



# Exercise: Parallel Traffic Modelling

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### 1 Introduction and Aims

The aim of this exercise is to take a simple example, the 1D traffic model as described in the lectures, and parallelise it in various ways. Although this code is probably not sufficiently complicated to show substantial performance differences, the idea is for you to experiment with different techniques in the simple traffic model before implementing them in a real MPI application.

You will be given source code, implemented in both C and Fortran, that contains:

- 1. a working serial code;
- 2. a working MPI code;
- 3. a working OpenMP code;
- 4. Makefiles and template batch submission scripts for ARCHER2.

The exercises below range from fairly basic to very advanced. Please start at whatever level you want to!

### 2 Instructions

Obtain the code as traffic.tar from the course web page.

#### 2.1 Verification

The way it is written the code should give **exactly** the same answer for both languages regardless of whether it is serial or parallel. For a road of length 100000, the velocity at iteration 2000 should be 0.931989 (to 6 decimal places). If you get a different answer then your code is probably wrong!

You can experiment with increasing the length of the road – just change the value of ncell near the top of the main program. If you decide to use a road of a different length, you should re-run the serial code to get a new baseline result. Note that the way the MPI code is implemented, it assumes that the **length** of the road is an exact multiple of the number of processes.

The number of iterations is set quite low and you may wish to increase this when measuring performance so that the parallel code still runs for a reasonable length of time (e.g. for around a second). Simply multiply the value of maxiter by, say, a factor of 10:

```
maxiter = 200000000/ncell;
maxiter = maxiter*10;
printfreq = maxiter/10;
...
```

## 3 MPI exercises

These range from fairly basic to very advanced. Please attempt whatever ones you feel comfortable with.

- 1. Run the MPI code on a range of process counts (e.g. 1, 2, 5, 10, 20, 40 and 50) and plot a graph of the speedup against the number of processes.
- 2. Do the same with very short and very long roads and compare the performance results.
- 3. The global sum requires a parallel reduction MPI\_Allreduce which is an expensive operation. Modify the code so it only calls reductions when necessary; investigate the effect on performance.
- 4. Replace the MPI\_Sendrecv call with separate calls to MPI\_Send and MPI\_Recv and check that the code still runs correctly. Note that you have probably written a technically incorrect code because MPI\_Send could be implemented as a synchronous send.
- 5. Replace the call to MPI\_Send with MPI\_Ssend to guarantee that it is implemented synchronously. As it stands, your code will probably deadlock (see Section 3.1 for more exercises on this topic).
- 6. Fix the deadlock by arranging the processes into odd/even pairs where, in each pair, one process sends first then receives and the other receives first then sends.
- 7. Solve the deadlock problem using non-blocking operations. There are a number of options:
  - (a) a non-blocking send (MPI\_ISsend), a blocking receive (MPI\_Recv) and a wait (MPI\_Wait);
  - (b) a non-blocking receive, a blocking send and a wait;
  - (c) a non-blocking send, a non-blocking receive and multiple waits (e.g. MPI\_Waitall).

When developing the non-blocking code, you should use synchronous send (i.e MPI\_Ssend / MPI\_Issend) as opposed to standard send (MPI\_Send / MPI\_Isend). This ensures an incorrect code is guaranteed to deadlock; with standard sends, an incorrect code might just happen to run correctly which is not desirable. Once working you can switch to MPI\_Isend which should improve performance.

- 8. Put an MPI\_Barrier at the end of every iteration. Although this is **completely unnecessary**, many people do this kind of thing "just to be safe". What is the effect on performance?
- 9. Implement the non-blocking halo exchange using *persistent communications*. In the case of running on 2 processes, where the up and down neighbour are both the same process, can you guarantee that the sends and receives will match correctly?
- 10. Try to overlap some of the computation with communications, i.e. update the interior cells of the road while waiting for the halo data to arrive.
- 11. Minimise the latency overhead by using deep halos, i.e. exchange more than one boundary element and then do multiple iterations before the next halo swap. It is much easier to implement an explicit depth first (e.g. 2 halo points) before attempting the general case of depth D.
- 12. Combine deep halos with overlapping communication and calculation.
- 13. Perform the halo swaps the neighbourhood collective operation MPI\_Neighbor\_alltoallv. You will need to create a 1D Cartesian topology using MPI\_Cart\_create with periodic boundary conditions.

### 3.1 Non-periodic boundary conditions

The reason that the traffic model deadlocks with a naive implementation using synchronous sends is because of the periodic boundary conditions: all processes are trying to send at the same time. With non-periodic boundaries, however, processes at the extreme ends of the road will not need to send or receive some of the data and the deadlock is broken.

Update the traffic model to use non-periodic boundaries:

- 1. Set the halo at the exit of the road (on the last process) to be zero so cars are always free to leave;
- 2. Each iteration, set the halo data at the entrance to the road (on the first process) to be 1 with probability density, otherwise set to zero. This maintains the same density of traffic for the whole simulation; see initroad() to see how to call the random number generator.
- 3. Run the code on one and many processes; does it give the same answer? Do you understand why?
- 4. Implement the halo swapping using blocking synchronous sends and receives (MPI\_Ssend / MPI\_Recv); unlike the periodic case, the code should not deadlock.
- 5. Compare the performance with the version using MPI\_Sendrecv and using MPI\_Send/MPI\_Recv. Although it works correctly, the synchronous version should be slower; do you understand why?

## 4 OpenMP exercises

- 1. Run the OpenMP code on a range of thread counts (e.g. 1, 2, 6, 12 and 24) and plot a graph of the speedup against the number of threads.
- 2. Change the code so it only computes the total number of moves when absolutely necessary. How does the impact on performance compare with the equivalent optimisation in MPI?
- 3. Before the first call to initroad(), zero both the oldroad and newroad arrays using a parallel loop. With a very long road (e.g. at least ten million cells), what is the effect on performance for small and large numbers of threads? Do you understand what is happening here?
- 4. Minimise the overhead of creating parallel regions by enclosing the entire iteration loop with a single parallel region. What is the effect on performance? Note that this is **very challenging**, e.g. you will now need to implement updateroad () using orphaned directives.

# 5 Hybrid MPI/OpenMP

#### 5.1 Process placement

The first thing to check when running a Hybrid MPI/OpenMP code on any parallel system is to check you know how to ensure that the process and threads are distributed correctly across nodes and cores.

The batch script archer2.job in the directory C-HYB (the same script is also in F-HYB) allows you to do this. It simply runs an application called xthi that does nothing but print out where each process and/or thread is running. i.e. what node it is on and which CPU-core(s) it is bound to.

Vary the parameters in the SLURM script and check that you understand what is happening. A couple of things to try:

- What happens if OMP NUM THREADS is set to 1 when cpus-per-task is 4?
- What happens if OMP\_NUM\_THREADS is set to 8 when cpus-per-task is 4?

### 5.2 Hybrid traffic model

It should be quite simple to introduce OpenMP directives into the MPI code in exactly the same way as the serial code.

- 1. Set the length of the road to include a factor of 128 (e.g. use 128000) so you have more freedom to vary the number of processes.
- 2. Compare performance for different numbers of processes or threads on the same number of cores. For example, on 2 nodes with a total of 256 cores you could use: 256 processes (P) with 1 thread per process (T); (P = 128, T = 2); (P = 64, T = 4); ...; (P = 2, T = 128).

### **6 MPI Shared Memory**

The exercise is to implement RMA calls in a real MPI program. You are provided with a working MPI program and the ultimate aim is to implement MPI shared memory so all communication on a node is done with direct reads and writes, and you only use send and receive when going between different nodes.

I have also provided a working version (traffic-rma) that uses MPI\_Put for **all** point-to-point communications which you may find useful.

I would suggest the following approach:

- compare the MPI and MPI-RMA versions and check that you understand how the RMA version works;
- change the RMA version to use MPI\_Get instead of MPI\_Put;
- introduce shared memory windows so that the program runs on a single node using reads and writes to shared arrays;
- extend the program so that it uses point-to-point send and receive between nodes.

There is a slight subtlety for Fortran programmers as the memory allocation routine returns a C pointer and you need to convince the compiler that it's really a proper Fortran array.

The way to do this is: