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# **Beetles**

***Release 1.0***

**KP Labs**

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## INSTALLATION

For the environment management in our repo, we utilize *conda*.

Required dependencies are stored in the *environment.yml* file. To create the environment with required packages, execute the following command:

```
conda env create -f environment.yml
```

Because of the fact that we utilize the Xilinx DNNDK tool for model quantization and compilation, the *tensorflow* package has to be installed manually. Please refer to the official documentation, where the process is fully described: ([https://www.xilinx.com/support/documentation/sw\\_manuals/ai\\_inference/v1\\_6/ug1327-dnndk-user-guide.pdf](https://www.xilinx.com/support/documentation/sw_manuals/ai_inference/v1_6/ug1327-dnndk-user-guide.pdf) - Chapter 1: Quick Start - Tensorflow Version: Installing with Anaconda).

Keep in mind, that the DNNDK tool requires **Ubuntu** 14.04, 16.04 or 18.04.



## MACHINE-LEARNING

## 2.1 ml\_intuition package

### 2.1.1 Subpackages

#### ml\_intuition.data package

##### Submodules

#### ml\_intuition.data.input\_fn module

File containing functions which calibrate input for frozen graphs used for quantization in scripts/quantize.sh. All arguments to such functions are passed through the shell environment, because they are executed through the internal decent tools.

`ml_intuition.data.input_fn.calibrate_2d_input` (*iter*)

Return dictionary with a batch of the training data to be used for quantization calibration. One dimension and the end is added and the min max normalization is performed.

**Parameters** *iter* (int) – Int object indicating the calibration step

**Return type** Dict[str, ndarray]

**Returns** Dict with name of the input node as key and training samples in np.ndarray as value

#### ml\_intuition.data.io module

All I/O related functions

`ml_intuition.data.io.extract_set` (*data\_path*, *dataset\_key*)

Function for loading a h5 format dataset as a dictionary of samples, labels, min and max values.

**Parameters**

- **data\_path** (str) – Path to the dataset.
- **dataset\_key** (str) – Key for dataset.

**Return type** Dict[str, Union[ndarray, float]]

**Returns** Dictionary containing labels, data, min and max values.

`ml_intuition.data.io.load_metrics` (*experiments\_path*, *filename=None*)

Load metrics to a dictionary.

#### Parameters

- **experiments\_path** (str) – Path to the experiments directory.
- **filename** (Optional[str]) – Name of the file holding metrics. Defaults to ‘inference\_metrics.csv’.

**Return type** Dict[List, List]

**Returns** Dictionary containing all metric names and values from all experiments.

`ml_intuition.data.io.load_npy (data_file_path, gt_input_path, use_unmixing=False)`  
Load .npz data and GT from specified paths

#### Parameters

- **data\_file\_path** (str) – Path to the data .npz file
- **gt\_input\_path** (str) – Path to the GT .npz file
- **use\_unmixing** (bool) – Boolean indicating whether to perform experiments on the un-mixing datasets, where classes in each pixel are present as abundance fractions.

**Return type** Tuple[ndarray, ndarray]

**Returns** Tuple with loaded data and GT

`ml_intuition.data.io.load_pb (path_to_pb)`  
Load .pb file as a graph

**Parameters** **path\_to\_pb** (str) – Path to the .pb file

**Return type** GraphDef

**Returns** Loaded graph

`ml_intuition.data.io.load_processed_h5 (data_file_path)`  
Load processed dataset containing the train, validation and test subsets with corresponding samples and labels.

**Parameters** **data\_file\_path** (str) – Path to the .h5 file.

**Return type** Dict

**Returns** Dictionary containing train, validation and test subsets.

`ml_intuition.data.io.load_satellite_h5 (data_file_path)`  
Load hyperspectral cube and ground truth transformation matrix from .h5 file

**Parameters** **data\_file\_path** (str) – Path to the .h5 file

**Return type** Tuple[ndarray, ndarray]

**Returns** Hyperspectral cube and transformation matrix, both as np.ndarray

`ml_intuition.data.io.load_tiff (file_path)`  
Load tiff image into np.ndarray

**Parameters** **file\_path** (str) – Path to the .tiff file

**Return type** ndarray

**Returns** Loaded image as np.ndarray

`ml_intuition.data.io.read_min_max (path)`  
Read min and max value from a .csv file

**Parameters** **path** (str) – Path to the .csv file containing min and max value

**Return type** Tuple[float, float]



**Returns** Tuple with min and max

`ml_intuition.data.io.save_confusion_matrix(matrix, dest_path, file-  
name='confusion_matrix')`

Save confusion matrix to provided destination. If filename is not provided 'confusion\_matrix.csv' will be used.

**Parameters**

- **matrix** (ndarray) – Matrix to save
- **dest\_path** (str) – Destination folder
- **filename** (str) – Name of the file, defaults to 'confusion\_matrix.csv'

**Return type** None

**Returns** None

`ml_intuition.data.io.save_md5(output_path, train_x, train_y, val_x, val_y, test_x, test_y)`

Save provided data as .md5 file

**Parameters**

- **output\_path** (str) – Path to the filename
- **train\_x** (ndarray) – Train set
- **train\_y** (ndarray) – Train labels
- **val\_x** (ndarray) – Validation set
- **val\_y** (ndarray) – Validation labels
- **test\_x** (ndarray) – Test set
- **test\_y** (ndarray) – Test labels

**Return type** None

**Returns** None

`ml_intuition.data.io.save_metrics(dest_path, metrics, file_name=None)`

Save given dictionary of metrics.

**Parameters**

- **dest\_path** (str) – Destination path.
- **file\_name** (Optional[str]) – Name to save the file.
- **metrics** (Dict[str, List]) – Dictionary containing all metrics.

## ml\_intuition.data.loggers module

Helper function logging data into MLFlow

`ml_intuition.data.loggers.log_dict_as_str_to_mlflow(dict_as_string)`

Log a string which represents a dictionary to MLflow

**Parameters** **dict\_as\_string** (str) – A string with dictionary format

**Return type** None

**Returns** None

`ml_intuition.data.loggers.log_metrics_to_mlflow(metrics, fair=False)`

Log provided metrics to mlflow

**Parameters**

- **metrics** (Dict[str, float]) – Metrics in a dictionary
- **fair** (bool) – Whether to add ‘\_fair’ suffix to the metrics name

**Return type** None**Returns** None

```
ml_intuition.data.loggers.log_params_to_mlflow(args)
```

Log provided arguments as dictionary to mlflow.

**Parameters** **args** (Dict) – Arguments to log**Return type** None

```
ml_intuition.data.loggers.log_tags_to_mlflow(run_name)
```

Log tags to mlflow based on provided args

**Parameters** **run\_name** (str) – Name of the current run**Return type** None**Returns** None**ml\_intuition.data.noise module**

```
class ml_intuition.data.noise.BaseNoise(params)
```

Bases: abc.ABC

**abstract** `__call__` (\*args, \*\*kwargs)

Each subclass should implement this method.

**Parameters**

- **args** – Arbitrary list of arguments.
- **kwargs** – Arbitrary dictionary of arguments.

**static** `get_proba` (n\_samples, prob)**Return type** int

```
class ml_intuition.data.noise.Gaussian(params)
```

Bases: `ml_intuition.data.noise.BaseNoise``__call__` (data, labels)

Perform Gaussian noise injection.

**Parameters**

- **data** (ndarray) – Input data that will undergo noise injection.
- **labels** (ndarray) – Class value for each data point.

**Return type** List[ndarray]**Returns** List containing the noisy data and the class labels.

```
class ml_intuition.data.noise.Impulsive(params)
```

Bases: `ml_intuition.data.noise.BaseNoise``__call__` (data, labels)

Perform impulsive noise injection.

**Parameters**

- **data** (ndarray) – Input data that will undergo noise injection.
- **labels** (ndarray) – Class value for each data point.

**Return type** List[ndarray]**Returns** List containing the noisy data and the class labels.

```
class ml_intuition.data.noise.Params (pa: float = None, pb: float = None, bc: bool = None,
                                     mean: float = None, std: float = None, pw: float =
                                     None)
```

Bases: tuple

Parameters of noise injection.

pa - Fraction of noisy pixels, the number of affected samples is calculated by: floor(n\_samples \* pa).

pb - Fraction of noisy bands. When established the number of samples that undergo noise injection, for each sample the: floor(n\_bands \* pb) bands are affected.

bc - Boolean indicating whether the indexes of affected bands are constant for each sample. When set to: False, different bands can be augmented with noise for each pixel.

mean - Gaussian noise parameter, the mean of the normal distribution.

std - Standard deviation of the normal distribution for Gaussian noise.

pw - Ratio of whitened pixels for the affected set of samples in the Impulsive noise injection.

Create new instance of Params(pa, pb, bc, mean, std, pw)

**property bc**

Alias for field number 2

**property mean**

Alias for field number 3

**property pa**

Alias for field number 0

**property pb**

Alias for field number 1

**property pw**

Alias for field number 5

**property std**

Alias for field number 4

```
class ml_intuition.data.noise.Shot (params)
```

Bases: *ml\_intuition.data.noise.BaseNoise***\_\_call\_\_** (data, labels)

Perform shot noise injection.

**Parameters**

- **data** (ndarray) – Input data that will undergo noise injection.
- **labels** (ndarray) – Class value for each data point.

**Return type** List[ndarray]**Returns** List containing the noisy data and the class labels.

`ml_intuition.data.noise.get_all_noise_functions` (*noise*)

Get all specified noise functions.

**Parameters** `noise` (`List[str]`) – List the of noise injection methods.

**Return type** `List`

**Returns** List of all noise injection functions.

`ml_intuition.data.noise.get_noise_functions` (*noise*, *noise\_params*)

Helper function for getting all noise injector instances.

**Parameters**

- **noise** (`List[str]`) – List the of noise injection methods.
- **noise\_params** (`str`) – Parameters of the noise injections.

**Return type** `List[BaseNoise]`

**Returns** List of instances of noise injectors functions.

`ml_intuition.data.noise.inject_noise` (*data\_source*, *affected\_subsets*, *noise\_injectors*,  
*noise\_params*)

Inject noise into given subsets.

**Parameters**

- **data\_source** (`Dict`) – Dictionary containing subsets.
- **affected\_subsets** (`List[str]`) – List of names of subsets that will undergo noise injection.
- **noise\_injectors** (`List[str]`) – List of names of noise injection methods.
- **noise\_params** (`str`) – Parameters of the noise injection.

## **ml\_intuition.data.preprocessing module**

All function related to the data preprocessing step of the pipeline.

`ml_intuition.data.preprocessing.align_ground_truth` (*cube\_2d\_shape*, *ground\_truth*,  
*cube\_to\_gt\_transform*)

Align original labels to match the satellite hyperspectral cube using transformation matrix

**Parameters**

- **cube\_2d\_shape** (`Tuple[int, int]`) – Shape of the hyperspectral data cube
- **ground\_truth** (`ndarray`) – Original labels as 2D array
- **cube\_to\_gt\_transform** (`ndarray`) – Cube to ground truth transformation matrix

**Return type** `ndarray`

**Returns** Transformed ground truth

`ml_intuition.data.preprocessing.get_padded_cube` (*data*, *padding\_size*)

Pad the cube with zeros

**Parameters**

- **data** (`ndarray`) – Data to pad
- **padding\_size** (`int`) – Size of the padding for each side

**Return type** `ndarray`

**Returns** Padded cube

`ml_intuition.data.preprocessing.normalize_labels(labels)`  
 Normalize labels so that they always start from 0

**Parameters** `labels` (ndarray) – labels to normalize

**Return type** ndarray

**Returns** Normalized labels

`ml_intuition.data.preprocessing.remove_nan_samples(data, labels)`  
 Remove samples which contain only nan values

**Parameters**

- **data** (ndarray) – Data with dimensions [SAMPLES, ...]
- **labels** (ndarray) – Corresponding labels

**Return type** Tuple[ndarray, ndarray]

**Returns** Data and labels with removed samples containing nans

`ml_intuition.data.preprocessing.reshape_cube_to_2d_samples(data, labels, channels_idx=0, use_unmixing=False)`

Reshape the data and labels from [CHANNELS, HEIGHT, WIDTH] to [PIXEL, CHANNELS, 1], so it fits the 2D Convolutional modules.

**Parameters**

- **data** (ndarray) – Data to reshape.
- **labels** (ndarray) – Corresponding labels.
- **channels\_idx** (int) – Index at which the channels are located in the provided data file.
- **use\_unmixing** (bool) – Boolean indicating whether to perform experiments on the unmixing datasets, where classes in each pixel are present as fractions.

**Returns** Reshape data and labels

**Return type** tuple with reshaped data and labels

`ml_intuition.data.preprocessing.reshape_cube_to_3d_samples(data, labels, neighborhood_size=5, background_label=0, channels_idx=0, use_unmixing=False)`

Reshape data to a array of dimensionality: [N\_SAMPLES, HEIGHT, WIDTH, CHANNELS] and the labels to dimensionality of: [N\_SAMPLES, N\_CLASSES]

**Parameters**

- **data** (ndarray) – Data passed as array.
- **labels** (ndarray) – Labels passed as array.
- **neighborhood\_size** (int) – Length of the spatial patch.
- **background\_label** (int) – Label to filter out the background.
- **channels\_idx** (int) – Index of the channels.

- **use\_unmixing** (bool) – Boolean indicating whether to perform experiments on the unmixing datasets, where classes in each pixel are present as abundances fractions.

**Return type** Tuple of data and labels reshaped to 3D format.

`ml_intuition.data.preprocessing.spectral_angle_mapper` (*data*, *endmembers*, *channel\_idx*)

Calculate the spectral angle mapper between the HSI pixels and endmembers.

**Parameters**

- **data** (ndarray) – Data cube.
- **endmembers** (ndarray) – The matrix containing the spectra for each class of dimensionality [n\_classes, n\_bands].
- **channel\_idx** (int) – Index of bands in HSI.

**Return type** Tuple[ndarray, ndarray]

**Returns** The tuple of both, normalized and unnormalized angle matrix for each pixel in HSI.

`ml_intuition.data.preprocessing.train_val_test_split` (*data*, *labels*, *train\_size=0.8*, *val\_size=0.1*, *stratified=True*, *seed=0*)

Split the data into train, val and test sets. The size of the training set is set by the *train\_size* parameter. All the remaining samples will be treated as a test set

**Parameters**

- **data** (ndarray) – Data with the [SAMPLES, ...] dimensions
- **labels** (ndarray) – Vector with corresponding labels
- **train\_size** (Union[List, float, int]) – If float, should be between 0.0 and 1.0, If *stratified* = True, it represents percentage of each class to be extracted. If float and *stratified* = False, it represents percentage of the whole dataset to be extracted with samples drawn randomly, regardless of their class. If int and *stratified* = True, it represents number of samples to be drawn from each class. If int and *stratified* = False, it represents overall number of samples to be drawn regardless of their class, randomly. Defaults to 0.8
- **val\_size** (float) – Should be between 0.0 and 1.0. Represents the percentage of each class from the training set to be extracted as a validation set, defaults to 0.1
- **stratified** (bool) – Indicated whether the extracted training set should be stratified, defaults to True
- **seed** (int) – Seed used for data shuffling

**Return type** Tuple[ndarray, ndarray, ndarray, ndarray, ndarray, ndarray]

**Returns** train\_x, train\_y, val\_x, val\_y, test\_x, test\_y

**Raises** **AssertionError** – When wrong type is passed as *train\_size*

**ml\_intuition.data.transforms module**

Module containing all the transformations that can be done on a dataset.

**class** ml\_intuition.data.transforms.**BaseTransform**

Bases: abc.ABC

**abstract** `__call__` (\*args, \*\*kwargs)

Each subclass should implement this method.

**Parameters**

- **args** – Arbitrary list of arguments.
- **kwargs** – Arbitrary dictionary of arguments.

**class** ml\_intuition.data.transforms.**ExtractCentralPixelSpectrumTransform**(neighborhood\_size)

Bases: ml\_intuition.data.transforms.BaseTransform

Extract central pixel from each spatial sample.

**Parameters** **neighborhood\_size** (int) – The spatial size of the patch.

`__call__` (samples, labels)

” Transform the labels for unsupervised unmixing problem. The label is the central pixel of each sample patch.

**Parameters**

- **samples** (ndarray) – Input samples.
- **labels** (ndarray) – Central pixel of each sample.

**Return type** List[ndarray]

**Returns** List containing the input samples and its targets as central pixel.

**class** ml\_intuition.data.transforms.**MinMaxNormalize**(min\_, max\_)

Bases: ml\_intuition.data.transforms.BaseTransform

Normalize each sample.

**Parameters**

- **min** – Minimum value of features.
- **max** – Maximum value of features.

`__call__` (samples, labels)

” Perform min-max normalization on the passed samples.

**Parameters**

- **samples** (ndarray) – Input samples that will undergo normalization.
- **labels** (ndarray) – Class values for each sample.

**Return type** List[ndarray]

**Returns** List containing the normalized samples and the class labels.

**class** ml\_intuition.data.transforms.**OneHotEncode**(n\_classes)

Bases: ml\_intuition.data.transforms.BaseTransform

Initializer of the one-hot encoding transformation.

**Parameters** **n\_classes** (int) – Number of classes.

**\_\_call\_\_** (*samples, labels*)

Perform one-hot encoding on the passed labels.

**Parameters**

- **samples** (ndarray) – Input samples.
- **labels** (ndarray) – Class values for each sample that will undergo one-hot encoding.

**Return type** List[ndarray]

**Returns** List containing the samples and the one-hot encoded class labels.

**class** `ml_intuition.data.transforms.PerBandMinMaxNormalization` (*min\_, max\_*)

Bases: `ml_intuition.data.transforms.BaseTransform`

**SPECTRAL\_DIM** = -1

**\_\_call\_\_** (*samples, labels*)

Perform per-band min-max normalization. Each band is treated as a separate feature.

**Parameters**

- **samples** (ndarray) – Input samples that will undergo transformation.
- **labels** (ndarray) – Abundance vectors for each sample.

**Return type** List[ndarray]

**Returns** List containing the normalized samples and the abundance vectors.

**static** **get\_min\_max\_vectors** (*data\_cube*)

Get the min-max vectors for each spectral band.

**Parameters** **data\_cube** (ndarray) – Hyperspectral data cube, with bands in the last dimension and spatial features in the first two dimensions.

**Return type** Dict[str, ndarray]

**Returns** Dictionary containing the min as well as the max vectors for each band.

**class** `ml_intuition.data.transforms.RNNSpectralInputTransform`

Bases: `ml_intuition.data.transforms.BaseTransform`

**\_\_call\_\_** (*samples, labels*)

” Transform the input samples to fit the recurrent neural network (RNN) input. This is performed for the pixel-based model; the input sample includes only spectral bands.

**Parameters**

- **samples** (ndarray) – Input samples that will undergo the transformation.
- **labels** (ndarray) – Class values for each sample.

**Return type** List[ndarray]

**Returns** List containing the normalized samples and the class labels.

**class** `ml_intuition.data.transforms.SpectralTransform` (*\*\*kwargs*)

Bases: `ml_intuition.data.transforms.BaseTransform`

Initializer of the spectral transformation.

**\_\_call\_\_** (*samples, labels*)

Transform 1D samples along the spectral axis. Only the spectral features are present for each sample in the dataset.

**Parameters**



- **samples** (ndarray) – Input samples that will undergo transformation.
- **labels** (ndarray) – Class value for each samples.

**Return type** List[ndarray]

**Returns** List containing the transformed samples and the class labels.

`ml_intuition.data.transforms.apply_transformations(data, transformations)`  
Apply each transformation from provided list

**Parameters**

- **data** (Dict) – Dictionary with ‘data’ and ‘labels’ keys holding np.ndarrays
- **transformations** (List[BaseTransform]) – List of transformations

**Return type** Dict

**Returns** Transformed data, in the same format as input

## Module contents

### 2.1.2 Submodules

#### 2.1.3 ml\_intuition.models module

All models that are used in the project.

**class** `ml_intuition.models.Ensemble` (*models=None, voting='hard'*)  
Bases: object

Ensemble for using multiple models for prediction

**Parameters**

- **models** (Union[List[Sequential], List[str], Sequential, None]) – Either list of tf.keras.models.Sequential models, or a list of paths to the models (can’t mix both).
- **voting** (str) – If ‘hard’, uses predicted class labels for majority rule voting. Else if ‘soft’, predicts the class label based on the argmax of the sums of the predicted probabilities. If ‘classifier’, a Random Forest trained on train set predictions is used as a voter.

**generate\_models\_with\_noise** (*copies=5, mean=None, std=None, seed=None*)  
Generate new models by injecting Gaussian noise into the original model’s weights.

**Parameters**

- **copies** (int) – Number of models to generate
- **mean** (Optional[float]) – Mean used to draw noise from normal distribution. If None, it will be calculated from the layer itself.
- **std** (Optional[float]) – Standard deviation used to draw noise from normal distribution. If None, it will be calculated from the layer itself.
- **seed** – Seed for random number generator.

**Return type** None

**Returns** None

**static inject\_noise\_to\_weights** (*weights, mean, std*)  
Inject noise into all layers

**Parameters**

- **weights** (`List[ndarray]`) – List of weights for each layer
- **mean** (`float`) – Mean used to draw noise from normal distribution.
- **std** (`float`) – Std used to draw noise from normal distribution.

**Return type** `List[ndarray]`

**Returns** Modified list of weights

**predict** (*data*, *batch\_size=1024*)

Return predicted classes

**Parameters**

- **data** (`Union[ndarray, List[ndarray]]`) – Either a single dataset which will be fed into all of the models, or a list of datasets, unique for each model
- **batch\_size** (`int`) – Size of the batch used for prediction

**Return type** `ndarray`

**Returns** Predicted classes

**predict\_probabilities** (*data*, *batch\_size=1024*)

Return predicted classes

**Parameters**

- **data** (`Union[ndarray, List[ndarray]]`) – Either a single dataset which will be fed into all of the models, or a list of datasets, unique for each model
- **batch\_size** (`int`) – Size of the batch used for prediction

**Return type** `ndarray`

**Returns** Predicted probabilities for each model and class. Shape: [Models, Samples, Classes]

**train\_ensemble\_predictor** (*data*, *labels*)

Train the Random Forest on train set predictions

**Parameters**

- **data** (`ndarray`) – Predictions of the models on training set
- **labels** (`ndarray`) – Corresponding labels

**Return type** `None`

**vote** (*predictions*)

Perform voting process on provided predictions

**Parameters** **predictions** (`ndarray`) – Predictions of all models

**Return type** `ndarray`

**Returns** Predicted classes

`ml_intuition.models.model_2d` (*kernel\_size*, *n\_kernels*, *n\_layers*, *input\_size*, *n\_classes*, *\*\*kwargs*)

2D model which consists of 2D convolutional blocks.

**Parameters**

- **kernel\_size** (`int`) – Size of the convolutional kernel.
- **n\_kernels** (`int`) – Number of kernels, i.e., the activation maps in each layer.

- **n\_layers** (int) – Number of layers in the network.
- **input\_size** (int) – Number of input channels, i.e., the number of spectral bands.
- **n\_classes** (int) – Number of classes.
- **kwargs** – Additional arguments.

**Return type** Sequential

**Returns** Compiled model ready for training

`ml_intuition.models.model_3d_deep(n_classes, input_size, **kwargs)`

Deep 3D convolutional model from: <https://arxiv.org/pdf/1907.11935.pdf>

**Parameters**

- **n\_classes** (int) – Number of classes in the dataset
- **input\_size** (int) – Size of the input sample
- **kwargs** – Additional arguments.

**Return type** Sequential

**Returns** Compiled model ready for training

`ml_intuition.models.model_3d_mfl(kernel_size, n_kernels, n_classes, input_size, **kwargs)`

Multiple Features Learning model from: <https://ieeexplore.ieee.org/document/6882821/figures#figures>

**Parameters**

- **kernel\_size** (int) – Size of the convolutional kernel
- **n\_kernels** (int) – Number of kernels in each convolutional layer
- **n\_classes** (int) – Number of classes in the dataset
- **input\_size** (int) – Size of the input sample
- **kwargs** – Additional arguments.

**Return type** Sequential

**Returns** Compiled model ready for training

`ml_intuition.models.pool_model_2d(kernel_size, n_kernels, n_layers, input_size, n_classes, **kwargs)`

2D model which consists of 2D convolutional layers and 2D pooling layers.

**Parameters**

- **kernel\_size** (int) – Size of the convolutional kernel.
- **n\_kernels** (int) – Number of kernels, i.e., the activation maps in each layer.
- **n\_layers** (int) – Number of layers in the network.
- **input\_size** (int) – Number of input channels, i.e., the number of spectral bands.
- **n\_classes** (int) – Number of classes.
- **kwargs** – Additional arguments.

**Return type** Sequential

**Returns** Compiled model ready for training

`ml_intuition.models.unmixing_cube_based_cnn(n_classes, input_size, **kwargs)`

Model for cube-based supervised hyperspectral unmixing proposed in the following publication (Chicago style citation):

Zhang, Xiangrong, Yujia Sun, Jingyan Zhang, Peng Wu, and Licheng Jiao. “Hyperspectral unmixing via deep convolutional neural networks.” *IEEE Geoscience and Remote Sensing Letters* 15, no. 11 (2018): 1755-1759.

**Parameters**

- **n\_classes** (`int`) – Number of classes.
- **input\_size** (`int`) – Number of input spectral bands.
- **kwargs** – Additional arguments.

**Return type** `Sequential`

**Returns** Model proposed in the publication listed above.

`ml_intuition.models.unmixing_cube_based_dcae(n_classes, input_size, **kwargs)`

Model for cube-based unsupervised hyperspectral unmixing proposed in the following publication (Chicago style citation):

Khajehrayeni, Farshid, and Hassan Ghassemian. “Hyperspectral unmixing using deep convolutional autoencoders in a supervised scenario.” *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing* 13 (2020): 567-576.

**Parameters**

- **n\_classes** (`int`) – Number of classes.
- **input\_size** (`int`) – Number of input spectral bands.
- **kwargs** – Additional arguments.

**Return type** `Sequential`

**Returns** Model proposed in the publication listed above.

`ml_intuition.models.unmixing_pixel_based_cnn(n_classes, input_size, **kwargs)`

Model for pixel-based supervised hyperspectral unmixing proposed in the following publication (Chicago style citation):

Zhang, Xiangrong, Yujia Sun, Jingyan Zhang, Peng Wu, and Licheng Jiao. “Hyperspectral unmixing via deep convolutional neural networks.” *IEEE Geoscience and Remote Sensing Letters* 15, no. 11 (2018): 1755-1759.

**Parameters**

- **n\_classes** (`int`) – Number of classes.
- **input\_size** (`int`) – Number of input spectral bands.
- **kwargs** – Additional arguments.

**Return type** `Sequential`

**Returns** Model proposed in the publication listed above.

`ml_intuition.models.unmixing_pixel_based_dcae(n_classes, input_size, **kwargs)`

Model for pixel-based unsupervised hyperspectral unmixing proposed in the following publication (Chicago style citation):

Khajehrayeni, Farshid, and Hassan Ghassemian. “Hyperspectral unmixing using deep convolutional autoencoders in a supervised scenario.” *IEEE Journal of Selected Topics in Applied Earth Observations and Remote Sensing* 13 (2020): 567-576.

**Parameters**

- **n\_classes** (int) – Number of classes.
- **input\_size** (int) – Number of input spectral bands.
- **kwargs** – Additional arguments.

**Return type** Sequential

**Returns** Model proposed in the publication listed above.

`ml_intuition.models.unmixing_rnn_supervised(n_classes, **kwargs)`

Model for the unmixing which utilizes a recurrent neural network (RNN) for extracting valuable information from the spectral domain in an supervised manner.

**Parameters**

- **n\_classes** (int) – Number of classes.
- **kwargs** – Additional arguments.

**Return type** Sequential

**Returns** RNN model instance.

## 2.1.4 Module contents

## 2.2 scripts package

### 2.2.1 Subpackages

scripts.ensemble package

Submodules

scripts.ensemble.ensemble\_runner module

Run N experiments utilizing the ensemble model.

```
scripts.ensemble.ensemble_runner.run_experiments(*, data_file_paths, train_size,
                                                    val_size=0.1, stratified=True,
                                                    background_label=0, channels_idx=0, neighborhood_sizes,
                                                    save_data=False, n_runs,
                                                    dest_path, model_paths,
                                                    model_experiment_names,
                                                    n_classes, voting='hard',
                                                    batch_size=1024, post_noise_sets,
                                                    post_noise, noise_params=None,
                                                    use_mlflow=False, experiment_name=None,
                                                    run_name=None)
```

Function for running experiments given a set of hyper parameters.

**Parameters**

- **data\_file\_paths** (list[str]) – Path to the data file. Supported types are: .npy

- **train\_size** (*Union[int, float]*) – If float, should be between 0.0 and 1.0. If stratified = True, it represents percentage of each class to be extracted, If float and stratified = False, it represents percentage of the whole dataset to be extracted with samples drawn randomly, regardless of their class. If int and stratified = True, it represents number of samples to be drawn from each class. If int and stratified = False, it represents overall number of samples to be drawn regardless of their class, randomly. Defaults to 0.8
- **val\_size** (*float*) – Should be between 0.0 and 1.0. Represents the percentage of each class from the training set to be extracted as a validation set, defaults to 0.1
- **stratified** (*bool*) – Indicated whether the extracted training set should be stratified, defaults to True
- **background\_label** (*int*) – Label indicating the background in GT file
- **channels\_idx** (*int*) – Index specifying the channels position in the provided data
- **neighborhood\_sizes** (*list[str]*) – Sizes of the neighbourhood of each provided model
- **save\_data** (*bool*) – Whether to save the prepared dataset
- **n\_runs** (*int*) – Number of total experiment runs.
- **dest\_path** (*str*) – Path to where all experiment runs will be saved as subfolders in this directory.
- **model\_paths** (*list[str]*) – Paths to all models to be used in ensemble
- **model\_experiment\_names** (*list[str]*) – Names of MLFlow experiments
- **n\_classes** (*int*) – Number of classes.
- **voting** (*str*) – Method of ensemble voting. If ‘hard’, uses predicted class labels for majority rule voting. Else if ‘soft’, predicts the class label based on the argmax of the sums of the predicted probabilities.
- **batch\_size** (*int*) – Size of the batch for the inference
- **post\_noise\_sets** (*list[str]*) – The list of sets to which the noise will be injected. One element can either be “train”, “val” or “test”.
- **post\_noise** (*list[str]*) – The list of names of noise injection methods after the normalization transformations.
- **noise\_params** (*Optional[str]*) – JSON containing the parameter setting of injection methods. Exemplary value for this parameter: “{“mean”: 0, “std”: 1, “pa”: 0.1}”. This JSON should include all parameters for noise injection functions that are specified in pre\_noise and post\_noise arguments. For the accurate description of each parameter, please refer to the ml\_intuition/data/noise.py module.
- **use\_mlflow** (*bool*) – Whether to log metrics and artifacts to mlflow.
- **experiment\_name** (*Optional[str]*) – Name of the experiment. Used only if use\_mlflow = True
- **run\_name** (*Optional[str]*) – Name of the run. Used only if use\_mlflow = True.

## scripts.ensemble.evaluate\_with\_ensemble module

Evaluate a dataset using an ensemble.

```
scripts.ensemble.evaluate_with_ensemble.evaluate(*, y_pred, data, dest_path,
                                                model_path, voting='hard')
```

Function for evaluating the trained model.

### Parameters

- **y\_pred** – Predictions of all the models to be provided into an ensemble to vote
- **data** – Either path to the input data or the data dict.
- **dest\_path** (str) – Directory in which to store the calculated metrics
- **model\_path** (str) – Path to the model.
- **voting** (str) – Method of ensemble voting. If 'hard', uses predicted class labels for majority rule voting. Else if 'soft', predicts the class label based on the argmax of the sums of the predicted probabilities.

## Module contents

### scripts.unmixing package

#### Submodules

## scripts.unmixing.evaluate\_unmixing module

Perform the inference of the unmixing models on the test dataset.

```
scripts.unmixing.evaluate_unmixing.evaluate(data, model_path, dest_path, neighbor-
                                                hood_size, batch_size, endmembers_path)
```

Function for evaluating the trained model for the unmixing problem.

### Parameters

- **model\_path** (str) – Path to the model.
- **data** – The data dictionary containing the subset for testing.
- **dest\_path** (str) – Directory in which to store the calculated metrics.
- **neighborhood\_size** (int) – Size of the spatial patch.
- **batch\_size** (int) – Size of the batch for inference.
- **endmembers\_path** (str) – Path to the endmembers matrix file, containing the average reflectances for each endmember, i.e., the pure spectra.

### scripts.unmixing.train\_unmixing module

Perform the training of the models for the unmixing problem.

```
scripts.unmixing.train_unmixing.train(data, model_name, dest_path, sample_size, n_classes,  
                                         neighborhood_size, lr, batch_size, epochs, verbose,  
                                         shuffle, patience, endmembers_path, seed)
```

Function for running experiments on various unmixing models, given a set of hyper parameters.

#### Parameters

- **data** (Dict[str, ndarray]) – The data dictionary containing the subsets for training and validation. First dimension of the dataset should be the number of samples.
- **model\_name** (str) – Name of the model, it serves as a key in the dictionary holding all functions returning models.
- **dest\_path** (str) – Path to where all experiment runs will be saved as subdirectories in this given directory.
- **sample\_size** (int) – Size of the input sample.
- **n\_classes** (int) – Number of classes.
- **neighborhood\_size** (int) – Size of the spatial patch.
- **lr** (float) – Learning rate for the model, i.e., regulates the size of the step in the gradient descent process.
- **batch\_size** (int) – Size of the batch used in training phase, it is the size of samples per gradient step.
- **epochs** (int) – Number of epochs for model to train.
- **verbose** (int) – Verbosity mode used in training, (0, 1 or 2).
- **shuffle** (bool) – Boolean indicating whether to shuffle dataset.
- **patience** (int) – Number of epochs without improvement in order to stop the training phase.
- **endmembers\_path** (str) – Path to the endmembers matrix file, containing the average reflectances for each endmember, i.e., the pure spectra.
- **seed** (int) – Seed for training reproducibility.

### scripts.unmixing.unmixing\_experiments\_runner module

Run experiments given set of hyperparameters for the unmixing problem.



```
scripts.unmixing.unmixing_experiments_runner.run_experiments(*, data_file_path,
                                                                ground_truth_path=None,
                                                                train_size,
                                                                val_size=0.1,
                                                                sub_test_size=None,
                                                                channels_idx=-
                                                                1,      neighbor-
                                                                hood_size=None,
                                                                n_runs=1,
                                                                model_name,
                                                                save_data=0,
                                                                dest_path=None,
                                                                sample_size,
                                                                n_classes,
                                                                lr=None,
                                                                batch_size=256,
                                                                epochs=100,
                                                                verbose=2,
                                                                shuffle=True,
                                                                patience=15,
                                                                use_mlflow=False,
                                                                endmem-
                                                                bers_path=None,
                                                                experi-
                                                                ment_name=None,
                                                                run_name=None)
```

Function for running experiments on unmixing given a set of hyperparameters.

#### Parameters

- **data\_file\_path** (str) – Path to the data file. Supported types are: .npy.
- **ground\_truth\_path** (Optional[str]) – Path to the ground-truth data file.
- **train\_size** (Union[int, float]) – If float, should be between 0.0 and 1.0. If int, specifies the number of samples in the training set. Defaults to 0.8
- **val\_size** (float) – Should be between 0.0 and 1.0. Represents the percentage of samples from the training set to be extracted as a validation set. Defaults to 0.1.
- **sub\_test\_size** (Optional[int]) – Number of pixels to subsample the test set instead of performing the inference on all samples that are not in the training set.
- **channels\_idx** (int) – Index specifying the channels position in the provided data.
- **neighborhood\_size** (Optional[int]) – Size of the spatial patch.
- **save\_data** (bool) – Boolean indicating whether to save the prepared dataset.
- **n\_runs** (int) – Number of total experiment runs.
- **model\_name** (str) – Name of the model, it serves as a key in the dictionary holding all functions returning models.
- **dest\_path** (Optional[str]) – Path to where all experiment runs will be saved as sub-directories in this directory.
- **sample\_size** (int) – Size of the input sample.
- **n\_classes** (int) – Number of classes.

- **lr** (Optional[float]) – Learning rate for the model, i.e., regulates the size of the step in the gradient descent process.
- **batch\_size** (int) – Size of the batch used in training phase, it is the size of samples per gradient step.
- **epochs** (int) – Number of epochs for model to train.
- **verbose** (int) – Verbosity mode used in training, (0, 1 or 2).
- **shuffle** (bool) – Boolean indicating whether to shuffle dataset.
- **patience** (int) – Number of epochs without improvement in order to stop the training phase.
- **use\_mlflow** (bool) – Whether to log metrics and artifacts to mlflow.
- **endmembers\_path** (Optional[str]) – Path to the endmembers matrix file, containing the average reflectances for each endmember, i.e., the pure spectra.
- **experiment\_name** (Optional[str]) – Name of the experiment. Used only if use\_mlflow = True
- **run\_name** (Optional[str]) – Name of the run. Used only if use\_mlflow = True.

## Module contents

### scripts.quantization package

#### Submodules

#### scripts.quantization.freeze\_model module

Freeze the graph and store it in .pb (Protocol Buffers) format

```
scripts.quantization.freeze_model.main(*, model_path, output_dir)
```

Freeze the graph and store it in .pb (Protocol Buffers) format

##### Parameters

- **model\_path** (str) – Path to the model to be saved
- **output\_dir** (str) – Directory in which the .pb graph and nodes json will be stored

#### scripts.quantization.quantize\_runner module

Freeze model, quantize it and evaluate N times.

```
scripts.quantization.quantize_runner.run_experiments(*, input_dir, n_runs, dest_path,  
                                                    data_file_path=None,  
                                                    ground_truth_path=None,  
                                                    dataset_path=None,  
                                                    background_label=0,  
                                                    channels_idx=2,          chan-  
                                                    nels_count=103,      train_size,  
                                                    batch_size=64, stratified=True,  
                                                    gpu=0)
```

Freeze model, quantize it and evaluate N times.

**Parameters**

- **input\_dir** (`str`) – Directory with saved data and models, each in separate *experiment\_n* folder.
- **n\_runs** (`int`) – Number of total experiment runs.
- **dest\_path** (`str`) – Path to where all experiment runs will be saved as sub folders in this directory.
- **data\_file\_path** (`Optional[str]`) – Path to the data file. Supported types are: `.npz` and `.md5`. This is optional, if the data is not already saved in the `input_dir`.
- **ground\_truth\_path** (`Optional[str]`) – Path to the data file.
- **dataset\_path** (`Optional[str]`) – Path to the already extracted `.h5` dataset
- **background\_label** (`int`) – Label indicating the background in GT file
- **channels\_idx** (`int`) – Index specifying the channels position in the provided data
- **channels\_count** (`int`) – Number of channels (bands) in the image.
- **train\_size** (`Union[int, float]`) – If float, should be between 0.0 and 1.0. If `stratified = True`, it represents percentage of each class to be extracted, If float and `stratified = False`, it represents percentage of the whole dataset to be extracted with samples drawn randomly, regardless of their class. If `int` and `stratified = True`, it represents number of samples to be drawn from each class. If `int` and `stratified = False`, it represents overall number of samples to be drawn regardless of their class, randomly. Defaults to 0.8
- **stratified** (`bool`) – Indicated whether the extracted training set should be stratified, defaults to `True`
- **batch\_size** (`int`) – Batch size
- **gpu** (`bool`) – Whether to run quantization on gpu.

**Module contents****2.2.2 Submodules****2.2.3 scripts.artifacts\_reporter module**

Collect the artifacts report based on the experiment runs placed in the “experiments\_path” directory.

```
scripts.artifacts_reporter.collect_artifacts_report(*, experiments_path,
                                                    dest_path,      filename=None,
                                                    use_mlflow=False)
```

Collect the artifacts report based on the experiment runs placed in the “experiments\_path” directory.

**Parameters**

- **experiments\_path** (`str`) – Path to the directory containing the experiment subdirectories.
- **dest\_path** (`str`) – Path to the destination directory or full path to the report `.csv` file.
- **filename** (`Optional[str]`) – Name of the file holding metrics. Defaults to ‘`inference_metrics.csv`’.
- **use\_mlflow** (`bool`) – Whether to log metrics and artifacts to mlflow.

## 2.2.4 scripts.evaluate\_model module

Perform the inference of the model on the provided dataset.

```
scripts.evaluate_model.evaluate(*, data, model_path, dest_path, n_classes, batch_size=1024,
                                use_ensemble=False, ensemble_copies=1, voting='hard',
                                noise, noise_sets, noise_params=None, seed=0)
```

Function for evaluating the trained model.

### Parameters

- **model\_path** (str) – Path to the model.
- **data** – Either path to the input data or the data dict.
- **dest\_path** (str) – Directory in which to store the calculated metrics.
- **n\_classes** (int) – Number of classes.
- **batch\_size** (int) – Size of the batch for inference.
- **use\_ensemble** (bool) – Use ensemble for prediction.
- **ensemble\_copies** (int) – Number of model copies for the ensemble.
- **voting** (str) – Method of ensemble voting. If ‘hard’, uses predicted class labels for majority rule voting. Else if ‘soft’, predicts the class label based on the argmax of the sums of the predicted probabilities.
- **noise** (list[str]) – List containing names of used noise injection methods that are performed after the normalization transformations.
- **noise\_sets** (list[str]) – List of sets that are affected by the noise injection. For this module single element can be “test”.
- **noise\_params** (Optional[str]) – JSON containing the parameters setting of noise injection methods. Exemplary value for this parameter: “{“mean”: 0, “std”: 1, “pa”: 0.1}”. This JSON should include all parameters for noise injection functions that are specified in the noise argument. For the accurate description of each parameter, please refer to the `ml_intuition/data/noise.py` module.
- **seed** (int) – Seed for RNG.

## 2.2.5 scripts.experiments\_runner module

Run training and evaluation of a model N times, given set of hyperparameters. Has the option to inject noise into train, val and test set.

```
scripts.experiments_runner.run_experiments(*, data_file_path, ground_truth_path=None,
                                             train_size, val_size=0.1, stratified=True,
                                             background_label=0, channels_idx=0,
                                             neighborhood_size=None, n_runs,
                                             model_name, kernel_size=5, n_kernels=200,
                                             save_data=0, n_layers=1, dest_path=None,
                                             sample_size, n_classes, lr=0.001,
                                             batch_size=128, epochs=200, verbose=2,
                                             shuffle=True, patience=15, pre_noise,
                                             pre_noise_sets, post_noise, post_noise_sets,
                                             noise_params=None, use_mlflow=False,
                                             experiment_name=None, run_name=None)
```

Function for running experiments given a set of hyper parameters.

## Parameters

- **data\_file\_path** (*str*) – Path to the data file. Supported types are: `.npy`.
- **ground\_truth\_path** (*Optional[str]*) – Path to the ground-truth data file.
- **train\_size** (*Union[int, float]*) – If float, should be between 0.0 and 1.0. If `stratified = True`, it represents percentage of each class to be extracted. If float and `stratified = False`, it represents percentage of the whole dataset to be extracted with samples drawn randomly, regardless of their class. If int and `stratified = True`, it represents number of samples to be drawn from each class. If int and `stratified = False`, it represents overall number of samples to be drawn regardless of their class, randomly. Defaults to 0.8.
- **val\_size** (*float*) – Should be between 0.0 and 1.0. Represents the percentage of each class from the training set to be extracted as a validation set. Defaults to 0.1.
- **stratified** (*bool*) – Indicated whether the extracted training set should be stratified. Defaults to `True`.
- **background\_label** (*int*) – Label indicating the background in GT file.
- **channels\_idx** (*int*) – Index specifying the channels position in the provided data.
- **neighborhood\_size** (*Optional[int]*) – Size of the spatial patch.
- **save\_data** (*bool*) – Whether to save the prepared dataset.
- **n\_runs** (*int*) – Number of total experiment runs.
- **model\_name** (*str*) – Name of the model, it serves as a key in the dictionary holding all functions returning models.
- **kernel\_size** (*int*) – Size of each kernel in each layer.
- **n\_kernels** (*int*) – Number of kernels in each layer.
- **n\_layers** (*int*) – Number of layers in the model.
- **dest\_path** (*Optional[str]*) – Path to where all experiment runs will be saved as sub-folders in this directory.
- **sample\_size** (*int*) – Size of the input sample.
- **n\_classes** (*int*) – Number of classes.
- **lr** (*float*) – Learning rate for the model, i.e., regulates the size of the step in the gradient descent process.
- **batch\_size** (*int*) – Size of the batch used in training phase, it is the size of samples per gradient step.
- **epochs** (*int*) – Number of epochs for model to train.
- **verbose** (*int*) – Verbosity mode used in training, (0, 1 or 2).
- **shuffle** (*bool*) – Boolean indicating whether to shuffle dataset `dataset_key` each epoch.
- **patience** (*int*) – Number of epochs without improvement in order to stop the training phase.
- **pre\_noise** (*list[str]*) – The list of names of noise injection methods before the normalization transformations. Exemplary names are “gaussian” or “impulsive”.
- **pre\_noise\_sets** (*list[str]*) – The list of sets to which the noise will be injected. One element can either be “train”, “val” or “test”.

- **post\_noise** (*list[str]*) – The list of names of noise injection methods after the normalization transformations.
- **post\_noise\_sets** (*list[str]*) – The list of sets to which the noise will be injected.
- **noise\_params** (*Optional[str]*) – JSON containing the parameter setting of injection methods. Exemplary value for this parameter: “{“mean”: 0, “std”: 1, “pa”: 0.1}”. This JSON should include all parameters for noise injection functions that are specified in `pre_noise` and `post_noise` arguments. For the accurate description of each parameter, please refer to the `ml_intuition/data/noise.py` module.
- **use\_mlflow** (*bool*) – Whether to log metrics and artifacts to mlflow.
- **experiment\_name** (*Optional[str]*) – Name of the experiment. Used only if `use_mlflow = True`
- **run\_name** (*Optional[str]*) – Name of the run. Used only if `use_mlflow = True`.

## 2.2.6 scripts.inference\_runner module

Run inference N times on the provided model given set of hyperparameters. Has the option to inject noise into the test set.

```
scripts.inference_runner.run_experiments(*,
                                         data_file_path=None,
                                         ground_truth_path=None, dataset_path=None,
                                         train_size, val_size=0.1, stratified=True, back-
                                         ground_label=0, channels_idx=0, neigh-
                                         borhood_size=None, save_data=False,
                                         n_runs, dest_path, models_path,
                                         model_name='model_2d', n_classes,
                                         use_ensemble=False, ensemble_copies=None,
                                         voting='hard', batch_size=1024, post_noise_sets,
                                         post_noise, noise_params=None,
                                         use_mlflow=False, experiment_name=None,
                                         run_name=None)
```

Run inference on the provided model given set of hyperparameters.

### Parameters

- **data\_file\_path** (*Optional[str]*) – Path to the data file. Supported types are: `.npy`
- **ground\_truth\_path** (*Optional[str]*) – Path to the ground-truth data file.
- **dataset\_path** (*Optional[str]*) – Path to the already extracted `.h5` dataset
- **train\_size** (*Union[int, float]*) – If `float`, should be between 0.0 and 1.0. If `stratified = True`, it represents percentage of each class to be extracted, If `float` and `stratified = False`, it represents percentage of the whole dataset to be extracted with samples drawn randomly, regardless of their class. If `int` and `stratified = True`, it represents number of samples to be drawn from each class. If `int` and `stratified = False`, it represents overall number of samples to be drawn regardless of their class, randomly. Defaults to 0.8
- **val\_size** (*float*) – Should be between 0.0 and 1.0. Represents the percentage of each class from the training set to be extracted as a validation set. Defaults to 0.1.
- **stratified** (*bool*) – Indicated whether the extracted training set should be stratified. Defaults to `True`.
- **background\_label** (*int*) – Label indicating the background in GT file.
- **channels\_idx** (*int*) – Index specifying the channels position in the provided data.

- **neighborhood\_size** (Optional[int]) – Size of the neighborhood of the pixel. Only used for 2D and 3D models.
- **save\_data** (bool) – Whether to save the prepared dataset.
- **n\_runs** (int) – Number of total experiment runs.
- **dest\_path** (str) – Path to where all experiment runs will be saved as subfolders in this directory.
- **models\_path** (str) – Name of the model, it serves as a key in the dictionary holding all functions returning models.
- **model\_name** (str) – The name of model for the inference.
- **n\_classes** (int) – Number of classes.
- **use\_ensemble** (bool) – Use ensemble for prediction.
- **ensemble\_copies** (Optional[int]) – Number of model copies for the ensemble.
- **voting** (str) – Method of ensemble voting. If ‘hard’, uses predicted class labels for majority rule voting. Else if ‘soft’, predicts the class label based on the argmax of the sums of the predicted probabilities.
- **batch\_size** (int) – Size of the batch for the inference
- **post\_noise\_sets** (list[str]) – The list of sets to which the noise will be injected. One element can either be “train”, “val” or “test”.
- **post\_noise** (list[str]) – The list of names of noise injection methods after the normalization transformations.
- **noise\_params** (Optional[str]) – JSON containing the parameter setting of injection methods. Exemplary value for this parameter: “{“mean”: 0, “std”: 1, “pa”: 0.1}”. This JSON should include all parameters for noise injection functions that are specified in `pre_noise` and `post_noise` arguments. For the accurate description of each parameter, please refer to the `ml_intuition/data/noise.py` module.
- **use\_mlflow** (bool) – Whether to log metrics and artifacts to mlflow.
- **experiment\_name** (Optional[str]) – Name of the experiment. Used only if `use_mlflow = True`.
- **run\_name** (Optional[str]) – Name of the run. Used only if `use_mlflow = True`.

## 2.2.7 scripts.predict\_with\_model module

Perform the inference of the model on the provided dataset.

```
scripts.predict_with_model.predict(*, data, model_path, n_classes, batch_size=1024, noise,
                                   noise_sets, noise_params=None)
```

Function for evaluating the trained model.

### Parameters

- **data** – Either path to the input data or the data dict.
- **model\_path** (str) – Path to the model.
- **n\_classes** (int) – Number of classes.
- **batch\_size** (int) – Size of the batch for inference.

- **noise** (*list[str]*) – List containing names of used noise injection methods that are performed after the normalization transformations.
- **noise\_sets** (*list[str]*) – List of sets that are affected by the noise injection. For this module single element can be “test”.
- **noise\_params** (*Optional[str]*) – JSON containing the parameters setting of noise injection methods. Exemplary value for this parameter: “{“mean”: 0, “std”: 1, “pa”: 0.1}”. This JSON should include all parameters for noise injection functions that are specified in the noise argument. For the accurate description of each parameter, please refer to the `ml_intuition/data/noise.py` module.

## 2.2.8 scripts.prepare\_data module

Load the data, reformat it to have [SAMPLES, ...] dimensions, split it into train, test and val sets and save them in .h5 file with ‘train’, ‘val’ and ‘test’ groups, each having ‘data’ and ‘labels’ keys.

```
scripts.prepare_data.main(*, data_file_path, ground_truth_path, output_path=None, train_size,
                           val_size=0.1, stratified=True, background_label=0, neighbor-
                           hood_size=None, channels_idx=0, save_data=False, seed=0,
                           use_unmixing=False)
```

### Parameters

- **data\_file\_path** (*str*) – Path to the data file. Supported types are: .npy.
- **ground\_truth\_path** (*str*) – Path to the data file.
- **output\_path** (*Optional[str]*) – Path under in which the output .h5 file will be stored. Used only if the parameter `save_data` is set to `True`.
- **train\_size** (*float or int*) – If float, should be between 0.0 and 1.0. If `stratified = True`, it represents percentage of each class to be extracted, If float and `stratified = False`, it represents percentage of the whole dataset to be extracted with samples drawn randomly, regardless of their class. If int and `stratified = True`, it represents number of samples to be drawn from each class. If int and `stratified = False`, it represents overall number of samples to be drawn regardless of their class, randomly. Defaults to 0.8
- **val\_size** (*float*) – Should be between 0.0 and 1.0. Represents the percentage of each class from the training set to be extracted as a validation set. Defaults to 0.1.
- **stratified** (*bool*) – Indicated whether the extracted training set should be stratified. Defaults to `True`.
- **background\_label** (*int*) – Label indicating the background in GT file.
- **neighborhood\_size** (*Optional[int]*) – Neighborhood size of the pixel to extract along with its spectral bands. Use only if you are training 2D or 3D convolutional model.
- **channels\_idx** (*int*) – Index specifying the channels position in the provided data.
- **save\_data** (*bool*) – Whether to save data as .md5 or to return it as a dict.
- **seed** (*int*) – Seed used for data shuffling.
- **use\_unmixing** (*bool*) – Boolean indicating whether to perform experiments on the un-mixing datasets, where classes in each pixel are present as fractions.

**Raises** `TypeError` – When provided data or labels file is not supported.



## 2.2.9 scripts.train\_model module

Perform the training of the model. Has the option to inject noise into train and val set.

```
scripts.train_model.train(*, data, model_name, dest_path, sample_size, n_classes, kernel_size=3,
                           n_kernels=16, n_layers=1, lr=0.005, batch_size=150, epochs=10,
                           verbose=2, shuffle=True, patience=3, seed=0, noise, noise_sets,
                           noise_params=None)
```

Function for training tensorflow models given a dataset.

### Parameters

- **model\_name** (str) – Name of the model, it serves as a key in the dictionary holding all functions returning models.
- **kernel\_size** (int) – Size of each kernel in each layer.
- **n\_kernels** (int) – Number of kernels in each layer.
- **n\_layers** (int) – Number of layers in the model.
- **dest\_path** (str) – Path to where to save the model under the name “model\_name”.
- **sample\_size** (int) – Size of the input sample.
- **n\_classes** (int) – Number of classes.
- **lr** (float) – Learning rate for the model, i.e., regulates the size of the step in the gradient descent process.
- **data** – Either path to the input data or the data dict itself. First dimension of the dataset should be the number of samples.
- **batch\_size** (int) – Size of the batch used in training phase, it is the size of samples per gradient step.
- **epochs** (int) – Number of epochs for model to train.
- **verbose** (int) – Verbosity mode used in training, (0, 1 or 2).
- **shuffle** (bool) – Boolean indicating whether to shuffle dataset dataset\_key each epoch.
- **patience** (int) – Number of epochs without improvement in order to stop the training phase.
- **seed** (int) – Seed for training reproducibility.
- **noise** (list[str]) – List containing names of used noise injection methods that are performed after the normalization transformations.
- **noise\_sets** (list[str]) – List of sets that are affected by the noise injection methods. For this module single element can be either “train” or “val”.
- **noise\_params** (Optional[str]) – JSON containing the parameters setting of injection methods. Exemplary value for this parameter: “{“mean”: 0, “std”: 1, “pa”: 0.1}”. This JSON should include all parameters for noise injection functions that are specified in the noise argument. For the accurate description of each parameter, please refer to the `ml_intuition/data/noise.py` module.

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