Lecture 2:

The classic and the predictive paradigms Decision Theory

Big Data and Machine Learning for Applied Economics Econ 4676

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Agenda

- 1 Review
- 2 Shifting Paradigms
- 3 How to Evaluate Estimators?
- 4 Statistical Decision Theory
- 5 Linear Regression
- 6 Recap

Review

Motivation

- ▶ We discussed the examples of Google Flu and Facebook face detection
 - ► Take away, the success was driven by an empiric approach
 - ightharpoonup Given data estimate a function f(x) that predicts y from x
- ► This is basically what we do as economists everyday so:
 - ► Are these algorithms merely applying standard techniques to novel and large datasets?
 - ▶ If there are fundamentally new empirical tools, how do they fit with what we know?
 - ► As empirical economists, how can we use them?

Big vs Small, Classic vs Predictive

- Classical Stats (small data?)
 - ► Get the most of few data (Gosset)
 - ▶ Lots of structure, e.g. $X_1, X_2, ..., X_n \sim t_v$
 - Carefully curated → approximates random sampling (expensive, slow) but very good and reliable
- ► Big Data (the 4 V's)
 - ▶ Data Volume
 - Data Variety
 - Data Velocity
 - ► Data Value

The Classic Paradigm

$$Y = f(X) + u \tag{1}$$

- ► Interest lies on inference
- ightharpoonup "Correct" f() to understand how Y is affected by X
- Model: Theory, experiment
- Hypothesis testing (std. err., tests)

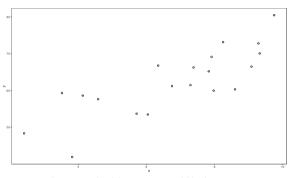
The Predictive Paradigm

$$Y = f(X) + u \tag{2}$$

- ► Interest on predicting *Y*
- ightharpoonup "Correct" f() to be able to predict (no inference!)
- ► Model?

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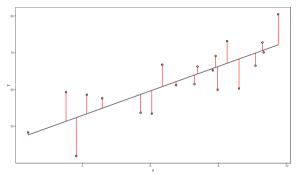
How to choose f(.)



Source: simulated data, see figures folder for scripts

How to choose f(.)

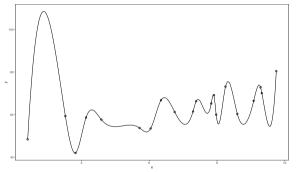
▶ Linear $f(X) = X\beta$



Source: simulated data, see figures folder for scripts

How to choose f(.)

▶ Spline f(X) = g(X), where g is a spline



Source: simulated data, see figures folder for scripts

- We need a bit of theory to give us a framework for choosing f
- ightharpoonup A decision theory approach involves an **action space** $\mathcal A$
- ▶ The **action space** A specify the possible "actions we might take"
- Some examples

Table 1: Action Spaces

Inference	Action Space
Estimation θ , $g(\theta)$	$\mathcal{A}=\Theta$
Prediction	$\mathcal{A} = space \ of \ X_{n+1}$
Model Selection	$\mathcal{A} = \{Model I, Model II,\}$
Hyp. Testing	$\mathcal{A} = \{Reject Accept H_0\}$

- ▶ After the data X = x is observed, where $X \sim f(X|\theta)$, $\theta \in \Theta$
- ► A decision is made
- ▶ The set of allowable decisions is the action space (A)
- ▶ The loss function in an estimation problem reflects the fact that if an action a is close to θ ,
 - then the decision *a* is reasonable and little loss is incurred.
 - ▶ if it is far then a large loss is incurred

$$L: \mathcal{A} \to [0, \infty] \tag{3}$$



Loss Function

- \blacktriangleright If θ is real valued, two of the most common loss functions are
 - ► Squared Error Loss:

$$L(a,\theta) = (a-\theta)^2 \tag{4}$$

► Absolute Error Loss:

$$L(a,\theta) = |a - \theta| \tag{5}$$

- ▶ These two are symmetric functions. However, there's no restriction. For example in hypothesis testing a "0-1" Loss is common.
- Loss is minimum if the action is correct



Risk Function

In a decision theoretic analysis, the quality of an estimator is quantified by its risk function, that is, for an estimator $\delta(x)$ of θ , the risk function is

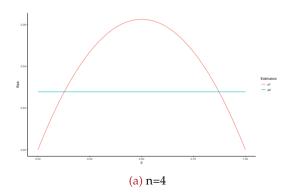
$$R(\theta, \delta) = E_{\theta}(L(\theta, \delta(X))) \tag{6}$$

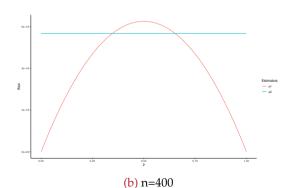
at a given θ , the risk function is the average loss that will be incurred if the estimator $\delta(X)$ is used

- Since θ is unknown we would like to use an estimator that has a small value of $R(\theta, \delta)$ for all values θ
- Loss is minimum if the action is correct
- ▶ If we need to compare two estimators (δ_1 and δ_2) then we will compare their risk functions
- ▶ If $R(\delta_1, \theta) < R(\delta_2, \theta)$ for all $\theta \in \Theta$, then δ_1 is preferred because it performs better for all θ

Example: Binomial Risk Function

- ▶ Let $X_1, X_2, ... X_n \sim Bernoulli(p)$
- Consider 2 estimators for p: $\hat{p}^1 = \frac{1}{n} \sum X_i$ and $\hat{p}^2 = \frac{\sum X_i + \sqrt{n/4}}{n + \sqrt{n}}$
- Their risks are: $R(\hat{p}^1, p) = \frac{p(1-p)}{n}$ and $R(\hat{p}^2, p) = \frac{n}{4(n+\sqrt{n})^2}$





How to choose f?

- ▶ In a prediction problem we want to predict Y from f(X) in such a way that the loss is minimum
- ▶ Assume also that $X \in \mathbb{R}^p$ and $Y \in \mathbb{R}$ with joint distribution Pr(X, Y)

$$R(Y, f(X)) = E[(Y - f(X))^{2}]$$
(7)

$$= \int (y - f(x))^2 Pr(dx, dy) \tag{8}$$

conditioning on X we have that

$$R(Y, f(X)|X) = E_X E_{Y|X}[(Y - f(X))^2|X]$$
(9)

this risk is also know as the **mean squared (prediction) error** MSE(f)

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It suffices to minimize the MSE(f) point wise so

$$f(x) = \operatorname{argmin}_{m} E_{Y|X}[(Y - m)^{2}|X = x)$$
(10)

Y a random variable and m a constant (predictor)

$$min_m E(Y-m)^2 = \int (y-m)^2 f(y) dy$$
 (11)

Result: The best prediction of Y at any point X = x is the conditional mean, when best is measured using a square error loss

Proof

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$$\int -2(y-m)f(y)dy = 0 \tag{12}$$

Dividing by -2 and reorganizing

$$m\int(y)dy = \int yf(y)dy \tag{13}$$

$$m\int(y)dy = \int yf(y)dy \tag{14}$$

$$m = E(Y|X=x) \tag{15}$$

The best prediction of Y at any point X = x is the conditional expectation function (CEF), when best is measured using a square error loss

- What shape does the CEF take?
- Linear
 - \triangleright (*y*, *X*) are jointly normal
 - ▶ When models are saturated.

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Linear Regression

Note the following from the *Regression-CEF Theorem* The function $X'\beta$ provides the minimum risk linear approximation to E(Y|X), that is

$$\beta = \underset{b}{\operatorname{argmin}} E\left\{ (E(Y|X) - X'b)^2 \right\} \tag{16}$$

► Proof

$$(Y - X'b)^{2} = (Y - E(Y|X)) + (E(Y|X) - X'b)^{2}$$

$$= (Y - E(Y|X))^{2} + (E(Y|X) - X'b)^{2} + 2(Y - E(Y|X))(E(Y|X) - X'b)$$
(18)

► The CEF approximation problem then has the same solution as the population least square problems

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Linear Regression

- ▶ Regression provides the best linear predictor for the dependent variable in the same way that the CEF is the best unrestricted predictor of the dependent variable.
- ▶ The fact that Regression approximates the CEF is useful because it helps describe the essential features of statistical relationships, without necessarily trying to pin them down exactly.
- ► Linear regression is the "work horse" of econometrics and (supervised) machine learning.
- Very powerful in many contexts.
- ▶ Big 'payday' to study this model in detail.

Linear Regression Model

 $f(X) = X\beta$, estimating f(.) boils down to estimating β

$$y = X\beta + u \tag{19}$$

where

- \triangleright y is a vector $n \times 1$ with typical element y_i
- ► X is a matrix $n \times k$ Note that we can represent it as a column vector $X = [X_1 \ X_2 \ \dots \ X_k]$
- \triangleright *β* is a vector *k* × 1 with typical element *β*_{*i*}

Thus

$$y_i = X_i'\beta + u_i$$
$$= \sum_{i=1}^k \beta_i X_{ji} + u_i$$



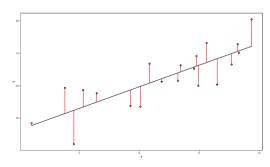
(20)

Linear Regression Model

How do we estimate β ?

- ► Method of Moments (for HW)
- ► MLE (more on this later)
- ightharpoonup OLS: minimize risk squared error loss \rightarrow minimizes SSR (e'e)
 - where $e = Y \hat{Y} = Y X\hat{\beta}$
 - In the HW, you will show that min SSR same as max R^2

OLS solution:
$$\hat{\beta} = (X'X)^{-1}X'y$$



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Gauss Markov Theorem

Gauss-Markov Theorem says that

$$\hat{\beta} = (X'X)^{-1}X'y \tag{21}$$

- ► The OLS estimator $(\hat{\beta})$ is BLUE, the more efficient than any other linear unbiased estimator,
- ▶ Efficiency in the sense that $Var(\tilde{\beta}) Var(\hat{\beta})$ is positive semidefinite matrix.

Proof: HW. Tip: a matrix $M_{v \times v}$ is positive semi-definite iff $c'Mc \ge 0 \ \forall x \in \mathbb{R}^p$

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Gauss Markov Theorem

- ► Gauss Markov Theorem that says OLS is BLUE is perhaps one of the most famous results in statistics.
 - $\triangleright E(\hat{\beta}) = \beta$
 - $V(\hat{\beta}) = \sigma^2(X'X)^{-1}$
- ▶ However, it is essential to note the limitations of the theorem.
 - Correctly specified with exogenous Xs,
 - ► The term error is homoscedastic
 - ▶ No serial correlation.
 - Nothing about the OLS estimator being the more efficient than any other estimator one can imagine.

Prediction vs Estimation

- ightharpoonup Predicting well in this context \rightarrow estimating well
 - Note that the prediction of *y* will be given by $\hat{y} = X\hat{\beta}$
 - Under Gauss-Markov framework
 - $\triangleright E(\hat{y}) = X\beta$
 - $V(\hat{y}) = \sigma^2 X'(X'X)^{-1} X$
- ► Then if $\hat{\beta}$ is unbiased and of minimum variance,
- ▶ then \hat{y} is an unbiased predictor and minimum variance, from the class of unbiased linear estimators/predictors
 - Proof: for HW similar to $\hat{\beta}$ proof

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Recap

- ► We start shifting paradigms
- ► Tools are not that different (so far)
- ightharpoonup Decision Theory: Risk with square error loss ightarrow MSE
- ▶ OLS is a "work horse" approximates the E[Y|X] quite well
- Next Class:
 - ► Next Class: OLS, Geometry, Properties

Further Readings

- ► Angrist, J. D., & Pischke, J. S. (2008). Mostly harmless econometrics. Princeton university press.
- ► Casella, G., & Berger, R. L. (2002). Statistical inference (Vol. 2, pp. 337-472). Pacific Grove, CA: Duxbury.
- ► Tom Shaffer The 42 V's of Big Data and Data Science. https://www.kdnuggets.com/2017/04/42-vs-big-data-data-science.html