内存管理 Memory Management

现代C++基础 Modern C++ Basics

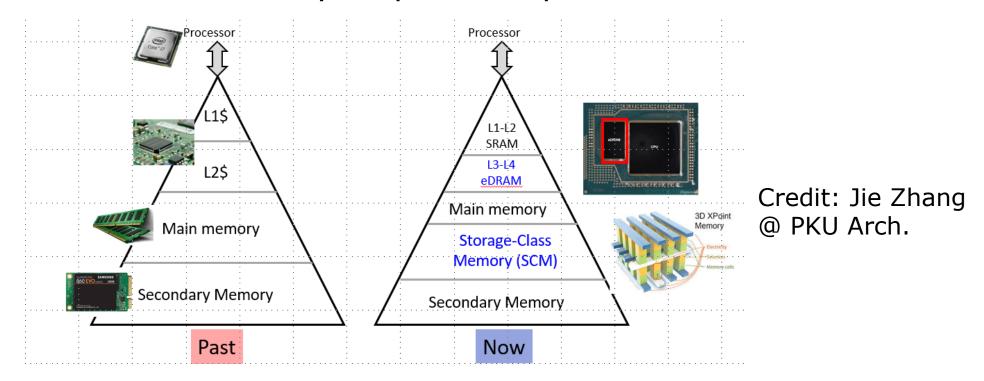
Jiaming Liang, undergraduate from Peking University

Low-level Memory Management

Smart Pointers

- Allocators
 - PMR

• The real structure of memory is quite complex...



- However, OS has abstracted them as virtual memory by page table, so in most cases users can view memory as a large contiguous array.
 - When such abstraction causes performance bottleneck, programmers need to dig into that further;
 - C++ also has some utilities to solve some common problems.

Memory Management

Low-level Memory Management

Memory Management

- Low-level Memory Management
 - Object layout
 - operator new/delete in detail

- Object will occupy a contiguous segment of memory that:
 - Starts at some address that matches some alignment;
 - And ends at some address that matches some size.
- A complete object may have many subobjects as members or elements (e.g. array or class).
 - sizeof reflects size of the type when it forms a complete object, which is always >0.
 - For example: static_assert(sizeof(Empty) > 0);
- In most cases, subobjects just occupy memory in the same way:

```
struct Empty {};
struct NonEmpty
{
    int a;
    Empty e;
};
// Padding may exist so we use '>='
static_assert(sizeof(NonEmpty) >= sizeof(int) + sizeof(Empty));
```

- However, some subobjects as class member can have 0 size...
 - Formally called "potentially-overlapping objects".
- 1. For a class, if it fulfills:
 - No non-static data members;
 - No virtual methods or virtual base class;
 - It's a base class.

Then it's **allowed** to have 0 size.

Moreover, it's **forced** to have 0 size if

- The derived class is a standard-layout class.
- Also called "Empty Base (Class) Optimization" (EBO/EBCO).

```
struct Empty {};
struct NonEmpty : Empty
{ // Standard-layout
    int a;
};
static_assert(sizeof(NonEmpty) == sizeof(int));
```

- So now we can understand static_cast / reinterpret_cast...
 - For static_cast, besides inheritance-related pointer conversion, it also processes void*.
 - You can convert any object pointer to void* (this is also implicit conversion).
 - You can also convert explicitly void* to any object pointer.
 - **BUT**, this requires the underlying object of type U and the converted pointer T* (ignoring cv) to have the relationship (called *pointer-interconvertible*) as:
 - T == U.
 - U is a union type, while T is type of its member (though using it still needs this member to be in its lifetime).
 - U is standard-layout, while T is type of its **first** member or its base class.
 - Or all vice versa/transitivity (i.e. you can swap T and U above; after all, "inter").

In lecture 5, *Lifetime & Type Safety*.

FYI, this can be checked by std::is_pointer_interconvertible_with_class and std::is_pointer_interconvertible_base_of since C++20.

• Empty base will be collapsed so conversion is safe.

```
struct Empty {};
struct NonEmpty : Empty
{ // standard-layout
    int a;
};

NonEmpty obj;
// ptr points to the base class of obj.
Empty* ptr = reinterpret_cast<Empty*>(&obj);
// ptr2 points to obj.a.
int* ptr2 = reinterpret_cast<int*>(&obj);

static_assert(std::is_pointer_interconvertible_with_class(&NonEmpty::a));
static_assert(std::is_pointer_interconvertible_base_of_v<Empty, NonEmpty>);
```

- A class is said to be standard-layout, if:
 - All non-static data members have the same accessibility and are also standard-layout.
 - This is because the layout of members that have different accessibility are unspecified (before C++23); e.g. as the sequence of declaration or first all public members and second all private members.
 - No virtual functions or non-standard-layout base classes.
 - The base class is not the type of the first member data.
 - There is at most one class in the inheritance hierarchy that has non-static member variable.
 - That's because layout of inheritance is not regulated.

1: Strictly speaking, it should be "similar types", e.g. adding cv-qualifiers is allowed. See [conv.qual] for details.

²: Except for <u>potentially non-unique object</u> like string literals.

- 2. Since C++20, for a member subobject that is marked with attribute [[no_unique_address]], it's **allowed** to have 0 size.
 - Particularly, msvc will ignore this attribute for backward compatibility; instead, it respects [[msvc::no_unique_address]].

```
• For example: struct Y
{
    int i;
    [[no_unique_address]] Empty e;
};
In gcc/msvc/clang,
sizeof(Y) == 4.
```

• Note: C++ regulates two objects of the same type¹ must have **distinct**

addresses².
• For example:

• For example:

Char c;

char c;

// e1 and e2 cannot share the same address because they have the

// same type, even though they are marked with [[no_unique_address]].

// However, either may share address with 'c'.

[[no_unique_address]] Empty e1, e2;

```
struct W
{
    char c[2];
    // e1 and e2 cannot have the same address, but one of
    // them can share with c[0] and the other with c[1]:
       [[no_unique_address]] Empty e1, e2;
};
```

- Theoretically, this can be optimized as sizeof(W) == 2; however, all three compilers make sizeof(W) == 3.
- And again, we can understand in standard layout...
 - A class is said to be standard-layout, if:
 - All non-static data members have the same accessibility and are also standard-layout.
 - This is because the layout of members that have different accessibility are unspecified (before C++23); e.g. as the sequence of declaration or first all public members and second all private members.
 - No virtual functions or non-standard-layout base classes.
 - The base class is not the type of the first member data.
 - There is at most one class in the inheritance hierarchy that has non-static member variable.
 - That's because layout of inheritance is not regulated.

Now EBCO doesn't guarantee to happen:

```
struct Empty {};
struct NonEmpty : Empty
{ // Not standard-layout
    Empty e;
    int a;
};

NonEmpty obj;
// ptr doesn't necessarily point to e.
Empty* ptr = reinterpret_cast<Empty*>(&obj);
```

- In ABI, base class may be put first;
- As subject of base class must be distinguished from the first member, then base class may be not really "empty".
- And a non-empty base leads to non-standard-layout*.

^{*:} there may be some defects in current definitions. See <u>SO question</u>.

Layout Compatible*

- This part is optional.
- Finally we fix our claim before:
 - Similarly, for union type, it's illegal to access an object that's not in its lifetime (it's only allowed in C)!
- union U { int a; float b; };

 pint main()
 {
 U u; u.a = 1; std::cout << u.b;</pre>

- Here u.a is in its lifetime, while u.b is not.
- You should use std::memcpy or std::bit_cast since C++20 to make them bitwise equivalent.
- Rigorously, when types have common initial sequence, it's legal

to access out of lifetime: struct T1 { int a, b; };

```
struct II { int a, b; };
struct T2 { int c; double d; };
union U { T1 t1; T2 t2; };
int f() {
  U u = { { 1, 2 } }; // active member is t1
  return u.t2.c; // OK, as if u.t1.a were nominated
}
```

Layout Compatible*

- Formally, we say two types are layout compatible if:
 - Naïve cases:
 - They are of the same type, ignoring cv qualifier; or,
 - They are enumerations with the same underlying integer type.
 - Otherwise,
 - 1. They are both standard-layout; and,
 - 2. Their common initial sequence covers all members.
- where common initial sequence means the longest sequence of non-static data members and bit-fields in declaration order that:
 - 1. corresponding entities are layout-compatible; and,
 - 2. corresponding entities have the same alignment requirements; and,
 - either both entities are bit-fields with the same width or neither is a bit-field.

Layout Compatible*

```
struct A { int a; char b; };
• For example: struct B { const int b1; volatile char b2; };
                        // A and B's common initial sequence is A.a, A.b and B.bl, B.b2
                        struct C { int c; unsigned : 0; char b; };
                        // A and C's common initial sequence is A.a and C.c
                        struct D { int d; char b : 4; };
                        // A and D's common initial sequence is A.a and D.d
                        struct E { unsigned int e; char b; };
                        // A and E's common initial sequence is empty
```

A and B are layout-compatible.

 Since C++20, you can use std::is layout compatible* and std::is corresponding member to check it.

```
struct T1 { int a, b; };
struct T2 { int c; double d; };
struct T3 { int a, b; };
static_assert(std::is_corresponding_member(&T1::a, &T2::c));
static_assert(!std::is_corresponding_member(&T1::b, &T2::d));
static assert(std::is layout compatible v<T1, T3>);
```

*: Strictly speaking, std::is_layout_compatible will tolerate non-struct-type, while the standard only regulates struct-type.

To maximize efficiency, data should be aligned properly.

```
• For example, on some platform: // 00 // long long, char, int can live here // 01 // char // 02 // char // 03 // char // 04 // char, int can live here // 05 // char // 06 // char // 07 // char // 07 // char // 08 // long long, char, int can live here
```

- In C++, it can be checked by alignof(T);
 - Platform-dependent, return std::size_t, quite like sizeof.

```
std::println("{} {} {}", alignof(char), alignof(int), alignof(long long));

Program returned: 0

1 4 8

*Or using type traits
std::alignment of.
```

 When wrapping data in class, every object will be aligned to its own alignment, leading to padding.

Each element in C array should be suitably aligned, thus sizeof(X) must be multiple of alignof(X).

- Naturally, all scalar types will have alignment not greater than alignof(std::max_align_t) (in <cstddef>).
 - And allocation will align to this alignment by default.
- However, sometimes you may want over-aligned data.
 - Then you can use alignas(N) to make alignment N.
 - Ignored when N == 0, compile error if N is not power of 2.
 - For example, to match OpenGL uniform layout:

```
struct BasicParams
{
    alignas(16) glm::vec3 cameraPos;
    int randOffset;

    alignas(16) glm::vec3 cameraForward, cameraRight, cameraUp;
    float g;
```

These three members are all aligned to 16.

- Note 1: you can also use alignas(T) to have alignment same as
 T.
- Note 2: when using multiple alignas, the largest one will be selected.
 - So our previous code segment can be rewritten:

```
alignas(std::max(alignof(float), alignof(int))) std::byte arr[20];
float* ptr = reinterpret_cast<float*>(arr);
*ptr = 1.0f;
int* ptr2 = reinterpret_cast<int*>(arr);
// std::cout << *ptr2; // -> illegal
alignas(float) alignas(int) std::byte arr[20];
```

- Note 3: you can do pack expansion in alignas, which is same as alignas(arg1) alignas(arg2) ... alignas(argN).
 - i.e. select the largest alignment among N arguments.

```
alignas(1) int a = 2; X
```

• Note 4: over-align only: if alignas is weaker than its natural alignment (i.e. alignment without alignas), compile error.

Some compilers will ignore or only warn.

Note 5: alignment is NOT part of the type, so you cannot alias it

in using or typedef.

```
struct C {
   long long x;
   int y;
};

using T = alignas(16) C;
```

Attributes are added after struct.

struct alignas(16) C {
 long long x;
 int y;
};

struct C {
 long long x;
 int y;
};

struct D
{
 alignas(16) C c;
};

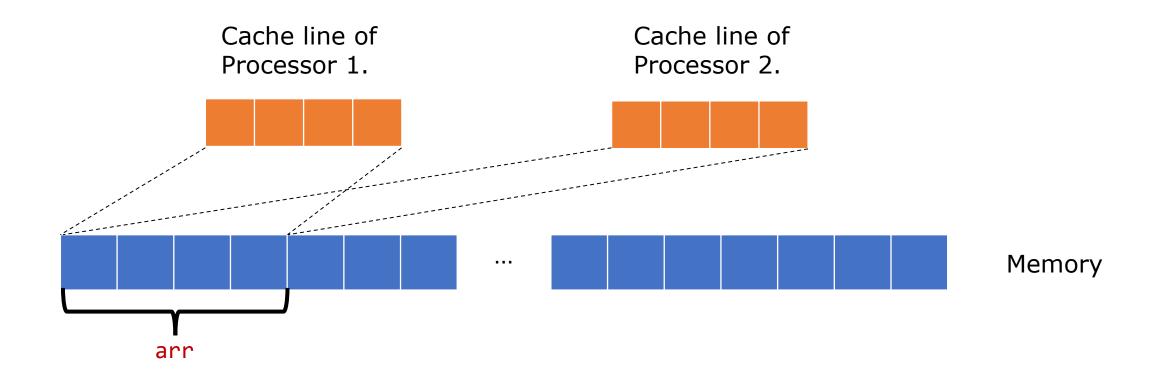


• Note 6: function parameter and exception parameter are not allowed to use alignas.

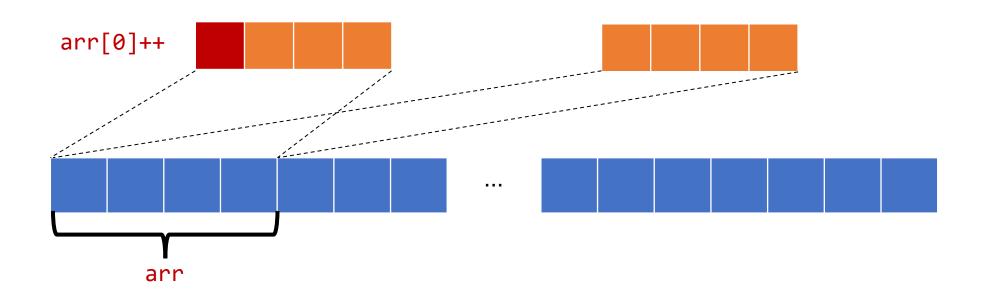
- Practical example: false sharing
 - From abstraction, when different threads operate on different data, parallelism will be maximized since no lock is needed.

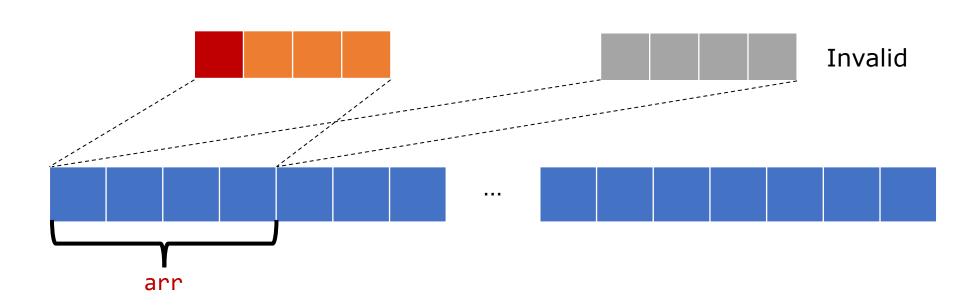
```
// Here to prevent compiler optimization to collapse
// We use atomic<int> instead of int.
std::atomic<int> arr[4];
void Work(int idx) { arr[idx]++; }
```

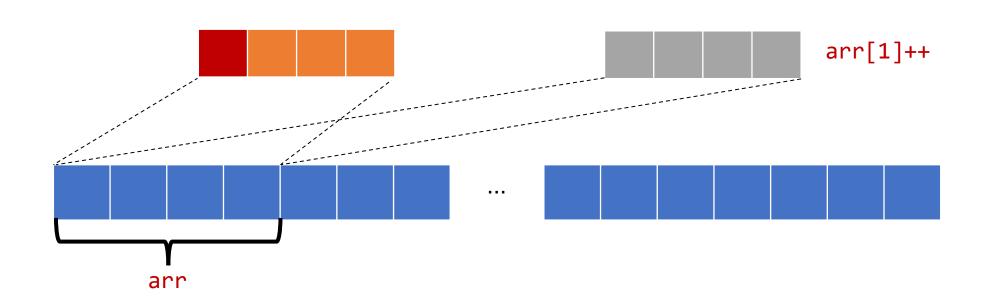
- However, due to limitation of computer architecture, such abstraction is wrong...
 - Cache on different processors has to obey coherence protocol like MESI.
 - To put it simply, when write happens on a cache line, it'll inform other processors whose cache also own this line to make it invalid.
 - And invalid line needs to be reloaded, leading to inefficiency.

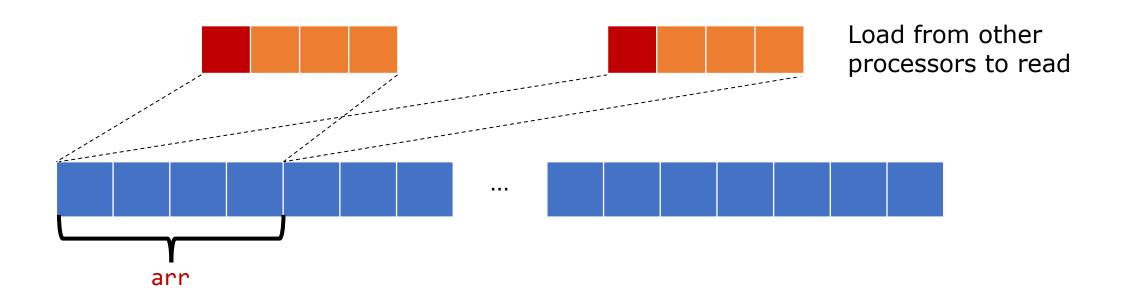


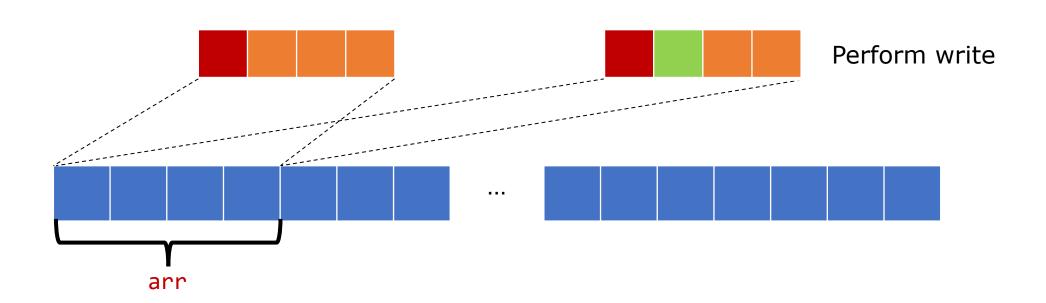
Illustrative animation for false sharing. (Details may vary for different architectures)

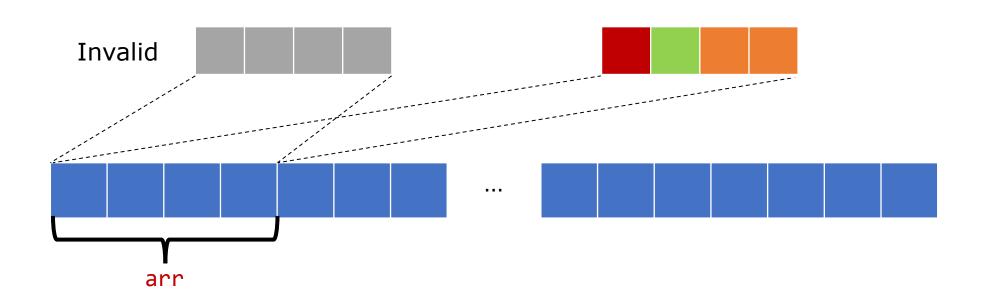












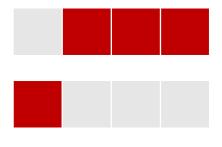
- So when writes in different threads are on the same cache line, every write will happen exclusively as if having a lock.
 - This leads to false parallelism, degrading the performance.
- Solution: make threads access data on different cache lines!
 - C++17 provides constant std::hardware_destructive_interference_size in <new>.

 On the other hand, for a single thread, we hope accessed data to lie on the same cache line to minimize pollution.

For example:

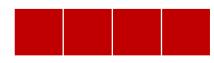
Improperly aligned, use two cache lines.





Properly aligned, use single cache line.





- To force data to lie on the same cache line, we can align the head as cache line head.
- C++17 thus introduces std::hardware_constructive_interference_size for that.

For example:

```
struct alignas(hardware_constructive_interference_size)
OneCacheLiner // occupies one cache line
{
    std::atomic_uint64_t x{};
    std::atomic_uint64_t y{};
}
oneCacheLiner;

struct TwoCacheLiner // occupies two cache lines
{
    alignas(hardware_destructive_interference_size) std::atomic_uint64_t x{};
    alignas(hardware_destructive_interference_size) std::atomic_uint64_t y{};
}
twoCacheLiner;
```

- Question: aren't std::hardware_destructive_interference_size and std::hardware_constructive_interference_size just same as cache line size?
 - Why do we need two constants to represent them?

- Reason: in some architecture, destructive interference will be larger than a cache line...
 - For example, on Intel Sandy Bridge processor, it will do adjacent-line prefetching.
 - So when loading a cache line, the next cache line may or may not be substituted, leading hardware_destructive_interference_size == 128 while hardware_constructive_interference_size == 64.

Note 1: there exist several utilities for alignment in <memory>.

- Assuming that we have a space that starts from ptr and has size space;
- Now we want to allocate an object with size and alignment on the space;
 - Assuming that it can be allocated on new_ptr on new_space (i.e. suitably aligned).
- So std::align just modifies ptr to new_ptr, space to new_space, and returns new_ptr.
 - If space is too small, then nothing happens and nullptr is returned.

• For example:

```
class Buffer
    std::vector<std::byte> buffer_;
    std::size_t size_;
    void* ptr_;
public:
    Buffer(std::size_t size) : size_{ size }
        buffer.resize(size);
        ptr_ = buffer.data();
    template<typename T>
    void* Alloc()
        auto addr = std::align(sizeof(T), alignof(T), ptr_, size_);
        ptr_ += sizeof(T);
        size_ -= sizeof(T);
        return addr;
```

- 2. To maximize optimization, you can inform compiler that a pointer is aligned by std::assume_aligned<N>(ptr) since C++20.
 - It's UB if it's not aligned to N, quite like [[assume]].
 - Since C++26 you can also add std::is_sufficiently_aligned<N>(ptr) to check precondition in debug mode.

```
• For example: void Func(int* ptr)
{
    static constexpr std::size_t alignment = 64;
    assert(std::is_sufficiently_aligned<alignment>(ptr));
    std::assume_aligned<alignment>(ptr);
    // Then compilers may do optimization based on
    // assumption of 64 alignment.
}
```

- Note 2: since C++17, you can use trait
 std::has_unique_object_representations to check if same value
 representations of two objects lead to the same object
 representation.
 - For example, for float, two NaN are not distinguishable but may have different bits, so the trait returns false.
 - Particularly, for a struct, when there are padding bytes, then it definitely returns false since they are not part of value of struct.
 - This trait can be used to check whether it's correct for a type to be hashed as a byte array.

Memory Management

- Low-level Memory Management
 - Object layout
 - operator new/delete in detail

- To combine allocation and construction, C++ uses newexpression to substitute malloc in C.
 - Roughly speaking, it calls two different functions:
 - Allocation new, which only allocates memory (quite like malloc).
 - Placement new, i.e. construct the object on memory.
- And similarly, delete-expression has two parts:
 - Destructor, i.e. destruct the object on memory.
 - Deallocation delete, which only deallocates memory (quite like free).
- C++ allows you to **override** (replace) the allocation new by operator new and the deallocation delete by operator delete.

- Thus the most basic versions like malloc and free are as below:
 - You can override them in global scope (i.e. namespace ::).

```
void* operator new ( std::size_t count );
void* operator new[]( std::size_t count );
void operator delete ( void* ptr ) noexcept;
void operator delete[]( void* ptr ) noexcept;
```

Besides, you can provide class-specific allocation & deallocation:

```
void* T::operator new ( std::size_t count );
void* T::operator new[]( std::size_t count );
void T::operator delete ( void* ptr );
void T::operator delete[]( void* ptr );
```

- Which is preferred than global override, and isn't required to be noexcept.
- They are always static function, even if you don't add keyword static.

```
std::println("Called overrided operator new, size={}", byteCnt);
   if (auto ptr = malloc(byteCnt); ptr)
       return ptr;
   throw std::bad alloc{};
   std::println("Called overrided operator delete, ptr={}", ptr);
   free(ptr);
class Base
public:
   static void* operator new[](std::size t byteCnt)
       std::println("INSIDE CLASS: Called overrided operator new[], size={}", byteCnt)
                                                                  Called overrided operator new, size=4
       if (auto ptr = malloc(byteCnt); ptr)
           return ptr;
       throw std::bad alloc{};
   Here we don't add static, but it's still static function. You can't use this here.
       std::println("INSIDE CLASS: Called overrided operator delete[], ptr={}", ptr);
       free(ptr);
```

void* operator new(std::size_t byteCnt)

NOTE: before P3107 (DR23), std::println will use std::string and thus may need to use operator new/delete, causing infinite recursion. MS-STL has implemented this DR so it's fine to do so.

```
int main()
    auto a = new int{ 1 };
    auto b = new Base[2];
    std::println("PtrA = {}, val = {}; PtrB = {}",
                 (void*)a, *a, (void*)b);
    delete[] b;
    delete a:
    return 0;
```

INSIDE CLASS: Called overrided operator new[], size=2 PtrA = 0x218395c8d10, val = 1; PtrB = 0x218395c8fd0INSIDE CLASS: Called overrided operator delete[], ptr=0x218395c8fd0 Called overrided operator delete, ptr=0x218395c8d10

 However, C++ also allows you to delete basePtr, which will call virtual dtor.

• Ideally, it should call Derived::operator delete instead of Base::operator delete...

class Derived : public Base

Let's try it!

```
lass Base
                                                                              static void* operator new(std::size_t byteCnt)
  static void* operator new(std::size t byteCnt)
                                                                                  std::println("Derived: Called overrided operator new, size={}", byteCnt)
                                                                                  if (auto ptr = malloc(byteCnt); ptr)
      std::println("Base: Called overrided operator new, size={}", byteCnt);
                                                                                      return ptr;
      if (auto ptr = malloc(byteCnt); ptr)
                                                                                  throw std::bad alloc{};
          return ptr;
      throw std::bad alloc{};
                                                                              void operator delete(void* ptr) noexcept
  void operator delete(void* ptr) noexcept
                                                                                  std::println("Derived: Called overrided operator delete, ptr={}", ptr);
      std::println("Base: Called overrided operator delete, ptr={}", ptr);
                                                                                  free(ptr);
      free(ptr);
                                                                              virtual ~Derived() { std::println("Derived dtor"); }
  virtual ~Base() { std::println("Base dtor"); }
```

```
Base* ptr = new Derived;
delete ptr;
```

```
Derived: Called overrided operator new, size=8
Derived dtor
Base dtor
Derived: Called overrided operator delete, ptr=0x2b96ff5c320
```

- The output is like:
 - So Derived::operator delete is called, quite like virtual dtor!
 - But operator delete is static! How?
- Reason: compiler will generate a "deleting destructor"*.
 - That is, it will generate a new virtual function:
 - For a normal object, just use normal dtor;
 - For delete ptr, it will call this new function.

```
virtual void DestroyWhenDelete(void* addr)
{
    this->~Derived();
    Derived::operator delete(addr);
}
```

 With virtual dispatch, we can extract more information from the type to improve malloc-like version!

^{*:} This is implementation-defined; here we use method of Itanium ABI. See this blog for details.

- Before going on, let's do some recap...
- In ICS, we've written a very basic allocation strategy:
 - Allocate memory block that's slightly larger than requested, then store block size and pointer to next block alongside it.
 - However, many metadata will never change after allocation, which will pollute cache line.
- So in modern memory allocators, it's much more complicated...

Roughly speaking, a common way is to split memory into bins indexed by

approximate size.

And metadata may record more info:

```
// Thread local data

/ struct mi_tld_s {
    unsigned long long heartbeat;
    bool recurse;
    mi_heap_t* heap_backing;
    mi_heap_t* heaps;
    mi_segments_tld_t segments;
    mi_os_tld_t os;
    mi_stats_t stats;
};
```

Adopted from mimalloc.

Sized-delete

- And in C++, we can almost always know object type exactly...
 - So we can know size of object!
- To facilitate optimization, C++ introduces size-aware delete (also called sized-delete).
 - Global sized delete is provided in C++14, while class-specific one is from C++11.
 void operator delete (void* ptr, std::size_t sz) noexcept;
 void operator delete[](void* ptr, std::size t sz) noexcept;
 - For a naïve example:

```
Called overrided operator new, size=4
Derived: Called overrided operator delete, ptr=0x145540d4ce0, size=4
```

Sized-delete

- Note 1: some practical example:
 - Like in jemalloc:

```
void
operator delete(void *ptr, std::size_t size) noexcept {
    sizedDeleteImpl(ptr, size);
}
```

```
JEMALLOC_ALWAYS_INLINE
void
sizedDeleteImpl(void* ptr, std::size_t size) noexcept {
    if (unlikely(ptr == nullptr)) {
        return;
    }
    LOG("core.operator_delete.entry", "ptr: %p, size: %zu", ptr, size);
    je_sdallocx_noflags(ptr, size);
    LOG("core.operator_delete.exit", "");
}
```

- Note 2: compilers are free to choose sized-delete or normal delete.
 - So, programmer should always provide both of them.
 - For gcc/msvc/clang (clang needs -fsized-deallocation flag):
 - For global override, it will prefer sized version when it exists.
 - For class-specific override, it will prefer normal delete when it exists (since you can easily know its size by sizeof).

Aligned new/delete

But these overloads don't specify alignment...

• Before C++17, over-aligned types may be not correctly handled (normally

compiler warning in e.g. -Wall).

```
// ptr is possibly not aligned to 1024!
A* ptr = new A;
delete ptr;

struct alignas(1024) A
{
   int a;
};
```

- Since C++17, alignment-aware new/delete are introduced.
 - Here std::align_val_t is scoped enumeration as tag.
 - For type whose alignment requirement exceeds macro __STDCPP_DEFAULT_ NEW_ALIGNMENT__, alignment-aware overloads are preferred.
 - Of course, you can override them too.

```
void* operator new ( std::size_t count, std::align_val_t al );
void* operator new[]( std::size_t count, std::align_val_t al );
```

For class-specific ones:

```
void* T::operator new ( std::size_t count, std::align_val_t al );
void* T::operator new[]( std::size_t count, std::align_val_t al );
void T::operator delete ( void* ptr, std::align_val_t al );
void T::operator delete[]( void* ptr, std::align_val_t al );
void T::operator delete ( void* ptr, std::size_t sz );
void T::operator delete[]( void* ptr, std::size_t sz );
void T::operator delete ( void* ptr, std::size_t sz, std::align_val_t al );
void T::operator delete[]( void* ptr, std::size_t sz, std::align_val_t al );
```

C11/C++17 provides aligned_alloc similarly; but MS-STL doesn't provide aligned_alloc since Windows doesn't provide ability to allocate aligned memory and thus must over-allocate and align manually. Therefore, it cannot be freed correctly by free; instead, aligned_alloc and aligned_free should be used.

Note 1: all new-overloads has nothrow variants:

```
void* operator new ( std::size_t count, const std::nothrow_t& tag );
void* operator new[]( std::size_t count, const std::nothrow_t& tag );
void* operator new ( std::size_t count, std::align_val_t al, const std::nothrow_t& tag ) noexcept;

void* operator new[]( std::size_t count, std::align_val_t al, const std::nothrow_t& tag ) noexcept;
```

- Note 2: essentially, new-expression new(args...) Type{...} will call operator new(size(, align), args...).
 - The arguments before args... are usually determined by compilers, while the latter are specified by users.

*: Placement is abused in the context of new/delete; here it just means to provide additional parameters in new(...), which includes nothrow variant and placement-new variant.

- That's why you can use:
 - new(std::nothrow) Type, for there exists nothrow variant.
 - new(ptr) Type, for there exists placement-new variant.
 - But they can't be overridden by users. Non-allocating placement allocation functions

```
void* operator new ( std::size_t count, void* ptr );
void* operator new[]( std::size_t count, void* ptr );
```

- More generally, you can provide customized arguments for userdefined placement* allocation new:
 - Class-specific ones also exist, omitted here.

```
void operator delete ( void* ptr, args... );
```

- Plus placement deallocation delete: void operator delete[](void* ptr, args...);
 - Each user-defined new must has a matching user-defined delete; when constructor throws, new memory will be freed by corresponding delete.
 - Otherwise memory leak! For example (omit sized-delete):

```
struct S
                                                                 int main()
   S() = default;
                                                                     S* p = new ("123") S;
   S(int) { throw std::runtime_error{ "Hi" }; }
                                                                     delete p;
   void* operator new(std::size t byteCnt, const std::string& msg)
                                                                     try {
                                                                         p = new("442") S\{1\};
       std::println("New {}: {}", msg, byteCnt);
                                                                     } catch(const std::exception& ex) {
       return ::operator new(byteCnt);
                                                                         std::println("Exception: {}", ex.what());
   // Non-placement deallocation function:
   void operator delete(void* ptr)
                                                               ▶New 123: 1
       std::println("Delete {}", ptr);
       ::operator delete(ptr);
                                                                Delete 0x5a75def022c0
                                                                                                        Only failed new-
                                                                 New 442: 1
                                                                                                        expression will call
   void operator delete(void* ptr, const std::string& msg)
                                                                 Delete 442: 0x5a75def022c0
                                                                                                        corresponding
                                                                 Exception: Hi
       std::println("Delete {}: {}", msg, ptr);
                                                                                                        placement delete!
       ::operator delete(ptr);
                                                       Prevent
```

memory leak.

• And similarly, for nothrow new, you need to customize placement delete... void operator delete (void* ptr, const std::nothrow_t& tag) noexcept;

 Finally, if a placement allocation corresponds to a non-placement deallocation, then compile error.

```
struct S
{
    // Placement allocation function:
    static void* operator new(std::size_t, std::size_t);

    // Non-placement deallocation function:
    static void operator delete(void*, std::size_t); This is sized delete.
};

S* p = new (0) S; // error: non-placement deallocation function matches
    // placement allocation function
```

- Note 3: for the default thrown operator new, it will call new handler when allocation fails.
 - As if:

```
void* operator new(std::size_t byteCnt)
   auto ptr = operator new(byteCnt, std::nothrow);
   while (ptr == nullptr)
       auto handler = std::get new handler();
       if (handler == nullptr)
           throw std::bad_alloc{};
       handler();
        ptr = operator new(byteCnt, std::nothrow);
   return ptr;
```

The default new handler is just nullptr, so it will throw std::bad_alloc directly.

- You can customize it by std::set_new_handler(...) in <new>
 (thread-safe), and the handler is expected to:
 - Make more memory available (so after calling handler, allocation retry may succeed);
 - Terminate the program (e.g. by std::terminate);
 - 3. Throw exception derived from std::bad_alloc, or std::set_new_handler(nullptr).
 - Return value: previous handler.
 - For example:

```
void handler()
{
    std::cout << "Memory allocation failed, terminating\n";
    std::set_new_handler(nullptr);
}
int main()
{
    std::set_new_handler(handler);
}</pre>
```

```
try
{
    while (true)
    {
        new int[1000'000'000ul]();
    }
}
catch (const std::bad_alloc& e)
{
    std::cout << e.what() << '\n';
}</pre>
```

Note 4: C++20 introduces class-specific destroying-delete.

- Which will be preferred over all other overloads.
- delete-expression will call destroying-delete directly, without calling dtor.
 - That is, it's duty of the destroying-delete to call dtor.
- Array doesn't have this overload.
- Note 5: it should be thread-safe to call operator new/delete.

- Special example: control allocation of coroutine.
 - Coroutine will allocate its state/frame by new;
 - C++ allows you to customize operator new/delete of promise_type to control such allocation!
- It's specially treated so not exactly same as normal class-specific allocation/deallocation.
 - Class-specific ones need lots of overloads to cover every possible case;
 - But promise_type only needs to define a few for compiler to choose!
 - For new, it only needs: void* operator new (std::size t count);
 - For delete, it only needs: void operator delete (void* ptr, std::size_t sz) noexcept;
 - When this overload doesn't exist, it needs: void operator delete (void* ptr) noexcept;

Memory resource will be covered in later sections.

• For example:

```
class CoroTask {
    inline static std::array<std:::byte, 200000> memory;
    // covered in t
    inline static std::pmr::monotonic_buffer_resource buffer{
        memory.data(), memory.size(), std::pmr::null_memory_resource()
    };
    inline static std::pmr::synchronized_pool_resource mempool{ &buffer };
public:
    struct promise_type {
        void* operator new(std::size_t size) {
            return mempool.allocate(size);
        void operator delete(void* ptr, std::size_t size) {
            mempool.deallocate(ptr, size);
    };
```

- Note 1: when defining get_return_object_on_allocation_failure, you should make operator new act as if nothrow instead of defining nothrow variant.
 - For example: void* operator new(std::size_t size) {
 return new(std::nothrow) std::byte[size];
 }
- Note 2: compilers are allowed to omit your operator new/delete when performing HALO.
 - So theoretically, one way to ensure HALO is to only declare operator new/delete without definition, so allocating on heap will lead to link error.
- Note 3: operator new is allowed to accept parameters of coroutine.
 - A naïve example:
 - And it's preferred if exist.

```
struct promise_type {
    void* operator new(std::size_t sz, int, const std::string&) {
        return mempool.allocate(sz);
    }
};

CoroTask coro1(int a, std::string s); // 这个协程会使用重载的operator new.
CoroTask coro2(int a); // 这个协程不会使用。
```

• Take std::generator as an example:

- Implementation may then allocate more bytes than size, then put allocator on additional space.
- The delete can extract allocator from the frame to do deallocation.

```
void operator delete( void* ptr, std::size_t n ) noexcept;
```

Use it by passing additional parameters.

- Final note: in shared library, global override of operator new/delete should be paid special attention.
 - Reason: if each shared library has its own override, it may be unclear which one is used.
 - For example, when A is loaded, its memory is allocated by its operator new;
 - And B is loaded, then operator delete is replaced;
 - And when A frees its memory, it uses operator delete of B, causing unknown results.
 - The behaviors are totally implementation-defined.
 - In static library, this will cause link error for symbol conflict.