# Digital System Design Final Project Report RISC-V G5

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## **Baseline**

## A. Pass Baseline Gate Level Simulation

- sdc cycle time = 2.7ns, slack = 0
- area =  $323040 \text{ um}^2$

#### B. AT

- AT =  $323040*5747 = 1,856,510,880 \text{ um}^2\text{ns} \approx 1.85*10^9$
- tb cycle time = 2.6ns
- 2210 cycles (haszard)

## C. Overview of Baseline circuit

- Icache
  - o 2way, 32word.
  - o Read only. Without proc write to cache, write-back to memory, no dirty bit.
- Dcache
  - o 2way, 32word.
  - Without write-back to memory, no dirty bit.

## D. General design

- 5 stages pipeline, IF, IF, EX, MEM and WB.
- With forwarding units, a load-use hazard detection unit.
- Branch and jump determination at ID stage.
  - o If the *rs* register at EX stage is needed for branch or jump, we have to let this *rs\_data* be propagated, and forward it from MEM stage. Otherwise, connecting it from alu\_output to PC adder will make it a critical path. There's no way to handle this problem, we will waste two cycles if encountering this situation with branch taken or jump.

## E. Design technique (not all are used)

### • Block input

- 1. Icache\_ren: Since reset ends at negedge, we can't read Icache at the next posedge, or we'll have only a half cycle to prepare the data. Therefore, we delay the Icache ren for a cycle.
- 2. mem\_ready, mem\_rdata: Since mem\_ready is set to high at negedge, mem\_rdata is sent at the same time. We have to delay mem\_ready in order to leave a whole cycle time for mem\_rdata to be stored at cache.

## • Memory prefetch

Speed up by 44 cycles. Our approach may not be perfect, because we didn't specify PC+4 to fetch the data. At *Compare\_tag state*, we set mem\_read to high, meaning that the memory is always preparing for the data. After some cycles, if instruction needed at PC now is missing, we enter the *Allocate state*. Since we have set mem\_read to high before, we don't need to wait five cycles to fetch the instruction. To make an analogy, it's like someone is going to the library to borrow a book. But he is told which one to borrow on the way to the library.

#### • Dcache reset

Speed up by 24 cycles. Instead of resetting the Dcache data to all zeros, we reset them to valid, and all-zero data. Since D\_mem are all zeros, if we need the address whose tags happen to be zero, we don't need to allocate this data from memory.

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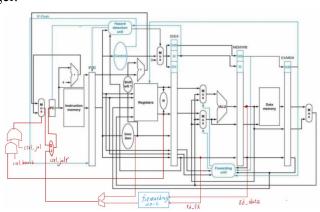
## • K-map reduce

- 1. We use 'type' as FSM to determine the instruction type, and alu\_ctrl to decide the alu operation. We don't need to list type and alo\_ctrl in order; instead, we can balance the bit 1 in each column.
- 2. The logic level does matter. The following pass different sdc cycle times.

```
3'd2 010 I
alu_ctrl_ID[0] = (func7[5] & func3[2] & !func3[1] & func3[0]) | (func3[2]&func3[1]) | (func7[5] & !func3[2] & op[5] );
alu_ctrl_ID[0] = ( (func7[5] & !func3[1]) & ((func3[2]&func3[0]) | op[5]) ) | (func3[2]&func3[1]);
3'd3 011 B
3'd6 110 J
```

## • Write register

- 1. Sequential circuit: By intuition, we use sequential circuit to store the value into registers. But this would require several muxes to be placed at the MEM stage, which may become a critical path.
- 2. Combinational circuit: We place this mux at the WB stage, just like the circuit on the textbook. In this way, we have to add registers for saving to avoid latch. These two approaches should have the same area; however, the combinational one is larger.



#### F. Review

We spent about two days passing the Baseline. Basically, we just simply build the
circuit on the textbook. There are two problems that took us most of the time. First,
the forwarding unit on the textbook is not enough; since branch and jump is
determined at the ID stage, we have to add one more forwarding unit for them.
Second, we can't forward the data from the end of the stage, for example alu\_output,
which will make it a critical path.

#### G. Remark

• In the above version. We blocked only mem\_ready and mem\_rdata and didn't apply techniques of memory prefetch and Dcache reset.

## H. Improvement after report

- After referencing others' presentations, we found that there's some techniques we had used before, but something went wrong then. However, that technique works on the current version. It's only slightly different from the above one.
- AT =  $312026*5635 = 1,758,266,510 \text{ um}^2\text{ns} \approx 1.75*10^9$
- sdc cycle time = 2.6 ns
- tb cycle time = 2.6 ns
- run time = 2067 cycles

# **Compression**

#### A. AT

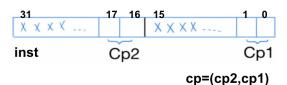
- $A*T = (313457 294020)*1728.3 = 541,747,733 \text{ um}^2 \text{ sns} \approx 5.8*10^8$
- area =  $294020 \text{ um}^2$
- sdc cycle time = 3ns
- tb cycle time = 4.2ns

## B. Advantage and disadvantage of RVC

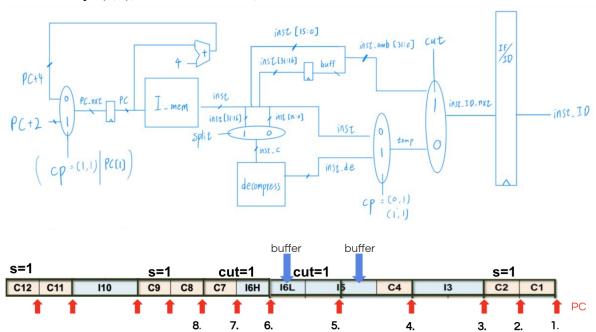
- 1. Less run time: RVC uses less run time because it has less instruction length, allowing Icache to store more RVC instructions than store 32 bit ones. This implies that RVC will have less miss rate, decreasing run time.
- 2. More area usage: A decompressor used to decompress a RVC instruction will have some area cost.
- 3. Complexity: Using a decoder to implement RVC will increase complexity, every stage has to make some modification according to it.

## C. Design

- Preliminary
  - 1. CP (compare): Given a 32 bits instruction and determine the {16,17} and {1,0} bits. If {1,0} are '11', then this is a 32 bits instruction, assigning cp=0; otherwise, this is a 16 bits instruction, assigning cp=1. If cp=0, then cp of the next 16 bits must be X, don't care, because it may be immediate of 32 bits instruction.
  - 2. cut: When cp2=0, we need to buffer the upper 16 bits and set cut\_nxt = 1. If cut =1, we have to take the buffered 16 bits and concatenate it with the current lower 16 bits.
  - 3. split: Read upper 16 bits RVC.



- PC increment and address alignment
  - PC never stalls, no cycle wasted.
  - Always PC+4, except when cp=(1,1) or (1,x) & cut or PC[1].
- Example (figure below)
  - 1. cp=(1,1), read lower 16 bits, PC+2.
  - 2. cp=(1,1) & s=1, read upper 16 bits, PC+2.
  - 3. cp=(x,0), read 32 bits instruction, PC+4.
  - 4. cp=(0,1), read lower 16 bits, buffer upper 16 bits, PC+4.
  - 5. cp=(0,x) & cut=1, concatenate buffered 16 bits with lower 16 bits. read this 32 bits instruction. PC+2.
  - 6. cp=(0,x) & cut=1, concatenate buffered 16 bits with lower 16 bits. read this 32 bits instruction. PC+2.
  - 7. cp=(0,x), read upper 16 bits, PC+2.
  - 8. cp=(1,1), read lower 16 bits, PC+2.



- Decompressor
  - Simply just map the 16 instructions to 32 bit one. Notice that the rd' has two
    positions, while rs1', rs'2 has fixed positions.

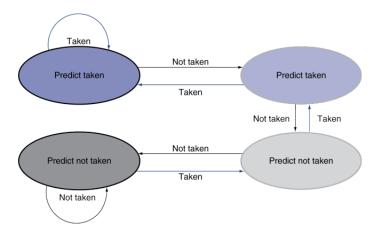
## D. Review

• Implementing RVC is kind of interesting. The PC increment and address alignment issue is worthy of thinking. In the online course, TA wants us to handle this problem, and it brings me a sense of accomplishment after solving this. The decoding part is tedious, however. I think that no further improvement can be done on this extension. Finally, due to its extension and being open source, RISC-V is taking over the world now. It's a good chance to have an initial look at this powerful ISA. Thanks to the Professor and TA for giving us the chance to implement this project.

## **Branch Prediction**

## A. Predictors

- 2-bit predictor v1
  - o FSM:

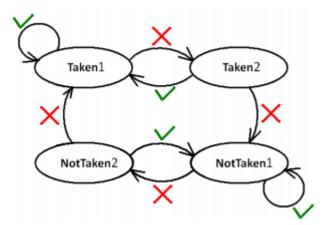


### o Features:

It'll take two consecutive wrong predictions to transition from strongly T/NT state to weakly NT/T state, and take one wrong prediction to transition from weakly t/nt state to weakly nt/t state. There's a serious problem with this predictor. If the branch pattern is  $T \rightarrow NT \rightarrow T \rightarrow NT...$  we'll transition between weakly T and weakly NT state, which means every prediction is wrong, wasting many cycles.

## • 2-bit predictor v2

o FSM



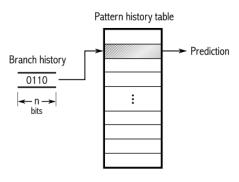
• Features: It'll take two consecutive wrong predictions to transition from T/NT state to NT/T state. No strong or weak state like predictor v1.

### **B.** Predictors

- Mechanism:
  - Record previous two branch history as follow:

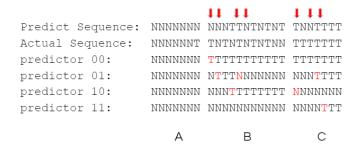
T: taken. NT: not taken NT / NT (i.e. 00) NT / T (i.e. 01) T / NT (i.e. 10)

T / T (i.e. 11)



- The predictors we choose are 1-bit predictor and 2-bit predictor v2
- Performance of Pattern-History-Table:

For example, Pattern-History-Table with 1-bit predictor: (N stands for branch not taken, T stands for branch taken)



A,B,C stands for three different types of sequences in the test pattern; the actual sequence of the first appearance of the first arrow is "NNT" (NN corresponds to predictor 00). However, the prediction predictor 00 will take at that point is branch not taken, it'll then update to branch taken.

## C. Analysis of test pattern:

- There are a total of 3 parts of sequence, respectively a, b, c.
  - a. All not taken.
  - b. NT / T/ NT / T / NT...
  - c. All taken.
- Five cases of comparisons:
  - 1. All not taken
    - a. All correct
    - b. Predict wrong every two branch instructions.
    - c. All wrong.
  - 2. 2-bit predictor v1
    - a. All correct
    - b. All wrong.
    - c. Predict wrong for the first three branch instructions, all correct thereafter.

## 3. 2-bit predictor v2

- a. All correct
- b. Predict wrong every two branch instructions.
- c. Predict wrong for the first three branch instructions, all correct thereafter.

#### 4 BHT 1-bit

- a. All correct
- b. Predict wrong for the first three branch instructions, all correct thereafter.
- c. Predict wrong for the first three branch instructions, all correct thereafter.

## 5. BHT 2-bit(v2)

- a. All correct
- b. Predict wrong for the first four branch instructions, all correct thereafter.
- c. Predict wrong for the first four branch instructions, all correct thereafter.

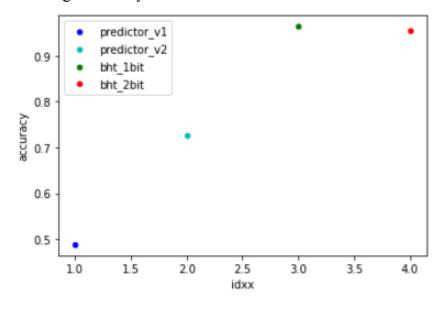
## D. Analysis of Branch predictor on Baseline (original test case):

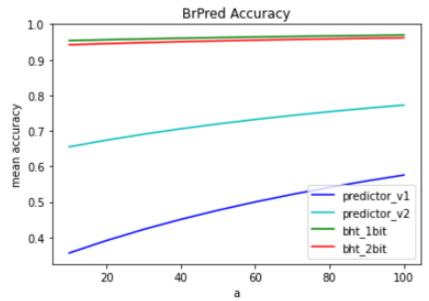
- 1. Without prediction: 2001 cycles
- 2. 2-bit predictor v1: 2015 cycles
- 3. 2-bit predictor v2: 1985 cycles
- 4. BHT 1-bit predictor: 1907 cycles
- 5. BHT 2-bit predictor v2: 1907 cycles

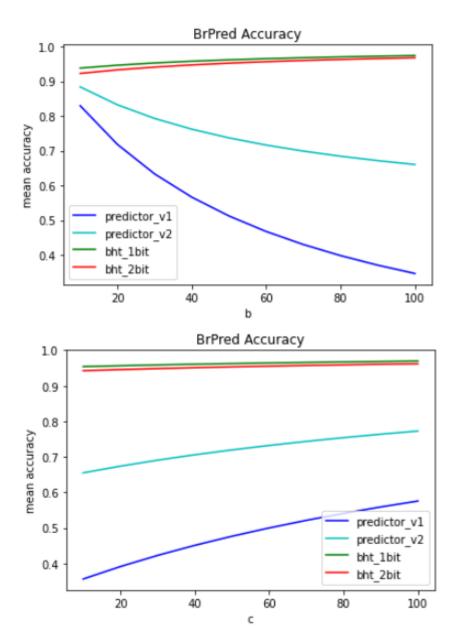
## E. Comparison of different types of test pattern

- i. Settings: different types of predictors, three different branch sequences and different combination of numbers of each sequence
- ii. Three parameters are set to values from 10, 20, 30, ..., 100. And use the combinations to generate different testbenches.
- iii. There are a total of 1000 testbenches for each predictors.
- iv. "a" stands for the first branching sequence, which is all not taken "b" stands for the second branching sequence, which is NT / T/ NT / T / NT...
  - "c" stands for the third branching sequence, which is all taken.
- v. Inference: With respect to three different branch sequences, the predictor will have different performance, which is:
  - For a: the performance will grow as the number of a increases
  - For b: the performance will degrade as the number of b increases
  - For c: the performance will grow as the number of c increases

total average accuracy over 1000 testbenches:







## 2 Level Cache

# B. L2 size comparizon

- a. Setting
  - i. Separate L1 cache to ICACHE and DCACHE
  - ii. Both L1 ICACHE and DCACHE use 2-way
  - iii. The size of each L1 cache is 32 words.
  - iv. Compare L2 size: 64 words, 128 words, 256 words
  - v. 10 possible value for nb
  - vi. 7 possible value for incre
  - vii. 70 combinations of testbench for each L2 size
  - viii. There're total of 210 testbenches.

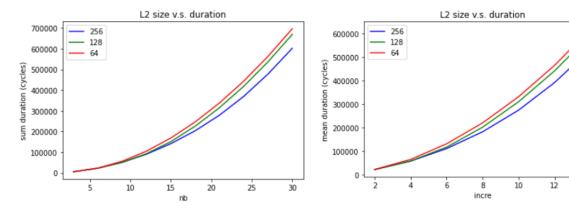
values of parameters in testbench: nb and incre

nb	3	6	9	12	15	18	21	24	27	30
incre	2	4	6	8	10	12	14			

## b. parameter meanings

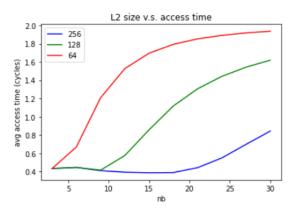
- i. "nb"
  - 1. It means the index of the Fibonacci Series, the CHIP needs to calculate the target Fibonacci number.
- ii. "incre"
  - 1. It means how many numbers will be generated for each Fibonacci number in the series.
  - 2. The start value is the origin Fibonacci number, it will increment 1 for each step.
  - 3. The size of final array will be nb\*(incre+1).
  - 4. In testbench, it will firstly calculate the target Fibonacci Number and then do the Bubble-Sort on the generated array.
- c. compare duration cycles in different L2 size settings.

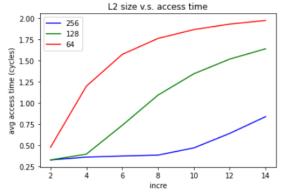
## i. results



### ii. inference

- 1. Duration grows up as nb and incre increases due to the increasing operations and the increasing accesses of cache.
- 2. 64 words L2 cache has the highest duration due to the smaller size. It easily has dirty access and then needs to write memory first then do the allocation. So the total stalls are larger than 128 words and 256 words L2 cache
- 3. The difference of duration becomes larger due to the increasing nb or incre will have more operations.
- d. compare average access time (cycles) in different L2 size settings.
  - i. results





## ii. inference

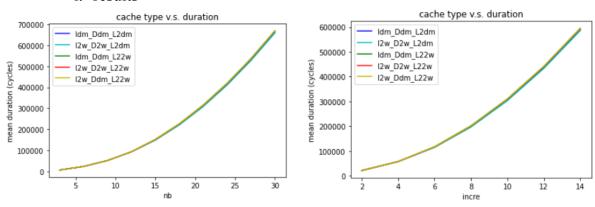
- 1. Average access time grows up as nb and incre increases due to the increasing operations and the increasing accesses of cache.
- 2. The difference of access time is larger than the duration. Since the duration includes a lot of cycles of other instructions that are not related to memory access.
- 3. 256 words L2 cache has the smallest average access time due to the large capacity in the cache. But the trade off is the area of the design.

## C. Cache type comparison

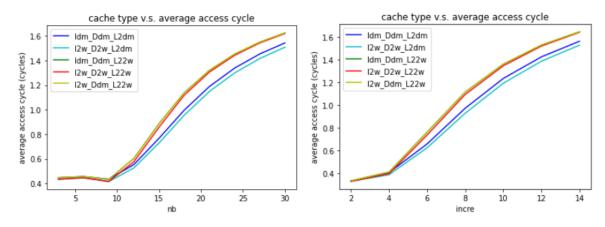
- a. setting
  - i. The size of each L1 cache is 32 words.
  - ii. Fix the size of L2 cache to 128 words.
  - iii. L1 Icache and Dcache share the same L2.
  - iv. 10 possible value for nb
  - v. 7 possible value for incre
  - vi. We tried 5 different type settings.

	1	2	3	4	5
I cache	2-way	dm	dm	2-way	2-way
D cache	2-way	dm	dm	2-way	dm
L2 cache	2-way	dm	2-way	dm	2-way

- vii. 70 combinations of testbench for each type setting
- viii. There're total of 350 testbenches.
- b. compare duration (cycles) in different L2 size settings.
  - i. results



- ii. inference
  - 1. different types of cache settings have almost the same duration. We check the access address in waveform, and find that the access address is almost linearly accessing.
- c. compare average access time (cycles) in different L2 size settings.
  - i. results



- ii. inference
  - 1. The setting of all dm (blue line) has smaller average access time than the setting of all 2-way (red line)

- 2. The best setting is L1 use 2-way and L2 use dm. (cyan line). It stalls only one cycle for each memory accessing on average.
- 3. Type of I cache only slightly affects the average access time. (yellow line and red line)