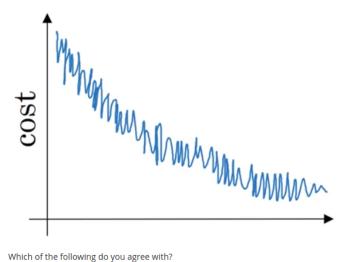
1.	Which notation would you use to denote the 3rd layer's activations when the input is the 7th example from the 8th minibatch?	1/1 point
	$\bigcirc \ a^{[3]\{7\}(8)}$	
	$\bigcirc \ a^{[8]\{7\}(3)}$	
	$\bigcirc a^{[3]\{8\}(7)}$	
	$\bigcirc \ a^{[8]\{3\}(7)}$	
	✓ Correct	
2.	Which of these statements about mini-batch gradient descent do you agree with?	1/1 point
	<ul> <li>One iteration of mini-batch gradient descent (computing on a single mini-batch) is faster than one iteration of batch gradient descent.</li> </ul>	
	O You should implement mini-batch gradient descent without an explicit for-loop over different mini-batches, so that the algorithm processes all mini-batches at the same time (vectorization).	
	<ul> <li>Training one epoch (one pass through the training set) using mini-batch gradient descent is faster than training one epoch using batch gradient descent.</li> </ul>	
	✓ Correct	
	✓ Correct	
3.	✓ Correct  Why is the best mini-batch size usually not 1 and not m, but instead something in-between?	1 / 1 point
3.		1/1 point
3.	Why is the best mini-batch size usually not 1 and not m, but instead something in-between?  If the mini-batch size is m, you end up with batch gradient descent, which has to process the whole	1/1 point
3.	Why is the best mini-batch size usually not 1 and not m, but instead something in-between?  If the mini-batch size is m, you end up with batch gradient descent, which has to process the whole training set before making progress.	1 / 1 point
3.	Why is the best mini-batch size usually not 1 and not m, but instead something in-between?  ✓ If the mini-batch size is m, you end up with batch gradient descent, which has to process the whole training set before making progress.  ✓ Correct  ☐ If the mini-batch size is m, you end up with stochastic gradient descent, which is usually slower than	1/1 point
3.	Why is the best mini-batch size usually not 1 and not m, but instead something in-between?  ✓ If the mini-batch size is m, you end up with batch gradient descent, which has to process the whole training set before making progress.  ✓ Correct  ☐ If the mini-batch size is m, you end up with stochastic gradient descent, which is usually slower than mini-batch gradient descent.  ☐ If the mini-batch size is 1, you end up having to process the entire training set before making any	1/1 point
3.	Why is the best mini-batch size usually not 1 and not m, but instead something in-between?  ✓ If the mini-batch size is m, you end up with batch gradient descent, which has to process the whole training set before making progress.  ✓ Correct  ☐ If the mini-batch size is m, you end up with stochastic gradient descent, which is usually slower than mini-batch gradient descent.  ☐ If the mini-batch size is 1, you end up having to process the entire training set before making any progress.	1/1 point



Which of the following do you agree with?

- Whether you're using batch gradient descent or mini-batch gradient descent, something is wrong,
- Whether you're using batch gradient descent or mini-batch gradient descent, this looks acceptable.
- If you're using mini-batch gradient descent, this looks acceptable. But if you're using batch gradient descent, something is wrong.
- If you're using mini-batch gradient descent, something is wrong. But if you're using batch gradient descent, this looks acceptable.



1/1 point

Jan 1st: 
$$heta_1=10^oC$$

Jan 2nd: 
$$heta_2 10^o C$$

(We used Fahrenheit in lecture, so will use Celsius here in honor of the metric world.)

Say you use an exponentially weighted average with  $\beta=0.5$  to track the temperature:  $v_0=0$ ,  $v_t=\beta v_{t-1}+(1-\beta)\theta_t$ . If  $v_2$  is the value computed after day 2 without bias correction, and  $v_2^{corrected}$  is the value you compute with bias correction. What are these values? (You might be able to do this without a calculator, but you don't actually need one. Remember what is bias correction doing.)

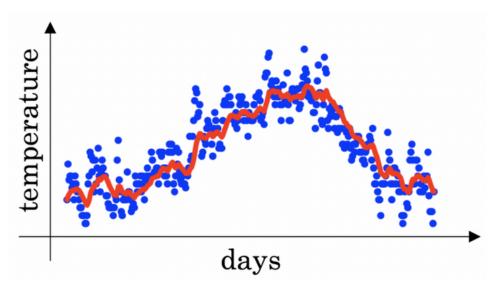
- $\bigcirc$   $v_2=7.5$  ,  $v_2^{corrected}=10$
- $\bigcirc$   $v_2=10$ ,  $v_2^{corrected}=7.5$
- $\bigcirc$   $v_2=10$ ,  $v_2^{corrected}=10$
- $\bigcirc \ v_2 = 7.5, v_2^{corrected} = 7.5$



- 6. Which of these is NOT a good learning rate decay scheme? Here, t is the epoch number.
  - $\alpha = 0.95^t \alpha_0$
  - $\bigcirc$   $\alpha = e^t \alpha_0$
  - $\bigcirc \ \alpha = \frac{1}{1+2*t}\alpha_0$
  - $\bigcirc \ \alpha = \frac{1}{\sqrt{t}} \alpha_0$

✓ Correct

7. You use an exponentially weighted average on the London temperature dataset. You use the following to track the temperature:  $v_t = \beta v_{t-1} + (1-\beta)\theta_t$ . The red line below was computed using  $\beta = 0.9$ . What would happen to your red curve as you vary  $\beta$ ? (Check the two that apply)



- Increasing  $\beta$  will shift the red line slightly to the right.

## ✓ Correct

True, remember that the red line corresponds to  $\beta=0.9$ . In lecture we had a green line \$\$\beta=0.98) that is slightly shifted to the right.

igspace Decreasing eta will create more oscillation within the red line.

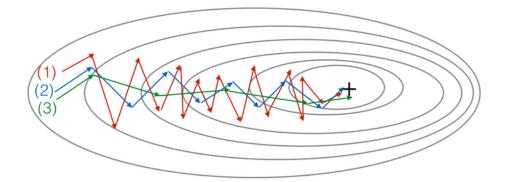
## ✓ Correct

True, remember that the red line corresponds to  $\beta=0.9$ . In lecture we had a yellow line  $\$\$  that had a lot of oscillations.

Increasing  $\beta$  will create more oscillations within the red line.

## 8. Consider this figure:

1 / 1 point



These plots were generated with gradient descent; with gradient descent with momentum ( $\beta$  = 0.5) and gradient descent with momentum ( $\beta$  = 0.9). Which curve corresponds to which algorithm?

- (1) is gradient descent with momentum (small  $\beta$ ), (2) is gradient descent with momentum (small  $\beta$ ), (3) is gradient descent
- (1) is gradient descent. (2) is gradient descent with momentum (large  $\beta$ ) . (3) is gradient descent with momentum (small  $\beta$ )
- (1) is gradient descent. (2) is gradient descent with momentum (small  $\beta$ ). (3) is gradient descent with momentum (large  $\beta$ )
- (1) is gradient descent with momentum (small  $\beta$ ). (2) is gradient descent. (3) is gradient descent with momentum (large  $\beta$ )



9.	Suppose batch gradient descent in a deep network is taking excessively long to find a value of the parameters that achieves a small value for the cost function $\mathcal{J}(W^{[1]},b^{[1]},\ldots,W^{[L]},b^{[L]})$ . Which of the following techniques could help find parameter values that attain a small value for $\mathcal{J}$ ? (Check all that apply)	1/1 point
	$\checkmark$ Try tuning the learning rate $\alpha$	
	✓ Correct	
	Try initializing all the weights to zero	
	✓ Try using Adam	
	✓ Correct	
	✓ Try mini-batch gradient descent	
	✓ Correct	
	✓ Try better random initialization for the weights	
	✓ Correct	
10.	Which of the following statements about Adam is False?	1 / 1 point
	igcap The learning rate hyperparameter $lpha$ in Adam usually needs to be tuned.	
	Adam combines the advantages of RMSProp and momentum	
	We usually use "default" values for the hyperparameters $\beta_1,\beta_2$ and $\varepsilon$ in Adam ( $\beta_1=0.9$ , $\beta_2=0.999$ , $\varepsilon=10^{-8}$ )	
	Adam should be used with batch gradient computations, not with mini-batches.	
	✓ Correct	