df < -data.frame(x,y)
    df[z>0.9. "v"]<-NA
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$$\leftarrow$$
 MAR

$$\leftarrow$$
 MNAR

dealing with missing values

- Deletion
- Indicators
- Imputation

dealing with missing values

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 - Complete Case Analysis
 - Available Case Analysis
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Complete case analysis a.k.a. *listwise* deletion: analyze only cases without missing values (delete the record if any value missing)

- Advantage: simple
- Disadvantages:
 - throws away information
 - reduces statistical power (reduces sample sizes)

age	income	gender
54	93500	F
44	72000	
27	90000	F
26		M
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31	135000	F
25	40000	М
39		- F

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- Advantage: keeps as much information as possible
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deletion

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excluding missing values from analyses in R

Arithmetic on missing values yield missing values

```
x <- c(1,2,NA,3)
mean(x) # returns NA
mean(x, na.rm=TRUE) # returns 2</pre>
```

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Most modeling functions in R offer options for dealing with missing values, e.g.

Usage

```
median(x, na.rm = FALSE)
```

Arguments

x an object for which a method has been defined, or a numeric vector containing the values whose median is to be computed.

na.rm a logical value indicating whether NA values should be stripped before the computation proceeds.

excluding missing values from analyses in R

Extract only complete cases

```
complete.cases() returns a logical vector indicating which cases are complete
```

```
# list rows of data that have missing values mydata[!complete.cases(mydata),]
```

```
na.omit() directly returns complete cases in data frame
```

```
# create new data frame without missing data
newdata <- na.omit(mydata)</pre>
```

dealing with missing values

- Deletion
- Indicators
- Imputation

indicators

The "missingness" of the data itself might be an important factor

 New binary attribute can be created to indicate whether or not a variable has/had missing data.

age	income	incomeMissing	gender	genderMissing
54	93500	0	F	0
44	72000	0		1
27	90000	0	F	0
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dealing with missing values

- Deletion
- Indicators
- Imputation
 - single imputation
 - multiple imputation (MI)
 - maximum likelihood (ML)

- single value imputation
 - missing values are replaced by an estimate (e.g. mean, median)
 - ...changes the distribution of that variable
 - ...the variance is underestimated
 - generally considered BAD!
- stratified imputation
 - replace missing values with conditional mean or median
- model-based imputation
 - use model to "predict" the missing value based on non-missing values

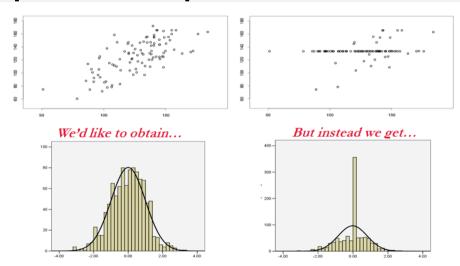
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example: mean imputation



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 - use model to "predict" the missing value based on non-missing values

- single value and stratified imputation
 - hotdeck (not exactly a "single value" or "stratified" imputation method)
 - mean imputation; conditional mean imputation
- model-based imputation
 - regression imputation
 - regression with error imputation
 - predictive mean matching
 - *k*-nearest neighbor imputation

examples of imputation effects

1,000 records without missing values:

$$x \sim \text{Exp}(1)$$

 $y \sim N(0, 0.5) + 0.5x$

Missing Value Mechanism:

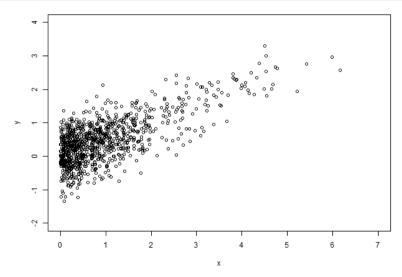
for y: MCAR, MAR, and MNAR

R code: data creation for example

```
#CREATE SOME FAKE DATA (with v = f(x))
x < -rexp(1000)
v<-0.5*rnorm(1000) + 0.5*x
df < -data.frame(x,y)
# now lets create some missing values....
dfMiss <- df
beta<-runif(1000) \# not included in dataframe
dfMiss[df$v>1.30,"v"]<-NA
                                #MNAR.
dfMiss[beta>0.90,"v"]<-NA
                                 #MCAR
dfMiss[df$x>2.65,"y"]<-NA
                                #MAR.
```

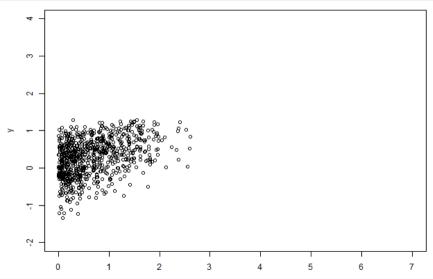
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scatter plot with no missing data



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scatter plot (missing data)

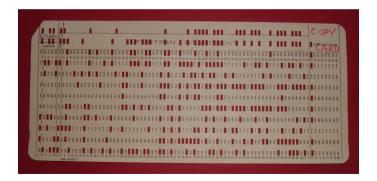


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hotdeck

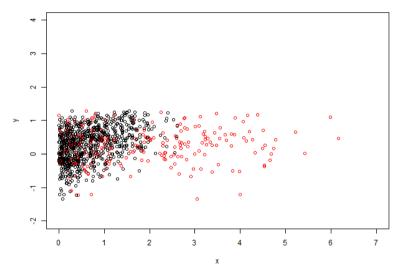
- "Hotdeck" imputation from 1940's 1950's by census bureau
- uses Hollerith cards from "similar group" for missing data



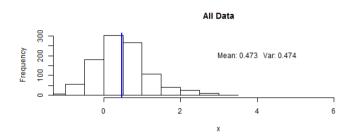
hotdeck (R code)

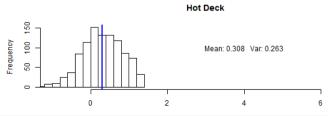
```
dfHD.imp <- dfMiss #copy of data with missings
#create vector identifying missings
missing <- is.na(dfHD.imp$v)
#create sample pool from non-missing data
hotdeck <- dfHD.imp[!missing, "y"] #sample pool
n <- length(hotdeck) #size of sample pool
m <- sum(missing)
                     #how many samples do I need?
#sample m values (with replacement) from pool
hotdeck <- hotdeck[sample(n.m.replace=TRUE)]
```

scatter plot: hotdeck imputation



histogram: hotdeck





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mean imputation (R code)

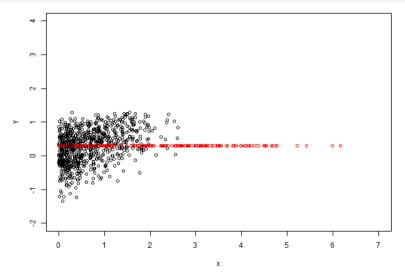
```
#imputation by mean
```

dfMean.imp<-dfMiss

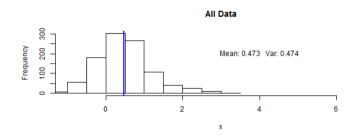
dfMean.imp[missing,"y"]<-mean(dfMean.imp\$y,na.rm=T)</pre>

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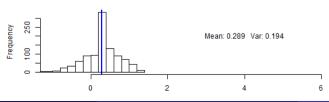
scatter plot: mean imputation



histogram: mean imputation



Mean Imputation



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regression imputation

Build regression model on complete cases. Use the model to generate predicted values for the missing ones.

 $lm(dfMiss\$y \sim dfMiss\$x)$

		Estimate	Std. Error	t value	Pr(> t)	
Coefficients:	(Intercept) x	0.00490 0.49430	0.0217 0.0159	0.236 30.99	0.821 < 2.2e-16	***

Residual std error: 0.4918 on 998 degrees of freedom

Multiple R-squared: 0.49, Adjusted R-squared: 0.49

F-statistic: 960.5 on 1 and 998 DF, p-value: < 2.2e-16

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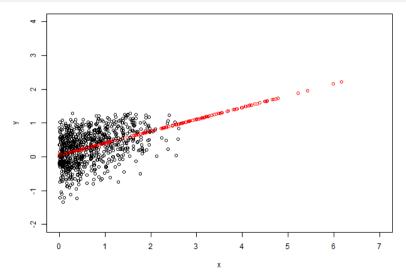
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F-statistic: 960.5 on 1 and 998 DF, p-value: < 2.2e-16

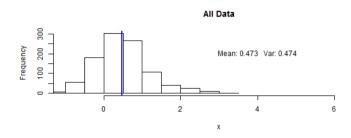
$$\hat{y} = 0.00490 + 0.49430x$$

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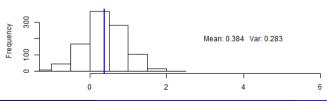
scatter plot: regression imputation



histogram: regression imputation



Regression Imputation



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regression imputation with error

_		Estimate	Std. Error	t value	Pr(> t)	
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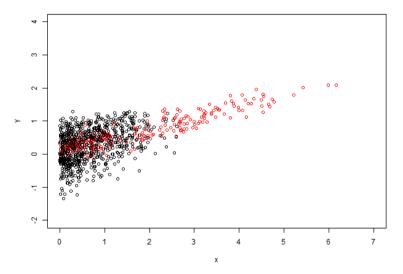
F-statistic: 960.5 on 1 and 998 DF, p-value: < 2.2e-16

$$\hat{y} = 0.00490 + 0.49430x + N(0, SE^2)$$

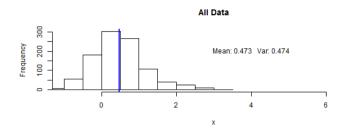
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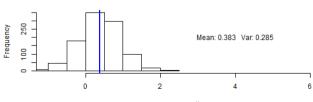
scatter plot: regression with error



histogram: regression with error



Regression Imputation with Error



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To mitigate problems with "global models" creating outrageous estimates, predictive mean matching is a hybrid approach that incorporates a model with the observed value range.

Predictive mean matching (PMM) is essentially a sophisticated "hot-deck" method which produces values that are more like real values.

- If the original variable is skewed, the imputed values will be skewed; if the original variable is bounded, the imputed values will be bounded
- PMM returns only observed values

- **1** Perform a linear regression $\mathbf{x} \sim \mathbf{y} + \mathbf{z}$ and estimate β (and σ)
- ② Draw β^* from the "posterior predictive distribution" of β , (e.g., a multivariate normal distribution with mean = β and related σ)
- Ompute predicted values $\hat{\mathbf{x}}$ for all \mathbf{x} using β^* : $\hat{\mathbf{x}}_{\text{miss}}$ and $\hat{\mathbf{x}}_{\text{obs}}$
- For each case of missing \mathbf{x} , identify non-missing cases whose $\hat{\mathbf{x}}_{obs}$ are closest $\hat{\mathbf{x}}_{miss}$
- Randomly sample from these cases and use the observed value of x as the imputed value

- Perform a linear regression $\mathbf{x} \sim \mathbf{y} + \mathbf{z}$ and estimate β (and σ)
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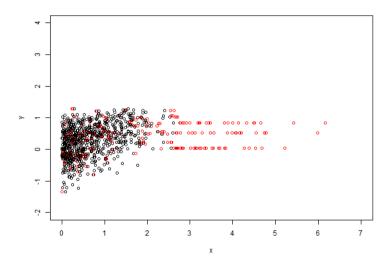
Note: in PMM, the purpose of the linear regression is *not* to generate imputed values, but to construct a metric for matching.

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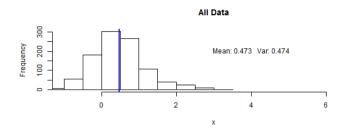
Note: in PMM, the purpose of the linear regression is *not* to generate imputed values, but to construct a metric for matching.

The default set of "donor pool" in the mice package is 5.

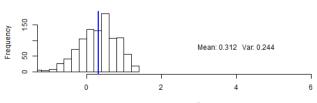
scatter plot: predictive mean matching



histogram: predictive mean matching



Predictive Mean Matching



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k-nearest neighbor

k-nearest neighbors (kNN) is a simple modeling technique that has applications beyond missing value imputation.

k-nearest neighbor

k-nearest neighbors (kNN) is a simple modeling technique that has applications beyond missing value imputation.

To that end, let's digress a bit and introduce the important concept of a *neighbor*.

what is a neighbor?

What is a *neighbor* of an observation? How do you determine which cases are it's *nearest* neighbors?

what is a neighbor?

What is a *neighbor* of an observation? How do you determine which cases are it's *nearest* neighbors?

Remember, usually the data is mixed-type, e.g. what are neighbors of cases:

Х	У	Z	Gender	Vote	Education
0.15	NA	.94	М	Dem	3
0.47	0.33	NA	F	NA	2
0.39	NA	NA	F	Rep	3
0.07	0.10	NA	М	Ind	1

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distance

To evaluate *nearness*, we need a measure for distance, e.g.:

• Euclidean distance:

$$d(i,j) = \sqrt{(x_{i1} - x_{j1})^2 + (x_{i2} - x_{j2})^2 + \ldots + (x_{ip} - x_{jp})^2}$$

Manhattan distance:

$$d(i,j) = |x_{i1} - x_{j1}| + |x_{i2} - x_{j2}| + \ldots + |x_{ip} - x_{jp}|$$

• Minkowski distance:

$$d(i,j) = (|x_{i1} - x_{j1}|^q + |x_{i2} - x_{j2}|^q + \ldots + |x_{ip} - x_{jp}|^q)^{\frac{1}{q}}$$

mixed data: Gower's distance

Use distance measure between 0 and 1 for each variable: $d_{ij}^{(f)}$

mixed data: Gower's distance

Use distance measure between 0 and 1 for each variable: $d_{ij}^{(f)}$

Aggregate:

$$d(i,j) = \frac{1}{p} \sum_{f=1}^{p} \delta_{ij}^{f} d_{ij}^{(f)}$$

where δ^f_{ij} is a weighting factor

$$\delta_{ij}^{f} = \begin{cases} 0 & \text{if } x_{if} \text{ or } x_{jf} \text{ is missing} \\ 0 & \text{if } x_{if} \text{ and } x_{jf} \text{ are false (with binary data)} \\ 1 & \text{otherwise} \end{cases}$$

For interval or ordinal data....

Uses range scaling:

$$d_{ij}^{(f)} = \frac{\left|x_{if} - x_{jf}\right|}{R_f}$$

 x_{if} , x_{jf} are values for object i and j in variable f and R_f is the range of variable f

Ordinal: Use normalized ranks then use interval-scaled method

For nominal data...

Simple matching coefficient:

$$d^{(f)}(i,j)=\frac{m}{p}$$

where

m: number of variables in which object i and j mismatch

p: number of variables

Binary data:

Jaccard distance:

$$d^{(f)}(i,j)=1-\frac{D_{ij}}{D_{ij}+X_{ij}}$$

b: both values are 1

where, x: only one value is 1

n: both values are 0

Binary data:

Jaccard distance:

$$d^{(f)}(i,j)=1-\frac{b_{ij}}{b_{ij}+x_{ij}}$$

b: both values are 1

where, x: only one value is 1

n: both values are 0

i j b n
$$x \mid d_{ij}$$
101000 111000 2 3 1 0.3 $\bar{3}$

Obs	male	citizen	own car	marital status	State	age	income
1	TRUE	TRUE	TRUE	M	TX	41	53
2	FALSE	TRUE	TRUE	M	TX	39	72
3	TRUE	TRUE	FALSE	S	CA	43	70
4	FALSE	FALSE	TRUE	D	OK	48	47
5	TRUE	TRUE	FALSE	D	NY	50	63
6	FALSE	FALSE	TRUE	M	OK	45	71
dist	male	citizen	own car	marital status	State	age	income
1 & 2	$1 - \frac{2}{3}$	$1 - \frac{2}{3}$	$1 - \frac{2}{3}$	$\frac{0}{2}$	<u>0</u> 2	<u>2</u> 11	1 <u>9</u> 25
2 & 6	$1 - \frac{1}{2}$	$1 - \frac{1}{2}$	$1 - \frac{1}{2}$	$\frac{1}{2}$	1/2	<u>6</u> 11	1 25

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		1	2	3 4 5	6		



distance metrics using R

For distance calculations in R, see the following functions:

- dist in base distribution (includes Minkowski)
- daisy in package cluster
- gower.dist in package StatMatch

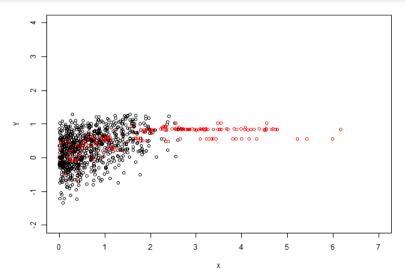
k-nearest neighbor

kNN uses the values of the k-nearest neighbors of the observation to impute the missing value

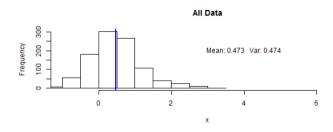
```
library(VIM)
```

```
#using x,y, and z data for kNN computation
dfKNN.imp <- kNN(dfMiss[,1:3],k=5)</pre>
```

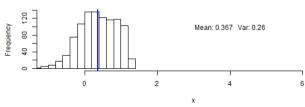
scatter plot: kNN with 5 neighbors



histogram: kNN



k-Nearest Neighbor



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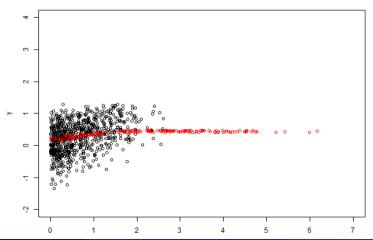
scatter plot: kNN with 400 neighbors

What would happen if we use 400 of the nearest neighbors?

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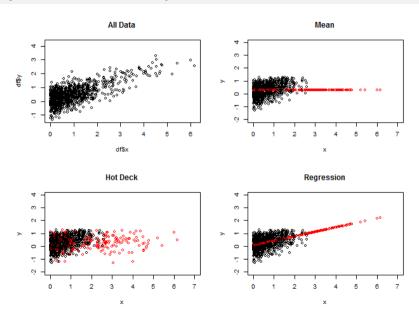
scatter plot: kNN with 400 neighbors

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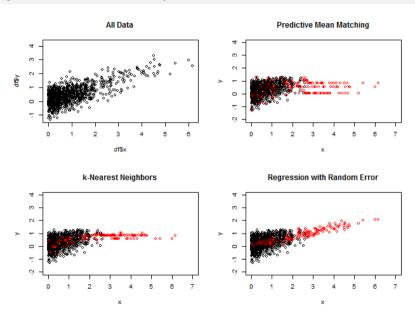


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single imputation summary



single imputation summary



single imputation and missing data

- Missing data is bad, yet almost certain to occur
- The three missing value mechanism types may all be present most resolution approaches assume MCAR or MAR
- Imputation methods do not create new information... they are not magical
- ...and can hurt estimates
 e.g. by artificially decreasing variance
- The goals of imputation:
 - Preserve the essential characteristics of the data (distributions, relationships among the variables)
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Multiple imputation (MI) is a modern and increasingly popular Monte Carlo technique for analyzing data with missing values (Rubin 1987).

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Multiple imputation (MI) is a modern and increasingly popular Monte Carlo technique for analyzing data with missing values (Rubin 1987).

MI is comprised of four steps.

- Replication
- Imputation
- Analysis
- Recombination

MI produces estimates that have nearly optimal statistical properties:

- approximately unbiased in large samples
- stable estimates

MI requires:

- missing data be "ignorable"
- good imputation model

replication step

Create m > 1 copies of the original data sets.

replication step

Create m > 1 copies of the original data sets.

- the number of sufficient copies for imputations, *m*, is typically small, i.e. 3-10 (depends on percentage of missing data)
- managing multiple copies of the data set can be complex
 - e.g., with "big data" and large volume, maybe very difficult
 - practically, keeping up with multiple copies could be a headache...
 - however, modern software packages (including R) take care of the latter problem automatically

In each copy, perform *single imputation* with some random element, e.g. regression with error.

In each copy, perform *single imputation* with some random element, e.g. regression with error.

The result is *m* complete, but slightly different data sets.

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- many possible strategies, e.g.,
 - regression with error
 - predictive mean matching
 - random forests
 - random sampling
- imputation model needs to be compatible with the analysis model

imputation step: several missing variables

A brief digression...

It is common to have missing data in *several* variables in an analysis.

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It is common to have missing data in *several* variables in an analysis.

In such a case you cannot simply impute based on a model for a single partially observed variable *y* given a set of fully observed *X* variables.

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It is common to have missing data in *several* variables in an analysis.

In such a case you cannot simply impute based on a model for a single partially observed variable *y* given a set of fully observed *X* variables.

One method to address this is to perform iterative imputation.

iterative imputation

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The process continues until a certain level of convergence is reached.

iterative regression imputation

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- impute all missing Y values using a crude approach (e.g., impute by randomly selecting from observed outcomes of variable)
- ② re-impute y_1 based on y_2, \ldots, y_k and X
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- and so on, randomly imputing each variable and looping through until approximate convergence.

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analysis step

Analyze each of the m complete data sets independently.

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analysis step

Analyze each of the m complete data sets independently.

A standard analysis is run on each of the datasets.

Calculate and save the estimates and standard errors from each analysis.

The inferences will later be combined across all *m* datasets.

recombination step

Combine analyses for some quantity of interest q by computing average and overall variance estimate across all m datasets.

e.g., the quantity of interest might be a regression coefficient, β_1

Let \hat{q}_j denote the estimate obtained from dataset j = 1, ..., m. Let s_j^2 denote the corresponding variance associated with \hat{q}_j .

The overall estimate is the average; the overall variance has two parts: "within" and "between" imputation variance.

overall estimate:
$$\bar{q} = \frac{1}{m} \sum_{j=1}^{m} \hat{q}_j$$

"within":
$$W = \frac{1}{m} \sum_{j=1}^{m} s_j^2$$

"between":
$$B = \frac{1}{m-1} \sum_{j=1}^{m} (\hat{q}_{j} - \bar{q})^{2}$$

overall variance :
$$\bar{s}_q^2 = W + (1 + \frac{1}{m}) B$$

Confidence intervals are obtained by:

$$ar{q} \pm \emph{t}_{lpha, \emph{df}} ar{s}_{\emph{q}}$$

where the degrees of freedom are given by,

$$df = (m-1)\left(1 + \frac{mW}{(m+1)B}\right)^2$$

A significance test of the null hypothesis q = 0 is performed by comparing the ratio to the same t-distribution.

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- In ML no conflict between the imputation and analysis models
- In ML, you do need to consider the distributions of all your variables

Suppose we have n observations and p variables.

First step in ML is to construct the likelihood function:

$$L=\prod_{i=1}^n f_i(x_{i1},\ldots,x_{ip};\Theta)$$

where $f_i(.)$ is the joint probability function for observations i = 1, ..., n and Θ is a set of parameters to be estimated. The ML estimates for Θ are the ones that maximize L.

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If we have missing data, e.g., if for observation i, variables x_1 and x_2 are missing, the joint probability i is:

$$f_i^*(x_{i3},\ldots,x_{ip};\Theta) = \int_{x_1} \int_{x_2} f_i(x_{i1},\ldots,x_{ip}) dx_1 dx_2$$

If there are m observations with complete data and n-m observations with data missing on x_1 and x_2 , the overall likelihood function for the full data set becomes:

$$L = \prod_{i=1}^{m} f_i(x_{i1}, \dots, x_{ip}; \Theta) \prod_{i=m+1}^{n} f_i^*(x_{i3}, \dots, x_{ip}; \Theta)$$

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Major issue...

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- This will probably improve over time.

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In many applications, at least for now, approximate solutions with good properties (i.e., MI) may be preferable to those with potentially theoretically better properites, (i.e., ML).

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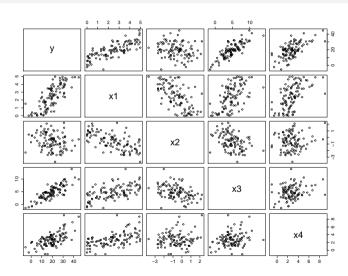
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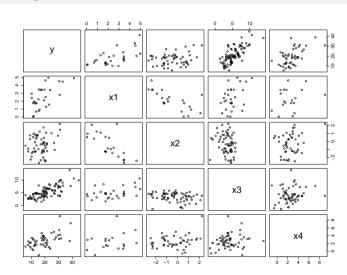
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- Analysis model: $y \sim x1 + x2 + x3 + x4$
- Goal: Estimate coefficients for analysis model

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Full data pairs plot

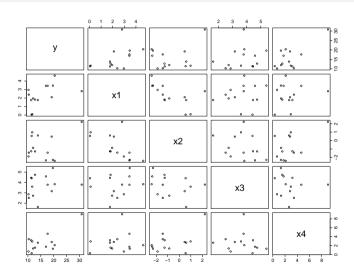


Available cases pairs plot



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Complete cases pairs plot



		Estimate	Std. Error	Pr(> t)	Notes
Full data	(Intercept) x1 x2 x3 x4	-0.4613 5.1622 4.2215 2.0978 -0.0734	0.2376 0.15894 0.15024 0.04478 0.0986	$\begin{array}{l} 0.0552 \\ < 2^{-16} \\ < 2^{-16} \\ < 2^{-16} \\ 0.4589 \end{array}$	95 df
Listwise deletion	(Intercept) x1 x2 x3 x4	-1.837 5.3471 4.7343 2.4607 -0.2205	1.0596 0.3608 0.3832 0.2536 0.1977	0.117 1.25E-07 6.01E-07 4.60E-06 0.294	9 df
MICE	(Intercept) x1 x2 x3 x4	-0.4993 4.9422 4.2716 2.1312 -0.0504	1.2335 0.3426 0.2767 0.2643 0.1378	7.30E-01 1.58E-04 1.41E-05 3.96E-02 7.23E-01	imputed 71 35 0 40

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- Most imputation methods expect MCAR or MAR as missing value mechanisms
- Deletion should only be used under MCAR and with relatively few affected cases
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- MI is not the *only* principled way to deal with missing values, but it is one good way
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feature engineering

- Feature transformation
- Feature construction
- Feature extraction
- Feature selection

definition of feature

Features

Features are functions of the original measurement variables that are useful for classification, pattern recognition, prediction, or other modeling technique.

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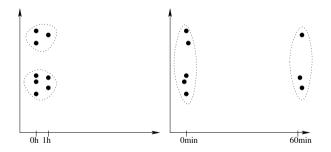
"Transformations impact interpretability"

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standardization

Some techniques (e.g. PCA, clustering) are sensitive to scale



To mitigate, some kind of standardization should be applied.

standardization

for a numerical attribute X, value $x_i \in X$:

min-max normalization : $dom(X) \rightarrow [0, 1]$

$$x_i^{'} \leftarrow \frac{x_i - \min_X}{\max_X - \min_X}$$

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robust z-score standardization : $dom(X) \rightarrow \mathbb{R}$

$$x_i^{'} \leftarrow \frac{x_i - \tilde{x}}{IQR_x}$$

Problems with skewed distribution

- Data difficult to examine because most observations are in a small part of the range of the data.
- The mean is not a good summary of the center of a skewed distribution.
- Certain techniques (e.g. outlier identification, some imputation techniques, etc.) expect the data to be normally distributed.

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Ladder of Powers

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Ladder of Powers

Positive skew: need to compress large values

→ descend the ladder of powers

Ladder of Powers

- Positive skew: need to compress large values
 - → descend the ladder of powers
- Negative skew: need to compress small values
 - → ascend the ladder of powers

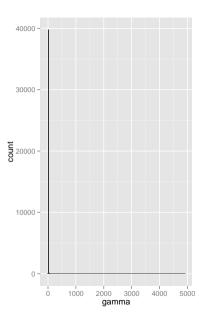
ladder of powers

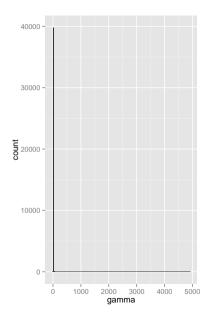
Transformation is (basically): $x \leftarrow x^{\lambda}$

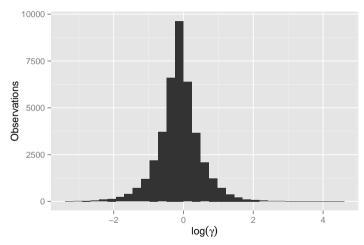
λ	Transformation $f_{\lambda}(x)$
3	<i>x</i> ³
2	x ³ x ²
1	X
$\frac{1}{2}$	\sqrt{X}
Ō	\sqrt{X} $\log(X)$
-1	$-\frac{1}{y}$
-2	$-\frac{\hat{1}}{v^2}$
-3	$-\frac{\overline{x^2}}{\overline{x^3}}$

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Box Cox transformations

Box-Cox transformations try to make the data more normal.

$$x \leftarrow \begin{cases} \frac{x^{\lambda} - 1}{\lambda} & \text{if } \lambda \neq 0 \\ \log(x) & \text{if } \lambda = 0 \end{cases}$$

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transformation example with R

Example transformations on the Prestige data frame in the car package; as well as simulated exponential distributions.

Using the symbox function from car package, and the boxcox function from EnvStats package.

Feature construction is a process that "augments the space of features" by creating new features from the existing ones in order to fill missing information about relationships between the variables.

Liu, H. and H. Motoda. 1998. Feature Extraction, Construction and Selection: A Data Mining Perspective. Kluwer Academic Publishers.

Find the best workers in a company

Attributes:

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 - the tasks, a worker has finished within each month,

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- ullet efficiency $= {{
 m hours\ actually\ spent\ to\ finish\ the\ tasks} \over {{
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y	<i>X</i> ₁	<i>X</i> ₂	<i>X</i> 3	<i>X</i> ₄
2148.54	18.4105	-66.0605	30.3264	-97.7713
1790.37	42.3706	-71.0270	27.7770	-97.4632
2227.08	43.0214	-76.1977	47.6838	-122.3012
360.94	35.7977	-78.6253	33.7930	-84.5041
1239.83	35.5514	-97.4075	36.7464	-119.6397

y
$$x_1$$
 x_2 x_3 x_4 2148.5418.4105-66.060530.3264-97.77131790.3742.3706-71.027027.7770-97.46322227.0843.0214-76.197747.6838-122.3012360.9435.7977-78.625333.7930-84.50411239.8335.5514-97.407536.7464-119.6397

$$a = \sin^2\left(\frac{x_1 - x_3}{2} \frac{\pi}{180}\right) + \cos\left(\frac{x_1 \pi}{180}\right) \cos\left(\frac{x_3 \pi}{180}\right) \sin^2\left(\frac{x_2 - x_4}{2} \frac{\pi}{180}\right)$$
$$Y = 2R \arctan\left(\sqrt{a}, \sqrt{1 - a}\right)$$

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Distance	Latitude 1	Longitude 1	Latitude 2	Longitude 2
2148.54	18.4105	-66.0605	30.3264	-97.7713
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Distance	Latitude 1 Longitude 1	Latitude 2 Longitude 2
2148.54	San Juan, PR	Austin, TX
1790.37	Boston, MA	Corpus Christi,TX
2227.08	Syracuse, NY	Seattle, WA
360.94	Raleigh, NC	Atlanta, GA
1239.83	Oklahoma City, OK	Fresno, CA

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• ratios (e.g., crimes per capita)

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- binning (create binary indicators, or "levels" corresponding to intervals)

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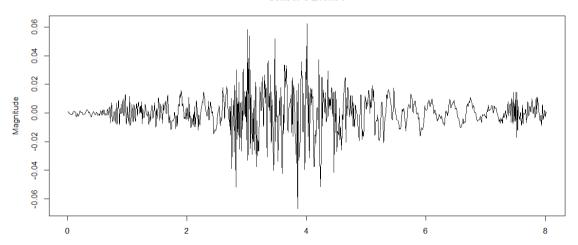
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- PCA, MDS
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- other mappings to new space (e.g., fast fourier transforms)

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mapping to new space

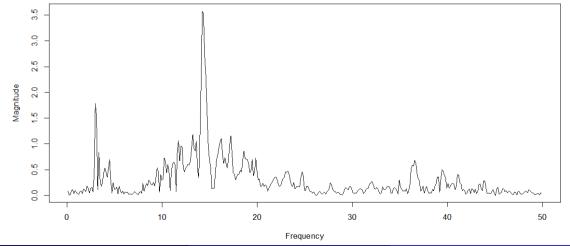
Sensor 8 Event 1



Charles Nicholson

mapping to new space

Frequency Spectrum



Charles Nicholson

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Basic approach: can be effective; can be disastrous

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- remove predictor attributes NOT related to target attribute

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Advanced approaches include *forward selection* and *backward elimination*; automatic selection in trees; variable ranking

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- Do you suspect interdependence of features?
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- Are your variables highly skewed?
 - If yes, consider reducing skew through transformations.

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- Do you have new ideas, time, and computing resources?
 - If yes, try lots of things! The biggest bang for your buck is in feature engineering.