

# AMS 562 FINAL PROJECT: SOLVING 1D POISSON ORDINARY DIFFERENTIAL EQUATION (ODE) WITH LAPACK/BLAS

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*Core components: BLAS/LAPACK, vector, classes.*

## Problem description:

In this project, we will solve a well-posed problem, the *Poisson* equation, numerically. 1D Poisson equation is a fundamental ODE in *boundary value problem* (BVP). The continuous formulation reads:

$$(0.1) \quad -u'' = f(x) \text{ for } x \in (a, b)$$

In order to solve this equation, one needs to know the boundary information, a.k.a. *boundary conditions*. In this project, we consider the most fundamental case, the fixed boundary conditions, a.k.a. *Dirichlet* boundary conditions:

$$(0.2) \quad u(a) = u_a$$

$$(0.3) \quad u(b) = u_b$$

Where  $u_a$  and  $u_b$  are constant values. The analytic solution is well-studied, but we will focus on solving it numerically. Assume we have a **uniformly** distributed grid  $\mathbf{X} = x_0, x_1, \dots, x_n$  with  $n+1$  grid points, where  $x_0 = a$  and  $x_n = b$ . Denote  $h = x_1 - x_0$  the interval size. Given an arbitrary grid position  $k = 1, 2, \dots, n-1$ , we can approximate  $u''_k$  by:

$$(0.4) \quad u''_k = \frac{u'_{k+1} - u'_k}{h}$$

Similarly, we can have:

$$(0.5) \quad u'_{k+1} = \frac{u_{k+1} - u_k}{h}$$

$$(0.6) \quad u'_k = \frac{u_k - u_{k-1}}{h}$$

The above equations are based on the formulas we have learned in Calculus classes, i.e. for a continuous and smooth function  $g(x)$  defined in  $(a, b)$ ,  $g'(x) = \lim_{h \rightarrow 0} \frac{g(x+h)-g(x)}{h}$  or  $g'(x) = \lim_{h \rightarrow 0} \frac{g(x)-g(x-h)}{h}$ . Plug Eq's (0.5) and (0.6) into (0.4), we have:

$$(0.7) \quad u_k'' = \frac{u_{k+1} - 2u_k + u_{k-1}}{h^2}$$

Combining with Poisson equation, we have:

$$(0.8) \quad -\frac{u_{k+1} - 2u_k + u_{k-1}}{h^2} = b_k$$

Where  $b_k = f(x_k)$ . The above numerical discretization method is called *finite difference method*.

Note that we are interested in the solutions on grid points  $\mathbf{X}_{1:n-1}$ , i.e.  $u_k$  for  $k = 1, 2, \dots, n-1$ . Eq (0.8) gives us  $n-1$  equations with exactly  $n-1$  unknowns, we can solve this problem by just solving a *linear system*. Denote  $\sigma = h^2$ , we can have:

$$(0.9) \quad -u_{k-1} + 2u_k - u_{k+1} = \sigma b_k$$

When  $k = 1$  and  $k = n-1$ , we have:

$$(0.10) \quad 2u_1 - u_2 = \sigma b_1 + u_0 = \sigma b_1 + u_a$$

$$(0.11) \quad -u_{n-2} + 2u_{n-1} = \sigma b_{n-1} + u_n = \sigma b_{n-1} + u_b$$

Where  $u_a$  and  $u_b$  are boundary conditions defined in Eq's (0.2) and (0.3). The system can be derived in the following way:

$$(0.12) \quad \begin{bmatrix} 2 & -1 & 0 & 0 & 0 & 0 & \dots & 0 \\ -1 & 2 & -1 & 0 & 0 & 0 & \dots & 0 \\ 0 & -1 & 2 & -1 & 0 & 0 & \dots & 0 \\ 0 & 0 & -1 & 2 & -1 & 0 & \dots & 0 \\ 0 & 0 & 0 & -1 & 2 & -1 & \dots & 0 \\ 0 & \dots & \dots & \dots & \dots & \dots & \dots & 0 \\ 0 & \dots & 0 & 0 & 0 & -1 & 2 & -1 \\ 0 & \dots & 0 & 0 & 0 & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ \dots \\ u_{n-2} \\ u_{n-1} \end{bmatrix} = \begin{bmatrix} \sigma b_1 + u_a \\ \sigma b_2 \\ \sigma b_3 \\ \sigma b_4 \\ \sigma b_5 \\ \dots \\ \sigma b_{n-2} \\ \sigma b_{n-1} + u_b \end{bmatrix}$$

We denote the linear system of (0.12) by  $\mathbf{A}\mathbf{u} = \mathbf{b}$ , where  $\mathbf{u}$  is the vector of unknowns (solution of Poisson equation on grid  $\mathbf{X}_{1:n-1}$ ) and  $\mathbf{b}$  is the right-hand side vector.

**An Example:**

Here, I provide a tiny example that can be solved by hand. Let's consider the model problem  $u(x) = x^2$  for  $x \in (0, 1)$ , so we have  $u_a = u(0) = 0$ ,  $u_b = u(1) = 1$  and  $f = -u'' = -2$ . Given a 5-point uniform grid, i.e.  $h = \frac{1}{4}$ , we have:

$$(0.13) \quad \mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

$$(0.14) \quad \mathbf{b} = \begin{bmatrix} h^2 b_1 + u_0 \\ h^2 b_2 \\ h^2 b_3 + u_4 \end{bmatrix} = \begin{bmatrix} -\frac{1}{8} \\ -\frac{1}{8} \\ \frac{7}{8} \end{bmatrix}$$

Solve the system, we have  $\mathbf{u} = [\frac{1}{16} \ \frac{1}{4} \ \frac{9}{16}]^T$ , which is the exact solution on  $\mathbf{X}_{1:3} = [\frac{1}{4} \ \frac{1}{2} \ \frac{3}{4}]$ .

### You tasks:

- (10%) In `solvers/BaseSolvers.h`, implement `assign_bcs`, `get_solution` (inline). Demonstrations of the `protected` variables:
  - `xl_`: left most grid point, i.e.  $a$ ;
  - `xr_`: right most grid point, i.e.  $b$ ;
  - `h_`: uniform grid size, i.e.  $h$ ;
  - `N_`: linear system size, i.e.  $n - 1$ ;
  - `lb_`: left boundary value, i.e.  $u_a$ ;
  - `rb_`: right boundary value, i.e.  $u_b$ ;
  - `u_`: solution vector  $\mathbf{u}$ ;
  - `A_`: matrix  $\mathbf{A}$ .
- (25%) In `solvers/LuSolver.cpp`:
  - implement the overridden function `assemble` for assembling the complete dense matrix, i.e. using `N_*N_` storage.
  - implement the overridden function `solve` to solve the problem given a vector `b_`.
    - \* Call `cblas_dcopy` and `cblas_dscal` to first copy and scale `b_` to `this->u_`.
    - \* Call `LAPACKE_dgesv` to solve the system and store the results to `this->u_`.
- (25%) In `solvers/PpSolver.cpp`:
  - implement the overridden function `assemble` for assembling the **packed** dense matrix of upper half, i.e. using `N_*(N_+1)/2` storage to only store the **upper** or **lower** half of `A_`.
  - implement the overridden function `solve` to solve the problem given a vector `b_`.
    - \* Call `cblas_dcopy` and `cblas_dscal` to first copy and scale `b_` to `this->u_`.
    - \* Call `LAPACKE_dppsv` to solve the system and store the results to `this->u_`.
- (25%) In `solvers/TriSolver.cpp`:
  - implement the overridden function `assemble` for assembling the **tridiagonal** matrix of upper half, i.e. using `2*N_-1` storage to only store the diagonal and off-diagonal of `A_`.
  - implement the overridden function `solve` to solve the problem given a vector `b_`.
    - \* Call `cblas_dcopy` and `cblas_dscal` to first copy and scale `b_` to `this->u_`.
    - \* Call `LAPACKE_dptsv` to solve the system and store the results to `this->u_`.
- (15%) Write a main program that:
  - solves the model problem  $u(x) = 2x^2$  in  $(0, 1)$ , with number of grid points 202, i.e. `N_` is 200.

- solves the model problem  $u(x) = \sin(\frac{\pi}{2}x)$  in  $(0, 1)$ , with number of grid points 202, i.e. `N_` is 200.
- for each of the model problems:
  - \* Call `cblas_dnorm2` to compute the 2 norm error.
  - \* Call `cblas_idamax` to compute the inf norm error.
- You should also provide a `README` file for your program.

**Hints:**

- Note that `A_` is given as a 1D vector!
- You can compute the error vectors by using `u_` minus the exact solution that can be obtained by explicitly evaluating the grid points in function  $u(x)$ . (For the vector subtraction, you can call `cblas_daxpy` or just write a simple loop.)
- **Don't forget to apply the boundary conditions when you implement `solve`!!**
- To get the raw pointer (`double *`) of the first position in `std::vector<double>`, you can call `std::vector<double>::data`, e.g. `A_.data()`, `u_.data()` and `b.data()`.
- MKL reference pages:
  - `cblas_dnorm2`: 50
  - `cblas_idamax`: 56
  - `cblas_dcopy`: 47
  - `LAPACKE_dgesv`: 568
  - `LAPACKE_dppsv`: 617
  - `LAPACKE_dptsv`: 627
- The general routines for solving a problem should be:
  - `ams562::XXSolver solver(0.0, 1.0, 202);`
  - `solver.assign_bc(lb, rb);` *//you should have lb, rb evaluated*
  - `solver.assemble();`
  - `solver.solve(b);` *//you should compute b before call this function*
  - `auto sol = solver.get_solution();`
  - *// Now doing the post-processing, i.e. analyze errors*
- For the Makefile:
  - You need to modify it by:
    - \* add libraries in `LIBS`, i.e. linking to LAPACK/BLAS
    - \* add your main program file in `MAIN`
  - Then `make`: build; `make test ARGS=...`: build main and run main executable, `ARGS` is optional; `make clean`: clean up object and executable files.