ISE 4623/5023: Deterministic Systems Models / Systems Optimization

University of Oklahoma

School of Industrial and Systems Engineering

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Individual Assignment 1 - Linear Algebra (100 points) Solution/Answers

Problem 1 (30 points)

Let
$$A = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 3 \end{bmatrix}$$
 and $B = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 4 & 2 \end{bmatrix}$

a)
$$AB = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 4 & 2 \end{bmatrix} = \begin{bmatrix} 1 \cdot 1 + 2 \cdot 2 + 2 \cdot 4 & 1 \cdot 1 + 2 \cdot 3 + 2 \cdot 2 \\ 2 \cdot 1 + 1 \cdot 2 + 3 \cdot 4 & 2 \cdot 1 + 1 \cdot 3 + 3 \cdot 2 \end{bmatrix} = \begin{bmatrix} 1 + 4 + 7 & 1 + 6 + 4 \\ 2 + 2 + 12 & 2 + 3 + 6 \end{bmatrix} = \begin{bmatrix} 13 & 11 \\ 16 & 11 \end{bmatrix}$$

b)
$$BA = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 \cdot 1 + 1 \cdot 2 & 1 \cdot 2 + 1 \cdot 1 & 1 \cdot 2 + 1 \cdot 3 \\ 2 \cdot 1 + 3 \cdot 2 & 2 \cdot 2 + 3 \cdot 1 & 2 \cdot 2 + 3 \cdot 3 \\ 4 \cdot 1 + 2 \cdot 2 & 4 \cdot 2 + 2 \cdot 1 & 4 \cdot 2 + 2 \cdot 3 \end{bmatrix} = \begin{bmatrix} 1 + 2 & 2 + 1 & 2 + 3 \\ 2 + 6 & 4 + 3 & 4 + 9 \\ 4 + 4 & 8 + 2 & 8 + 6 \end{bmatrix} = \begin{bmatrix} 3 & 3 & 5 \\ 8 & 7 & 13 \\ 8 & 10 & 14 \end{bmatrix}$$

c)
$$-B = -1 \cdot \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 4 & 2 \end{bmatrix} = \begin{bmatrix} -1 & -1 \\ -2 & -3 \\ -4 & -2 \end{bmatrix}$$

d) A + 2B = Not possible: Different dimensions

e)
$$A^T = \begin{bmatrix} 1 & 2 & 2 \\ 2 & 1 & 3 \end{bmatrix}^T = \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ 2 & 3 \end{bmatrix}$$

f)
$$B^T = \begin{bmatrix} 1 & 1 \\ 2 & 3 \\ 4 & 2 \end{bmatrix}^T = \begin{bmatrix} 1 & 2 & 4 \\ 1 & 3 & 2 \end{bmatrix}$$

Problem 2 (30 points)

a)
$$3x_1 + x_2 = 2$$

$$-6x_1 - 2x_2 = -4$$

$$\rightarrow \text{Infinite solutions since } R_2 = -2 \cdot R_1$$

$$2x_{1} + x_{2} = 4 \xrightarrow{x_{1} + 2x_{2} = 5} \rightarrow \begin{bmatrix} 2 & 1 & | & 4 \\ 1 & 2 & | & 5 \end{bmatrix} \xrightarrow{R_{1} = R_{1} - 2 \cdot R_{2}} \begin{bmatrix} 0 & -3 & | & -6 \\ 1 & 2 & | & 5 \end{bmatrix} \xrightarrow{R_{1} = \frac{R_{1}}{-3}} \begin{bmatrix} 0 & 1 & | & 2 \\ 1 & 2 & | & 5 \end{bmatrix}$$

$$\xrightarrow{R_2 = R_2 - 2 \cdot R_1} \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

c)
$$2x_1 + x_2 = 4$$

 $-4x_1 - 2x_2 = -5$ \rightarrow No solution since \neq $R_2 = -4x_1 - 2x_2 = -5$

Computing an inverse matrix

Consider a 2x2 matrix:

$$\underset{2\times 2}{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

The 2×2 inverse matrix is then:

$$A_{2\times 2}^{-1} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{D} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Where D = ad - bc. D is called the determinant of the matrix.

The 3×3 matrix can be defined as:

$$B_{3\times 3} = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & k \end{bmatrix}$$

Then the inverse matrix is:

$$B_{3\times 3}^{-1} = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & k \end{bmatrix}^{-1} = \frac{1}{\det(B)} \begin{bmatrix} (ek - fh) & -(bk - ch) & (bf - ce) \\ -(dk - fg) & (ak - cg) & -(af - cd) \\ (dh - eg) & -(ah - bg) & (ae - bd) \end{bmatrix}$$

Where det(B) is equal to:

$$det(B) = a(ek - fh) - b(dk - fg) + c(dh - eg)$$

Figure 1: https://rpubs.com/aaronsc32/inverse-matrices

a)
$$C^{-1} = \begin{bmatrix} 1 & 2 \\ 4 & 2 \end{bmatrix}^{-1} = \frac{1}{(1 \cdot 2 - 4 \cdot 2)} \cdot \begin{bmatrix} 2 & -2 \\ -4 & 1 \end{bmatrix} = -\frac{1}{6} \cdot \begin{bmatrix} 2 & -2 \\ -4 & 1 \end{bmatrix} = \begin{bmatrix} \frac{-1}{3} & \frac{1}{3} \\ \frac{2}{3} & -\frac{1}{6} \end{bmatrix}$$

b)
$$D^{-1} = \begin{bmatrix} 2 & 4 \\ 4 & 8 \end{bmatrix}^{-1} \rightarrow \text{Not possible since } R_2 \text{ is linearly dependent of } R_1 : R_2 = 2 \cdot R_1$$

c)
$$E^{-1} = \begin{bmatrix} 1 & 2 & 4 \\ 4 & 2 & 6 \\ 5 & 4 & 10 \end{bmatrix}^{-1}$$
 \rightarrow Not possible since R_3 is linearly dependent of R_1 and R_2 : $R_3 = R_1 + R_2$

$$d) F^{-1} = \begin{bmatrix} 1 & 2 & 4 \\ 4 & 2 & 6 \\ 5 & 4 & 8 \end{bmatrix}^{-1} = \frac{1}{1 \cdot (2 \cdot 8 - 4 \cdot 6) - 2 \cdot (4 \cdot 8 - 6 \cdot 5) + 4 \cdot (4 \cdot 4 - 2 \cdot 5)} \cdot \begin{bmatrix} (2 \cdot 8 - 4 \cdot 6) & -(2 \cdot 8 - 4 \cdot 4) & (2 \cdot 6 - 2 \cdot 4) \\ -(4 \cdot 8 - 6 \cdot 5) & (1 \cdot 8 - 5 \cdot 4) & -(1 \cdot 6 - 4 \cdot 4) \\ (4 \cdot 4 - 2 \cdot 5) & -(1 \cdot 4 - 5 \cdot 2) & (1 \cdot 2 - 4 \cdot 2) \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{2}{3} & 0 & \frac{1}{3} \\ -\frac{1}{6} & -1 & \frac{5}{6} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$$