

EPFL

SEMESTER PROJECT

Minimal Rational Interpolation for Time-Harmonic Maxwell's Equations

Fabio Matti

supervised by
Prof. Fabio Nobile
Dr. Davide Pradovera

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ABSTRACT

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1 INTRODUCTION

2 FINITE ELEMENT DISCRETIZATION OF THE TIME-HARMONIC MAXWELL'S EQUATIONS

2.1 VECTOR POTENTIAL FORMULATION OF THE TIME-HARMONIC MAXWELL'S EQUATIONS

Let \mathbf{E} denote an electric field, \mathbf{B} a magnetic field strength, ρ an electric charge density, and \mathbf{j} an electric current density. Maxwell's equations are stated in [Monk, 2003] as

$$\nabla \cdot (\epsilon \mathbf{E}) = \rho \quad (2.1)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (2.2)$$

$$\nabla \times \mathbf{E} = -\partial_t \mathbf{B} \quad (2.3)$$

$$\nabla \times (\mu^{-1} \mathbf{B}) = \partial_t (\epsilon \mathbf{E}) + \mathbf{j} \quad (2.4)$$

with ϵ being the permittivity and μ the permeability.

Equation (2.2) allows for an expression of the magnetic field $\mathbf{B} = \nabla \times \mathbf{u}$ in terms of a vector valued function \mathbf{u} , the vector potential (in literature commonly denoted with \mathbf{A}). Similarly, (2.3) suggests rewriting the electric field $\mathbf{E} = -\nabla \phi - \partial_t \mathbf{u}$ using a scalar function ϕ , referred to as the scalar potential.

The physical quantities \mathbf{E} and \mathbf{B} remain unchanged if we transform $\mathbf{u} \rightarrow \mathbf{u}' = \mathbf{u} + \nabla \psi$ or $\phi \rightarrow \phi' = \phi - \partial_t \psi$ for arbitrary functions ψ . A convenient choice of ψ is suggested in [Kagerer, 2018] to be

$$\psi = \int_0^t \phi dt' \quad (2.5)$$

which transforms $\phi \rightarrow \phi' = 0$ and $\mathbf{u} \rightarrow \mathbf{u}' = \mathbf{u} + \nabla \int_0^t \phi dt'$. Thus, the expressions for the electrical and magnetic field become

$$\mathbf{E} = -\partial_t \mathbf{u} \quad (2.6)$$

$$\mathbf{B} = \nabla \times \mathbf{u} \quad (2.7)$$

where I renamed the variable \mathbf{u}' to \mathbf{u} for simplicity.

Plugging the identities (2.6) and (2.7) into (2.4) yields

$$\nabla \times (\mu^{-1} \nabla \times \mathbf{u}) = \epsilon \partial_t^2 \mathbf{u} + \mathbf{j} \quad (2.8)$$

For the rest of this report, I restrict myself to vector potentials \mathbf{u} that exhibit a harmonic dependence on time t , i.e. may be factorized into a term solely depending on the position \mathbf{x} and a complex exponential

$$\mathbf{u}(\mathbf{x}, t) = \mathbf{u}(\mathbf{x}) \exp(i\omega t) \quad (2.9)$$

Substituting this expression into (2.8) results in the

Time-harmonic potential equation

$$\nabla \times (\mu^{-1} \nabla \times \mathbf{u}) - \epsilon \omega^2 \mathbf{u} = \mathbf{j} \quad (2.10)$$

2.2 WEAK FORMULATION FOR THE TIME-HARMONIC POTENTIAL EQUATION

Equation (2.10) may be multiplied by a vector-valued function $\mathbf{v} \in H_{\text{curl}}(\Omega)$, where

$$H_{\text{curl}}(\Omega) = \{\mathbf{u} : \Omega \rightarrow \mathbb{C}, \text{ such that } \mathbf{u} \in L^2(\mathbb{C})^3, \nabla \times \mathbf{u} \in L^2(\mathbb{C})^3\} \quad (2.11)$$

and then integrated over all of Ω to obtain

$$\int_{\Omega} (\nabla \times (\mu^{-1} \nabla \times \mathbf{u})) \cdot \mathbf{v} - \omega^2 \int_{\Omega} \epsilon \mathbf{u} \cdot \mathbf{v} = \int_{\Omega} \mathbf{j} \cdot \mathbf{v} \quad (2.12)$$

This may further be simplified (2.12) to (see Section for details)

Weak formulation of the time-harmonic potential equation

$$\int_{\Omega} (\mu^{-1} \nabla \times \mathbf{u}) \cdot (\nabla \times \mathbf{v}) - \omega^2 \int_{\Omega} \epsilon \mathbf{u} \cdot \mathbf{v} = \int_{\Omega} \mathbf{j} \cdot \mathbf{v} + \int_{\partial\Omega} \underbrace{((\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{n}) \cdot \mathbf{v}}_{=\mathbf{g}} \quad (2.13)$$

where \mathbf{n} denotes the surface normal to the boundary $\partial\Omega$.

Boundary conditions on the electric field \mathbf{E} may be enforced in a Dirichlet-type fashion through the relation (2.6) and the assumption (2.9)

$$\mathbf{u}|_{\partial\Omega} = -\frac{1}{i\omega} \mathbf{E}|_{\partial\Omega} \quad (2.14)$$

Those on the magnetic field \mathbf{B} through a Neumann-type condition following from (2.7) and again (2.9)

$$\mathbf{g}|_{\partial\Omega} = (\mu^{-1} \mathbf{B}|_{\partial\Omega}) \times \mathbf{n} \quad (2.15)$$

2.3 TWO-DIMENSIONAL RESONANT CAVITY

A resonant cavity is a region Ω enclosed by a boundary $\partial\Omega$. The boundary is subdivided into one (or more) inlets Γ_N and a perfect electrically conducting wall $\Gamma_D = \partial\Omega \setminus \Gamma_N$.

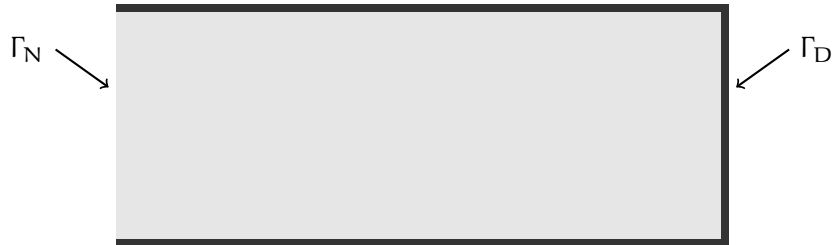


FIGURE 2.1 – Example of a two-dimensional resonant cavity: The rectangular cavity.

Suppose the current density $\mathbf{j} \equiv 0$ and orient the coordinate system in such a way that $\mathbf{u} = u_z \mathbf{e}_z$ and $\mathbf{v} = v_z \mathbf{e}_z$. Consequently,

$$(\mu^{-1} \nabla \times \mathbf{u}) \cdot (\nabla \times \mathbf{v}) = (\mu^{-1} \nabla u_z) \cdot (\nabla v_z) \quad (2.16)$$

Use $g_z = (\mathbf{g})_z$ along the boundary Γ_N , to convert (2.13) into the weak formulation for a two-dimensional resonant cavity

$$\int_{\Omega} (\mu^{-1} \nabla u_z) \cdot (\nabla v_z) - \omega^2 \int_{\Omega} \epsilon u_z v_z = \int_{\partial\Omega} g_z v_z \quad (2.17)$$

Let \mathbf{E} and \mathbf{B} refer to the electric and magnetic fields inside the cavity. For now, I distinguish two types of boundaries.

For the perfectly conducting boundary, treated in [Monk, 2003], it holds that

$$\mathbf{n} \times \mathbf{E} = 0, \text{ on } \Gamma_D \quad (2.18)$$

For the boundaries in a two-dimensional resonant cavity (see Figure 2.1), this only holds true if $E_z = 0$, which translates to the Dirichlet boundary condition $\mathbf{u}|_{\Gamma_D} = 0$ in light of (2.14).

For the inlet, it is easiest to enforce the boundary condition through the magnetic field \mathbf{B} (considering $\mathbf{n} = -\mathbf{e}_x$ as depicted in Figure 2.1):

$$g_z = ((\mu^{-1} \mathbf{B}) \times (-\mathbf{e}_x))_z = \mu^{-1} B_x \quad (2.19)$$

2.4 WAVEGUIDE

2.5 IMPERFECT CONDUCTOR

3 FINITE ELEMENT APPROXIMATION WITH FENICS

$$a_{\omega}(u, v) = L(v).$$

4 GREEDY MINIMAL RATIONAL INTERPOLATION FOR THE TIME-HARMONIC MAXWELL'S EQUATIONS

[F. Bonzzoni]

Algorithm 1 Minimal rational interpolation

Require: $\omega_1, \dots, \omega_S$
Require: $\mathbf{U} = [\mathbf{u}(\omega_1) | \dots | \mathbf{u}(\omega_S)]$ ▷ Snapshot matrix
 Compute \mathbf{G} with $g_{ij} = \langle \mathbf{u}(\omega_i), \mathbf{u}(\omega_j) \rangle_M$, $i, j \in \{1, \dots, S\}$ ▷ Gramian matrix
 Compute the singular value decomposition $\mathbf{G} = \mathbf{V}\Sigma\mathbf{V}^H$
 Define $\mathbf{q} = \mathbf{V}[:, S]$
 Define $\tilde{\mathbf{u}}(\omega) = \mathbf{P}(\omega)/\mathbf{Q}(\omega)$ with $\mathbf{P}(\omega) = \sum_{j=1}^S \frac{q_j \mathbf{u}(\omega_j)}{\omega - \omega_j}$ and $\mathbf{Q}(\omega) = \sum_{j=1}^S \frac{q_j}{\omega - \omega_j}$

[D. Pradovera, 2021]

Algorithm 2 Greedy minimal rational interpolation

Require: $\tau > 0$ ▷ Relative L_2 -error tolerance
Require: $\Omega_{\text{test}} = \{\omega_i\}_{i=1}^M$ ▷ Set of candidate support points
Require: $a_\omega(\mathbf{u}, \mathbf{v}) = \mathbf{L}(\mathbf{v})$ ▷ Finite element formulation of the problem
 Choose $\omega_1, \dots, \omega_t \in \Omega_{\text{test}}$ ▷ Usually the smallest and largest element
 Remove $\omega_1, \dots, \omega_t$ from Ω_{test}
 Solve $a_{\omega_i}(\mathbf{u}_i, \mathbf{v}) = \mathbf{L}(\mathbf{v})$ for $i \in \{1, \dots, t\}$
 Build surrogate $\tilde{\mathbf{u}}_t = \mathbf{P}_t(\omega)/\mathbf{Q}_t(\omega)$ using the solutions $\mathbf{u}_1, \dots, \mathbf{u}_t$
while $\Omega_{\text{test}} \neq \emptyset$ **do**
 $\omega_{t+1} \leftarrow \operatorname{argmin}_{\omega \in \Omega_{\text{test}}} |\mathbf{Q}_t(\omega)|$
 Solve $a_{\omega_{t+1}}(\mathbf{u}_{t+1}, \mathbf{v}) = \mathbf{L}(\mathbf{v})$
 Build surrogate $\tilde{\mathbf{u}}_{t+1} = \mathbf{P}_{t+1}(\omega)/\mathbf{Q}_{t+1}(\omega)$ using the solutions $\mathbf{u}_1, \dots, \mathbf{u}_{t+1}$
 if $\|\mathbf{u}_{t+1}(\omega_{t+1}) - \tilde{\mathbf{u}}_{t+1}(\omega_{t+1})\|_M / \|\mathbf{u}_{t+1}(\omega_{t+1})\|_M < \tau$ **then return**
 end if
 $t \leftarrow t + 1$
end while

[Klein, 2012]

Defining

$$\mathbf{v}_i = (\omega - \omega_i)^{-1} \quad (4.1)$$

and requiring

$$0 = \mathbf{Q}(\omega) = \sum_{i=1}^S q_i \mathbf{v}_i(\omega) \quad (4.2)$$

can be equivalently expressed as a generalized eigenvalue problem

$$\underline{\mathbf{A}}\mathbf{u} = \omega \underline{\mathbf{B}}\mathbf{u} \quad (4.3)$$

with

$$\underline{\mathbf{A}} = \begin{pmatrix} 0 & q_1 & q_2 & \dots & q_s \\ 1 & \omega_1 & & & \\ 1 & & \omega_2 & & \\ \vdots & & & \ddots & \\ 1 & & & & \omega_s \end{pmatrix} \quad \text{and} \quad \underline{\mathbf{B}} = \begin{pmatrix} 0 & & & & \\ & 1 & & & \\ & & 1 & & \\ \vdots & & & \ddots & \\ & & & & 1 \end{pmatrix} \quad (4.4)$$

[Trefethen, 2010]

Algorithm 3 Additive Householder triangularization

Require: $\mathbf{U}[1 \dots s, 1 \dots N]$ ▷ Next snapshot matrix
Require: $\mathbf{R}[1 \dots S, 1 \dots S]$ ▷ Previous triangular matrix
Require: $\mathbf{E}[1 \dots S, 1 \dots N]$ ▷ Previous orthonormal matrix
Require: $\mathbf{V}[1 \dots S, 1 \dots N]$ ▷ Previous Householder matrix

Extend size of \mathbf{R} to $(S + s) \times (S + s)$
Extend \mathbf{E} with S orthonormal columns to $(S + s) \times N$
Extend size of \mathbf{V} to $(S + s) \times N$

for $j = S + 1 : S + s$ **do**
 $\mathbf{u} = \mathbf{U}[j]$
 for $k = 1 : j - 1$ **do**
 $\mathbf{u} \leftarrow \mathbf{u} - 2\langle \mathbf{V}[k, :], \mathbf{u} \rangle_{\mathbf{M}} \mathbf{V}[k, :]$
 $\mathbf{R}[k, j] \leftarrow \langle \mathbf{E}[k, :], \mathbf{u} \rangle_{\mathbf{M}}$
 $\mathbf{u} \leftarrow \mathbf{u} - \mathbf{R}[k, j] \mathbf{E}[k, :]$
 end for
 $\mathbf{R}[j, j] \leftarrow \|\mathbf{u}\|_{\mathbf{M}}$
 $\alpha \leftarrow \langle \mathbf{E}[j, :], \mathbf{u} \rangle_{\mathbf{M}}$
 if $|\alpha| \neq 0$ **then**
 $\mathbf{E}[j, :] \leftarrow \mathbf{E}[j, :](-\alpha/|\alpha|)$
 end if
 $\mathbf{V}[j, :] \leftarrow \mathbf{R}[j, j] \mathbf{E}[j, :] - \mathbf{u}$
 $\mathbf{V}[j, :] \leftarrow \mathbf{V}[j, :] - \langle \mathbf{E}[S + 1 : j], \mathbf{V}[j, :] \rangle_{\mathbf{M}} \mathbf{E}[S + 1 : j, :]$
 $\sigma \leftarrow \|\mathbf{V}[j, :]\|_{\mathbf{M}}$
 if $\sigma \neq 0$ **then**
 $\mathbf{V}[j, :] \leftarrow \mathbf{V}[j, :]/\sigma$
 else
 $\mathbf{V}[j, :] \leftarrow \mathbf{E}[j, :]$
 end if
end for

5 EXAMPLES

5.1 TWO-DIMENSIONAL RECTANGULAR CAVITY

5.2 DUAL MODE CIRCULAR WAVEGUIDE FILTER



FIGURE 5.1 – Dual-mode circular waveguide filter.

5.3 IMPERFECTLY CONDUCTING BOUNDARIES

6 CONCLUSION AND OUTLOOK

7 APPENDIX

7.1 DETAILED DERIVATION FOR THE WEAK FORMULATION OF THE TIME-HARMONIC POTENTIAL EQUATION

The goal is to rewrite the curl-integral on the left-hand side of (2.12):

$$\int_{\Omega} (\nabla \times (\mu^{-1} \nabla \times \mathbf{u})) \cdot \mathbf{v} \quad (7.1)$$

In order to simplify the curls and apply the Gauss theorem, I first show the following vector calculus identity:

Curl product rule

$$(\nabla \times \mathbf{a}) \cdot \mathbf{b} = \nabla \cdot (\mathbf{a} \times \mathbf{b}) + \mathbf{a} \cdot (\nabla \times \mathbf{b}) \quad (7.2)$$

where \mathbf{a}, \mathbf{b} are vector-value functions. The completely antisymmetric tensor ε_{ijk} , frequently referred to as the Levi-Civita tensor, may be employed to rewrite the components of the curl of a vector-function \mathbf{a} as the sum

$$(\nabla \times \mathbf{a})_k = \sum_i \sum_j \varepsilon_{ijk} \partial_i a_j \quad (7.3)$$

where ∂_i denotes the partial derivative with respect to the i -th coordinate direction. This yields

$$\begin{aligned} (\nabla \times \mathbf{a}) \cdot \mathbf{b} &= \sum_k (\nabla \times \mathbf{a})_k b_k \\ &= \sum_k \left(\sum_i \sum_j \varepsilon_{ijk} \partial_i a_j \right) b_k \\ &= \sum_k \sum_i \sum_j \partial_i (\varepsilon_{ijk} a_j b_k) - \sum_k \sum_i \sum_j a_j (\varepsilon_{ijk} \partial_i b_k) \\ &= \sum_k \sum_i \sum_j \partial_i (\varepsilon_{jki} a_j b_k) - \sum_k \sum_i \sum_j a_j ((-\varepsilon_{ikj}) \partial_i b_k) \\ &= \sum_i \partial_i (\mathbf{a} \times \mathbf{b})_i + \sum_j a_j (\nabla \times \mathbf{b})_j \\ &= \nabla \cdot (\mathbf{a} \times \mathbf{b}) + \mathbf{a} \cdot (\nabla \times \mathbf{b}) \end{aligned} \quad (7.4)$$

by expressing the scalar product as a component-sum, using the product rule and applying the symmetry and anti-symmetry properties of the Levi-Civita tensor. Now the identity (7.2) to (7.1) together with Gauss' theorem gives

$$\begin{aligned} \int_{\Omega} (\nabla \times (\mu^{-1} \nabla \times \mathbf{u})) \cdot \mathbf{v} &= \int_{\Omega} \nabla \cdot ((\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{v}) + \int_{\Omega} (\mu^{-1} \nabla \times \mathbf{u}) \cdot (\nabla \times \mathbf{v}) \\ &= \int_{\partial\Omega} ((\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{v}) \cdot \mathbf{n} + \int_{\Omega} (\mu^{-1} \nabla \times \mathbf{u}) \cdot (\nabla \times \mathbf{v}) \end{aligned} \quad (7.5)$$

For later convenience, the boundary integral can further be simplified using the

Commutative behavior of the scalar triple product

$$(\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c} = -(\mathbf{a} \times \mathbf{c}) \cdot \mathbf{b} \quad (7.6)$$

This identity follows immediately from a small manipulation with the Levi-Civita tensor:

$$\begin{aligned} (\mathbf{a} \times \mathbf{b}) \cdot \mathbf{c} &= \sum_k \left(\sum_i \sum_j \varepsilon_{ijk} a_i b_j \right) c_k \\ &= \sum_j \left(\sum_i \sum_k (-\varepsilon_{ikj}) a_i c_k \right) b_j \\ &= -(\mathbf{a} \times \mathbf{c}) \cdot \mathbf{b} \end{aligned} \quad (7.7)$$

The boundary integral becomes

$$\int_{\partial\Omega} ((\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{v}) \cdot \mathbf{n} = - \int_{\partial\Omega} ((\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{n}) \cdot \mathbf{v} \quad (7.8)$$

This concludes the short derivation, because now (7.1) may be rewritten as

$$- \int_{\partial\Omega} ((\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{v}) \cdot \mathbf{n} + \int_{\Omega} (\mu^{-1} \nabla \times \mathbf{u}) \cdot (\nabla \times \mathbf{v}) \quad (7.9)$$

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