

Automated Software Testing

An Overview

Mathieu Acher

Associate Professor

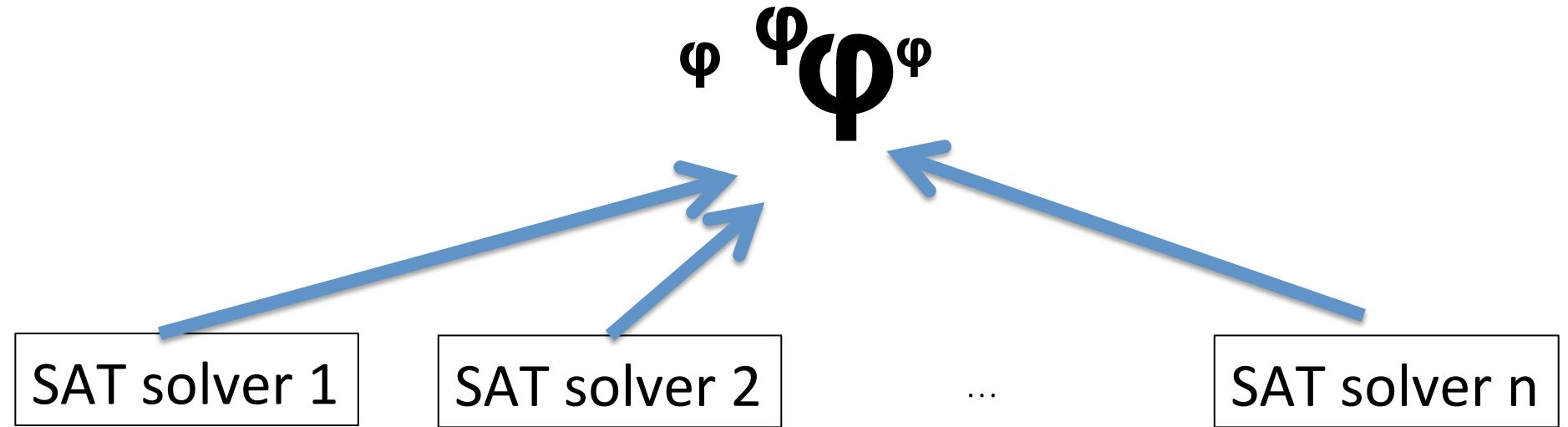
mathieu.acher@irisa.fr



Material

[https://github.com/FAMILIAR-project/
HackOurLanguages-SF](https://github.com/FAMILIAR-project/HackOurLanguages-SF)

Comparing solver variants' performance



You Retweeted



Thomas Thüm

@ThomasThuem

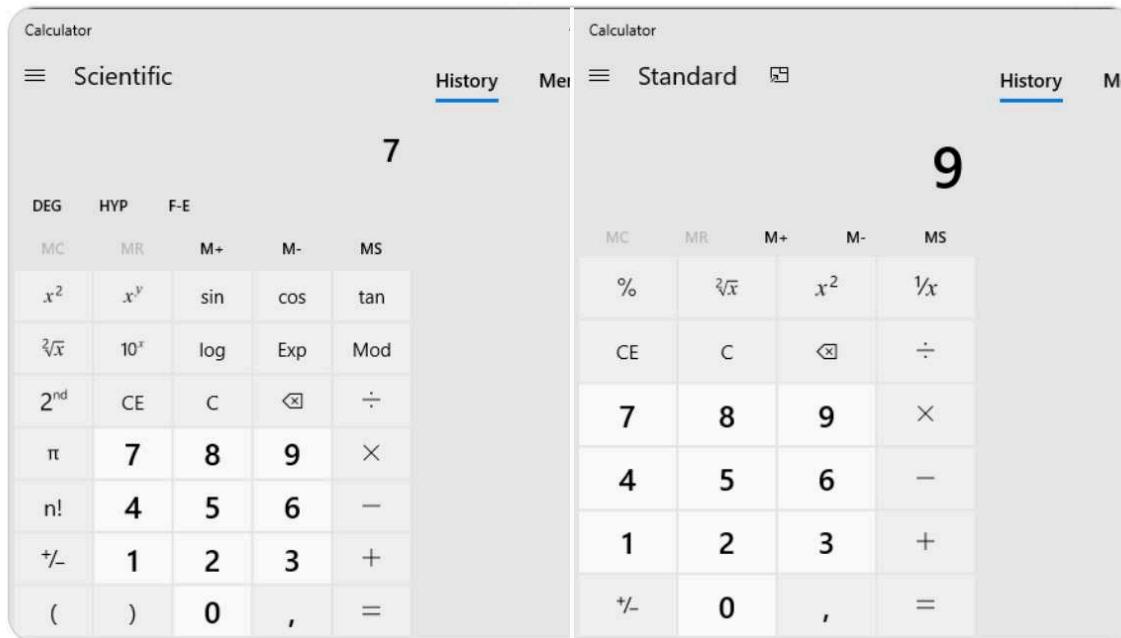
▼

How much is $1 + 2 * 3$?

According to [@Windows 10](#), the result depends on the mode that you have chosen!!!!

The Calculator app gives the correct result in Scientific mode and a wrong result with the default mode called Standard.

I bet this caused thousands of wrong calculations!



Formal verification or testing?

```
procedure insert2 (integer x, t)
begin B[t] ← B[t] ∨ (2 ↑ (x mod 16));
    size[t] ← size[t] + 1;
    if x < least[t] then least[t] ← x
    else if x > greatest[t] then greatest[t] ← x;
end;
```

The implementation of deletion would be similar. It is safe to use 0 and $2^{16}-1$ for $-\infty$ and $+\infty$.

Beware of bugs in the above code; I have only proved it correct, not tried it.

THE CORRESPONDENCE BETWEEN DONALD E.
KNUTH AND PETER VAN EMDE BOAS ON PRIORITY
DEQUES DURING THE SPRING OF 1977

Formal verification or testing?

xavierleroy commented on 12 Jul 2018

Contributor + 😊 ...

Fixed in commit [abf674c](#). Thanks @mtrigger for the report and @m-schmidt for the fix.

The test suite for GCC builtins looks very interesting. CompCert's formal verification doesn't cover builtin functions, so we need more testing here.

Support of GCC Builtins

<https://github.com/AbsInt/CompCert/issues/243>

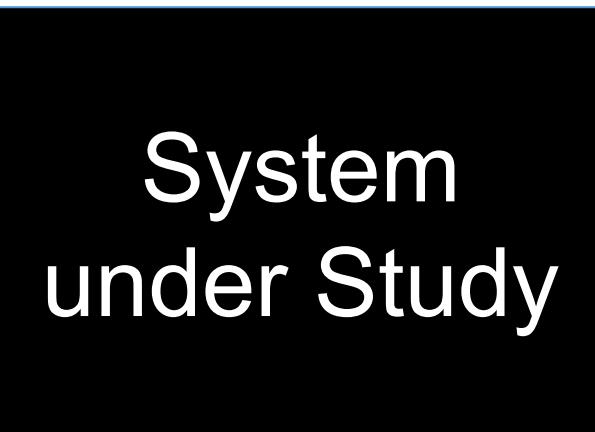
Plan

- Testing Problem
 - Test Generation Problem (input)
 - Oracle Problem (output)
- Assertion-based testing
- Mutation Testing
- Test Generation
- Metamorphic Testing
- Multimorphic Testing

Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

Input

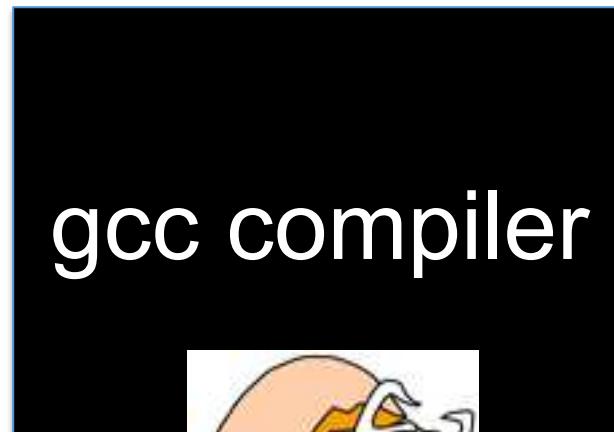


Output

Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

C programs



Assembly
codes

Configuration is an additional part of the (test) input!



See [Options that Control Optimization](#).

```
-faggressive-loop-optimizations
-falign-functions=[n[:m:[n2[:m2]]]]
-falign-jumps=[n[:m:[n2[:m2]]]]
-falign-labels=[n[:m:[n2[:m2]]]]
-falign-loops=[n[:m:[n2[:m2]]]]
-fasynchronous-thread-profile-future-profile=at
-automatic-vectorizer-abilities
-fbranch-target-load-optimize=fbranch-target-load-optimize2
-fbranch-bb-exclusive -fcaller-saves
-fcombine-stack-adjustments -fconserve-stack
-fcompare-elim -fcprop-registers -fcrossjumping
-fcse-follow-jumps -fcse-skip-blocks -fcx-fortran-rules
-fcx-limited-range
-fdata-sections -fdce -fdelayed-branch
-fdelete-null-pointer-checks -fdevirtualize -fdevirtualize-speculatively
-fdevirtualize-at-ltrans -fdse
-fearly-inlining -fipa-sra -fexpensive-optimizations -ffat-lto-objects
-ffast-math -ffinite-math-only -ffloat-store -fexcess-precision=style
-fforward-propagate -ffp-contract=style -ffunction-sections
-fgcse -fgcse-after-reload -fgcse-las -fgcse-lm -fgraphite-identity
-fgcse-sm -fhoist-adjacent-loads -fif-conversion
-fif-conversion2 -findirect-inlining
-finline-functions -finline-functions-called-once -finline-limit=n
-finline-small-functions -fipa-cp -fipa-cp-clone
-fipa-bit-cp -fipa-vrp -fipa-pta -fipa-profile -fipa-pure-const
-fipa-reference -fipa-reference-addressable
-fipa-stack-alignment -fipa-ifc -fira-algorithm=algorithm
-fira-region=region -fira-hoist-pressure
-fira-loop-pressure -fno-ira-share-save-slots
-fno-ira-share-spill-slots
-fisolate-erroneous-paths-dereference -fisolate-erroneous-paths-attribute
-fivopts -fkeep-inline-functions -fkeep-static-functions
-fkeep-static-consts -flimit-function-alignment -flive-range-shrinkage
-floop-block -floop-interchange -floop-strip-mine
-floop-unroll-and-jam -floop-nest-optimize
-floop-parallelize-all -fira-remat -flto -flto-compression-level
-flto-partition=alg -fmerge-all-constants
-fmerge-constants -fmodulo-sched -fmodulo-sched-allow-regmoves
-fmove-loop-invariants -fno-branch-count-reg
-fno-defer-pop -fno-fp-int-built-in-exact -fno-function-cse
-fno-guess-branch-probability -fno-inline -fno-math-errno -fno-peephole
-fno-peephole2 -fno-printf-return-value -fno-sched-interblock
-fno-sched-spec -fno-signed-zeros
-fno-toplevel-reorder -fno-trapping-math -fno-zero-initialized-in-bss
-fomit-frame-pointer -foptimize-sibling-calls
-fpartial-inlining -fpeel-loops -fpredictive-commoning
-fprefetch-loop-arrays
-fprofile-correction
```

gcc (compiler): 200+ options
Boolean options

Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

Training
set

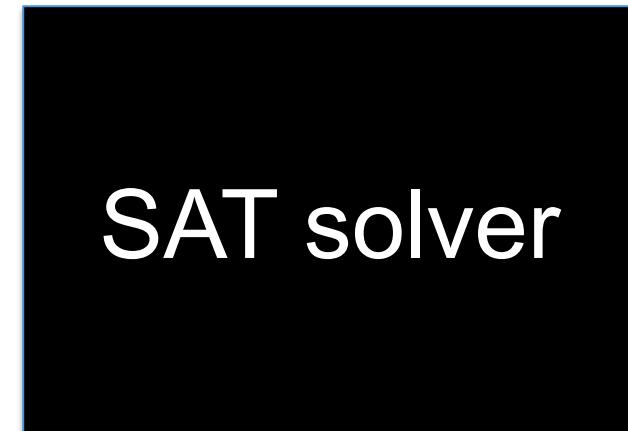
Machine
Learning
(classifier)

Accuracy

Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

SAT
formulae



SAT/UNSAT

Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

Wikipedia
pages
(HTML or Wikitext format)



CSV files

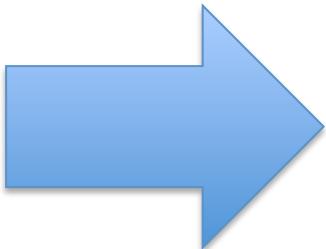


<http://blog.mathieuacher.com/WikipediaMatrixChallenge/>

How to automatically extract tabular data out of Wikipedia pages?



WIKIPEDIA
The Free Encyclopedia



CSV
(Comma Separated Values)

Product	Image process...	Sensor format	Sensor type	Sensor manufac...	Megapixels	Focus points	Metering pixels	Viewfinder cov...
D3X	EXPPEED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D1X	-	APS-C	CCD	Sony	5.3	5	1005	96%
D1	-	APS-C	CCD	Sony	2.66	5	1005	96%
D4S	EXPPEED 4	Full-frame	CMOS	Nikon	16.2	51	91000	100%
D4	EXPPEED 3	Full-frame	CMOS	Nikon	16.2	51	91000	100%
D5S	EXPPEED	Full-frame	CMOS	Nikon	12.1	51	1005	100%
D3	EXPPEED	Full-frame	CMOS	Nikon	12.1	51	1005	100%
D2Hs	-	APS-C	JETTL-BCAST	Nikon	4.1	11	1005	100%
D2H	-	APS-C	JETTL-BCAST	Nikon	4.1	11	1005	100%
D1H	-	APS-C	CCD	Sony	2.7	5	1005	96%
D810	EXPPEED 4	Full-frame	CMOS	Sony	36.5	51	91000	100%
D600	EXPPEED 3	Full-frame	CMOS	Sony	36.3	51	91000	100%
D700	EXPPEED	Full-frame	CMOS	Nikon	12.1	51	1005	96%
D700	EXPPEED 4	Full-frame	CMOS	Nikon	24.8	51	91000	100%
D1	EXPPEED 3	Full-frame	CMOS	Nikon	16.2	39	2016	100%

diversity of Wikipedia pages (input)
difficulty of assessing an extractor (output)

WikipediaMatrix

https://en.wikipedia.org/wiki/Comparison_of_Canon_EOS_digital_cameras

Article

Talk

Read

Edit

View history

Search Wikipedia



Wiki Loves Monuments: Photograph a monument, help Wikipedia and win!



Comparison of Canon EOS digital cameras

From Wikipedia, the free encyclopedia

The following tables provide general information as well as a comparison of technical specifications for a number of Canon EOS digital cameras.

General information [edit]

Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Viewfinder magnification, coverage	Display size, dots (ratio)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions, WxHxD (mm)	Video	Main Battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 × 158 × 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 × 158 × 80	-	NP-E3
1Ds Mk III	Dual DIGIC III	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 × 160 × 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 × 158 × 80	-	NP-E3
1D Mk II	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 × 158 × 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 × 158 × 80	-	NP-E3
1D Mk III	Dual DIGIC III	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 × 157 × 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	APS-H CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 920k	No	Yes	10	CF, SD	2009Q4	1.180	156 × 157 × 80	1080p30	LP-E4

WikipediaMatrix

https://en.wikipedia.org/wiki/Comparison_of_Canon_EOS_digital_cameras

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1D Mk IV	Dual DIGIC 4	APS-H CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 920k	No	Yes	10	CF, SD	2009Q4	1.180	156 x 157 x 80	1080p30	LP-E4

```
==General information==
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|-
! Model
! Image processor
! Sensor format
! Megapixels
! Min ISO
! Max ISO
! Autofocus points
! Viewfinder
magnification,
coverage
! Display
size, dots

(ratio)
! Touch
screen
! Live view
! Max FPS
! Storage
```

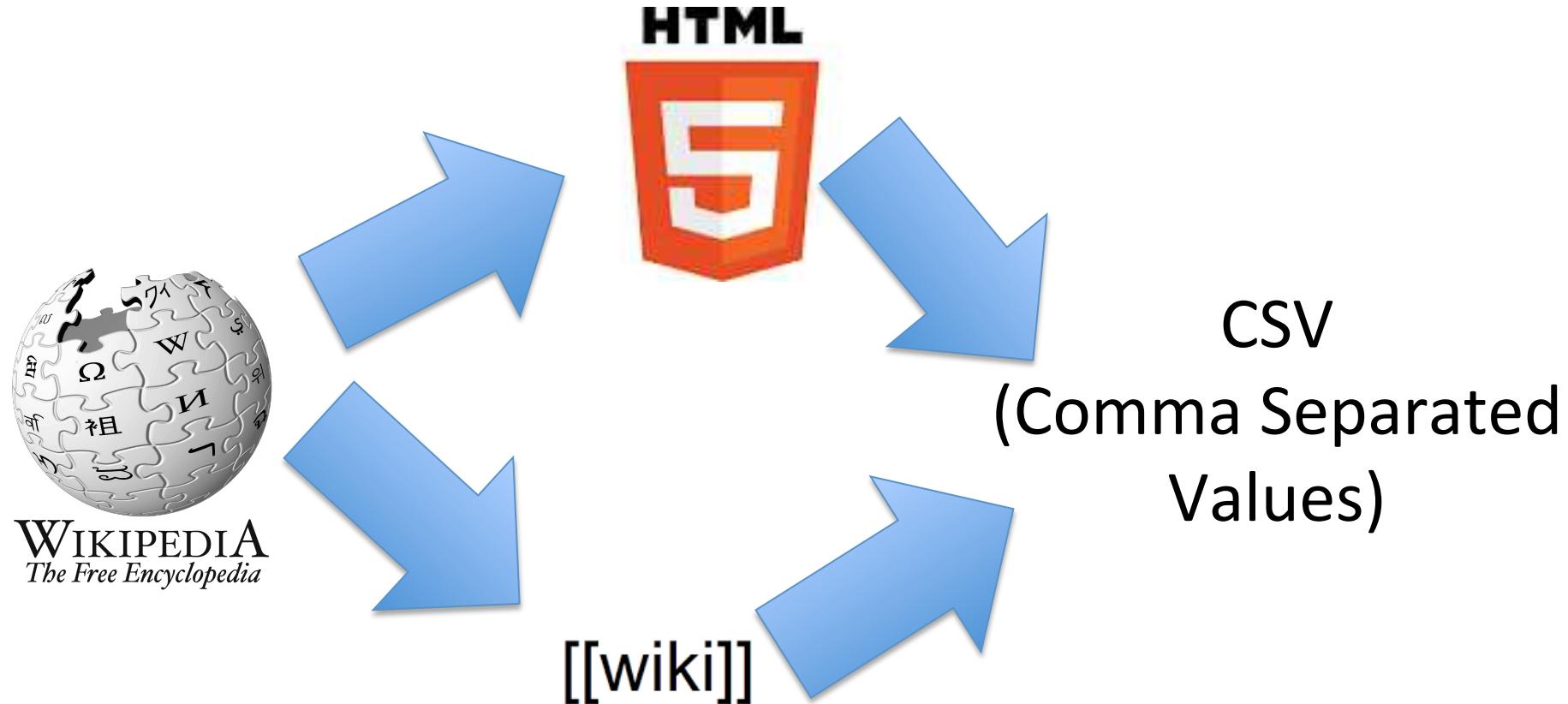
Wikitext

[[wiki]]

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</th>
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<th>Sensor format
</th>
<th>Megapixels
</th>
<th>Min ISO
</th>
<th>Max ISO
</th>
<th>Autofocus points
</th>
<th>Viewfinder
<p>magnification,
</p><p>coverage
</p>
</th>
<th>Display
<p>size, dots
</p><p>(ratio)
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</th>
<th>Touch
<p>screen
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<th>Live view
</th>
<th>Max FPS
</th>
<th>Storage
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WikipediaMatrix



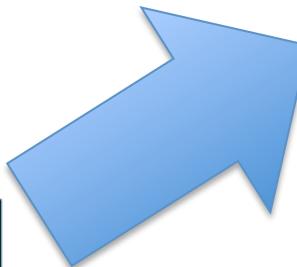
WikipediaMatrix

HTML

Comparison_between_Esperanto_and_Ido
Comparison_between_Esperanto_and_Interlingua
Comparison_between_Esperanto_and_Novial
Comparison_between_Ido_and_Interlingua
Comparison_between_Ido_and_Novial
Comparison_between_U.S._states_and_countries_by_GDP_(PPP)
Comparison_of_ALGOL_68_and_C++
Comparison_of_Afrikaans_and_Dutch
Comparison_of_Android_e-book_reader_software
Comparison_of_Asian_national_space_programs
Comparison_of_Axis_&_Allies_games
Comparison_of_C_Sharp_and_Visual_Basic_.NET
Comparison_of_Chernobyl_and_other_radioactivity_releases
Comparison_of_Exchange_ActiveSync_clients
Comparison_of_Hokkien_writing_systems
Comparison_of_Home_Owners'_and_Civic_Associations
Comparison_of_IOC,_FIFA,_and_ISO_3166_country_codes
Comparison_of_Java_and_C++
Comparison_of_Linux_distributions
Comparison_of_MD_and_DO_in_the_United_States
Comparison_of_Norwegian_Bokmål_and_Standard_Danish
Comparison_of_Portuguese_and_Spanish
Comparison_of_Symbian_devices
Comparison_of_United_States_presidential_candidates,_2008
Comparison_of_World_War_I_tanks
Comparison_of_browser_synchronizers
Comparison_of_business_integration_software
Comparison_of_consumer_brain-computer_interfaces
Comparison_of_domestic_robots
Comparison_of_e-book_formats
Comparison_of_e-book_readers
Comparison_of_file_hosting_services
Comparison_of_layout_engines_(Cascading_Style_Sheets)
Comparison_of_layout_engines_(MathML)

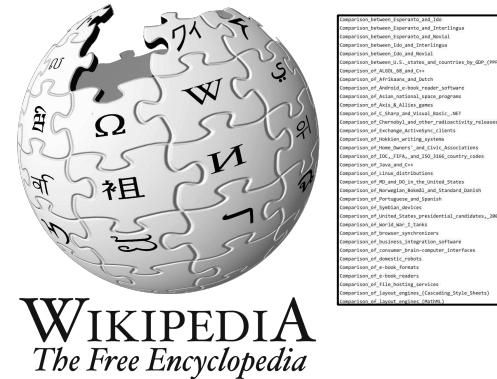


CSV
(Comma Separated
Values)

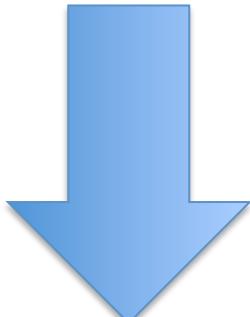


Thousands of Wikipedia pages!

WikipediaMatrix: The Truth



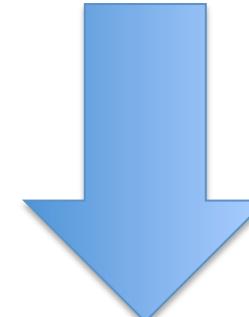
Extractor1



CSV1



Extractor2



CSV2

Who's right?



Tests

(input)

Product	Image processor	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
Find								
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs								
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D1X	-	APS-C	CMOS	Sony	5.3	11	1005	100%
D3X	-	CCD	Sony	-	5	1005	-	98%

Article Talk Read Edit View history Search Wikipedia

Comparison of Canon EOS digital cameras

From Wikipedia, the free encyclopedia

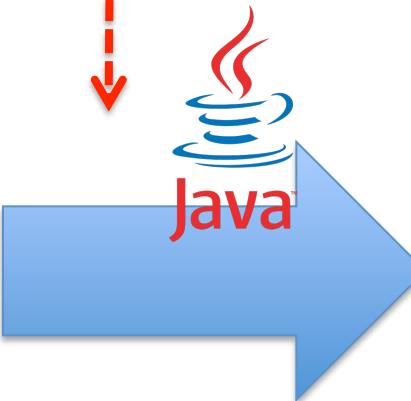
The following tables provide general information as well as a comparison of technical specifications for a number of Canon EOS digital cameras.

General information [edit]

Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Display magnification, coverage	Display size, dots (pixel)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main Battery
1Ds	DIGIC	Full-frame	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame	16.7	50	3200	45	0.70x, 100%	2.0", 120k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E3
1Ds Mk III	Dual DIGIC II	Full-frame	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.215	156 x 158 x 80	-	LP-E4
1D	DIGIC	APS-H	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
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1D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

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(transformation)

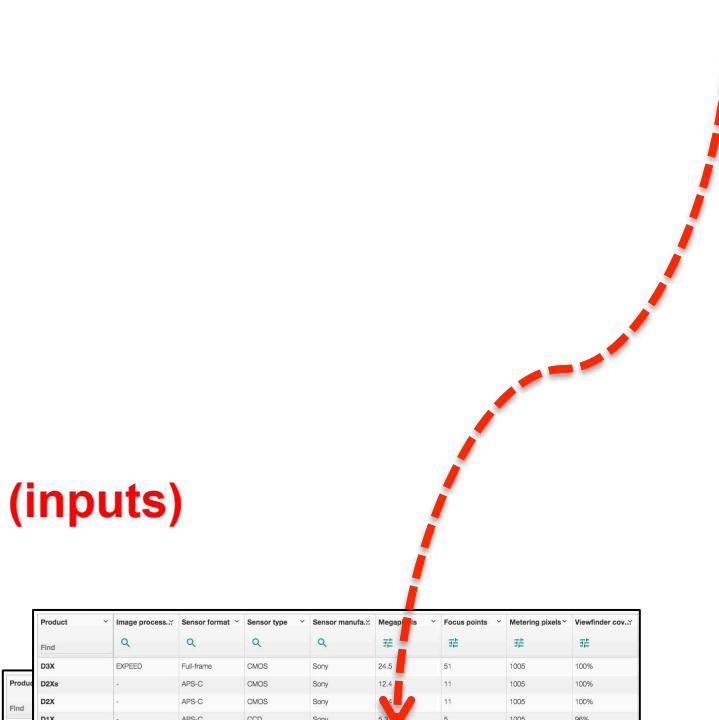


(output)

example
CSV

Tests

(inputs)



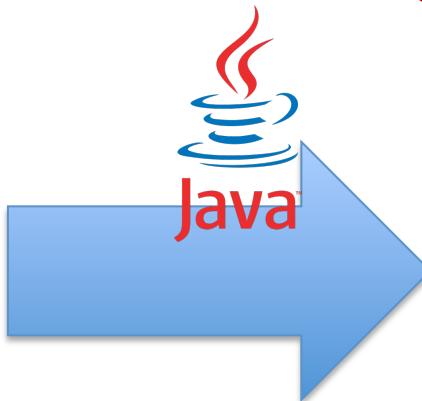
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43 / 43



example
CSV

Tests

(inputs)

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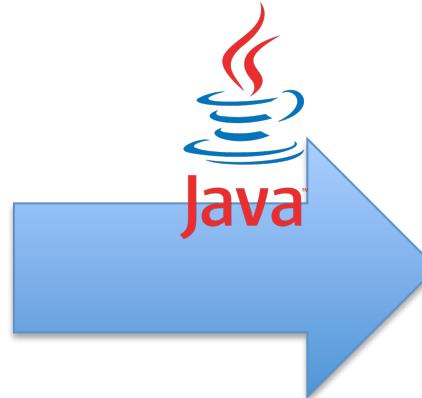
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Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Display magnification, coverage	Display size, dots (x,y)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E3
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.215	156 x 158 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II Dual DIGIC II	DIGIC II	CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

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RuntimeException....



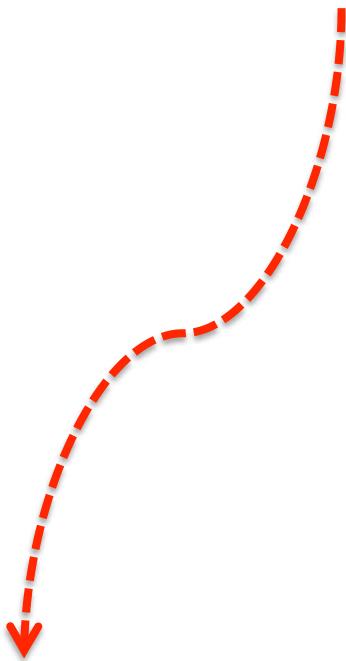
example

CSV



Tests

(input)



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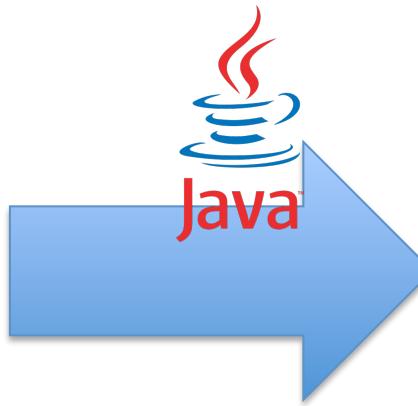
Comparison of Canon EOS digital cameras

From Wikipedia, the free encyclopedia

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General information [edit]

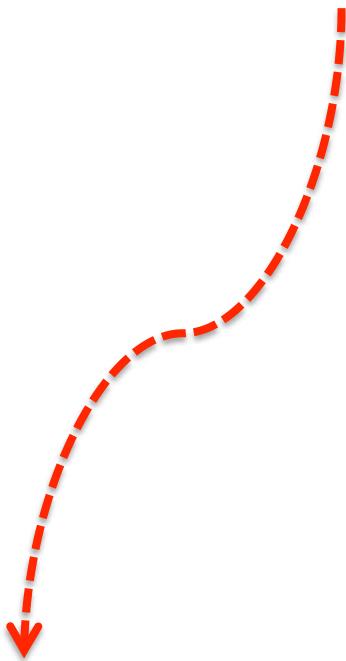
Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Viewfinder magnification, coverage	Display size, dots (pixels)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.215	156 x 158 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10 Mx II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10 Mx II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.220	156 x 158 x 80	-	NP-E3
1D Mk II	Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10 Mx IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



F1;f2; , ;
“” . ” .
‘’ , ,

Tests

(input)



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Comparison of Canon EOS digital cameras

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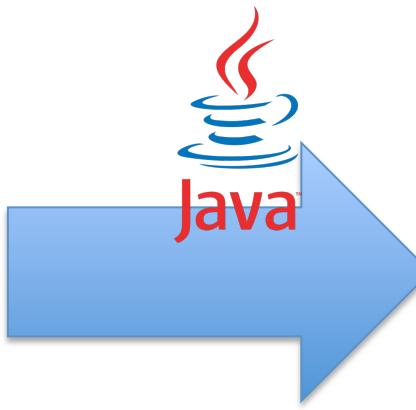
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1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 150 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 156 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
10D Mk II Dual DIGIC II	DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



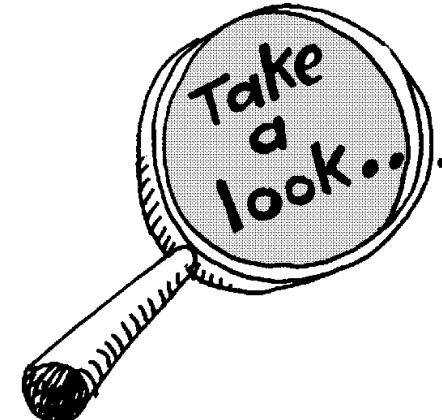
f1,f2,f3
v11,v12,v13
v21,v22,v23



example

CSV

You can start with some values/inputs and then (manually) observe



Article Talk Read Edit View history Search Wikipedia Q

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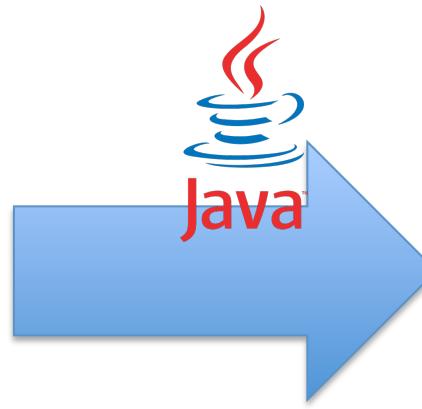
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1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	6.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
10D Mk II Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4	
10D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



f1,f2,f3
v11,v12,v13
v21,v22,v23

example

CSV



But manual testing is a terrible idea

non reproducible; error-prone; time-consuming



Article Talk Read Edit View history Search Wikipedia Q

Wiki Loves Monuments: Photograph a monument, help Wikipedia and win!

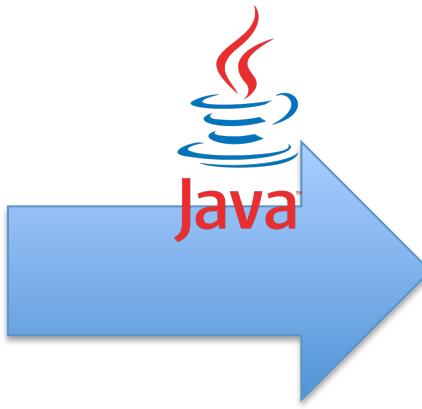
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1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.70x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	6.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II Dual DIGIC II	DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV Dual DIGIC 4	DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



f1,f2,f3
v11,v12,v13
v21,v22,v23

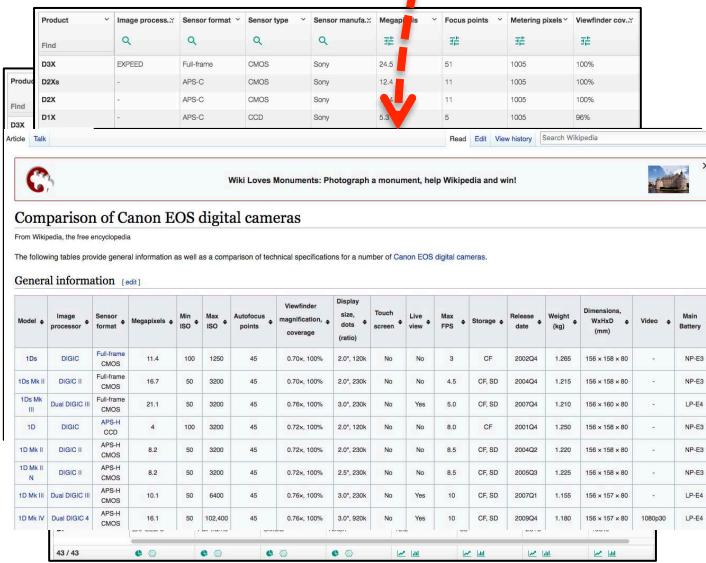
example

CSV



Tests

(input)



The screenshot shows a Wikipedia page comparing Canon EOS cameras. At the top, there's a search bar and a navigation menu. Below the header, there's a table with various camera models listed. A red arrow points from the text '(input)' to the table. To the right of the table, there's a sidebar with the text 'Wiki Loves Monuments: Photograph a monument, help Wikipedia and win!' and a small image of a camera.

Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Display magnification, coverage	Display size, dots (pixel)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main Battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 156 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 156 x 80	-	NP-E3
10 Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10 Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II	Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10 Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

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Observations and assertions



f₁, f₂, f₃
v₁₁, v₁₂, v₁₃
v₂₁, v₂₂, v₂₃

example

CSV



Automated testing

(You cannot test using one single page!)

Product	Image process.	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D3X	-	APS-C	CCD	Sony	5.3	5	1005	98%

Comparison of Canon EOS digital cameras

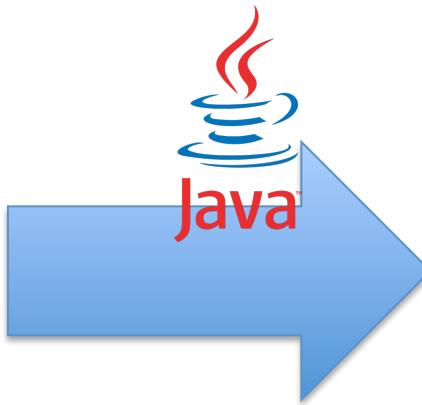
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Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Display magnification, coverage	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main Battery	
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 156 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 156 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4	
1D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

Case by case verification



f1,f2,f3
v11,v12,v13
v21,v22,v23

example

CSV

Automated testing

Case by case
verification?

Challenge: identify a set of
input that is covering enough
cases

Generic
properties?

Product	Image process.	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D3	-	APS-C	CCD	Sony	5.3	5	1005	98%

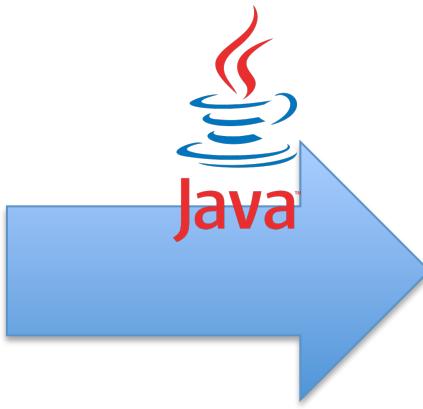
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1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.7x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.7x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.7x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk III	DIGIC II	APS-H	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk IV	Dual DIGIC 4	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk V	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.115	156 x 157 x 80	1080p30	LP-E4



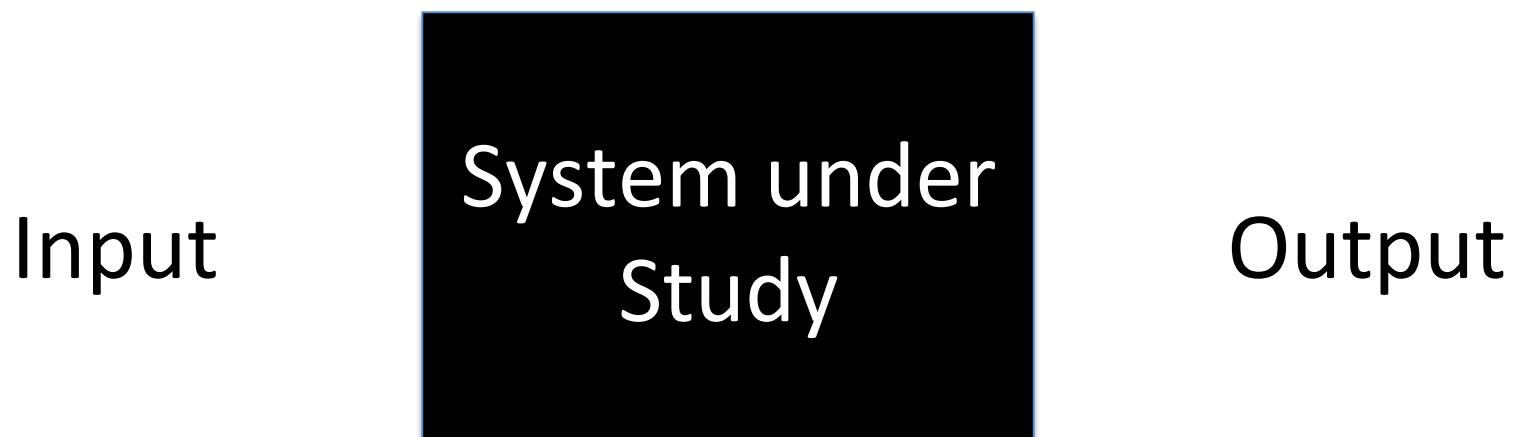
f1,f2,f3
v11,v12,v13
v21,v22,v23

example

CSV

Back to the Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)



Assertion-based Testing

- Eg unit tests à la JUnit

```
@Test
def void basicOrTest() {
    val result = parseHelper.parse("""
        solver sat4j-java
        A v B
    """)
    val dimacsPrinted = DIMACSPrinter.dimacsFile(result.expression)
    val oracle = "p cnf 2 1\n1 2 0"
    Assertions.assertNotNull(result)
    val errors = result.eResource.errors
    Assertions.assertTrue(errors.isEmpty, """Unexpected errors: «errors.join(", ")»""")
    Assertions.assertTrue(dimacsPrinted == oracle)
}
```

A test engineer walks into
a bar and



Thanks to Xavier Devroey
and Gilles Perrouin for
sharing this example and
their slides!

— Bill Sempf (@sempf)

A test engineer walks into
a bar and

- orders a beer

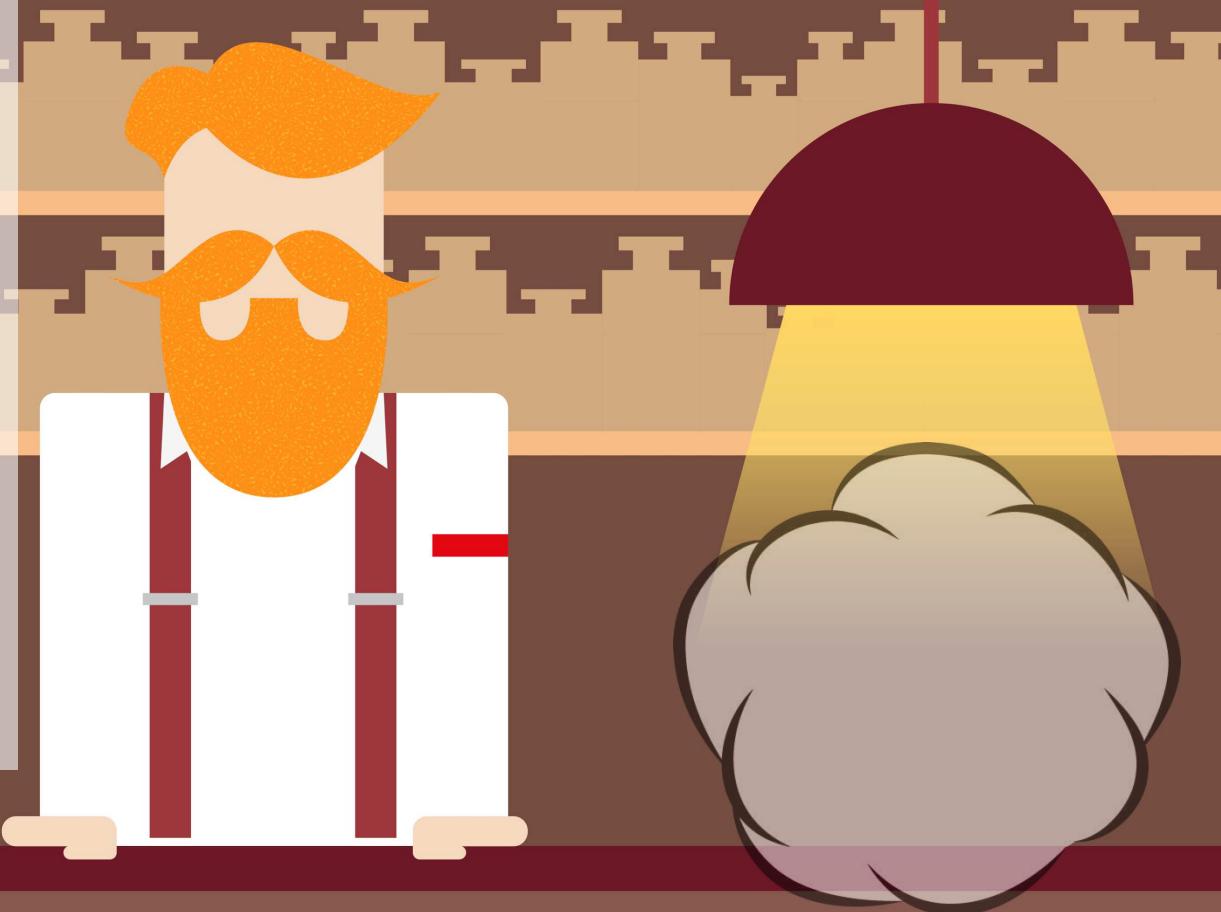
— Bill Sempf (@sempf)



A test engineer walks into
a bar and

- orders a beer
- orders 0 beers

— Bill Sempf (@sempf)



A test engineer walks into
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers

— Bill Sempf (@sempf)

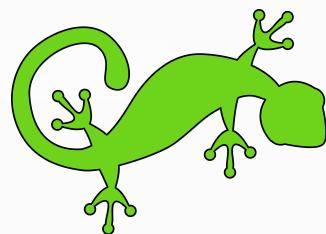
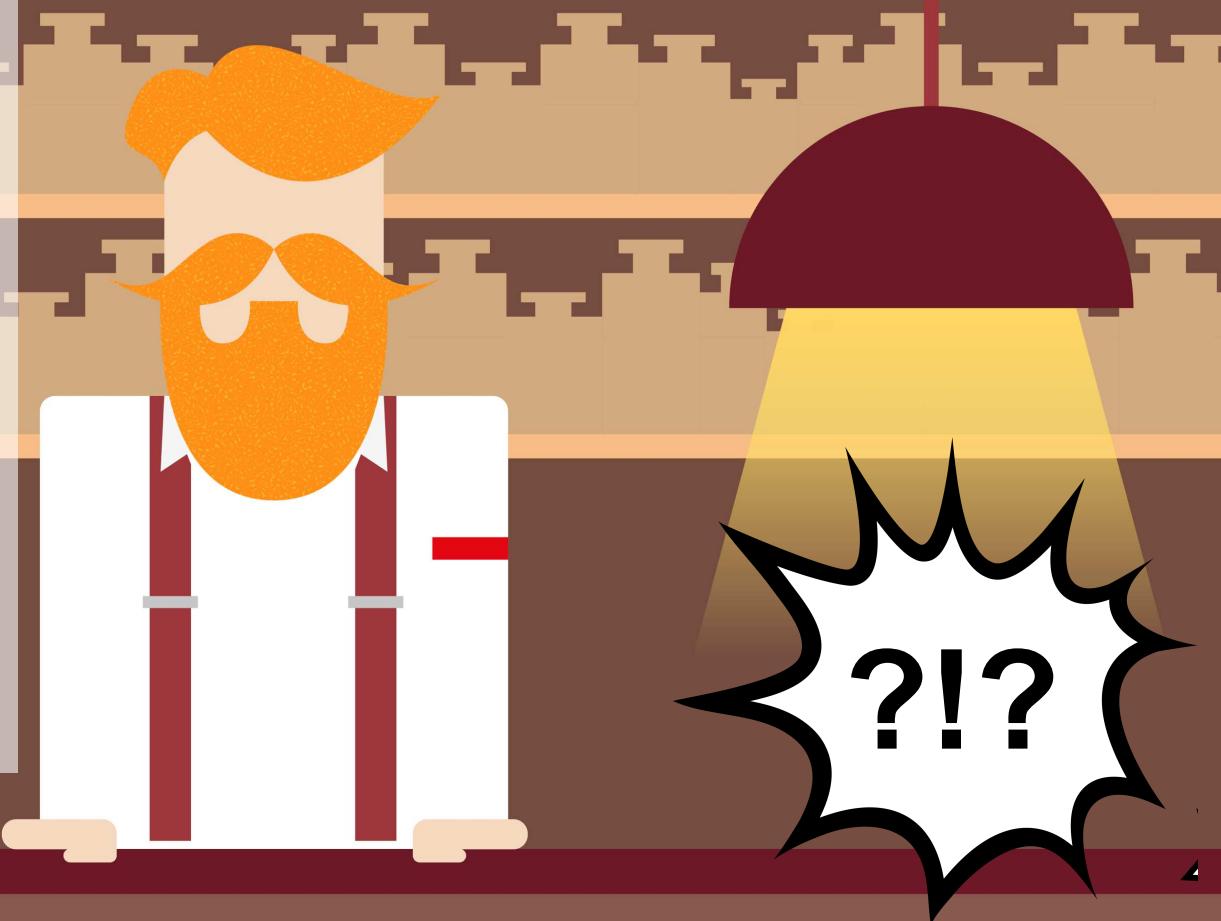
9,999,999



A test engineer walks into
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers
- orders a lizard

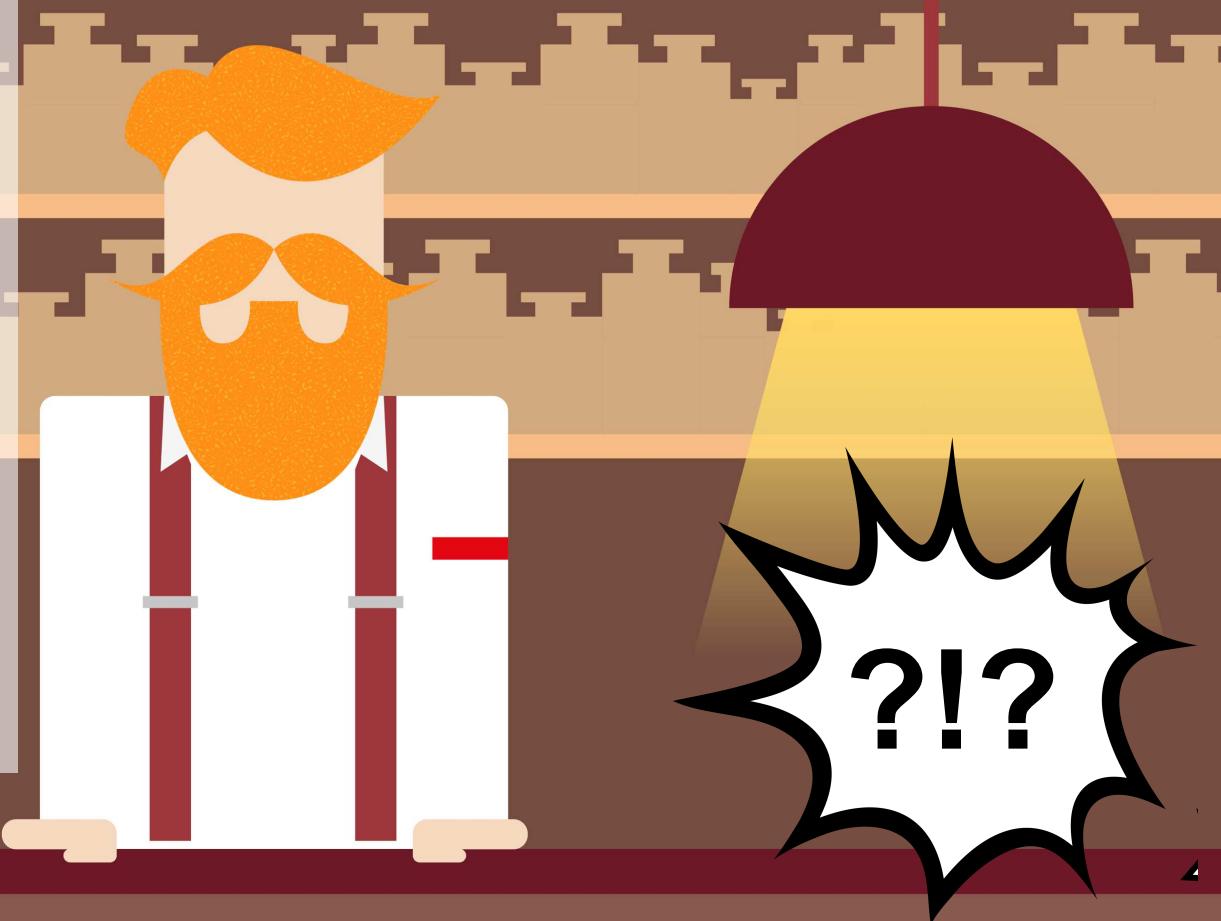
— Bill Sempf (@sempf)



A test engineer walks into
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers
- orders a lizard
- orders -1 beers

— Bill Sempf (@sempf)



-1

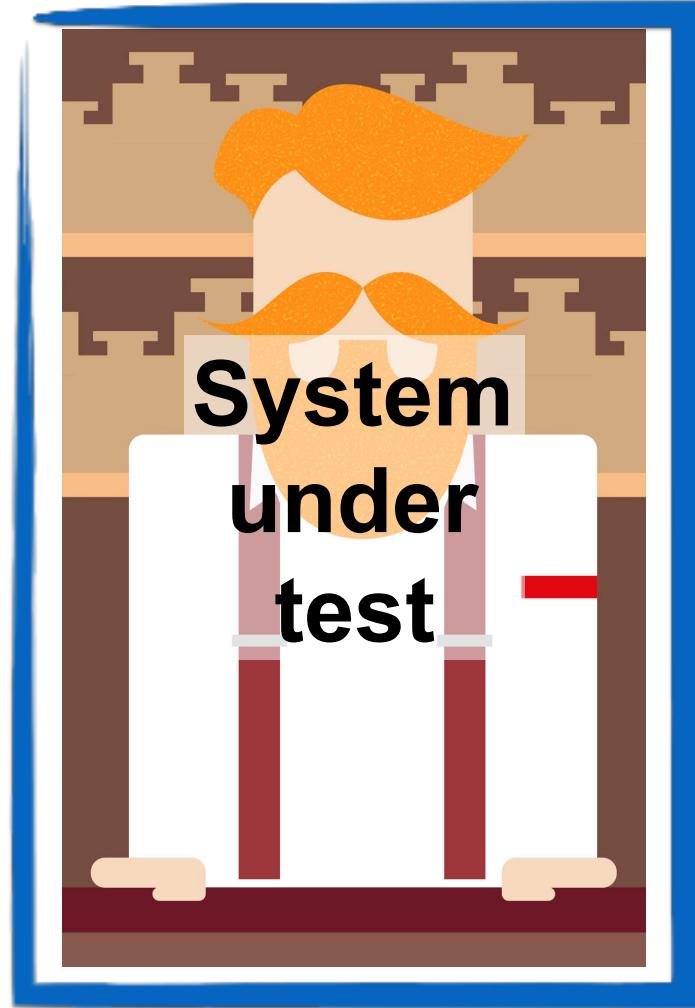
A test engineer walks into
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers
- orders a lizard
- orders -1 beers
- orders a "sfdeljknesv"

— Bill Sempf (@sempf)



"sfdeljknesv"





Specification





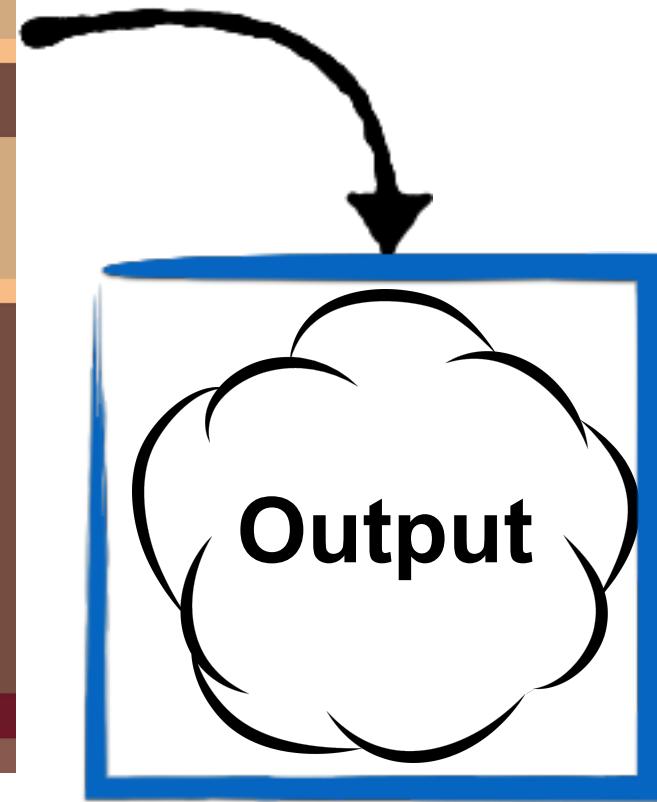
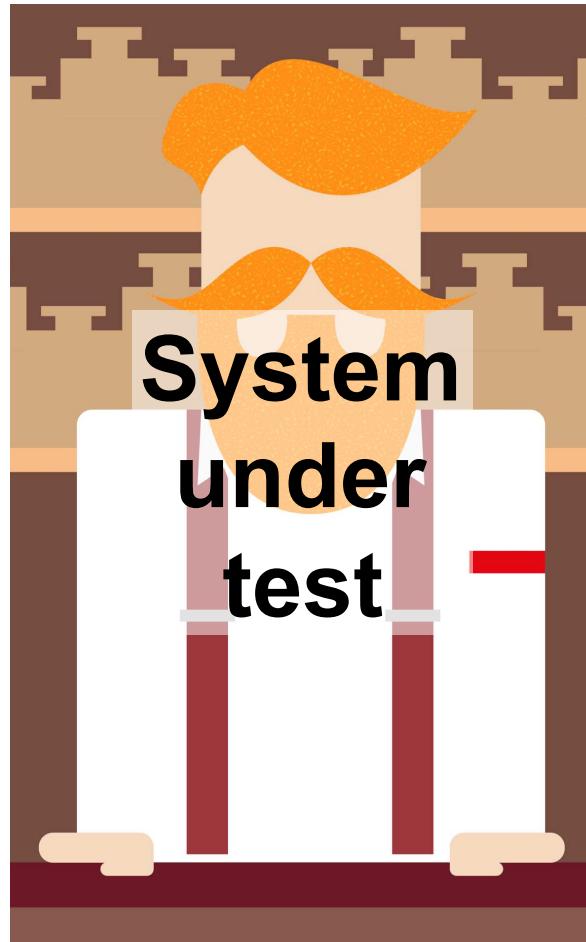
Specification

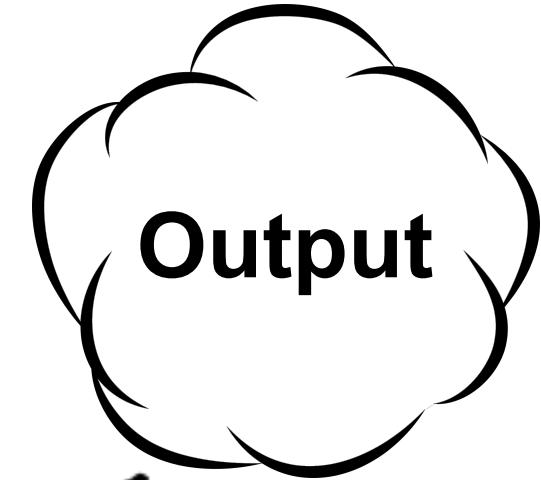
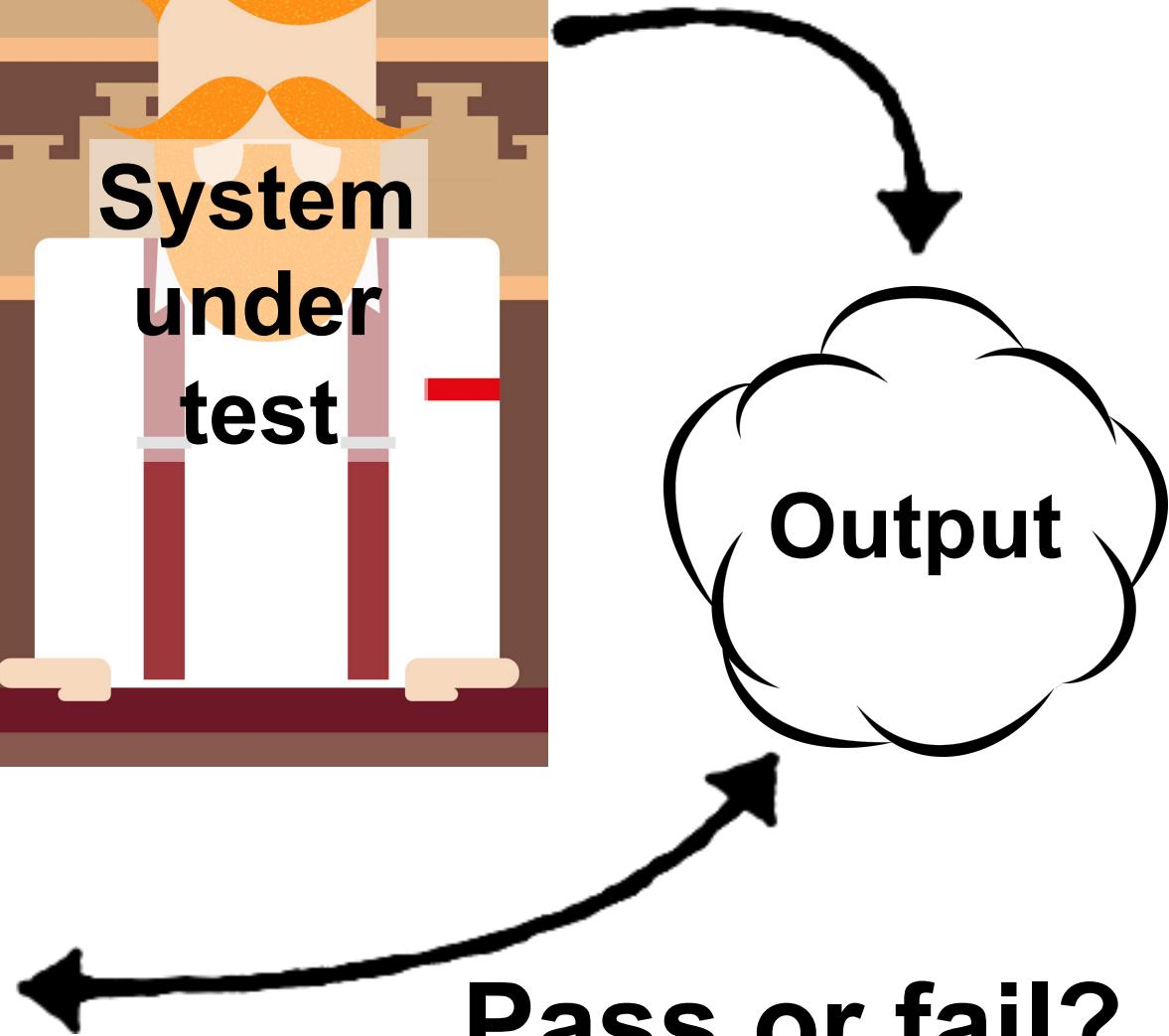
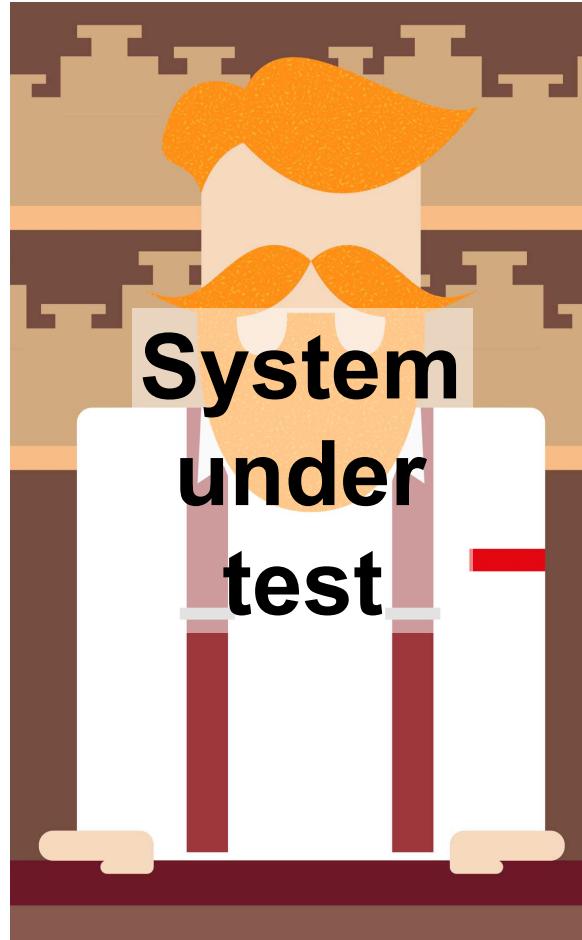


Test case



Specification





What is a test?

A test consists of

- an **input**
- an **oracle**

End-to-end test:

- Batch program: input = file, oracle = expected file
- Interactive program: input = UI events, oracle = windows

Unit test:

- Input = sequence of calls
- Oracle = assert statement



Example unit test

```
Object[] a = new Object[];  
LinkedList ll = new LinkedList();  
ll.addFirst(a);  
TreeSet ts = new TreeSet(ll);  
Set u =  
Collections.unmodifiableSet(ts);
```

input

```
assert u.equals(u);
```

oracle

Assertion fails:
used to be a bug in the JDK!

```
@Test
def void basicBiImplTest() {
    val result = parseHelper.parse('''
        solver sat4j-java
        A <=> B
    ''')
    val prettyPrinted = PrettyPrinter.prettyPrint(result.expression)

    val oracle = "(A <=> B)"

    Assertions.assertNotNull(result)
    val errors = result.eResource.errors
    Assertions.assertTrue(errors.isEmpty, '''Unexpected errors: «errors.join(", ")»'''')

    Assertions.assertTrue(prettyPrinted == oracle)
}
```

```
@Test
def void basicOrTest() {
    val result = parseHelper.parse("""
        solver sat4j-java
        A v B
    """)
    val dimacsPrinted = DIMACSPrinter.dimacsFile(result.expression)

    val oracle = "p cnf 2 1\n1 2 0"

    Assertions.assertNotNull(result)
    val errors = result.eResource.errors
    Assertions.assertTrue(errors.isEmpty, """Unexpected errors: «errors.join(", ")»""")
    Assertions.assertTrue(dimacsPrinted == oracle)
}
```

Strengths and Limits

- Precise oracles
- Domain-specific knowledge
- Examples-based
 - Input test is limited by construction
 - Incomplete (cases)
- Tests subject to developers bias
- Costly
 - One specific oracle per example (labelling)

Mutation Testing

- Based on Caroline Landry (DiverSE team, STAMP project) slides at Breizh Camp

Test Your Tests

- What do you expect from test cases?
 - Cover requirements
 - Stress the application
 - Prevent regressions
 - Reveal bugs
- Quality of test suite matters!
 - But what's a good test suite?



Test Your Tests

- What do you expect from test cases?
 - Cover requirements
 - Stress the application
 - Prevent regressions
 - **Reveal bugs**
- Quality of test suite matters!
 - But what's a good test suite?



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <=  
n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

Coverage



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}
```

Coverage



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

Coverage

```
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}  
  
@Test  
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```



Example

```
long fact(int n) {  
    if (n <= 1) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result *= i;  
    }  
    return result;  
}  
@Test  
public void testFact() {  
    assertEquals(1,  
    fact(0));  
}
```

Is this test suite good
at detecting bugs?

Coverage



Example

```
long fact(int n) {  
    @Test
```

```
    if (n <= 1) return 1;  
    else return n * fact(n - 1);  
}
```

Is this test suite good

at detecting bugs?

```
long fact(int n) {  
    @Test  
    if (n <= 1) return 1;  
    else return n * fact(n - 1);  
}  
}
```

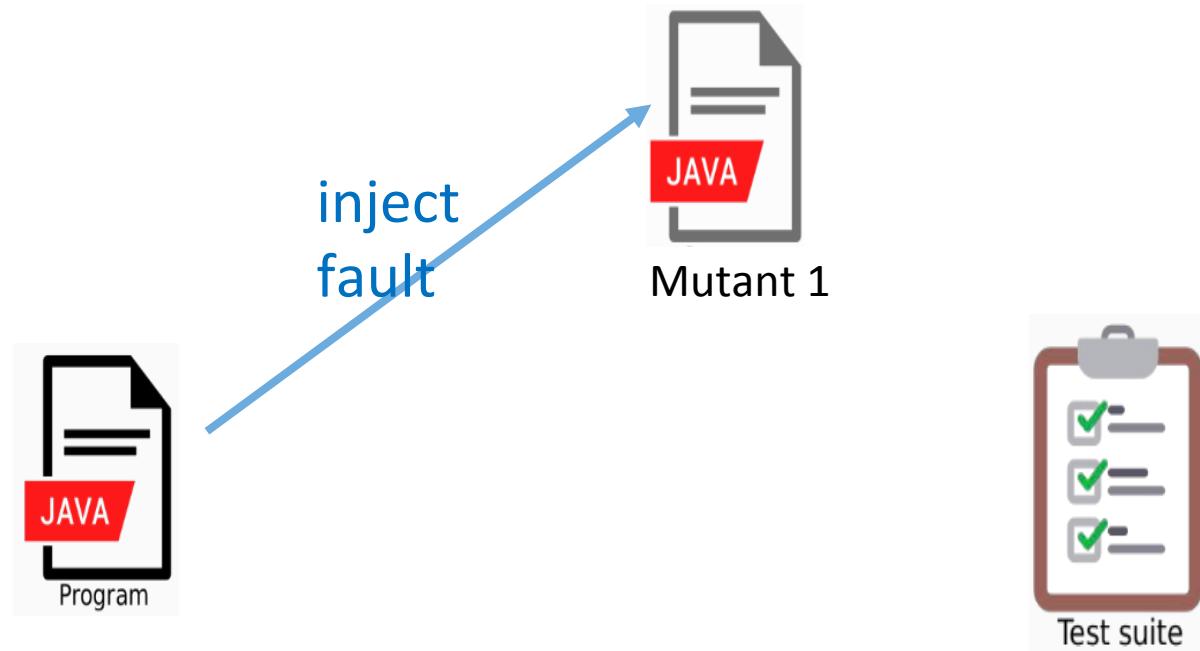
Let's mutate our code
to see.



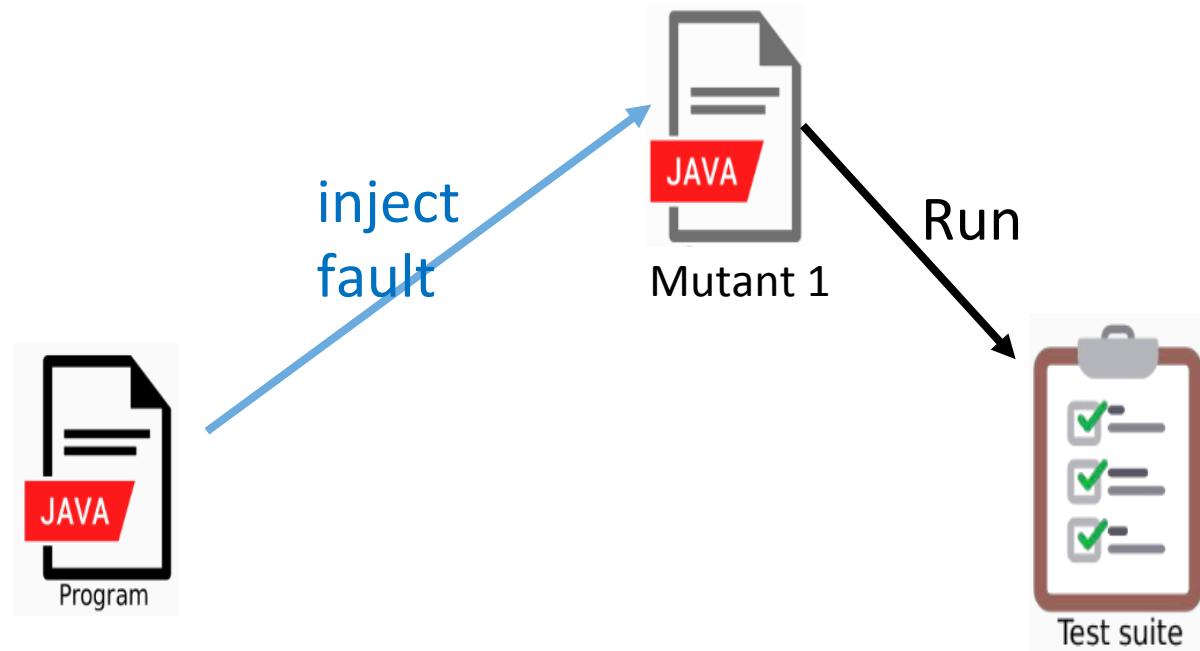
Mutation Analysis



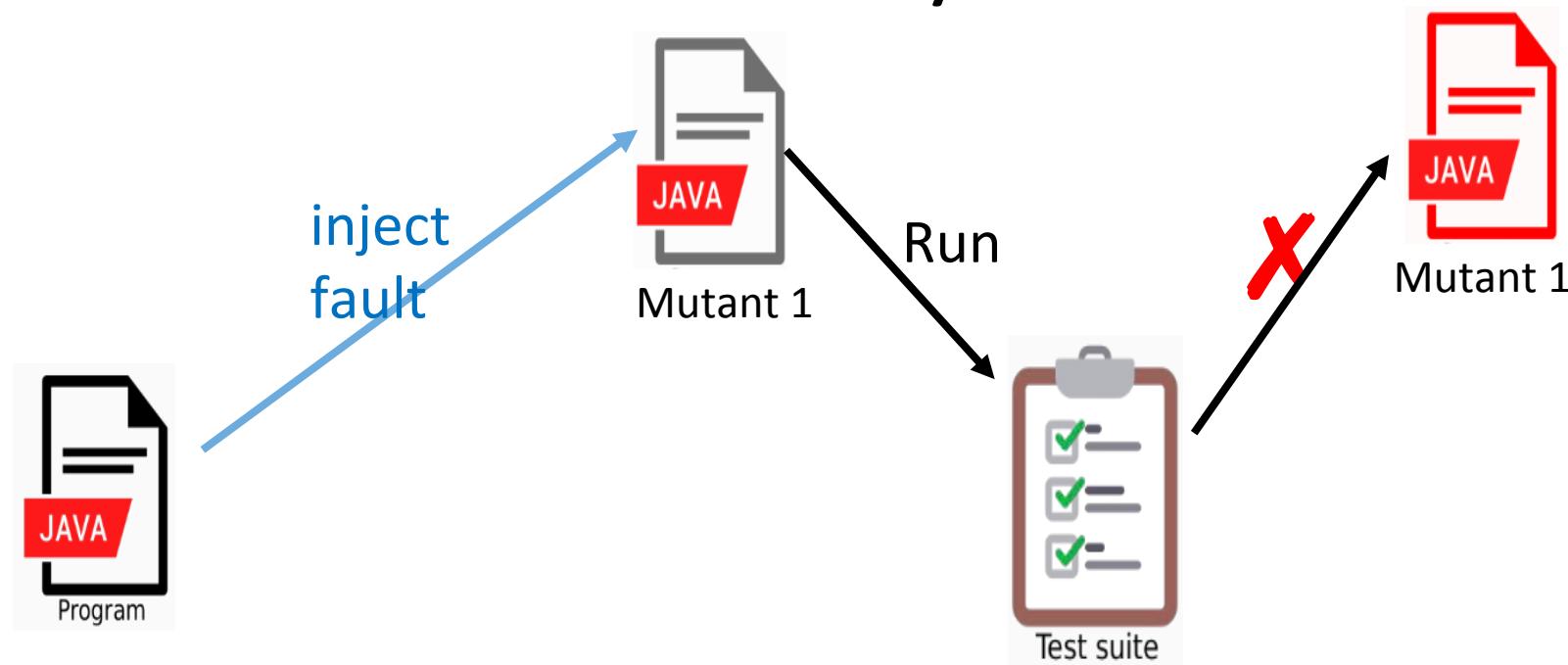
Mutation Analysis



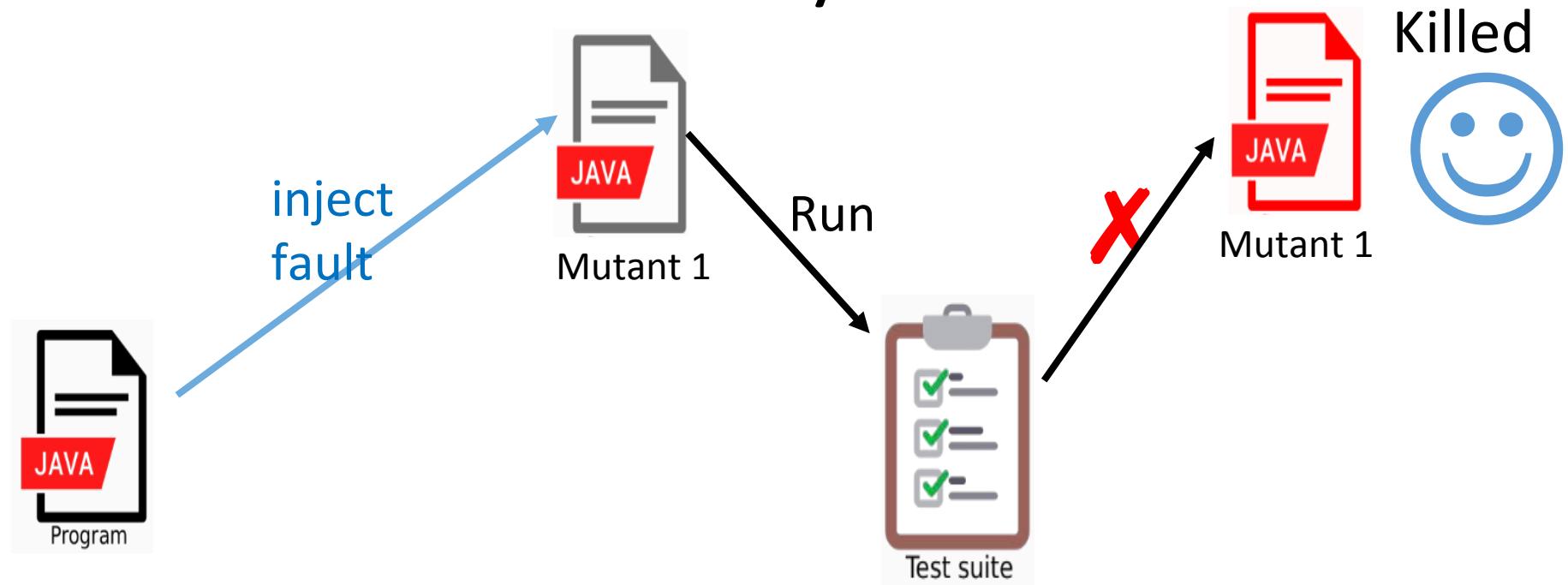
Mutation Analysis



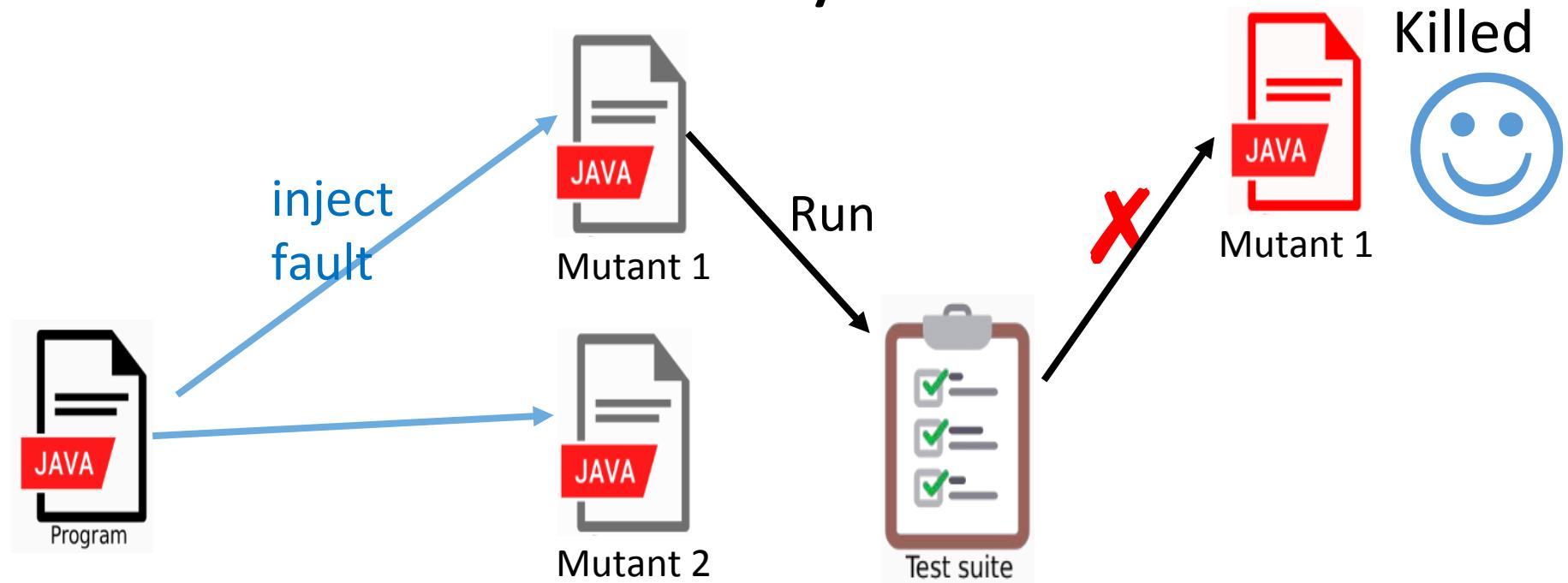
Mutation Analysis



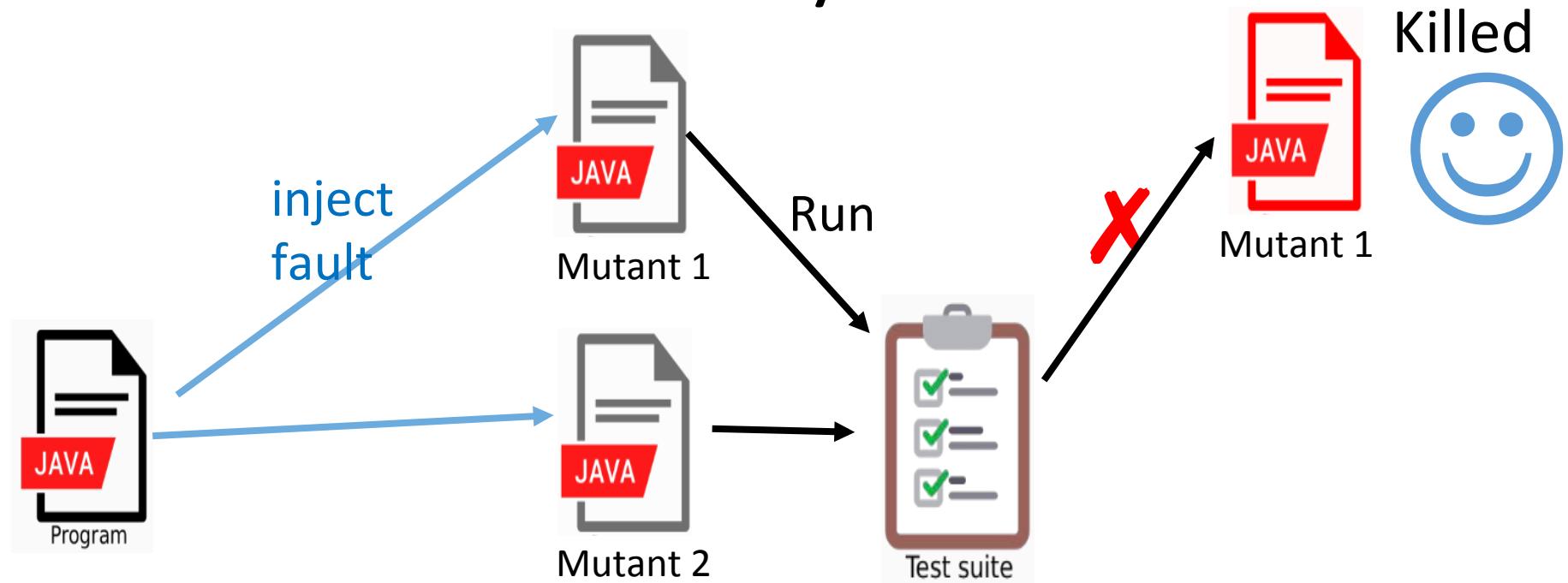
Mutation Analysis



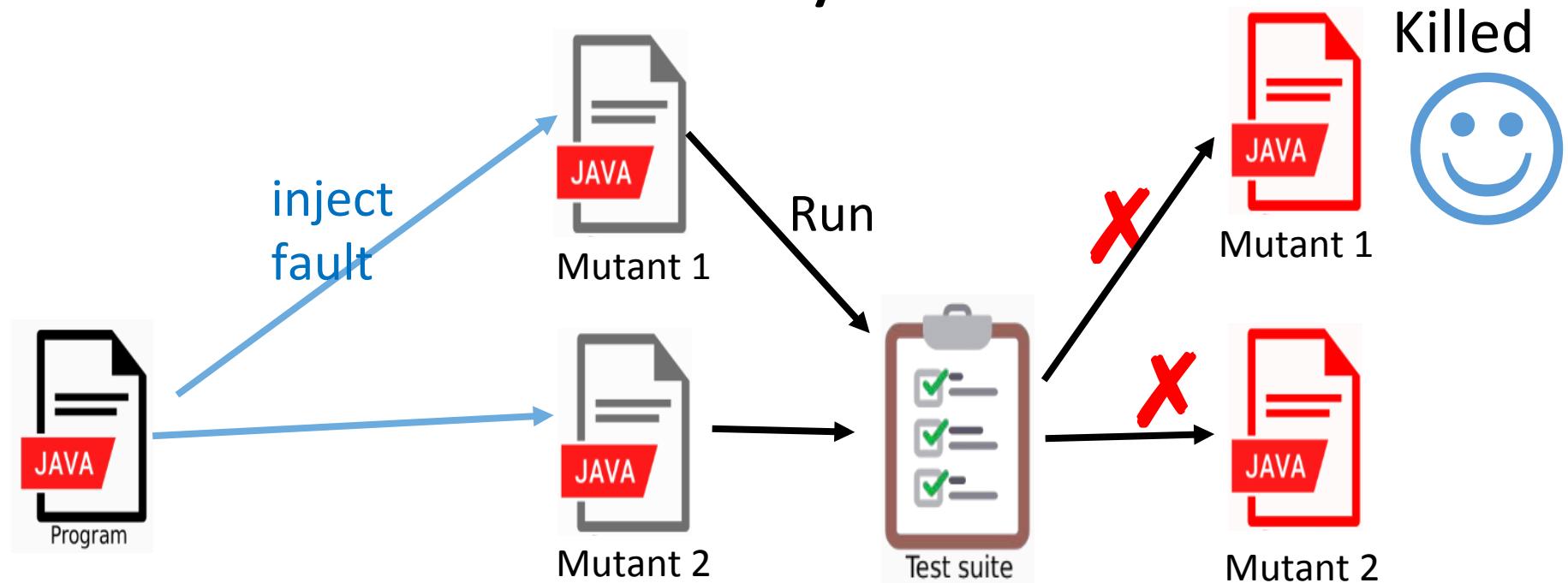
Mutation Analysis



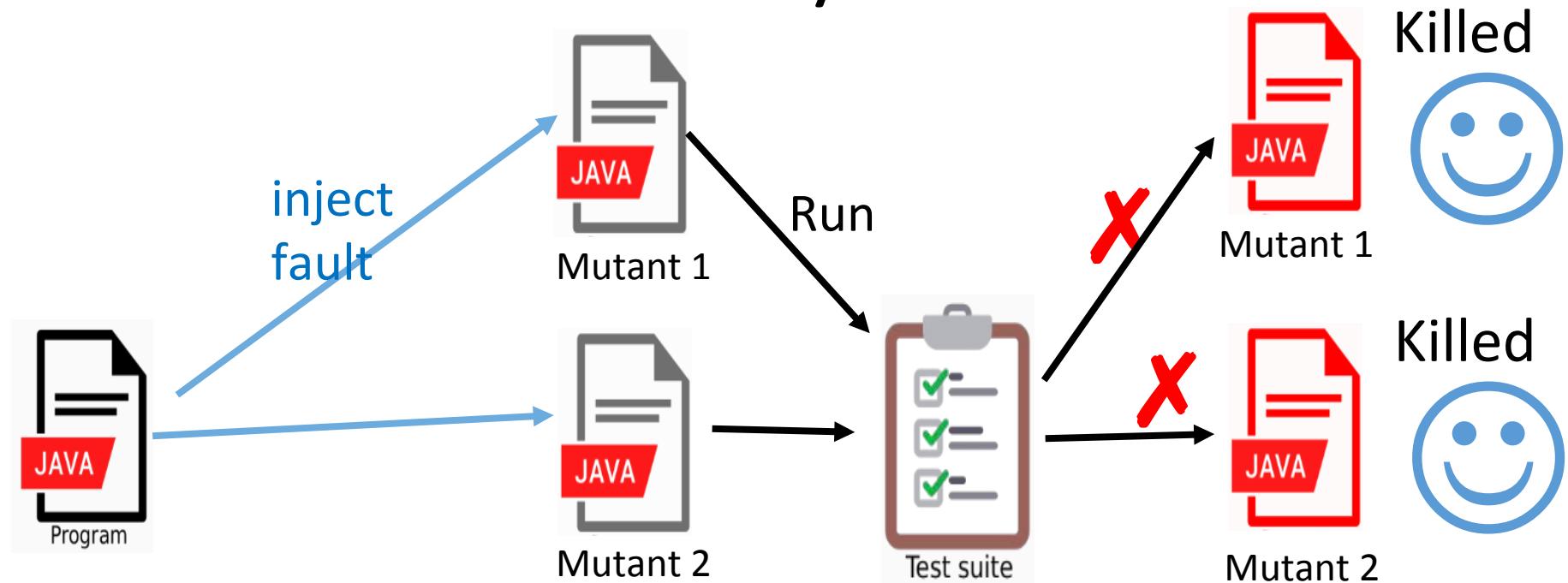
Mutation Analysis



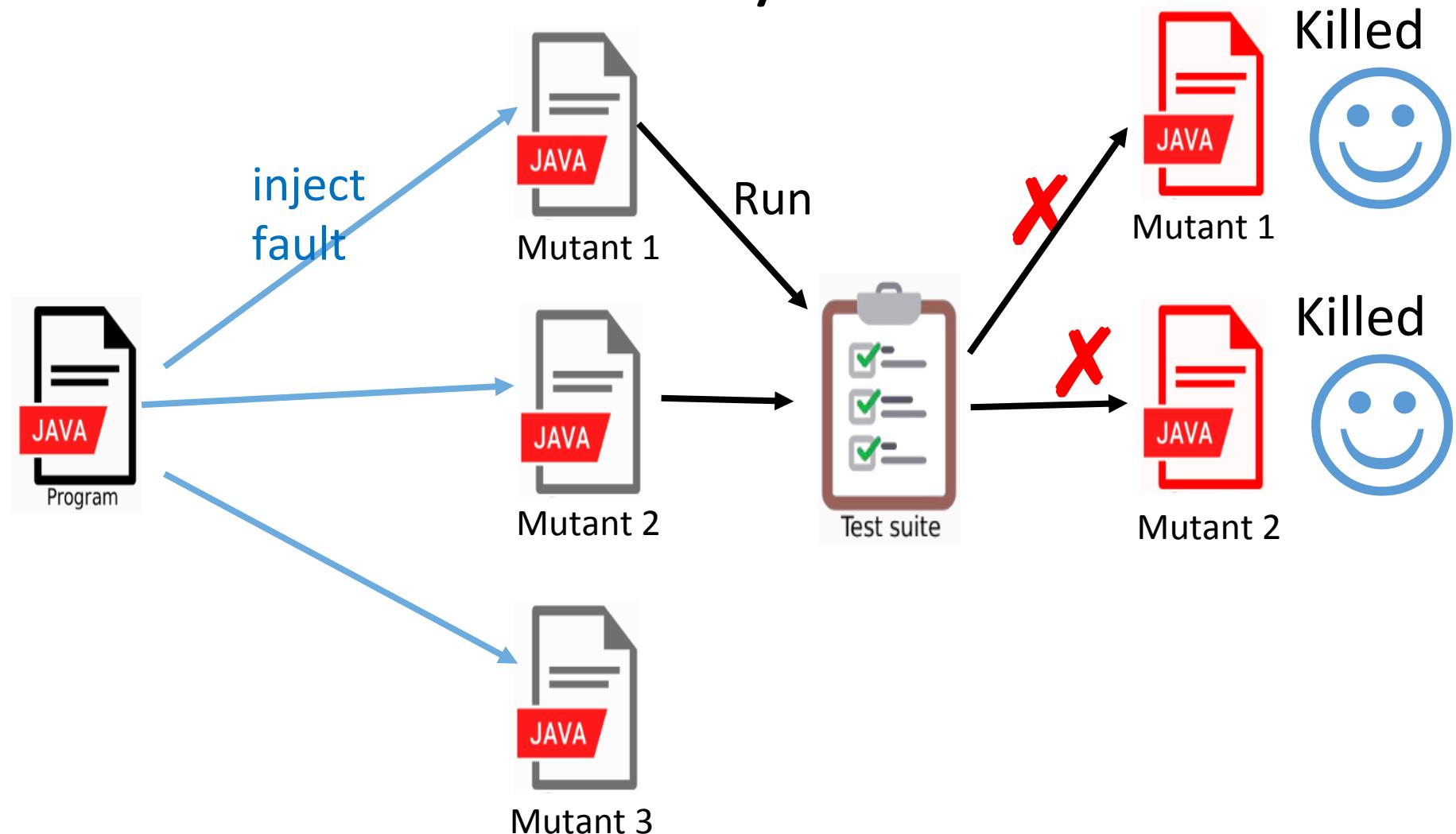
Mutation Analysis



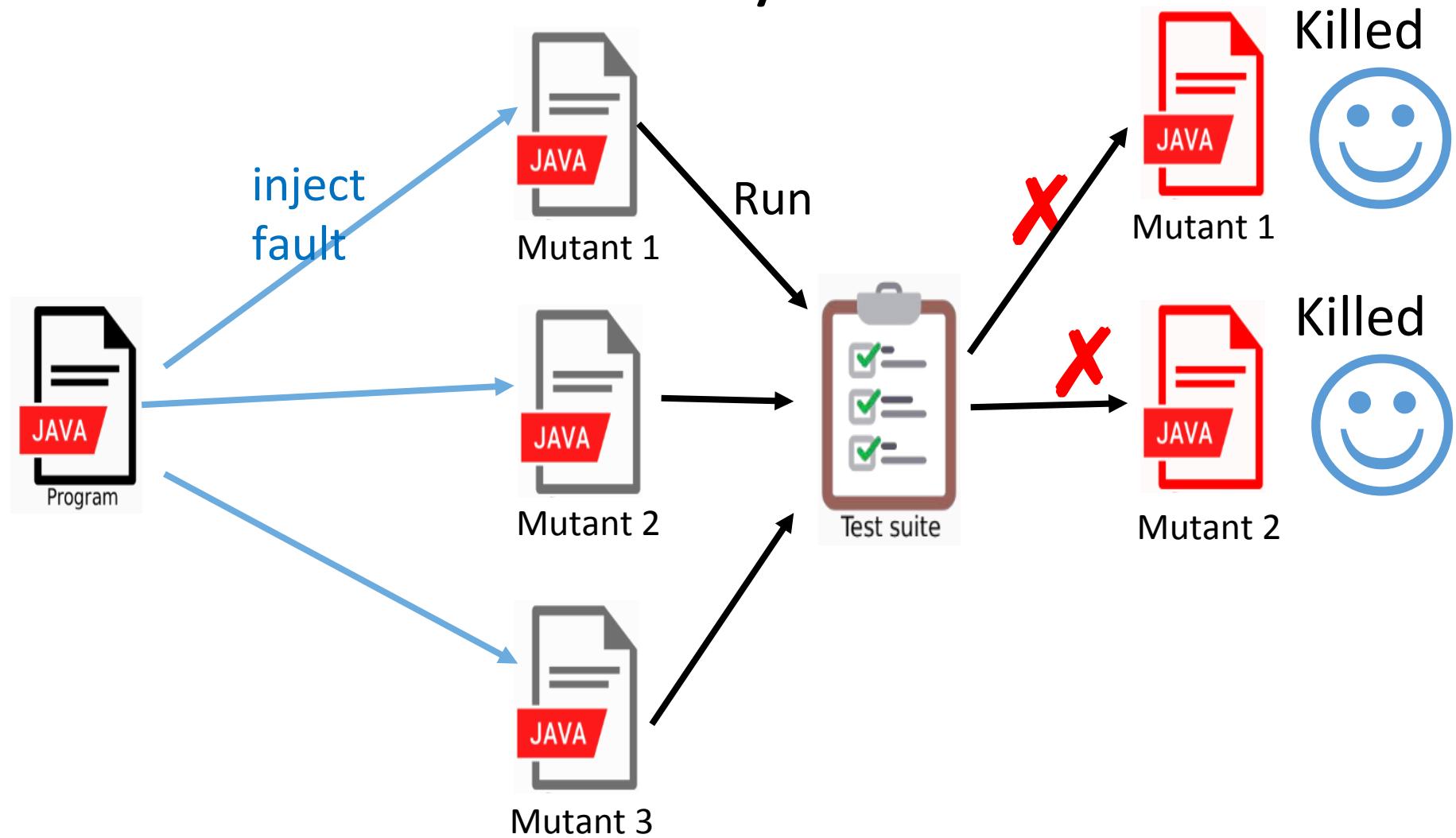
Mutation Analysis



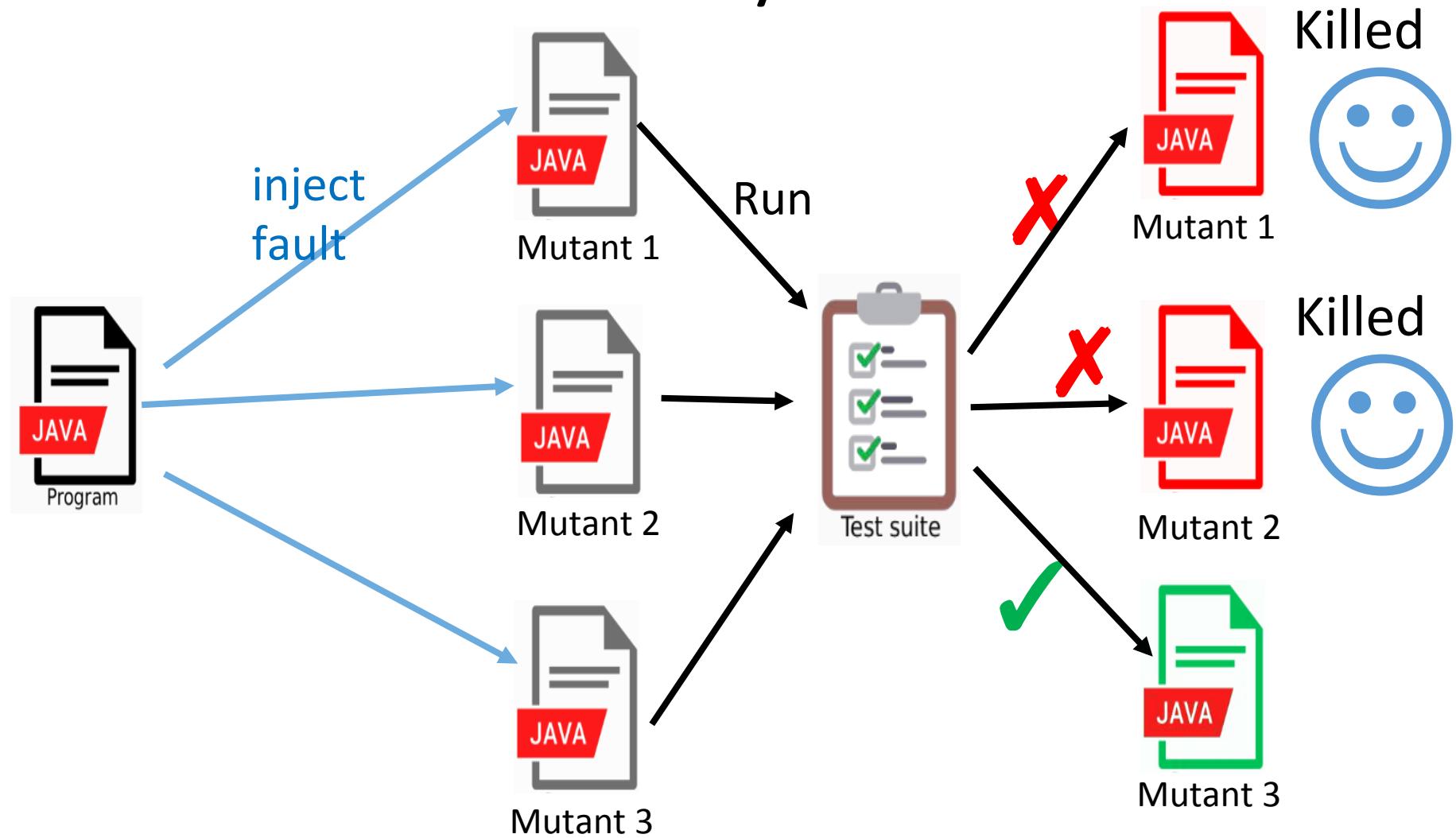
Mutation Analysis



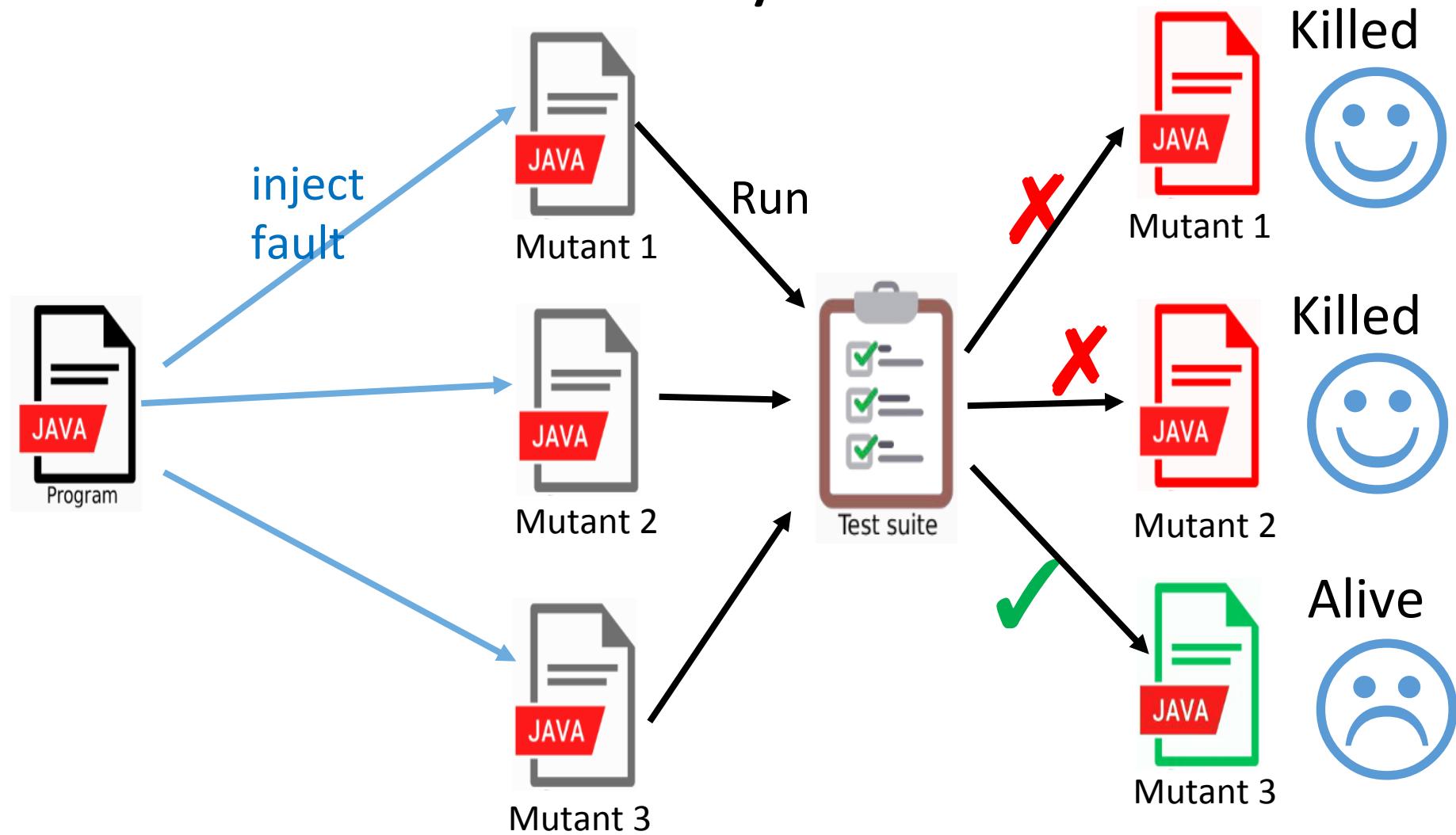
Mutation Analysis



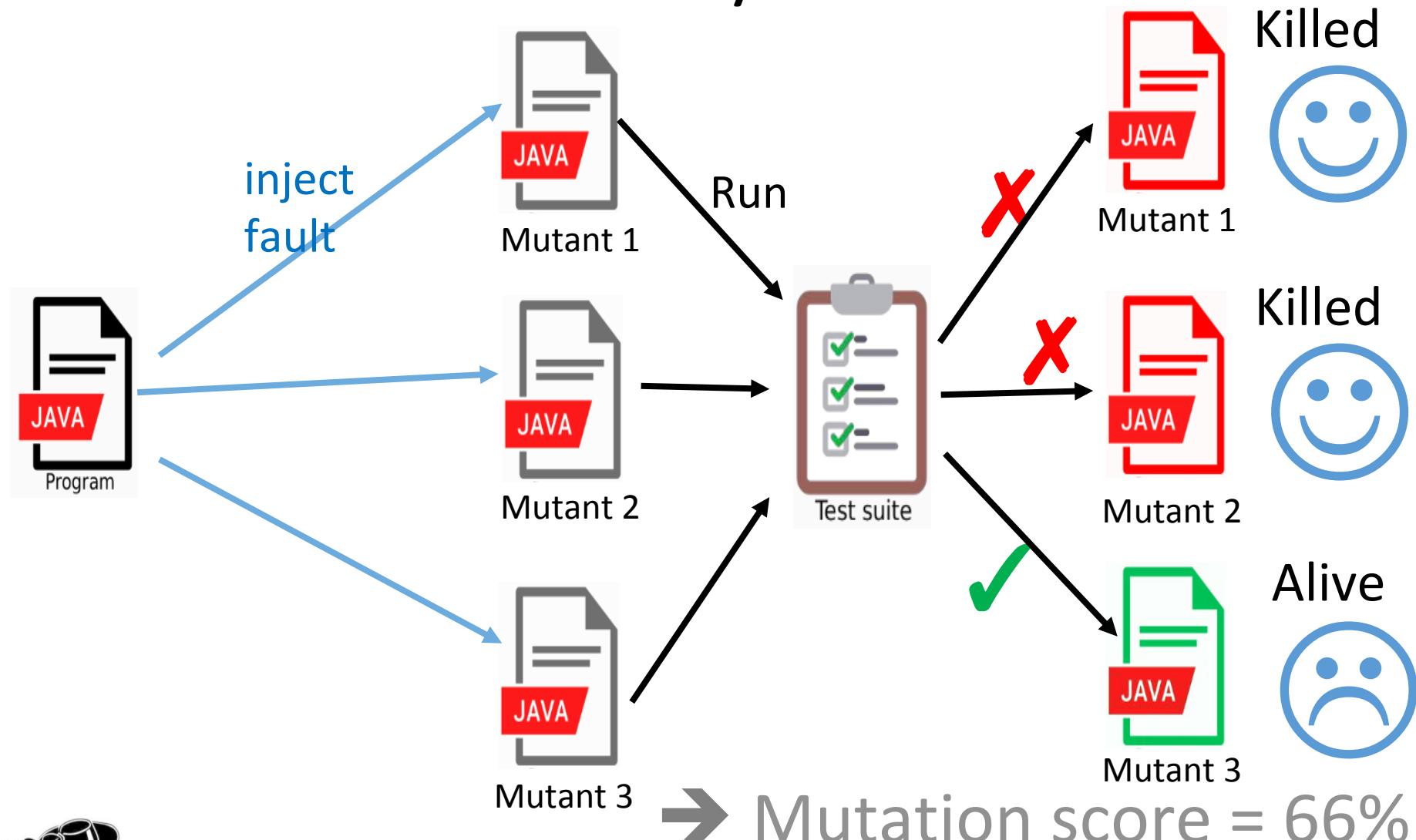
Mutation Analysis



Mutation Analysis



Mutation Analysis



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

@Test

```
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}
```

@Test

```
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```



Example

```
long fact(int n) {  
    if (n != 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```



@Test

```
factorialWith5Test()  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}
```



@Test

```
factorialWith0Test()  
) {  
    assertEquals(1,  
fact(0));  
}
```



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

The diagram illustrates the transformation of the factorial function into a loop invariant form. Blue arrows point from specific code segments to boxes containing simplified expressions. The first arrow points from the condition `n == 0` to a box labeled `n != 0`. The second arrow points from the `return 1;` statement to a box labeled `return 1+1`. The third arrow points from the loop initialization `i = 2` to a box labeled `i < n`. The fourth arrow points from the loop condition `i <= n` to a box labeled `!(i <= n)`. The fifth arrow points from the loop update `i++` to a box labeled `i--`. The sixth arrow points from the assignment `result = result * i;` to a box labeled `result/i`. The seventh arrow points from the final `return result;` statement to a box labeled `result+1`.



Example

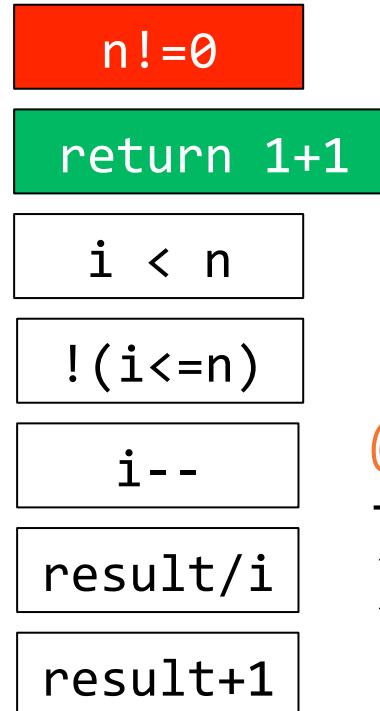
```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}  
  
n!=0  
return 1+1  
i < n  
!(i<=n)  
i--  
result/i  
result+1
```



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```



@Test
factorialWith0Test(
) {
 assertEquals(1,
 fact(0));
}



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}  
@Test  
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```



Example →

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
  
    return result;  
}
```

Mutation

score = 71%

Test suite:

- Weak oracle
- Missing input

@Test

```
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
  
    assertTrue(5 <  
obs);  
}
```

@Test

```
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```



Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
n!=0  
return 1+1  
i < n  
!(i<=n)  
i--  
result/i  
result+1
```

@Test

```
factorialWith5Test()  
{  
    long obs = fact(5);  
    assertTrue(5 < obs);  
}
```

@Test

```
factorialWith0Test() {  
    assertEquals(1,  
    fact(0));  
}
```

@Test

```
factorialWith5Test() {  
    assertEquals(120,  
    fact(5));  
}
```



Mutation Analysis

- Tests are good if they can detect bugs
- Mutation operators
 - Based on common faults
- PIT or PITest
 - Open source, in active development and production ready
 - Integrates with major build systems
 - State of the art mutation testing
 - Extensible via plugins
 - Concurrent execution
 - Test selection



Limitations of mutation testing

- Expensive computation
- Huge number of mutants
- Presence of equivalent mutants

```
int Min (int i, intj){  
    int minval = i;  
    if (j<i) then minval = j;  
    return minval  
}
```

```
int Min (int i, intj){  
    int minval = i;  
    if (j<minval) then minval = j;  
    return minval  
}
```



Test Input Generation

- The case of compilers
- Csmith PLDI'11
- Equivalence modulo inputs PLDI'14

Random Generator: Csmith



C program

gcc -O0

gcc -O2

clang -Os

...

results

vote



majority

minority



Finding and Understanding Bugs in C Compilers

Xuejun Yang Yang Chen Eric Eide John Regehr

University of Utah, School of Computing

{jxyang, chenyang, eeide, regehr }@cs.utah.edu

- *Randomized differential* testing has the advantage that no oracle for test results is needed.
- Idea: if one has multiple, deterministic implementations of the same specification, all implementations must produce the same result from the same valid input
- 300+ bugs found in compilers (eg gcc)

```
1 int foo (void) {  
2     signed char x = 1;  
3     unsigned char y = 255;  
4     return x > y;  
5 }
```

Figure 1. We found a bug in the version of GCC that shipped with Ubuntu Linux 8.04.1 for x86. At all optimization levels it compiles this function to return 1; the correct result is 0. The Ubuntu compiler was heavily patched; the base version of GCC did not have this bug.

http://llvm.org/bugs/show_bug.cgi?id=14972

llvm bug 14972

```
struct tiny { char c; char d; char e; };

void foo(struct tiny x) {
    if (x.c != 1) abort();
    if (x.e != 1) abort();
}

int main() {
    struct tiny s;
    s.c = 1; s.d = 1; s.e = 1;
    foo(s);
    return 0;
}
```

```
$ clang -m32 -O0 test.c ; ./a.out
$ clang -m32 -O1 test.c ; ./a.out
Aborted (core dumped)
```

llvm bug 14972

```
struct tiny { char c; char d; char e; };

void foo(struct tiny x) {
    if (x.c != 1) abort();
    if (x.e != 1) abort();
}

int main() {
    struct tiny s;
    s.c = 1; s.d = 1; s.e = 1;
    foo(s);
    return 0;
}
```

```
$ clang -m32 -O0 test.c ; ./a.out
$ clang -m32 -O1 test.c ; ./a.out
Aborted (core dumped)
```

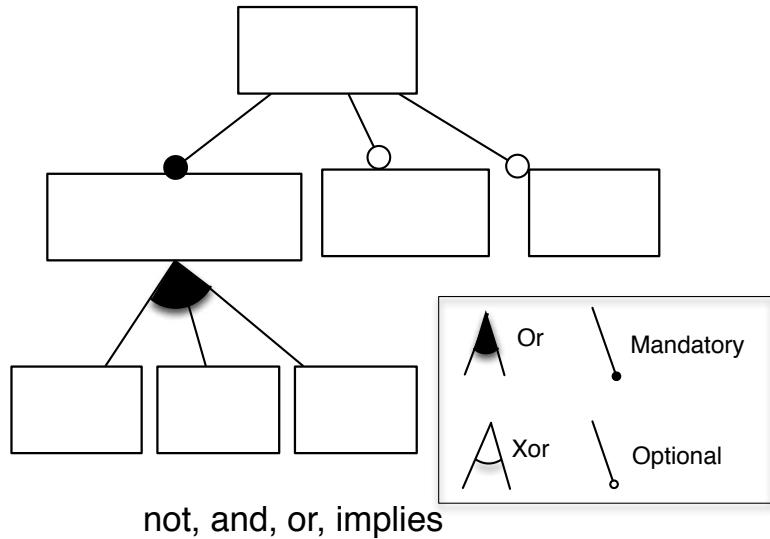
A bug in the LLVM optimizer causes this miscompilation. The developers believe that the Global Value Numbering (GVN) optimization turns the struct initialization into a single 32-bit load. Subsequently, the Scalar Replacement of Aggregates (SROA) optimization decides that the 32-bit load is undefined behavior, as it reads past the end of the struct, and thus does not emit the correct instructions to initialize the struct. The developer who fixed the issue characterized it as

“... very, very concerning when I got to the root cause, and very annoying to fix.”

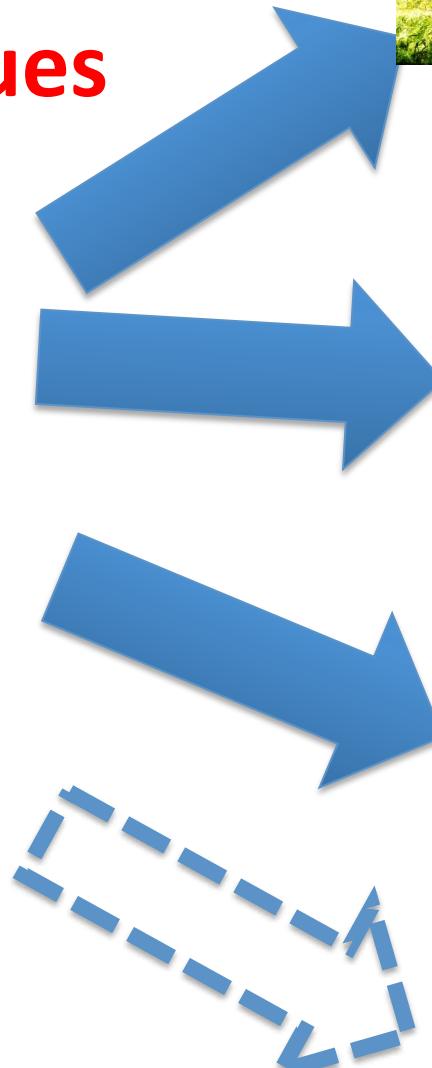
Test Input Generation (2)

- An example for performance-related testing

We synthesize video sequence variants with variability techniques



Variability Models (feature models)



Why?

**Industrial needs:
consumer and provider of
video algorithms have severe**

**difficulties to test their
algorithms on different kinds
of inputs.**



Test algorithms on different kinds of inputs that influence execution time, precision, and/or recall



Algorithm 1

0.63



0.81

Algorithm 2

0.93

Algorithm 3

0.82



0.43

0.92

0.81

0.8



0.39

0.03

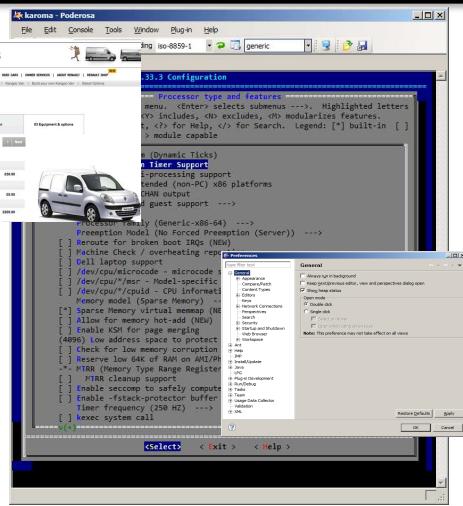
0.01

Why?

Problem: collecting videos is a key economic problem.

Solution: hundreds of video sequences with different characteristics.





Feature Model

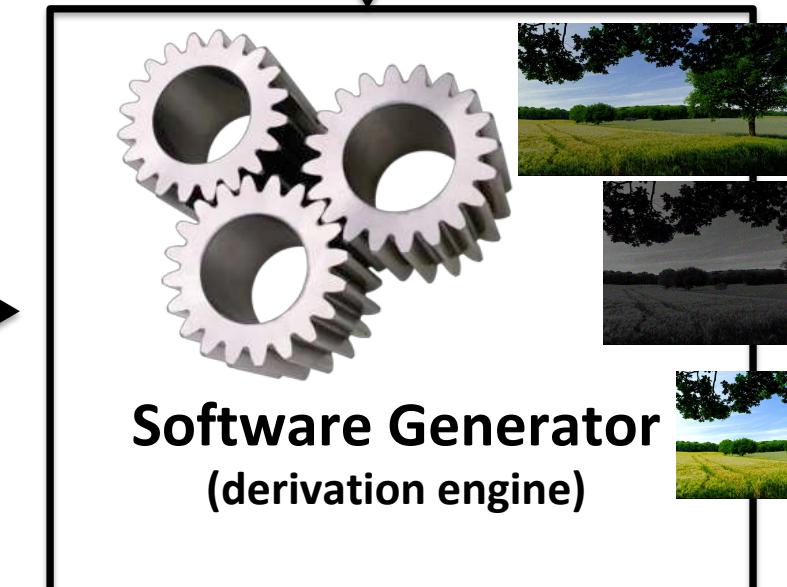
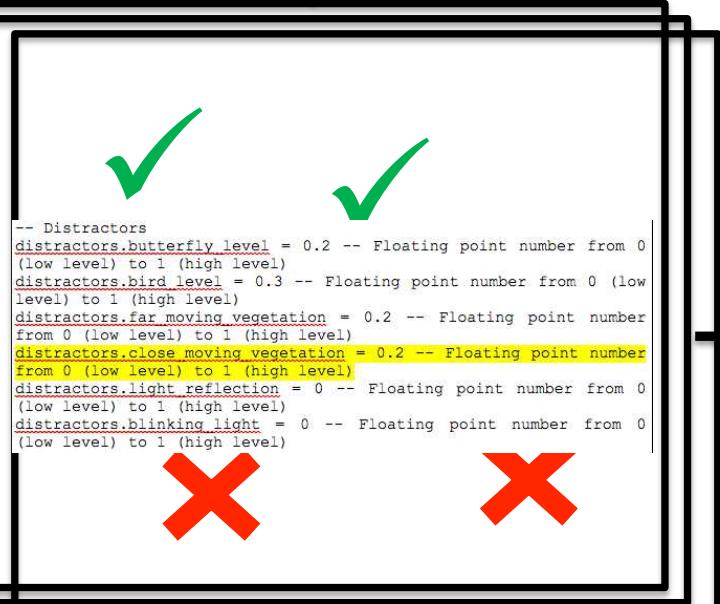
mapping

```

printC"-->Step9")
if (CFG.distractors.close_moving_vegetation~=0) then
    windvect5, precwindvect5, newwindvect5 =
    generate_wind_vector_field2(workwidth, workheight, 256, 1, 1, 35, picnum,
    precwindvect5, newwindvect5)
    windvectmul =
    windvect5:mul(24*CFG.distractors.close_moving_vegetation)
    globalvect = compose_vect(masque_feuilles_sombres, windvectmul, globalvect)
    hfvx, hfvy =
    windvect:mul6*CFG.distractors.close_moving_vegetation):to_matrix()
    hfvx = MATRIX.multerm(hfvx, invdepthmat)
    hfvy = MATRIX.multerm(hfvy, invdepthmat)
    lfvect = windvect2:resize_bilinear(windvect2.Width, windvect2.Height/16)
    lfvector = lfvector:resize_bilinear(windvect2.Width, windvect2.Height)
    lfvx, lfvy = lfvector:mul(
12*CFG.distractors.close_moving_vegetation):to_matrix()
    lfvx = MATRIX.multerm(lfvx, depthmat)
    lfvy = MATRIX.multerm(lfvx, depthmat*0.1)
    windvectcomp = VECT2D.new_from_matrices(MATRIX.addterm(lfvx, hfvx),
    MATRIX.addterm(lfvx, hfvy))
    globalvect = compose_vect(masque_ble, windvectcomp, globalvect)
    globalvect = compose_vect(masque_orge, windvectcomp, globalvect)
    globalvect = compose_vect(masque_ble_fond, windvectcomp, globalvect)
end

printC"-->Step10")

```



Old Approach



Developers

*modify
 N times*

Video Sequences Generator

N Configuration Files



...

generates



N Video Sequences



VM Approach



Developers and
Domain Experts

generates



VM interpreter, and
configuration files
customizer

*model
1 time*

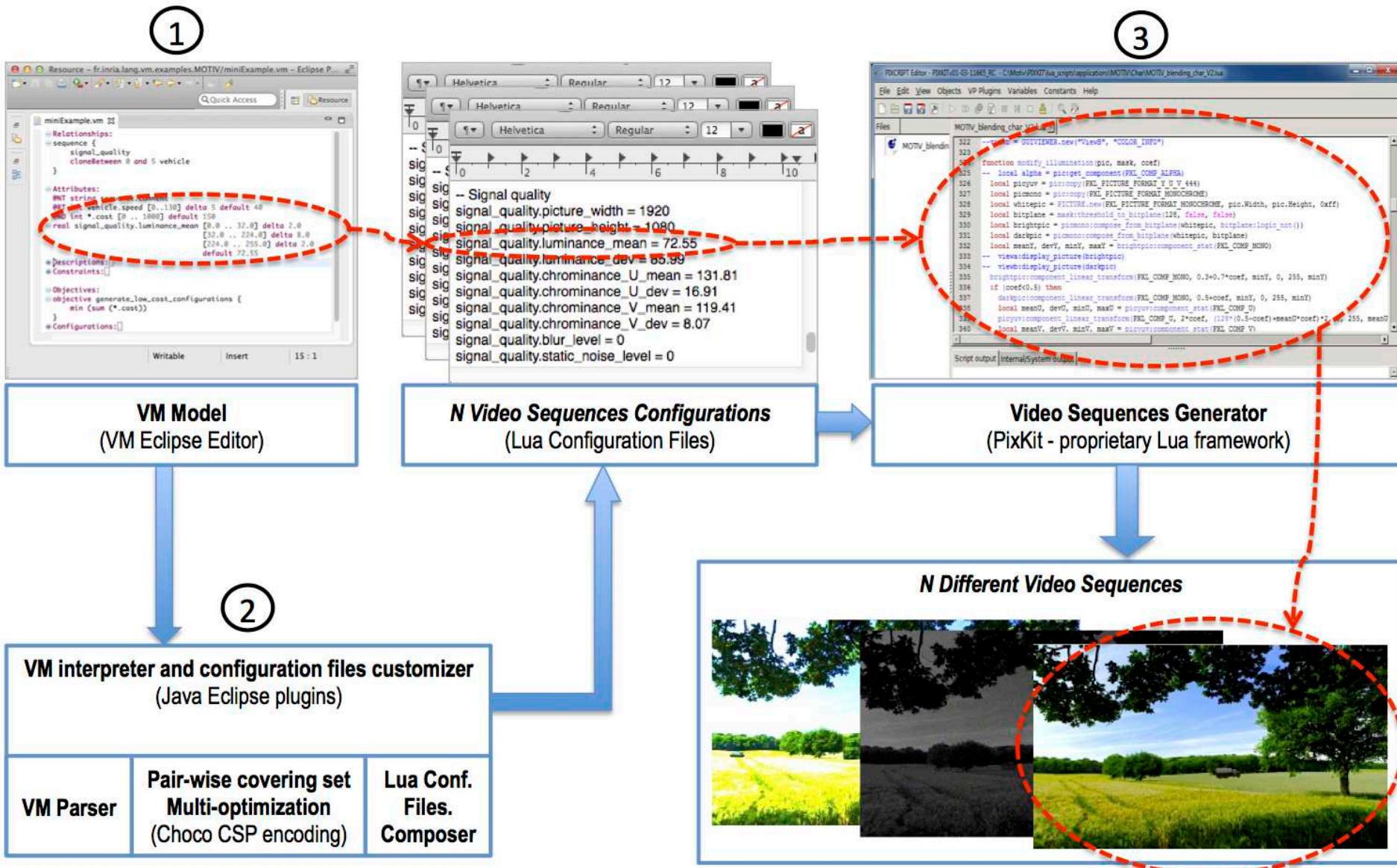


VM model

Artifact(s)



Processing
tool(s)



(configuration file)

```
-- Distractors
distractors.butterfly level = 0.2 -- Floating point number from 0
(low level) to 1 (high level)
distractors.bird level = 0.3 -- Floating point number from 0 (low
level) to 1 (high level)
distractors.far moving vegetation = 0.2 -- Floating point number
from 0 (low level) to 1 (high level)
distractors.close moving vegetation = 0.2 -- Floating point number
from 0 (low level) to 1 (high level)
distractors.light reflection = 0 -- Floating point number from 0
(low level) to 1 (high level)
distractors.blinking light = 0 -- Floating point number from 0
(low level) to 1 (high level)
```

```
print(">Step9")
if (CFG.distractors.close moving vegetation~=0) then
    windvect5, precwindvect5, newwindvect5 =
generate_wind_vector_field2(workwidth, workheight, 256, 1, 1, 35, picnum,
precwindvect5, newwindvect5)
    windvectmul =
windvect5:mul(24*CFG.distractors.close moving vegetation)
    globalvect = compose_vect(masque_feuilles_sombres, windvectmul, globalvect)
    hfvx, hfvy =
windvect0:mul(6*CFG.distractors.close moving vegetation):to_matrix()
    hfvx = MATRIX.multerm(hfvx, invdepthmat)
    hfvy = MATRIX.multerm(hfvy, invdepthmat)
    lfvect = windvect2:resize_bilinear(windvect2.Width, windvect2.Height/16)
    lfvect = lfvect:resize_bilinear(windvect2.Width, windvect2.Height)
    lfvx, lfvy = lfvect:mul(
12*CFG.distractors.close moving vegetation):to_matrix()
    lfvx = MATRIX.multerm(lfvx, depthmat)
    lfvy = MATRIX.multerm(lfyv, depthmat*0.1)
    windvectcomp = VECT2D.new_from_matrices(MATRIX.addterm(lfvx, hfvx),
MATRIX.addterm(lfyv, hfvy))
    globalvect = compose_vect(masque_ble, windvectcomp, globalvect)
    globalvect = compose_vect(masque_orge, windvectcomp, globalvect)
    globalvect = compose_vect(masque_ble_fond, windvectcomp, globalvect)
end
print(">Step10")
```

(Lua code)

Defects detection

Benchmarking

Incremental design

Performance prediction



Algorithm 1

0.63

0.81

0.43

0.39

Algorithm 2

0.93

0.92

0.3

0.03

Algorithm 3

0.82

0.81

0.8

0.01

Metamorphic Testing

- A metamorphic relation is a pair of conditions such that if two inputs fulfill the first, then the result of their evaluations must fulfill the second.
 - Example1 the shortest path between nodes A and B in a graph should have the same length as the shortest path between B and A
 - Example2: the “object of interest” in an image should be the same regardless of the colour palette
- Metamorphic testing is testing software by:
 - generating inputs that fulfill a metamorphic relation
 - confirming that their outputs fulfill that metamorphic relation

Metamorphic testing in real-world

- A compiler output shouldn't change if you inject dead code paths
 - EMI idea can be seen as a “metamorphic” relation
 - Injecting dead code/runtime-constants into shaders made things in pictures disappear or turn to noise.
- “Refining” a search query should yield a subset of its original results
 - In Spotify: two searches for albums with the same query should return the same number of total results regardless of the size of pagination
- Unsupervised clustering (k-means): “do we get the same result if we shuffle the inputs?” and “do additional inputs at cluster boundaries belong to those clusters?”

Example: Testing Computer Vision

- Test Generation Problem (input)
- Oracle Problem (output)

Training
set

Machine
Learning
(classifier)

Accuracy



Metamorphic Testing for CV

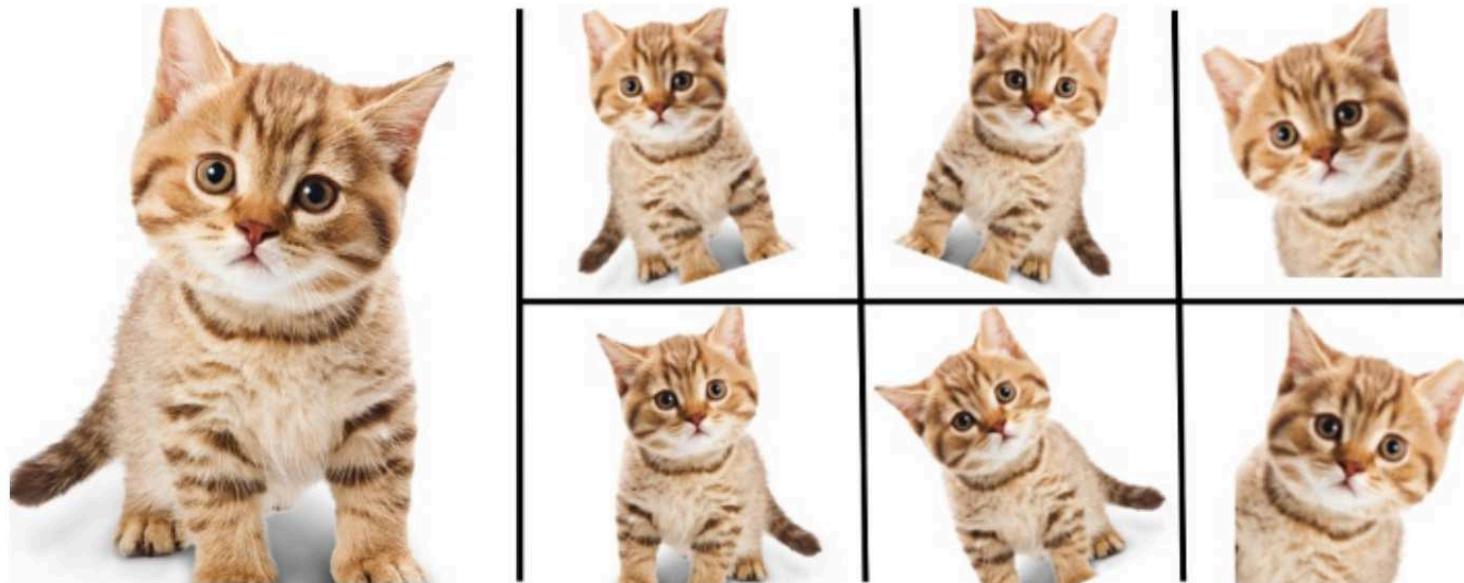
Given an image, you can:

- change its colour palette
- flip it
- rotate it
- zoom...

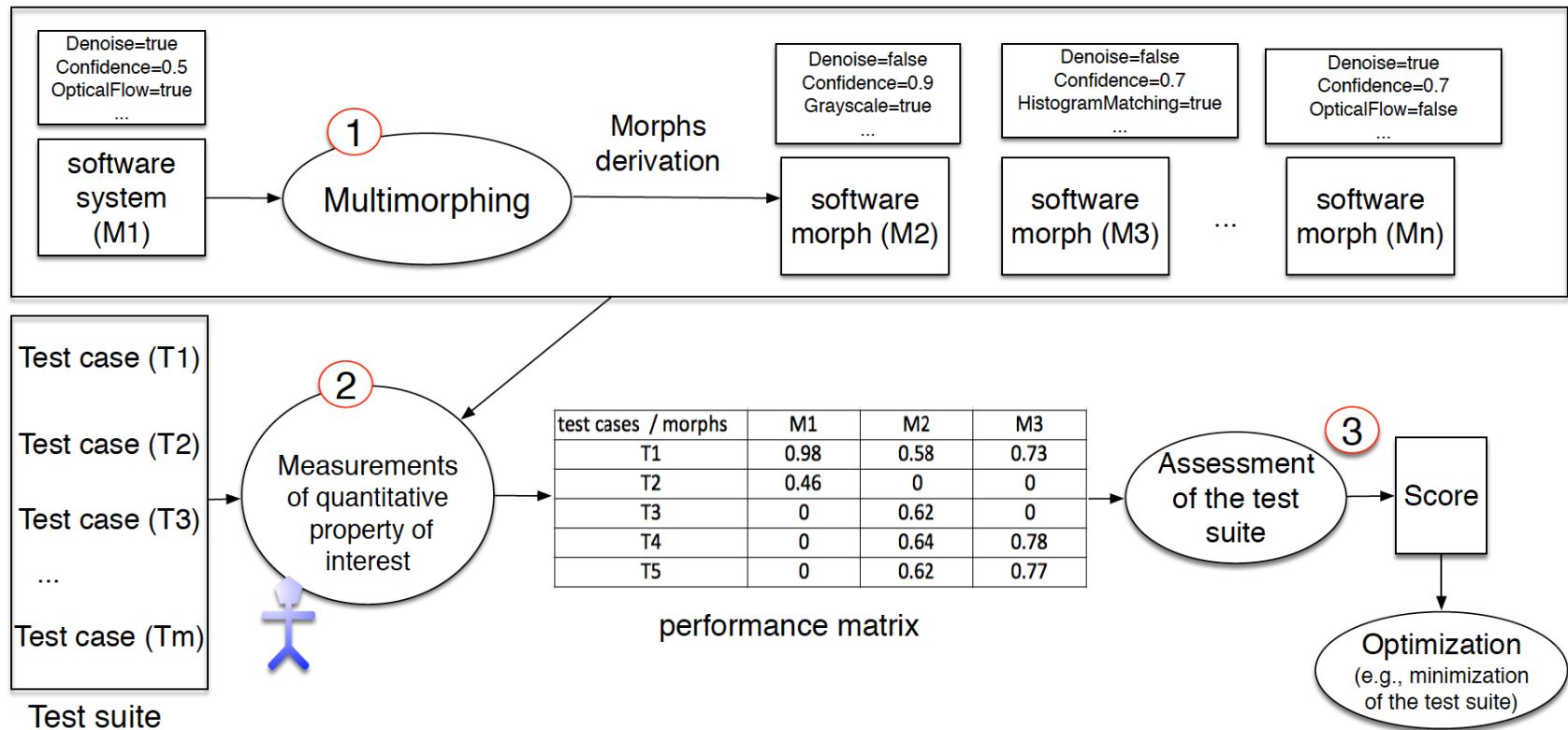
And still know what the output should be!

Free test-cases (input)

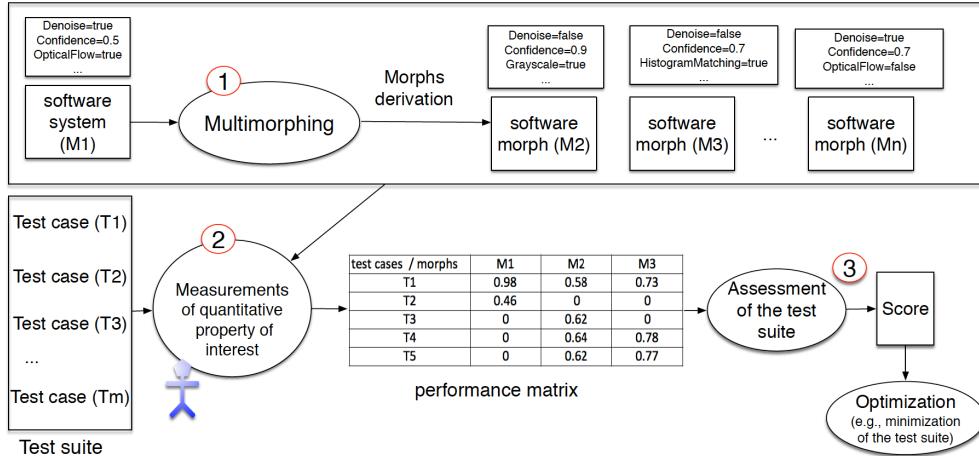
Don't need to specify the oracle (output)



Multimorphic Testing



Multimorphic Testing



Case	App. Domain	# morphs	# test suites
OpenCV	Tracking in videos	252	49
COCO	Obj. rec. in images	52	12
Haxe	Code Generation	21	84

Test suite reduction

Bugs in compiler (target variant)

Dispersion score

Minimization of test suite

Prioritization of test cases

Better understanding of weaknesses



Algorithm 1

0.63

Algorithm 2

0.93

Algorithm 3

0.82

0.81

0.92

0.81

0.43

0.3

0.8

0.39

0.03

0.01

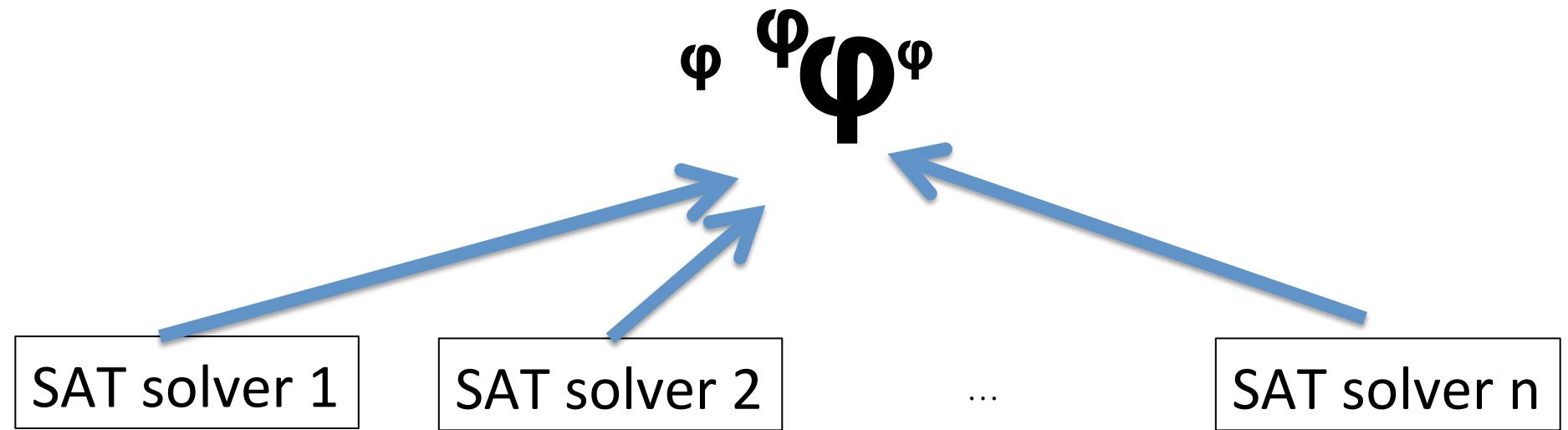
Conclusion

- Testing Problem
 - Test Generation Problem (input)
 - Oracle Problem (output)
- Assertion-based testing
- Mutation Testing
- Test Generation
- Metamorphic Testing
- Multimorphic Testing
- Many testing topics not covered (property-based testing, search-based testing, fuzzing, etc.)
- **Many techniques can be used to test model transformations (eg compilers)**

Back to the project...

- What testing techniques to use?

Comparing solver variants' performance



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