

unmixing_noise_injection_ensemble

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If you plan on using this implementation, please cite our work:

@INPROCEEDINGS{Tulczyjew2021IGARSS, author={Tulczyjew, Lukasz and Nalepa, Jakub}, booktitle={IGARSS 2021 - 2021 IEEE International Geoscience and Remote Sensing Symposium}, title={Investigating the impact of the training set size on deep learning-powered hyperspectral unmixing}, year={2021}, note={in press}}

1 Noise injection into unmixing models ensemble

- Inject noise into the models for unmixing and verify its robustness against noise.
- Create N copies of the base model and augment them with noise. Each model makes its own predictions, which are later aggregated to create an ensemble final prediction.
- `-data-file-path` - path to the hyperspectral image (HSI).
- `-ground-truth-path` - path to the ground truth map containing the fractions of abundances for entire HSI.
- `-train-size` - magnitude of the learning set that is utilized to fine-tune the weights of the model.
- `-sub-test-size` - size of the test set to evaluate the generalization of the model. It is sampled from the remaining HSI excluding the training subset. If not specified, all non-training samples constitute the test set. Can be employed in the case of experiments when changing the magnitudes of training sets while keeping the size of testing sets constant.
- `-val-size` - fraction or size of the validation subset, it is designed to monitor the overfitting.
- `-channels-idx` - index of the spectral dimension in input HSI.
- `batch-size` - number of samples per update step in the training phase.
- `-shuffle` - indicates whether to shuffle the dataset in experiment.
- `-patience` - stopping condition for a specific number of epochs without improvement.
- `-model-name` - name of the utilized model, exemplary values: `unmixing_pixel_based_cnn`, `unmixing_cube_based_cnn`, `unmixing_pixel_based_dcae`, `unmixing_cube_based_dcae` for the pixel-based, cube-based CNN and DCAE respectively.
- `-sample-size` - number of spectral bands in a given HSI.
- `-neighborhood-size` - size of the spatial extent which is employed for each sample in the form of local neighboring pixels. Most cases allows to leverage the quality of the segmentation as well as the unmixing.
- `-n-classes` - number of endmembers in the HSI for which the abundances will be estimated by the model.
- `-lr` - learning rate regulates the step size during weights updates in the training phase.
- `-epochs` - second stopping condition, i.e., the maximum number of epochs.

- `-verbose` - verbosity mode.
- `-save-data` - indicates whether to save the training and test data.

2 Train base Pixel-based CNN

We specify the necessary parameters for the experiment.

```
[1]: # Execute pixel-based CNN:
from os.path import join

base_path = r'../datasets/urban'
data_file_path = join(base_path, 'urban.npy')
ground_truth_path = join(base_path, 'urban_gt.npy')
endmembers_path = None
train_size = 15500
sub_test_size = 5000
val_size = 0.1
channels_idx = -1
batch_size = 256
shuffle = True
patience = 3
model_name = 'unmixing_pixel_based_cnn'
sample_size = 162
neighborhood_size = None
n_classes = 6
dest_path = join('../examples', 'unmixing_results')
lr = 0.0005
epochs = 10
verbose = 0
save_data = False
use_mlflow = False
seed = 1

[2]: import os
import warnings
warnings.filterwarnings('ignore')

import tensorflow as tf

from ml_intuition import enums
from ml_intuition.data.utils import parse_train_size, subsample_test_set, \
    plot_training_curve, show_statistics
from scripts import prepare_data
from scripts.unmixing import train_unmixing, evaluate_unmixing

os.makedirs(dest_path, exist_ok=True)
```

```
cnn_dest_path = join(dest_path, 'pixel-based-cnn')
os.makedirs(cnn_dest_path, exist_ok=True)
```

3 Prepare data

We prepare data for the unmixing by utilizing the *prepare_data.main* method. It accepts various parameters such as path to the data file or ground-truth for a specific HSI. Furthermore, magnitude of the learning set can be also specified. Moreover, the method accepts the neighborhood size parameter, which specifies the spatial extent of each sample. For each run in the experiment, for the sake of reproducibility, it is possible to set a specific seed. The returned object is a dictionary with three keys: *train*, *test* and *val*. Each of them contains an additional dictionary with *data* and *labels* keys, holding corresponding *numpy.ndarray* objects with the data. For more details about the parameters, refer to the documentation of *prepare_data.main* function (located in *scripts/prepare_data*).

```
[3]: # Prepare data for unmixing:
data = prepare_data.main(data_file_path=data_file_path,
                        ground_truth_path=ground_truth_path,
                        train_size=parse_train_size(train_size),
                        val_size=val_size,
                        stratified=False,
                        background_label=-1,
                        channels_idx=channels_idx,
                        neighborhood_size=neighborhood_size,
                        save_data=save_data,
                        seed=seed,
                        use_unmixing=True)

# Subsample the test set to constitute a constant size:
if sub_test_size is not None:
    subsample_test_set(data[enums.Dataset.TEST], sub_test_size)
```

4 Train and evaluate the model

Few parameters previously initialized are employed in this step e.g., the name of the model, size of the spectral extent, learning rate and batch size. The results including the metrics are stored in *cnn_dest_path* directory.

```
[4]: # Train the model:
train_unmixing.train(model_name=model_name,
                    dest_path=cnn_dest_path,
                    data=data.copy(),
                    sample_size=sample_size,
                    neighborhood_size=neighborhood_size,
```

```

        n_classes=n_classes,
        lr=lr,
        batch_size=batch_size,
        epochs=epochs,
        verbose=verbose,
        shuffle=shuffle,
        patience=patience,
        endmembers_path=endmembers_path,
        seed=seed)
# Evaluate the model:
evaluate_unmixing.evaluate(
    model_path=os.path.join(cnn_dest_path, model_name),
    data=data.copy(),
    dest_path=cnn_dest_path,
    neighborhood_size=neighborhood_size,
    batch_size=batch_size,
    endmembers_path=endmembers_path)
tf.keras.backend.clear_session()

```

c:\users\lukasz\desktop\machine-learning\venv\lib\site-packages\tensorflow\python\framework\tensor_util.py:125: DeprecationWarning: np.asscalar(a) is deprecated since NumPy v1.16, use a.item() instead
 tensor_proto.float_val.extend([np.asscalar(x) for x in proto_values])

Layer (type)	Output Shape	Param #
conv3d (Conv3D)	(None, 1, 1, 158, 3)	18
max_pooling3d (MaxPooling3D)	(None, 1, 1, 79, 3)	0
conv3d_1 (Conv3D)	(None, 1, 1, 76, 6)	78
max_pooling3d_1 (MaxPooling3D)	(None, 1, 1, 38, 6)	0
conv3d_2 (Conv3D)	(None, 1, 1, 34, 12)	372
max_pooling3d_2 (MaxPooling3D)	(None, 1, 1, 17, 12)	0
conv3d_3 (Conv3D)	(None, 1, 1, 14, 24)	1176
max_pooling3d_3 (MaxPooling3D)	(None, 1, 1, 7, 24)	0
flatten (Flatten)	(None, 168)	0
dense (Dense)	(None, 192)	32448
dense_1 (Dense)	(None, 150)	28950

```

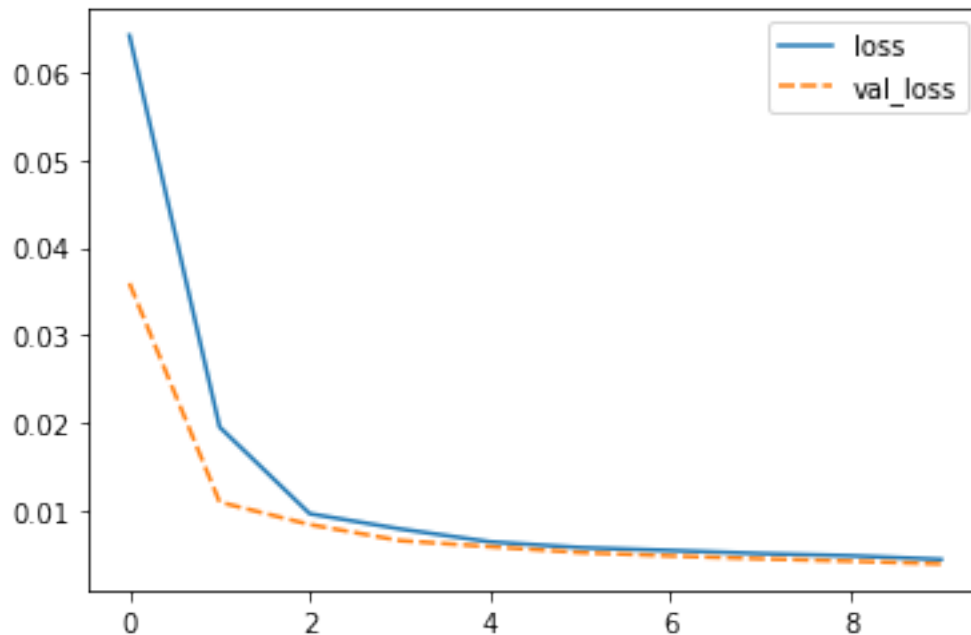
-----
dense_2 (Dense)                (None, 6)                906
=====
Total params: 63,948
Trainable params: 63,948
Non-trainable params: 0
-----

```

```

[5]: plot_training_curve(os.path.join(cnn_dest_path, 'training_metrics.csv'),
                        curve_names=['loss', 'val_loss'],
                        y_limit=False)

```



5 Evaluate an ensemble of models

To run the ensembles for the unmixing problem, use the `evaluate_unmixing` module and provide all necessary arguments. It accepts following types of ensemble voting: - mean, where the average of all models is computed - booster, where an additional model is trained on the training set predictions

Each layer is modified separately. It is achieved by drawing a random number for each of the parameters of the layer. The number is drawn from the normal distribution with provided mean and standard deviation calculated from the layer's parameters, multiplied by 0.1.

6 Evaluate the mean ensemble:

```
[6]: from scripts.unmixing.evaluate_unmixing import evaluate

mean_dest_path = os.path.join(cnn_dest_path, 'noise-mean')
os.makedirs(mean_dest_path, exist_ok=True)
evaluate(data=data.copy(),
        model_path=os.path.join(cnn_dest_path, model_name),
        dest_path=mean_dest_path,
        neighborhood_size=neighborhood_size,
        batch_size=batch_size,
        endmembers_path=endmembers_path,
        use_ensemble=True,
        ensemble_copies=8,
        noise_params={"mean": 0, "std": 1},
        voting='mean')
```

```
c:\users\lukasz\desktop\machine-learning\venv\lib\site-
packages\tensorflow\python\framework\tensor_util.py:125: DeprecationWarning:
np.asscalar(a) is deprecated since NumPy v1.16, use a.item() instead
    tensor_proto.float_val.extend([np.asscalar(x) for x in proto_values])
```

7 Evaluate the booster random forest regressor ensemble:

```
[7]: from scripts.unmixing.evaluate_unmixing import evaluate

booster_dest_path = os.path.join(cnn_dest_path, 'noise-booster')
os.makedirs(booster_dest_path, exist_ok=True)
evaluate(data=data.copy(),
        model_path=os.path.join(cnn_dest_path, model_name),
        dest_path=booster_dest_path,
        neighborhood_size=neighborhood_size,
        batch_size=batch_size,
        endmembers_path=endmembers_path,
        use_ensemble=True,
        ensemble_copies=8,
        noise_params={"mean": 0, "std": 1},
        voting='booster', # Booster type of voting
        voting_model='RFR', # Random Forest Regressor model
        voting_model_params={"}) # Default parameters
```

```
c:\users\lukasz\desktop\machine-learning\venv\lib\site-
packages\tensorflow\python\framework\tensor_util.py:131: DeprecationWarning:
np.asscalar(a) is deprecated since NumPy v1.16, use a.item() instead
    tensor_proto.int_val.extend([np.asscalar(x) for x in proto_values])
```

8 Original base model results:

```
[8]: show_statistics(os.path.join(cnn_dest_path, 'inference_metrics.csv'))
```

```
[8]:      aRMSE      aSAM  overallRMSE    rmsAAD  perClassSumRMSE  classORMSE  \  
0  0.05045  0.154137    0.066649  0.227918          0.39539    0.081193  
  
      class1RMSE  class2RMSE  class3RMSE  class4RMSE  class5RMSE  inference_time  
0    0.068023    0.058313    0.053067    0.075524    0.059269          0.297013
```

9 Mean results:

```
[9]: show_statistics(os.path.join(mean_dest_path,  
                                'inference_metrics.csv'))
```

```
[9]:      aRMSE      aSAM  overallRMSE    rmsAAD  perClassSumRMSE  classORMSE  \  
0  0.062937  0.18116    0.078619  0.255331          0.464713    0.100972  
  
      class1RMSE  class2RMSE  class3RMSE  class4RMSE  class5RMSE  inference_time  
0    0.079178    0.067611    0.056964    0.081861    0.078127          2.39901
```

10 Booster results:

```
[10]: show_statistics(os.path.join(booster_dest_path,  
                                'inference_metrics.csv'))
```

```
[10]:      aRMSE      aSAM  overallRMSE    rmsAAD  perClassSumRMSE  classORMSE  \  
0  0.022011  0.074186    0.038362  0.142907          0.22021    0.056896  
  
      class1RMSE  class2RMSE  class3RMSE  class4RMSE  class5RMSE  inference_time  
0    0.030881    0.02539    0.025169    0.038791    0.043084          1.912657
```