Summary

The overall structure of our program follows the general strategy of solving the stiffness equation by first defining the local-level stiffness matrix, transforming it into global level stiffness matrix, assembling it and then solving for the un-known variables in our equations. In this program, we have followed the generalized naming conventions that are mostly used for structural analysis purposes. We have prepared the functions with complete code modularity, such as the functions MD estiff, MD compute memberFEFs, MD estiff, MD etran, MD memberID etc. that are called into the main function ud 3d1el.m. This call is based on the decision variable, ends that controls whether moments are released or not at the ends of the member, depending on which we have defined the element level stiffness matrix and element level member forces. This part of the project is done to be considered for the extra-credit part. We have also demonstrated the member-force distribution in each member as a function of x along the length of the member in the post processing part, and have validated against the in-built MASTAN2 GUI output, for the shear-force and bending moment diagrams. The control flows between each of the functions has been shown in the flow chart. In our program, we have also taken into consideration the special case of mixedstructures that are frames, that can have any member with moments released at the ends. Besides, the conditions of support settlements can also be prescribed in the structure while defining in the MASTAN2 GUI, and we also validated the results for those verification problem cases as well. The final output of the program ud 3d1el.m have been extracted into the three variables DEFL, REACT, ELE FOR.