Minimal rational interpolation for

time-harmonic Maxwell's equations

June 24, 2022 Fabio Matti

Primer

1

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compute the snapshots

$$\mathbf{u}(\omega_1), \mathbf{u}(\omega_2), \dots, \mathbf{u}(\omega_S)$$

and build the rational surrogate

$$\tilde{\mathbf{u}}(\omega) = \frac{\mathbf{P}(\omega)}{\mathbf{Q}(\omega)}$$

such that $\tilde{\mathbf{u}}(\omega) \approx \mathbf{u}(\omega)$ close to $\omega_1, \omega_2, \dots, \omega_S$.

Outline

- ▶ Problem formulation
- ► Finite element method
- ► Minimal rational interpolation
- ► Example applications
- ► Conclusion and outlook

Time-harmonic vector potential $\mathbf{u}(\mathbf{x},t) = \mathbf{u}(\mathbf{x}) \exp(i\omega t)$.

$$\textbf{B} = \nabla \times \textbf{u}$$

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Time-harmonic potential equation

$$\nabla \times (\mu^{-1}\nabla \times \mathbf{u}) - \varepsilon \omega^2 \mathbf{u} = \mathbf{j}$$

 $\mathsf{H}_{\mathrm{curl}}(\Omega) = \{ \mathbf{v} : \Omega \to \mathbb{C}^3, \text{ such that } \mathbf{v} \in \mathsf{L}_2(\Omega)^3, \ \nabla \times \mathbf{v} \in \mathsf{L}_2(\Omega)^3 \}$

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Weak formulation of the time-harmonic potential equation

Find $\mathbf{u} \in H_{\text{curl}}(\Omega)$, such that

$$\int_{\Omega} \langle \mu^{-1} \nabla \times \mathbf{u}, \nabla \times \mathbf{v} \rangle - \omega^2 \int_{\Omega} \varepsilon \langle \mathbf{u}, \mathbf{v} \rangle = \int_{\Omega} \langle \mathbf{j}, \mathbf{v} \rangle + \int_{\partial \Omega} \langle \mathbf{g}, \mathbf{v} \rangle$$

for all $\mathbf{v} \in \mathsf{H}_{\mathrm{curl}}$, where $\mathbf{g} = (\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{n}$.

$$\nabla \times (\mu^{-1}\nabla \times \mathbf{u}) - \varepsilon \omega^2 \mathbf{u} = \mathbf{j}$$

Perfectly conducting boundary

$$\mathbf{g} = \mathbf{0}$$
 and $\mathbf{E} \times \mathbf{n} = \mathbf{0}$, on Γ_D

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, on $\Gamma_{\mathbf{N}}$

Imperfectly conducting boundary

$$\mathbf{g} = i\omega\lambda(\mathbf{n} \times \mathbf{u}) \times \mathbf{n}$$
, on Γ_{I}

$$\int_{\Omega} \langle \boldsymbol{\mu}^{-1} \nabla \times \boldsymbol{u}, \nabla \times \boldsymbol{v} \rangle - \omega^2 \int_{\Omega} \varepsilon \langle \boldsymbol{u}, \boldsymbol{v} \rangle = \int_{\Omega} \langle \boldsymbol{j}, \boldsymbol{v} \rangle + \int_{\partial \Omega} \langle \boldsymbol{g}, \boldsymbol{v} \rangle$$

FEniCS is used to obtain FEM solutions of the form

$$\boldsymbol{\bar{u}} = (\bar{u}_1, \bar{u}_2, \ldots, \bar{u}_N)$$

where N is the number of degrees of freedom.

Finite element method | Vertex basis

FEniCS is used to obtain FEM solutions of the form

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where N is the number of degrees of freedom. Inner product in this representation is

$$\langle ar{\mathbf{u}}, ar{\mathbf{v}}
angle_{\mathsf{M}} = ar{\mathbf{u}}^{\mathsf{H}} \underline{\mathbf{M}} ar{\mathbf{v}} pprox \int_{\Omega} \langle \mathbf{u}, \mathbf{v}
angle$$

and the norm

$$\|\bar{\boldsymbol{u}}\|_{M} = \sqrt{\langle \bar{\boldsymbol{u}}, \bar{\boldsymbol{u}} \rangle_{M}} \approx \|\boldsymbol{u}\|_{L_{2}(\Omega)}$$

Rational surrogate

$$\tilde{\mathbf{u}}(\omega) = \frac{\mathbf{P}(\omega)}{\mathbf{Q}(\omega)} = \sum_{j=1}^{S} \frac{\mathbf{p}_{j}}{\omega - \omega_{j}} / \sum_{j=1}^{S} \frac{\mathbf{q}_{j}}{\omega - \omega_{j}}$$

in barycentric coordinates with support points $\omega_1, \omega_2, \dots, \omega_S$.

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Interpolation property

$$\tilde{\mathbf{u}}(\omega_i) = \mathbf{u}(\omega_i), \ \forall i \in \{1, 2, \dots, S\}$$

if and only if $\mathbf{p_i} = q_i \mathbf{u}(\omega_i)$, $\forall i$.

Given snapshots $\mathbf{u}(\omega_1)$, $\mathbf{u}(\omega_2)$, ..., $\mathbf{u}(\omega_S)$:

1. Compute the Gramian matrix $\underline{\mathbf{G}}$ with entries $g_{ij} = \langle \mathbf{u}(\omega_i), \mathbf{u}(\omega_j) \rangle$, $i, j \in \{1, 2, \dots, S\}$

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- 3. Define $\mathbf{q} = (q_1, q_2, ..., q_S)^T = \underline{\mathbf{V}}[:, S]$
- 4. Define the minimal rational surrogate $\mathbf{\tilde{u}}(\omega) = \mathbf{P}(\omega)/Q(\omega)$ with

$$\mathbf{P}(\omega) = \sum_{j=1}^{S} \frac{q_j \mathbf{u}(\omega_j)}{\omega - \omega_j} \text{ and } Q(\omega) = \sum_{j=1}^{S} \frac{q_j}{\omega - \omega_j}$$

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- 2. Starting with t = 2, iteratively take a new support point

$$\omega^{(t)} = \operatorname{argmin}_{\omega \in \Omega_{\text{test}}} |Q^{(t)}(\omega)|$$

from Ω_{test} to build the minimal rational surrogate $\tilde{\mathbf{u}}_{t+1}$ based on $\mathbf{u}(\omega^{(0)}), \mathbf{u}(\omega^{(1)}), \dots, \mathbf{u}(\omega^{(t+1)})$ and increment t

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3. Stop when relative error

$$\|\mathbf{u}(\boldsymbol{\omega}_{t+1}) - \mathbf{\tilde{u}}_t(\boldsymbol{\omega}_{t+1})\|_{M} / \|\mathbf{u}(\boldsymbol{\omega}_{t+1})\|_{M}$$

is small enough

With the QR-decomposition of the snapshot matrix $\underline{\mathbf{U}} = [\mathbf{u}(\omega_1), \dots, \mathbf{u}(\omega_S)].$

$$\underline{\mathbf{U}} = \mathbf{Q} \; \underline{\mathbf{R}}$$

the Gramian matrix can be expressed as

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- ▶ \underline{G} and \underline{R} have the same right-singular vector (exactly what is needed for MRI)
- ► <u>R</u> can be built sequentially (modified Householder triangularization for gMRI)

Efficient way of storing the surrogate (e_i canonical basis vector)

$$\mathring{\mathbf{u}}(\omega) = \sum_{i=1}^{S} \frac{q_i \mathbf{e}_i}{\omega - \omega_i} / \sum_{i=1}^{S} \frac{q_i}{\omega - \omega_i}$$

Efficient way of storing the surrogate $(e_j$ canonical basis vector)

$$\dot{\mathbf{u}}(\omega) = \sum_{j=1}^{S} \frac{q_j \mathbf{e}_j}{\omega - \omega_j} / \sum_{j=1}^{S} \frac{q_j}{\omega - \omega_j}$$

The original surrogate can be recovered with

$$\mathbf{\tilde{u}}(\omega) = \underline{\mathbf{U}}\mathbf{\mathring{u}}(\omega)$$

Neat helper quantity ($\mathbf{r}_j = \underline{\mathbf{R}}[:,S]$ from QR-decomposition)

$$\mathbf{\hat{u}}(\omega) = \sum_{j=1}^{S} \frac{q_j \mathbf{r}_j}{\omega - \omega_j} / \sum_{j=1}^{S} \frac{q_j}{\omega - \omega_j}$$

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Proposed way of approximating relative error in gMRI

$$\frac{\|\textbf{u}(\boldsymbol{\omega}_{t+1}) - \boldsymbol{\tilde{u}}_t(\boldsymbol{\omega}_{t+1})\|_M}{\|\textbf{u}(\boldsymbol{\omega}_{t+1})\|_M} \approx \frac{\|\textbf{r}_{t+1} - \boldsymbol{\hat{u}}_t(\boldsymbol{\omega}_{t+1})\|}{\|\boldsymbol{\hat{u}}_t(\boldsymbol{\omega}_{t+1})\|}$$

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We want to find ω , such that

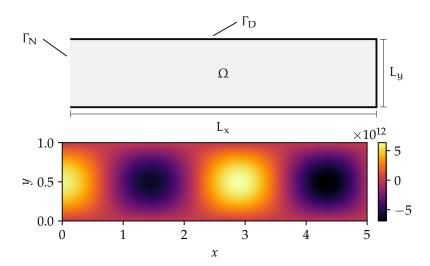
$$0 = Q(\omega) = \sum_{i=1}^{S} \frac{q_i}{\omega - \omega_i}$$

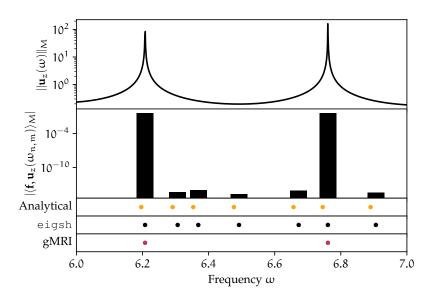
Equivalent eigenvalue problem

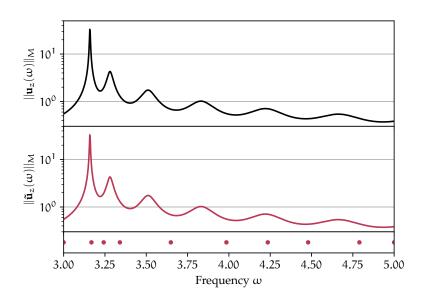
$$\mathbf{A}\mathbf{w} = \omega \mathbf{B}\mathbf{w}$$

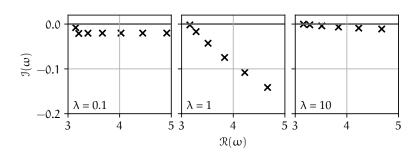
with

$$\underline{\mathbf{A}} = \begin{pmatrix} 0 & q_1 & q_2 & \dots & q_S \\ 1 & \omega_1 & & & & \\ 1 & & \omega_2 & & & \\ \vdots & & & \ddots & & \\ 1 & & & & \omega_S \end{pmatrix} \text{ and } \underline{\mathbf{B}} = \begin{pmatrix} 0 & & & & \\ & 1 & & & & \\ & & 1 & & & \\ \vdots & & & \ddots & & \\ & & & & 1 \end{pmatrix}$$

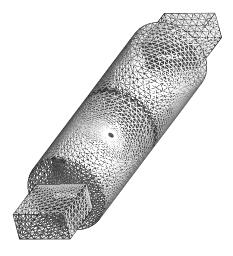


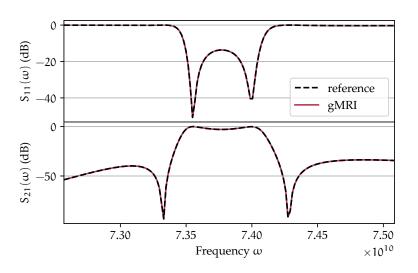






Dual-mode circular waveguide filter





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Conclusion and outlook

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