

data_noise_injection

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1 Noise injection into data

If you plan on using this implementation, please cite our work (<https://www.mdpi.com/2072-4292/13/8/1532>):

@Article{Nalepa2021RemoteSens, AUTHOR = {Nalepa, Jakub and Myller, Michal and Cwiek, Marcin and Zak, Lukasz and Lakota, Tomasz and Tulczyjew, Lukasz and Kawulok, Michal}, TITLE = {Towards On-Board Hyperspectral Satellite Image Segmentation: Understanding Robustness of Deep Learning through Simulating Acquisition Conditions}, JOURNAL = {Remote Sensing}, VOLUME = {13}, YEAR = {2021}, NUMBER = {8}, ARTICLE-NUMBER = {1532}, URL = {https://www.mdpi.com/2072-4292/13/8/1532}, ISSN = {2072-4292}, DOI = {10.3390/rs13081532}}

This example presents how the noise can be injected into any part of the dataset: train, test and validation. There are three types of noise implemented:

- Gaussian
- Impulsive
- Shot

There are a few parameters which indicate how a given noise behaves:

- *pa* - Fraction of noisy pixels, the number of affected samples is calculated by: $\text{floor}(n_samples * pa)$.
- *pb* - Fraction of noisy bands. When established the number of samples that undergo noise injection, for each sample the: $\text{floor}(n_bands * pb)$ bands are affected.
- *bc* - Boolean indicating whether the indexes of affected bands, are constant for each sample. When set to: False, different bands can be augmented with noise for each pixel.
- *mean* - Gaussian noise parameter, the mean of the normal distribution.
- *std* - Gaussian noise parameter, standard deviation of the normal distribution.
- *pw* - Impulsive noise parameter, ratio of whitened pixels for the affected set of samples.

```
[1]: import os
import sys
sys.path.append(os.path.dirname(os.getcwd()))
```

```
[ ]: import os
import shutil
import re
from copy import copy
```

```

import clize
import mlflow
import tensorflow as tf
from clize.parameters import multi

from scripts import evaluate_model, prepare_data, train_model
from ml_intuition.data.utils import plot_training_curve, show_statistics

```

Specify path to the `.npz` dataset and ground truth, as well as the output path to store all the artifacts.

```

[3]: DEST_PATH = 'data_noise_injection_results'
DATA_FILE_PATH = os.path.join(os.path.dirname(os.getcwd()), 'datasets/pavia/
    ↪pavia.npz')
GT_FILE_PATH = os.path.join(os.path.dirname(os.getcwd()), 'datasets/pavia/
    ↪pavia_gt.npz')
experiment_dest_path = os.path.join(DEST_PATH, 'experiment_0')
os.makedirs(experiment_dest_path, exist_ok=True)

```

2 Prepare the data

To fit into the the pipeline, the data has to be preprocessed. It is achieved by the `prepare_data.main` function. It accepts a path to a `.npz` file with the original cube as well as the corresponding ground truth. In this example, we randomly extract 250 samples from each class (balanced scenario), use 10% of them as validation set, and extract only spectral information of a pixel. The returned object is a dictionary with three keys: `train`, `test` and `val`. Each of them contains an additional dictionary with `data` and `labels` keys, holding corresponding `numpy.ndarray` objects with the data. For more details about the parameters, refer to the documentation of `prepare_data.main` function (located in `scripts/prepare_data`).

```

[4]: data = prepare_data.main(data_file_path=DATA_FILE_PATH,
                             ground_truth_path=GT_FILE_PATH,
                             output_path=None,
                             train_size=250,
                             val_size=0.1,
                             stratified=True,
                             background_label=0,
                             channels_idx=2,
                             neighborhood_size=None,
                             save_data=False,
                             seed=0)

```

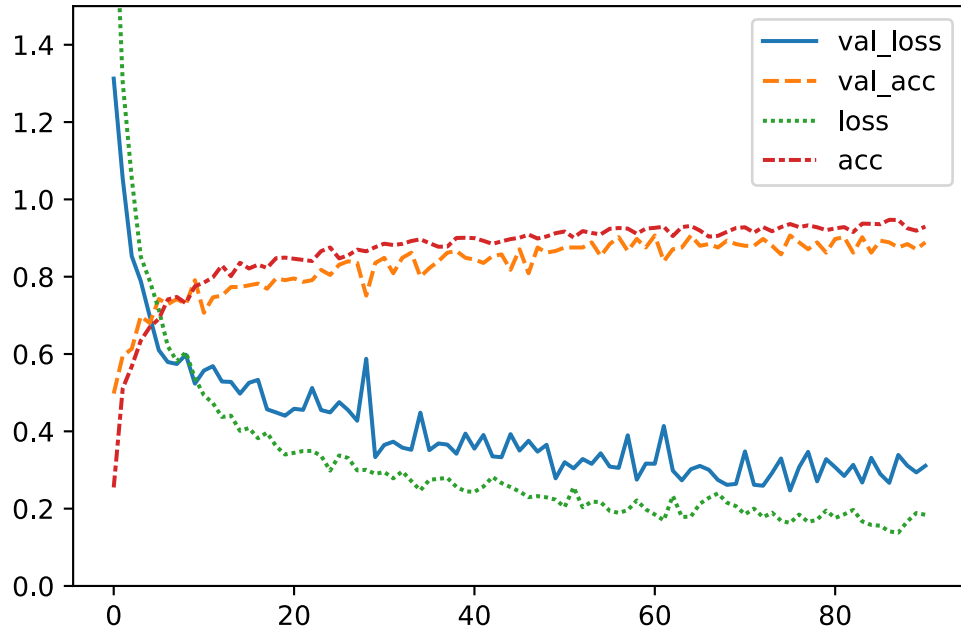
3 Train the model with nosiy training set

The function `trian_model.train` executed the trainig procedure. In order to inject noise into the training set, provide `noise` with a name of the noise type, `noise_sets` with the set you would like to augment, and `noise_params` with the noise parameters. Trained model will be stored under `experiment_dest_path` folder path.

```
[5]: train_model.train(model_name='model_2d',
                        kernel_size=5,
                        n_kernels=200,
                        n_layers=1,
                        dest_path=experiment_dest_path,
                        data=data,
                        sample_size=103,
                        n_classes=9,
                        lr=0.001,
                        batch_size=128,
                        epochs=200,
                        verbose=0,
                        shuffle=True,
                        patience=15,
                        noise=['gaussian'],
                        noise_sets=['train'],
                        noise_params="{\"mean\": 0, \"std\": 1, \"pa\": 0.1, \"pb\":
↪ 1}")
```

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 99, 1, 200)	1200
conv2d_1 (Conv2D)	(None, 32, 1, 200)	200200
conv2d_2 (Conv2D)	(None, 14, 1, 200)	200200
conv2d_3 (Conv2D)	(None, 5, 1, 200)	200200
flatten (Flatten)	(None, 1000)	0
dense (Dense)	(None, 200)	200200
dense_1 (Dense)	(None, 128)	25728
dense_2 (Dense)	(None, 9)	1161
Total params: 828,889		
Trainable params: 828,889		
Non-trainable params: 0		

```
[6]: plot_training_curve(os.path.join(experiment_dest_path, "training_metrics.csv"),
    → ['val_loss', 'val_acc', 'loss', 'acc'])
```



4 Evaluate the model

Evaluate the model, calculating all metrics. All artifacts will be stored under provided `experiment_dest_path`. In this step, it is also possible to inject noise into the `test` set, similarly to the previous function call. But first, let's evaluate the model on original test dataset:

```
[ ]: evaluate_model.evaluate(
    model_path=os.path.join(experiment_dest_path, 'model_2d'),
    data=copy(data),
    dest_path=experiment_dest_path,
    n_classes=9,
    batch_size=1024,
    noise=[],
    noise_sets=[])
tf.keras.backend.clear_session()
```

```
[8]: show_statistics(os.path.join(experiment_dest_path, "inference_metrics.csv"))
```

```
[8]: accuracy_score  balanced_accuracy_score  cohen_kappa_score  Class_0  \
0          0.859942                0.902939                0.816331  0.865068

      Class_1  Class_2  Class_3  Class_4  Class_5  Class_6  Class_7  \
0  0.827382  0.825311  0.955935  0.999087  0.862733  0.924074  0.868298

      Class_8  inference_time
0  0.998565      6.757337
```

And now let's evaluate the model on the noisy test set, using Gaussian noise with mean 0 and std 1 affecting only 10% of the pixels

```
[9]: evaluate_model.evaluate(
      model_path=os.path.join(experiment_dest_path, 'model_2d'),
      data=copy(data),
      dest_path=os.path.join(experiment_dest_path, "noisy"),
      n_classes=9,
      batch_size=1024,
      noise=['gaussian'],
      noise_sets=['test'],
      noise_params="{\"mean\": 0, \"std\": 1, \"pa\": 0.1, \"pb\": 1}")
```

```
[10]: show_statistics(os.path.join(experiment_dest_path, "noisy", "inference_metrics.
      ↪ csv"))
```

```
[10]: accuracy_score  balanced_accuracy_score  cohen_kappa_score  Class_0  \
0          0.792183                0.836907                0.731185  0.790785

      Class_1  Class_2  Class_3  Class_4  Class_5  Class_6  Class_7  \
0  0.763085  0.763656  0.889126  0.968037  0.79117  0.844444  0.786422

      Class_8  inference_time
0  0.935438      6.741781
```

We can see that the accuracy of the model dropped in comparison with the original one.