

Minimal rational interpolation for time-harmonic Maxwell's equations

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and build the rational surrogate

$$\tilde{\mathbf{u}}(\omega) = \frac{\mathbf{P}(\omega)}{Q(\omega)}$$

such that $\tilde{\mathbf{u}}(\omega) \approx \mathbf{u}(\omega)$ close to $\omega_1, \omega_2, \dots, \omega_S$.

- ▶ Problem formulation
- ▶ Finite element method
- ▶ Minimal rational interpolation
- ▶ Example applications
- ▶ Conclusion and outlook

Time-harmonic vector potential $\mathbf{u}(\mathbf{x}, t) = \mathbf{u}(\mathbf{x}) \exp(i\omega t)$.

$$\mathbf{B} = \nabla \times \mathbf{u} \quad (\text{Magnetic field})$$

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Maxwell's equation

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Time-harmonic potential equation

$$\nabla \times (\mu^{-1} \nabla \times \mathbf{u}) - \epsilon \omega^2 \mathbf{u} = \mathbf{j}$$

$$H_{\text{curl}}(\Omega) = \{\mathbf{v} : \Omega \rightarrow \mathbb{C}^3, \text{ such that } \mathbf{v} \in L_2(\Omega)^3, \nabla \times \mathbf{v} \in L_2(\Omega)^3\}$$

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Weak formulation of the time-harmonic potential equation

Find $\mathbf{u} \in H_{\text{curl}}(\Omega)$, such that

$$\int_{\Omega} \langle \mu^{-1} \nabla \times \mathbf{u}, \nabla \times \mathbf{v} \rangle - \omega^2 \int_{\Omega} \epsilon \langle \mathbf{u}, \mathbf{v} \rangle = \int_{\Omega} \langle \mathbf{j}, \mathbf{v} \rangle + \int_{\partial\Omega} \langle \mathbf{g}, \mathbf{v} \rangle$$

for all $\mathbf{v} \in H_{\text{curl}}$, where $\mathbf{g} = (\mu^{-1} \nabla \times \mathbf{u}) \times \mathbf{n}$.

Perfectly conducting boundary

$$\mathbf{u} \times \mathbf{n} = \mathbf{0}, \text{ on } \Gamma_D$$

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Imperfectly conducting boundary

$$\mathbf{g} = i\omega\lambda(\mathbf{n} \times \mathbf{u}) \times \mathbf{n}, \text{ on } \Gamma_I$$

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FEniCS is used to obtain FEM solutions of the form

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where N is the number of degrees of freedom. Inner product in this representation is

$$\langle \bar{\mathbf{u}}, \bar{\mathbf{v}} \rangle_M = \bar{\mathbf{u}}^H \underline{\mathbf{M}} \bar{\mathbf{v}} \approx \int_{\Omega} \langle \mathbf{u}, \mathbf{v} \rangle$$

and the norm

$$\|\bar{\mathbf{u}}\|_M = \sqrt{\langle \bar{\mathbf{u}}, \bar{\mathbf{u}} \rangle_M} \approx \|\mathbf{u}\|_{L_2(\Omega)}$$

Rational surrogate

$$\tilde{\mathbf{u}}(\omega) = \frac{\mathbf{P}(\omega)}{Q(\omega)} = \sum_{i=1}^S \frac{\mathbf{p}_i}{\omega - \omega_i} / \sum_{i=1}^S \frac{q_i}{\omega - \omega_i}$$

in barycentric coordinates with support points $\omega_1, \omega_2, \dots, \omega_3$.

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Interpolation property

$$\tilde{\mathbf{u}}(\omega_i) = \mathbf{u}(\omega_i), \quad \forall i \in \{1, 2, \dots, S\}$$

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3. Define $\mathbf{q} = (q_1, q_2, \dots, q_S)^T = \underline{\mathbf{V}}[:, S]$
4. Define $\tilde{\mathbf{u}}(\omega) = \mathbf{P}(\omega)/Q(\omega)$ with

$$\mathbf{P}(\omega) = \sum_{j=1}^S \frac{q_j \mathbf{u}(\omega_j)}{\omega - \omega_j} \quad \text{and} \quad Q(\omega) = \sum_{j=1}^S \frac{q_j}{\omega - \omega_j}$$

Greedy minimal rational interpolation (gMRI)

Given $\Omega_{\text{test}} = \{\omega_1, \omega_2, \dots, \omega_T\}$ as candidate support points:

1. Build initial surrogate $\tilde{\mathbf{u}}_t$ with some initial support points $\omega_1, \omega_2, \dots, \omega_t \in \Omega_{\text{test}}$ (usually smallest and largest element)

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2. Iteratively add a new support point

$$\omega_{t+1} = \operatorname{argmin}_{\omega \in \Omega_{\text{test}}} |Q_t(\omega)|$$

to build $\tilde{\mathbf{u}}_{t+1}$ based on $\mathbf{u}(\omega_1), \mathbf{u}(\omega_2), \dots, \mathbf{u}(\omega_{t+1})$

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3. Stop when relative error

$$\|\mathbf{u}(\omega_{t+1}) - \tilde{\mathbf{u}}_{t+1}(\omega_{t+1})\|_M / \|\mathbf{u}(\omega_{t+1})\|_M$$

is small enough

With the QR-decomposition of the snapshot matrix $\underline{\mathbf{U}} = [\mathbf{u}(\omega_1), \dots, \mathbf{u}(\omega_S)]$.

$$\underline{\mathbf{U}} = \underline{\mathbf{Q}} \underline{\mathbf{R}}$$

the Gramian matrix can be expressed as

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- ▶ $\underline{\mathbf{G}}$ and $\underline{\mathbf{R}}$ have the same right-singular vector (exactly what is needed for MRI)
- ▶ $\underline{\mathbf{R}}$ can be built sequentially (modified Householder triangularization for gMRI)

Efficient way of storing the surrogate (\mathbf{e}_j canonical basis vector)

$$\mathbf{\hat{u}}(\omega) = \sum_{j=1}^S \frac{q_j \mathbf{e}_j}{\omega - \omega_j} / \sum_{j=1}^S \frac{q_j}{\omega - \omega_j}$$

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Can recover the original surrogate

$$\tilde{\mathbf{u}}(\omega) = \underline{\mathbf{U}} \mathring{\mathbf{u}}(\omega)$$

Neat helper quantity ($\mathbf{r}_j = \mathbf{R}[:, S]$ from QR-decomposition)

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Proposed way of approximating relative error in gMRI

$$\frac{\|\mathbf{u}_{t+1} - \tilde{\mathbf{u}}_t(\omega_{t+1})\|_M}{\|\mathbf{u}_{t+1}\|_M} \approx \frac{\|\mathbf{r}_{t+1} - \hat{\mathbf{u}}_t(\omega_{t+1})\|}{\|\hat{\mathbf{u}}_t(\omega_{t+1})\|}$$

We want to find ω , such that

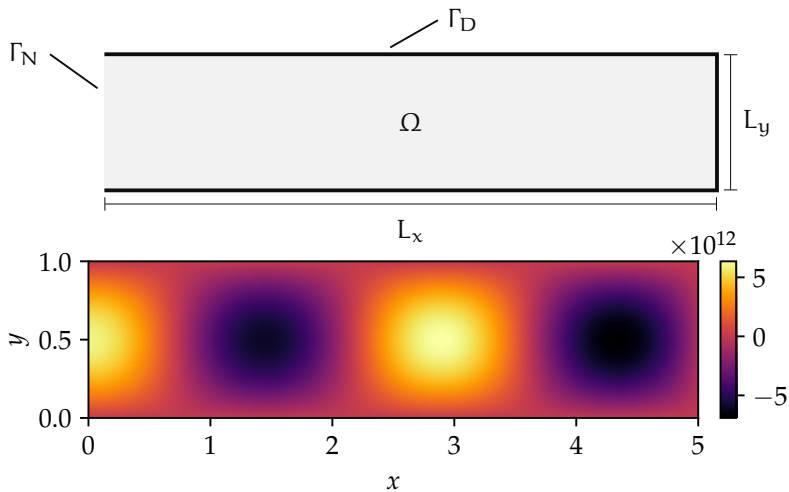
$$0 = Q(\omega) = \sum_{i=1}^S \frac{q_i}{\omega - \omega_i}$$

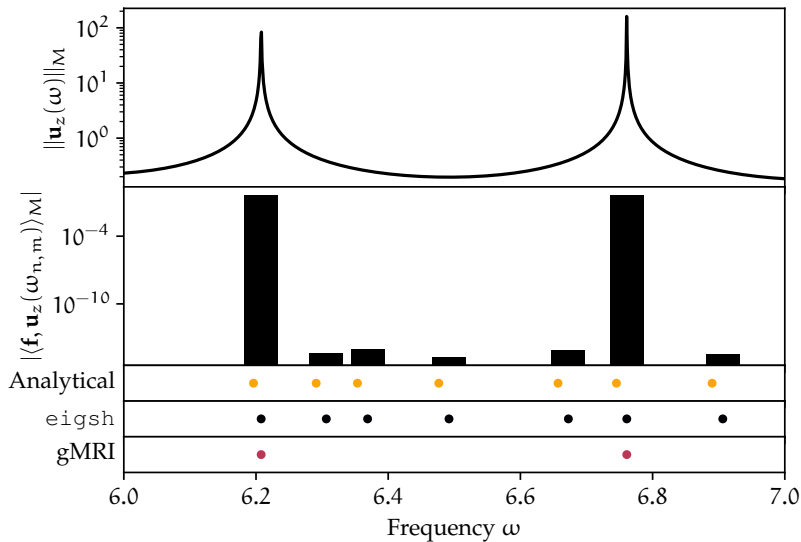
Equivalent eigenvalue problem

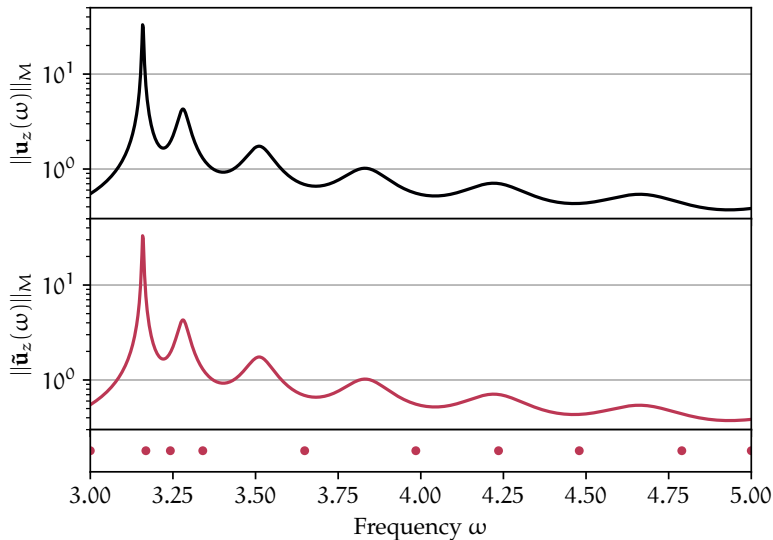
$$\underline{\mathbf{A}}\mathbf{w} = \omega \underline{\mathbf{B}}\mathbf{w}$$

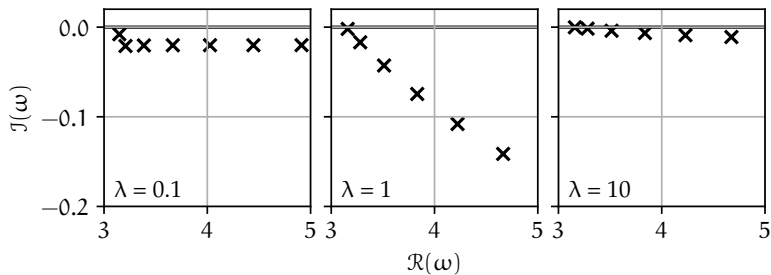
with

$$\underline{\mathbf{A}} = \begin{pmatrix} 0 & q_1 & q_2 & \dots & q_S \\ 1 & \omega_1 & & & \\ 1 & & \omega_2 & & \\ \vdots & & & \ddots & \\ 1 & & & & \omega_S \end{pmatrix} \quad \text{and} \quad \underline{\mathbf{B}} = \begin{pmatrix} 0 & & & & \\ & 1 & & & \\ & & 1 & & \\ \vdots & & & \ddots & \\ & & & & 1 \end{pmatrix}$$

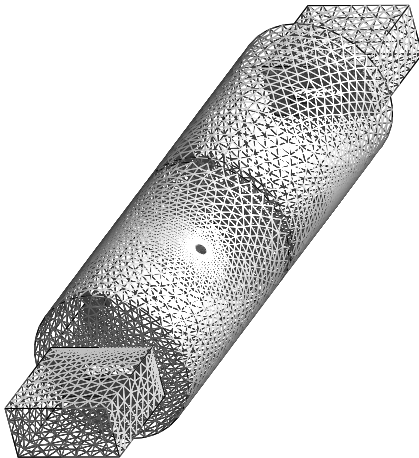


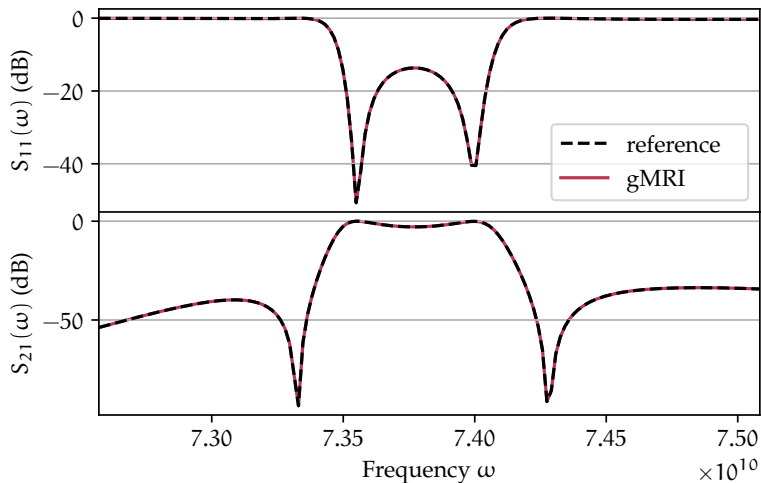






Dual-mode circular waveguide filter





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