Bharatiya Vidya Bhavan's SARDAR PATEL INSTITUTE OF TECHNOLOGY



DEPARTMENT OF ELECTRONICS AND TELECOMMUNICATION

ESE (Reexam)

Class: - TE EXTC

Sem: - VI

Total Marks: - 100

Duration: - 3 Hour

Subject: - Operating System (ETC605)

Jan 2020

1) (a) Discuss the functions and services provided by a typical operating system. [CO1]

[10]

Various Components: Kernel, Device Drivers, System Programs

Services:- User Interface, Program execution, I/O operation, File-system manipulation, Communications, Error detection, Resource allocation, Accounting, Protection and security

(b) Define the term process. Hence, list various fields required in the process control block.
[CO2]

Total 8 different fields of PCB (may be nine). Context switching is the major reason for having PCB for each process apart from the individual field requirement.

2) (a) Consider a following set of processes, with length of CPU bursts given in milliseconds as follows:

Process	Burst Time	Arrival Time		
P1	10	0		
P2	- 29	0		
P3	3	0		
P4	7	0		
P5	12	0		

Draw the Gantt charts for FCFS, Non Preemptive SJF and RR (Quantum=10) What is the waiting time of each process for each of the above algorithms? What is the turnaround time of each process for each of the above algorithms? Which algorithm results in the minimum average waiting time? [CO2]

Consider a following set of processes, with length of CPU bursts given in milliseconds as follows:

Process	Burst Time	Arrival Time
P1	14	0
P2	8	0
P3	21	0
P4	10	0

Draw the Gantt charts for FCFS, Non Preemptive SJF and RR (Quantum=10) What is the waiting time of each process for each of the above algorithms? What is the turnaround time of each process for each of the above algorithms? Which algorithm results in the minimum average waiting time? [CO2]

[10]

(b) With respect to any typical OS like Linux or Unix OS, Draw and discuss the process state transition diagram. [CO3]

[10]

Five process states: New, Ready, Running, Blocked, Halted

Draw the process state transition diagram with justification.

(a) Discuss the mechanism of translating the virtual address to its respective physical address for a particular operating system. Consider the concept of segmentation. [CO3] [10]

Memory is divided into segments. Then a segment can be divided into pages of fixed size.

Hence, first describe the concept of segmentation with virtual address definition. [04]

Second, describe the segment translation process with diagram. [06]

OR

Discuss various file allocation methods. [CO3]

[10]

Three Allocation Methods (a) Contiguous (2) Linked (3) Indexed

Take an example with diagram representation in each of the three methods for the comparison.

3) (b) Consider the following page reference string: 7,0,1,2,0,3,0,4,2,3,0,3,2,1,2,0,1,7,0,1

How many page faults would occur for the following replacement algorithms, assuming three page frames? Remember that all frames are initially empty, so your first unique pages will cost one page each.

FIFO

LRU

OPTIMAL [CO2]

[10]

4) (a For a typical file systems, list various file attributes and file operations. [CO2] [10]

File Attributes:- Name, Identifier, Size, Type, Location, Protection, Time-Date-User-Identifier [5]

File Operations:- Create, Write, Read, Reposition, Delete, Truncate [5]

4) (b) List and compare FCFS, SSTF SCAN and C-SCAN disk scheduling algorithms. [CO2] [10]

Four algorithms (a) FCFS (b) SSTF (c) SCAN (d) C-SCAN

Take an example with diagram and table for calculating the seek time in each of the four algorithms for the comparison.

- (a) In an embedded system, there are two types of scheduling algorithms viz static and Dynamic. Compare these two algorithms. [CO3]
- 5) (b) Consider a system with three tasks, which we'll call Task 1, Task 2 and Task 3. Assume all are periodic tasks with periods T1, T2 and T3. Each has a deadline that is the beginning of its next cycle.

Task 1 has P1 = 4 ms, C1 = 1 ms, Task 2 has P2 = 10 ms, C2 = 2 ms and Task 3 has P3 = 15 ms, C3 = 4 ms. Consider static priority scheduling (RMA), draw the time space diagram and calculate processor utilization, schedulability. [CO3]

Ans 5(a):

One major limitation of fixed-priority scheduling is that it is not always possible to fully utilize the CPU.

Static (RMA) only guarantees feasibility at 69% utilization, EDF guarantees it at 100%

Dynamic (EDF) is complicated enough to have unacceptable overhead

Dynamic More complicated than RMA: harder to analyze, Less predictable: can't guarantee which process runs when

Dynamic algorithm behaves unpredictably at overloads, and suffers more from overloads than Static (RMA)

Ans 5(b):

U (schedule bound) = 0.779, Ui (utilization) = 0.7166 i.e Ui < U and is definitely schedulable.

Task1 Priority > Task2 Priority > Task3 Priority

Proce	Burst	Arriva	Priori	FC	EFS	Non P	re-SJF	 	RR (0	Q=10)
SS	Time	1 Time	ty	TW	TA	TW	TA	 	TW	TA
P1	10	0		0	10	10	20		0	10
P2	29	0		10	39	32	61	 	32	61
P3	3	0		39	42	0	3		20	23
P4	7	0		42	49	3	10		23	30
P5	12	0 3		49	61	20	32		40	52
Avera	ige valu	le =		28		13	egge Harry	na to s	23	

Proce	Burst	Arriva	Priori	FCF	S	Non P	re-SJF	-	-	RR (Q=10)
SS	Time	1 Time	ty	TW	TA	TW	TA			TW	TA
P1	14	0		0	14	18	32			28	42
P2	8	0		14	22	0	8			10	18
P3	21	0		22	43	32	53	7 (1) (1) (1) (1) (1) (1) (1) (1) (1) (1)		32	53
P4	10	0		43	53	8	18			28	38
Avera	ige =			19.75		14.5				24.5	

FCFS:-

Current Cylinder	Next Cylinder	Total Cylinder Travel
53	98	45
98	183	85
183	37	146
37	122	85
122	14	108
14	124	110
124	65	59
65	67	2
		640

SCAN:-

Current Cylinder	Next Cylinder	Total Cylinder Travel
53	65	12
65	67	2
67	98	31
98	122	24
122	124	2
124	183	59
183	199	16
199	37	162
37	14	23
		331

SSTF:-

Current Cylinder	Next Cylinder	Total Cylinder Travel
53	65	12
65	67	2
67	37	30
37	14	23
14	98	84
98	122	24
122	124	2
124	183	59
		236

C-SCAN:-

the state of the second second

Current Cylinder	Next Cylinder	Total Cylinder Travel	
53	65	12	
65	67	2	
67	98	31	
98	122	24	
122	124	2	
124	183	59	
183	199	16	
199	0	199	to a large graded
0	14	14	
14	37	23	
		382	

Q.3 (b)