unmixing

March 26, 2021

1 Parameters description for the unmixing experiments

Train and evaluate the convolutional neural network (CNN) as well as the deep convolutional autoencoder (DCAE) for the unmixing problem. Exemplary hyperparameters to set:

- -data-file-path path to the hyperspectral image (HSI).
- -ground-truth-path path to the ground truth map containing the fractions of abundances for entire HSI.
- -train-size magnitude of the learning set that is utilized to fine-tune the weights of the model.
- —sub-test-size size of the test set to evaluate the generalization of the model. It is sampled from the remaining HSI excluding the training subset. If not specified, all non-training samples constitute the test set.Can be employed in the case of experiments when changing the magnitudes of training sets while keeping the size of testing sets constant.
- -val-size fraction or size of the validation subset, it is designed to monitor the overfitting.
- -channels-idx index of the spectral dimension in input HSI.
- batch-size number of samples per update step in the training phase.
- -shuffle indicates whether to shuffle the dataset in experiment.
- –patience stopping condition for a specific number of epochs without improvement.
- -model-name name of the utilized model, exemplary values: unmixing_pixel_based_cnn, unmixing_cube_based_cnn, unmixing_pixel_based_dcae, unmixing_cube_based_dcae for the pixel-based, cube-based CNN and DCAE respectively.
- -sample-size number of spectral bands in a given HSI.
- -neighborhood-size size of the spatial extent which is employed for each sample in the form of local neighboring pixels. Most cases allows to leverage the quality of the segmentation as well as the unmixing.
- -n-classes number of endmembers in the HSI for which the abundances will be estimated by the model.
- -lr learning rate regulates the step size during weights updates in the training phase.
- epochs second stopping condition, i.e., the maximum number of epochs.
- -verbose verbosity mode.
- -save-data indicates whether to save the training and test data.

2 Cube-based DCAE

We specify the necessary parameters for the experiment.

```
[1]: # Execute cube-based DCAE:
     from os.path import join
     base_path = r'../datasets/urban'
     data_file_path = join(base_path, 'urban.npy')
     ground_truth_path = join(base_path, 'urban_gt.npy')
     endmembers_path = join(base_path, 'urban_m.npy')
     train_size = 15500
     sub test size = 47249
     val_size = 0.1
     channels idx = -1
     batch size = 256
     shuffle = True
     patience = 3
     model_name = 'unmixing_cube_based_dcae'
     sample_size = 162
     neighborhood_size = 5
     n_{classes} = 6
     dest_path = join('../examples', 'unmixing_results')
     lr = 0.0005
     epochs = 10
     verbose = 0
     save_data = False
     use_mlflow = False
     seed = 1
[2]: import os
     import warnings
     warnings.filterwarnings('ignore')
     import tensorflow as tf
     from ml intuition import enums
     from ml_intuition.data.utils import parse_train_size, subsample_test_set, \
```

```
plot_training_curve, show_statistics
from scripts import prepare_data
from scripts.unmixing import train_unmixing, evaluate_unmixing
os.makedirs(dest_path, exist_ok=True)
dcae_dest_path = join(dest_path, 'cube-based-dcae')
os.makedirs(dcae_dest_path, exist_ok=True)
```

3 Prepare data

We prepare data for the unmixing by utilizing the prepare_data.main method. It accepts various parameters such as path to the data file or ground-truth for a specific HSI. Furthermore, magnitude of the learning set can be also specified. Moreover, the method accepts the neighborhood size parameter, which specifies the spatial extent of ech sample. For each run in the experiment, for the sake of reproducibility, it is possible to set a specific seed. The returned object is a dictionary with three keys: train, test and val. Each of them contains an additional dictionary with data and labels keys, holding corresponding numpy.ndarray objects with the data. For more details about the parameters, refer to the documentation of prepare_data.main function (located in scripts/prepare_data).

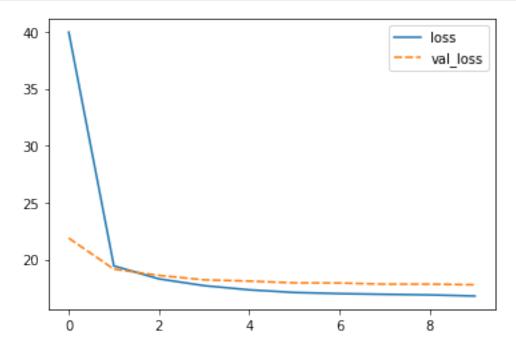
4 Train and evaluate the model

Few parameters previously initialized are employed in this step e.g., the name of the model, size of the spectral extent, learning rate and batch size. The results including the metrics are stored in $dcae_dest_path$ directory.

c:\users\lukasz\desktop\machine-learning\venv\lib\sitepackages\tensorflow\python\framework\tensor_util.py:125: DeprecationWarning:
np.asscalar(a) is deprecated since NumPy v1.16, use a.item() instead
 tensor_proto.float_val.extend([np.asscalar(x) for x in proto_values])

Layer (type)	Output Shape	Param #
conv3d (Conv3D)	(None, 3, 3, 160, 16)	448
conv3d_1 (Conv3D)	(None, 1, 1, 158, 32)	13856
conv3d_2 (Conv3D)	(None, 1, 1, 156, 64)	6208
conv3d_3 (Conv3D)	(None, 1, 1, 154, 128)	24704
flatten (Flatten)	(None, 19712)	0
dense (Dense)	(None, 256)	5046528
dropout (Dropout)	(None, 256)	0
dense_1 (Dense)	(None, 6)	1542
softmax (Softmax)	(None, 6)	0
dense_2 (Dense)	(None, 162)	1134
Total params: 5,094,420		

Total params: 5,094,420
Trainable params: 5,093,286
Non-trainable params: 1,134



```
[5]:
           aRMSE
                                                     perClassSumRMSE
                       aSAM
                             overallRMSE
                                             rmsAAD
                                                                       classORMSE
        0.052665 0.167482
                                0.080721
                                          0.285665
                                                            0.474069
                                                                         0.085252
        class1RMSE
                    class2RMSE
                                 class3RMSE
                                             class4RMSE
                                                          class5RMSE
                                                                          rRMSE \
     0
          0.102679
                       0.083158
                                   0.052504
                                                0.087284
                                                            0.063191
                                                                       0.060676
              rSID
                    inference_time
        3085.67749
                          28.327313
```

5 Pixel-based CNN

We perform the same steps for the pixel-based CNN model, however a few parameters must be altered. Since we utilize only the spectral dimension, the <code>neighborhood_size</code> is set to <code>None</code>, the learning rate is also adjusted. The <code>endmembers_path</code> is also not needed anymore, since we train the model on the fractions of abundances of each endmember. The pipeline looks similar to the DCAE model.

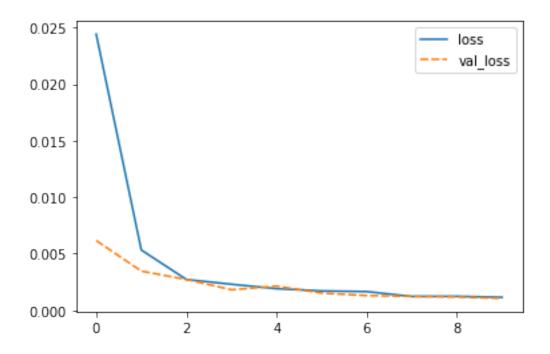
```
[6]: # Execute the pixel-based CNN:
endmembers_path = None
```

```
model_name = 'unmixing_pixel_based_cnn'
lr = 0.01
neighborhood_size = None
cnn_dest_path = join(dest_path, 'pixel-based-cnn')
os.makedirs(cnn_dest_path, exist_ok=True)
# Prepare data for unmixing:
data = prepare_data.main(data_file_path=data_file_path,
                         ground truth path=ground truth path,
                         train_size=parse_train_size(train_size),
                         val size=val size,
                         stratified=False,
                         background_label=-1,
                         channels_idx=channels_idx,
                         neighborhood_size=neighborhood_size,
                         save_data=save_data,
                         seed=seed,
                         use_unmixing=True)
# Subsample the test set to constitute a constant size:
if sub_test_size is not None:
    subsample_test_set(data[enums.Dataset.TEST], sub_test_size)
# Train the model:
train_unmixing.train(model_name=model_name,
                     dest_path=cnn_dest_path,
                     data=data,
                     sample size=sample size,
                     neighborhood_size=neighborhood_size,
                     n_classes=n_classes,
                     lr=lr,
                     batch_size=batch_size,
                     epochs=epochs,
                     verbose=verbose,
                     shuffle=shuffle,
                     patience=patience,
                     endmembers_path=endmembers_path,
                     seed=seed)
# Evaluate the model:
evaluate_unmixing.evaluate(
    model_path=os.path.join(cnn_dest_path, model_name),
    data=data,
    dest path=cnn dest path,
    neighborhood_size=neighborhood_size,
    batch size=batch size,
    endmembers_path=endmembers_path)
tf.keras.backend.clear_session()
```

c:\users\int users\int ukasz\desktop\machine-learning\venv\lib\sitepackages\tensorflow\python\framework\tensor_util.py:125: DeprecationWarning:
np.asscalar(a) is deprecated since NumPy v1.16, use a.item() instead
 tensor_proto.float_val.extend([np.asscalar(x) for x in proto_values])

Layer (type)	Output Shape	Param #
conv3d (Conv3D)	(None, 1, 1, 158, 3)	18
max_pooling3d (MaxPooling3D)	(None, 1, 1, 79, 3)	0
conv3d_1 (Conv3D)	(None, 1, 1, 76, 6)	78
max_pooling3d_1 (MaxPooling3	(None, 1, 1, 38, 6)	0
conv3d_2 (Conv3D)	(None, 1, 1, 34, 12)	372
max_pooling3d_2 (MaxPooling3	(None, 1, 1, 17, 12)	0
conv3d_3 (Conv3D)	(None, 1, 1, 14, 24)	1176
max_pooling3d_3 (MaxPooling3	(None, 1, 1, 7, 24)	0
flatten (Flatten)	(None, 168)	0
dense (Dense)	(None, 192)	32448
dense_1 (Dense)	(None, 150)	28950
dense_2 (Dense)	(None, 6)	906

Total params: 63,948 Trainable params: 63,948 Non-trainable params: 0



[7]: aRMSE aSAM overallRMSE rmsAAD perClassSumRMSE classORMSE \
0 0.023885 0.073451 0.032043 0.109212 0.189771 0.037084

class1RMSE class2RMSE class3RMSE class4RMSE class5RMSE inference_time
0 0.036499 0.033178 0.024482 0.024789 0.033738 1.865043