Visual Grounding

金江林

Outline

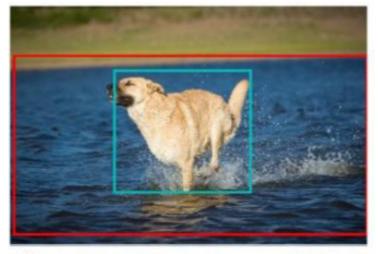
- Visual Grounding Background
 - Task
 - Dataset
- Fully Supervised
- Weakly Supervised
- Semi-Supervised
 - Consistency Regularization
 - Pseudo Label
 - Match
- Further Work

Task

 Phrase Grounding: 对于给定的 sentence, 要定位其中提到的全 部物体 (phrase)

Referring expression grounding:
 每个语言描述 (expression) 只指示
 一个物体

Phrases Grounding



(h) A white dog is running over the water.

Refer expression Grounding



books about bears

Dataset

- Phrases Grounding
 - Flickr30k Entities
 - ReferItGame(RefClef)
- Refer expression Grounding
 - RefCOCO
 - RefCOCO+
 - RefCOCOg



A man with pierced ears is wearing glasses and an orange hat, A man with glasses is wearing a beer can crotched hat,

A man with gauges and glasses is wearing a Blitz hat.

A man in an orange hat starring at something.

A mun wears an orange hat and glasses,

During a gay pride parade in an Asian city, some people hold up rainbow flags to show their support.

A group of youths much down a street waving flags showing a color spectrum.

Oriental people with rainbow flags walking down a city street. A group of people walk down a street waving rainbow flags. People are outside waving flags.



A couple in their wedding attire stand behind a table with a wedding cake and flowers.

A bride and groom are standing in front of their wedding cake at their reception.

A bride and groom smile as they view their wedding cake at a reception.

A couple stands behind their wedding cake.

Mun and woman cutting wedding cake.

RefClef



right rocks rocks along the right side stone right side of stairs

RefCOCO



woman on right in white shirt woman on right right woman

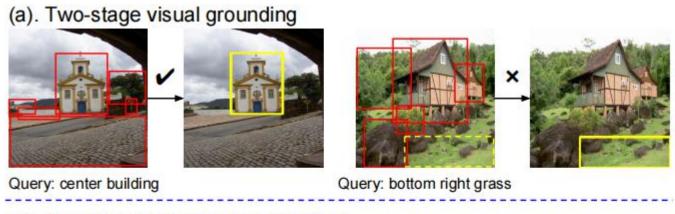
RefCOCO+



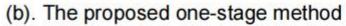
guy in yellow dirbbling ball yellow shirt and black shorts yellow shirt in focus

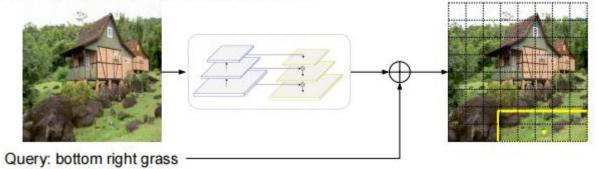
Methods

□one stage or two stage

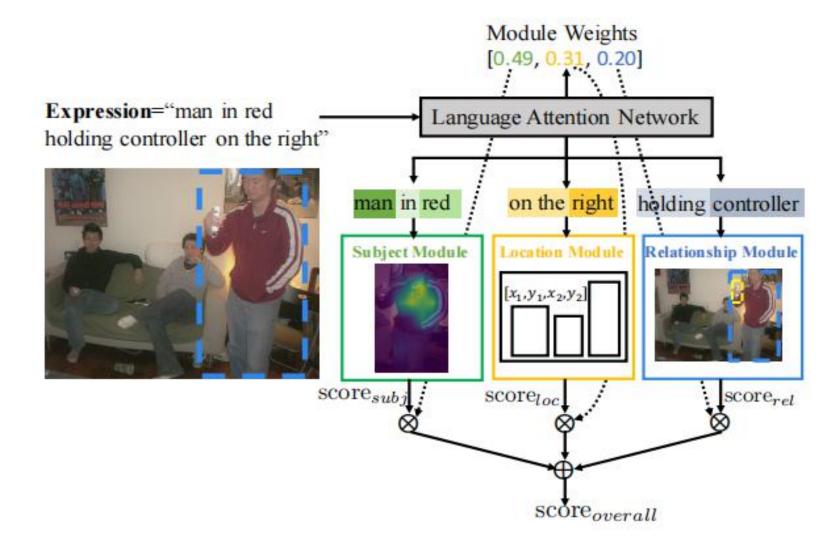


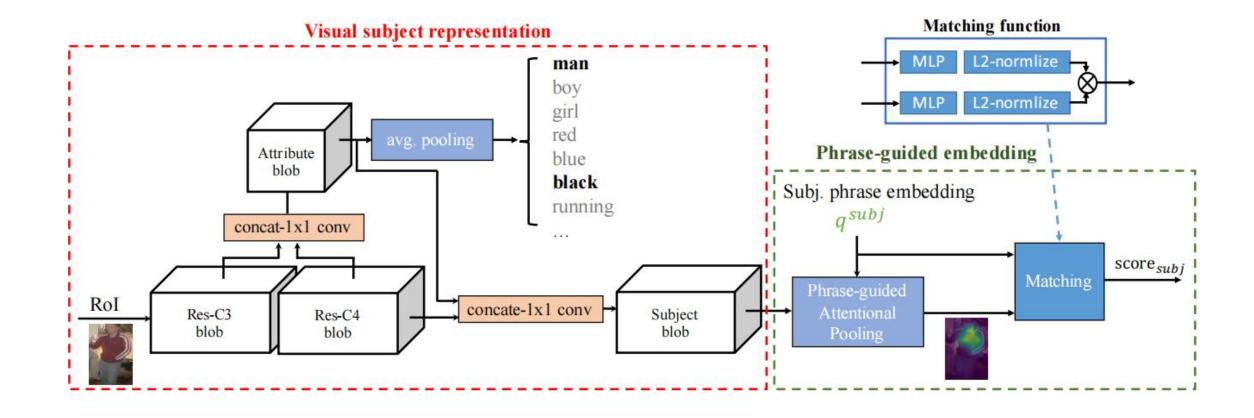
✓ 训练效率高

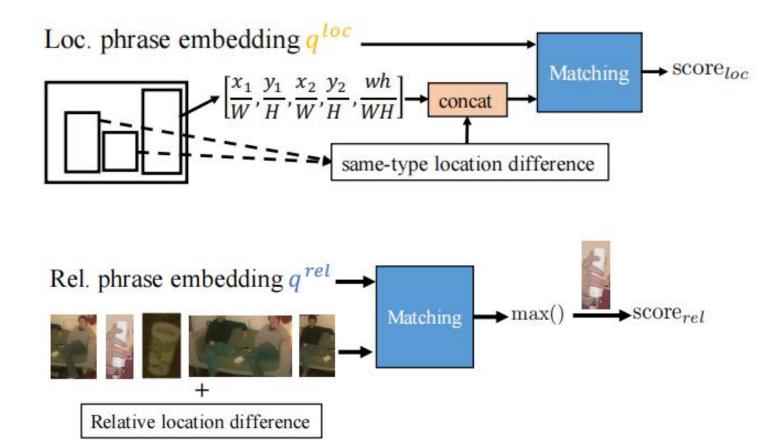




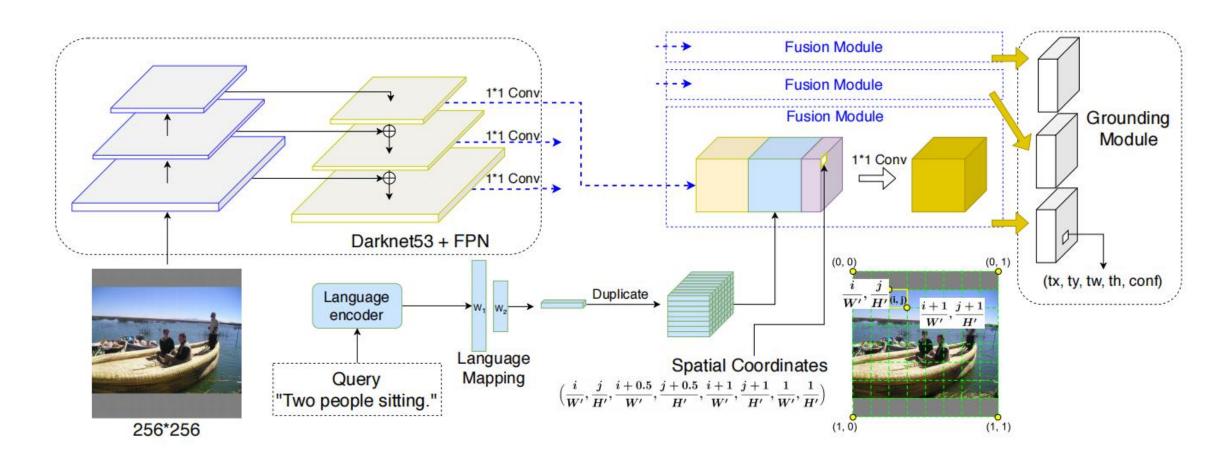
- ✓ 推理更快
- ✓ 结果更准确







CVPR 2018, MAttNet: Modular Attention Network for Referring Expression Comprehension



Results

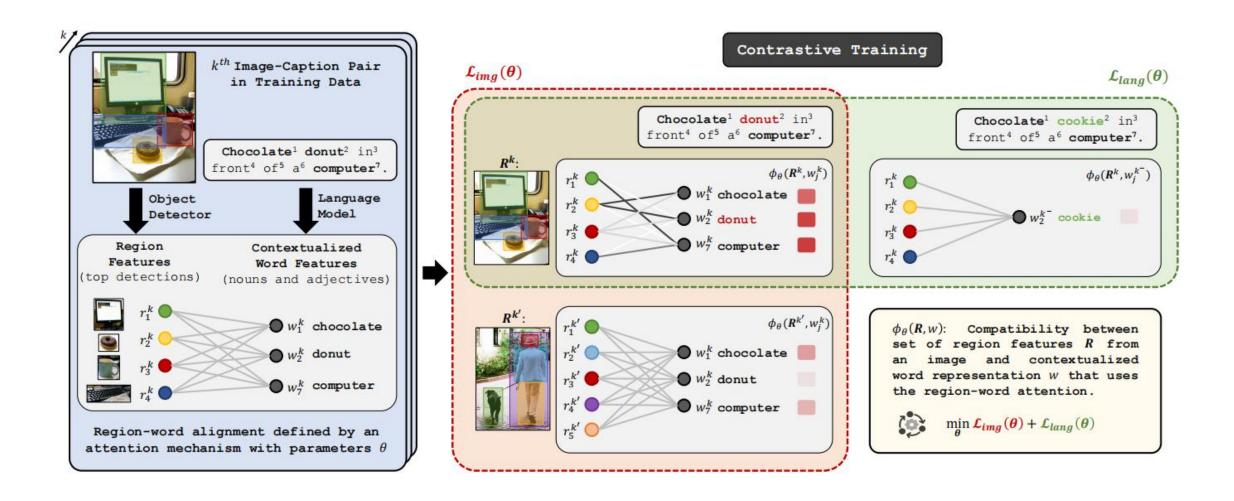
Phrase localization results on the test set of Flickr30K Entities

Similarity Net-Resnet [42]	Edgebox N=200	Res101-COCO	Word2vec, FV	60.89	184
CITE-Resnet [29]	Edgebox N=200	Res101-COCO	Word2vec, FV	61.33	196
Similarity Net-Darknet [42]	Edgebox N=200	Darknet53-COCO	Word2vec, FV	41.04	305
Ours-FV	None	Darknet53-COCO	Word2vec, FV	68.38	16
Ours-LSTM	None	Darknet53-COCO	LSTM	67.62	21
Ours-Bert-no Spatial	None	Darknet53-COCO	Bert	67.08	38
Ours-Bert	None	Darknet53-COCO	Bert	68.69	38

Referring expression comprehension results on the test set of ReferltGame

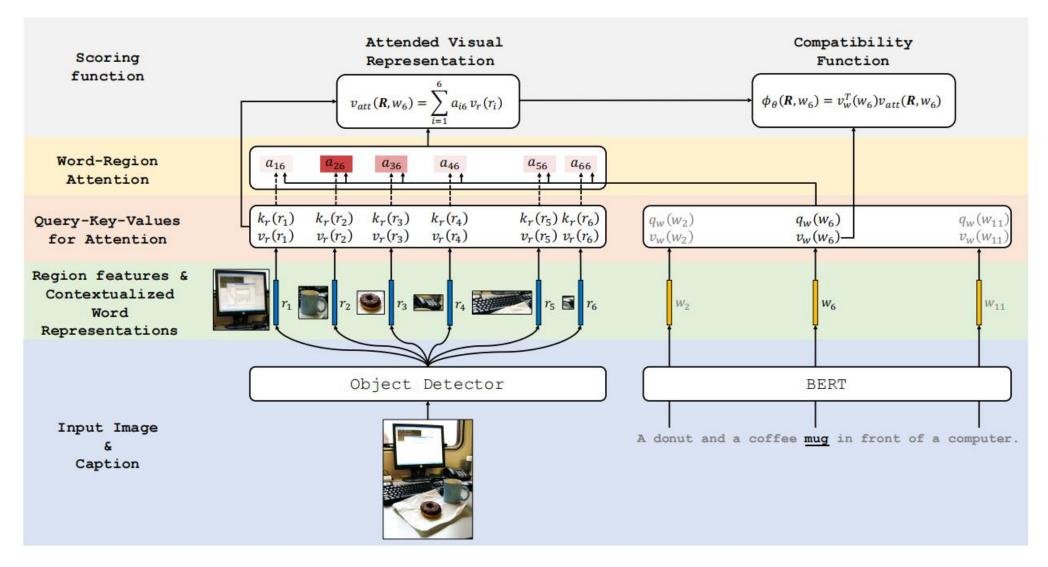
Similarity Net-Resnet [42]	Edgebox N=200	Res101-COCO	Word2vec, FV	34.54	184
CITE-Resnet [29]	Edgebox N=200	Res101-COCO	Word2vec, FV	35.07	196
Similarity Net-Darknet [42]	Edgebox N=200	Darknet53-COCO	Word2vec, FV	22.37	305
Ours-FV	None	Darknet53-COCO	Word2vec, FV	59.18	16
Ours-LSTM	None	Darknet53-COCO	LSTM	58.76	21
Ours-Bert-no Spatial	None	Darknet53-COCO	Bert	58.16	38
Ours-Bert	None	Darknet53-COCO	Bert	59.30	38

Weakly Supervised



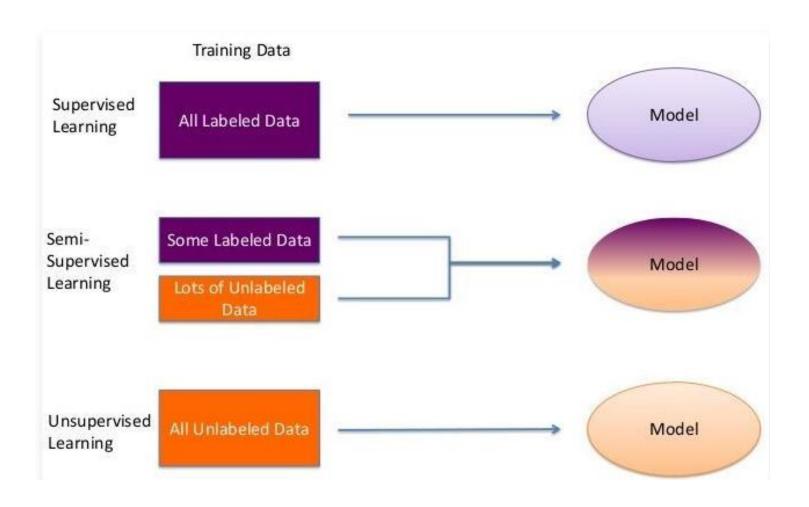
ECCV 2020, Contrastive Learning for Weakly Supervised Phrase Grounding

Weakly Supervised



ECCV 2020, Contrastive Learning for Weakly Supervised Phrase Grounding

Semi-Supervised



- > 完整的大量注释难以获得
- > 充分利用数据信息
- ▶ 提高模型的性能
- 有标签数据和无标签数据具有相同的分布
- > 模型性能下降

Semi-Supervised

● Consistency Regularization:给定一个未标记的数据点及其扰动的形式 ,目标是最小化两个输出之间的距离。对于无标签图像,添加噪声之后模型预测也应该保持不变

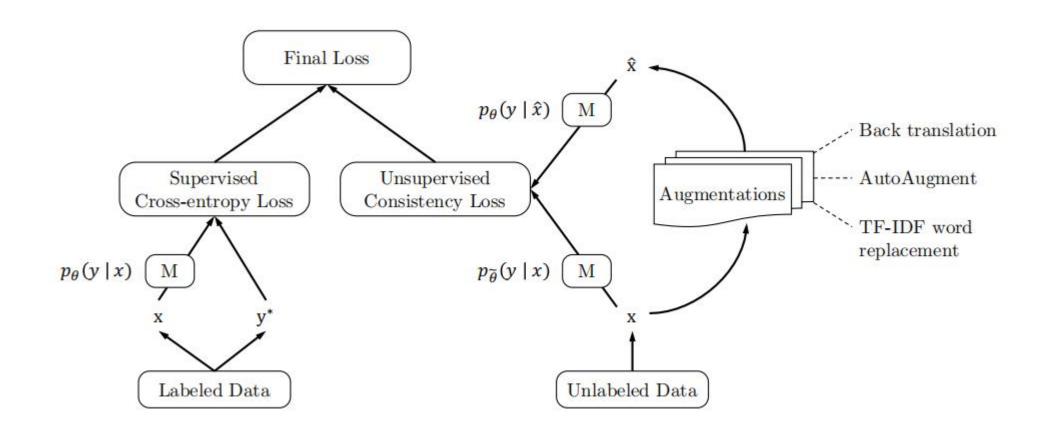
$$d(f_{\theta}(x), f(\hat{x})),$$

● Pseudo Label:先使用模型生成伪标签,然后与有标签的数据一起训练,提供额外的信息。

$$L = \frac{1}{n} \sum_{m=1}^{n} \sum_{i=1}^{C} L(y_i^m, f_i^m) + \alpha(t) \frac{1}{n'} \sum_{m=1}^{n'} \sum_{i=1}^{C} L(y_i'^m, f_i'^m),$$

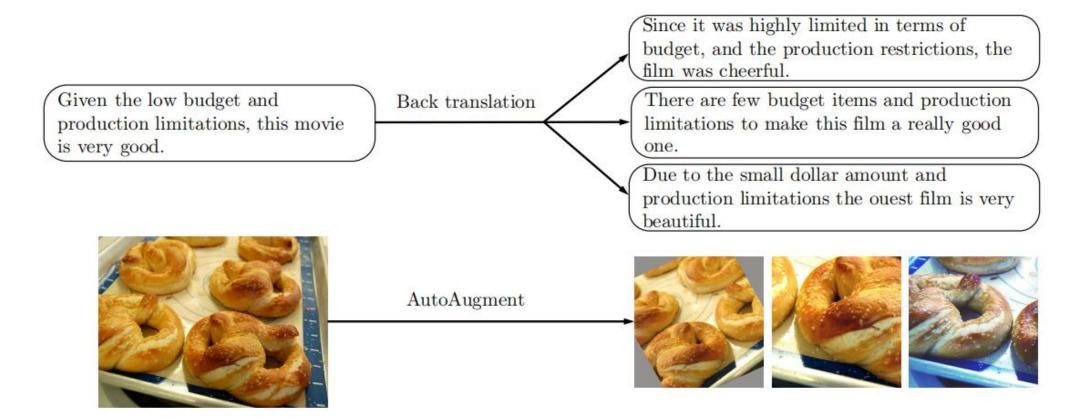
● Match系列:将几种半监督方法进行混合

Semi-Supervised-Consistency Regularization



Data Augmentation

- 图像分类:AutoAugment,在所有的图像处理转换方式中进行搜索,以便找到一个最优的增强策略
- 文本分类:Back translation,把一个样本 (语言A) 转换成另一个语言B再转换回来



NeurIPS 2020, Unsupervised Data Augmentation for Consistency Training

Results

	Fully supervised baseline				
Datasets (# Sup examp	IMDb (25k)	Yelp-2 (560k)	Yelp-5 (650k)	Amazon-2 (3.6m)	
Pre-BERT SOTA BERT _{LARGE}		4.32 4.51	2.16 1.89	29.98 29.32	3.32 2.63
Semi-supervised se					ing
Initialization	UDA	IMDb (20)	Yelp-2 (20)	Yelp-5 (2.5k)	Amazon-2 (20)
Random	X	43.27 25.23	40.25 8.33	50.80 41.35	45.39 16.16
BERTBASE	×	27.56 5.45	13.60 2.61	41.00 33.80	26.75 3.96
BERT _{LARGE}	X	11.72 4.78	10.55 2.50	38.90 33.54	15.54 3.93
BERT _{FINETUNE} .	X	6.50 4.20	2.94 2.05	32.39 32.08	12.17 3.50

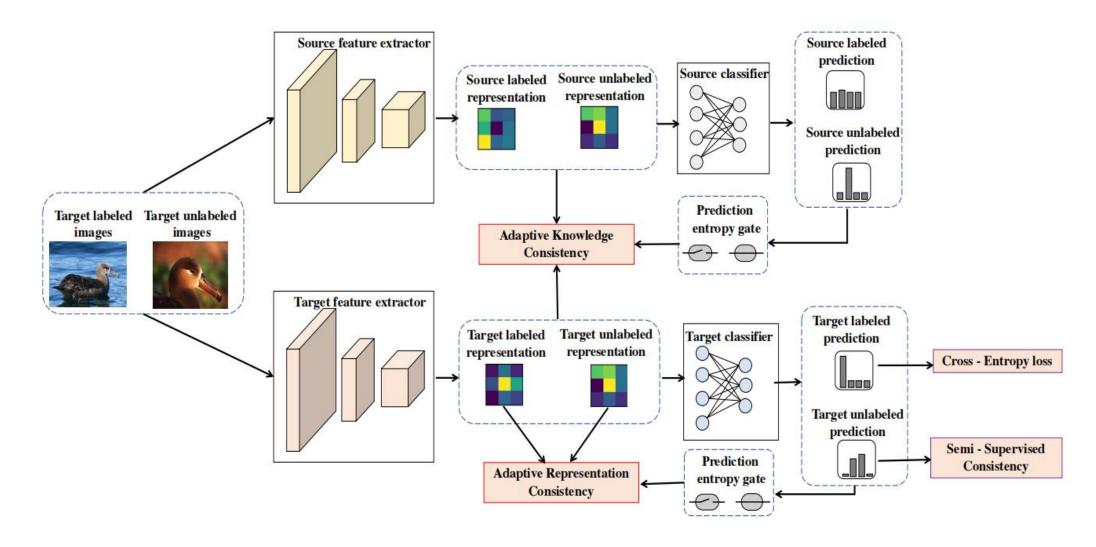
Methods	top-1 acc	top-5 acc
Supervised	55.09	77.26
Pseudo-Label [36] [‡]	_	82.41
VAT [44] [‡]	-	82.78
VAT + EntMin [44] [‡]	-	83.39
UDA	68.66	88.52

Accuracy on ImageNet with 10% of the labeled set

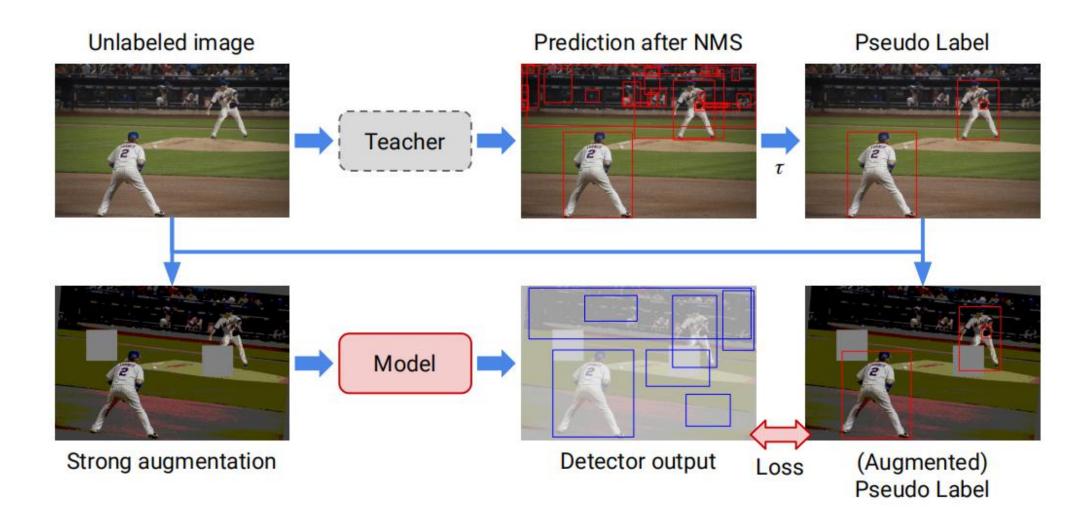
Methods	top-1 / top-5 accuracy
Supervised	77.28 / 93.73
AutoAugment	78.28 / 94.36
UDA	79.04 / 94.45

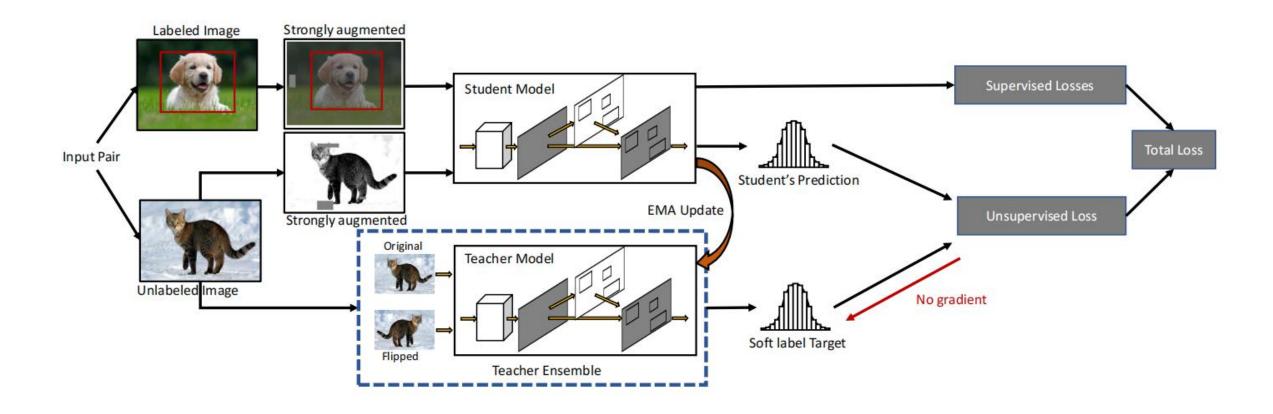
Accuracy on the full ImageNet

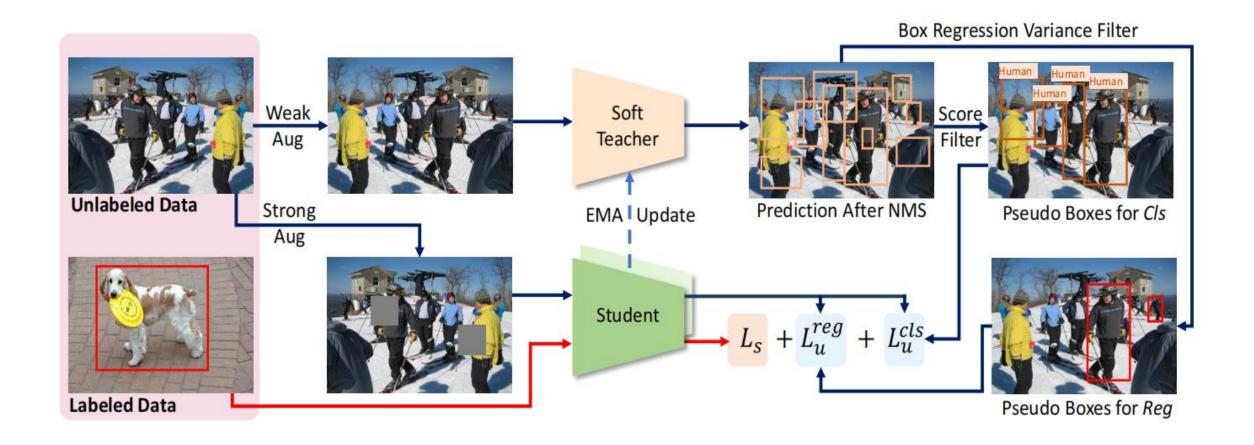
Consistency Regularization

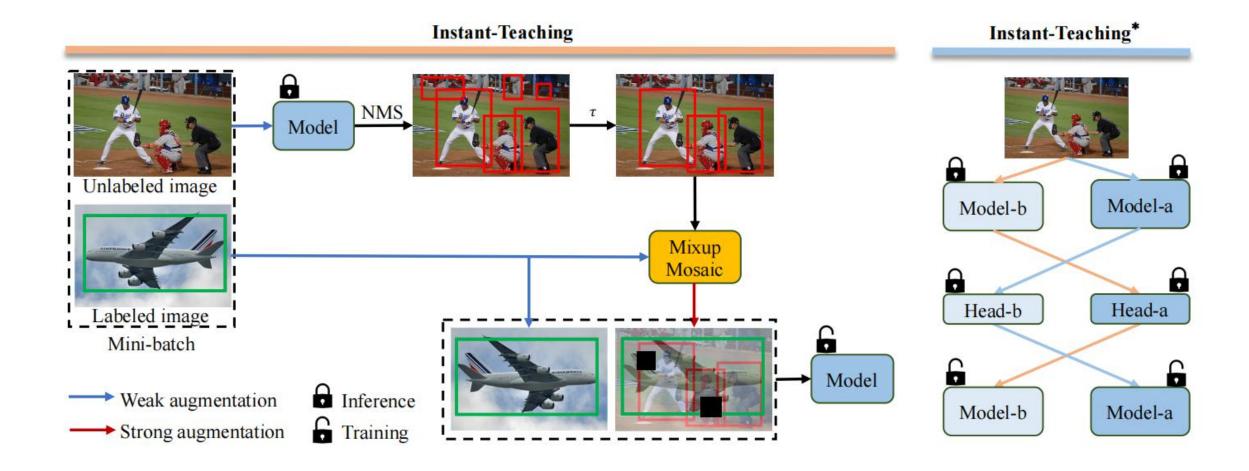


Semi-Supervised-Pseudo Label









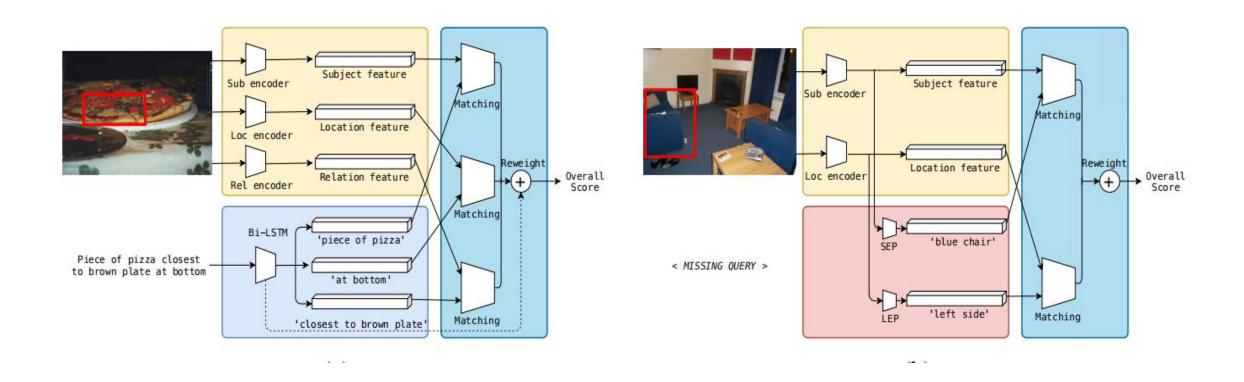
CVPR 2021, Instant-Teaching: An End-to-End Semi-Supervised Object Detection Framework

Results

Percentage labeled	1%	2%	5%	10%
Supervised model	9.05±0.16	12.70±0.15	18.47±0.22	23.86±0.81
CSD^{\ddagger}	11.12 ± 0.15 (+2.07)	$14.15\pm0.13 (+1.45)$	$18.79 \pm 0.13 (+0.32)$	$22.76\pm0.09(-1.10)$
STAC [40]	$13.97 \pm 0.35 (+4.92)$	$18.25\pm0.25\ (+5.55)$	$24.38\pm0.12\ (+5.91)$	$28.64 \pm 0.21 \ (+4.78)$
Humble teacher (our	s) $16.96\pm0.38 (+7.91)$	21.72±0.24 (+9.02)	$27.70\pm0.15\ (+9.23)$	$31.61\pm0.28\ (+7.74)$
	3 1 25	S 41	25 d	7/ al
Instant-Teaching (ours)	R50-FPN 16.00±0.20 (-	+6.95) 20.70±0.30 (+8.	.00) 25.50±0.05 (+7.03) 29.45±0.15 (+5.59)
Instant-Teaching* (ours)	R50-FPN 18.05±0.15 (-	+9.00) 22.45±0.15 (+9.	(.75) 26.75±0.05 (+8.28) 30.40±0.05 (+6.54)

Method	1%	5%	10%
Supervised baseline (Ours)	10.0 ± 0.26	20.92 ± 0.15	26.94 ± 0.111
Supervised baseline (STAC) [27]	9.83 ± 0.23	21.18 ± 0.20	26.18 ± 0.12
STAC [27]	13.97 ± 0.35	24.38 ± 0.12	28.64 ± 0.21
Ours	20.46 ±0.39	30.74 ±0.08	34.04 ± 0.14
			No.

Soft Teacher

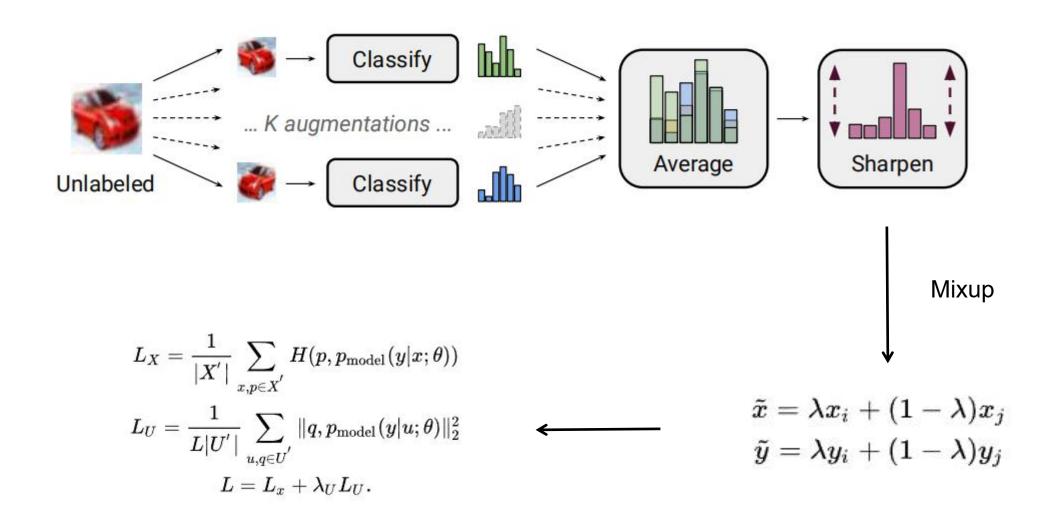


	Type /	Re	efCOC	O	Re	fCOCC)+	RefCC	OCOg
	Labeled %	Val	testA	testB	Val	testA	testB	Val	testA
Accu-Att [7]	100%	81.27	81.17	80.01	65.56	68.76	60.63	-	-
PLAN [39]	100%	81.67	80.81	81.32	64.18	66.31	61.46	-	V - 1
Multi-hop [27]	100%	84.90	87.40	83.10	73.80	78.70	65.80	-	V - 1
NegBag [21]	100%	76.90	75.60	78.00	-	() = (-1	-	68.40
S-L-R [37]	100%	79.56	78.95	80.22	62.26	64.60	59.62	71.65	71.92
MAttNet [35]	100%	85.65	85.26	84.57	71.01	75.13	66.17	78.10	78.12
LSEP	100%	85.71	85.69	84.26	71.99	75.36	66.25	78.96	78.29
MAttNet	annotation-75%	81.89	83.52	79.48	61.7	2 64.8	7 56.53	72.3	30 72.02
LSEP	annotation-75%	83.11	84.46	79.58	68.0	1 70.4	7 61.49	75.6	74.89

Dataset	Split	MAttNet (FS)	MAttNet	LSEP
RefCOCO	val	75.78	73.17	74.25
	testA	82.01	79.54	80.47
	testB	70.03	67.83	68.59

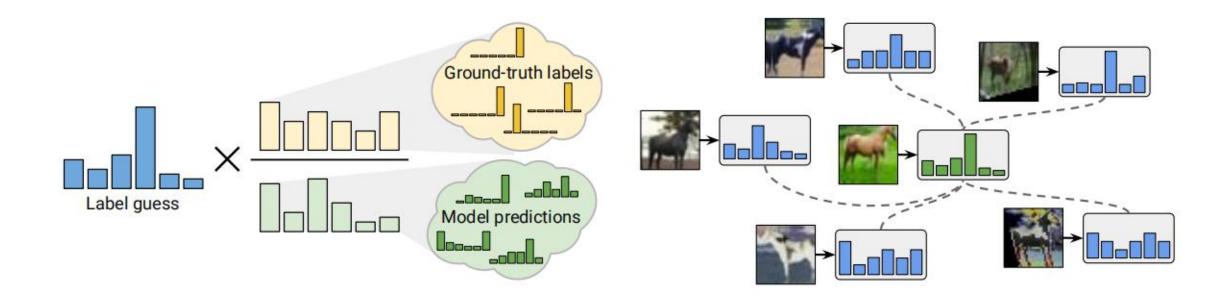
WACV 21, Utilizing Every Image Object for Semi-supervised Phrase Grounding

Semi-Supervised-Match



NeurIPS 2019, MixMatch: A Holistic Approach to Semi-Supervised Learning

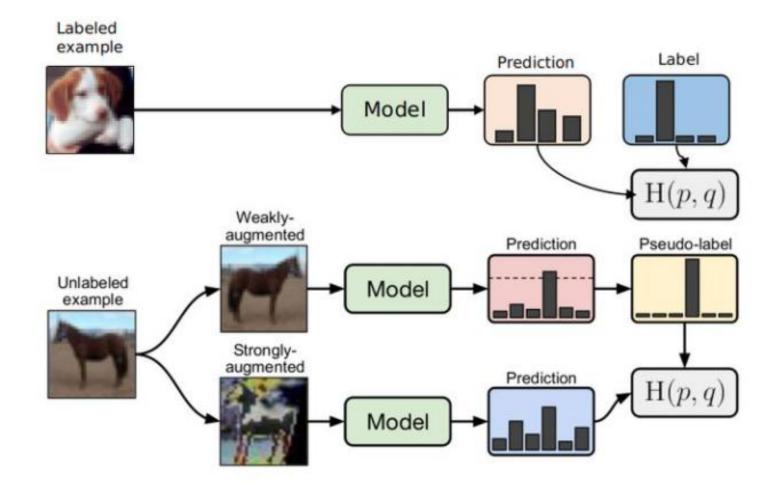
Match



$$ilde{q} = ext{Normalize} \left(q imes rac{p(y)}{ ilde{p}(y)}
ight).$$

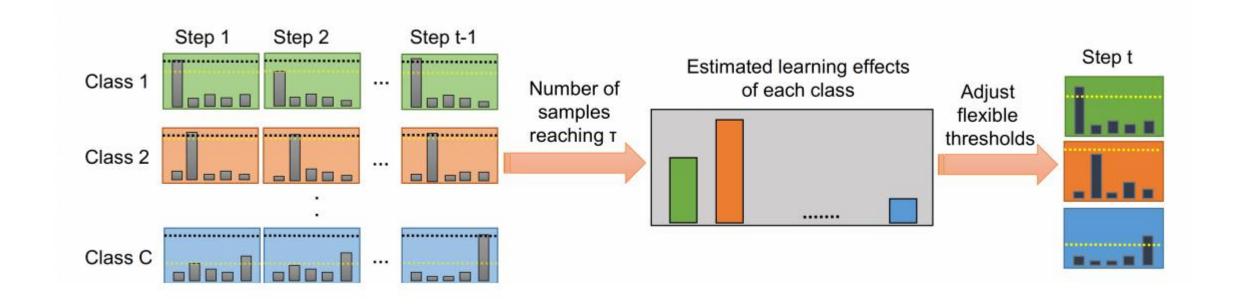
- q: 对当前无标签数据的标签猜测
- $\tilde{p}(y)$:平均版本的无标签猜测
- p(y):有标签数据的标签分布

Match



NeurIPS 2020, FixMatch: Simplifying Semi-Supervised Learning with Consistency and Confidence

Match



Results

		CIFAR-10			CIFAR-100	
Method	40 labels	250 labels	4000 labels	400 labels	2500 labels	10000 labels
П-Model		54.26±3.97	14.01±0.38	-	57.25±0.48	37.88±0.11
Pseudo-Labeling	I .	49.78±0.43	16.09 ± 0.28	(-	57.38±0.46	36.21±0.19
Mean Teacher	-	32.32±2.30	9.19 ± 0.19	Y7 <u>2</u> 1	53.91±0.57	35.83 ± 0.24
MixMatch	47.54±11.50	11.05 ± 0.86	6.42±0.10	67.61±1.32	39.94±0.37	28.31 ± 0.33
UDA	29.05±5.93	8.82±1.08	4.88 ± 0.18	59.28±0.88	33.13 ± 0.22	24.50±0.25
ReMixMatch	19.10±9.64	5.44±0.05	4.72 ± 0.13	44.28±2.06	27.43±0.31	23.03±0.56
FixMatch (RA)	13.81±3.37	5.07±0.65	4.26±0.05	48.85±1.75	28.29±0.11	22.60±0.12
FixMatch (CTA)	11.39±3.35	5.07±0.33	4.31±0.15	49.95±3.01	28.64±0.24	23.18±0.11
FlexMatch	4.99±0.16	4.80±0.06	3.95±0.03	32.44±1.99	23.85±0.23	19.92±0.06
Fully-Supervised		4.45±0.12			19.07± 0.18	3

Further Work

- Semi-Supervised visual grounding
 - methods
 - one stage
 - two stage
 - strategy
 - teacher
 - data augmentation
- baseline model
 - mattnet
 - lesp

Further Work

