

Advanced Message-Passing Programming Exercises

MPI Performance

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1 Introduction

The purpose of this exercise is to investigate the performance of basic point-to-point MPI operations. You are given a simple ping-pong code that exchanges messages of increasing size between two MPI ranks, and prints out the average time taken and the bandwidth over a large number of repetitions. With this code you can investigate how the following factors affect the performance:

- different underlying protocols for different message sizes;
- different MPI send modes (e.g. synchronous vs. buffered);
- different communication hardware (e.g. over the inter-node network or intra-node memory copies);
- different NUMA regions within a node;
- different MPI datatypes (e.g. contiguous or strided data).

For this exercise, the important points of the ARCHER2 architecture are that every node has 128 CPU-cores, each comprising two multicore processors with 64 CPU-cores each.

2 Compiling and Running

The code is contained in `pingpong.tar` on the course web pages:

- copy the tar file to your **/work/** directory, i.e. `/work/tall17/tall17/username/`.
- alternatively, you can fetch the file directly from ARCHER2 using: `wget https://github.com/EPCCed/archer2-`
- unpack: `tar -xvf pingpong.tar`
- changed directory to `pingpong` and compile with `make`
- submit the job: `sbatch archer2.job`

You will need to load some non-default modules to view the results:

```
[user@archer2 ~]$ module load gnuplot
```

By default, the code runs on two processes on the same node (so communications **will not** take place over the network), and benchmarks standard and synchronous sends. Note that **the program also prints out the exact location of the two processes**.

For each mode, two “.plot” files are written containing the times and the bandwidths as a function of message size. The results for the two different modes can be compared using:

```
gnuplot -persist plot_time.gp
gnuplot -persist plot_bandwidth.gp
```

Check that you understand the general form of the graphs before proceeding.

3 Experiments

The supplied gnuplot “.gp” files compare the results for standard and synchronous modes. If you want to compare different modes, or more than two modes, you will have to edit the gnuplot files – the format should be self-explanatory. Also note that the code overwrites the “.plot” files so you will need to make copies after each run if you want to keep a record of the results (e.g. when changing the placement of processes on the cores or nodes).

If you run on more than two processes, the program sends messages between the first (rank zero) and last ranks with all the other processes remaining idle. This is useful when altering the assignment of processes to cores.

By varying `nodes` and `tasks-per-node` in the Slurm script you should have complete control of the placement of the first and last processes.

You should experiment with the following:

1. Communication between two processes on the same node with `nodes=1` and `tasks-per-node=2` (by default, processes will be placed right next to each other on the same multicore processor).
2. Communication between two processes widely separated on the same node (e.g. `nodes=1` and `tasks-per-node=128`).
3. Can you explain any variations in the latency and bandwidth as you change the process locations?
4. Investigate the performance of buffered or strided sends.