

# Automated Software Testing

Mathieu Acher

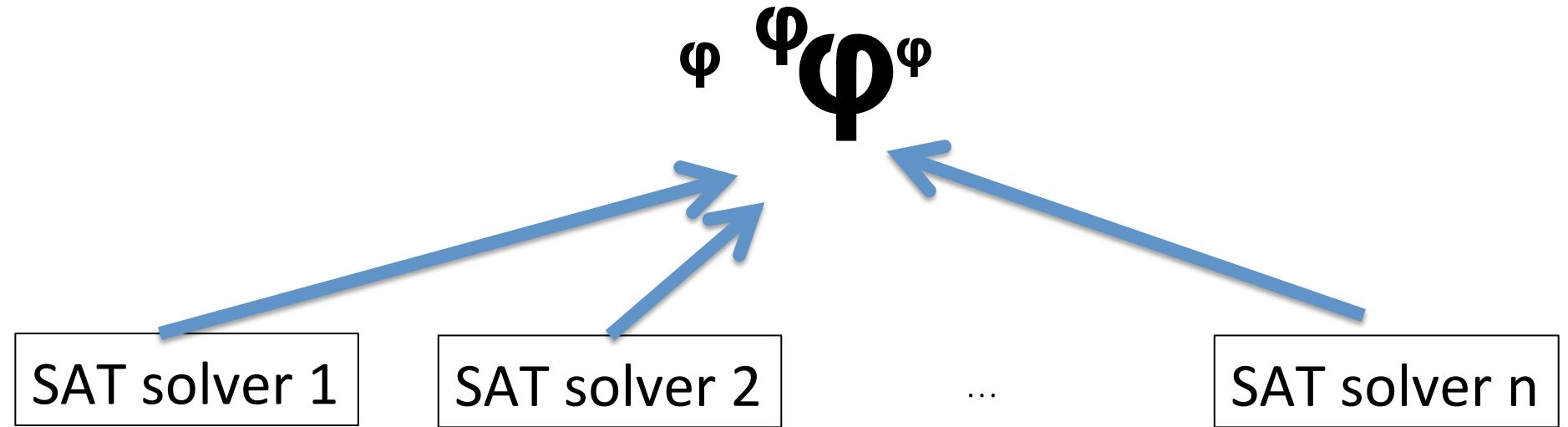
Maître de Conférences

[mathieu.acher@irisa.fr](mailto:mathieu.acher@irisa.fr)

# Material

[https://github.com/FAMILIAR-project/  
HackOurLanguages-SF](https://github.com/FAMILIAR-project/HackOurLanguages-SF)

# Comparing solver variants' performance



You Retweeted



Thomas Thüm

@ThomasThuem

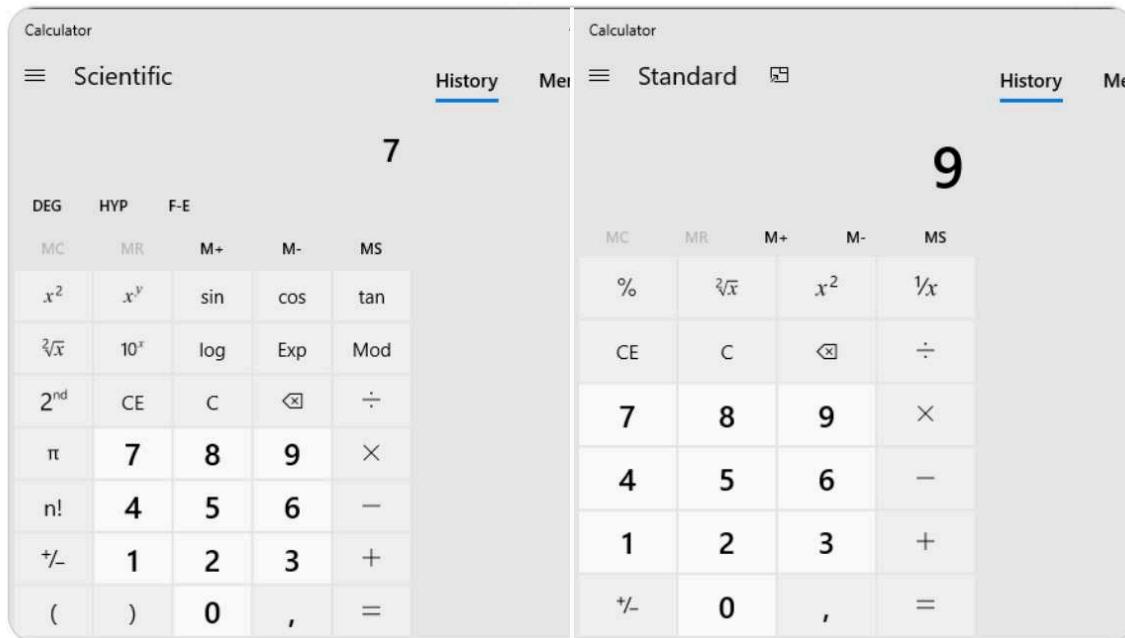
▼

How much is  $1 + 2 * 3$ ?

According to [@Windows 10](#), the result depends on the mode that you have chosen!!!!

The Calculator app gives the correct result in Scientific mode and a wrong result with the default mode called Standard.

I bet this caused thousands of wrong calculations!



# Formal verification or testing?

```
procedure insert2 (integer x, t)
begin B[t] ← B[t] ∨ (2 ↑ (x mod 16));
    size[t] ← size[t] + 1;
    if x < least[t] then least[t] ← x
    else if x > greatest[t] then greatest[t] ← x;
end;
```

The implementation of deletion would be similar. It is safe to use 0 and  $2^{16}-1$  for  $-\infty$  and  $+\infty$ .

Beware of bugs in the above code; I have only proved it correct, not tried it.

THE CORRESPONDENCE BETWEEN DONALD E.  
KNUTH AND PETER VAN EMDE BOAS ON PRIORITY  
DEQUES DURING THE SPRING OF 1977

# Formal verification or testing?

xavierleroy commented on 12 Jul 2018

Contributor + 😊 ...

Fixed in commit [abf674c](#). Thanks @mtrigger for the report and @m-schmidt for the fix.

The test suite for GCC builtins looks very interesting. CompCert's formal verification doesn't cover builtin functions, so we need more testing here.

Support of GCC Builtins

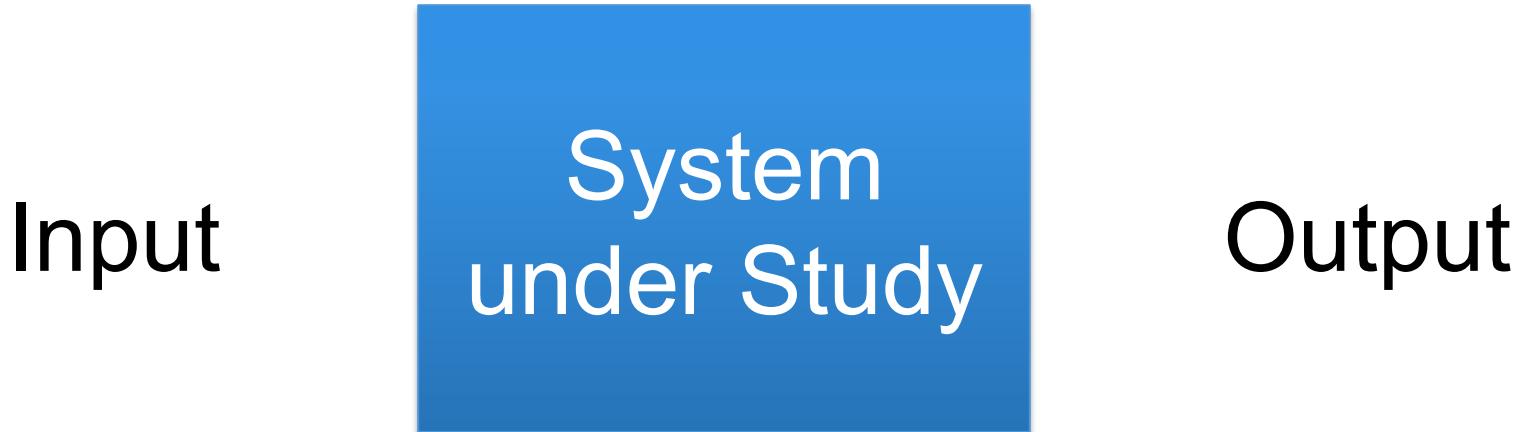
<https://github.com/AbsInt/CompCert/issues/243>

# Plan

- Testing Problem
  - Test Generation Problem (input)
  - Oracle Problem (output)
- Assertion-based testing
- Mutation Testing
- Test Generation
- Metamorphic Testing
- Multimorphic Testing

# Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)



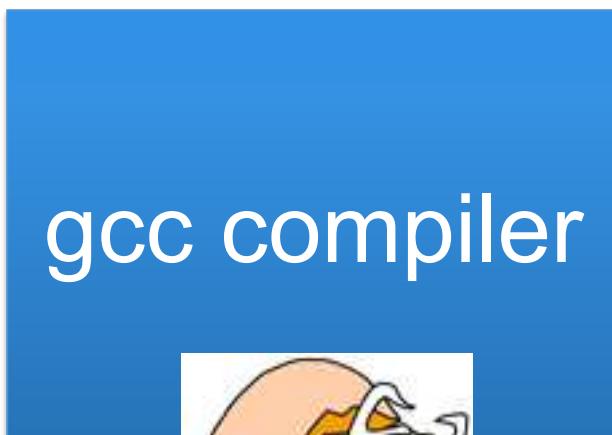
# Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

C programs

gcc compiler

Assembly  
codes



# Configuration is an additional part of the (test) input!



See [Options that Control Optimization](#).

```
-faggressive-loop-optimizations
-falign-functions=[n[:m:[n2[:m2]]]]
-falign-jumps=[n[:m:[n2[:m2]]]]
-falign-labels=[n[:m:[n2[:m2]]]]
-falign-loops=[n[:m:[n2[:m2]]]]
-fasynchronous-thread-profile-future-profile=at
-automatic-vectorizer-abilities
-fbranch-target-load-optimize=fbranch-target-load-optimize2
-fbranch-bb-exclusive -fcaller-saves
-fcombine-stack-adjustments -fconserve-stack
-fcompare-elim -fcprop-registers -fcrossjumping
-fcse-follow-jumps -fcse-skip-blocks -fcx-fortran-rules
-fcx-limited-range
-fdata-sections -fdce -fdelayed-branch
-fdelete-null-pointer-checks -fdevirtualize -fdevirtualize-speculatively
-fdevirtualize-at-ltrans -fdse
-fearly-inlining -fipa-sra -fexpensive-optimizations -ffat-lto-objects
-ffast-math -ffinite-math-only -ffloat-store -fexcess-precision=style
-ffoward-propagate -ffp-contract=style -ffunction-sections
-fgcse -fgcse-after-reload -fgcse-las -fgcse-lm -fgraphite-identity
-fgcse-sm -fhoist-adjacent-loads -fif-conversion
-fif-conversion2 -findirect-inlining
-finline-functions -finline-functions-called-once -finline-limit=n
-finline-small-functions -fipa-cp -fipa-cp-clone
-fipa-bit-cp -fipa-vrp -fipa-pta -fipa-profile -fipa-pure-const
-fipa-reference -fipa-reference-addressable
-fipa-stack-alignment -fipa-ifc -fira-algorithm=algorithm
-fira-region=region -fira-hoist-pressure
-fira-loop-pressure -fno-ira-share-save-slots
-fno-ira-share-spill-slots
-fisolate-erroneous-paths-dereference -fisolate-erroneous-paths-attribute
-fivopts -fkeep-inline-functions -fkeep-static-functions
-fkeep-static-consts -flimit-function-alignment -flive-range-shrinkage
-floop-block -floop-interchange -floop-strip-mine
-floop-unroll-and-jam -floop-nest-optimize
-floop-parallelize-all -fira-remat -flto -flto-compression-level
-flto-partition=alg -fmerge-all-constants
-fmerge-constants -fmodulo-sched -fmodulo-sched-allow-regmoves
-fmove-loop-invariants -fno-branch-count-reg
-fno-defer-pop -fno-fp-int-built-in-exact -fno-function-cse
-fno-guess-branch-probability -fno-inline -fno-math-errno -fno-peephole
-fno-peephole2 -fno-printf-return-value -fno-sched-interblock
-fno-sched-spec -fno-signed-zeros
-fno-toplevel-reorder -fno-trapping-math -fno-zero-initialized-in-bss
-fomit-frame-pointer -foptimize-sibling-calls
-fpartial-inlining -fpeel-loops -fpredictive-commoning
-fprefetch-loop-arrays
-fprofile-correction
```

gcc (compiler): 200+ options  
Boolean options

# Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

Training  
set

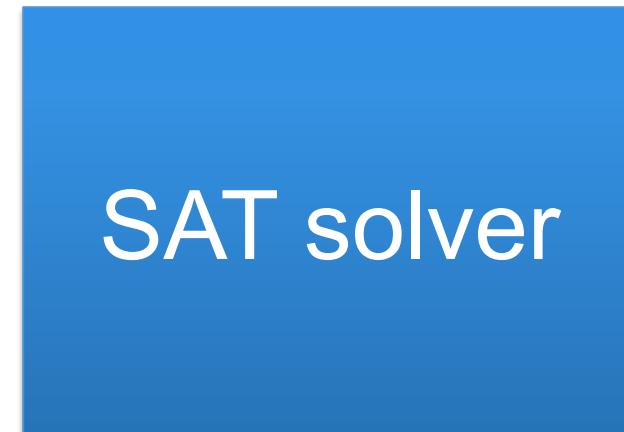
Machine  
Learning  
(classifier)

Accuracy

# Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

SAT  
formulae



SAT/UNSAT

# Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)

Wikipedia  
pages  
(HTML or Wikitext format)



CSV files

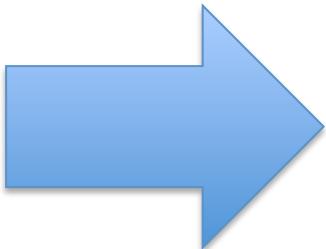


<http://blog.mathieuacher.com/WikipediaMatrixChallenge/>

# How to automatically extract tabular data out of Wikipedia pages?



**WIKIPEDIA**  
*The Free Encyclopedia*



CSV  
(Comma Separated Values)

Product	Image process...	Sensor format	Sensor type	Sensor manufac...	Megapixels	Focus points	Metering pixels	Viewfinder cov...
D3X	EXPPEED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D1X	-	APS-C	CCD	Sony	5.3	5	1005	96%
D1	-	APS-C	CCD	Sony	2.66	5	1005	96%
D4S	EXPPEED 4	Full-frame	CMOS	Nikon	16.2	51	91000	100%
D4	EXPPEED 3	Full-frame	CMOS	Nikon	16.2	51	91000	100%
D5S	EXPPEED	Full-frame	CMOS	Nikon	12.1	51	1005	100%
D3	EXPPEED	Full-frame	CMOS	Nikon	12.1	51	1005	100%
D2Hs	-	APS-C	JETTL-BCAST	Nikon	4.1	11	1005	100%
D2H	-	APS-C	JETTL-BCAST	Nikon	4.1	11	1005	100%
D1H	-	APS-C	CCD	Sony	2.7	5	1005	96%
D810	EXPPEED 4	Full-frame	CMOS	Sony	36.5	51	91000	100%
D600	EXPPEED 3	Full-frame	CMOS	Sony	36.3	51	91000	100%
D700	EXPPEED	Full-frame	CMOS	Nikon	12.1	51	1005	96%
D700	EXPPEED 4	Full-frame	CMOS	Nikon	24.8	51	91000	100%
D1	EXPPEED 3	Full-frame	CMOS	Nikon	16.2	39	2016	100%

diversity of Wikipedia pages (input)  
difficulty of assessing an extractor (output)

# WikipediaMatrix

[https://en.wikipedia.org/wiki/Comparison\\_of\\_Canon\\_EOS\\_digital\\_cameras](https://en.wikipedia.org/wiki/Comparison_of_Canon_EOS_digital_cameras)

Article

Talk

Read

Edit

View history

Search Wikipedia



Wiki Loves Monuments: Photograph a monument, help Wikipedia and win!



## Comparison of Canon EOS digital cameras

From Wikipedia, the free encyclopedia

The following tables provide general information as well as a comparison of technical specifications for a number of Canon EOS digital cameras.

### General information [edit]

Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Viewfinder magnification, coverage	Display size, dots (ratio)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions, WxHxD (mm)	Video	Main Battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 × 158 × 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 × 158 × 80	-	NP-E3
1Ds Mk III	Dual DIGIC III	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 × 160 × 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 × 158 × 80	-	NP-E3
1D Mk II	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 × 158 × 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 × 158 × 80	-	NP-E3
1D Mk III	Dual DIGIC III	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 × 157 × 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	APS-H CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 920k	No	Yes	10	CF, SD	2009Q4	1.180	156 × 157 × 80	1080p30	LP-E4

# WikipediaMatrix

[https://en.wikipedia.org/wiki/Comparison\\_of\\_Canon\\_EOS\\_digital\\_cameras](https://en.wikipedia.org/wiki/Comparison_of_Canon_EOS_digital_cameras)

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1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E3
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
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1D Mk II	DIGIC I	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk III	Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	APS-H CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 920k	No	Yes	10	CF, SD	2009Q4	1.180	156 x 157 x 80	1080p30	LP-E4

```
==General information==
{| class="wikitable sortable" style="text-align: center; font-size: 85%; width: auto;" |
! Model
! Image processor
! Sensor format
! Megapixels
! Min ISO
! Max ISO
! Autofocus points
! Viewfinder
magnification,
coverage
! Display
size, dots

(ratio)
! Touch
screen
! Live view
! Max FPS
! Storage
```

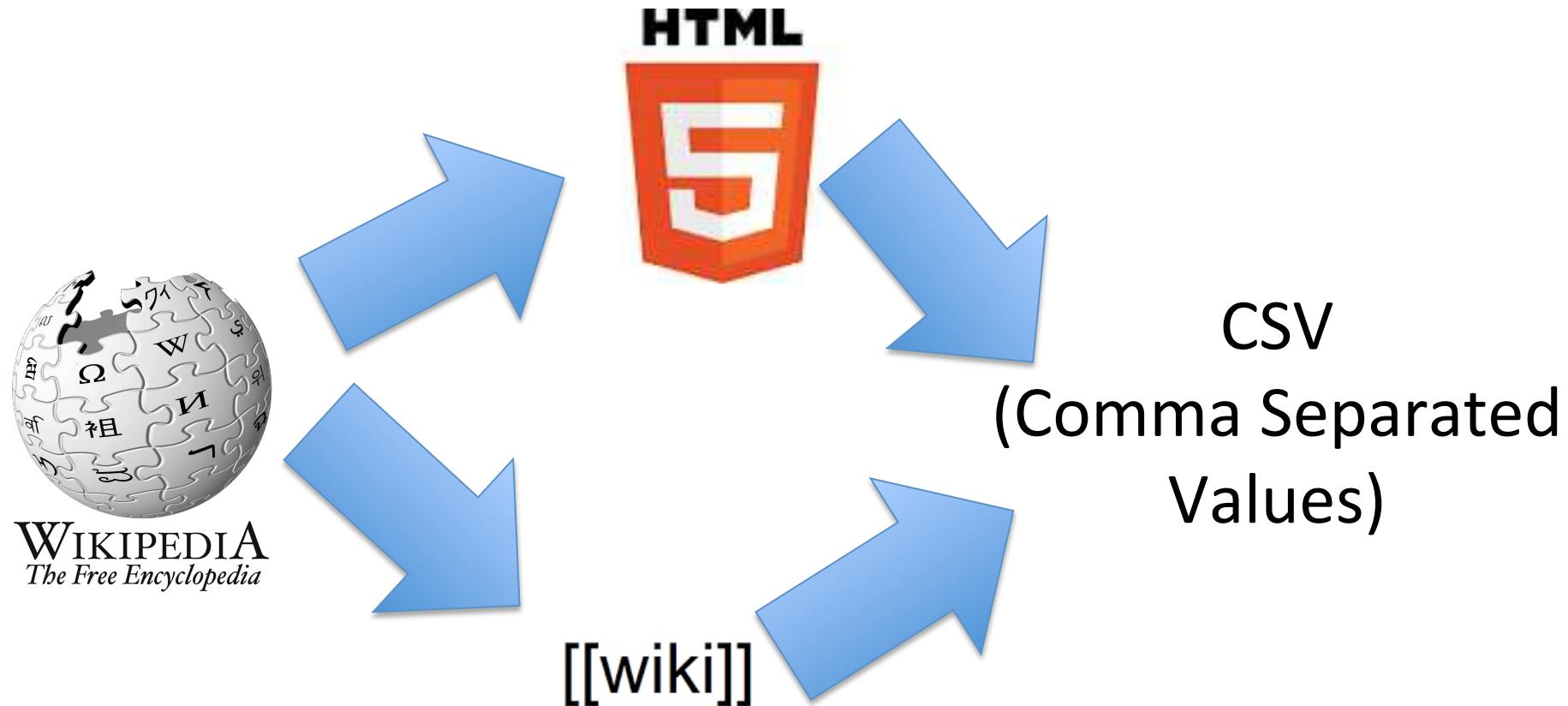
**Wikitext**

**[[wiki]]**

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</th>
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<th>Sensor format
</th>
<th>Megapixels
</th>
<th>Min ISO
</th>
<th>Max ISO
</th>
<th>Autofocus points
</th>
<th>Viewfinder
<p>magnification,
</p><p>coverage
</p>
</th>
<th>Display
<p>size, dots
</p><p>(ratio)
</p>
</th>
<th>Touch
<p>screen
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</th>
<th>Live view
</th>
<th>Max FPS
</th>
<th>Storage
</th>
```



# WikipediaMatrix



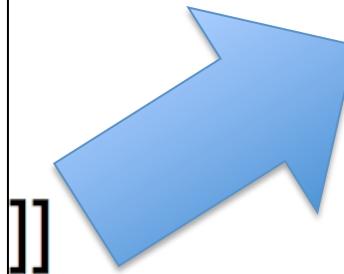
# WikipediaMatrix

HTML

Comparison\_between\_Esperanto\_and\_Ido  
Comparison\_between\_Esperanto\_and\_Interlingua  
Comparison\_between\_Esperanto\_and\_Novial  
Comparison\_between\_Ido\_and\_Interlingua  
Comparison\_between\_Ido\_and\_Novial  
Comparison\_between\_U.S.\_states\_and\_countries\_by\_GDP\_(PPP)  
Comparison\_of\_ALGOL\_68\_and\_C++  
Comparison\_of\_Afrikaans\_and\_Dutch  
Comparison\_of\_Android\_e-book\_reader\_software  
Comparison\_of\_Asian\_national\_space\_programs  
Comparison\_of\_Axis\_&\_Allies\_games  
Comparison\_of\_C\_Sharp\_and\_Visual\_Basic\_.NET  
Comparison\_of\_Chernobyl\_and\_other\_radioactivity\_releases  
Comparison\_of\_Exchange\_ActiveSync\_clients  
Comparison\_of\_Hokkien\_writing\_systems  
Comparison\_of\_Home\_Owners'\_and\_Civic\_Associations  
Comparison\_of\_IOC,\_FIFA,\_and\_ISO\_3166\_country\_codes  
Comparison\_of\_Java\_and\_C++  
Comparison\_of\_Linux\_distributions  
Comparison\_of\_MD\_and\_DO\_in\_the\_United\_States  
Comparison\_of\_Norwegian\_Bokmål\_and\_Standard\_Danish  
Comparison\_of\_Portuguese\_and\_Spanish  
Comparison\_of\_Symbian\_devices  
Comparison\_of\_United\_States\_presidential\_candidates,\_2008  
Comparison\_of\_World\_War\_I\_tanks  
Comparison\_of\_browser\_synchronizers  
Comparison\_of\_business\_integration\_software  
Comparison\_of\_consumer\_brain-computer\_interfaces  
Comparison\_of\_domestic\_robots  
Comparison\_of\_e-book\_formats  
Comparison\_of\_e-book\_readers  
Comparison\_of\_file\_hosting\_services  
Comparison\_of\_layout\_engines\_(Cascading\_Style\_Sheets)  
Comparison\_of\_layout\_engines\_(MathML)

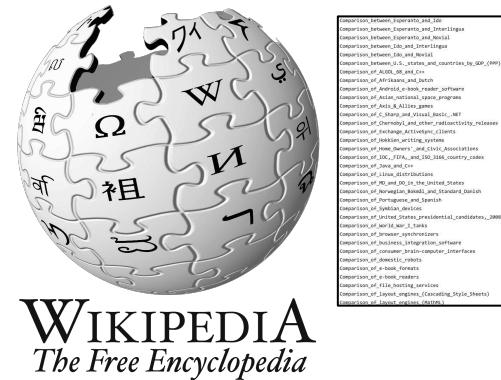


CSV  
(Comma Separated  
Values)

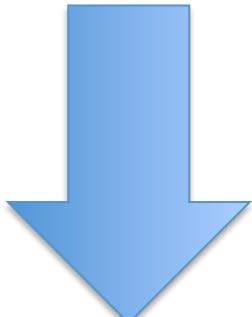


Thousands of Wikipedia pages!

# WikipediaMatrix: The Truth



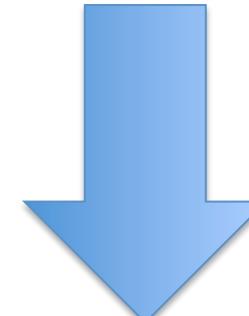
# Extractor1



# CSV1



## Extractor2



# CSV2

# Who's right?

# Tests

(input)

Product	Image processor	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
Find								
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs								
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D1X	-	APS-C	CMOS	Sony	5.3	11	1005	100%
D3X	-	CCD	Sony	-	5	1005	-	98%

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Comparison of Canon EOS digital cameras

From Wikipedia, the free encyclopedia

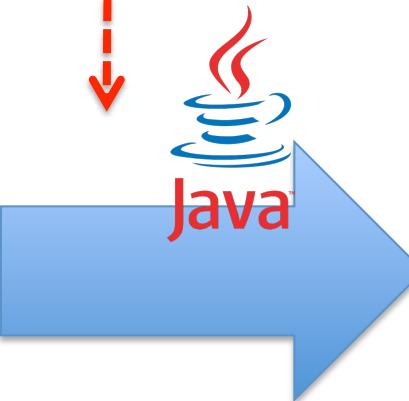
The following tables provide general information as well as a comparison of technical specifications for a number of Canon EOS digital cameras.

General information [edit]

Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Display magnification, coverage	Display size, dots (pixel)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main Battery
1Ds	DIGIC	Full-frame	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame	16.7	50	3200	45	0.70x, 100%	2.0", 120k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E3
1Ds Mk III	Dual DIGIC II	Full-frame	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.215	156 x 158 x 80	-	LP-E4
1D	DIGIC	APS-H	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II Dual DIGIC II	DIGIC II	CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

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(transformation)

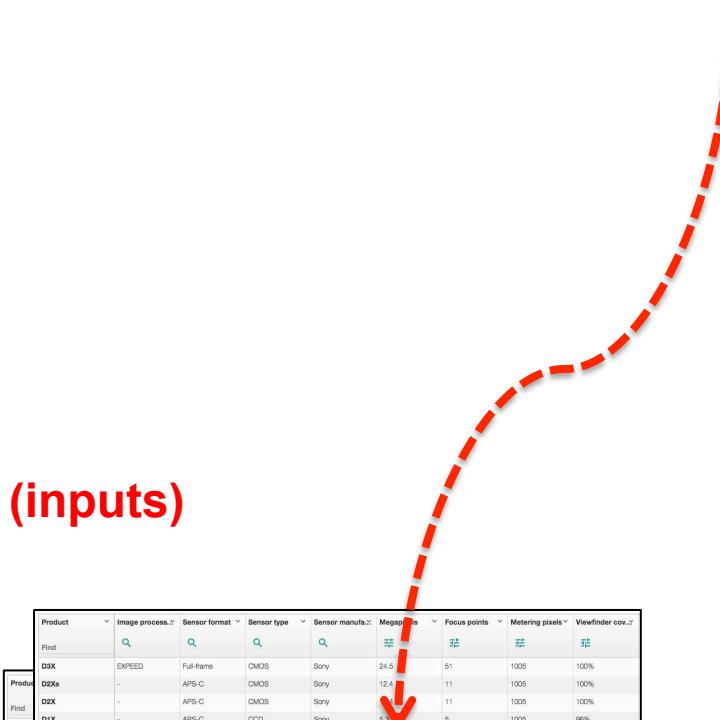


(output)

example  
CSV

# Tests

(inputs)



Product	Image process.	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D2X	-	APS-C	CMOS	Sony	-	11	1005	100%
D3X	-	APS-C	CCD	Sony	5.3	5	1005	98%

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Comparison of Canon EOS digital cameras

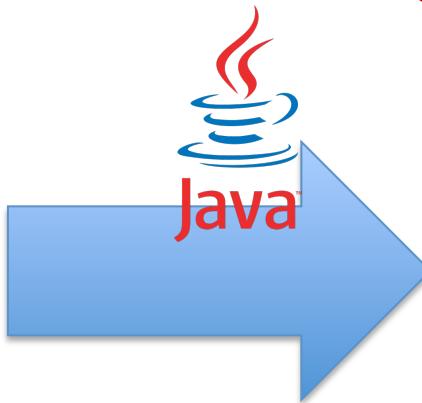
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1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II Dual DIGIC II	Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

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example

CSV

# Tests

(inputs)

Product	Image process.	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
Find								
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs								
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D1X								
D3X	-	APS-C	CCD	Sony	5.3	5	1005	98%

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The following tables provide general information as well as a comparison of technical specifications for a number of Canon EOS digital cameras.

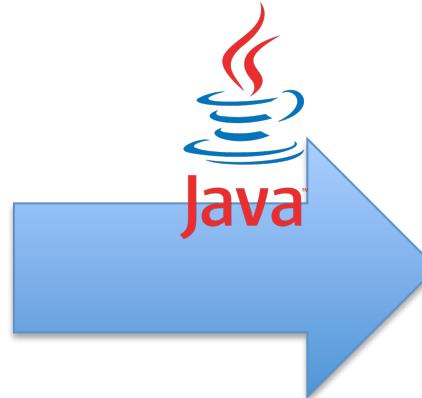
General information [edit]

Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Display magnification, coverage	Display size, dots (x,y)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E3
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.215	156 x 158 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk II N	DIGIC II	APS-H	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II Dual DIGIC II	Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

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RuntimeException....



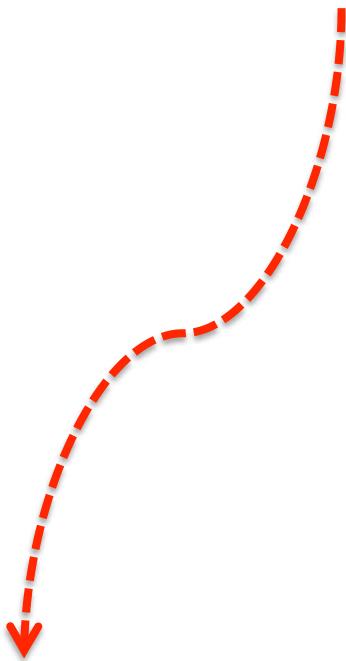
example

CSV



# Tests

(input)



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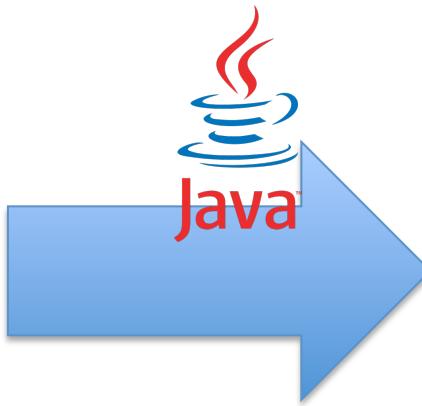
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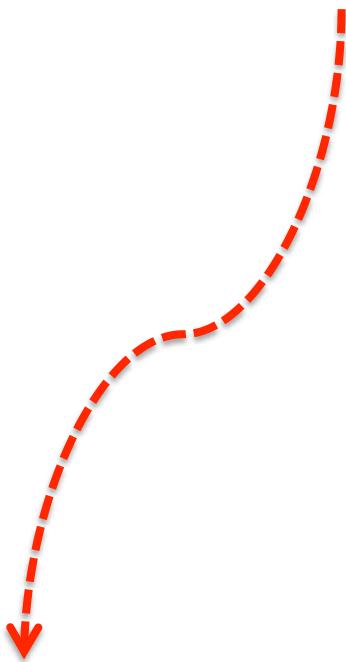
Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Viewfinder magnification, coverage	Display size, dots (pixels)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.215	156 x 158 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10 Mx II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10 Mx II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.220	156 x 158 x 80	-	NP-E3
1D Mk II	Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10 Mx IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 300k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



F1;f2; , ;  
“” . ” .  
‘’ , ,

# Tests

(input)



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Comparison of Canon EOS digital cameras

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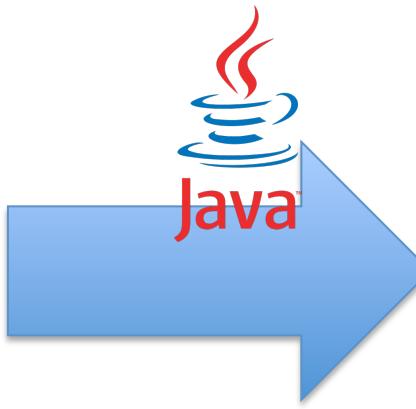
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1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
10D Mk II Dual DIGIC II	DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



f1,f2,f3  
v11,v12,v13  
v21,v22,v23



example

CSV

# Manual testing is a terrible idea

non reproducible; error-prone; time-consuming



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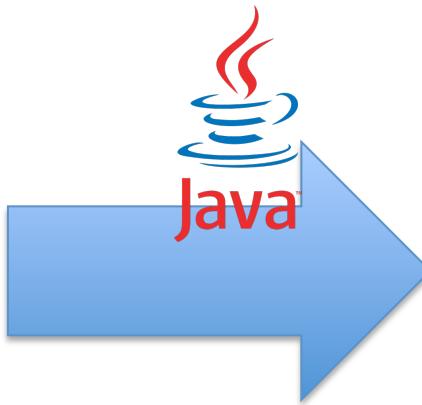
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1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	6.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
10D Mk II Dual DIGIC II	DIGIC II	CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



f1,f2,f3  
v11,v12,v13  
v21,v22,v23

example

CSV

# You can start with some values/inputs and then (manually) observe



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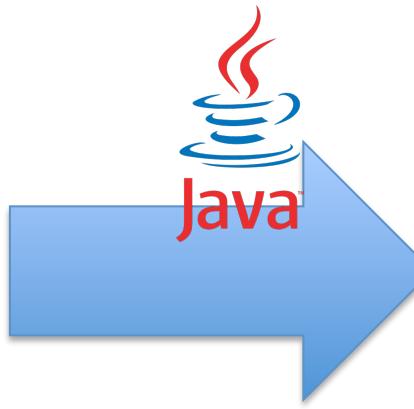
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1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	6.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
10D Mk II Dual DIGIC II	DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



f1,f2,f3  
v11,v12,v13  
v21,v22,v23

example

CSV



# But manual testing is a terrible idea

## non reproducible; error-prone; time-consuming



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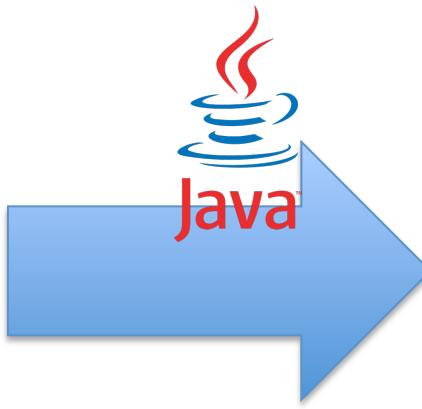
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1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.70x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 158 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	6.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II Dual DIGIC II	DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV Dual DIGIC 4	DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4



f1,f2,f3  
v11,v12,v13  
v21,v22,v23

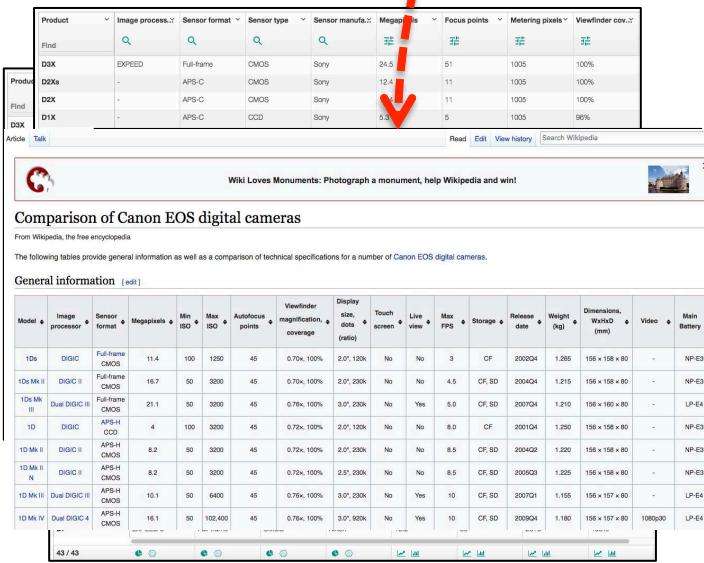
example

CSV



# Tests

(input)



Comparison of Canon EOS digital cameras

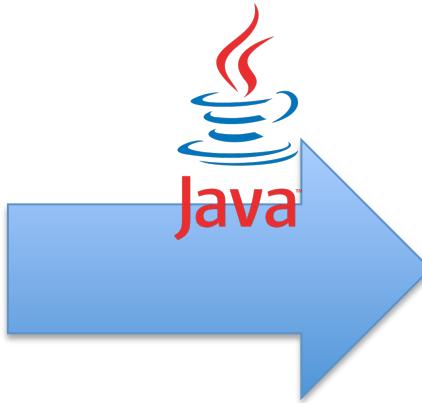
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Model	Image processor	Sensor format	Megapixels	Min ISO	Max ISO	Autofocus points	Display magnification, coverage	Display size, dots (pixels)	Touch screen	Live view	Max FPS	Storage	Release date	Weight (kg)	Dimensions WxHxD (mm)	Video	Main Battery
1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 156 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 156 x 80	-	NP-E3
10D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10D Mk II N	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
10D Mk II Dual DIGIC II	DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
10D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.110	156 x 157 x 80	1080p30	LP-E4

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## Observations and assertions



f1,f2,f3  
v11,v12,v13  
v21,v22,v23

example

CSV



# Automated testing

(challenge: identify a set of input that is covering enough cases)

Case by case verification?

Generic properties?

Product	Image process.	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
Find								
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
Find								
D2Xs	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D3X	-	APS-C	CCD	Sony	5.3	5	1005	98%
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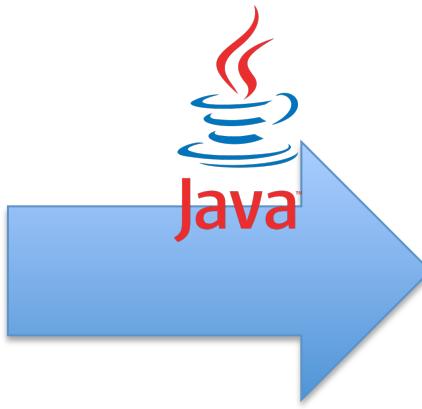
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1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 130k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 160 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.200	156 x 158 x 80	-	NP-E3
10 Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
10 Mk III	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk II	Dual DIGIC II	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk IV	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.115	156 x 157 x 80	1080p30	LP-E4

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f1,f2,f3  
v11,v12,v13  
v21,v22,v23

example

CSV

# Automated testing

(You cannot test using one single page!)

Product	Image process.	Sensor format	Sensor type	Sensor manuf.	Megapixels	Focus points	Metering pixels	Viewfinder cov.
D3X	EXPED	Full-frame	CMOS	Sony	24.5	51	1005	100%
D2Xs	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D2X	-	APS-C	CMOS	Sony	12.4	11	1005	100%
D3X	-	APS-C	CCD	Sony	5.3	5	1005	98%

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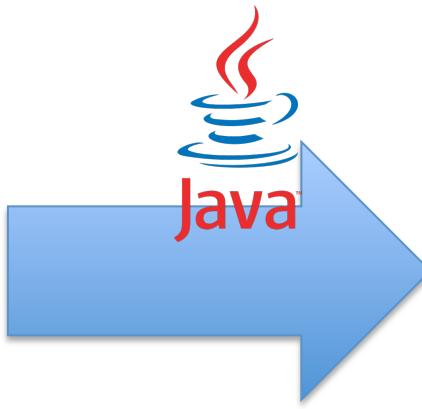
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1Ds	DIGIC	Full-frame CMOS	11.4	100	1250	45	0.70x, 100%	2.0", 120k	No	No	3	CF	2002Q4	1.265	156 x 158 x 80	-	NP-E3
1Ds Mk II	DIGIC II	Full-frame CMOS	16.7	50	3200	45	0.70x, 100%	2.0", 230k	No	No	4.5	CF, SD	2004Q4	1.215	156 x 158 x 80	-	NP-E2
1Ds Mk III	Dual DIGIC II	Full-frame CMOS	21.1	50	3200	45	0.76x, 100%	3.0", 230k	No	Yes	5.0	CF, SD	2007Q4	1.210	156 x 156 x 80	-	LP-E4
1D	DIGIC	APS-H CCD	4	100	3200	45	0.72x, 100%	2.0", 120k	No	No	8.0	CF	2001Q4	1.250	156 x 156 x 80	-	NP-E3
1D Mk II	DIGIC II	CMOS	8.2	50	3200	45	0.72x, 100%	2.0", 230k	No	No	8.5	CF, SD	2004Q2	1.220	156 x 158 x 80	-	NP-E3
1D Mk III	DIGIC II	APS-H CMOS	8.2	50	3200	45	0.72x, 100%	2.5", 230k	No	No	8.5	CF, SD	2005Q3	1.225	156 x 158 x 80	-	NP-E3
1D Mk IV	Dual DIGIC 4	APS-H CMOS	10.1	50	6400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2007Q1	1.155	156 x 157 x 80	-	LP-E4
1D Mk V	Dual DIGIC 4	CMOS	16.1	50	102,400	45	0.76x, 100%	3.0", 230k	No	Yes	10	CF, SD	2009Q4	1.115	156 x 157 x 80	1080p30	LP-E4

43 / 43

Case by case verification?  
Generic properties?



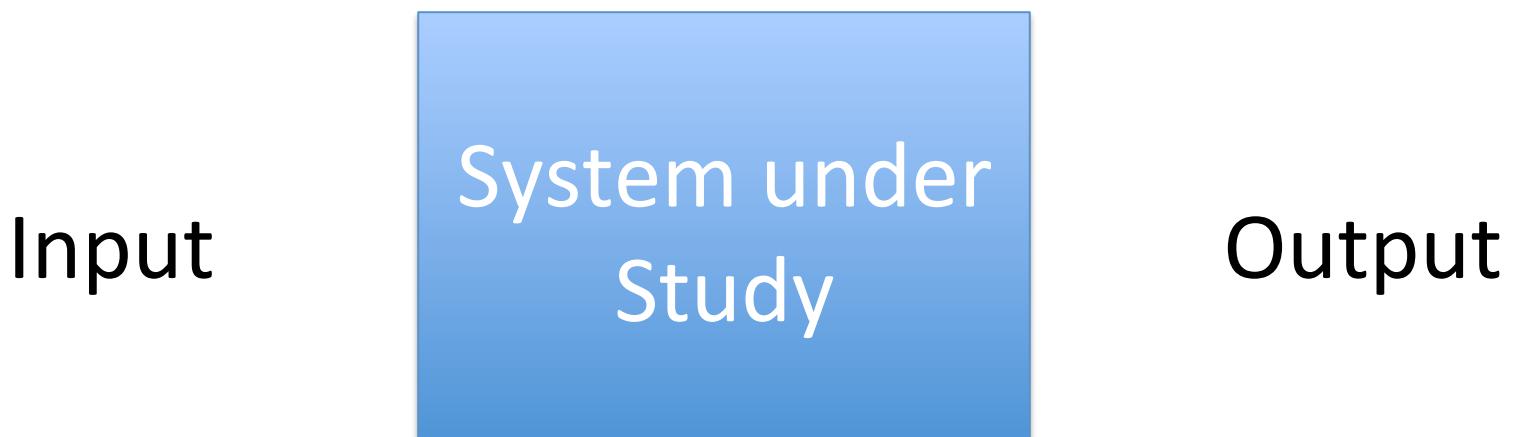
f1,f2,f3  
v11,v12,v13  
v21,v22,v23

example

CSV

# Testing Problem

- Test Generation Problem (input)
- Oracle Problem (output)



# Assertion-based Testing

- Eg unit tests à la JUnit

```
@Test
def void basicOrTest() {
    val result = parseHelper.parse("""
        solver sat4j-java
        A v B
    """)
    val dimacsPrinted = DIMACSPrinter.dimacsFile(result.expression)
    val oracle = "p cnf 2 1\n1 2 0"
    Assertions.assertNotNull(result)
    val errors = result.eResource.errors
    Assertions.assertTrue(errors.isEmpty, """Unexpected errors: «errors.join(", ")»""")
    Assertions.assertTrue(dimacsPrinted == oracle)
}
```

A test engineer walks into  
a bar and



— Bill Sempf (@sempf)

A test engineer walks into  
a bar and

- orders a beer

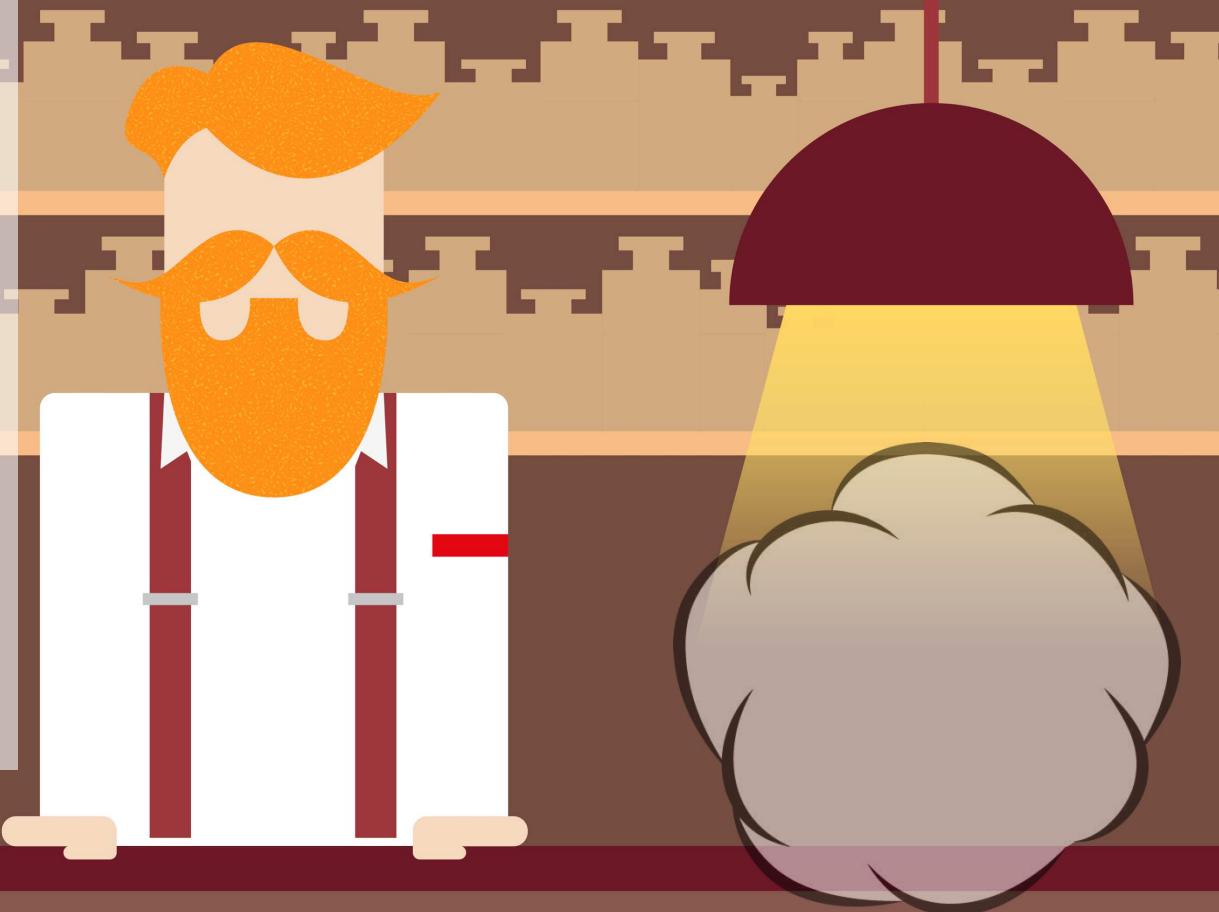
— Bill Sempf (@sempf)



A test engineer walks into  
a bar and

- orders a beer
- orders 0 beers

— Bill Sempf (@sempf)



A test engineer walks into  
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers

— Bill Sempf (@sempf)

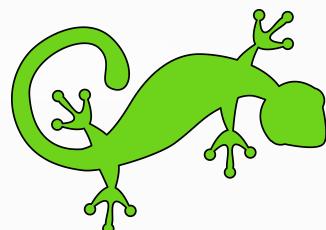
9,999,999



A test engineer walks into  
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers
- orders a lizard

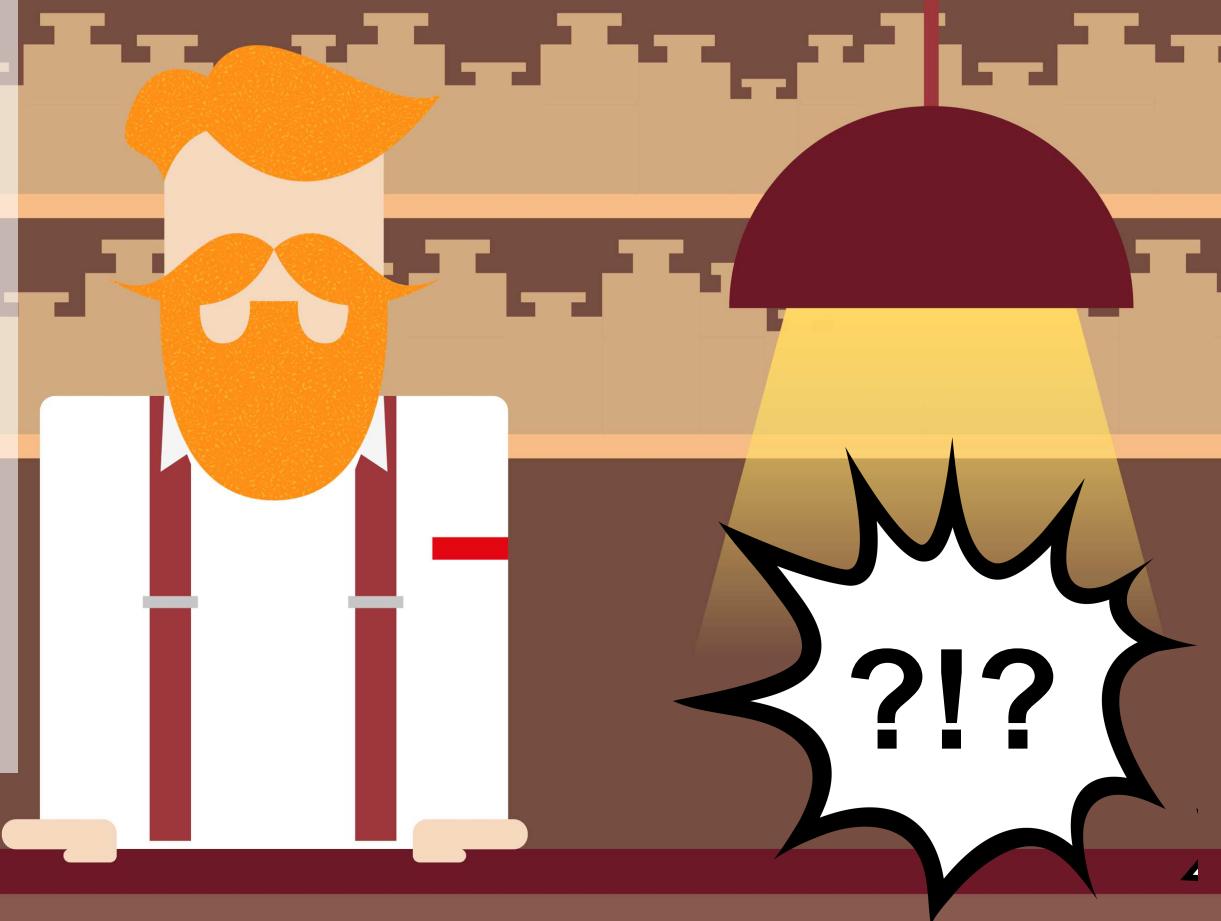
— Bill Sempf (@sempf)



A test engineer walks into  
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers
- orders a lizard
- orders -1 beers

— Bill Sempf (@sempf)

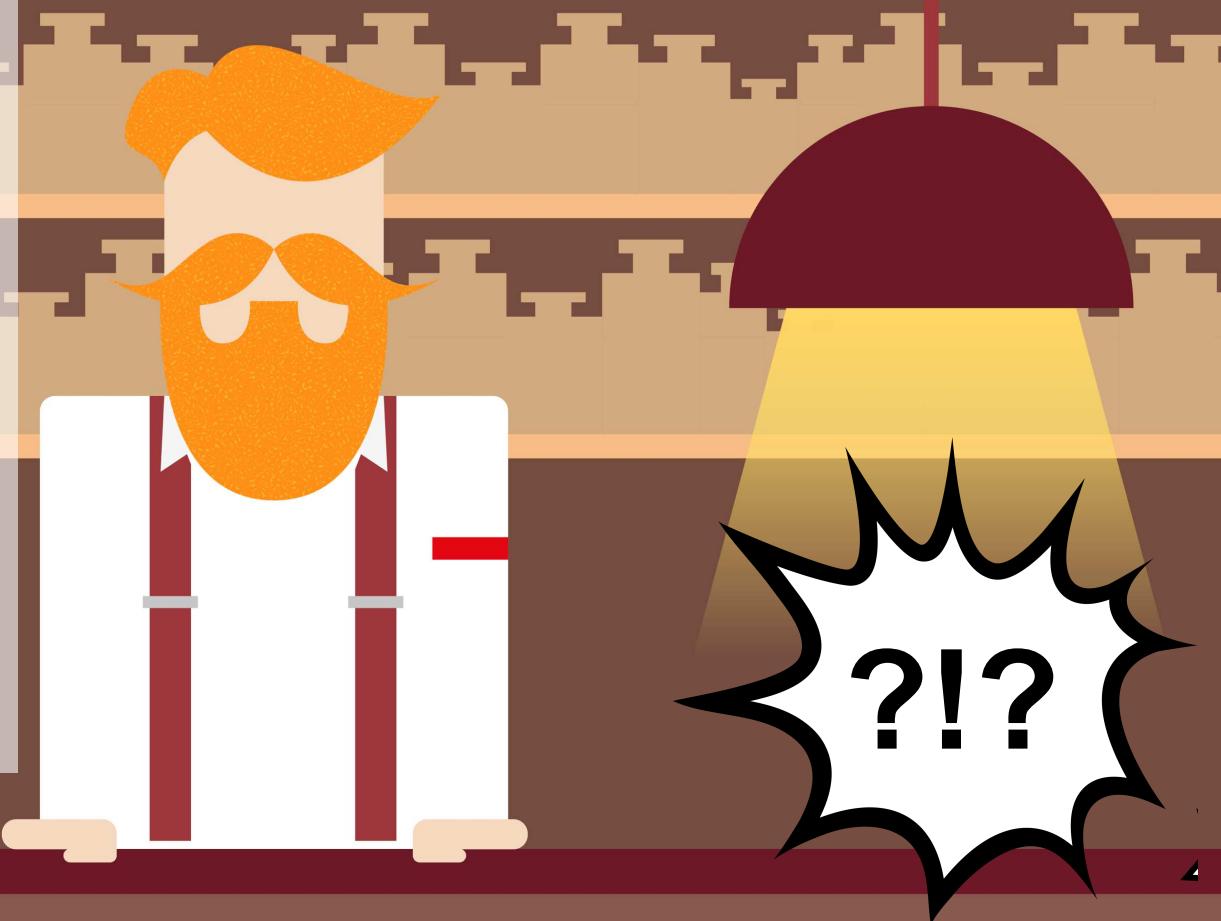


-1

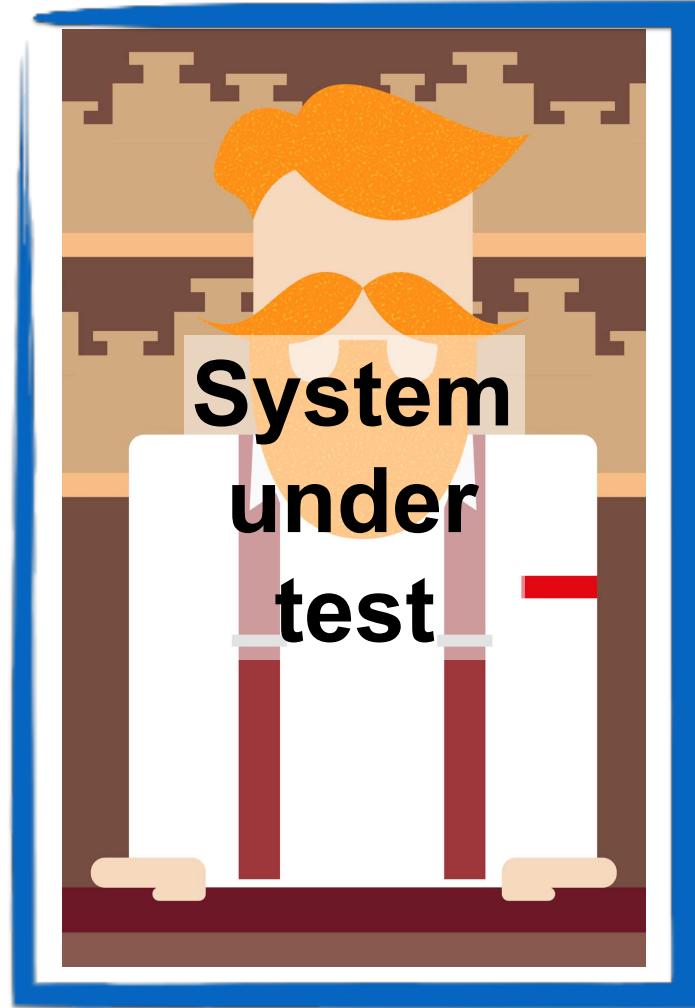
A test engineer walks into  
a bar and

- orders a beer
- orders 0 beers
- orders 9999999 beers
- orders a lizard
- orders -1 beers
- orders a "sfdeljknesv"

— Bill Sempf (@sempf)



"sfdeljknesv"



**System  
under  
test**



Specification





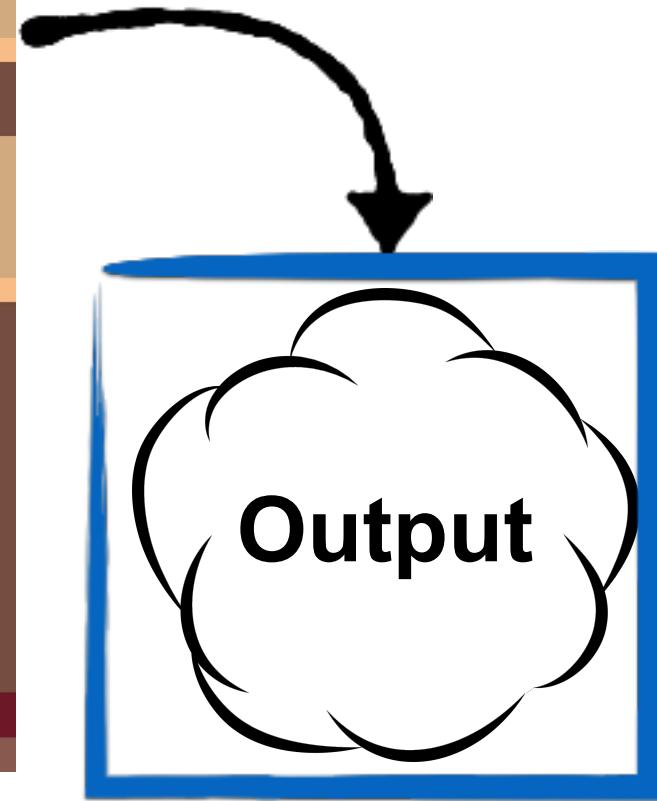
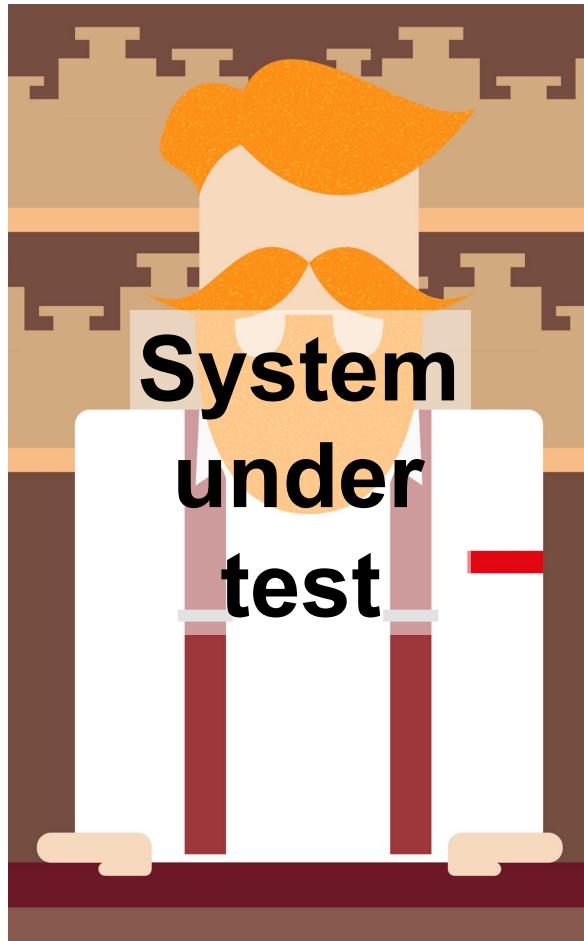
Specification



Test case

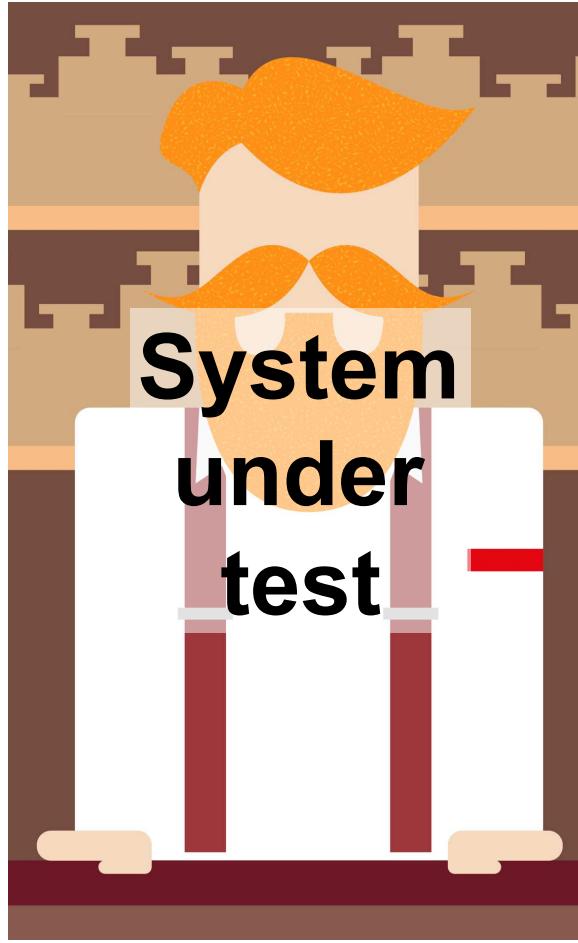


Specification

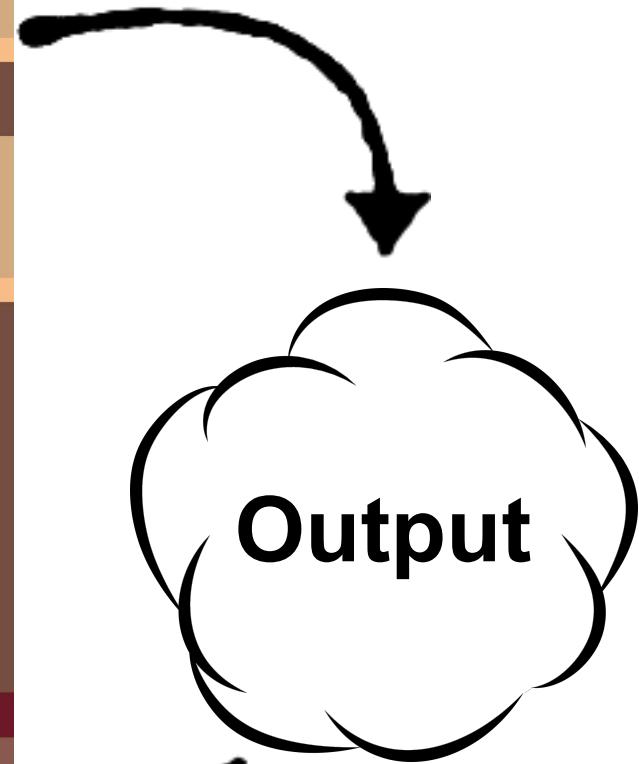




Specification



Test case



Pass or fail?

# What is a test?

A test consists of

- an **input**
- an **oracle**

End-to-end test:

- Batch program: input = file, oracle = expected file
- Interactive program: input = UI events, oracle = windows

Unit test:

- Input = sequence of calls
- Oracle = assert statement



# Example unit test

```
Object[] a = new Object[];  
LinkedList ll = new LinkedList();  
ll.addFirst(a);  
TreeSet ts = new TreeSet(ll);  
Set u =  
Collections.unmodifiableSet(ts);
```

```
assert u.equals(u);
```

input

oracle

Assertion fails:  
used to be a bug in the JDK!

```
@Test
def void basicBiImplTest() {
    val result = parseHelper.parse('''
        solver sat4j-java
        A <=> B
    ''')
    val prettyPrinted = PrettyPrinter.prettyPrint(result.expression)

    val oracle = "(A <=> B)"

    Assertions.assertNotNull(result)
    val errors = result.eResource.errors
    Assertions.assertTrue(errors.isEmpty, '''Unexpected errors: «errors.join(", ")»'''')

    Assertions.assertTrue(prettyPrinted == oracle)
}
```

```
@Test
def void basicOrTest() {
    val result = parseHelper.parse("""
        solver sat4j-java
        A v B
    """)
    val dimacsPrinted = DIMACSPrinter.dimacsFile(result.expression)

    val oracle = "p cnf 2 1\n1 2 0"

    Assertions.assertNotNull(result)
    val errors = result.eResource.errors
    Assertions.assertTrue(errors.isEmpty, '''Unexpected errors: «errors.join(", ")»'''')

    Assertions.assertTrue(dimacsPrinted == oracle)
}
```

# Strengths and Limits

- Precise oracles
- Domain-specific knowledge
- Examples-based
  - Input test is limited by construction
  - Incomplete (cases)
- Tests subject to developers bias
- Costly
  - One specific oracle per example (labelling)

# Mutation Testing

- Based on Caroline Landry (DiverSE team, STAMP project) slides at Breizh Camp

# Test Your Tests

- What do you expect from test cases?
  - Cover requirements
  - Stress the application
  - Prevent regressions
  - Reveal bugs
- Quality of test suite matters!
  - But what's a good test suite?



# Test Your Tests

- What do you expect from test cases?
  - Cover requirements
  - Stress the application
  - Prevent regressions
  - **Reveal bugs**
- Quality of test suite matters!
  - But what's a good test suite?



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <=  
n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

## Coverage



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}  
  
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}
```

## Coverage



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}  
  
@Test  
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```

# Coverage



# Example

```
long fact(int n) {  
    if (n <= 1) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result *= i;  
    }  
    return result;  
}  
@Test  
public void testFact() {  
    assertEquals(1,  
    fact(0));  
}
```

Is this test suite good  
at detecting bugs?

## Coverage



# Example

```
long fact(int n) {  
    if (n <= 1) return 1;  
    return n * fact(n - 1);  
}
```

@Test

Is this test suite good  
at detecting bugs?

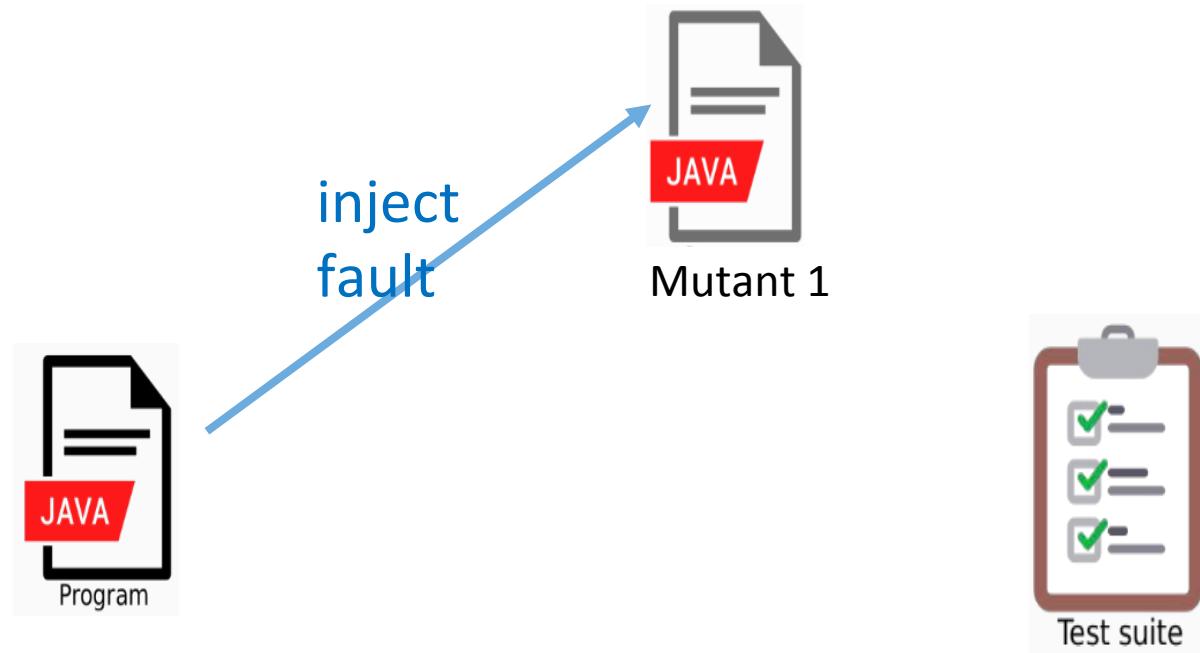
Let's mutate our code  
to see.



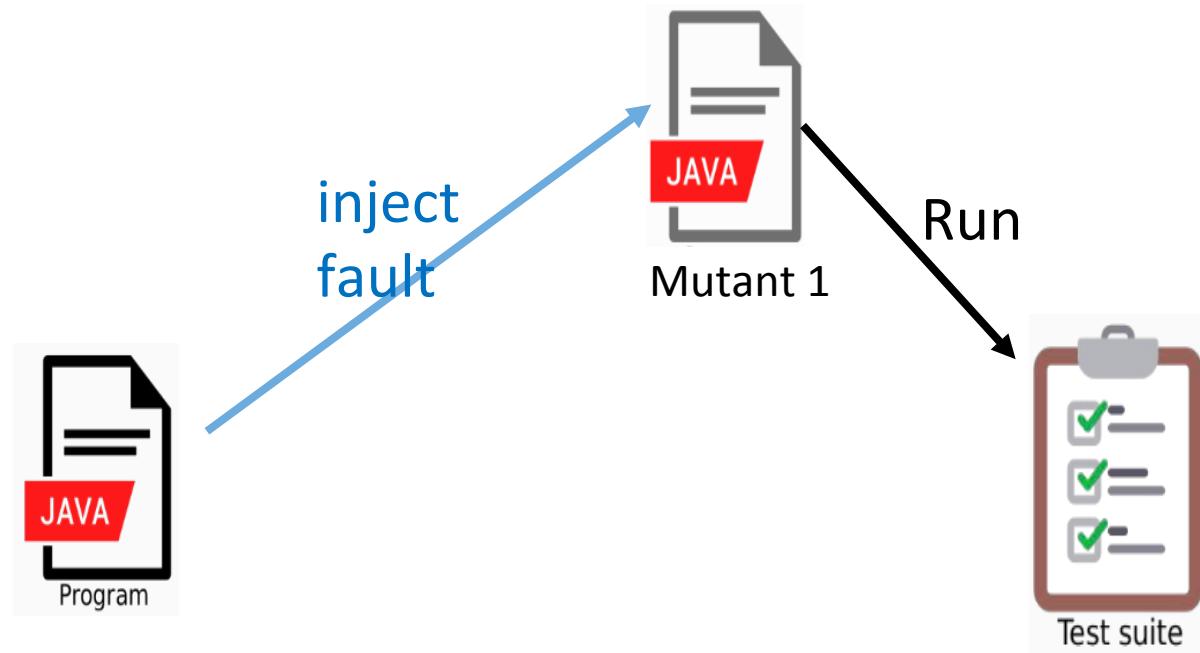
# Mutation Analysis



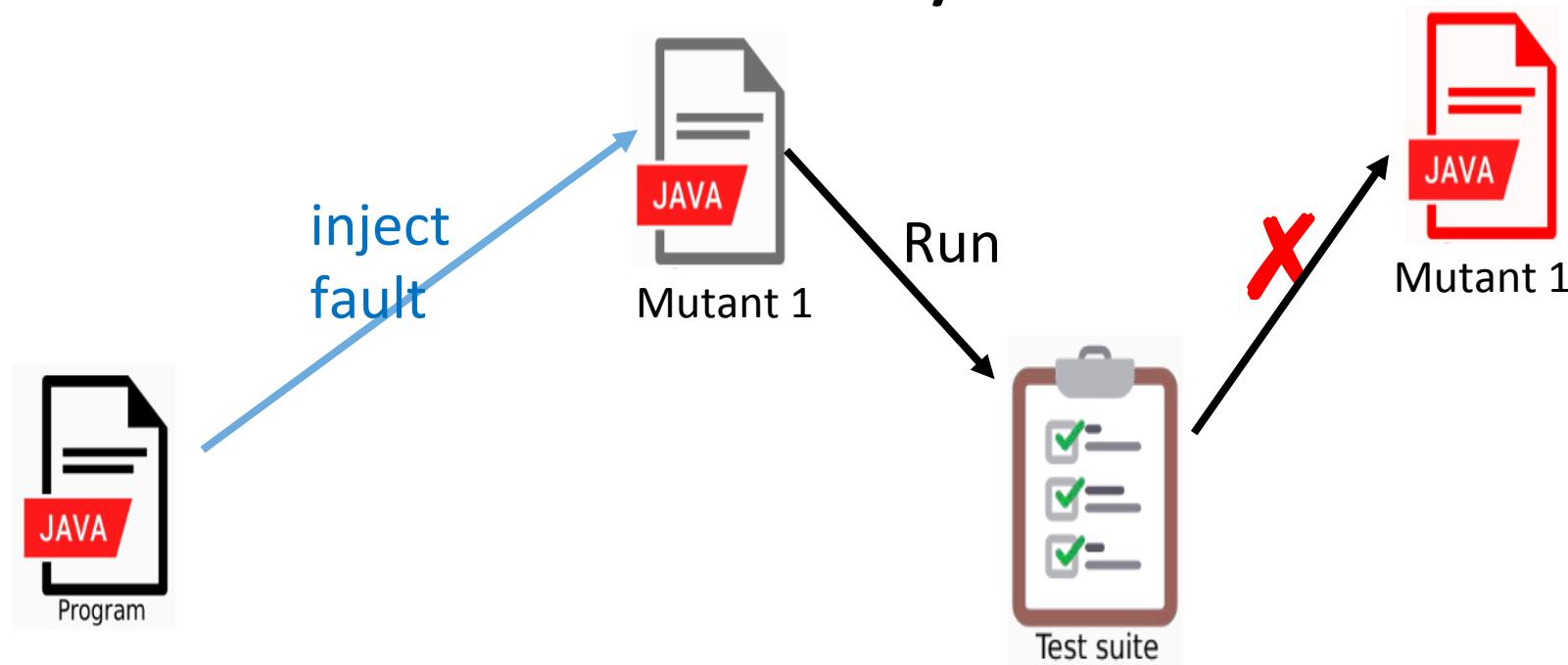
# Mutation Analysis



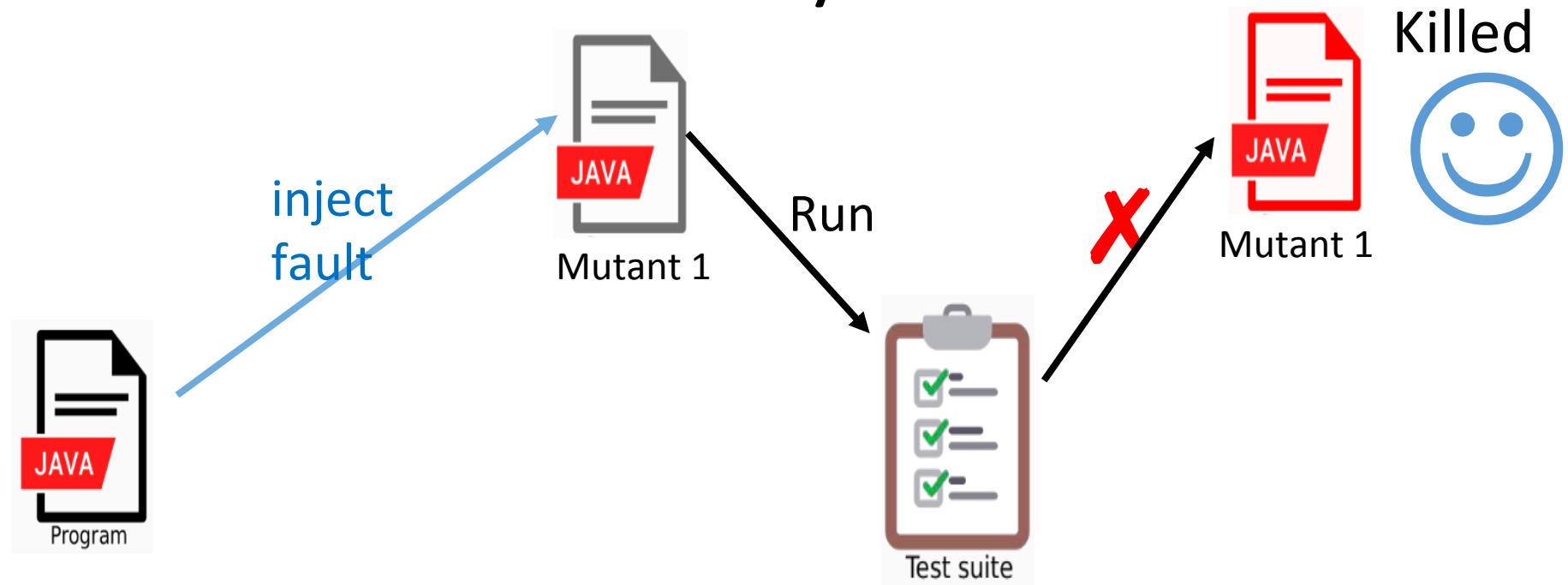
# Mutation Analysis



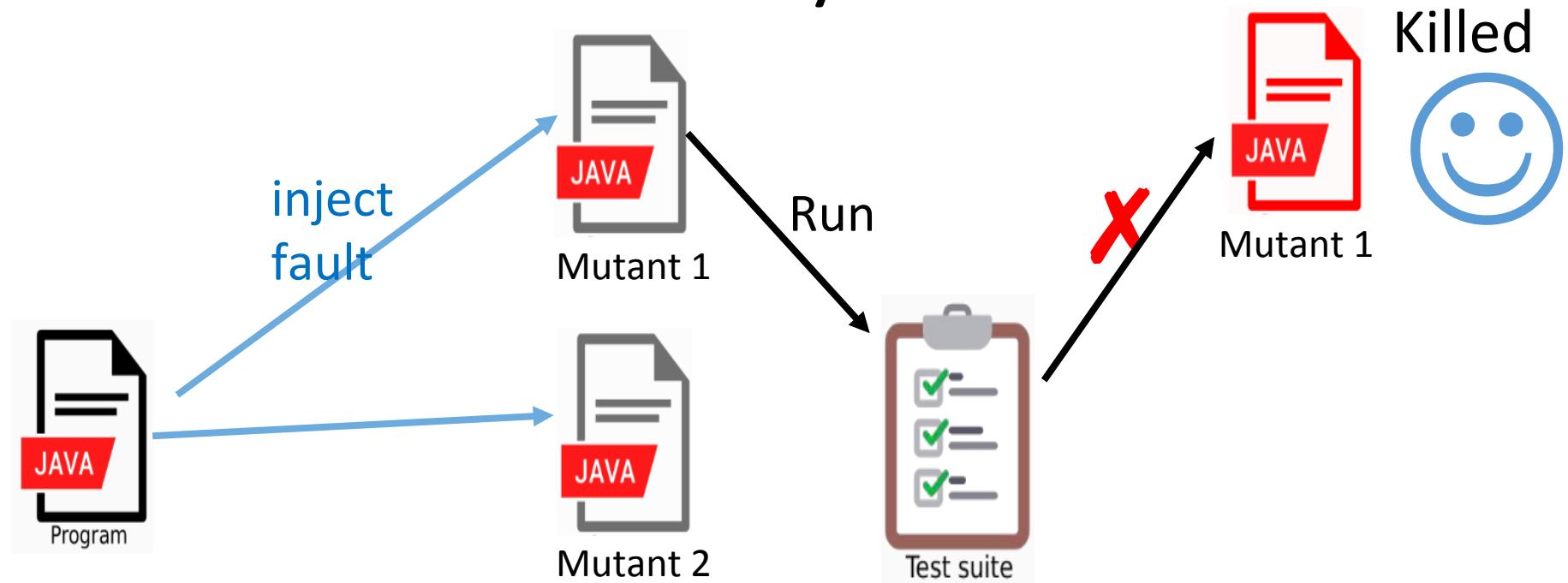
# Mutation Analysis



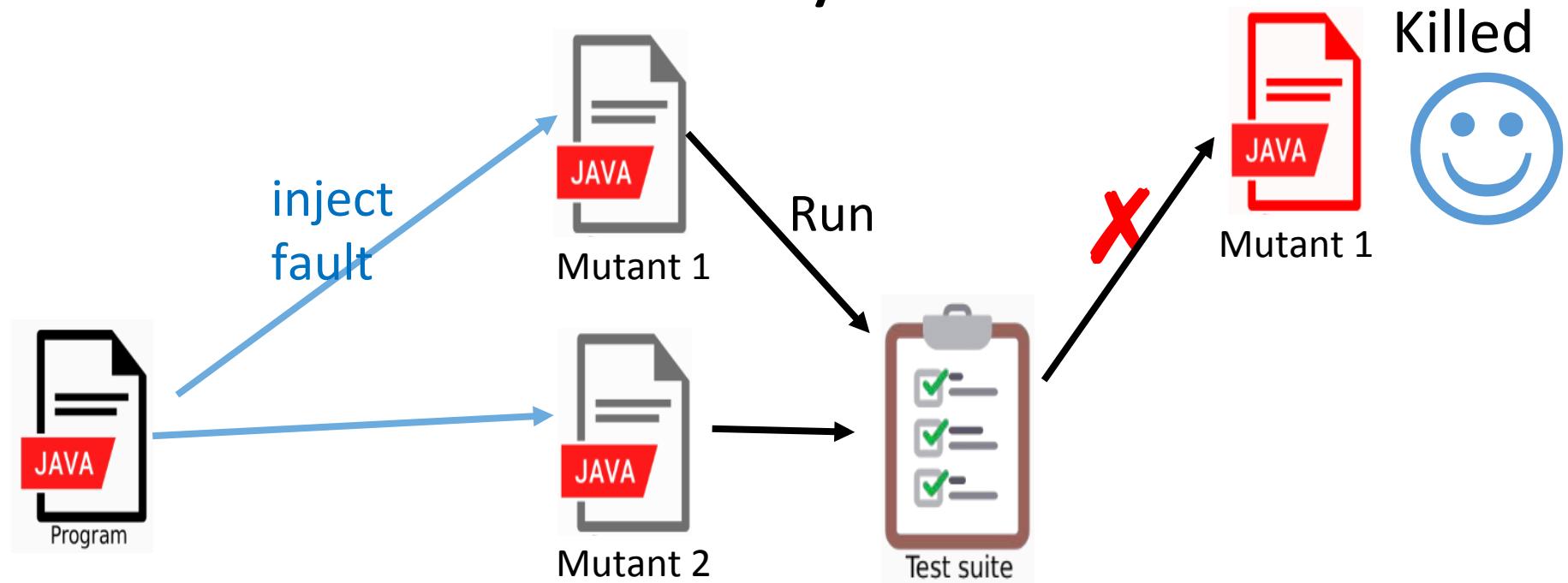
# Mutation Analysis



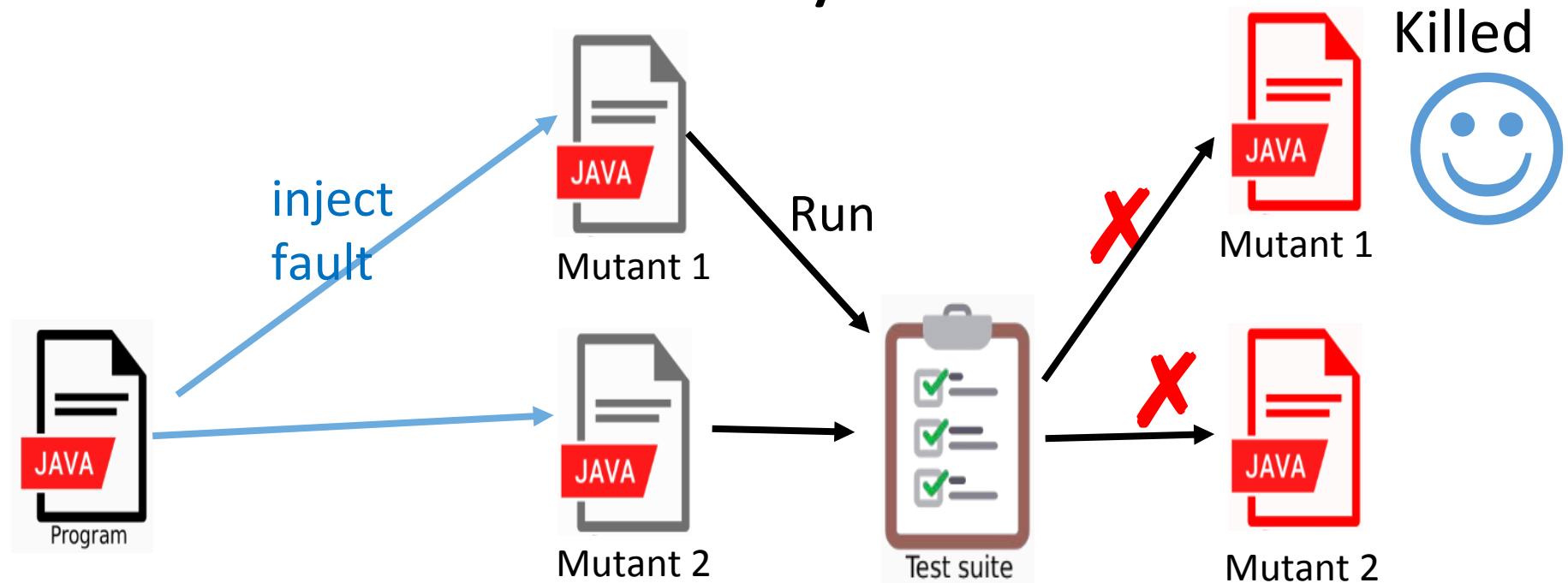
# Mutation Analysis



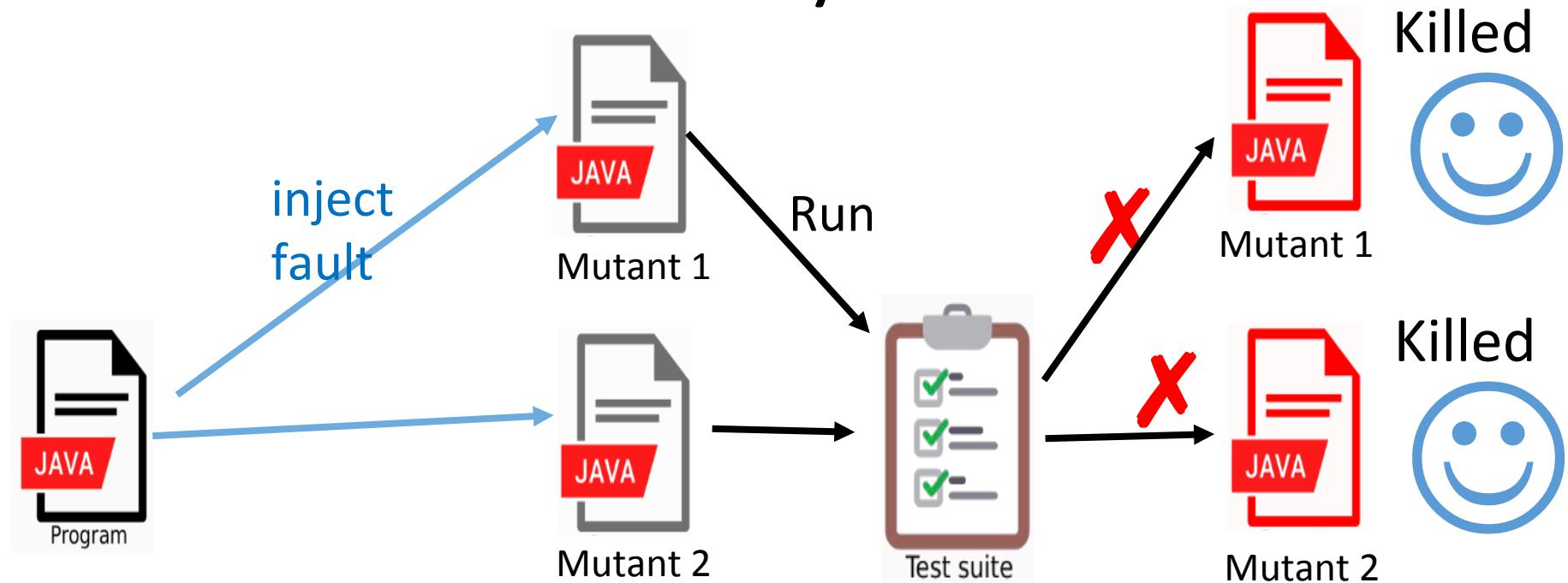
# Mutation Analysis



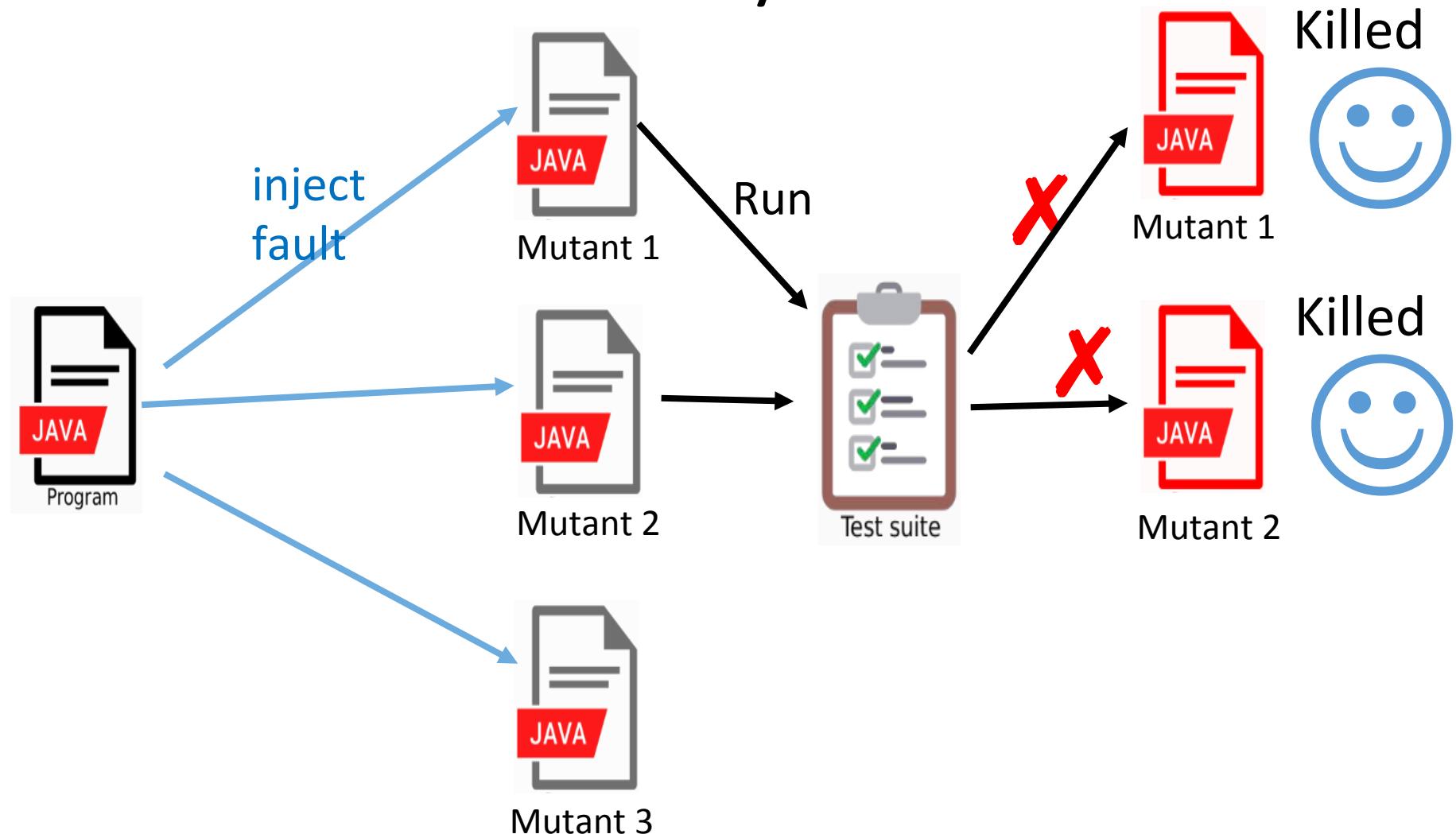
# Mutation Analysis



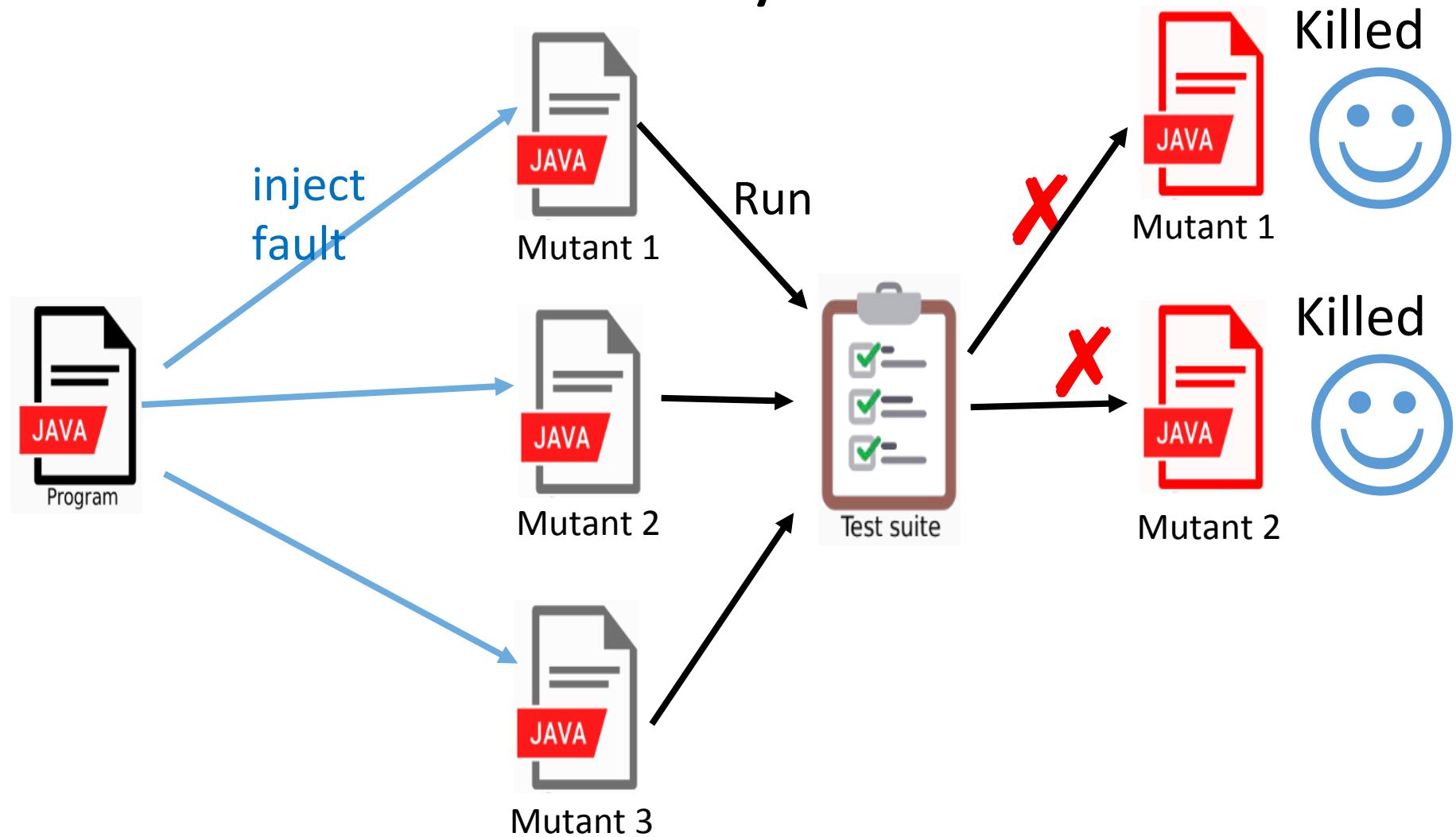
# Mutation Analysis



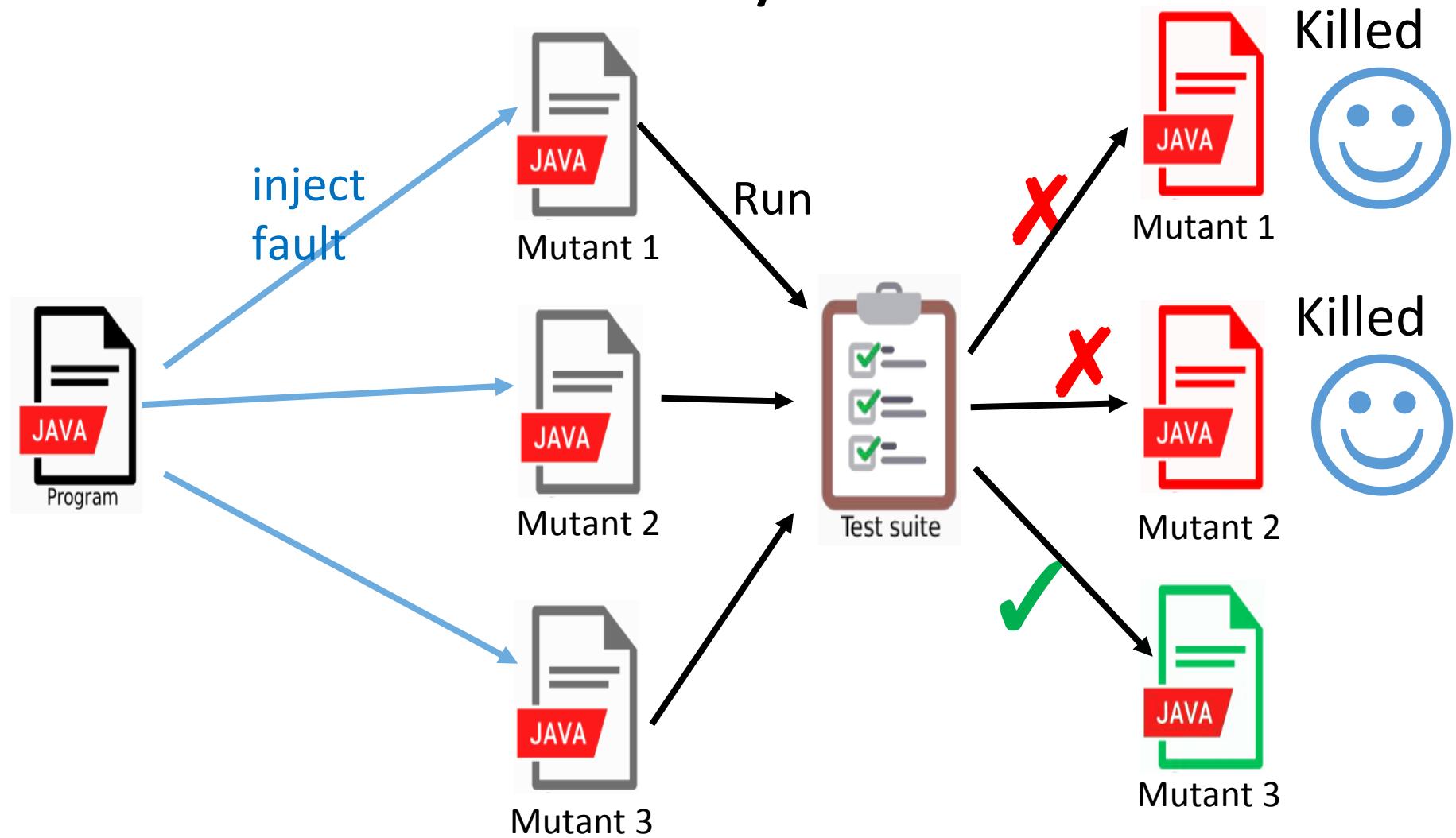
# Mutation Analysis



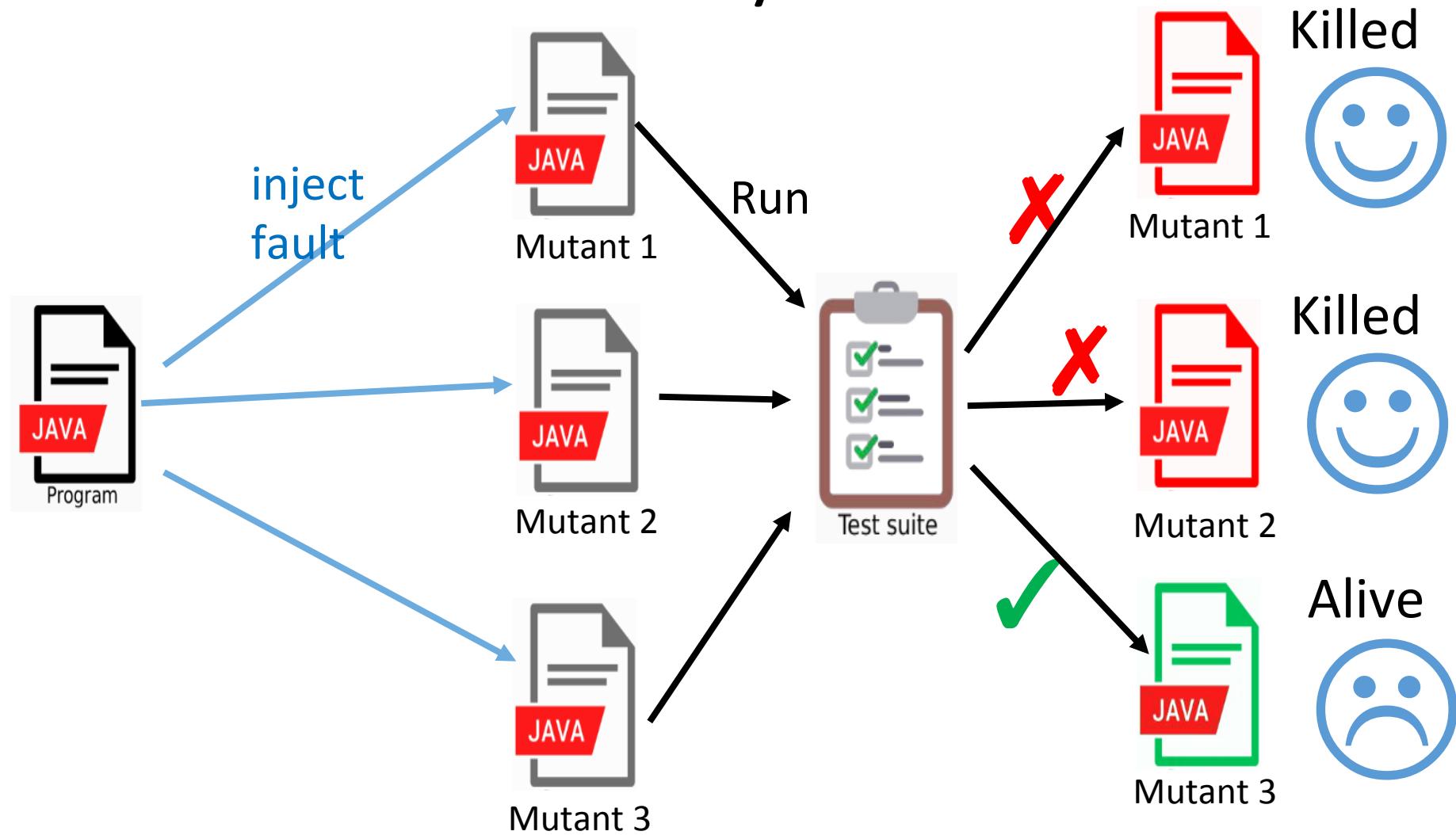
# Mutation Analysis



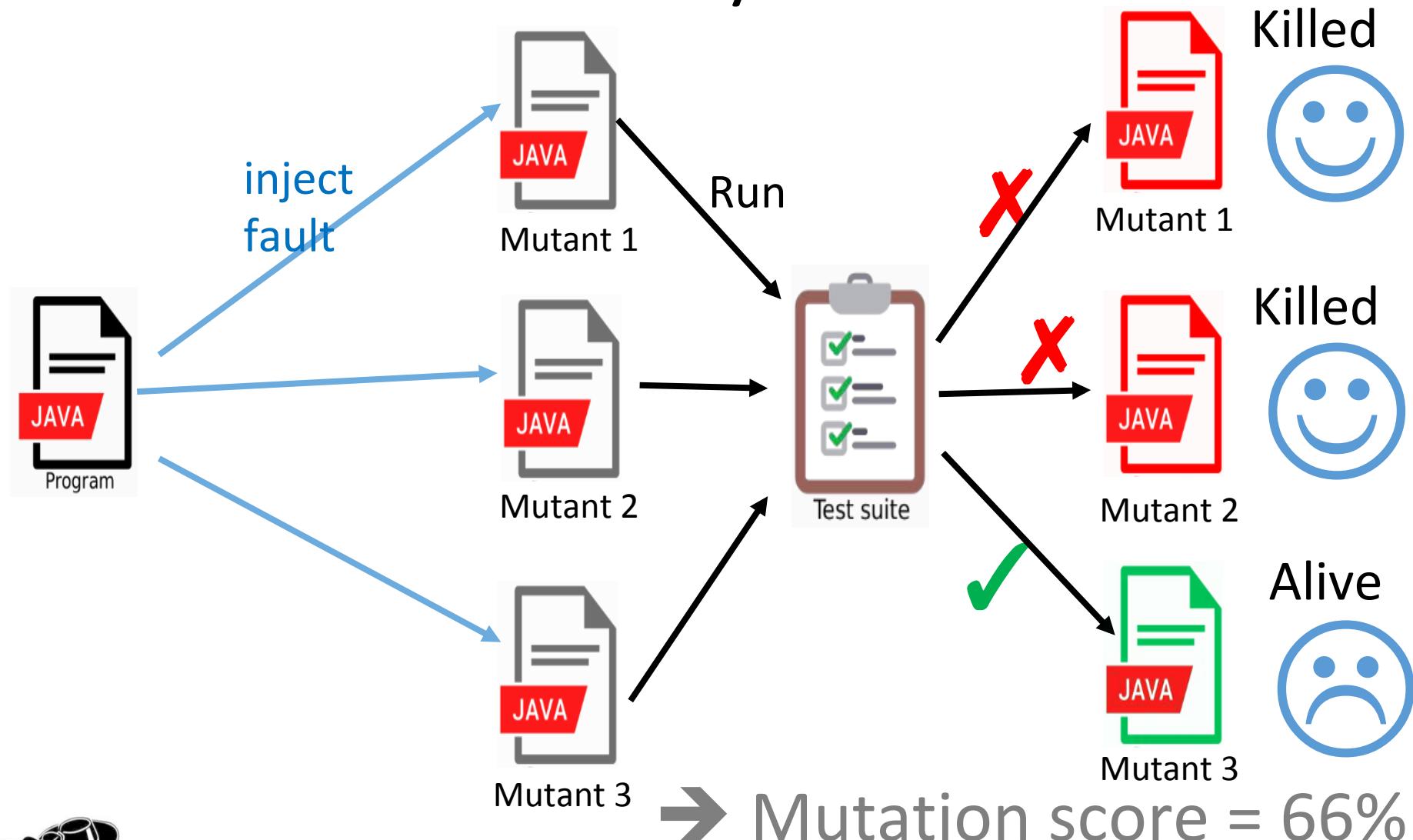
# Mutation Analysis



# Mutation Analysis



# Mutation Analysis



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

@Test

```
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}
```

@Test

```
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```



# Example

```
long fact(int n) {  
    if (n != 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```



@Test

```
factorialWith5Test()  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}
```



@Test

```
factorialWith0Test()  
) {  
    assertEquals(1,  
fact(0));  
}
```



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

The diagram illustrates the flow of control through the code. Blue arrows point from specific code lines to boxes containing intermediate or final values:

- An arrow points from the condition `n == 0` to a box labeled `n != 0`.
- An arrow points from the `return 1;` statement to a box labeled `return 1+1`.
- Two arrows point from the loop condition `i <= n` to boxes labeled `i < n` and `!(i <= n)`.
- An arrow points from the assignment `result = result * i;` to a box labeled `i--`.
- An arrow points from the assignment `result = result * i;` to a box labeled `result/i`.
- An arrow points from the final `return result;` statement to a box labeled `result+1`.



# Example

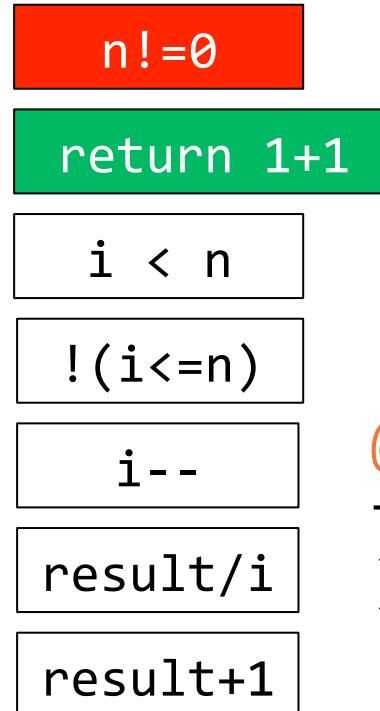
```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
}  
  
n!=0  
return 1+1  
i < n  
!(i<=n)  
i--  
result/i  
result+1
```



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```



```
@Test  
factorialWith0Test(  
) {  
    assertEquals(1,  
    fact(0));  
}
```



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
@Test  
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
    assertTrue(5 <  
obs);  
@Test  
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```



# Example →

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
  
    return result;  
}
```

Mutation

score = 71%

Test suite:

- Weak oracle
- Missing input

@Test

```
factorialWith5Test(  
) {  
    long obs =  
fact(5);  
  
    assertTrue(5 <  
obs);  
}
```

@Test

```
factorialWith0Test(  
) {  
    assertEquals(1,  
fact(0));  
}
```



# Example

```
long fact(int n) {  
    if (n == 0) {  
        return 1;  
    }  
    long result = 1;  
    for (int i = 2; i <= n; i++) {  
        result = result * i;  
    }  
    return result;  
}
```

```
n!=0  
return 1+1  
i < n  
!(i<=n)  
i--  
result/i  
result+1
```

@Test

```
factorialWith5Test()  
{  
    long obs = fact(5);  
    assertTrue(5 < obs);  
}
```

@Test

```
factorialWith0Test() {  
    assertEquals(1,  
    fact(0));  
}
```

@Test

```
factorialWith5Test() {  
    assertEquals(120,  
    fact(5));  
}
```



# Mutation Analysis

- Tests are good if they can detect bugs
- Mutation operators
  - Based on common faults
- PIT or PITest
  - Open source, in active development and production ready
  - Integrates with major build systems
  - State of the art mutation testing
  - Extensible via plugins
  - Concurrent execution
  - Test selection



# Limitations of mutation testing

- Expensive computation
- Huge number of mutants
- Presence of equivalent mutants

```
int Min (int i, intj){  
    int minval = i;  
    if (j<i) then minval = j;  
    return minval  
}
```

```
int Min (int i, intj){  
    int minval = i;  
    if (j<minval) then minval = j;  
    return minval  
}
```



# Test Input Generation

- The case of compilers
- Csmith PLDI'11
- Equivalence modulo inputs PLDI'14

# Random Generator: Csmith



*C program*

gcc -O0

gcc -O2

clang -Os

...

*results*

**vote**



*majority*

*minority*



# Finding and Understanding Bugs in C Compilers

Xuejun Yang    Yang Chen    Eric Eide    John Regehr

University of Utah, School of Computing

{jxyang, chenyang, eeide, regehr }@cs.utah.edu

- *Randomized differential* testing has the advantage that no oracle for test results is needed.
- Idea: if one has multiple, deterministic implementations of the same specification, all implementations must produce the same result from the same valid input
- 300+ bugs found in compilers (eg gcc)

```
1 int foo (void) {  
2     signed char x = 1;  
3     unsigned char y = 255;  
4     return x > y;  
5 }
```

---

**Figure 1.** We found a bug in the version of GCC that shipped with Ubuntu Linux 8.04.1 for x86. At all optimization levels it compiles this function to return 1; the correct result is 0. The Ubuntu compiler was heavily patched; the base version of GCC did not have this bug.

# llvm bug 14972

```
struct tiny { char c; char d; char e; };

void foo(struct tiny x) {
    if (x.c != 1) abort();
    if (x.e != 1) abort();
}

int main() {
    struct tiny s;
    s.c = 1; s.d = 1; s.e = 1;
    foo(s);
    return 0;
}
```

```
$ clang -m32 -O0 test.c ; ./a.out
$ clang -m32 -O1 test.c ; ./a.out
Aborted (core dumped)
```

# llvm bug 14972

```
struct tiny { char c; char d; char e; };

void foo(struct tiny x) {
    if (x.c != 1) abort();
    if (x.e != 1) abort();
}

int main() {
    struct tiny s;
    s.c = 1; s.d = 1; s.e = 1;
    foo(s);
    return 0;
}
```

```
$ clang -m32 -O0 test.c ; ./a.out
$ clang -m32 -O1 test.c ; ./a.out
Aborted (core dumped)
```

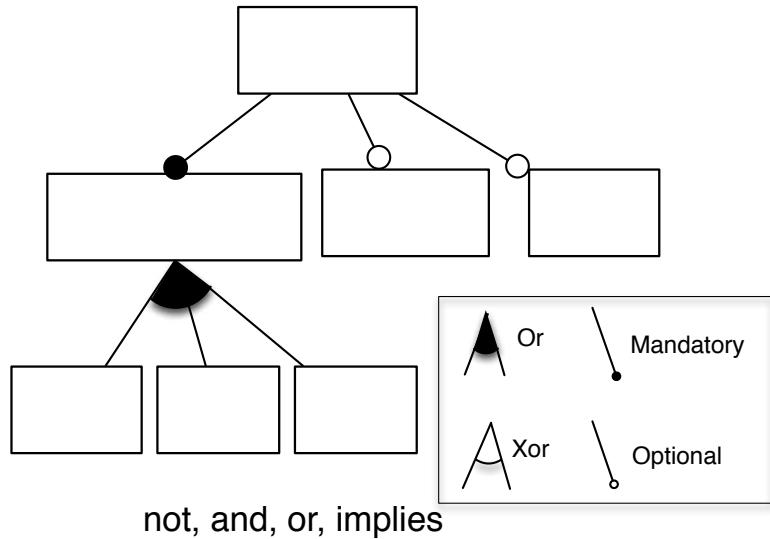
A bug in the LLVM optimizer causes this miscompilation. The developers believe that the Global Value Numbering (GVN) optimization turns the struct initialization into a single 32-bit load. Subsequently, the Scalar Replacement of Aggregates (SROA) optimization decides that the 32-bit load is undefined behavior, as it reads past the end of the struct, and thus does not emit the correct instructions to initialize the struct. The developer who fixed the issue characterized it as

*“... very, very concerning when I got to the root cause, and very annoying to fix.”*

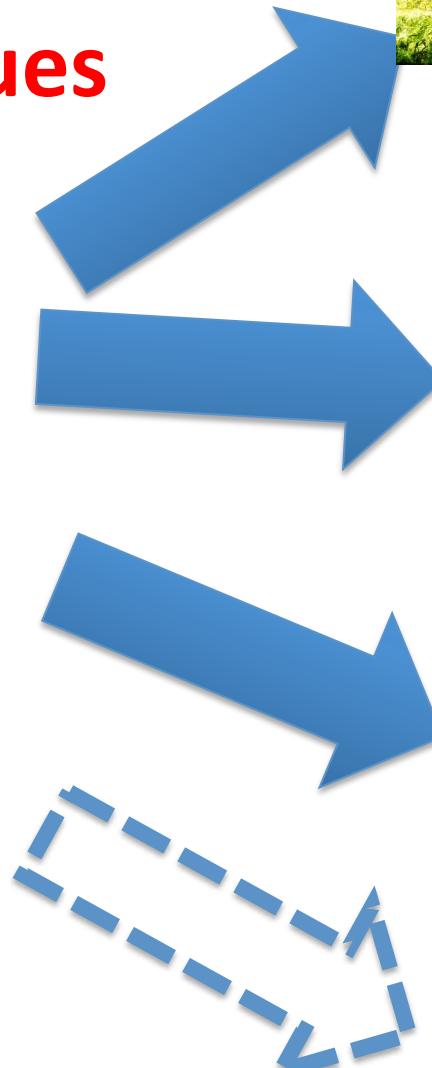
# Test input generation

- Performance-related testing

# We synthesize video sequence variants with variability techniques



## Variability Models (feature models)



# Why?

**Industrial needs:  
consumer and provider of  
video algorithms have severe**

**difficulties to test their  
algorithms on different kinds  
of inputs.**



# Test algorithms on different kinds of inputs that influence execution time, precision, and/or recall



**Algorithm 1**

0.63



0.81

**Algorithm 2**

0.93

**Algorithm 3**

0.82



0.43

0.92

0.81



0.39

0.3

0.8

0.03

0.01

# Why?

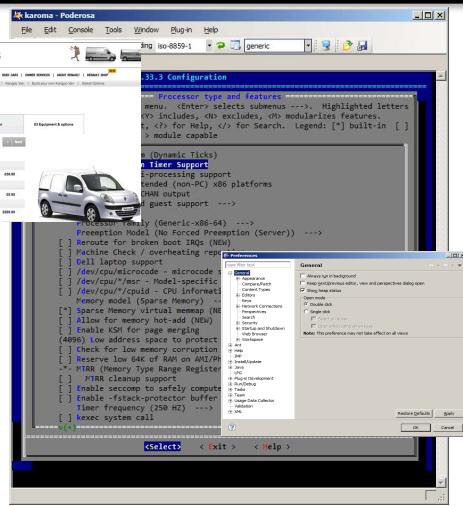


**Problem: collecting videos is a key economic problem.**



**Solution: hundreds of video sequences with different characteristics.**





## Feature Model

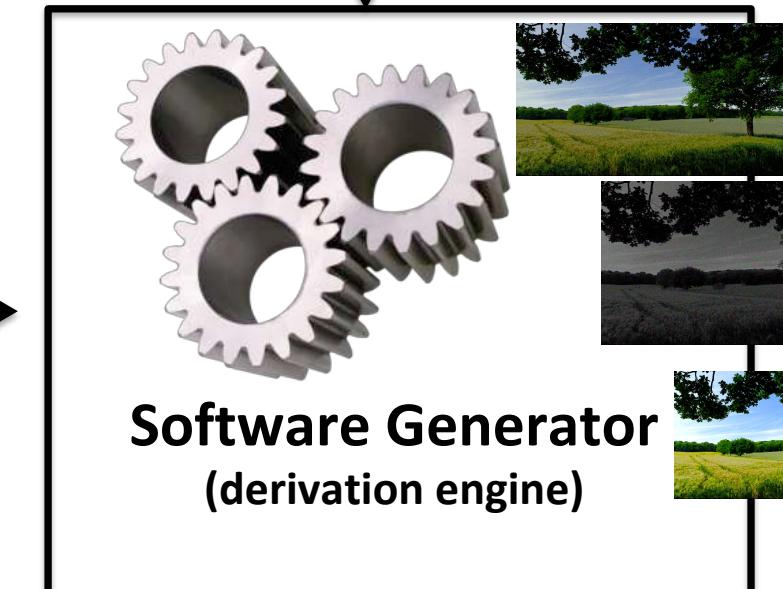
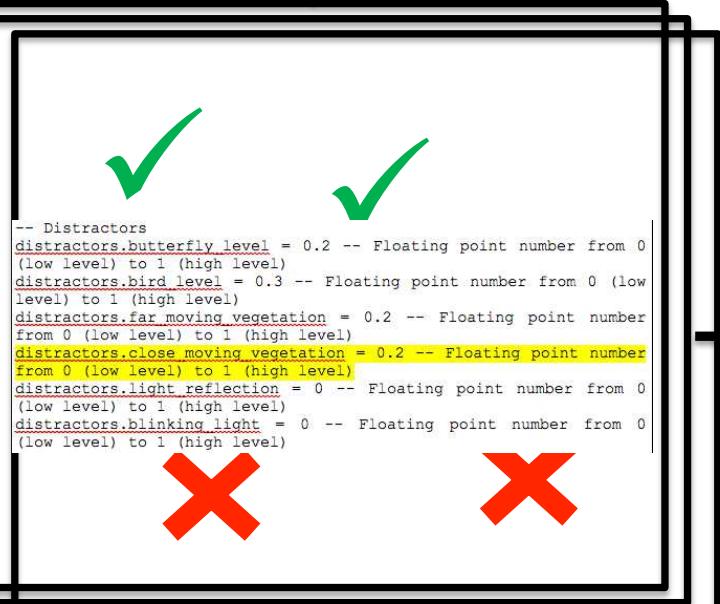
mapping

```

printC"-->Step9")
if (CFG.distractors.close_moving_vegetation~=0) then
    windvect5, precwindvect5, newwindvect5 =
    generate_wind_vector_field2(workwidth, workheight, 256, 1, 1, 35, picnum,
    precwindvect5, newwindvect5)
    windvectmul =
    windvect5:mul(24*CFG.distractors.close_moving_vegetation)
    globalvect = compose_vect(masque_feuilles_sombres, windvectmul, globalvect)
    hfvx, hfvy =
    windvect:mul6*CFG.distractors.close_moving_vegetation):to_matrix()
    hfvx = MATRIX.multerm(hfvx, invdepthmat)
    hfvy = MATRIX.multerm(hfvy, invdepthmat)
    lfvect = windvect2:resize_bilinear(windvect2.Width, windvect2.Height/16)
    lfvector = lfvector:resize_bilinear(windvect2.Width, windvect2.Height)
    lfvx, lfvy = lfvector:mul(
12*CFG.distractors.close_moving_vegetation):to_matrix()
    lfvx = MATRIX.multerm(lfvx, depthmat)
    lfvy = MATRIX.multerm(lfvx, depthmat*0.1)
    windvectcomp = VECT2D.new_from_matrices(MATRIX.addterm(lfvx, hfvx),
    MATRIX.addterm(lfvx, hfvy))
    globalvect = compose_vect(masque_ble, windvectcomp, globalvect)
    globalvect = compose_vect(masque_orge, windvectcomp, globalvect)
    globalvect = compose_vect(masque_ble_fond, windvectcomp, globalvect)
end

printC"-->Step10")

```



## Old Approach



Developers

*modify  
 $N$  times*

Video Sequences Generator

$N$  Configuration Files



...

*generates*



$N$  Video Sequences



## VM Approach

Developers and Domain Experts



*generates*



VM interpreter, and  
configuration files  
customizer

*model  
1 time*

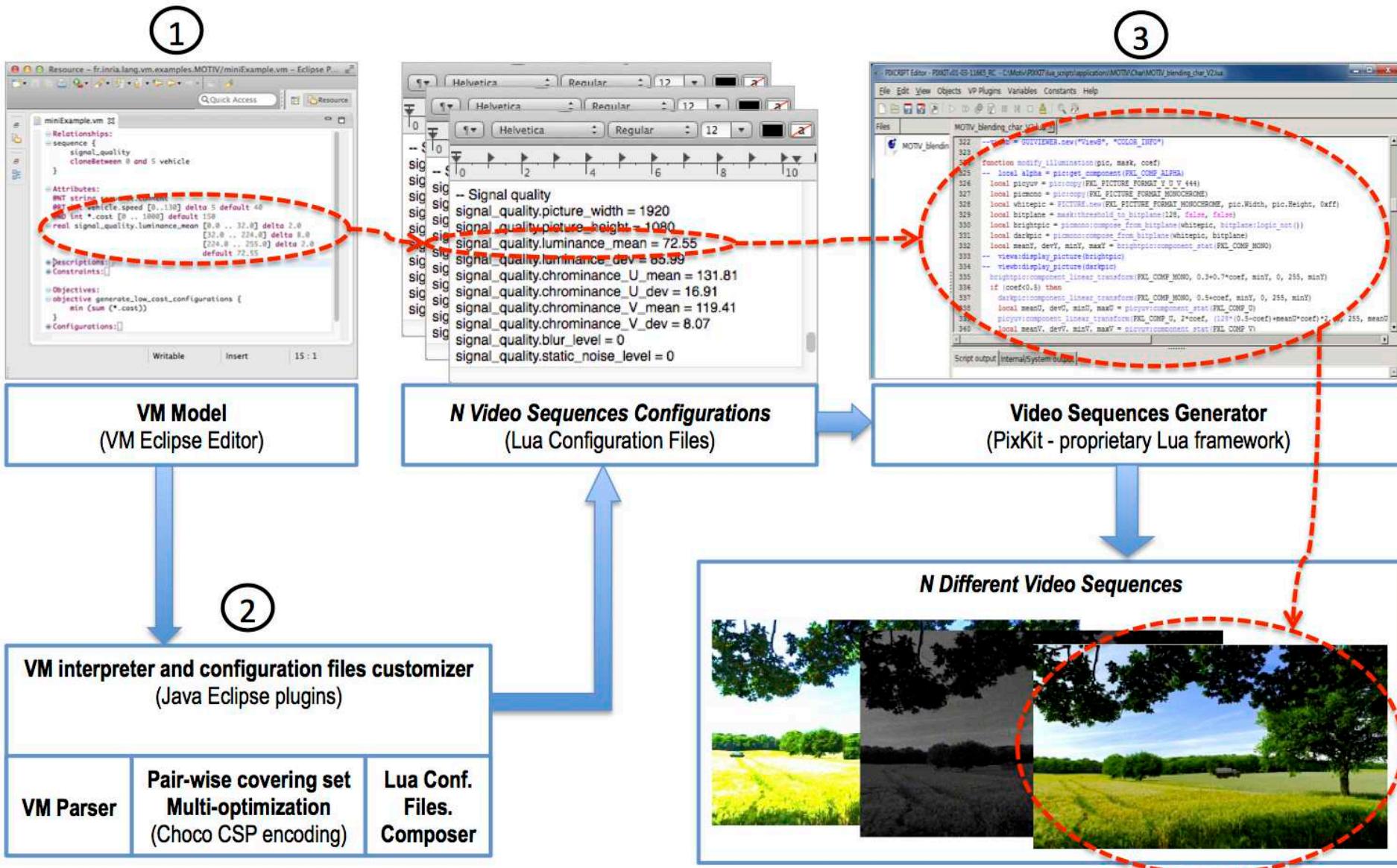


VM model

Artifact(s)



Processing  
tool(s)



# (configuration file)

```
-- Distractors
distractors.butterfly level = 0.2 -- Floating point number from 0
(low level) to 1 (high level)
distractors.bird level = 0.3 -- Floating point number from 0 (low
level) to 1 (high level)
distractors.far moving vegetation = 0.2 -- Floating point number
from 0 (low level) to 1 (high level)
distractors.close moving vegetation = 0.2 -- Floating point number
from 0 (low level) to 1 (high level)
distractors.light reflection = 0 -- Floating point number from 0
(low level) to 1 (high level)
distractors.blinking light = 0 -- Floating point number from 0
(low level) to 1 (high level)
```

---

```
print("=>Step9")
if (CFG.distractors.close moving vegetation~=0) then
    windvect5, precwindvect5, newwindvect5 =
generate_wind_vector_field2(workwidth, workheight, 256, 1, 1, 35, picnum,
precwindvect5, newwindvect5)
    windvectmul =
windvect5:mul(24*CFG.distractors.close moving vegetation)
    globalvect = compose_vect(masque_feuilles_sombres, windvectmul, globalvect)
    hfvx, hfvy =
windvect0:mul(6*CFG.distractors.close moving vegetation):to_matrix()
    hfvx = MATRIX.multerm(hfvx, invdepthmat)
    hfvy = MATRIX.multerm(hfvy, invdepthmat)
    lfvect = windvect2:resize_bilinear(windvect2.Width, windvect2.Height/16)
    lfvect = lfvect:resize_bilinear(windvect2.Width, windvect2.Height)
    lfvx, lfvy = lfvect:mul(
12*CFG.distractors.close moving vegetation):to_matrix()
    lfvx = MATRIX.multerm(lfvx, depthmat)
    lfvy = MATRIX.multerm(lfyv, depthmat*0.1)
    windvectcomp = VECT2D.new_from_matrices(MATRIX.addterm(lfvx, hfvx),
MATRIX.addterm(lfyv, hfvy))
    globalvect = compose_vect(masque_ble, windvectcomp, globalvect)
    globalvect = compose_vect(masque_orge, windvectcomp, globalvect)
    globalvect = compose_vect(masque_ble_fond, windvectcomp, globalvect)
end
print("=>Step10")
```

---

(Lua code)

Defects detection

Benchmarking

Incremental design

Performance prediction



**Algorithm 1**

0.63

0.81

0.43

0.39

**Algorithm 2**

0.93

0.92

0.3

0.03

**Algorithm 3**

0.82

0.81

0.8

0.01

# Metamorphic testing

- A metamorphic relation is a pair of conditions such that if two inputs fulfill the first, then the result of their evaluations must fulfill the second.
  - Example1 the shortest path between nodes A and B in a graph should have the same length as the shortest path between B and A
  - Example2: the “object of interest” in an image should be the same regardless of the colour palette
- Metamorphic testing is testing software by:
  - generating inputs that fulfill a metamorphic relation
  - confirming that their outputs fulfill that metamorphic relation

# Metamorphic testing in real-world

- A compiler output shouldn't change if you inject dead code paths
  - EMI idea can be seen as a “metamorphic” relation
  - Injecting dead code/runtime-constants into shaders made things in pictures disappear or turn to noise.
- “Refining” a search query should yield a subset of its original results
  - In Spotify: two searches for albums with the same query should return the same number of total results regardless of the size of pagination
- Unsupervised clustering (k-means): “do we get the same result if we shuffle the inputs?” and “do additional inputs at cluster boundaries belong to those clusters?”

# Example: Testing Computer Vision

- Test Generation Problem (input)
- Oracle Problem (output)

Training  
set

Machine  
Learning  
(classifier)

Accuracy



# Metamorphic Testing for CV

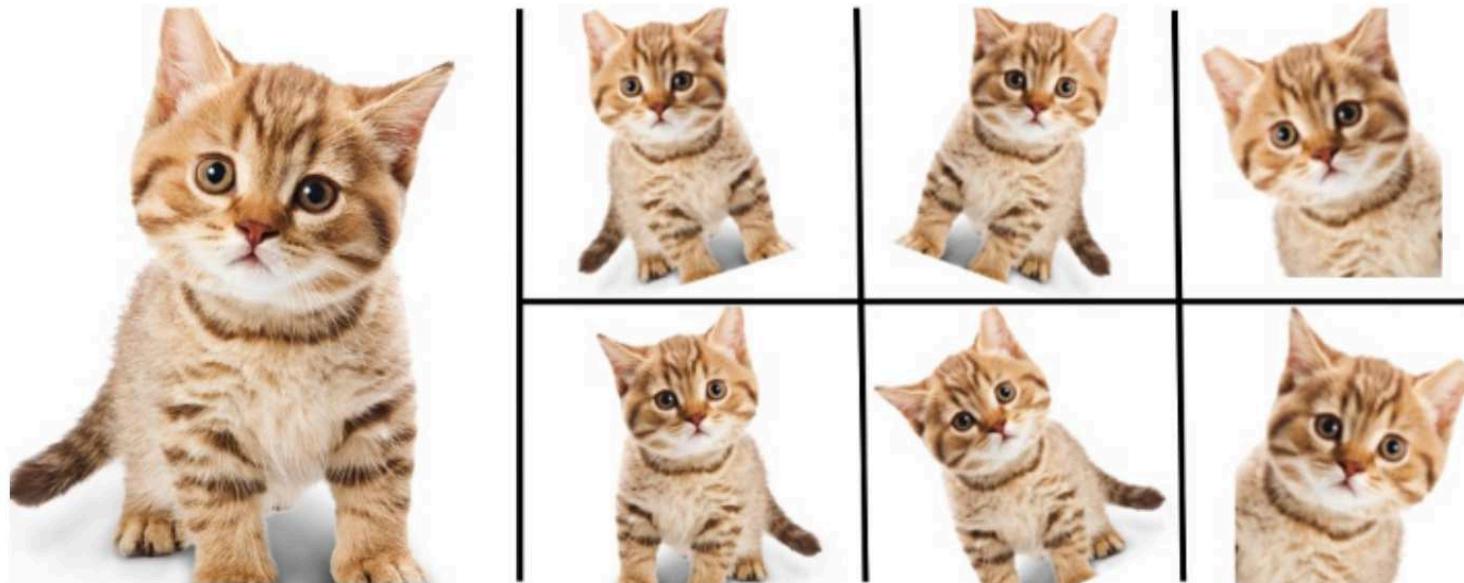
Given an image, you can:

- change its colour palette
- flip it
- rotate it
- zoom...

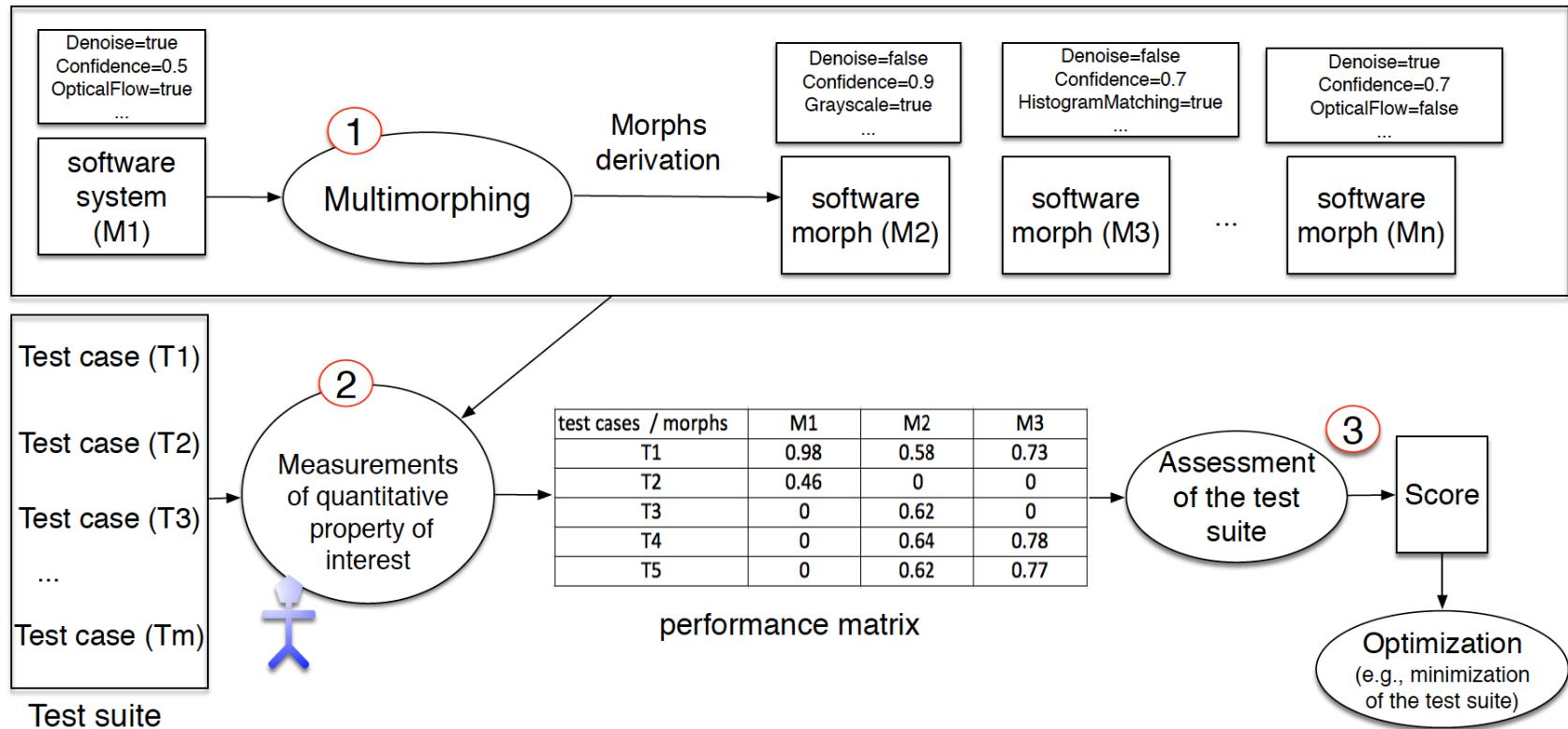
And still know what the output should be!

**Free test-cases (input)**

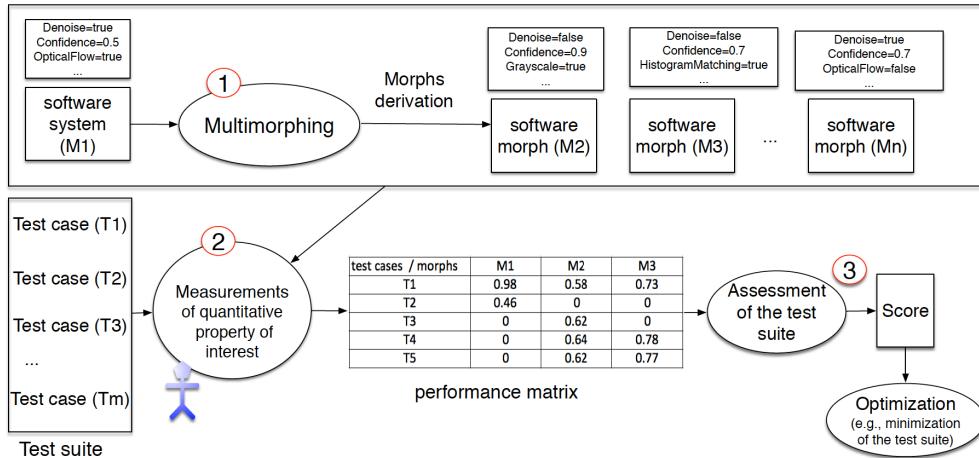
**Don't need to specify the oracle (output)**



# Multimorphic Testing



# Multimorphic Testing



Case	App. Domain	# morphs	# test suites
OpenCV	Tracking in videos	252	49
COCO	Obj. rec. in images	52	12
Haxe	Code Generation	21	84

Test suite reduction

Bugs in compiler (target variant)

# Dispersion score

Minimization of test suite

Prioritization of test cases

Better understanding of weaknesses



Algorithm 1

0.63

Algorithm 2

0.93

Algorithm 3

0.82

0.81

0.92

0.81

0.43

0.3

0.8

0.39

0.03

0.01

# Conclusion

- Testing Problem
  - Test Generation Problem (input)
  - Oracle Problem (output)
- Assertion-based testing
- Mutation Testing
- Test Generation
- Metamorphic Testing
- Multimorphic Testing
- **Many techniques can be used to test model transformations (eg compilers)**

# Back to the project...

# Comparing solver variants' performance

